

**Homework #2**

Due: Friday, September 12

1) A mass  $m$  is initially at rest, partially supported by a spring and partially by stops (see Figure 1). In the position shown, the spring force is  $mg/4$ . At time  $t = 0$  the stops are rotated, suddenly releasing the mass. Determine the motion of the mass.

*Main concept: definition of the coordinate system and relation with the form of the equation of motion.*

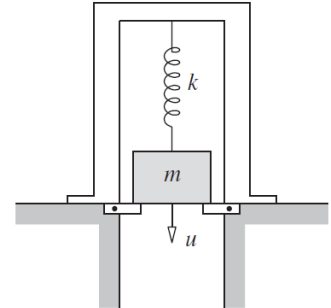


Figure 1

2) The weight of the wooden block shown in Fig. 2 is 20 lb and the spring stiffness is 120 lb/in. The block is initially at rest. A bullet weighing 0.4 lb is fired at a speed of 50 ft/sec into the block and becomes embedded in the block. Determine the resulting motion  $u(t)$  of the block.

*\*Hint: Use conservation of momentum.*

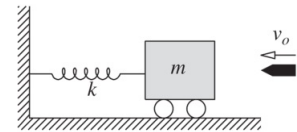


Figure 2

3) The vertical suspension system of an automobile is idealized as a viscously damped SDF system. Under the 3500-lb weight of the car the suspension system deflects 2.1 inches. The suspension is designed to have a damping ratio of  $\zeta = 0.7$  with no one in the car.

- (a) Calculate the damping and stiffness coefficients of the suspension.
- (b) With four 150-lb passengers in the car, what is the effective damping ratio?
- (c) Calculate the natural vibration frequency for case (b).

*Main concept: static equilibrium position and the vibration properties of a system with damping.*

4) Find a linear elastic oscillator, measure its damped natural frequency and determine its percentage of critical damping. Submit a sketch of the system, your measurements, and calculations.

*Note: It is up to you how you measure the response. One option is to use your cell phone as an accelerometer.*

# Solution.

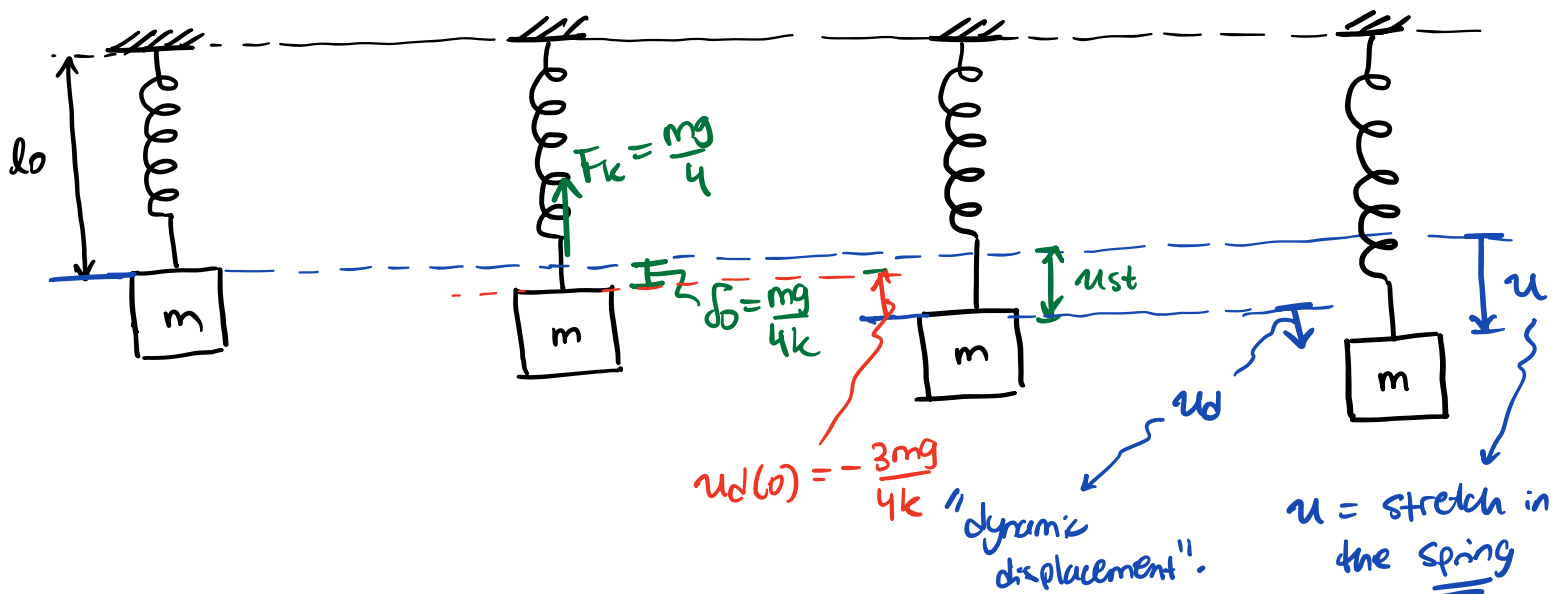
## Problem #1.

