CPE301 – SPRING 2019

MIDTERM 1

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Primary Github address: https://github.com/miggnuggets/submissions.git

Directory: Repository_301

1. COMPONENTS LIST AND CONNECTION BLOCK DIAGRAM w/ PINS

List of Components used Atmega328P, ESP2866, USB serial, and LM35

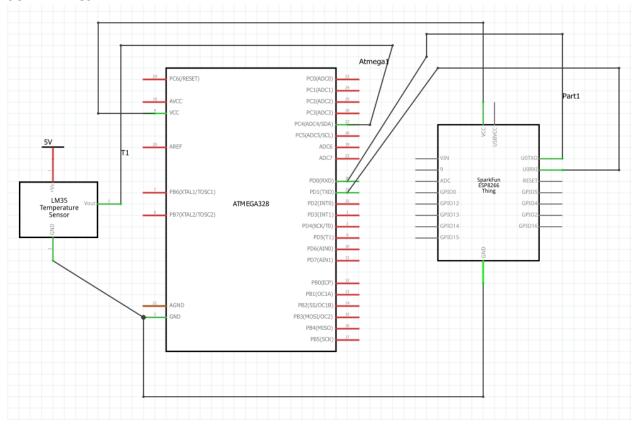
2. INITIAL/MODIFIED/DEVELOPED CODE OF TASK 1/A

```
#define F CPU 16000000UL
#define BAUD 9600 // BAUD rate
#define BAUD PRESCALLER F CPU/16/BAUD-1 // Prescaler
#include <avr/io.h>
#include <util/delay.h>
#include <stdio.h>
#include <avr/interrupt.h>
#include <stdlib.h>
void read_adc(void); //Read Temp using ADC
void adc_init(void); // Start ADC
void USART_init( unsigned int ubrr ); // Start USART communication
void USART_tx_string(char *data); //Print String USART
volatile unsigned int adc_temp; // Volatile temp variable
volatile unsigned int tempF; // Volatile Fahrenheit
volatile unsigned int tempC; // Volatile Celsius
char outs[256]; // String array used for sending USART commands
volatile char received_data; // String array used for receiving USART communication
int main(void) {
      adc init(); // Start A2D Converter on PC4
      USART init(BAUD PRESCALLER); // Start the USART (RS232 interface)
      _delay_ms(500); // Delay for hardware start up
      while(1)
      {
             // Constantly read the temp from ADC and send to thingspeak
             /* Start AT commands */
             //AT connect check
             unsigned char AT[] = "AT\r\n";
             //Set device mode, 1 = Station mode
```

```
unsigned char AT_CWMODE[] = "AT+CWMODE=1\r\n";
              //Perform Wifi connection, provide SSID and Password
              unsigned char AT_CWJAP[] = "AT+CWJAP=\"Michael iPhone\",\"hello dad\"\r\n";
              //Set device for single IP Address Mode
             unsigned char AT_CIPMUX[] = "AT+CIPMUX=0\r\n";
              // Start TCP connection to Thingspeak.com at port 80
              unsigned char AT CIPSTART[] =
"AT+CIPSTART=\"TCP\",\"api.thingspeak.com\",80\r\n";
              // Give upcoming string length
             unsigned char AT_CIPSEND[] = "AT+CIPSEND=100\r\n";
             // Send commands listed from above
              delay ms(200);
             USART_tx_string(AT);
              _delay_ms(5000);
             USART_tx_string(AT_CWMODE);
              delay ms(5000);
             USART_tx_string(AT_CWJAP);
              _delay_ms(15000);
             USART_tx_string(AT_CIPMUX);
              delay ms(10000);
             USART_tx_string(AT_CIPSTART);
              _delay_ms(10000);
             USART_tx_string(AT_CIPSEND);
             _delay_ms(5000);
             PORTC^=(1<<5);
             // Read next ADC value from LM35
             read_adc();
              // Convert temp into Celsius and Fahrenheit
              adc temp = (adc temp*500)/1023;
             tempC = adc_temp;
             tempF = (tempC*1.8)+32;
              // Send to thingspeak using provided link, website channel key, and field
location
             snprintf(outs, sizeof(outs), "GET
https://api.thingspeak.com/update?api_key=G7MZKO6271CLAB83&field1=%3d\r\n", tempF);
             USART_tx_string(outs);//send data
             _delay_ms(10000);
       }
}
/* ADC Start */
void adc_init(void) // Start ADC
{
       ADMUX = (0<<REFS1) | // Reference Selection Bits
       (1<<REFS0) | // AVcc - external cap at AREF
       (0<<ADLAR) | // ADC Left Adjust Result
       (1<<MUX2) | // Analog Channel Selection Bits
       (0<<MUX1) | // ADC2 (PC2 PIN25)
       (0<<MUX0); // 010
       ADCSRA = (1<<ADEN) | // ADC Enable
       (0<<ADSC) | // ADC Start Conversion
       (0<<ADATE) | // ADC Auto Trigger Enable
```

