

# What is a Knowledge Graph?



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# Outline

- On the definition & representation
- Part I: Symbolic
  - Logical Foundations
  - Databases & Querying
  - KG Construction
- Part II: Vector
  - NLP
  - KG Embeddings
  - Graph ML

# On the definition of a Knowledge Graph

Given entities E, relations R, KG is a directed multi-relational graph G that comprises triples (s, p, o)

$$\mathcal{G} \subseteq \mathcal{E} \times \mathcal{R} \times \mathcal{E}$$
$$(s, p, o) \in \mathcal{G}$$

“Abstract schema and instances”

- \* describes entities and relations
- \* defines a schema
- \* interrelating arbitrary entities
- \* various topical domains

“Every RDF / LPG / RDF\* graph is a knowledge graph”

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- \* various topical domains

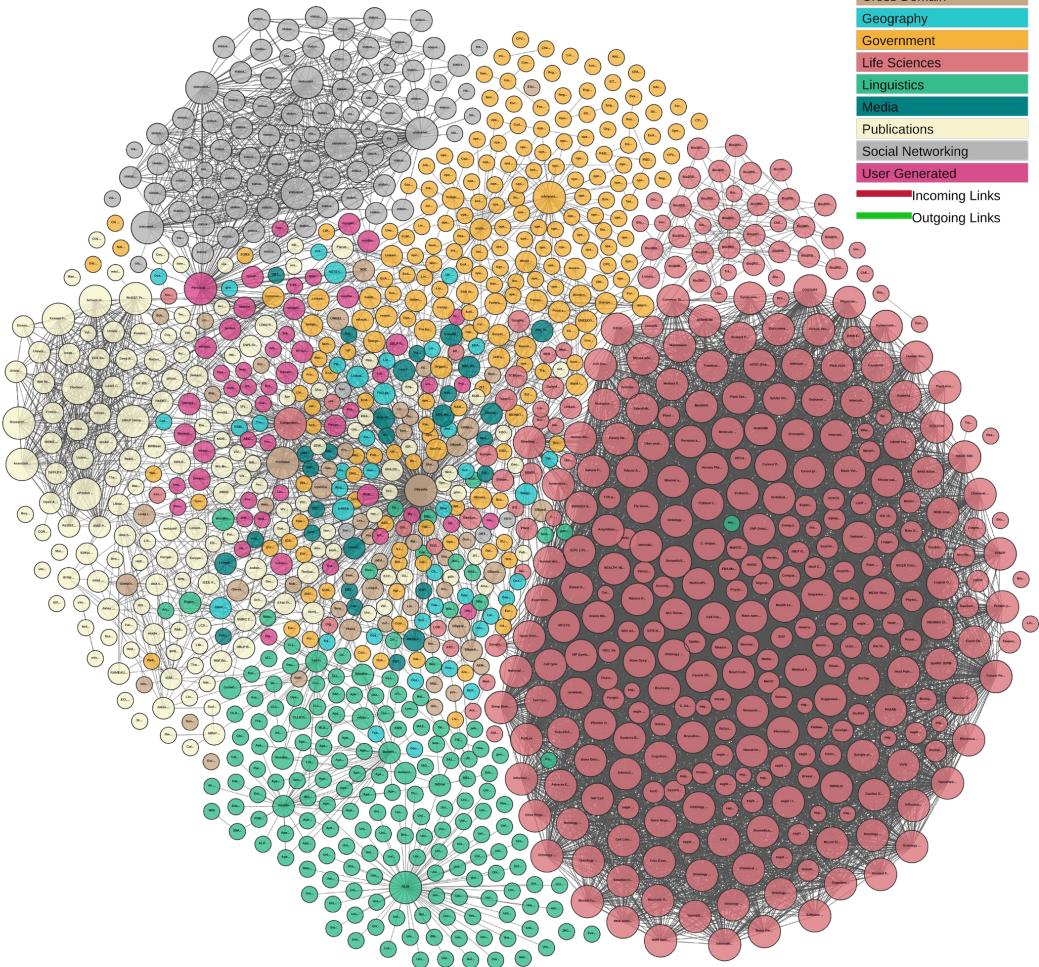
“Every RDF / LPG / RDF\* graph is a knowledge graph”

Graph-structured world model

# World models?

Entities and  
relations define our  
**domain of discourse**

How to encode it?



Source: <https://lod-cloud.net/>

# On representation of Knowledge Graphs



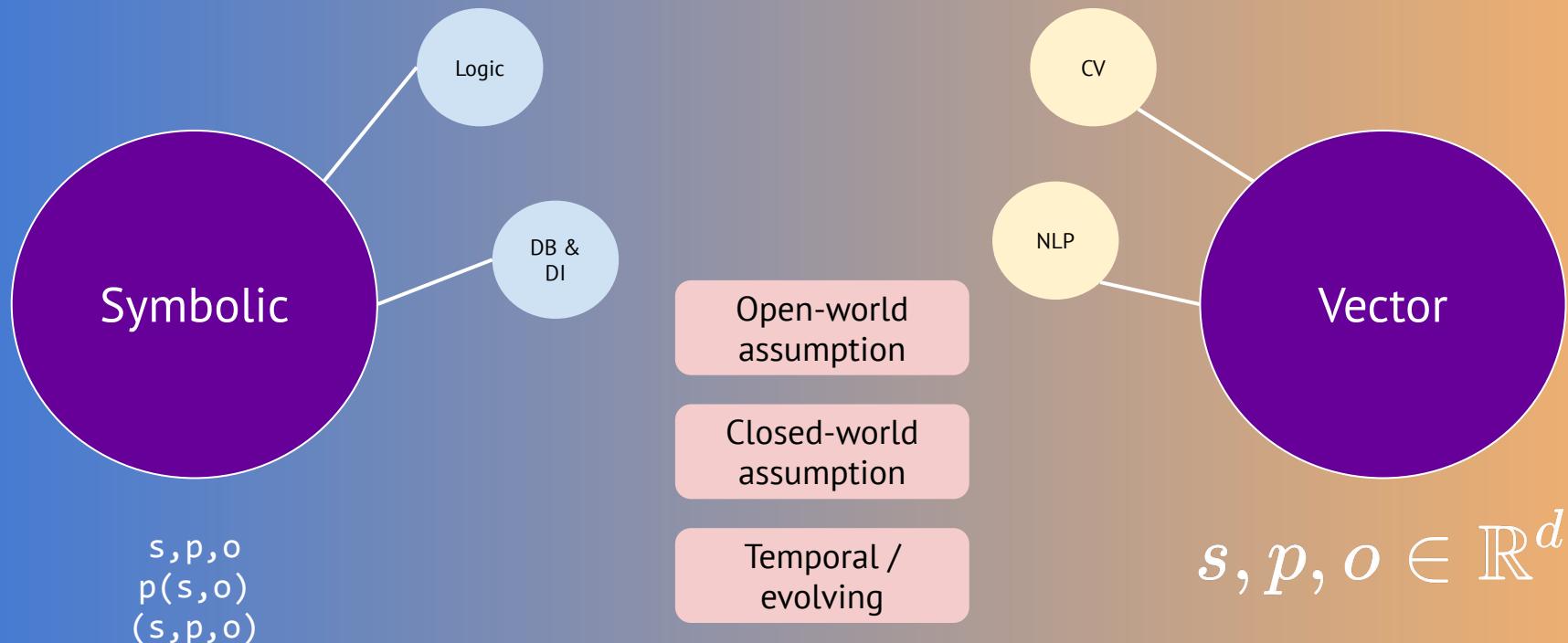
Symbolic

$s, p, o$   
 $p(s, o)$   
 $(s, p, o)$

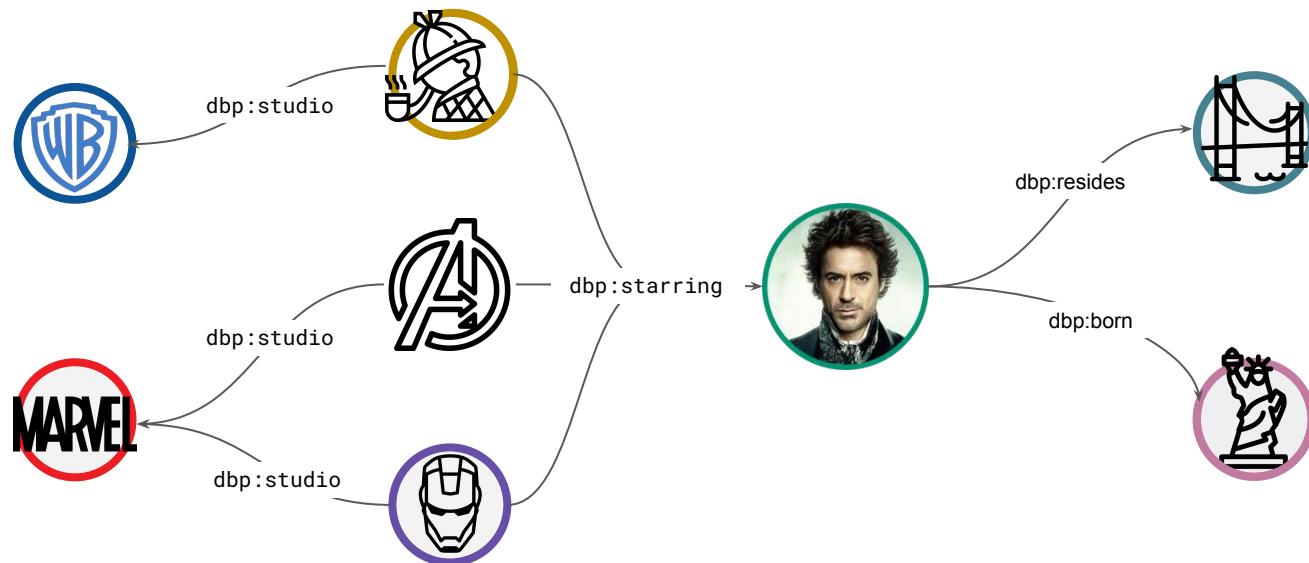
Vector

$s, p, o \in \mathbb{R}^d$

# On representation of Knowledge Graphs



# Symbolic: Triples



RDJ  
RDJ

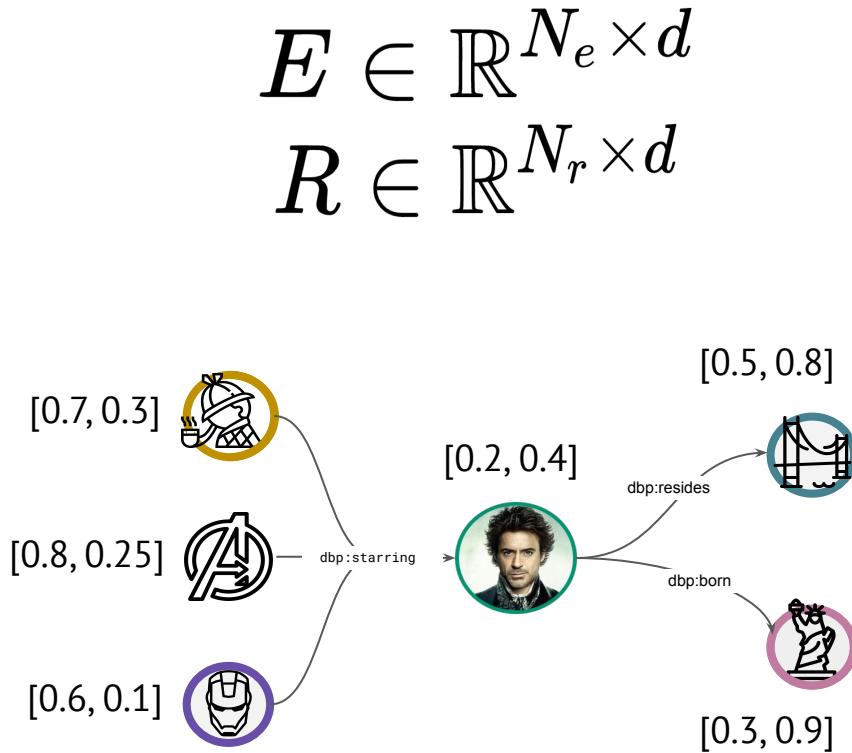
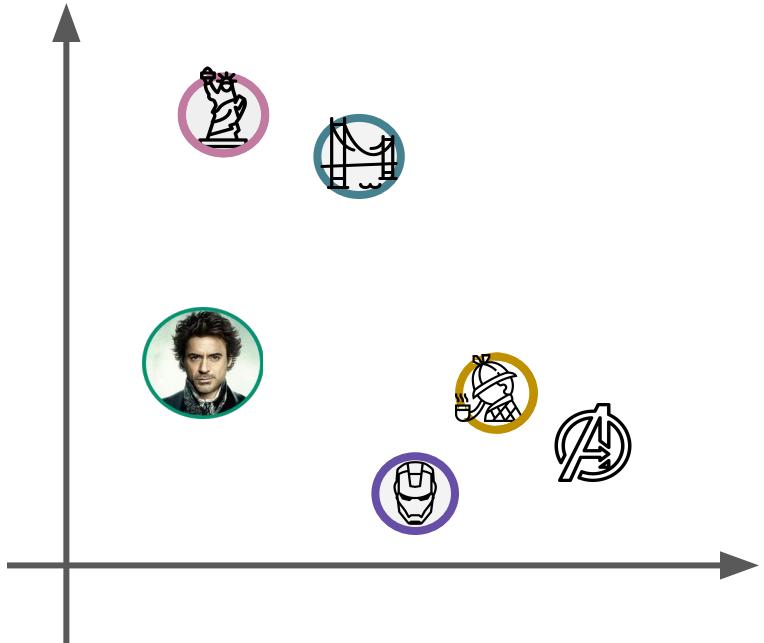
Sherlock\_Holmes  
Sherlock\_Holmes

dbp:resides SF .  
dbp:born NY .  
dbp:studio WB .  
dbp:starring RDJ .

Avengers  
Avengers  
Iron\_Man  
Iron\_Man

dbp:studio Marvel .  
dbp:starring RDJ .  
dbp:studio Marvel .  
dbp:starring RDJ .

# Vector: Embeddings



# **Part I: Symbolic**

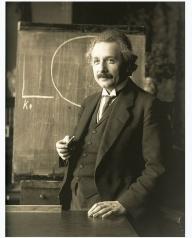
# History



2007



- Derived from parsing Wikipedia infoboxes
- 6B+ facts
- The first de-facto standard for creating and publishing KGs



Albert Einstein

Einstein in 1921, by Ferdinand Schmutzler

**Born** 14 March 1879  
Ulm, Kingdom of Württemberg, German Empire

**Died** 18 April 1955 (aged 76)  
Princeton, New Jersey, U.S.

**Citizenship** Kingdom of Württemberg, part of the German Empire (1879–1890)<sup>[note 1]</sup> Stateless (1896–1901) Switzerland (1901–1955) Austria, part of the Austro-Hungarian Empire (1911–1912) Kingdom of Prussia, part of the German Empire (1914–1918)<sup>[note 1]</sup> Free State of Prussia (Weimar Republic, 1918–1933)

# History



yago  
select knowledge



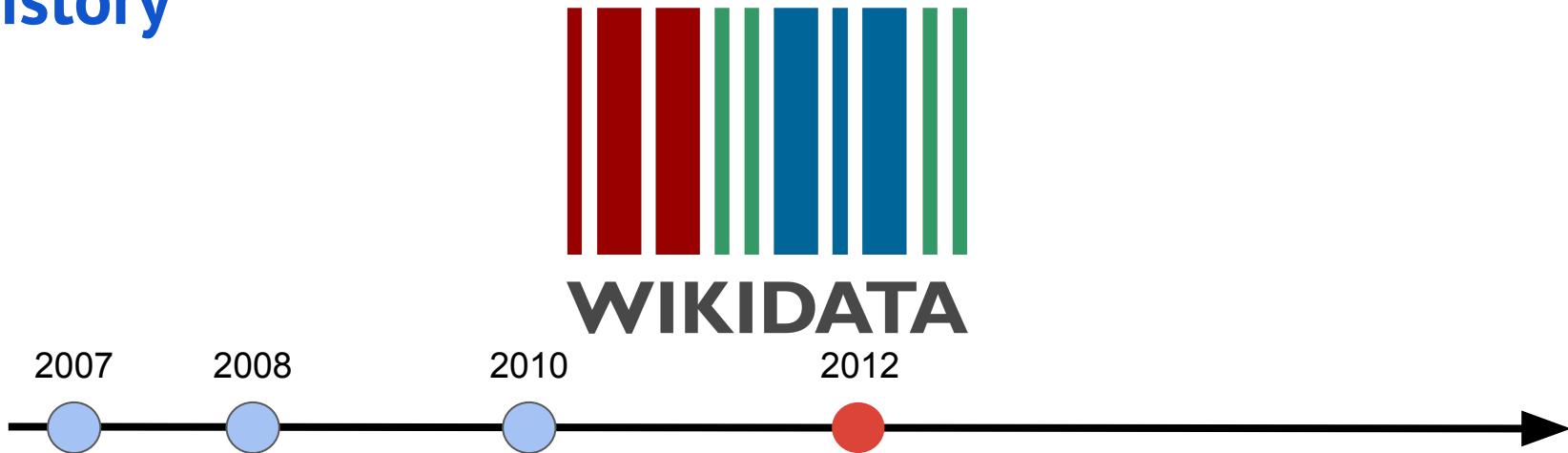
- Wikipedia + categories from WordNet
- 120M+ facts

