

Beyond Shallow Embeddings of Knowledge Graphs

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The ImageNet Moment for KGs



Wikidata: 100M nodes

Embs: [100M, dim] ?

 PyTorch BigGraph

~200 GB

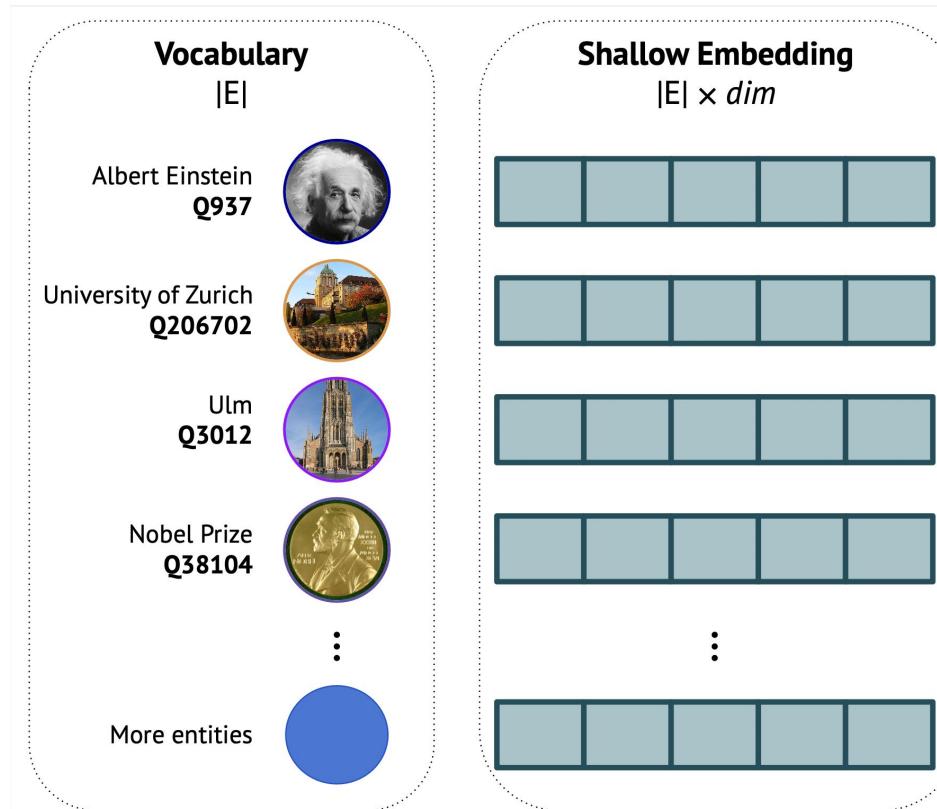


Graph ML

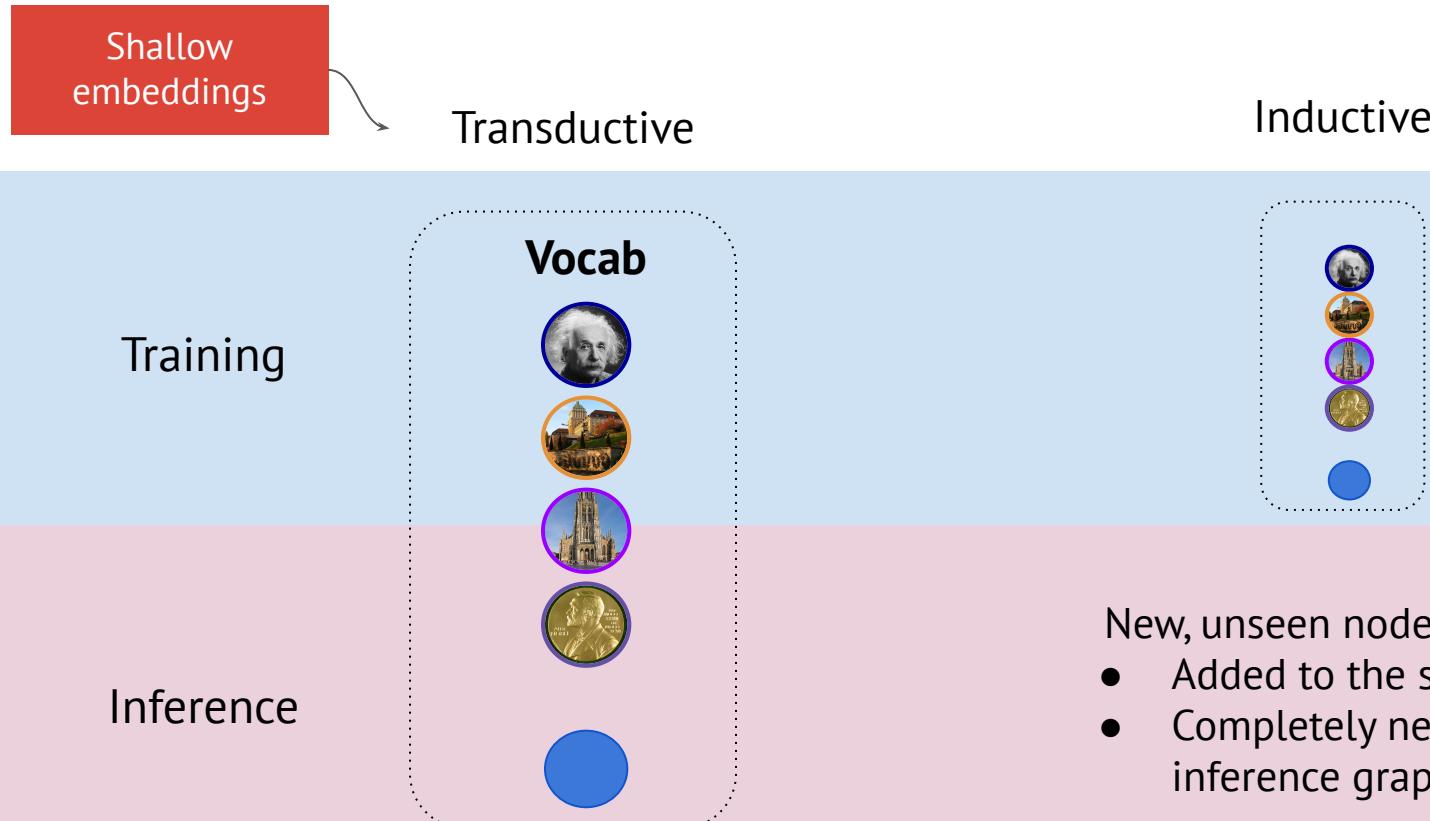
NLP

Vision

Shallow Embedding



Transductive vs Inductive



- New, unseen nodes (entities)
- Added to the seen graph
- Completely new inference graph

OGB WikiKG: Just 2.5M nodes

Leaderboard for [ogbl-wikikg2](#)

The MRR score on the test and validation sets. The higher, the better.

