

# README 自主导航

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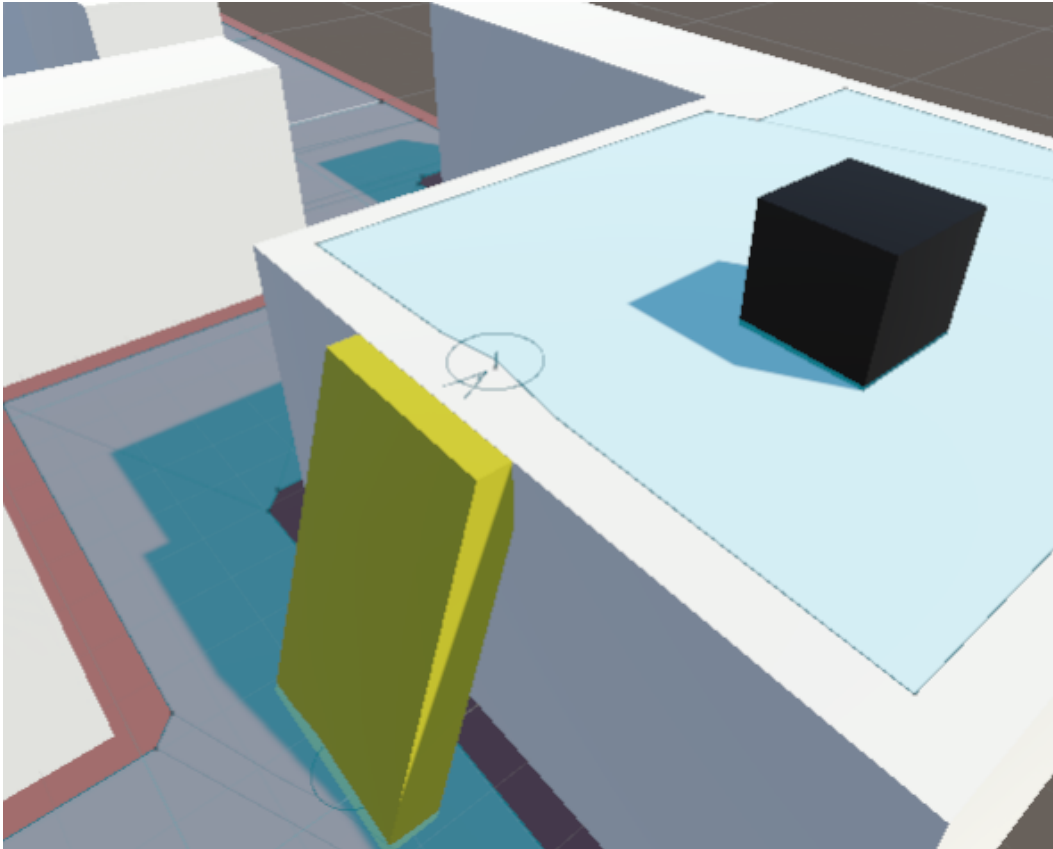
邮箱 1298955072@qq.com (有问题比如导入包失败等 请联系)