# History



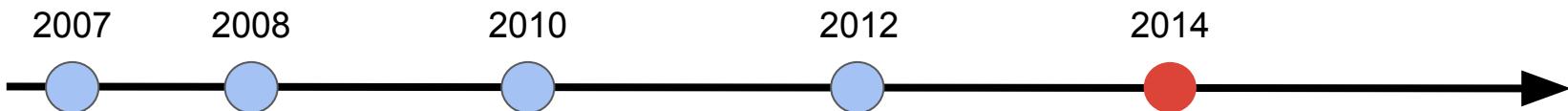
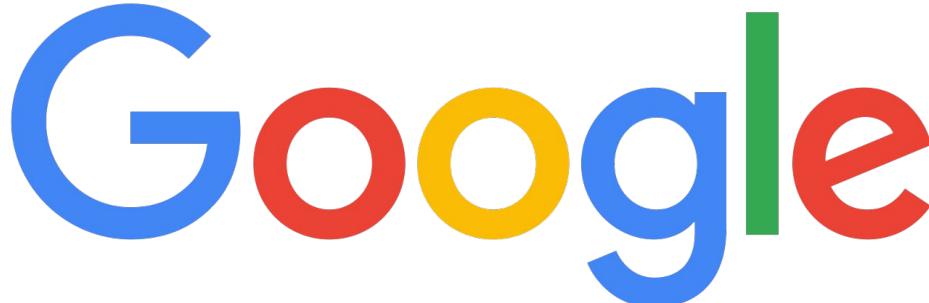
- NELL - Never Ending Language Learner
- Automatic facts from parsing web pages
- 15B+ facts

# History



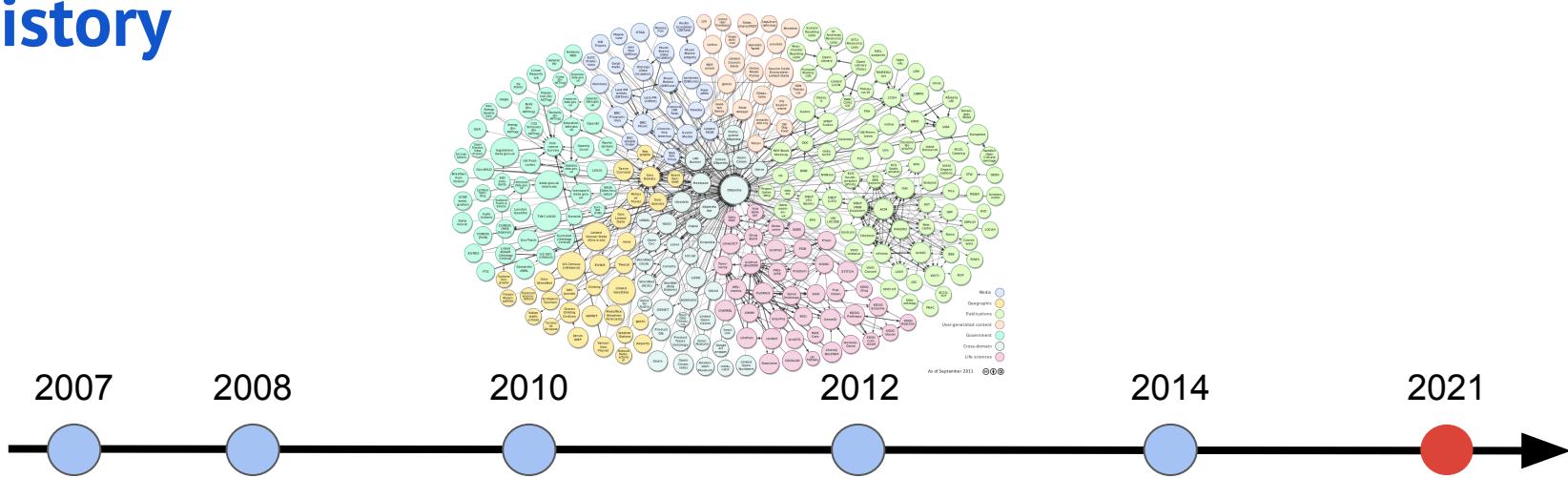
- The source of facts for Wiki infoboxes
- Flexible schema + qualifiers
- 100M+ entities, 7B+ statements
- Big Tech contributes to Wikidata

## History



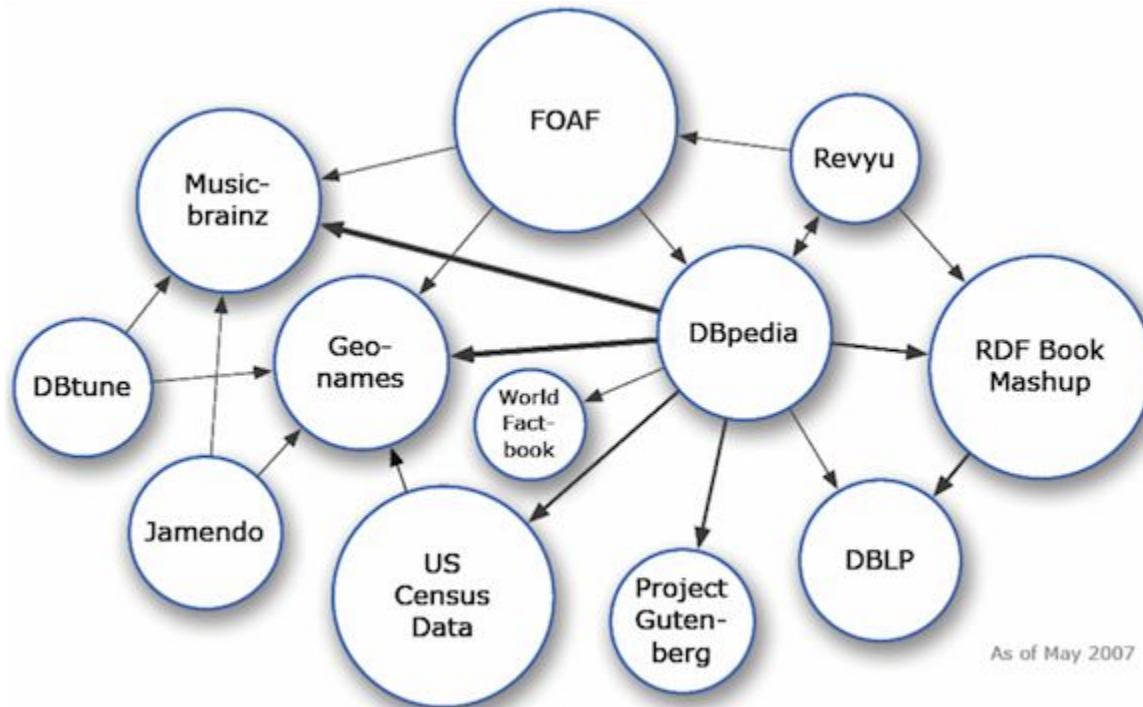
- Google Knowledge Graph - based on the acquired Freebase (2007)
- Common knowledge + user-specific info
- Everyone else started to want “my own KG” after that

# History

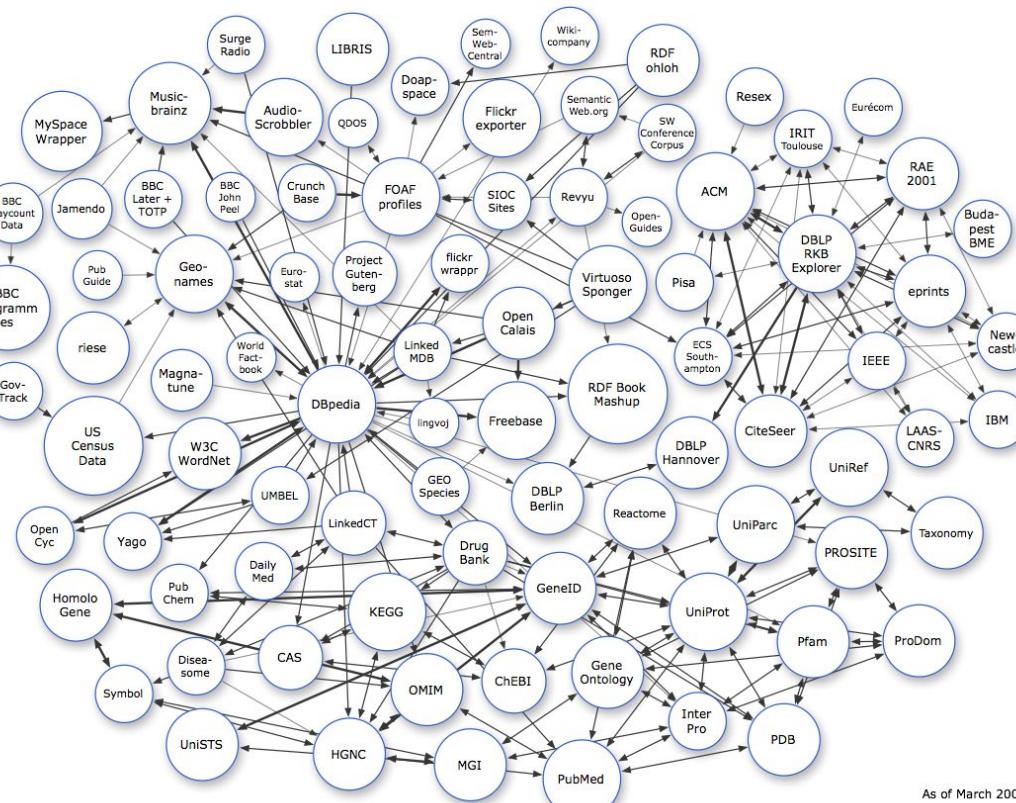


- Open and Linked KGs
- Domain-specific KGs in various domains
- Personal KGs
- ... many more