Package: $\geq 1.2.4$

Deprecated [ogbl-wikikg](#) leaderboard can be found [here](#).

BERT-Large is $\sim 340M$ params

Rank	Method	Test MRR	Validation MRR	Contact	References	#Params	Hardware	Date
1	PairRE (200dim)	0.5208 ± 0.0027	0.5423 ± 0.0020	Linlin Chao	Paper , Code	500,334,800	Tesla P100 (16GB GPU)	Jan 28, 2021
2	RotatE (250dim)	0.4332 ± 0.0025	0.4353 ± 0.0028	Hongyu Ren – OGB team	Paper , Code	1,250,435,750	Quadro RTX 8000 (45GB GPU)	Jan 23, 2021
3	TransE (500dim)	0.4256 ± 0.0030	0.4272 ± 0.0030	Hongyu Ren – OGB team	Paper , Code	1,250,569,500	Quadro RTX 8000 (45GB GPU)	Jan 23, 2021
4	ComplEx (250dim)	0.4027 ± 0.0027	0.3759 ± 0.0016	Hongyu Ren – OGB team	Paper , Code	1,250,569,500	Quadro RTX 8000 (45GB GPU)	Jan 23, 2021

BERT (340M params) - disruption in NLP 
KG embs (>1B params) - 😬

Life beyond shallow embedding?

Do we really need to learn & store the whole **shallow** embedding matrix $|E| \times dim$

Trying to fit a $100M \times 200$ tensor on a Tesla V100 ->



Life beyond shallow embedding?

Neural Bellman-Ford
Nets
[1]

NodePiece
[2]

- [1] Zhu et al. Neural Bellman-Ford Networks: A General Graph Neural Network Framework for Link Prediction. NeurIPS'21
- [2] Galkin et al. NodePiece: Compositional and Parameter-Efficient Representations for Large Knowledge Graphs. arxiv:2021

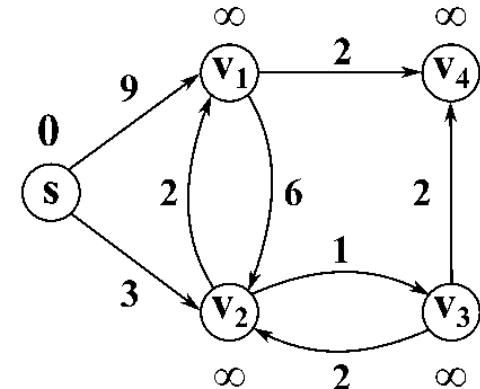
Neural Bellman-Ford Nets

Vanilla Bellman-Ford for shortest paths

```

for  $v \in V$ 
    do  $d[v] \leftarrow +\infty$ 
 $d[s] \leftarrow 0$ 
for  $i \leftarrow 1$  to  $|V| - 1$ 
    do for  $(u, v) \in E$ 
        if  $d[v] > d[u] + w(u, v)$ 
            then  $d[v] \leftarrow d[u] + w(u, v)$ 
return  $d$ 

```



Source: Wikipedia

$$d[v] = \min(d[u] + w(u, v), d[v]) \quad \text{-- vanilla Bellman-Ford iteration}$$

Generalized Bellman-Ford

$$d[v] = \min(d[u] + w(u, v), d[v])$$

- ↓
- Generalize $+$ to any operator \otimes
 - Generalize \min to any operator \oplus
 - \oplus and \otimes satisfy a **semiring** system



$$\mathbf{h}_q^{(0)}(u, v) \leftarrow \mathbb{1}_q(u = v)$$

Boundary

Generalized Bellman-Ford

$$\mathbf{h}_q^{(t)}(u, v) \leftarrow \left(\bigoplus_{(x,r,v) \in \mathcal{E}(v)} \mathbf{h}_q^{(t-1)}(u, x) \otimes \mathbf{w}_q(x, r, v) \right) \oplus \mathbf{h}_q^{(0)}(u, v)$$

Parameterize -> Neural Bellman-Ford

$$\mathbf{h}_q^{(0)}(u, v) \leftarrow \mathbb{1}_q(u = v)$$

Boundary

Generalized Bellman-Ford

$$\mathbf{h}_q^{(t)}(u, v) \leftarrow \left(\bigoplus_{(x, r, v) \in \mathcal{E}(v)} \mathbf{h}_q^{(t-1)}(u, x) \otimes \mathbf{w}_q(x, r, v) \right) \oplus \mathbf{h}_q^{(0)}(u, v)$$

↓

Parameterizing those operators we recover a relational GNN! 

$$\mathbf{h}_v^{(0)} \leftarrow \text{INDICATOR}(u, v, q)$$

$$\mathbf{h}_v^{(t)} \leftarrow \text{AGGREGATE} \left(\left\{ \text{MESSAGE} \left(\mathbf{h}_x^{(t-1)}, \mathbf{w}_q(x, r, v) \right) \middle| (x, r, v) \in \mathcal{E}(v) \right\} \cup \left\{ \mathbf{h}_v^{(0)} \right\} \right)$$

NBF recovers classical graph algorithms

$$\mathbf{h}_v^{(0)} \leftarrow \text{INDICATOR}(u, v, q)$$

$$\mathbf{h}_v^{(t)} \leftarrow \text{AGGREGATE} \left(\left\{ \text{MESSAGE} \left(\mathbf{h}_x^{(t-1)}, \mathbf{w}_q(x, r, v) \right) \middle| (x, r, v) \in \mathcal{E}(v) \right\} \cup \left\{ \mathbf{h}_v^{(0)} \right\} \right)$$

Table 1: Comparison of operators in NBFNet and other methods from the view of path formulation.