Position of no force  
in the spring.

@  $t=0$

static equilibrium  
position

@ time =  $t$



A free body diagram gives the E.O.M @ time  $\underline{t}$ .

$k u$   $\uparrow$   $m \ddot{u}$

$m$

$mg$   $\downarrow$

$$\Rightarrow m \ddot{u} + k u = mg$$

$$u_{st} = \frac{mg}{k}$$

if we introduce

$$u_d = u - u_{st}$$

(see picture above)

$$\ddot{u}_d = \ddot{u}$$

for  $u_d$  the EOM is:

$$m \ddot{u}_d + k u_d = 0$$

and the solution to this EOM is:

$$u_d(t) = A \cdot \cos(\omega_n t) + B \cdot \sin(\omega_n t)$$

where  $A$  and  $B$  can be found based on the initial conditions.

@  $t=0$  (see picture above)

$$u_d(0) = -\frac{3mg}{4k} \quad \dot{u}_d(0) = 0 \text{ (starts from rest).}$$

and:

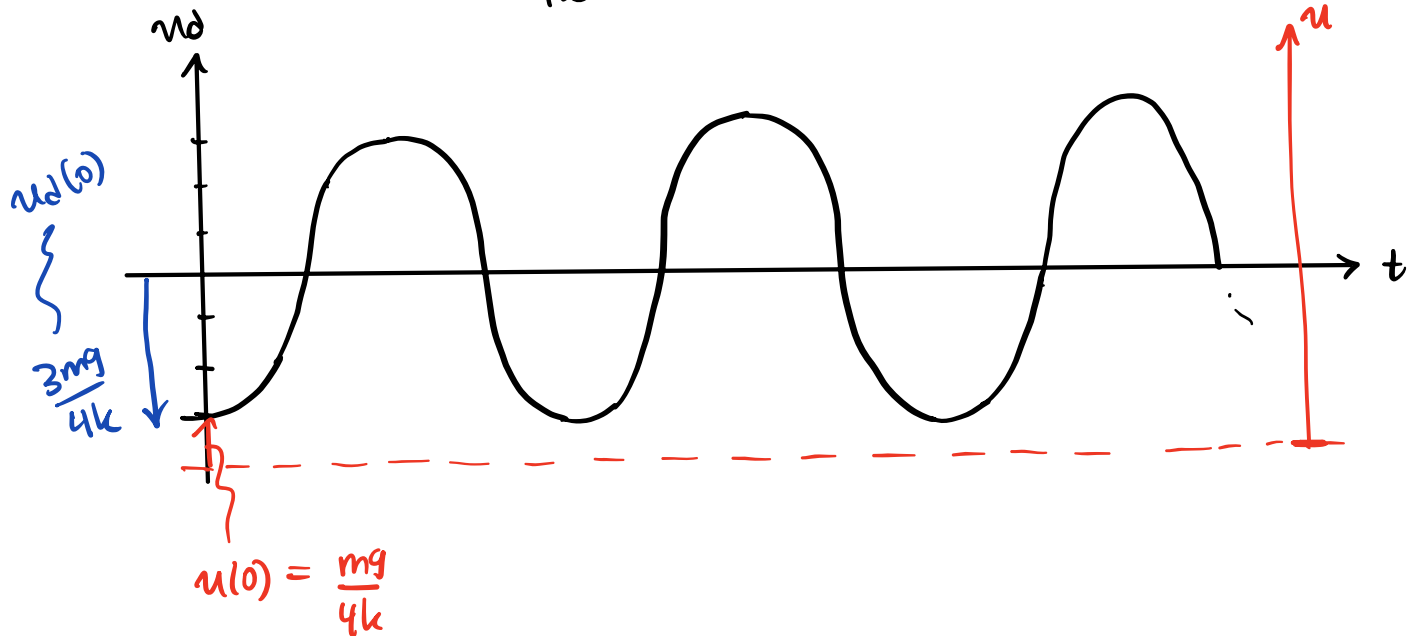
$$\dot{u}_d(t) = -A \cdot \omega_n \cdot \sin(\omega_n t) + B \cdot \omega_n \cdot \cos(\omega_n t)$$
$$\dot{u}_d(0) = 0 \Rightarrow B \cdot \omega_n \cdot (1) = 0 \Rightarrow \boxed{B = 0}$$