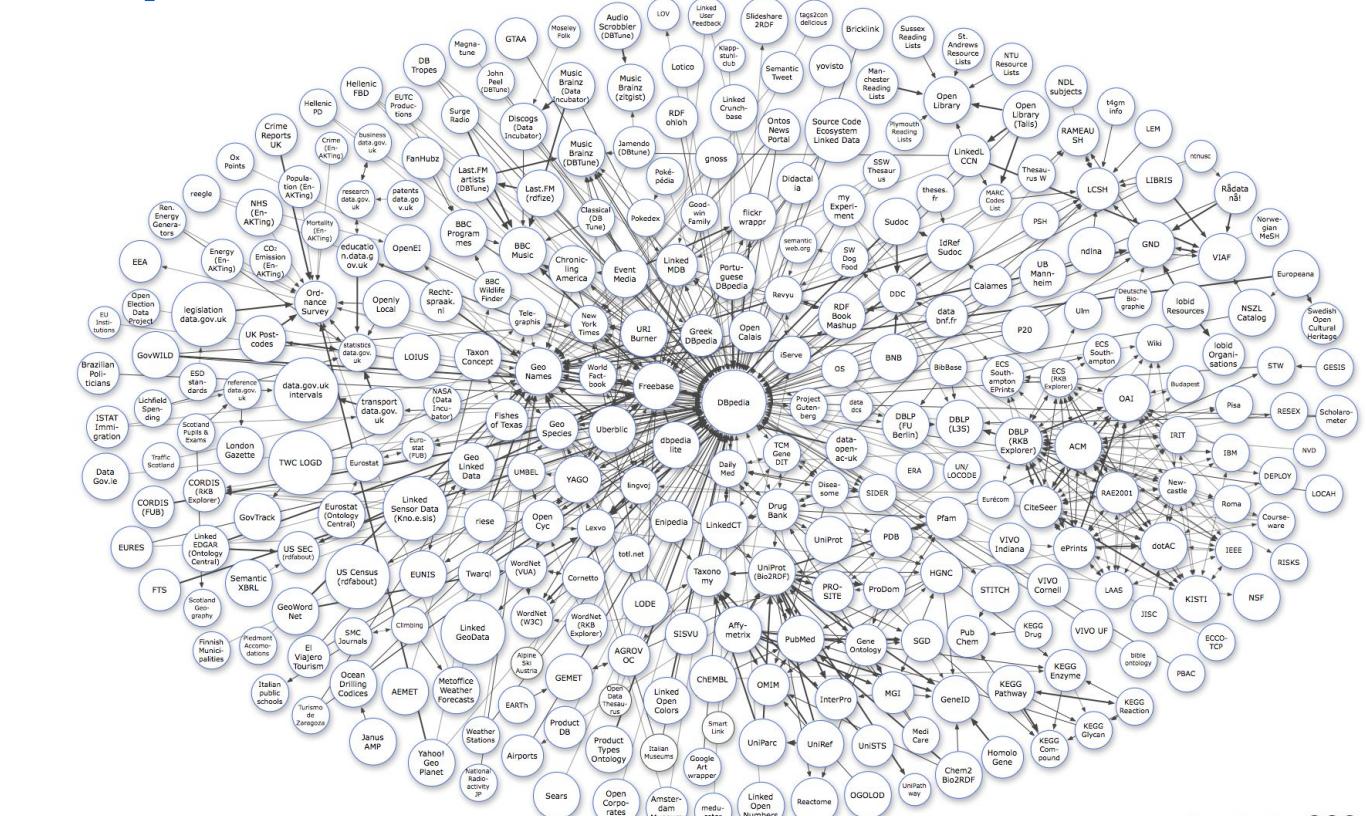
# Linked Open Data - 2007



# Linked Open Data - 2009



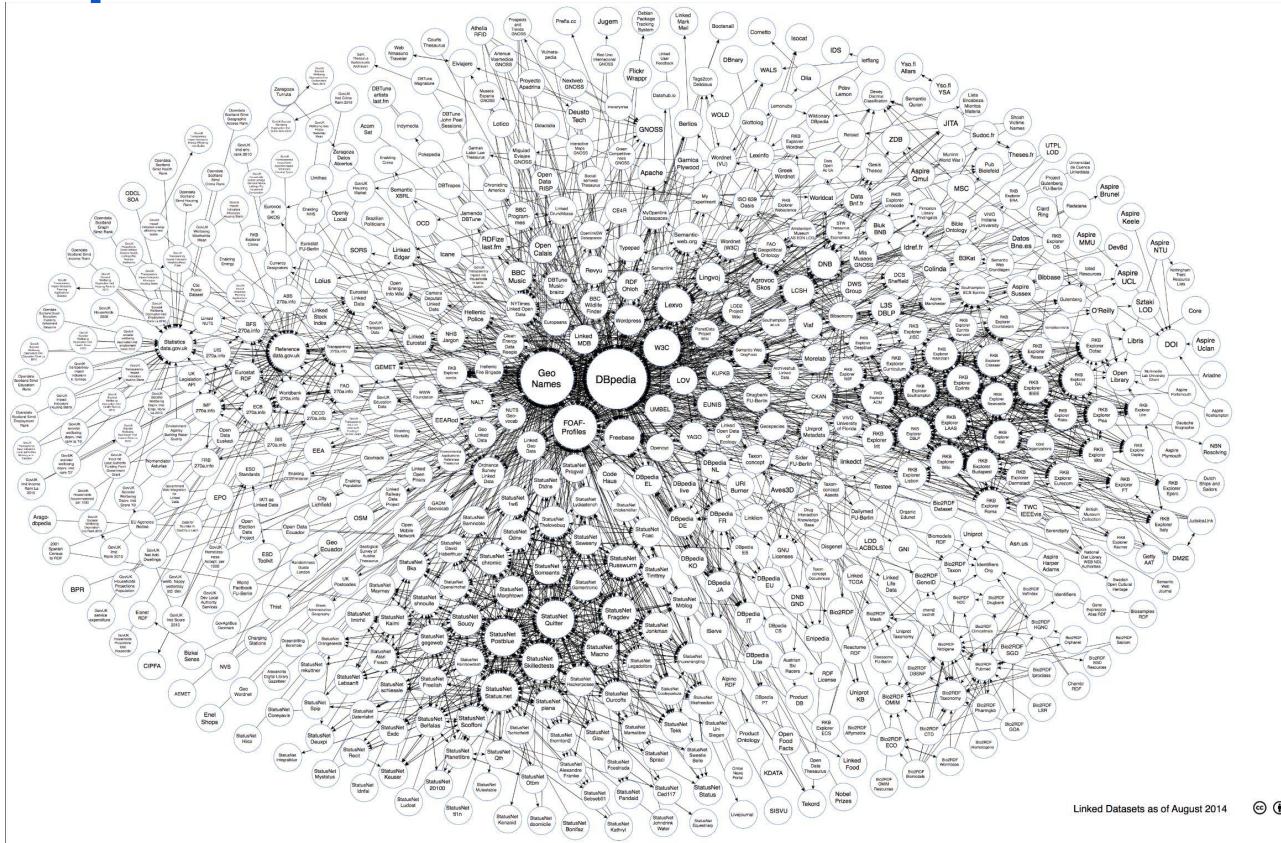
# Linked Open Data - 2011



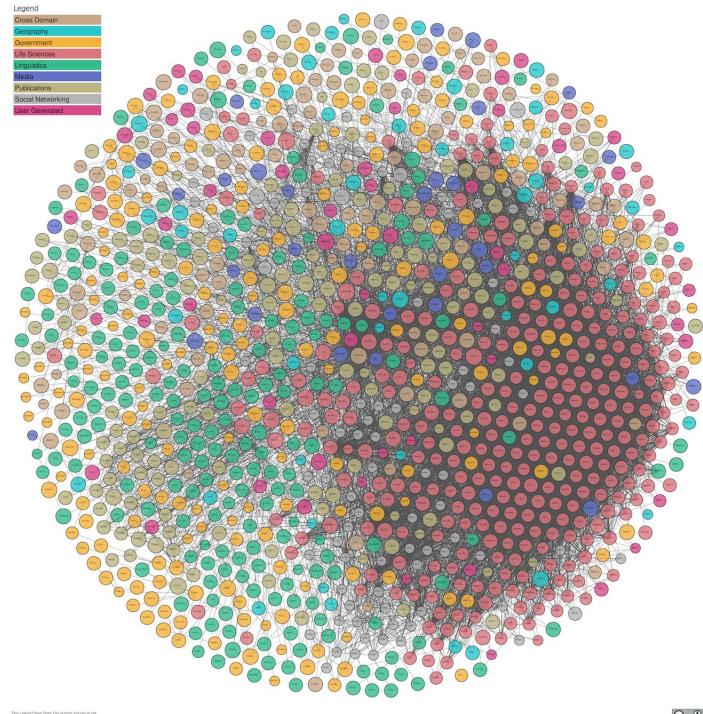
As of September 2011 



# Linked Open Data - 2014



# Linked Open Data - 2020



The Linked Open Data Cloud from linkeddata.net



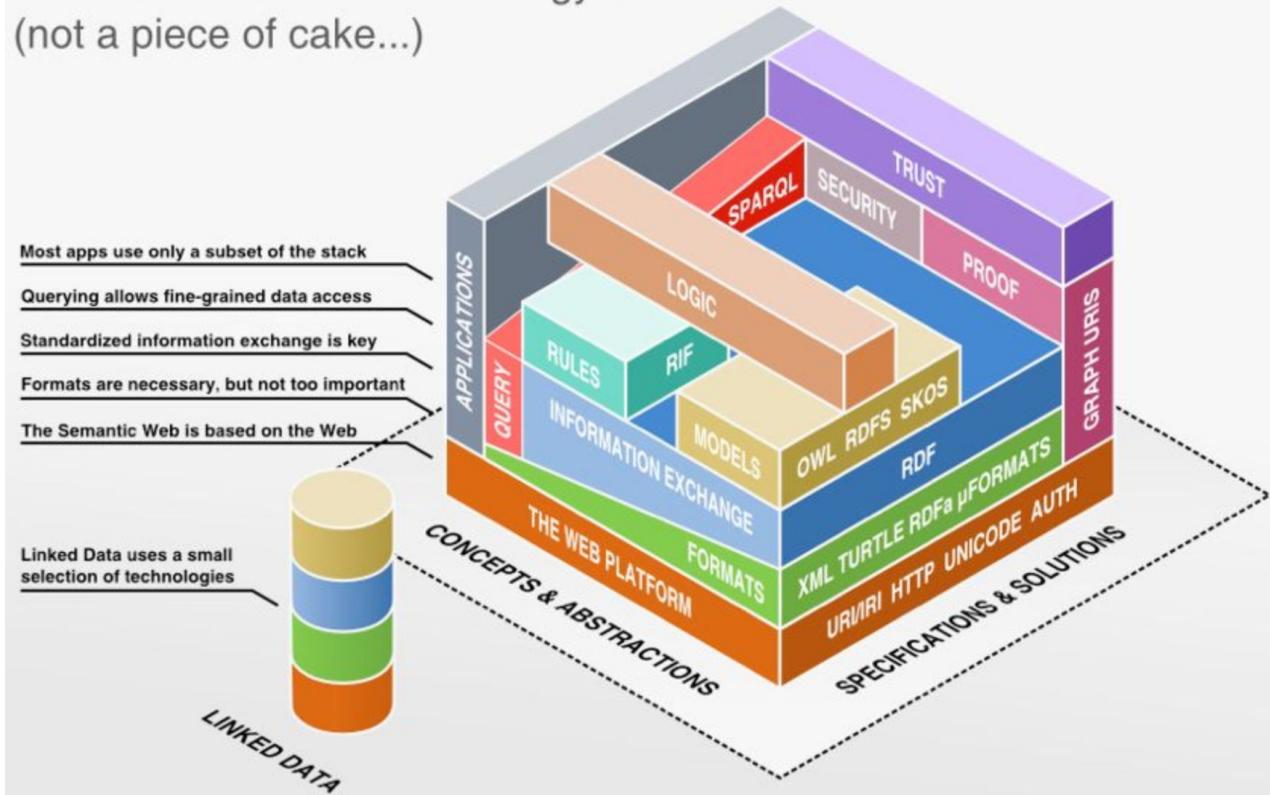
# **Part I: Symbolic Logical Foundations**

# Semantic Web Layer Cake

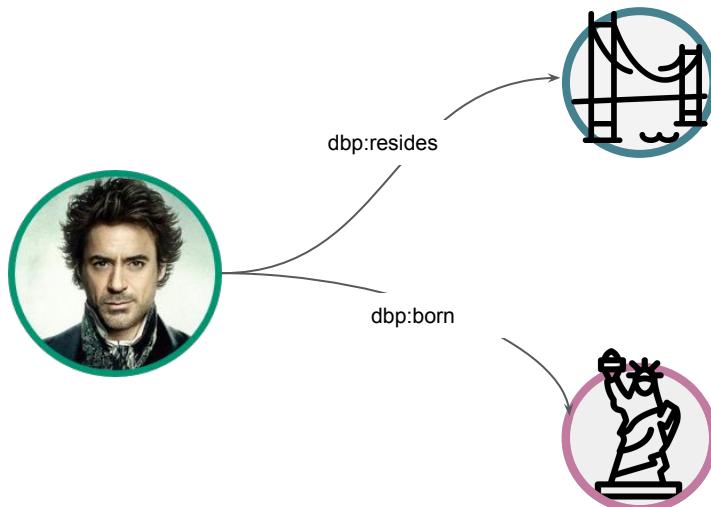
A stack of standards  
for KGs

1. Web Platform
2. Serialization
3. Modeling
4. Complex Logic
5. Querying
6. Interfaces

The Semantic Web Technology Stack  
(not a piece of cake...)



# Resource Description Framework (RDF)



<http://example.com/RDJ>

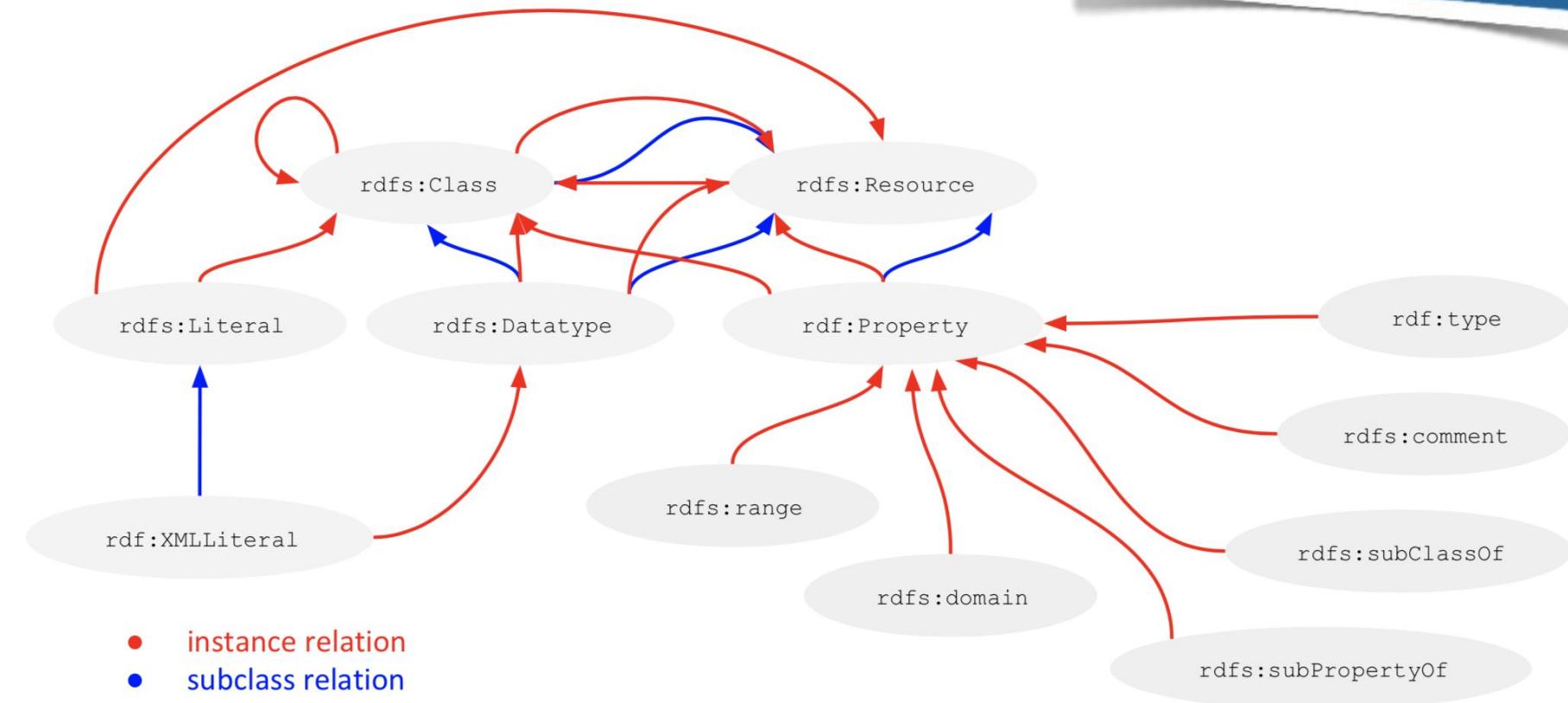
ex:RDJ

<http://dbpedia.org/resides> <http://dbpedia.org/resource/SanFrancisco>

dbr:resides

1. Facts as triples
2. All entities and relations are (ideally) URIs

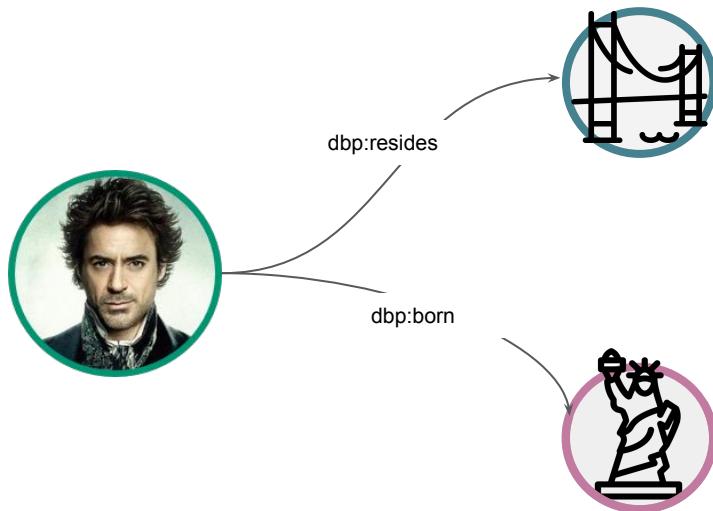
# RDFS Language Model



- instance relation
- subclass relation

[http://www.w3.org/TR/rdf-schema/#ch\\_classes](http://www.w3.org/TR/rdf-schema/#ch_classes)

# RDF + RDFS



ex:RDJ

ex:NewYork

**rdf:type**

**rdf:type**

ex:Person

ex:City

# RDF + RDFS Class Hierarchies

## RDFS Vocabulary

rdfs:Class

rdf:Property

rdfs:range

rdfs:domain

rdfs:subClassOf

rdfs:subPropertyOf

rdfs:label

rdfs:comment

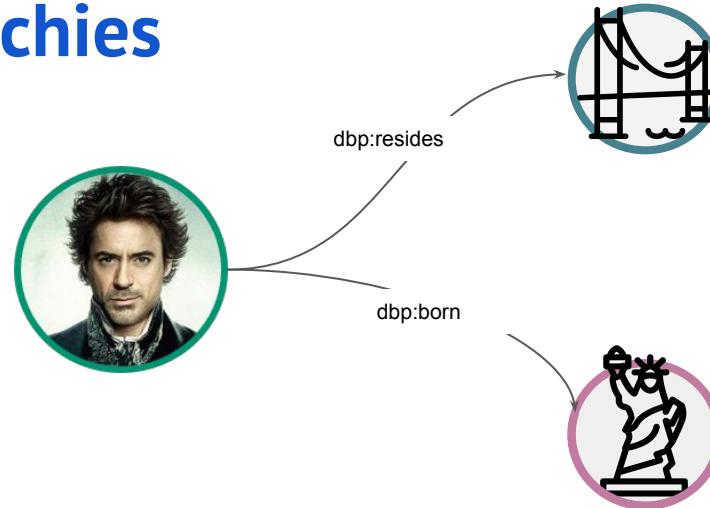
rdfs:seeAlso

rdfs:isDefinedBy

ex:RDJ  
ex:Actor  
ex:Person

rdf:type  
rdfs:subClassOf  
rdfs:subClassOf

ex:Actor  
ex:Person  
ex:Mammal



# RDF + RDFS Property Ranges & Domains

## RDFS Vocabulary

rdfs:Class

rdf:Property

rdfs:range

rdfs:domain

rdfs:subClassOf

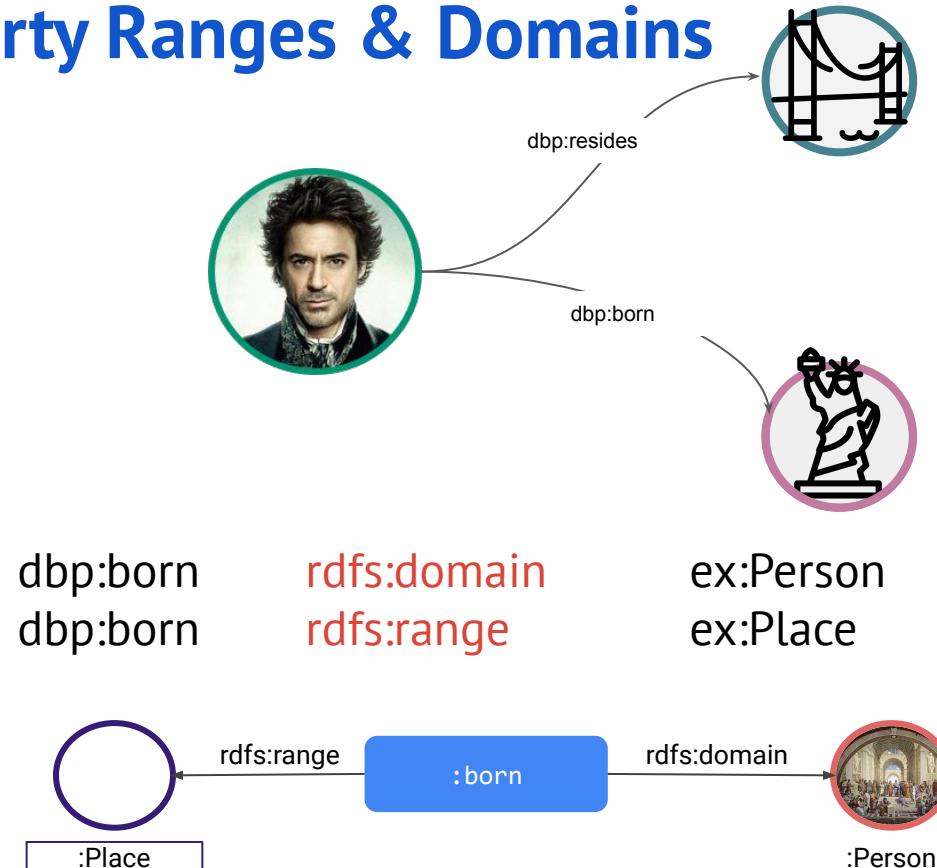
rdfs:subPropertyOf

rdfs:label

rdfs:comment

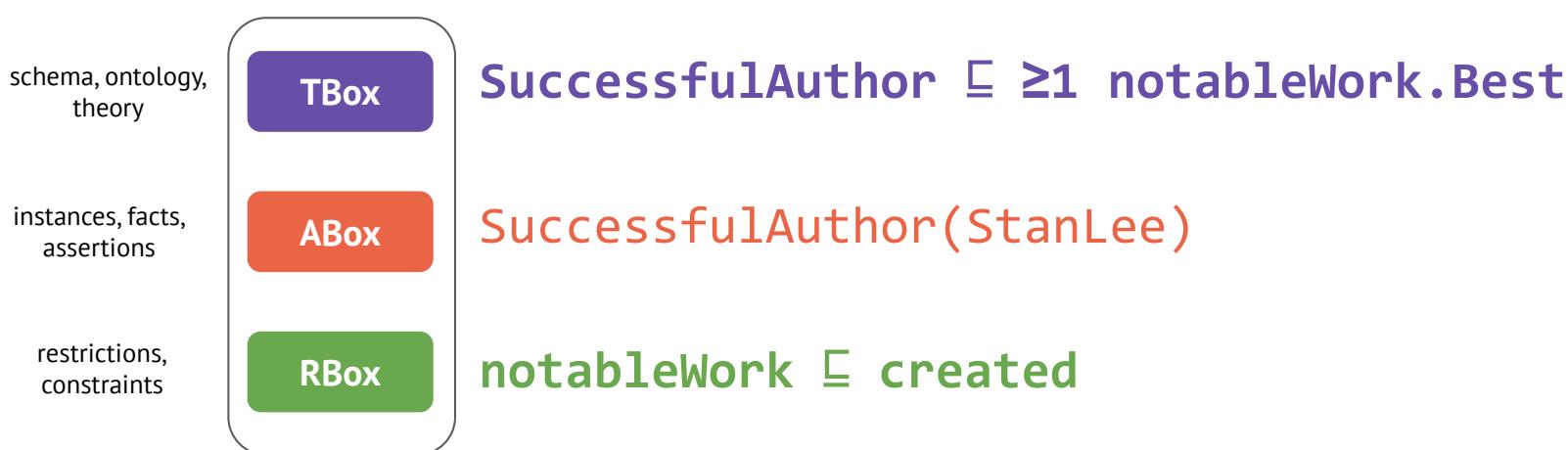
rdfs:seeAlso

rdfs:isDefinedBy



# More Logics: OWL

Based on logical formalisms, e.g., Description Logics (DL)

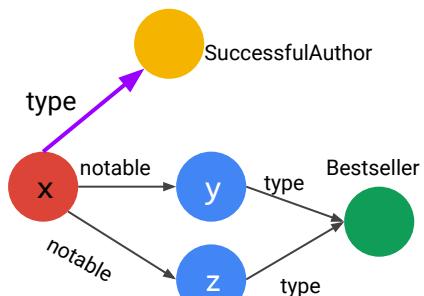


Logically consistent collection of axioms

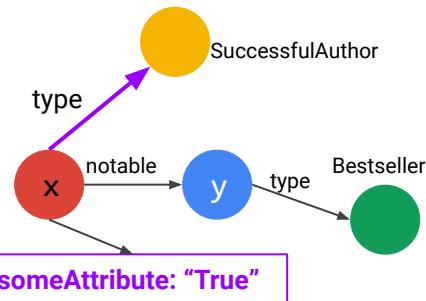
# More Logics: OWL

eg, Qualified Restrictions

```
SuccessfulAuthor ⊑ ≥1 notableWork.Bestseller  
:SuccessfulAuthor a owl:Class ;  
    rdfs:subClassOf [  
        a owl:Restriction;  
        owl:onProperty :notableWork;  
        owl:minQualifiedCardinality 1;  
        owl:onClass :Bestseller ] .
```



# Reasoners



- Input: RDF/OWL graph  
Output: RDF/OWL graph with new facts (assertions)
  - New node attributes
  - New edges between nodes

Explanation 1  Display laconic explanation

Explanation for: instanceB Type C

instanceB predicateA instanceA	?
instanceA Type A	?
C EquivalentTo predicateA some A	?