## 1. Scene1

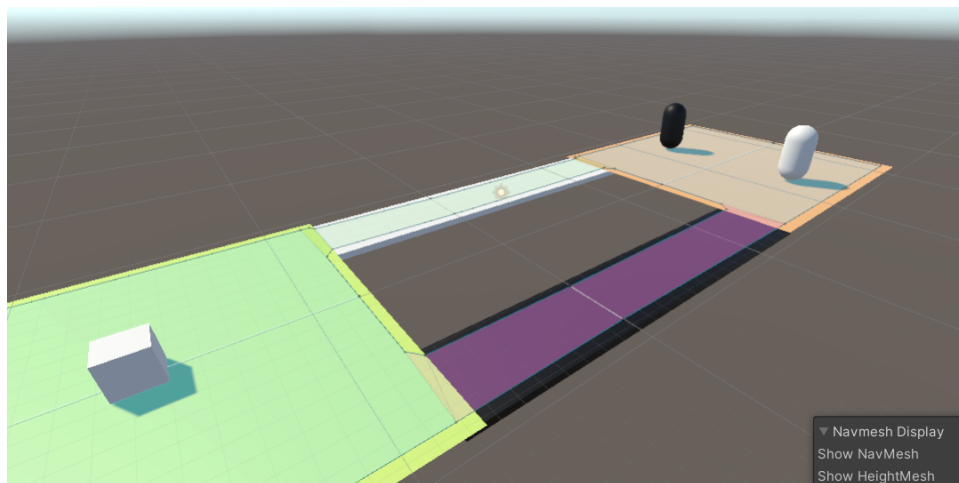


实现Off mesh link案例

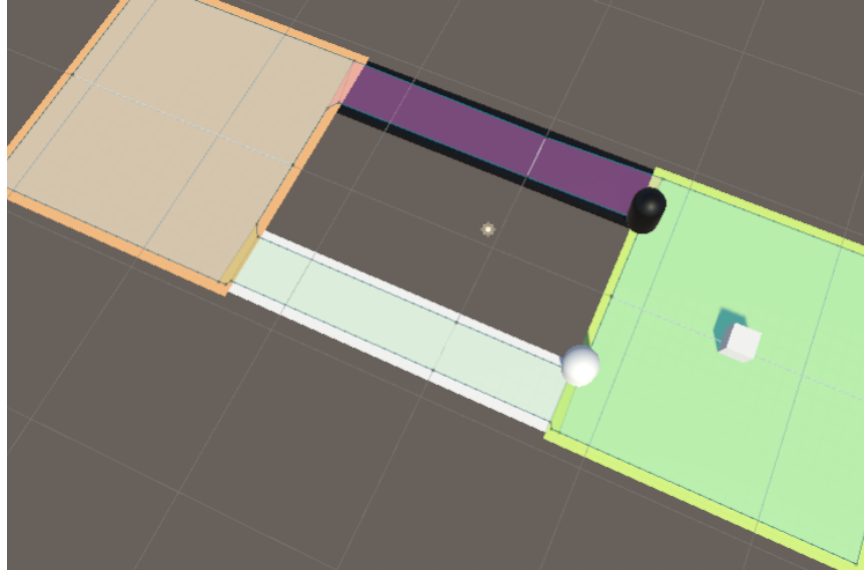
小球为nav agent, 小方块为destination



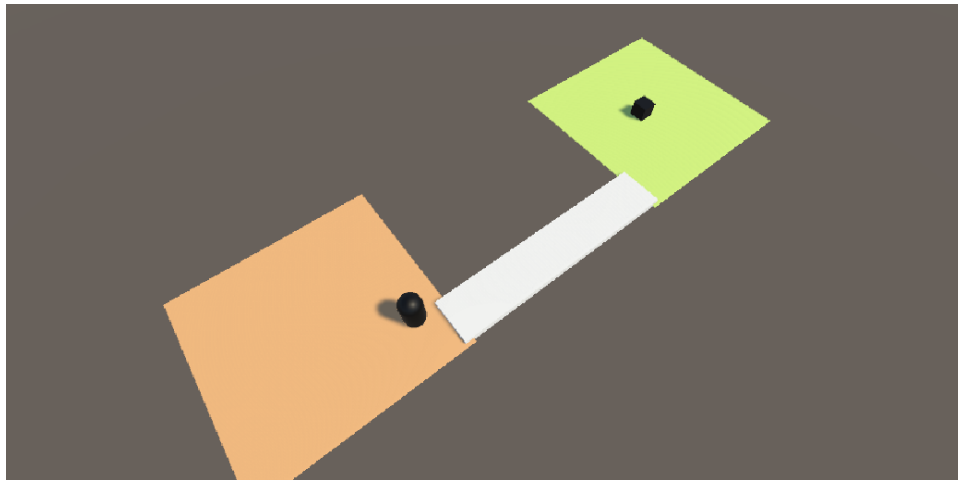
## 2. Scene2



实现网格控制不同的胶囊按照不同路径寻路

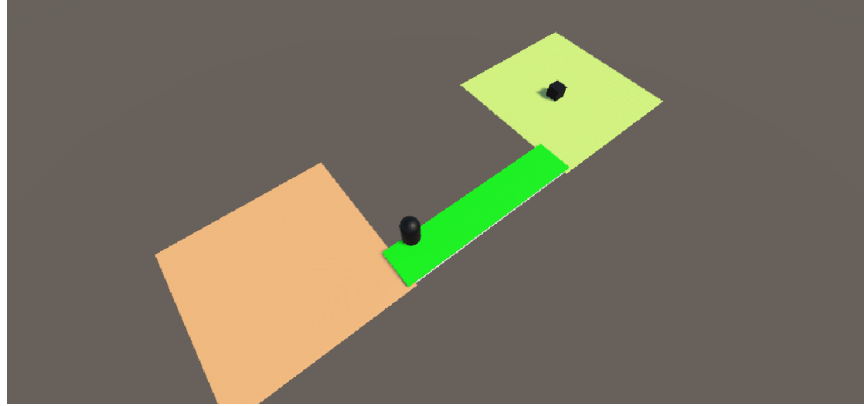


