

S5D9 Bus USBX sprintf float Example

by

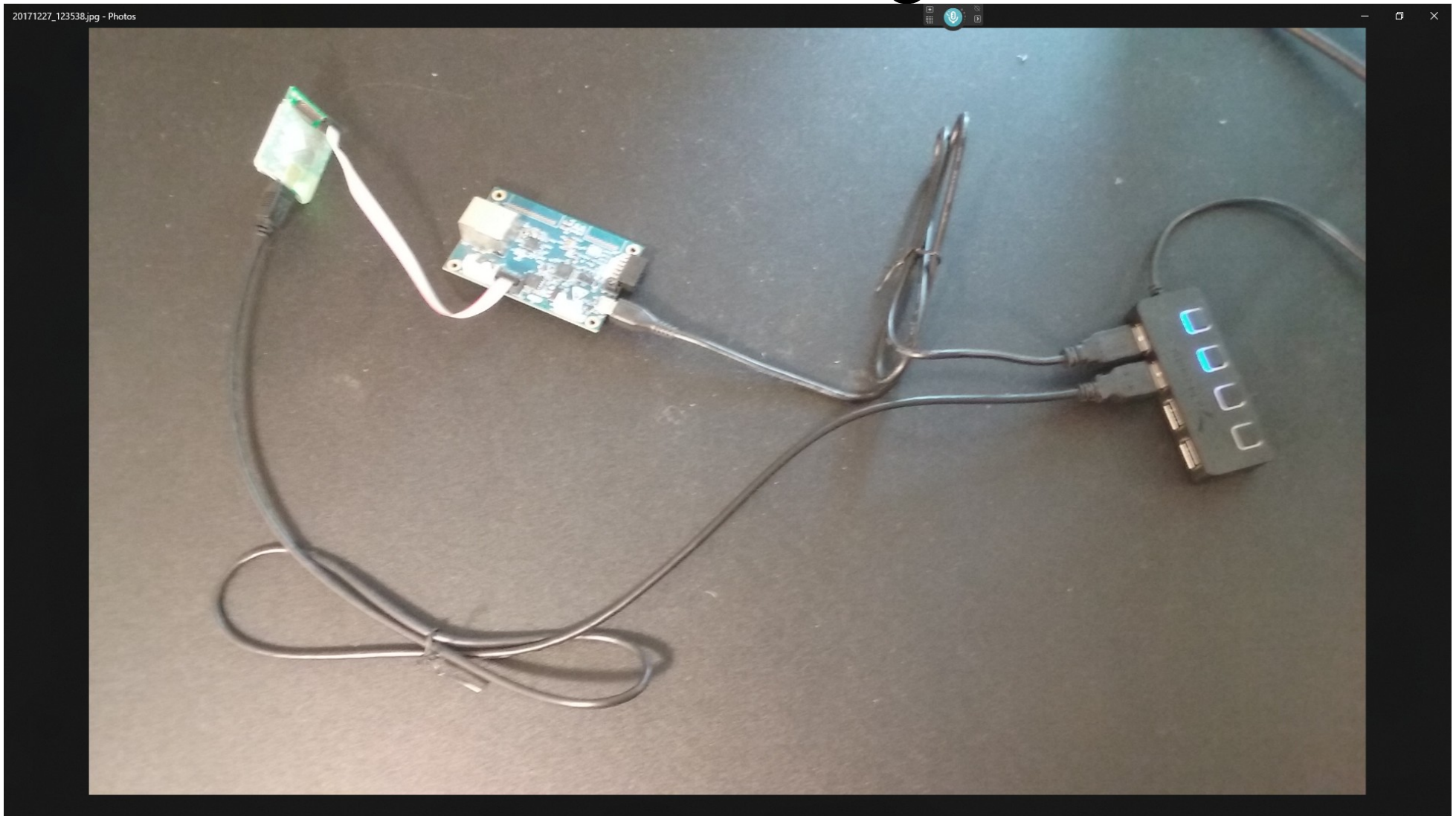
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<https://www.miketechuniverse.com>

- This example shows how to set up for floating number support in the sprintf function.