and  $u_d(0) = u_0 \Rightarrow A \cdot (1) = u_0 \Rightarrow \boxed{A = u_0}$

thus, the motion:

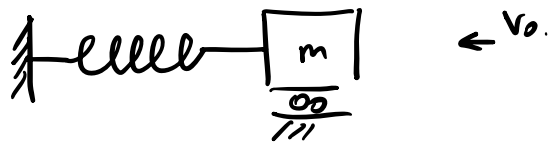
$$u_d(t) = -\frac{3mg}{4k} \cdot \cos(\omega_n t)$$

and  $u(t) = -\frac{3mg}{4k} \cdot \cos(\omega_n t) + \frac{mg}{k}$  (because  $u(t) = u_{st} + u_d(t)$ )



Problem # 2

$t \rightarrow u$



E.O.M:

$$m \ddot{u} + k u = 0$$

$$\Rightarrow u(t) = A \cdot \cos(\omega_n t) + B \cdot \sin(\omega_n t)$$

where  $u(0) = 0 \rightarrow A \cdot (1) + B \cdot (0) = 0 \Rightarrow A = 0$   
 $\dot{u}(0) = \dot{u}_0$

$$\hookrightarrow \dot{u}(t) = B \cdot \omega_n \cdot \cos(\omega_n t)$$

$$\dot{u}(0) = \dot{u}_0 \Rightarrow B \cdot \omega_n = \dot{u}_0 \Rightarrow B = \frac{\dot{u}_0}{\omega_n}$$

and  $u(t) = \frac{\dot{u}_0}{\omega_n} \cdot \sin(\omega_n t)$

So, need to get  $\dot{u}_0 \rightarrow$  conservation of linear momentum!  
 ( $m_b$  is the mass of the bullet).

$$\underbrace{m \cdot (0) + m_b \cdot v_0}_{\text{before impact}} = \underbrace{(m + m_b) \dot{u}_0}_{\text{after impact. Bullet now is part of the block.}}$$

$$\Rightarrow \dot{u}_0 = -\frac{m_b}{m + m_b} \cdot v_0$$

Plugging the values:  $\dot{u}_0 = -\frac{0.4}{20.4 \text{ lb}} \cdot v_0$  so  $\text{ft/sec} = -0.98 \text{ (ft/sec)}$   
 $= -11.76 \text{ (in/sec)}$