Class	Method	MESSAGE $\mathbf{w}_q(e_i) \otimes \mathbf{w}_q(e_j)$	AGGREGATE $\mathbf{h}_q(P_i) \oplus \mathbf{h}_q(P_j)$	INDICATOR $\textcircled{0}_q, \textcircled{1}_q$	Edge Representation $\mathbf{w}_q(e = (u, v))$
Traditional Link Prediction	Katz Index [25]	$\mathbf{w}_q(e_i) \times \mathbf{w}_q(e_j)$	$\mathbf{h}_q(P_i) + \mathbf{h}_q(P_j)$	0, 1	$\frac{\beta w_e}{\sum_{v' \in \mathcal{N}(u)} w_{uv'}}$
	Personalized PageRank [37]	$\mathbf{w}_q(e_i) \times \mathbf{w}_q(e_j)$	$\mathbf{h}_q(P_i) + \mathbf{h}_q(P_j)$	0, 1	
	Graph Distance [32]	$\mathbf{w}_q(e_i) + \mathbf{w}_q(e_j)$	$\min(\mathbf{h}_q(P_i), \mathbf{h}_q(P_j))$	$+\infty, 0$	
Graph Theory Algorithms	Widest Path [3]	$\min(\mathbf{w}_q(e_i), \mathbf{w}_q(e_j))$	$\max(\mathbf{h}_q(P_i), \mathbf{h}_q(P_j))$	$-\infty, +\infty$	w_e
	Most Reliable Path [3]	$\mathbf{w}_q(e_i) \times \mathbf{w}_q(e_j)$	$\max(\mathbf{h}_q(P_i), \mathbf{h}_q(P_j))$	0, 1	w_e
Logic Rules	NeuralLP [63] / DRUM [41]	$\mathbf{w}_q(e_i) \times \mathbf{w}_q(e_j)$	$\mathbf{h}_q(P_i) + \mathbf{h}_q(P_j)$	0, 1	Weights learned by LSTM [21]
NBFNet	Relational operators of knowledge graph embeddings [5, 62, 47]	Learned set aggregators [7]	Learned indicator functions	Learned relation embeddings	

NBFNet: No Trainable Entity Embeddings

$$\mathbf{h}_v^{(0)} \leftarrow \text{INDICATOR}(u, v, q)$$

- Initial node representations are initialized as a sum of adjacent relations
- Only one learnable bias (indicator) per node: $|E| \times \text{dim} \rightarrow |E| \times 1$
- Only relations are trained -> **inductive out-of-the-box!**

$$\mathbf{h}_v^{(t)} \leftarrow \text{AGGREGATE} \left(\left\{ \text{MESSAGE} \left(\mathbf{h}_x^{(t-1)}, \mathbf{w}_q(x, r, v) \right) \middle| (x, r, v) \in \mathcal{E}(v) \right\} \cup \left\{ \mathbf{h}_v^{(0)} \right\} \right)$$

- Standard message passing relational GNN framework
- Message: any pairwise function (TransE, DistMult, RotatE, etc)
- Final node representation: $\text{MLP}([\text{layer1}, \text{layer2}, \dots \text{layerK}])$

NBFNet: No Trainable Entity Embeddings

Table 8: Number of parameters in NBFNet. The number of parameters only grows with the number of relations $|\mathcal{R}|$, rather than the number of nodes $|\mathcal{V}|$ or edges $|\mathcal{E}|$. For FB15k-237 augmented with flipped triplets, $|\mathcal{R}|$ is 474. Our best configuration uses $T = 6$, $d = 32$ and hidden dimension $m = 128$. Note 2 NBFNet instances are required to model $p(v|u, q)$ and $p(u|v, q^{-1})$ respectively.

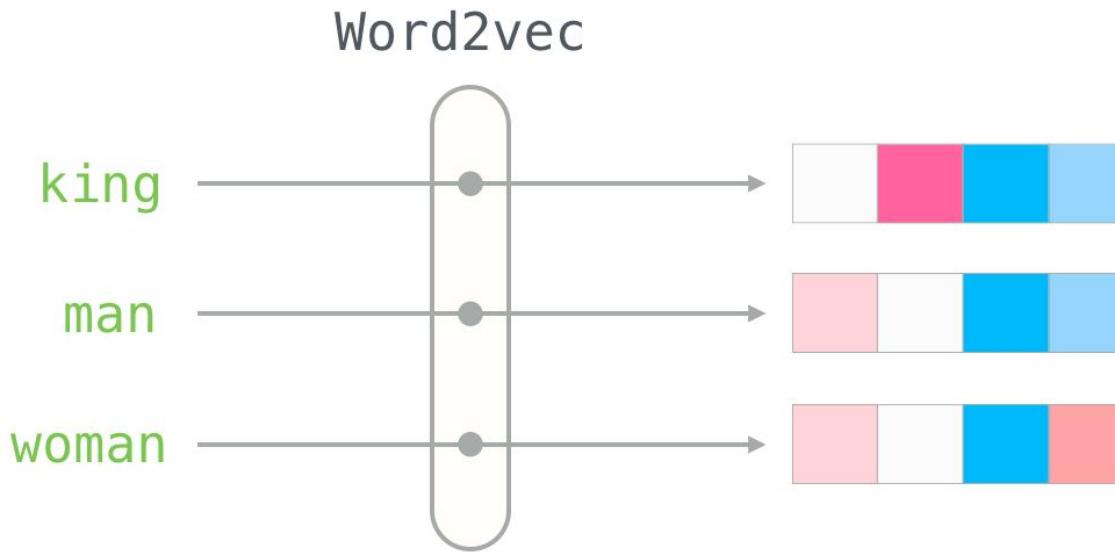
	#Parameter	
	Analytic Formula	FB15k-237
INDICATOR	$ \mathcal{R} d$	15,168
MESSAGE	$ \mathcal{R} Td$	91,008
AGGREGATE	$T(13d^2 + d)$	80,064
$f(\cdot)$	$m(d + 1) + m + 1$	4,353
Total		190,593
2 NBFNet instances		381,186