E2 Studio 5.4.0.023
SSP 1.3.0

Hardware Setup with S5D9 board and Jlink debug board.



Must create a new thread to use the USBX communication framework.

The screenshot shows the Synergy Configuration interface for the project `SSD9_ex9_usbx`. The **Threads** panel is active, displaying the **System Thread** and **System Thread Objects**. A context menu is open, showing the **Framework** option selected, with the **Communications Framework on sf_el_ux_comms** option highlighted. The **Properties** panel at the bottom left shows the **Thread** settings for the **system_thread**.

Property	Value
Symbol	system_thread
Name	System Thread
Stack size (bytes)	1024
Priority	15
Auto start	Enabled
Time slicing interval (ticks)	1

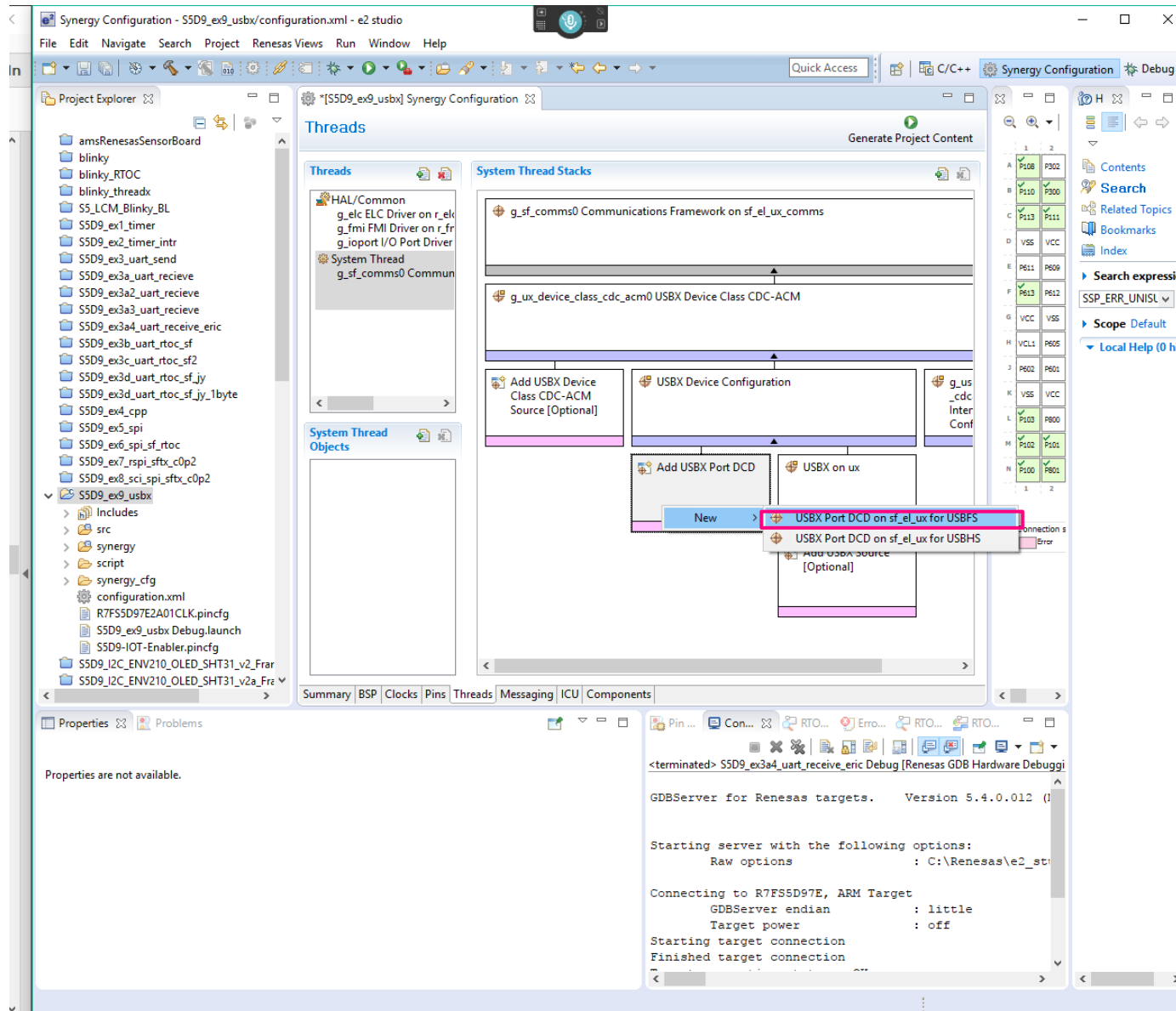
The **Console** panel at the bottom right shows the output of the GDB server:

```
<terminated> SSD9_ex3a4_uart_receive_eric Debug [Renesas GDB Hardware Debugging] GDB server
GDBServer for Renesas targets. Version 5.4.0.012 (Mar 16 2017 09:59:57)

Starting server with the following options:
Raw options : C:\Renesas\e2_studio 5.4.0.23 ssp 1.3.0\eclipse\

Connecting to R7FS5D97E, ARM Target
GDBServer endian : little
Target power : off
Starting target connection
Finished target connection
```