- Every fact can be explained (most ML models can't do that)
- Inference time grows very fast with graph size
- 🔥 research: speed of ML reasoning + explainability of rule-based

# Knowledge Graph

## TBox (Terminology Box)

Data schema

Ontology

Онтология:

- Formal model curated by experts
- Often created & maintained manually

## ABox (Assertion Box)

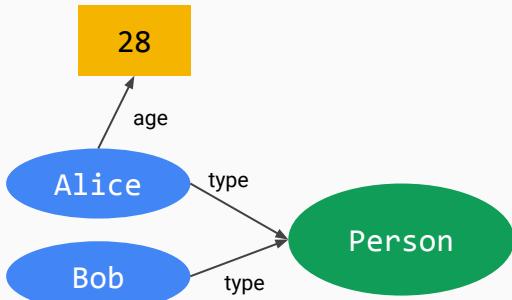
Actual “**content**”

Triples, edges between entities

- Often created from existing sources using **semantic data integration**

# Open World Assumption

- Incomplete picture of the world
- Everything not explicitly stated - *possibly* true
- Extendable by design



# Closed World Assumption

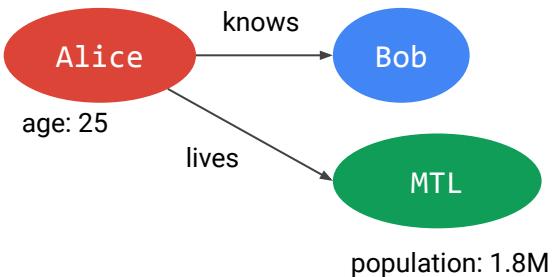
- Explicitly state everything about the world
- Everything not True == False
- Source of truth
  - Column in DB
  - Object field
  - Frame slot

Person	Age
Alice	28
Bob	N/A

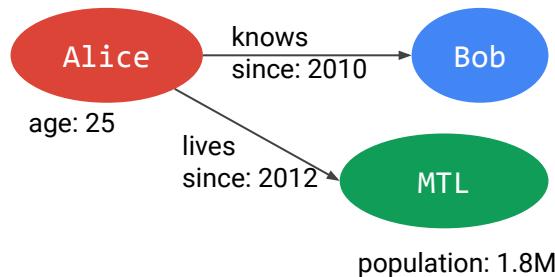
# **Part I: Symbolic Graph Databases & Querying**

# Graph DBs: RDF vs LPG

RDF



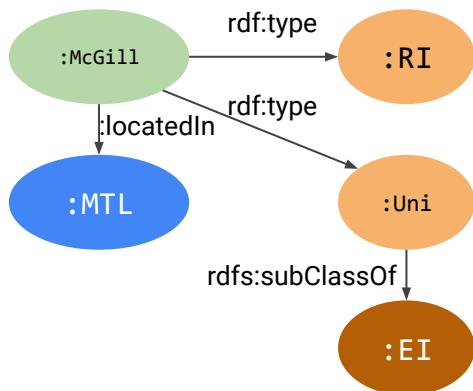
LPG (Labeled Property Graph)



- Query Language: SPARQL
- RDFS/OWL properties of predicates
- Semantic scheme (w/ ontologies)
- Logical inference

- QLs Cypher, Gremlin, GraphQL
- Any properties of predicates
- Non-semantic scheme
- No logical inference

# SPARQL Query Structure



:McGill  
:McGill  
:McGill  
:University

rdf:type  
rdf:type  
:locatedIn  
rdfs:subClassof

:University .  
:Research\_Institution .  
:MTL .  
:Educational\_Institution .

# SPARQL Query Structure

Prefixes

```
PREFIX rdf: <http://www.w3.org/1999/02/22-rdf-syntax-ns#> .  
PREFIX rdfs: <http://www.w3.org/2000/01/rdf-schema#> .
```

Query Type

```
SELECT ?type ?city
```

Projected Variables

```
FROM <named_graph>
```

Graph Source

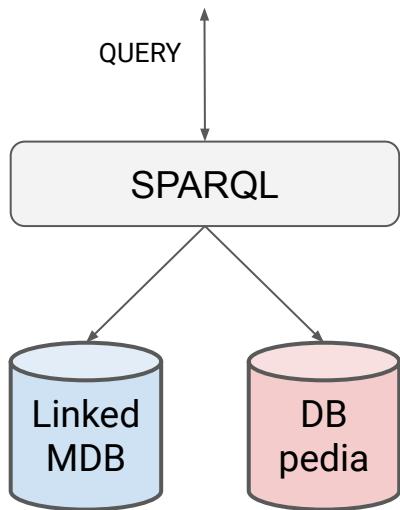
```
WHERE {  
    ?s      rdf:type          ?type .  
    ?s      :locatedIn        ?city .  
    ?type   rdfs:subClassOf   ?num .  
}
```

BGP

Modifiers

```
ORDER BY <> LIMIT <num> OFFSET <num>
```

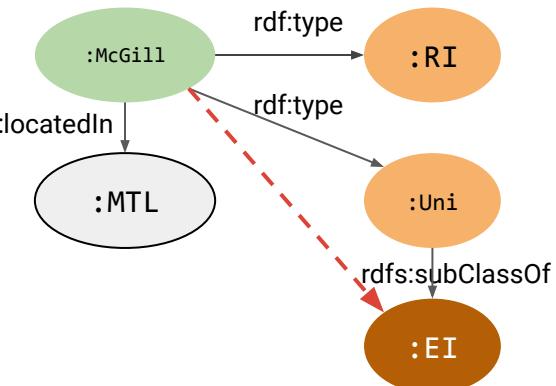
# SPARQL 1.1 - Federated Querying



- Federated queries - query other endpoints within a query using **SERVICE**

```
SELECT ?film ?label ?subject WHERE {  
    SERVICE <http://data.linkedmdb.org/sparql> {  
        ?movie rdf:type movie:film .  
        ?movie rdfs:label ?label .  
        ?movie owl:sameAs ?dbpediaLink  
        FILTER (regex(str(?dbpediaLink), "dbpedia"))  
    }  
    SERVICE <http://dbpedia.org/sparql> {  
        ?dbpediaLink dct:subject ?subject .  
    }  
}
```

# Advanced SPARQL - Reasoning



```
:McGill    rdf:type          :University .
:McGill    rdf:type          :Research_Institution .
:McGill    :locatedIn       :MTL .
:University  rdfs:subClassOf  :Educational_Institution .
(:McGill  rdf:type          :Educational_Institution .)
```

- Standard SPARQL - no reasoning, all triples have to be **materialized**
- Some Graph DBMS do allow for reasoning (inferring new triples in memory)
  - RDFS (subClassOf, range, domain)
  - OWL 2 RL / QL
  - SWRL
  - owl:sameAs

```
SELECT ?t WHERE {
:McGill a ?t }
```

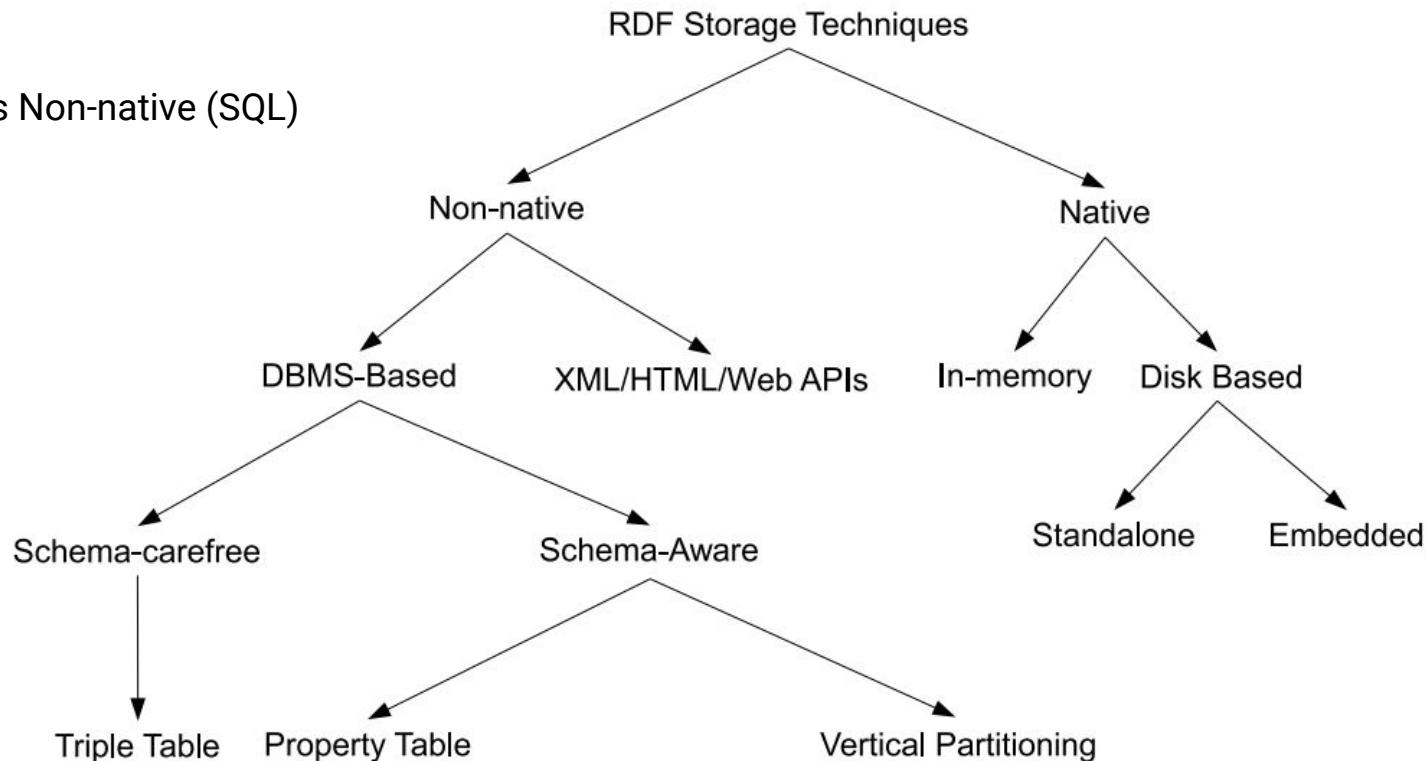
# HOW TO STORE RDF DATA ?



# RDF & Graph Databases

[Faye et al. A survey of RDF storage approaches, 2012]

- Native (NoSQL) vs Non-native (SQL)
- RDF vs LPG



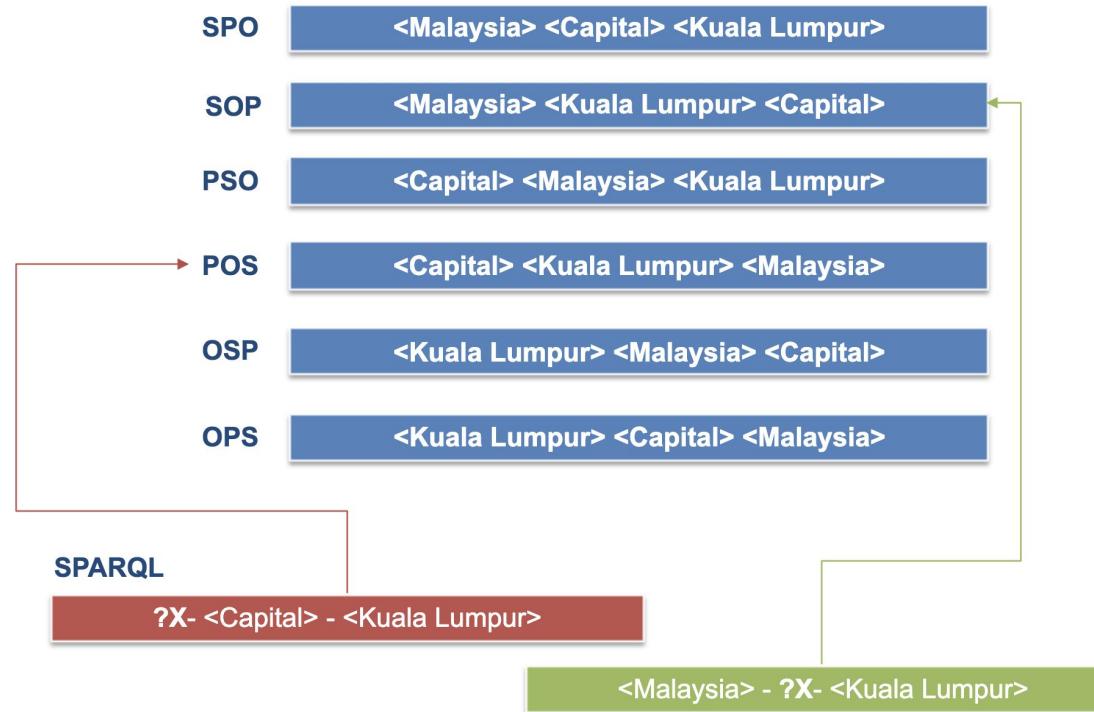
**Figure 2.** A classification of RDF data storage approaches

# RDF Databases - Native - B+ Trees - RDF-3X

- Six separate indexes
  - (SPO, SOP, OSP, OPS, PSO, POS)
  - Stored in the leaf pages of the clustered B+ tree

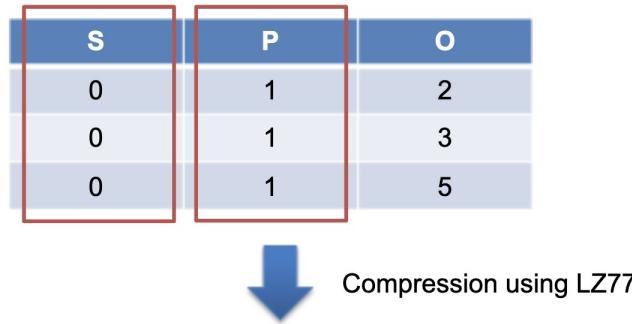


# RDF Databases - Native - B+ Trees - RDF-3X



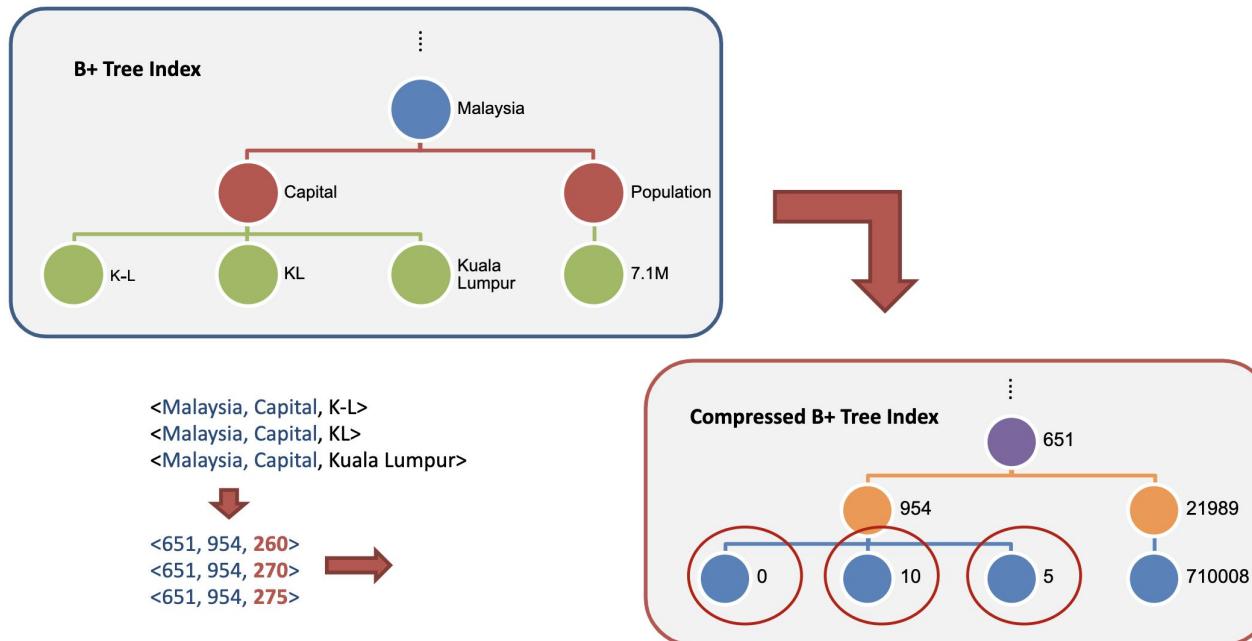
# RDF Databases - Native - B+ Trees - RDF-3X

- Store collation order
  - Neighboring indexes are very similar
  - Stores the change between triples