SOTA RotatE
30M params

New Transductive Link Prediction SOTA

Model	# Params	FB15k-237		WN18RR	
		MRR	H@10	MRR	H@10
RotatE	30 M	0.338	0.553	0.476	0.571
NBFNet	381 K	0.378	0.563	0.547	0.661

Back to 2014



Unseen words = [OOV] (out-of-vocabulary)

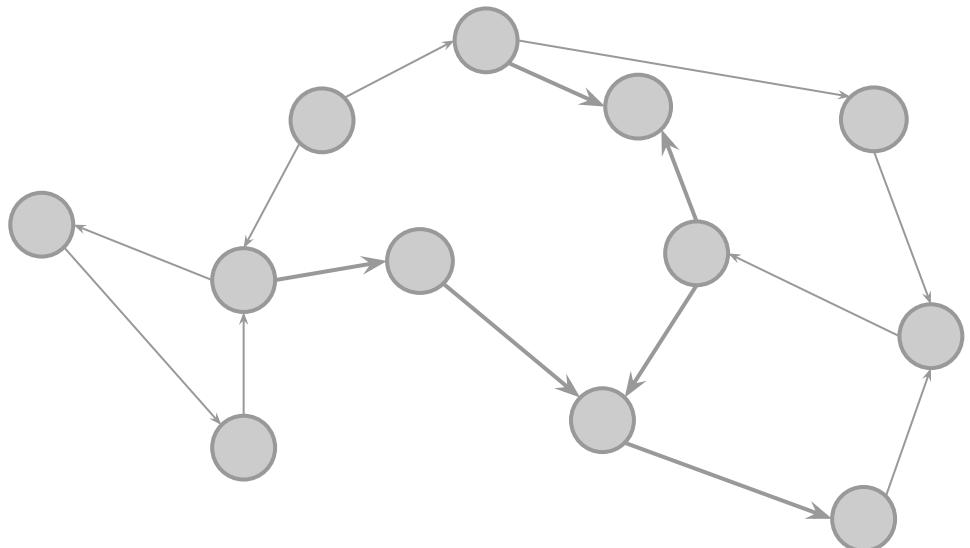
■ Byte-Pair Encoding / WordPiece

"I love tacos, apples, and tea!"

i	love	tacos	,	app	##les	,	and	t	##e	##a	!
6	7	8	5	10	11	5	9	30	41	37	3

- Fixed-size vocab of subword units (30-50K)
- We can tokenize any unseen word

■ Tokenization + Graphs?



If nodes in a graph are
"**words**",
can we design a fixed-size
vocab of
"**sub-word**" units?

Tokenizing KGs

BERT-Large
(340M)

NodePiece

KG Embedding
(1250M)

Encoder
(Transformer)
~300M

Vocabulary
30K x 1024d

Encoder

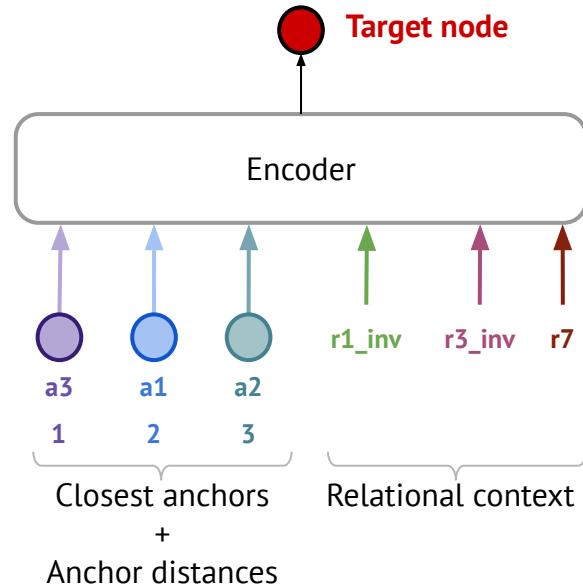
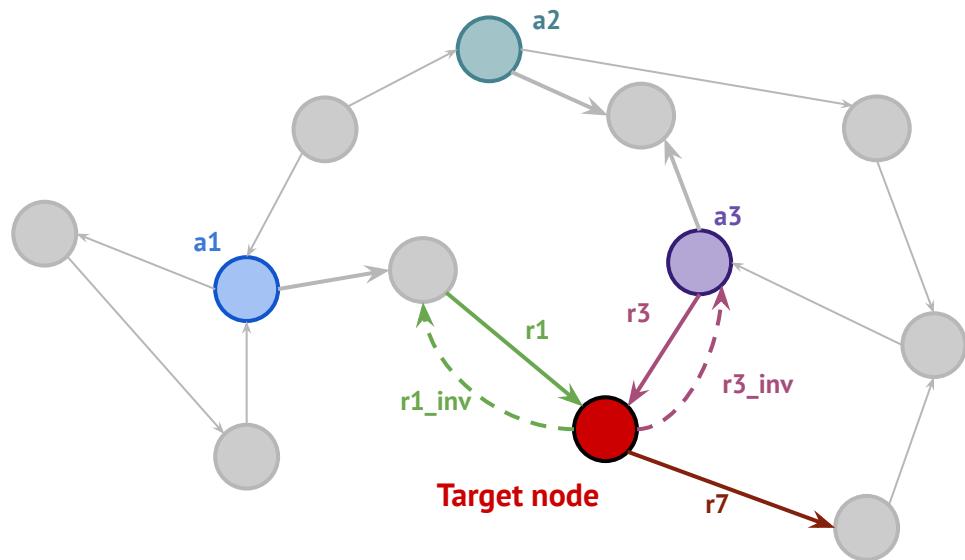
Vocab: K anchors,
All relations

Vocabulary
2.5M x 500d

Tokenizing KGs

	Shallow embedding, only known words, otherwise OOV	Compositional representations, subword units
Language	Word2vec, GloVe	Byte-Pair Encoding, WordPiece
Graphs	All KG embedding algorithms (TransE, etc)	NodePiece