Choose the port



Property: Disable → Priority 3 Interrupt

The screenshot displays the Synergy Configuration tool interface. The left pane shows the Project Explorer with a tree view of files and folders. The main area is divided into several sections: 'Threads' on the left, 'System Thread Stacks' in the center, and a 'Properties' pane at the bottom. The 'System Thread Stacks' section shows a stack of threads, including 'g_sf_comms0 Communications Framework on sf_el_ux_comms', 'g_ux_device_class_cdc_acm0 USBX Device Class CDC-ACM', and 'g_sf_el_ux_dcd_fs_0 USBX Port DCD on sf_el_ux for USBFS'. The 'Properties' pane at the bottom shows the 'Full Speed Interrupt Priority' property for the 'g_sf_el_ux_dcd_fs_0 USBX Port DCD on sf_el_ux for USBFS' module. A dropdown menu is open for this property, showing a list of priorities from 0 to 15. The 'Priority 3 (CM4: valid, CM0+: low)' option is highlighted. The 'Properties' pane also shows the 'USB Controller Selection' property set to 'USBFS'. The 'Debug' pane on the right shows the 'GDBServer for Renesas targets' and the 'Starting server with the following options' section.

Threads

System Thread Stacks

g_sf_comms0 Communications Framework on sf_el_ux_comms

g_ux_device_class_cdc_acm0 USBX Device Class CDC-ACM

Add USBX Device Class CDC-ACM Source [Optional]

USBX Device Configuration

g_sf_el_ux_dcd_fs_0 USBX Port DCD on sf_el_ux for USBFS

USB

Priority 0 (highest)

Priority 1

Priority 2

Priority 3 (CM4: valid, CM0+: low) - not valid if using ThreadX

Priority 4 (CM4: valid, CM0+: invalid)

Priority 5 (CM4: valid, CM0+: invalid)

Priority 6 (CM4: valid, CM0+: invalid)

Priority 7 (CM4: valid, CM0+: invalid)

Priority 8 (CM4: valid, CM0+: invalid)

Priority 9 (CM4: valid, CM0+: invalid)

Priority 10 (CM4: valid, CM0+: invalid)

Priority 11 (CM4: valid, CM0+: invalid)

Priority 12 (CM4: valid, CM0+: invalid)

Priority 13 (CM4: valid, CM0+: invalid)

Priority 14 (CM4: valid, CM0+: invalid)

Priority 15 (CM4: lowest - not valid if using ThreadX, CM0+: invalid)

Disabled

g_sf_el_ux_dcd_fs_0 USBX Port DCD on sf_el_ux for USBFS

Property

Common

Full Speed Interrupt Priority

Module g_sf_el_ux_dcd_fs_0 USBX Port DCD on sf_el_ux for USBFS

Name

USB Controller Selection

g_sf_el_ux_dcd_fs_0

USBFS

GDBServer for Renesas targets. Version 5.4.0.012 (0)