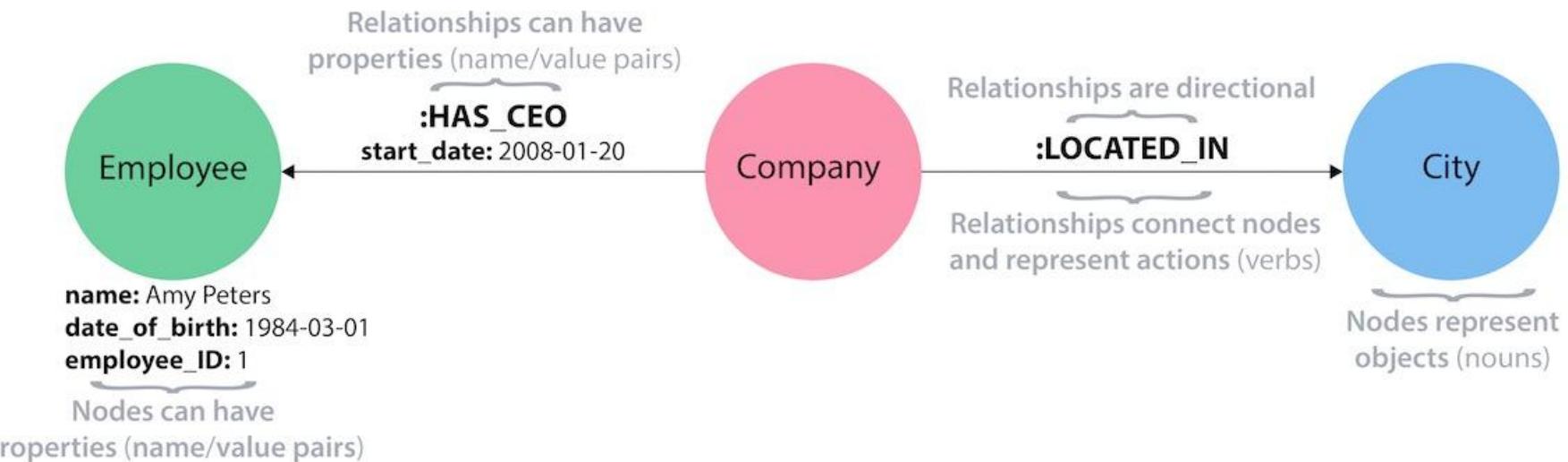


# RDF Databases - Native - B+ Trees - RDF-3X

- Compression
  - Stores only the change ( $\delta$ ) between triples



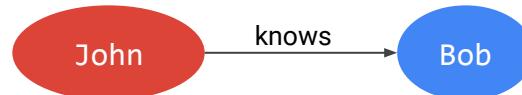
# Labeled Property Graph (LPG) Databases



# LPG - Cypher

- Standard for Neo4j
- Almost 1-1 mapping to SPARQL

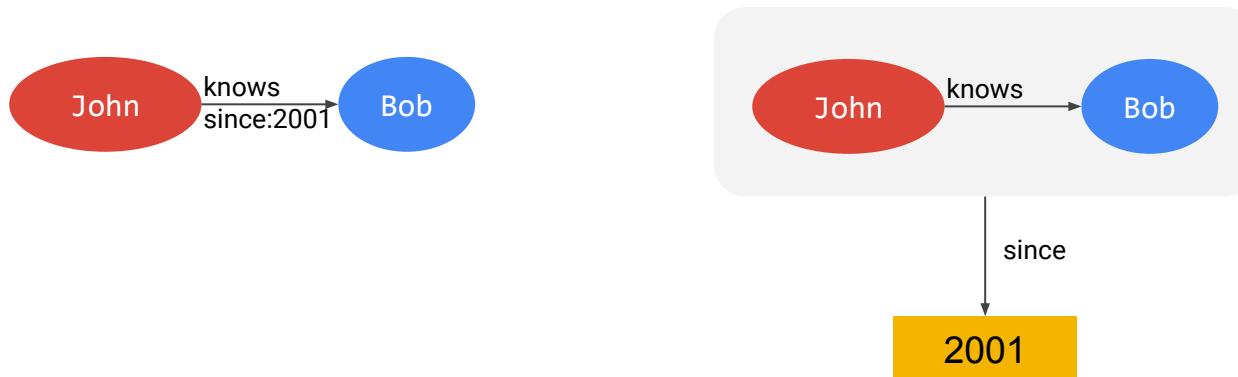
Cypher	SPARQL
<pre>MATCH (s:Person) WHERE s.name = "John" RETURN s;</pre>	<pre>SELECT ?s WHERE { ?s a :Person; :name "John" }</pre>
<pre>MATCH (s:Person)-[:knows]-(friend) WHERE s.name = "John" RETURN s, friend ;</pre>	<pre>SELECT ?s ?friend WHERE { ?s a :Person; :name "John" ; :knows ?friend }</pre>



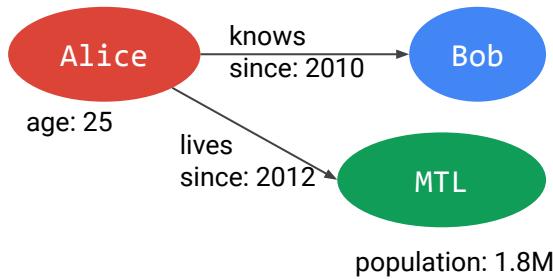
# LPG - Cypher

- Standard for Neo4j
- Almost 1-1 mapping to SPARQL

Cypher	SPARQL* (Reification)
<pre>MATCH (s:Person)-[:knows {since:2001}] -&gt; (js) RETURN s;</pre>	<pre>SELECT ?s WHERE { &lt;&lt;?s :knows :js&gt;&gt; :since 2001 }</pre>



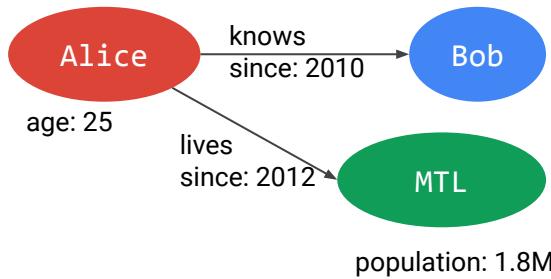
# RDF\* / SPARQL\*



<< Alice knows Bob >> since 2010 .  
<< Alice lives MTL >> since 2012 .

Alice age 25 .  
MTL population 1.8M .

# RDF\* / SPARQL\*



```
<< Alice knows Bob >> since 2010 .  
<< Alice lives MTL >> since 2012 .
```

```
Alice age 25 .  
MTL population 1.8M .
```

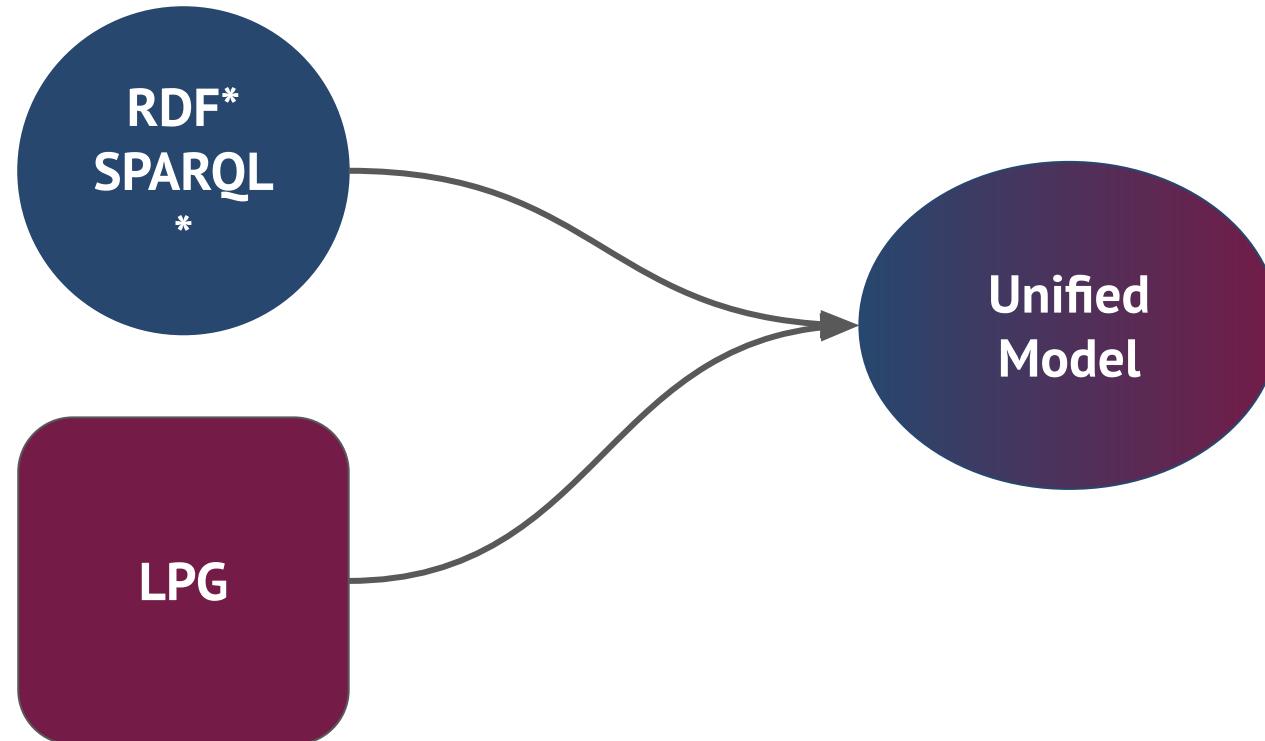
Since when Alice knows Bob?

```
SELECT ?date WHERE {  
<< Alice knows Bob >> since ?date . }
```

What is a population of a city when Alice lives since 2012?

```
SELECT ?population WHERE {  
<< Alice lives ?city >> since 2012 .  
?city population ?population . }
```

# RDF\* / SPARQL\* + LPG Convergence



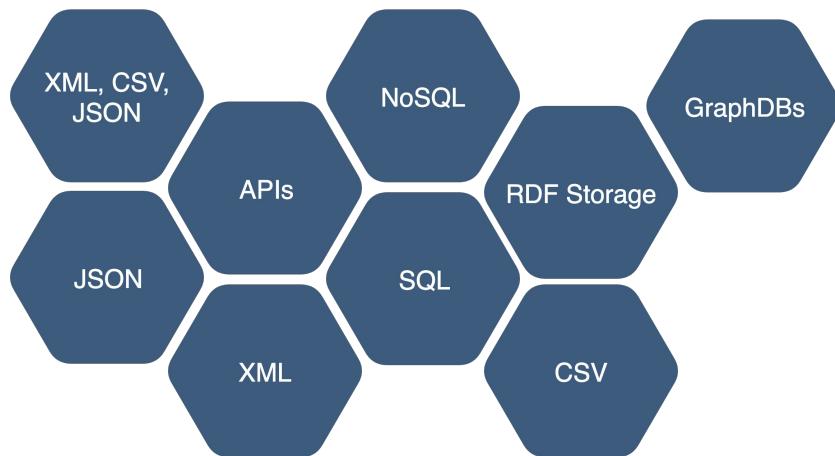
# **Part I: Symbolic KG Construction**

# KG Construction

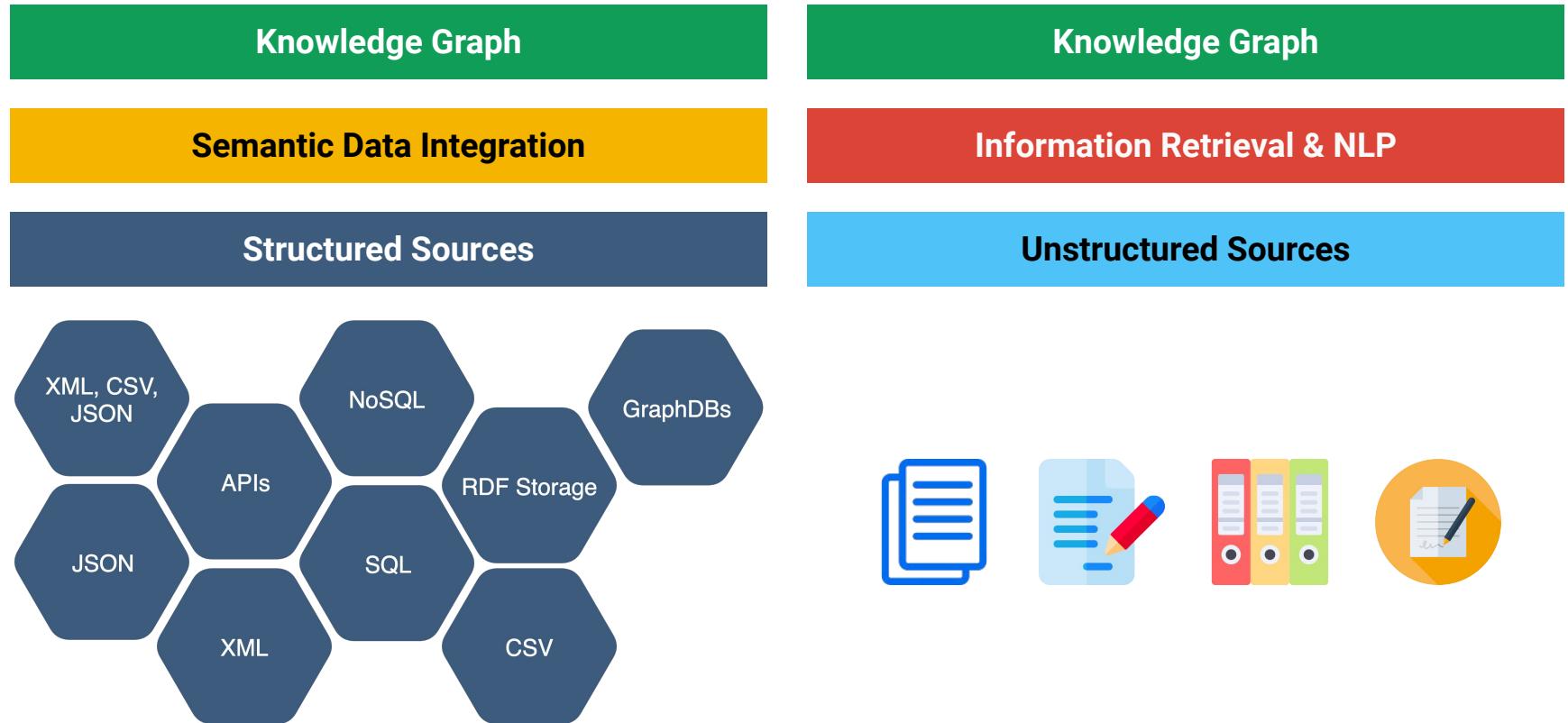
Knowledge Graph

Semantic Data Integration

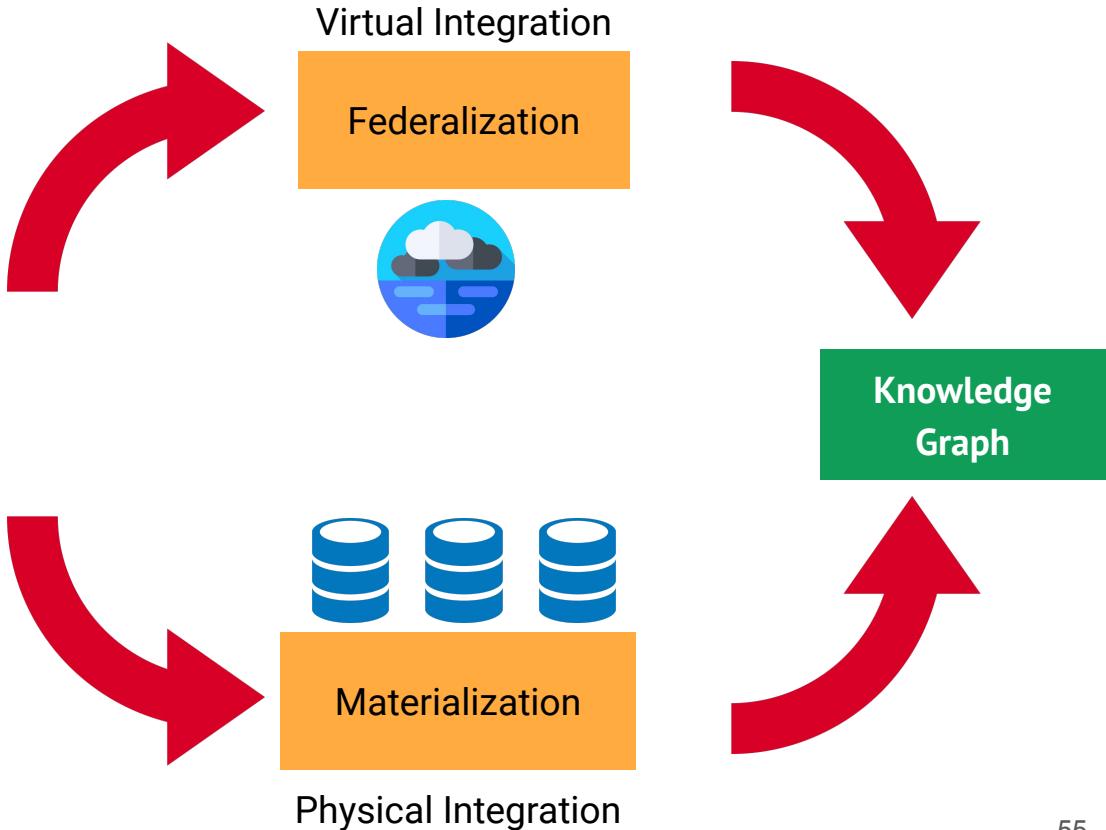
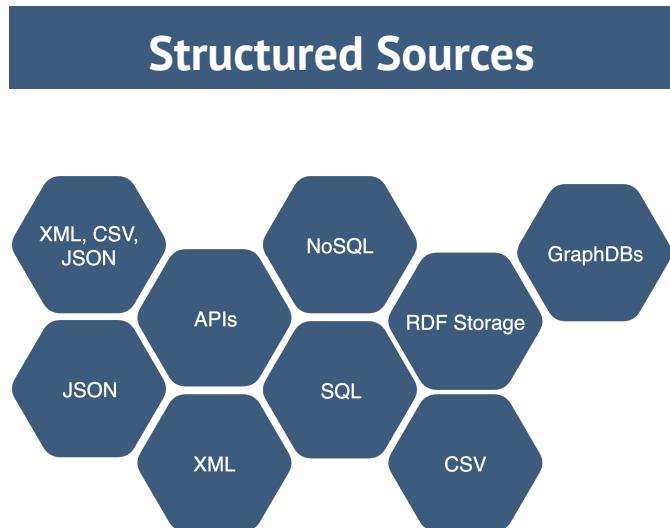
Structured Sources