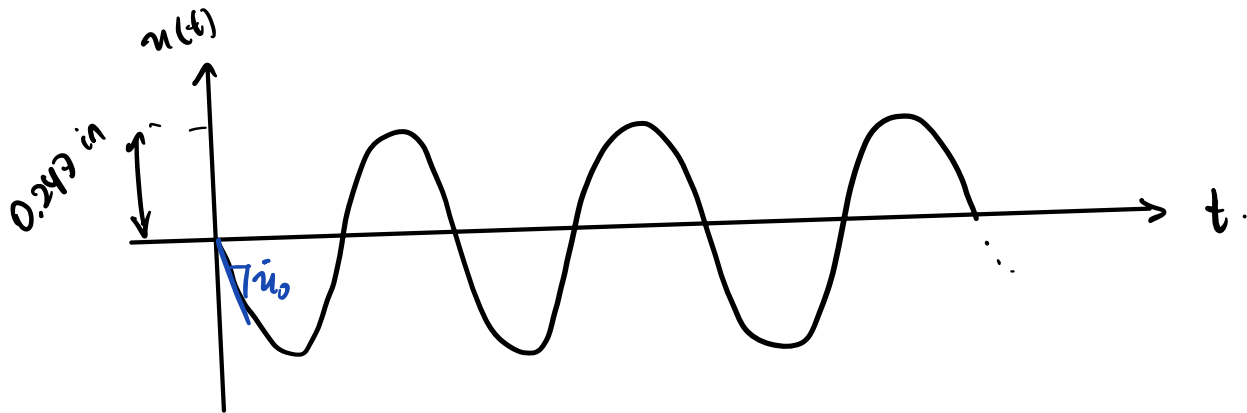
Now,  $\omega_n = \sqrt{k/M} \rightarrow$  here  $M = 20.4 \text{ lb}!$

$$= \sqrt{\frac{120 \text{ lb/in}}{20.4 \text{ lb}} \cdot 386 \frac{\text{in}}{\text{s}^2}} = 47.65 \text{ (rad/sec)}$$

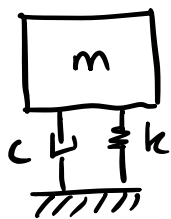
So:  $\frac{\dot{u}_0}{\omega_n} = \frac{11.76}{47.65} \left( \frac{\text{in/s}}{115} \right) = -0.247 \text{ (in)}$

and the motion is:

$$u(t) = 0.247 \cdot \sin(47.65t) \text{ (in)}.$$



### Problem # 3.



(a) we are given:

$$\delta_{st} = 2.1 \text{ (in)}$$

$$\delta_{st} = \frac{mg}{k} \Rightarrow k = \frac{mg}{\delta_{st}} = \frac{3,500 \text{ (lb)}}{2.1 \text{ (in)}} = 1667 \text{ (lb/in)}.$$

$$\boxed{k = 1667 \text{ (lb/in)}}$$

for damping  $c$ :  $c = 2m \cdot \omega_n \cdot \zeta$

$$\omega_n = \sqrt{\frac{k}{m}} = \sqrt{\frac{1667 \text{ (lb/in)} \cdot 386 \text{ (in/s}^2\text{)}}{3,500 \text{ (lb)}}} = 13.56 \text{ (rad/s)}$$

$$c = 2 \cdot 3500 \text{ (lb)} \cdot 13.56 \left( \frac{\text{rad}}{\text{s}} \right) \cdot 0.7 = 66,444 \text{ (lb/sec)}$$

↑  
mass pound.

however, if we want  $[c \cdot \dot{u}] = [\text{Force}]$  we can get  $c$  in  $\frac{\text{lb} \cdot \text{s}}{\text{in}}$ .

$$c = 66,444 \left( \frac{\text{lb}}{\text{s}^2} \right) \cdot \frac{1}{386} \cdot \left( \frac{\text{s}^2}{\text{in}} \right) = 172.13 \left( \frac{\text{lb} \cdot \text{s}}{\text{in}} \right).$$

(b) New mass, same stiffness, same  $c$ .

$$\omega_n^{\text{NEW}} = \sqrt{\frac{k}{M}} = \sqrt{\frac{1667 \text{ (lb/in)} \cdot 386 \text{ (in/s}^2\text{)}}{150.4 + 3500 \text{ (lb)}}} = 12.53 \text{ (rad/s)}$$

$$\text{now } c = 2m \omega_n \zeta \Rightarrow \zeta = \frac{c}{2m \omega_n}$$

$$\Rightarrow \zeta^{\text{NEW}} = \frac{c}{2M \cdot \omega_n^{\text{NEW}}} = \frac{172.13 \text{ (lb} \cdot \text{s/in)}}{2 \cdot (3500 + 150.4 \text{ lb}) \cdot 12.53 \text{ (1/s)}} \cdot 386 \text{ (in/s}^2\text{)}$$