Starting server with the following options:

Raw options : C:\Renesas\e2_st

Connecting to R7FS5D97E, ARM Target

GDBServer endian : little

Target power : off

Starting target connection

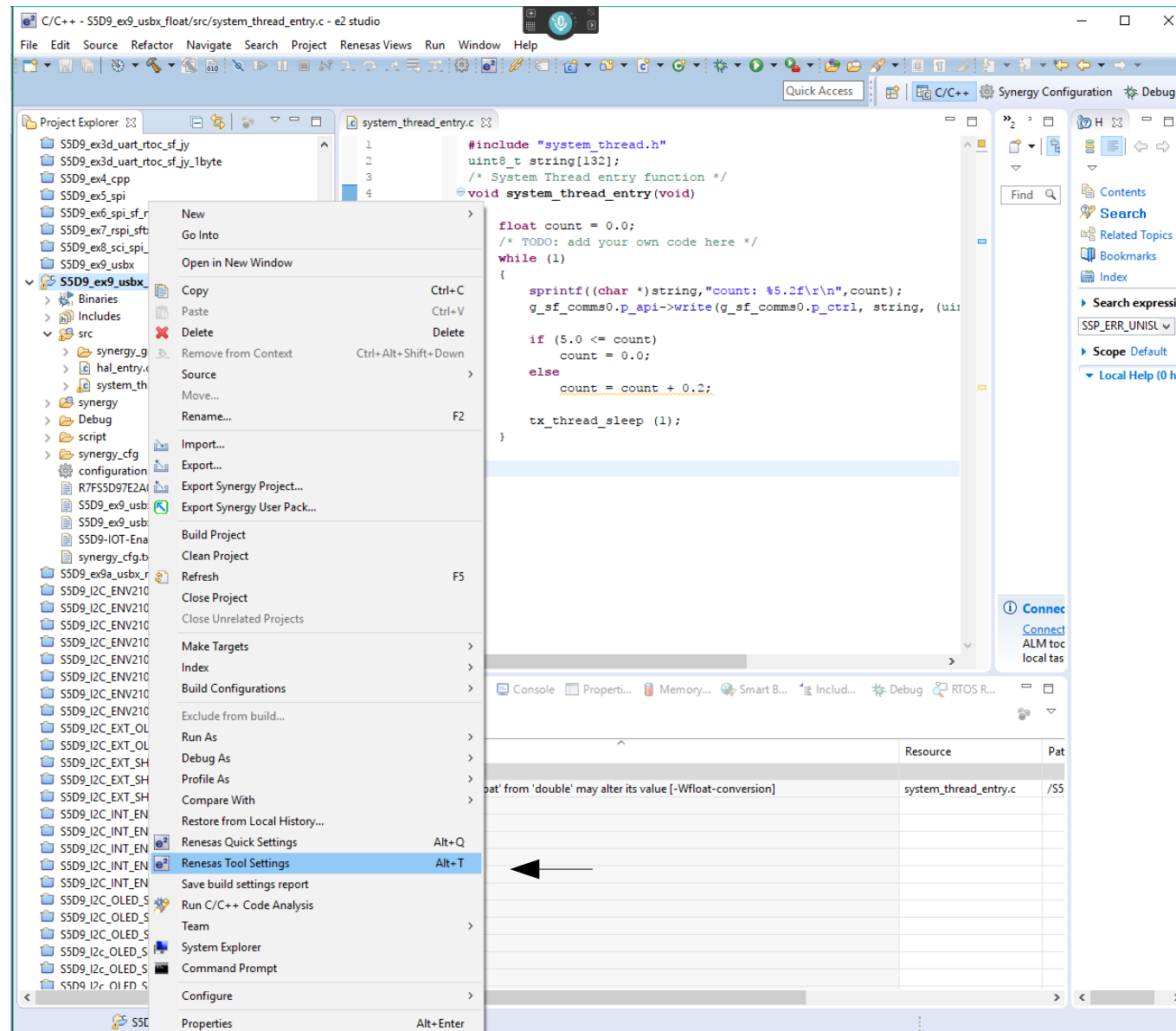
Finished target connection

Update the Class Code for uploading Window OS driver.