# KG Construction



# Semantic Data Integration

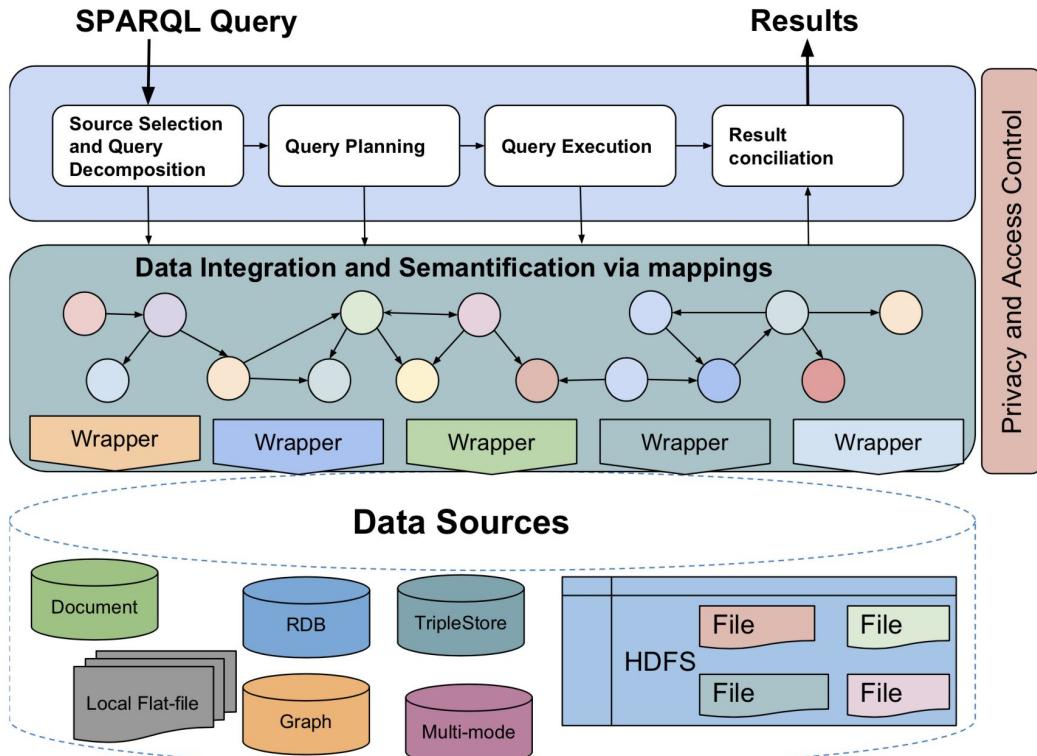


# Physical Integration (Materialization)

Data Warehouses



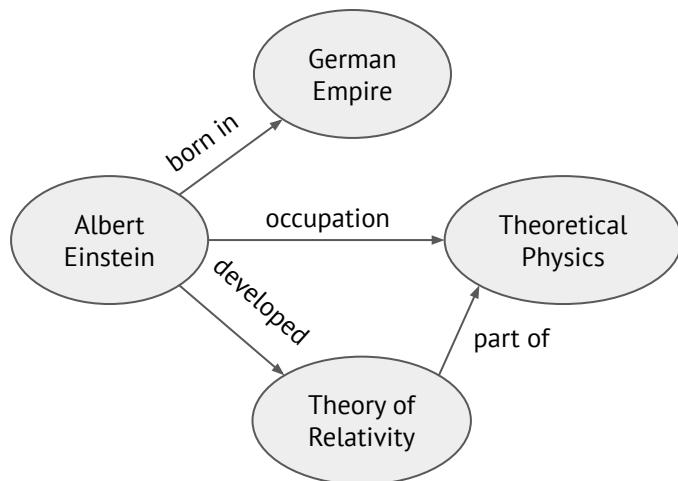
# Virtual Integration (Federalization)



Data Lakes

# Building KGs from texts

Albert Einstein was a German-born theoretical physicist who developed the theory of relativity.



Knowledge Graph

Information Retrieval

Unstructured Sources



# **Part II: Vector (some ML)**

**NLP**

# NLP - Named Entity Recognition

apple (Q89)

fruit of the apple tree  
apples

Apple (Q1754545)

1990 album by Mother Love bone

Apple (Q213710)

UK international record label; imprint of Apple Corps Ltd.  
LC 01074 | LC 1074 | Apple Records

Apple Inc. (Q312)

American producer of hardware, software, and services, based in Cupertino, California

Apple Computer, Inc. | Apple Computer | Apple Computer Inc | Apple | Apple Incorporated | Apple Computer Incorporated | 



Who is the CEO of **Apple**?



{**Apple** belongs to which genus?}

movie character



{**Downey** played **Iron Man** in which year?}

comic character

Who is the alter ego of **Iron man**?

# NLP - Relation Linking

List of known relations

Surface forms (synonyms),  
easily multi-lingual

Relations constraints

Relations hierarchy

Most used types of  
subjects and objects

Name all the movies in which Robert Downey Jr **acted?**

wdt:P161

Find me all the films **casting** Robert Downey Jr ?

List all the movies **starring** Robert Downey Junior?

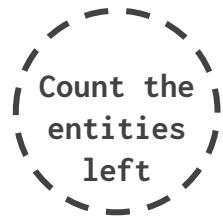
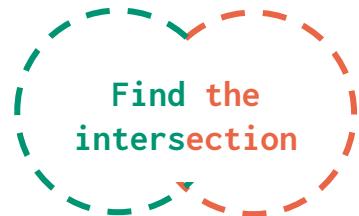
RDJ **has acted** in which movies?

**cast member** (P161)

actor in the subject production |  
starring | film starring | actor | actress | contestant or a play

**performer** (P175)

actor, musician, band or other performer associated with this role or musical work  
artist | musician | played by | portrayed by | recorded by | recording by | dancer | actor | musical artist



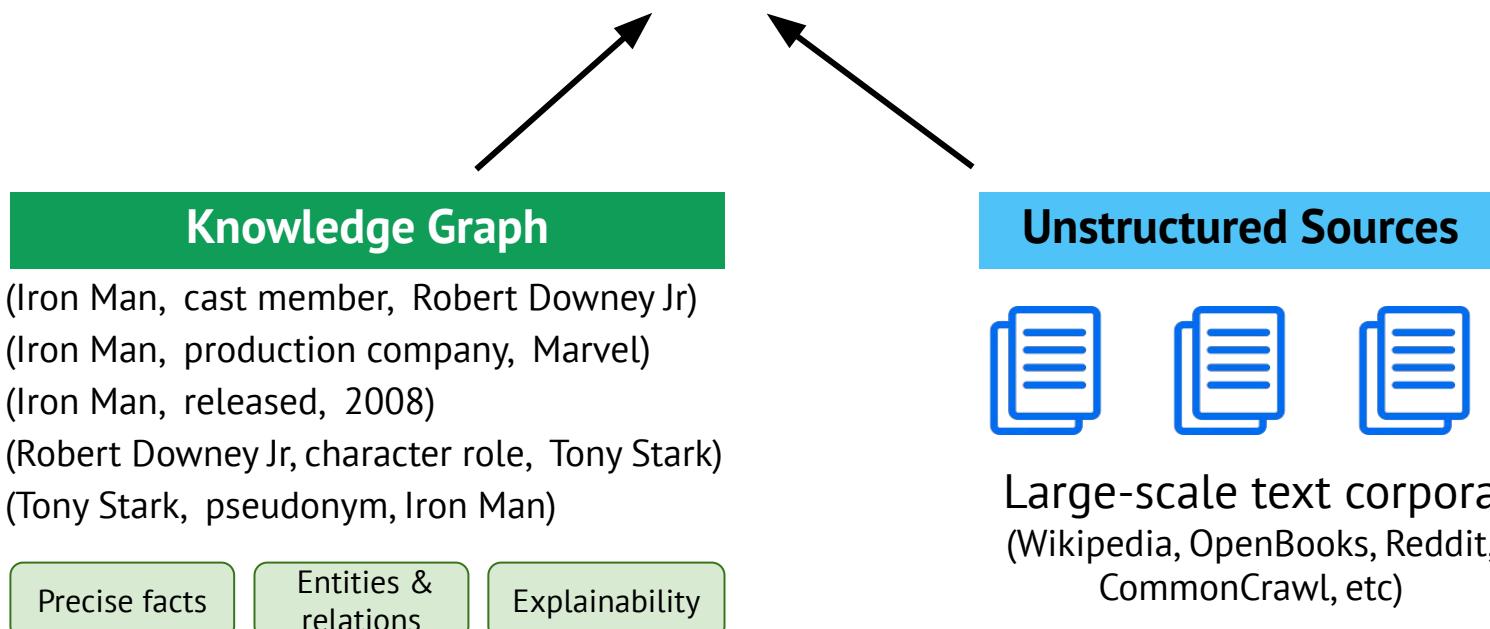
# NLP - Question Answering

How many **Marvel movies** was **Robert Downey Jr.**  
**casted** in?

```
SELECT COUNT(?uri) WHERE {  
    ?uri dbp:studio dbr:Marvel_Studios.  
    ?uri dbo:starring dbr:Robert_Downey_Jr  
}
```

# NLP - Language Modeling

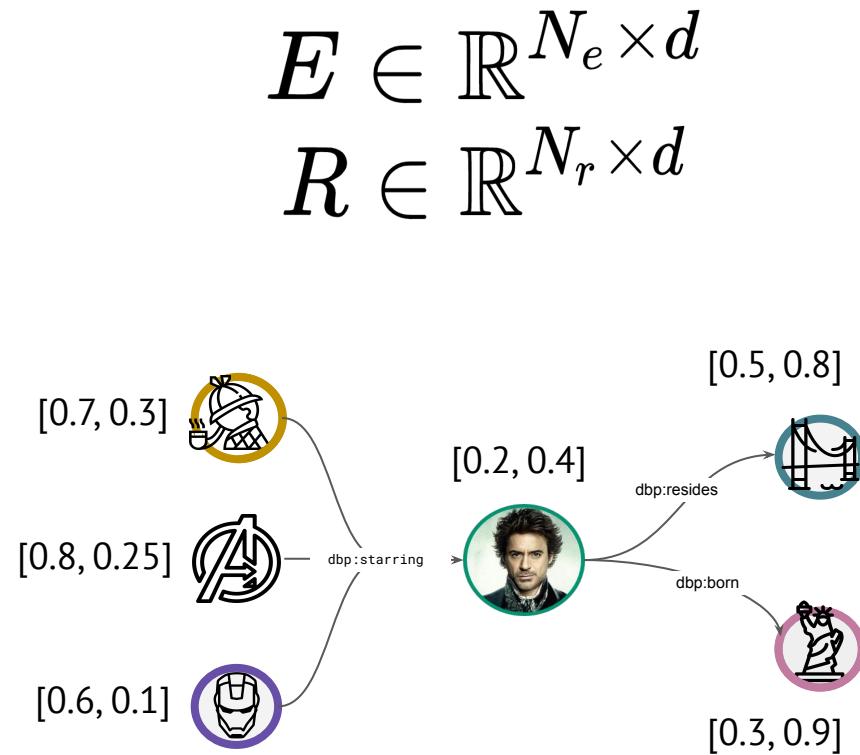
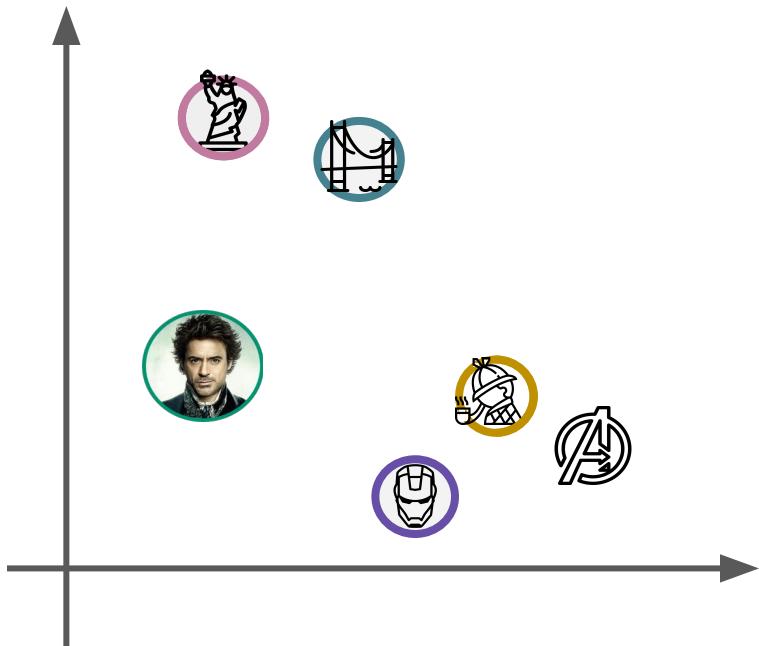
Robert Downey Jr. portrayed [MASK] in the Marvel movie in 2008.



## **Part II: Vector (some ML)**

### **Representation Learning (KG Embeddings)**

# Embeddings



# Embeddings

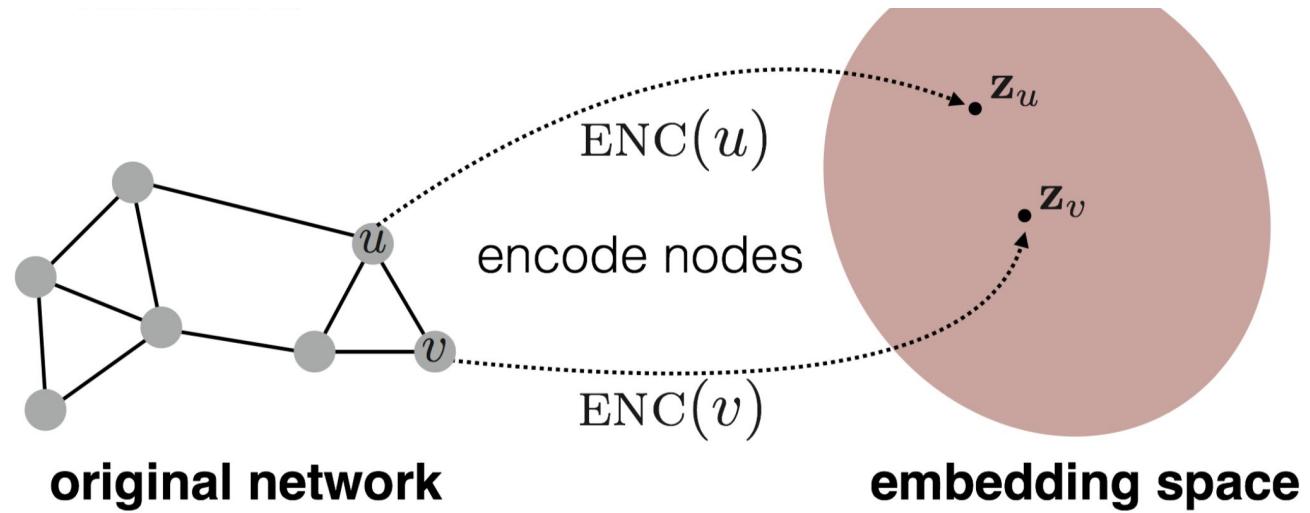
Tensor  
Factorization

Translation

Neural Networks

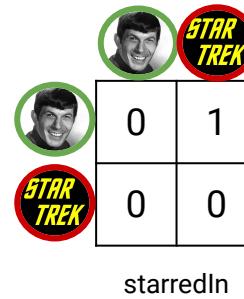
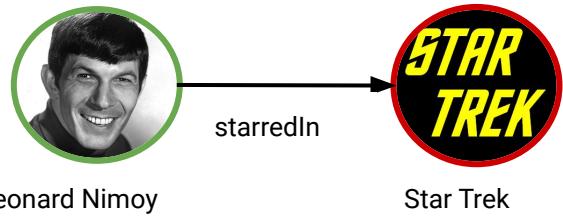
Graph Neural  
Nets

Goal: encode nodes so that **similarity in the embedding space (e.g., dot product)** approximates **similarity in the original network**

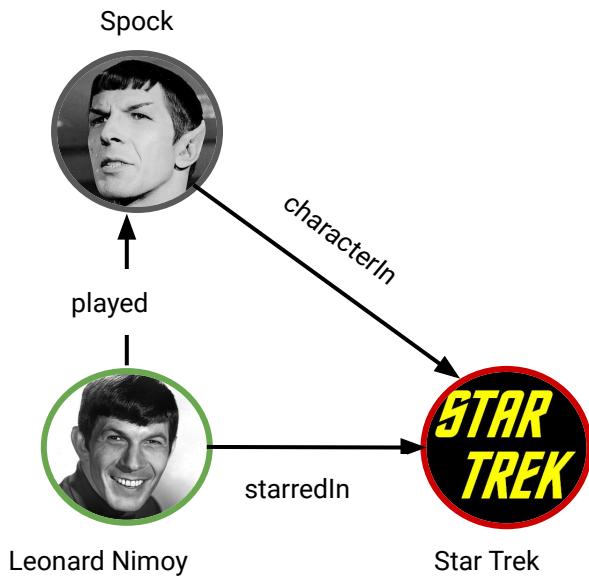


Source: Stanford CS224w, <http://web.stanford.edu/class/cs224w/>

# KGE - Graphs as Tensors



# KGE - Graphs as Tensors



A 3x3 matrix representing the "starredIn" relationship. The columns are labeled with Leonard Nimoy, Spock, and Star Trek. The rows are labeled with Star Trek, Spock, and Leonard Nimoy. The matrix values are:

0	1	0
0	0	0
0	0	0

starredIn

A 3x3 matrix representing the "played" relationship. The columns are labeled with Leonard Nimoy, Spock, and Star Trek. The rows are labeled with Star Trek, Spock, and Leonard Nimoy. The matrix values are:

0	0	1
0	0	0
0	0	0

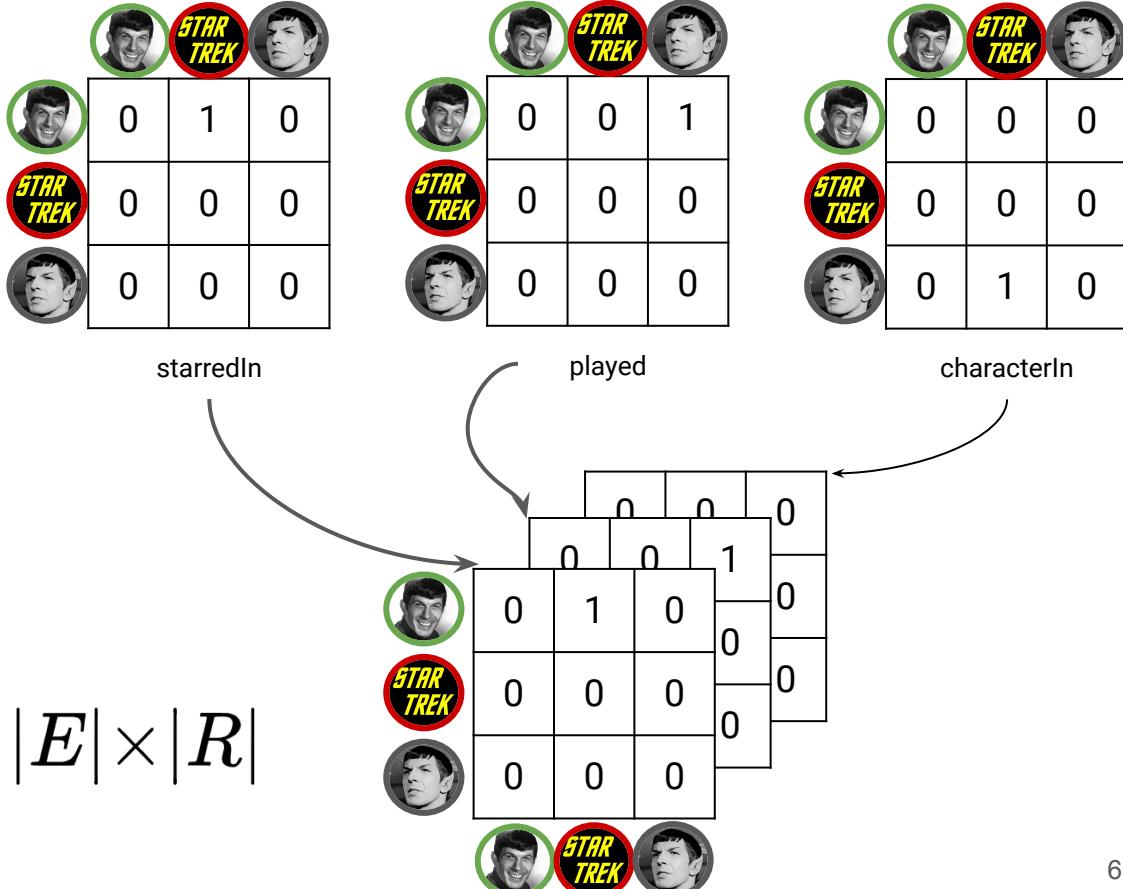
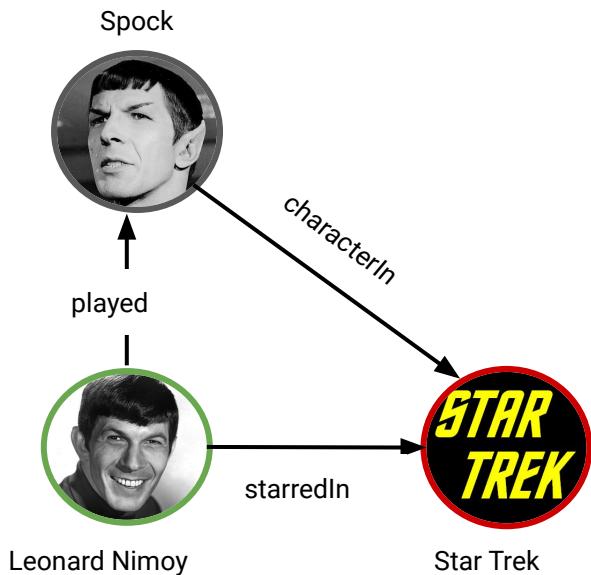
played

A 3x3 matrix representing the "characterIn" relationship. The columns are labeled with Leonard Nimoy, Spock, and Star Trek. The rows are labeled with Star Trek, Spock, and Leonard Nimoy. The matrix values are:

0	0	0
0	0	0
0	1	0

characterIn

# KGE - Graphs as Tensors

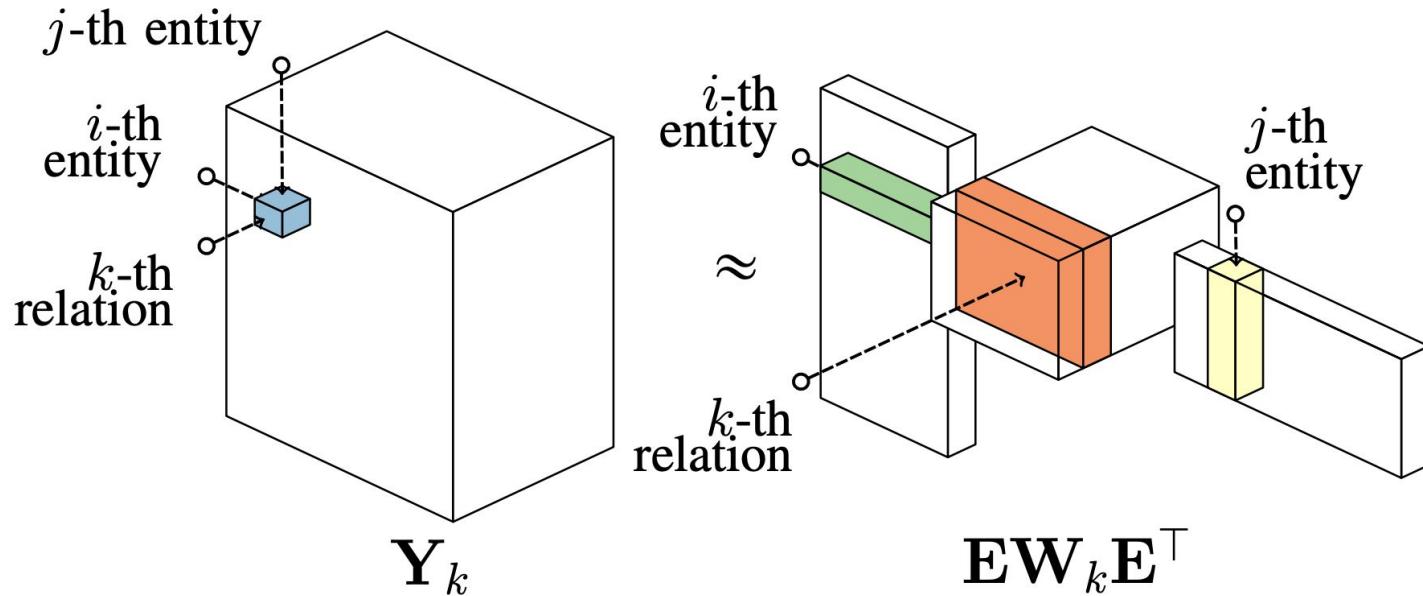


$$\mathcal{T} : \mathbb{R}^{|E| \times |E| \times |R|}$$

# KGE - RESCAL

## Tensor Factorization

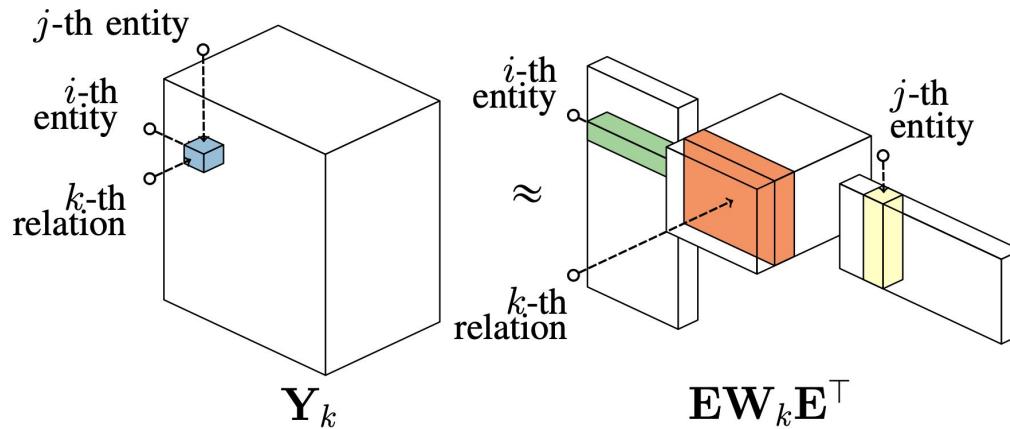
Goal - factorize a sparse 3D tensor to dense E and R



# KGE - RESCAL

## Tensor Factorization

Goal - factorize a sparse 3D tensor to dense E and R



$$\mathbf{E} : \mathbb{R}^{|E| \times n}$$

$$\mathbf{W} : \mathbb{R}^{|k| \times n \times n}$$

# KGE - TransE

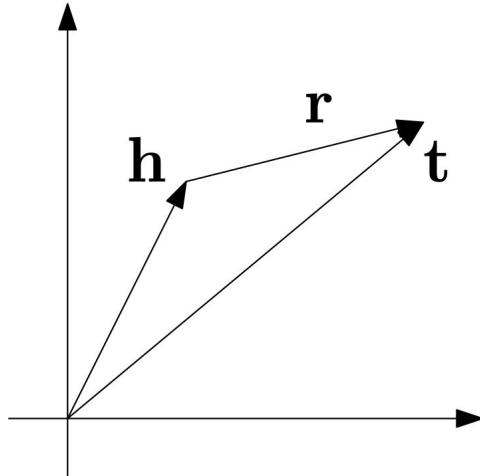
Tensor  
Factorization

Translation

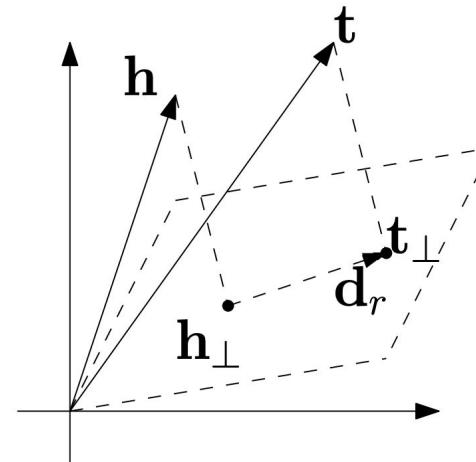
$$\|h\|_2^2 = \|t\|_2^2 = 1$$

Translate entities and relations into one embedding space

$$h + r \approx t \quad \text{Moscow} + \text{capitalOf} \approx \text{Russia}$$



(a) TransE



(b) TransH

Bordes et al. Translating Embeddings for Modeling Multi-relational Data. NIPS 2013

Wang et al. Knowledge Graph Embedding by Translating on Hyperplanes. AAAI 2014

# KGE - TransE

Tensor  
Factorization

Translation

LOTS of  
models

TABLE 9  
Knowledge graph embedding using margin-based ranking loss.

GE Algorithm	Energy Function $f_r(\mathbf{h}, \mathbf{t})$
TransE [91]	$\ h + r - t\ _{l1}$
TKRL [53]	$\ M_{rh}h + r - M_{rt}t\ $
TransR [15]	$\ hM_r + r - tM_r\ _2^2$
CTransR [15]	$\ hM_r + r_c - tM_r\ _2^2 + \alpha\ r_c - r\ _2^2$
TransH [14]	$\ (h - w_r^T h w_r) + d_r - (t - w_r^T t w_r)\ _2^2$
SePLi [39]	$\frac{1}{2}\ W_i e_{ih} + b_i - e_{it}\ ^2$
TransD [125]	$\ M_{rh}h + r - M_{rt}t\ _2^2$
TranSparse [126]	$\ M_r^h(\theta_r^h)h + r - M_r^t(\theta_r^t)t\ _{l1/2}^2$
m-TransH [127]	$\ \sum_{\rho \in \mathcal{M}(R_r)} a_r(\rho) \mathbb{P}_{n_r}(t(\rho)) + b_r\ ^2, t \in \mathcal{N}^{\mathcal{M}(R_r)}$
DKRL [128]	$\ h_d + r - t_d\  + \ h_d + r - t_s\  + \ h_s + r - t_d\ $
ManifoldE [129]	Sphere: $\ \varphi(h) + \varphi(r) - \varphi(t)\ ^2$ Hyperplane: $(\varphi(h) + \varphi(r_{head}))^T (\varphi(t) + \varphi(r_{tail}))$ $\varphi$ is the mapping function to Hilbert space
TransA [130]	$\ h + r - t\ $
puTransE [43]	$\ h + r - t\ $
KGE-LDA [60]	$\ h + r - t\ _{l1}$
SE [90]	$\ R_u h - R_u t\ _{l1}$
SME [92] linear	$(W_{u1}r + W_{u2}h + b_u)^T (W_{v1}r + W_{v2}t + b_v)$
SME [92] bilinear	$(W_{u1}r + W_{u2}h + b_u)^T (W_{v1}r + W_{v2}t + b_v)$
SSP [59]	$-\lambda\ e - s^T es\ _2^2 + \ e\ _2^2, S(s_h, s_t) = \frac{s_h + s_t}{\ s_h + s_t\ _2^2}$
NTN [131]	$u_r^T \tanh(h^T W_r t + W_{rh}h + W_{rt}t + b_r)$
HOLE [132]	$r^T (h \star t), \text{ where } \star \text{ is circular correlation}$
MTransE [133]	$\ h + r - t\ _{l1}$

# KGE - Incorporating OWL Rules

## Tensor Factorization

## Translation

$$\min_{\theta} \sum_{(h,r,t) \in \mathcal{S}} \alpha_{h,t}^r \log(1 + \exp(-y_{h,t}^r f_{h,t}^r)) + \lambda \sum_{i=1}^l \frac{\mathcal{R}_i}{N_i}$$

subject to       $\|h\| = 1$  and  $\|t\| = 1$ .

Rule	Definition $\forall h, t, s \in \mathcal{E} : \dots$	Formulation based on score function	Formulation based on NN	Equivalent regularization form (Denoted as $\mathcal{R}_i$ in Equation (2))
Equivalence	$(h, r_1, t) \Leftrightarrow (h, r_2, t)$	$f_{h,t}^{r_1} = f_{h,t}^{r_2} + \xi_{h,t}$	$\Phi_{h,t}^T (\beta^{r_1} - \beta^{r_2}) = \xi_{h,t}$	$\max(\ \beta^{r_1} - \beta^{r_2}\ _1 - \xi_{Eq}, 0)$
Symmetric	$(h, r, t) \Leftrightarrow (t, r, h)$	$f_{h,t}^r = f_{t,h}^r + \xi_{h,t}$	$(\Phi_{h,t} - \Phi_{t,h})^T \beta^r = \xi_{h,t}$	$\max( (\Phi_{h,t} - \Phi_{t,h})^T \beta^r  - \xi_{Sy}, 0)$
Asymmetric	$(h, r, t) \Rightarrow \neg(t, r, h)$	$f_{h,t}^r = f_{t,h}^r + \mathcal{M}_{h,t}$	$(\Phi_{h,t} - \Phi_{t,h})^T \beta^r = \mathcal{M}$	NC
Negation	$(h, r_1, t) \Leftrightarrow \neg(h, r_2, t)$	$f_{h,t}^{r_1} = \mathcal{M} - f_{h,t}^{r_2} + \xi_{h,t}$	$\Phi_{h,t}^T (\beta^{r_1} + \beta^{r_2}) = \mathcal{M} + \xi_{h,t}$	NC
Implication	$(h, r_1, t) \Rightarrow (h, r_2, t)$	$f_{h,t}^{r_1} \leq f_{h,t}^{r_2}$	$\Phi_{h,t}^T (\beta^{r_1} - \beta^{r_2}) \leq 0$	$\max(\sum_i (\beta_i^{r_1} - \beta_i^{r_2}) + \xi_{Im}, 0)$
Inverse	$(h, r_1, t) \Rightarrow (t, r_2, h)$	$f_{h,t}^{r_1} \leq f_{t,h}^{r_2}$	$\Phi_{h,t}^T \beta^{r_1} - \Phi_{t,h}^T \beta^{r_2} \leq 0$	$\max(\Phi_{h,t}^T \beta^{r_1} - \Phi_{t,h}^T \beta^{r_2} + \xi_{In}, 0)$
Reflexivity	$(h, r, h)$	$f_{h,h}^r = \mathcal{M} - \xi_{h,h}$	$\Phi_{h,h}^T \beta^r = \mathcal{M} - \xi_{h,h}$	NC
Irreflexive	$\neg(h, r, h)$	$f_{h,h}^r = \xi_{h,h}$	$\Phi_{h,h}^T \beta^r = \xi_{h,h}$	NC
Transitivity	$(h, r, t) \wedge (t, r, s) \Rightarrow (h, r, s)$	$\sigma(f_{h,s}^r) \geq \sigma(f_{h,t}^r) \times \sigma(f_{t,s}^r)$	$\sigma(\Phi_{h,t} \beta^r) \times \sigma(\Phi_{t,s} \beta^r) - \sigma(\Phi_{h,s}^T \beta^r) \leq 0$	$\max(\sigma(\Phi_{h,t} \beta^r) \times \sigma(\Phi_{t,s} \beta^r) - \sigma(\Phi_{h,s}^T \beta^r) + \xi_{Tr}, 0)$
Composition	$(h, r_1, t) \wedge (t, r_2, s) \Rightarrow (h, r_3, s)$	$\sigma(f_{h,s}^{r_1}) \geq \sigma(f_{h,t}^{r_2}) \times \sigma(f_{t,s}^{r_3})$	$\sigma(\Phi_{h,t} \beta^{r_1}) \times \sigma(\Phi_{t,s} \beta^{r_2}) - \sigma(\Phi_{h,s}^T \beta^{r_3}) \leq 0$	$\max(\sigma(\Phi_{h,t} \beta^{r_1}) \times \sigma(\Phi_{t,s} \beta^{r_2}) - \sigma(\Phi_{h,s}^T \beta^{r_3}) + \xi_{Co}, 0)$

Table 1: Formulation and representation of rules (NC: Not considered for implementation).