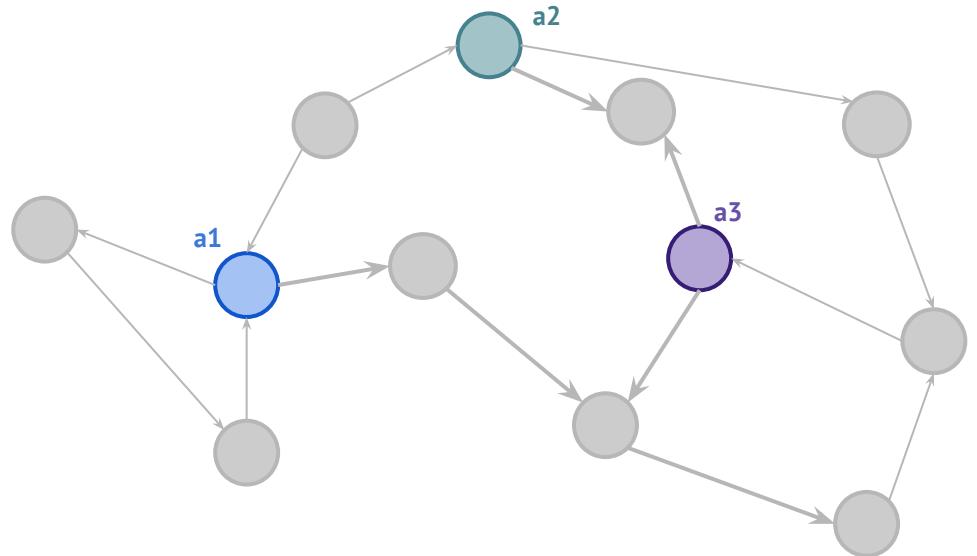
■ NodePiece - “*subword units*” for KGs



Vocabulary = Anchors + Relation types

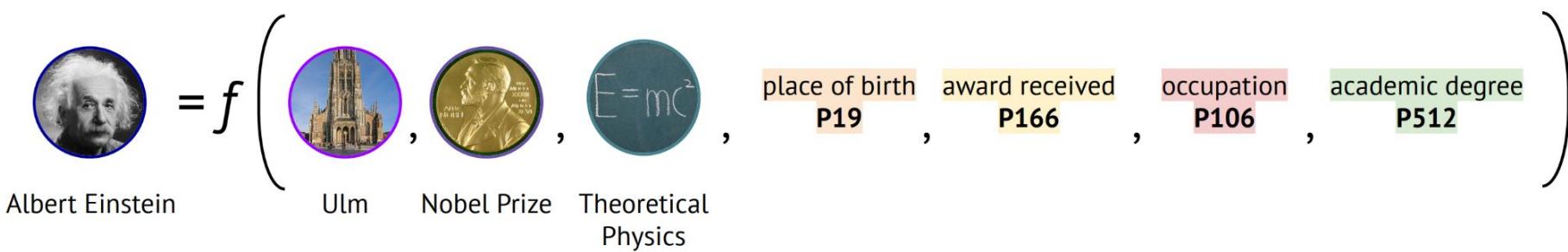
Inductive out-of-the-box: unseen nodes are “tokenized” with the same Vocab

Anchor Node Selection



Current strategy:
40% top degrees
40% top PageRank
20% random

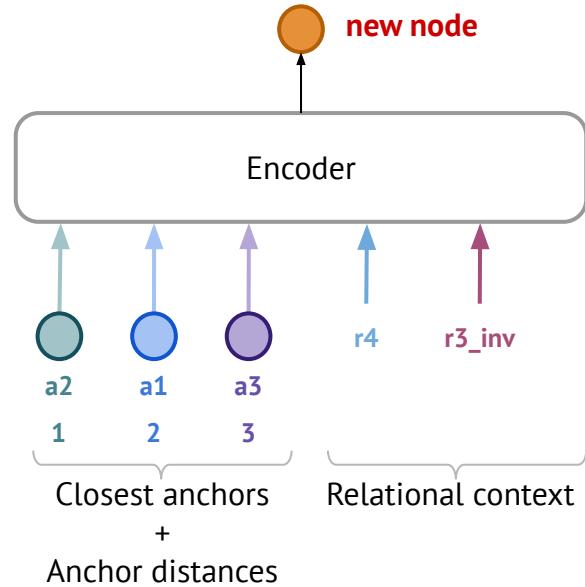
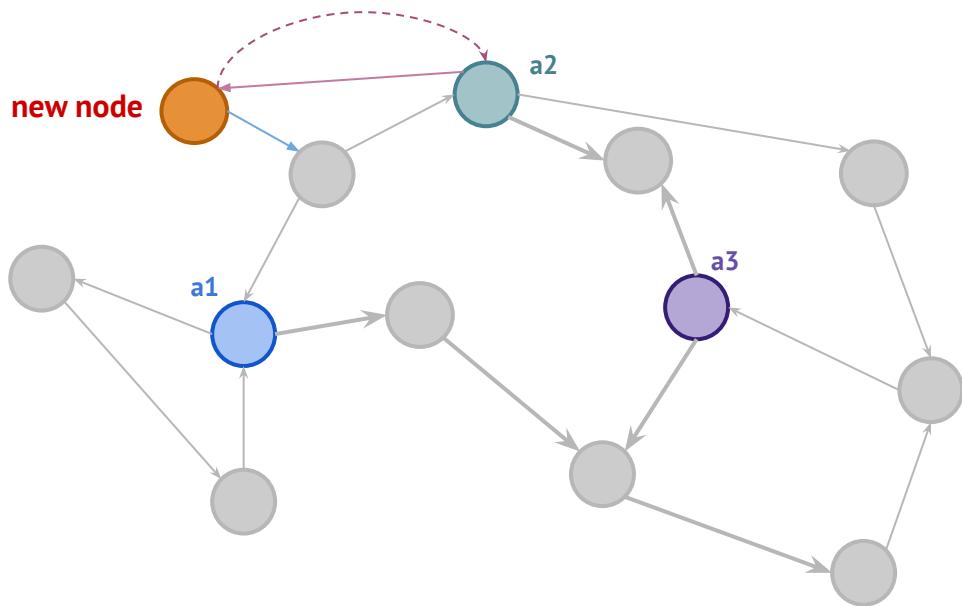
Tokenizing Einstein