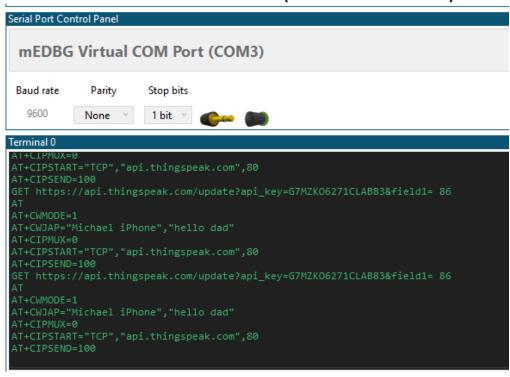
```
(0<<ADIF) | // ADC Interrupt Flag
       (0<<ADIE) // ADC Interrupt Enable
       (1<<ADPS2) │ // ADC Prescaler Select Bits
       (0<<ADPS1)
       (1<<ADPS0);
}
/* Read value from ADC */
void read_adc(void) {
       unsigned char i =4;
       adc_temp = 0; // Start adc_temp variable
       while (i--) {
              ADCSRA |= (1<<ADSC);
              while(ADCSRA & (1<<ADSC));</pre>
              adc_temp+= ADC;
              _delay_ms(50);
       adc_temp = adc_temp / 4; // Average a few samples
}
/* Start USART communication (RS-232) */
void USART_init( unsigned int ubrr ) {
       UBRROH = (unsigned char)(ubrr>>8);
       UBRROL = (unsigned char)ubrr;
       UCSRØB = (1 << TXENØ) | (1 << RXENØ) | (1 << RXCIEØ); // Enable receiver,
transmitter & RX interrupt
      UCSR0C |= (1<<UCSZ01) | (1 << UCSZ00);</pre>
}
/* USART string sender (RS-232) */
void USART_tx_string( char *data ) {
       while ((*data != '\0')) {
              while (!(UCSR0A & (1 <<UDRE0)));</pre>
              UDR0 = *data;
              data++;
       }
}
```

3. SCHEMATICS



Use fritzing.org

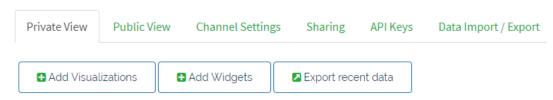
4. SCREENSHOTS OF EACH TASK OUTPUT (ATMEL STUDIO OUTPUT)



Midterm_1

Channel ID: **752257**Author: miggnuggets
Access: Private

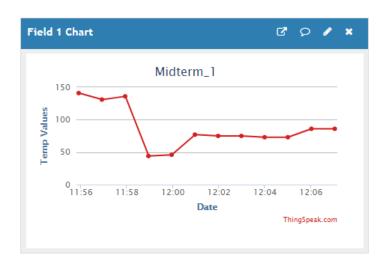
Temperature Sensor



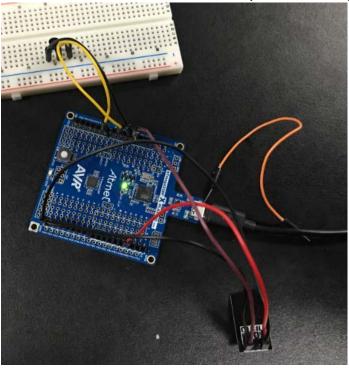
Channel Stats

Created: <u>about an hour ago</u>
Last entry: <u>less than a minute ago</u>

Entries: 12



5. SCREENSHOT OF EACH DEMO (BOARD SETUP)



6. VIDEO LINKS OF EACH DEMO https://youtu.be/OlwerILGVhs

7. GITHUB LINK OF THIS DA

https://github.com/miggnuggets/submissions.git

Student Academic Misconduct Policy http://studentconduct.unlv.edu/misconduct/policy.html

"This assignment submission is my own, original work".

Michael Johnson