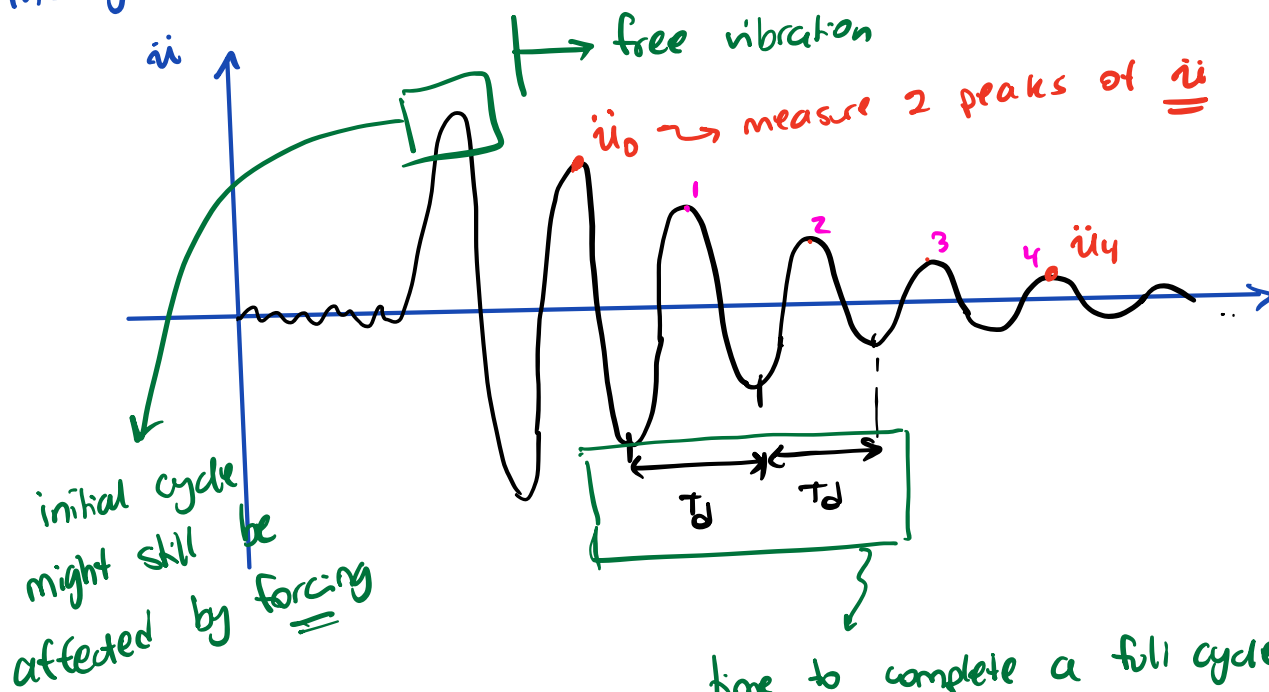
$$\Rightarrow \zeta^{\text{NEW}} = 0.647.$$

$$(c) \omega_n^{\text{NEW}} = 12.53 \text{ (rad/sec)}.$$

for dimensionless  $\zeta$ .

# Problem #4.

the general idea was to measure  $\ddot{u}(t)$  for free vibration.



From the two peaks of  $\ddot{u}$ , get  $\zeta$  using log-decrement:

$$\ln \left( \frac{\ddot{u}_i}{\ddot{u}_{i+j}} \right) = 2\pi\zeta j \rightarrow \text{for my example plot:}$$

$$\ln \left( \frac{\ddot{u}_0}{\ddot{u}_4} \right) = 8\pi\zeta \Rightarrow \zeta = \frac{\ln(\ddot{u}_0/\ddot{u}_4)}{8\pi}.$$