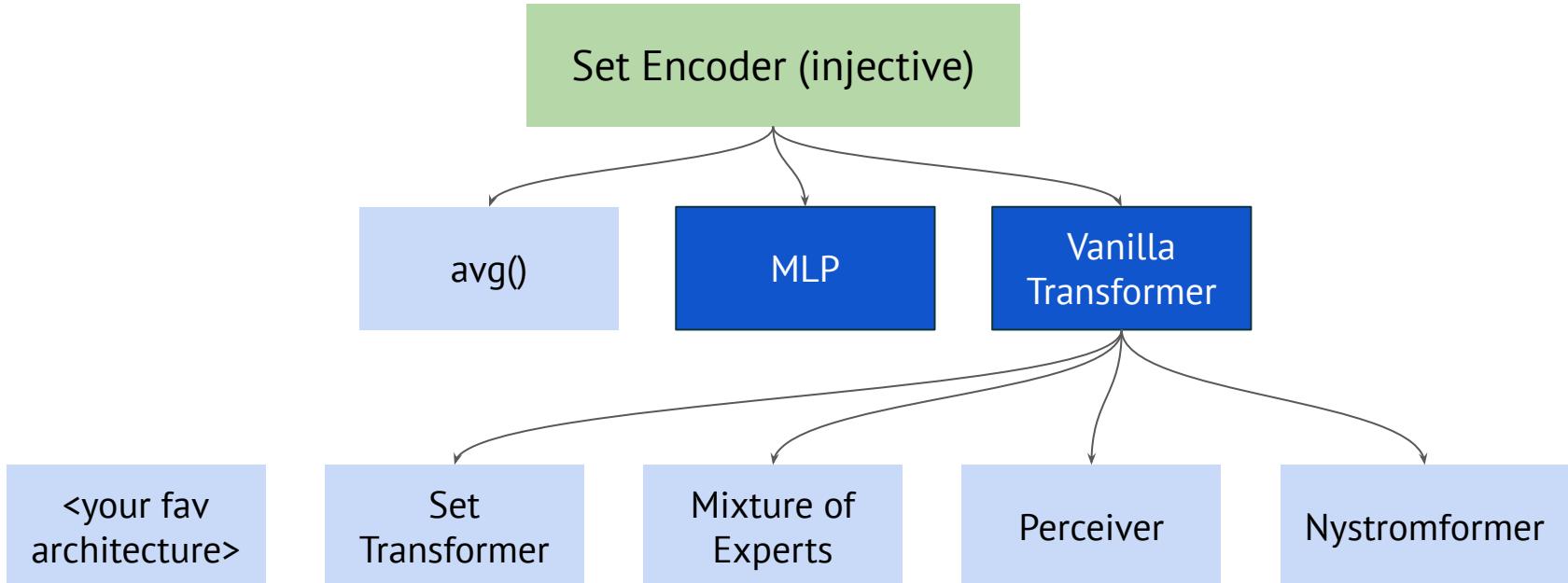
3 nearest anchors

4 unique outgoing relations in the context

Unseen Node Tokenization



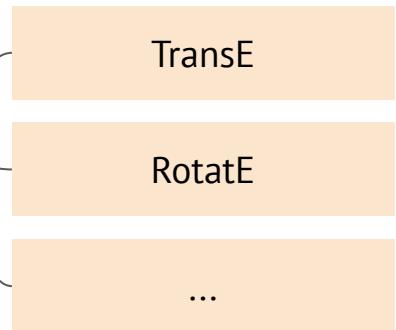
Set Encoder



Tasks

Link Prediction / Relation Prediction

$score(h, r, t)$



Any GNN works, too!