# KGE - RotatE

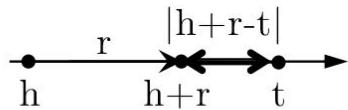
## Tensor Factorization

## Translation

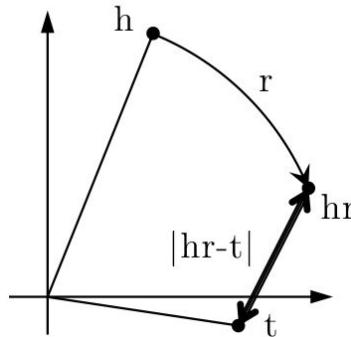
Idea:

Entities are vectors  
in **complex space**

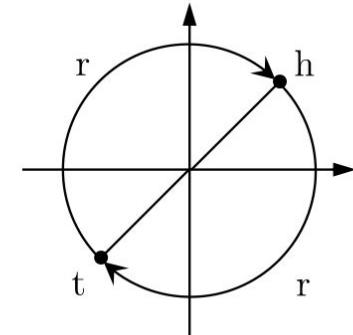
Relations: rotations  
in **complex space**



(a) TransE models  $\mathbf{r}$  as translation in real line.



(b) RotatE models  $\mathbf{r}$  as rotation in complex plane.



(c) RotatE: an example of modeling symmetric relations  $\mathbf{r}$  with  $r_i = -1$

Figure 1: Illustrations of TransE and RotatE with only 1 dimension of embedding.

**Score function:**

$$d_r(\mathbf{h}, \mathbf{t}) = \|\mathbf{h} \circ \mathbf{r} - \mathbf{t}\| \quad |r_i| = 1$$

**Loss & Optimization:**

$$L = -\log \sigma(\gamma - d_r(\mathbf{h}, \mathbf{t})) - \sum_{i=1}^n \frac{1}{k} \log \sigma(d_r(\mathbf{h}'_i, \mathbf{t}'_i) - \gamma),$$

# KGE - RotatE & Patterns

## Translation

Model	Score Function	Symmetry	Antisymmetry	Inversion	Composition
SE	$-\ W_{r,1}h - W_{r,2}t\ $	$\times$	$\times$	$\times$	$\times$
TransE	$-\ h + r - t\ $	$\times$	$\checkmark$	$\checkmark$	$\checkmark$
TransX	$-\ g_{r,1}(h) + r - g_{r,2}(t)\ $	$\checkmark$	$\checkmark$	$\times$	$\times$
DistMult	$\langle h, r, t \rangle$	$\checkmark$	$\times$	$\times$	$\times$
ComplEx	$\text{Re}(\langle h, r, t \rangle)$	$\checkmark$	$\checkmark$	$\checkmark$	$\times$
RotatE	$-\ h \circ r - t\ $	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$

Table 2: The pattern modeling and inference abilities of several models.

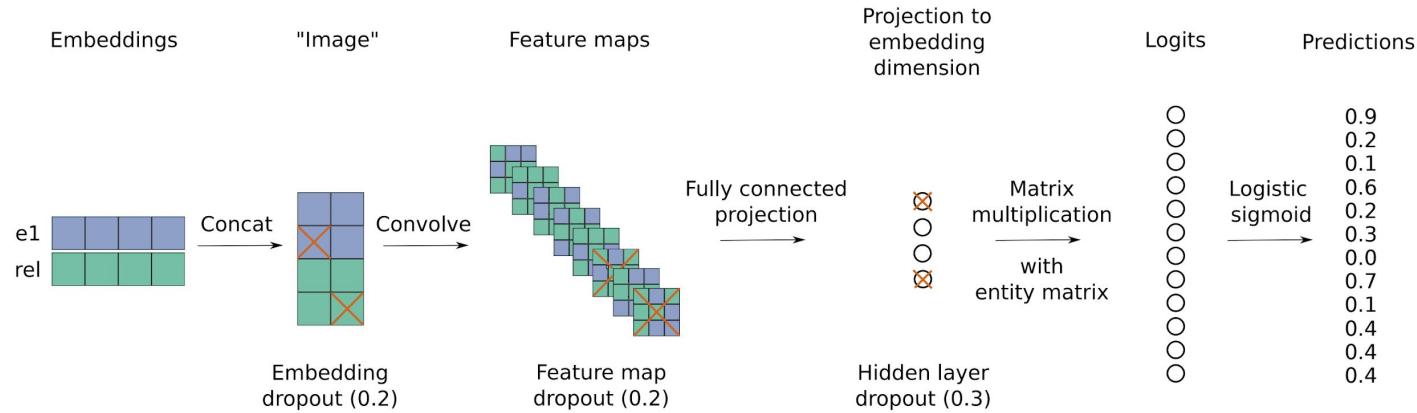
# KGE - ConvE

Tensor  
Factorization

Translation

Convolution

Goal: CNNs for predicting a probability of the object



**Score function:**  $\psi_r(\mathbf{e}_s, \mathbf{e}_o) = f(\text{vec}(f([\overline{\mathbf{e}_s}; \overline{\mathbf{r}_r}] * \omega)) \mathbf{W}) \mathbf{e}_o,$

**Loss & Optimization:**  $\mathcal{L}(p, t) = -\frac{1}{N} \sum_i (t_i \cdot \log(p_i) + (1-t_i) \cdot \log(1-p_i)),$

# KGE - CoKE

## Tensor Factorization

## Translation

## Transformer

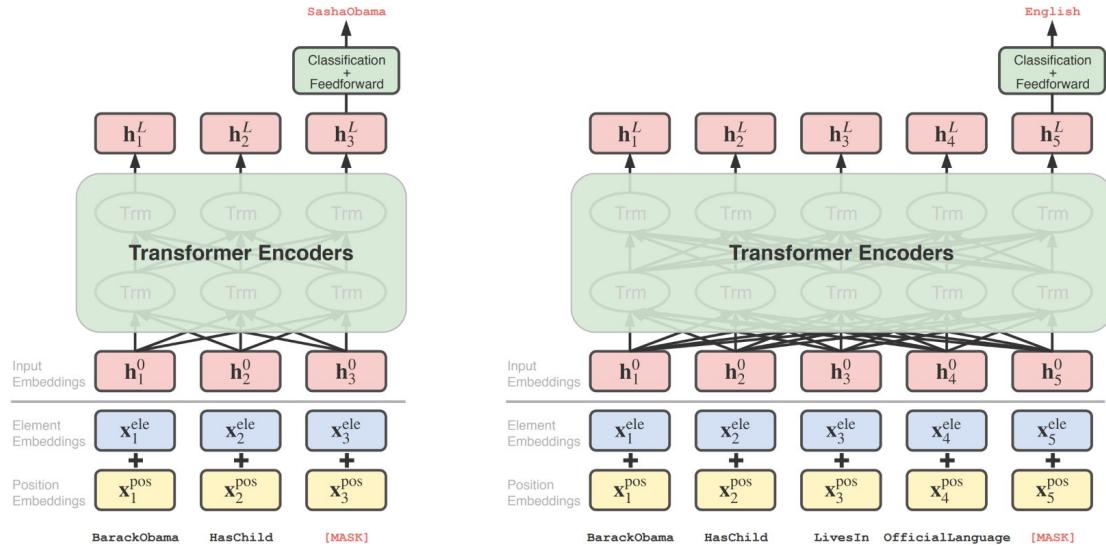


Figure 2: Overall framework of CoKE. An edge (left) or a path (right) is given as an input sequence, with an entity replaced by a special token **[MASK]**. The input is then fed into a stack of Transformer encoder blocks. The final hidden state corresponding to **[MASK]** is used to predict the target entity.

# KGE - CompGCN Encoder

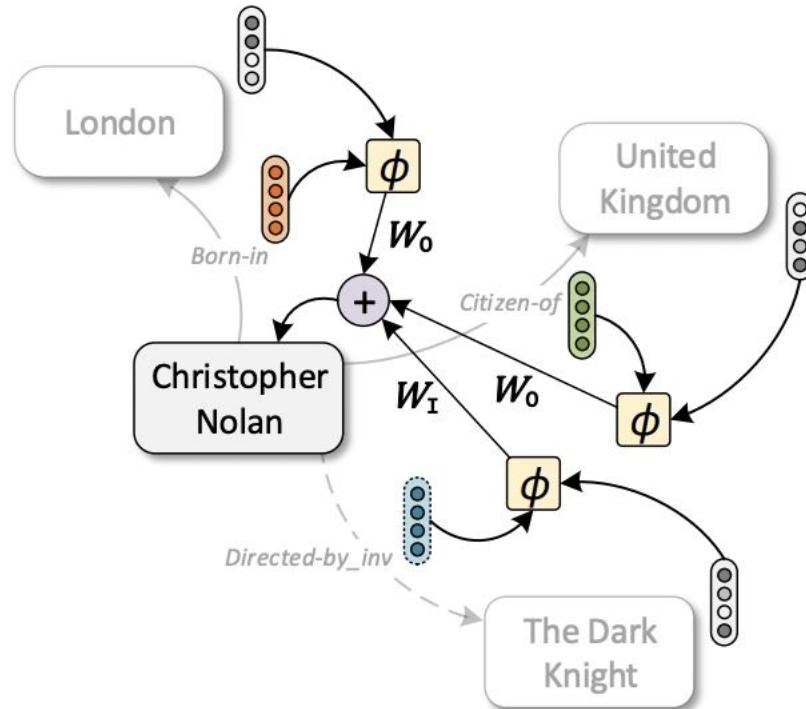
Tensor  
Factorization

Translation

Transformer

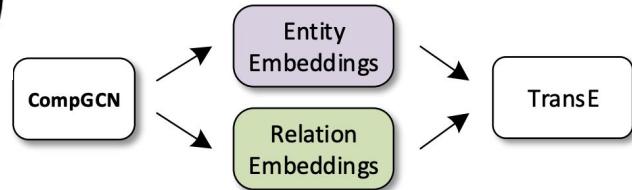
Graph Neural  
Nets

- Message Passing
- Encoder-Decoder
- Many architectures

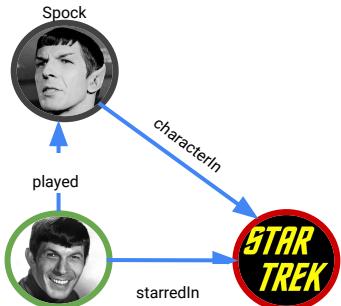


$$\mathbf{h}_v = f \left( \sum_{(u,r) \in \mathcal{N}(v)} \mathbf{W}_{\lambda(r)} \phi(\mathbf{x}_u, \mathbf{z}_r) \right)$$

**CompGCN Update**



# KGE - Training



Optimization

Loss Function

Negative Sampling

Entity matrix

$$\mathbf{E} : \mathbb{R}^{|E| \times n}$$

$$\text{Spock} = [0.1, 0.2, 0.3]$$

$$\text{Leonard Nimoy} = [0.4, 0.8, 0.1]$$

$$\text{Star Trek} = [0.22, 0.34, 0.87]$$

Relations matrix

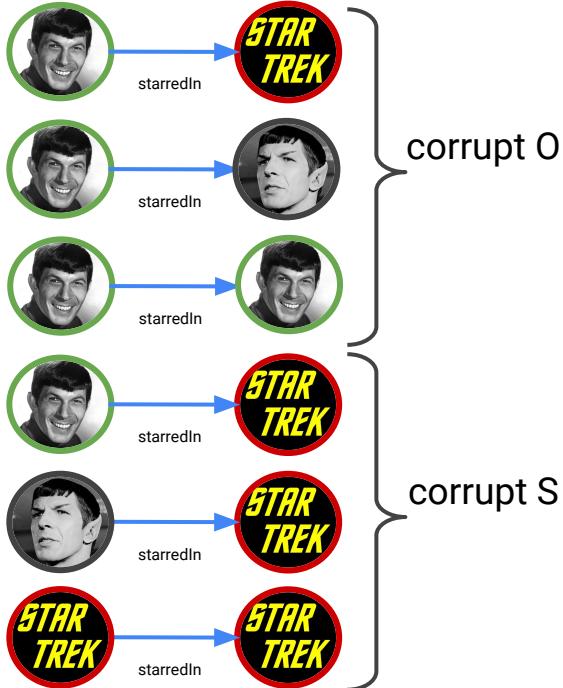
$$\mathbf{W} : \mathbb{R}^{|k| \times n}$$

$$\text{characterIn} = [0.1, 0.1, 0.6]$$

$$\text{played} = [0.2, 0.3, 0.4]$$

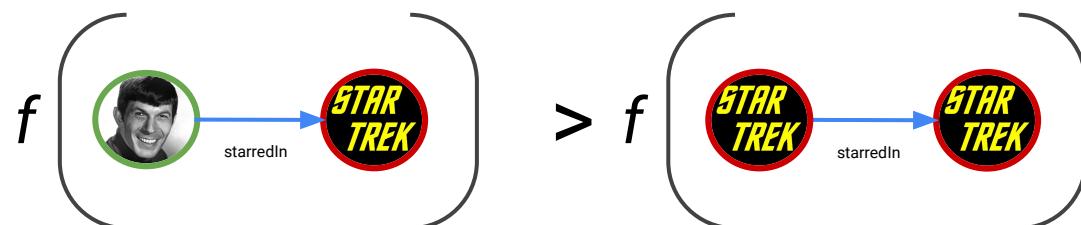
$$\text{starredIn} = [0.9, -0.2, 0.1]$$

# KGE - Training - Negative Sampling + Margin Loss

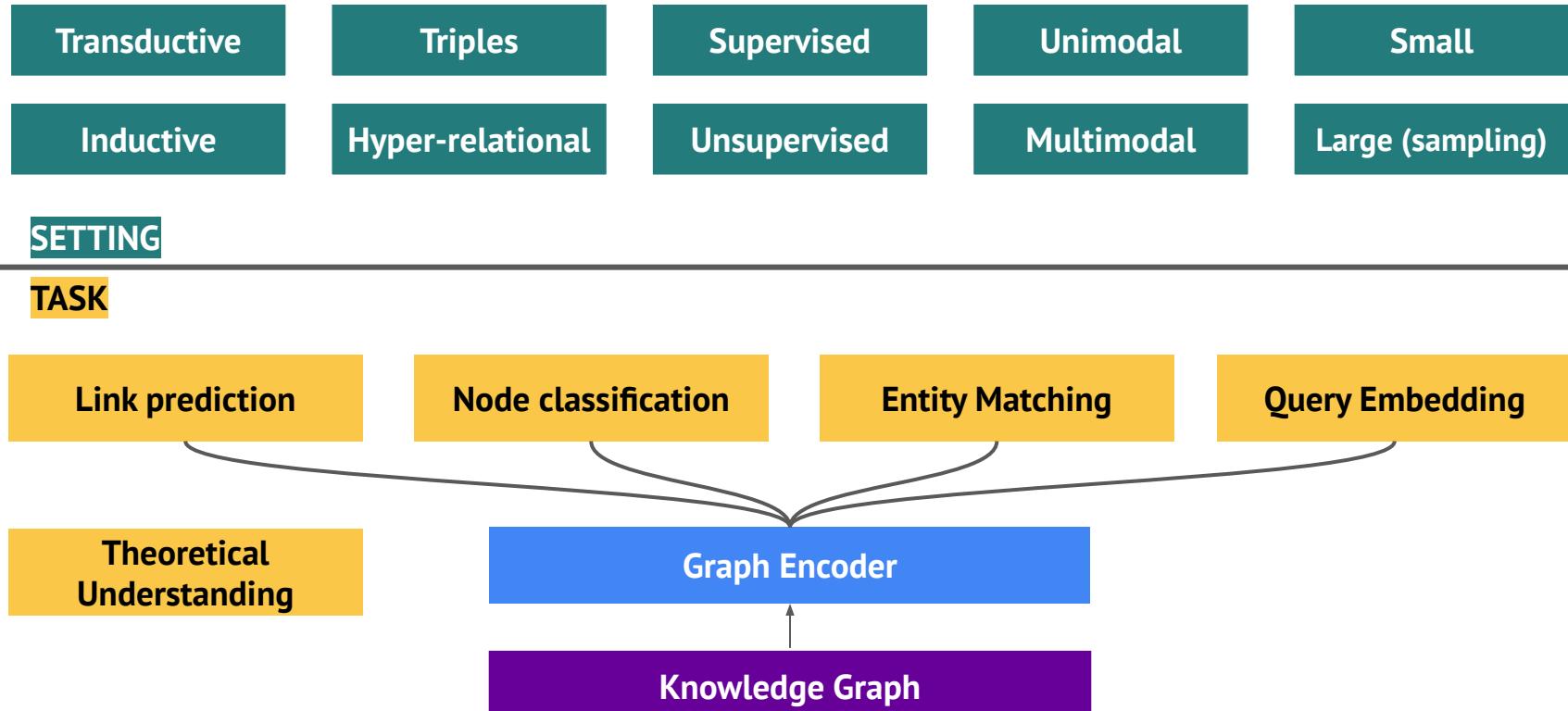


$$L(\Omega) = \sum_{(e_1, r, e_2) \in T} \sum_{(e'_1, r, e'_2) \in T'} \max\{S_{(e'_1, r, e'_2)} - S_{(e_1, r, e_2)} + 1, 0\}$$

Negative sampling: incorrect triples should have lower (higher) score than correct triples



# Big Picture in $\mathbb{R}^5$



# Conclusion