### 3. Scene3

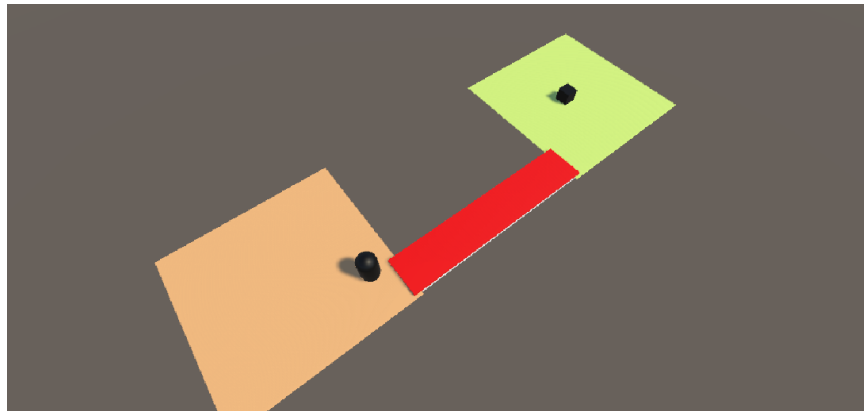


实现Nav mesh obstacle

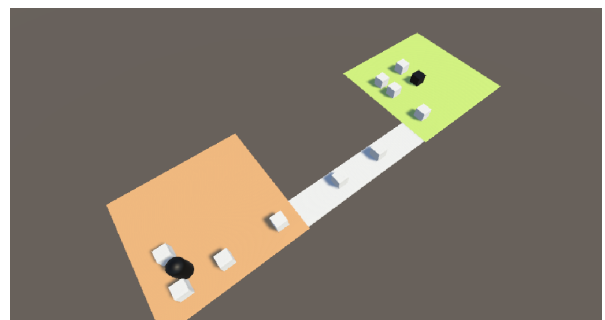
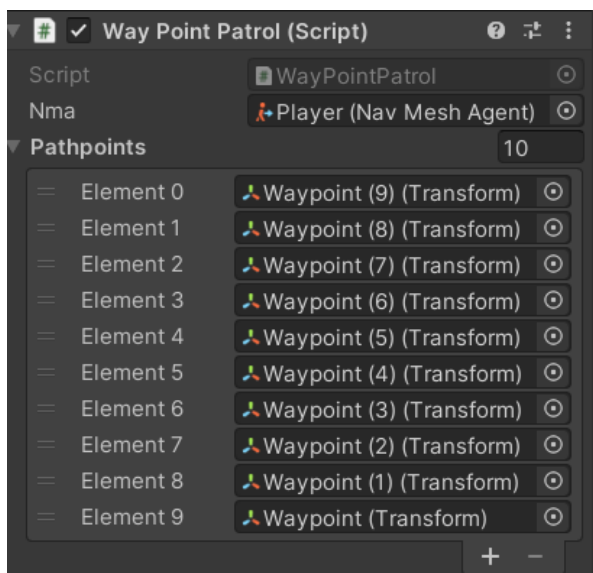
点击鼠标左键,控制Nav mesh obstacle组件为false

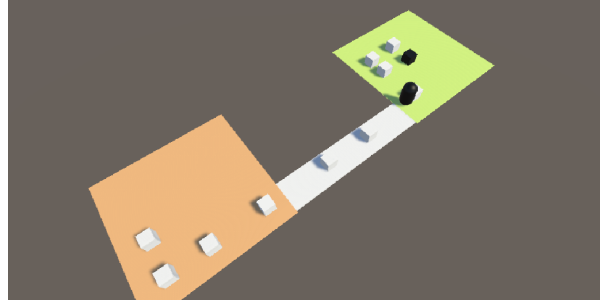


松开鼠标左键,控制Nav mesh obstacle组件为true



## 4. Scene4





实现**设定自主巡航路径**，实现**自助导航案例**。