$$\begin{bmatrix} h_1 \\ h_2 \\ \vdots \\ h_N \end{bmatrix} + \text{GNN}$$

Transductive Link Prediction

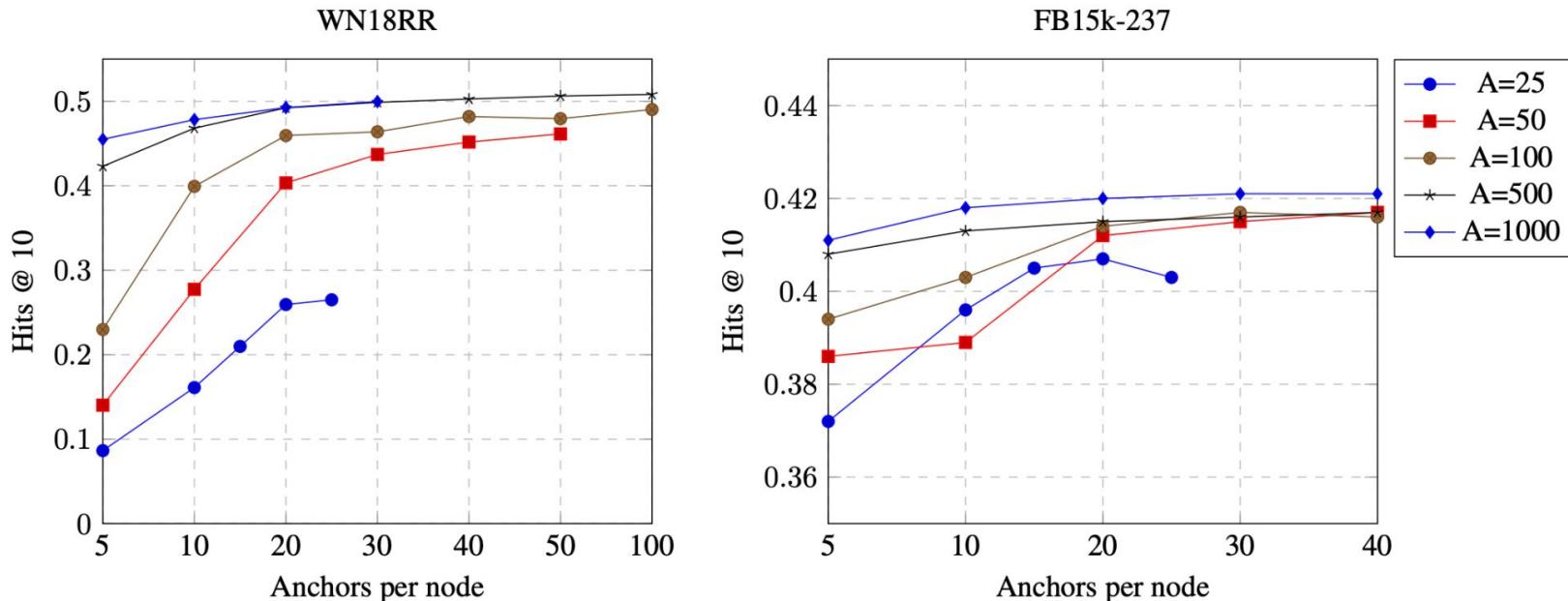
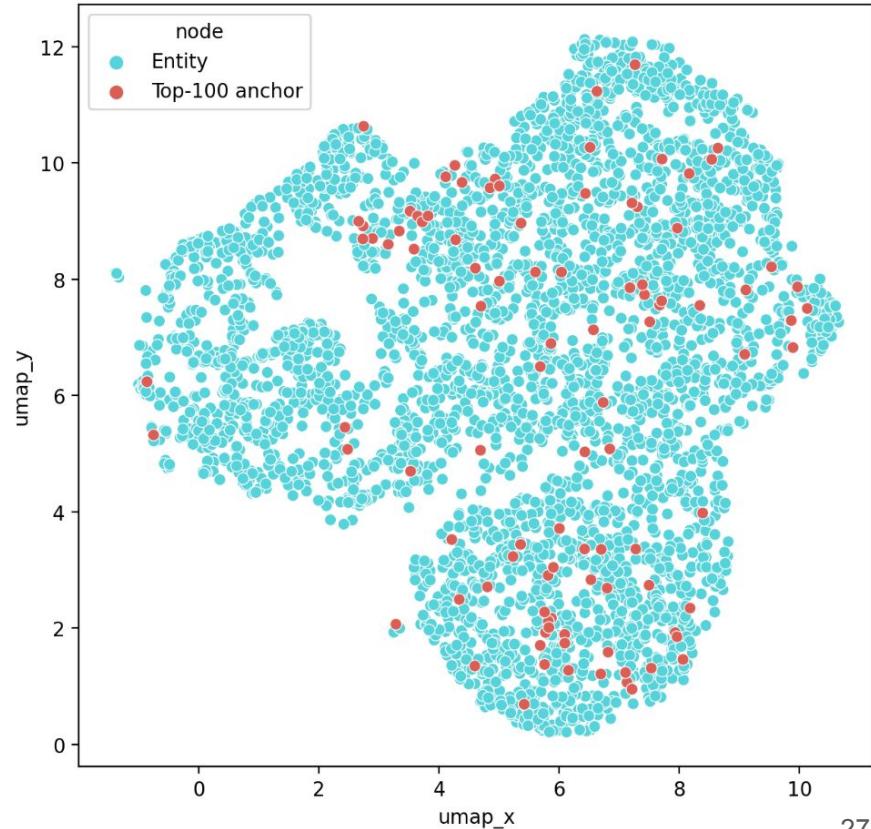
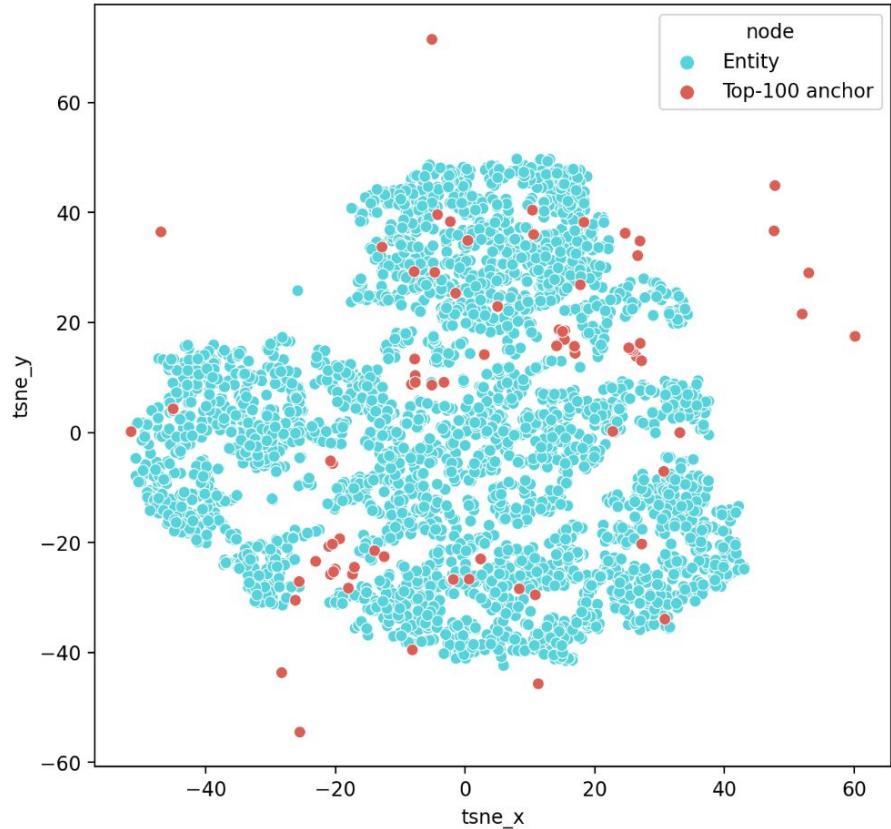
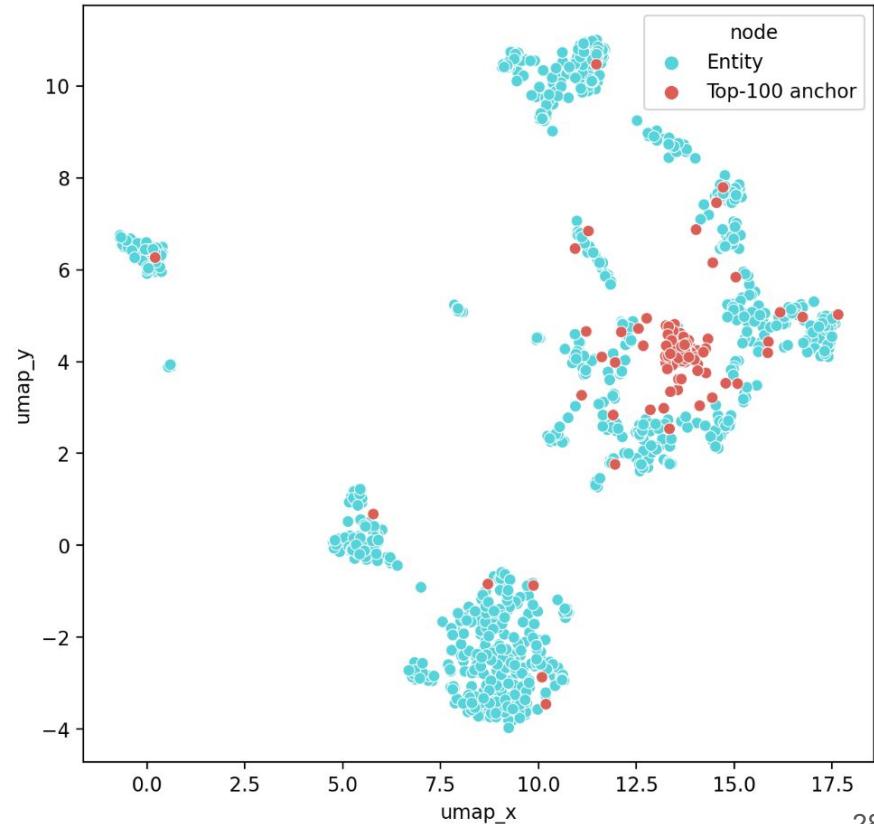
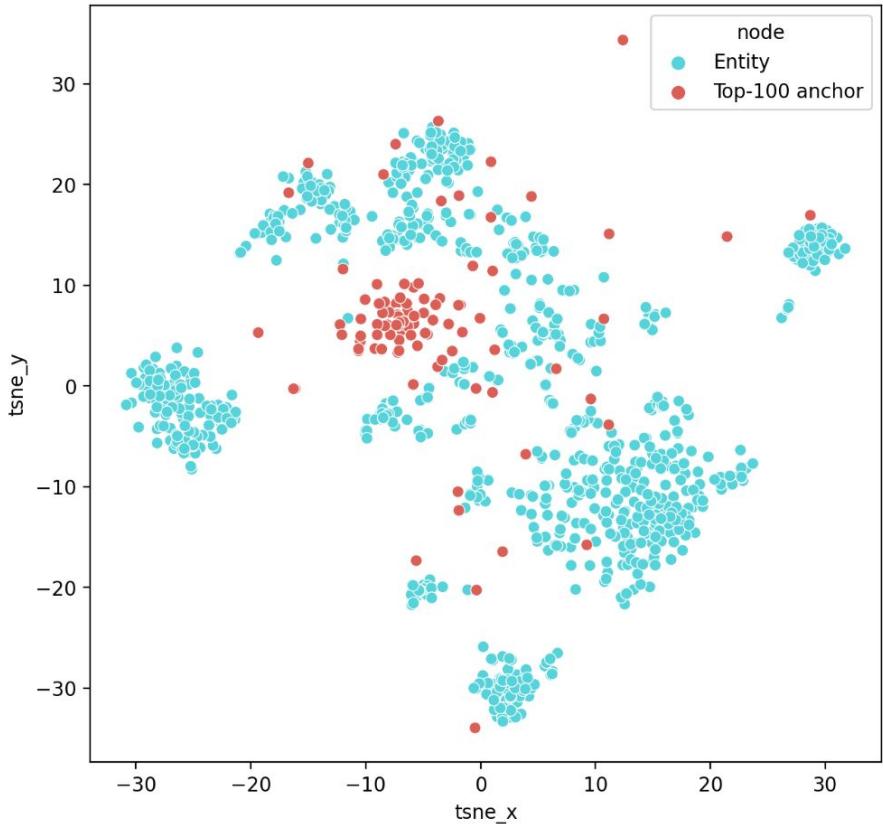


Figure 2: Combinations of total anchors A and anchors per node. Denser FB15k-237 saturates faster on smaller A while sparse WN18RR saturates at around 500 anchors.

WN18RR anchors + entities



FB15k-237 anchors + entities



■ OGB WikiKG 2 : New SOTA

Leaderboard for ogbl-wikikg2

The MRR score on the test and validation sets. The higher, the better.

Package: $\geq 1.2.4$

Deprecated [ogbl-wikikg](#) leaderboard can be found [here](#).

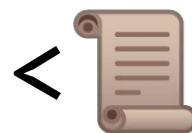


Validation								
Rank	Method	Test MRR	MRR	Contact	References	#Params	Hardware	Date
1	NodePiece + AutoSF	0.5703 ± 0.0035	0.5806 ± 0.0047	Mikhail Galkin (Mila)	Paper, Code	6,860,602	Tesla V100 (32 GB)	Jul 17, 2021
2	AutoSF	0.5458 ± 0.0052	0.5510 ± 0.0063	Yongqi Zhang (4Paradigm)	Paper, Code	500,227,800	Quadro RTX 8000 (45GB GPU)	Apr 2, 2021
3	PairRE (200dim)	0.5208 ± 0.0027	0.5423 ± 0.0020	Linlin Chao	Paper, Code	500,334,800	Tesla P100 (16GB GPU)	Jan 28, 2021
4	RotatE (250dim)	0.4332 ± 0.0025	0.4353 ± 0.0028	Hongyu Ren – OGB team	Paper, Code	1,250,435,750	Quadro RTX 8000 (45GB GPU)	Jan 23, 2021
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~100x
smaller



> Neural Bellman-Ford Nets



< NodePiece <

Contact



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Socials



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