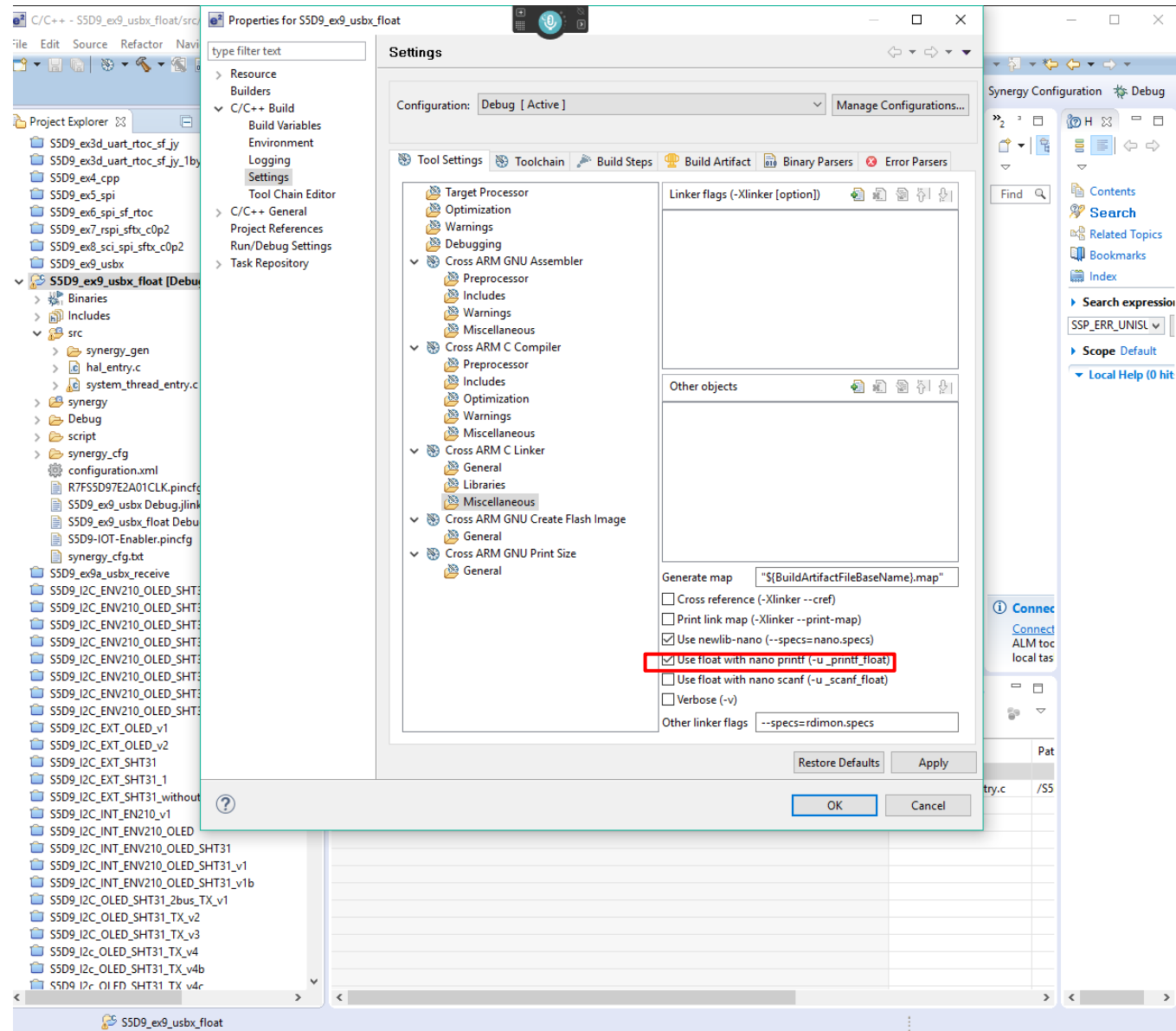
The screenshot shows the Synergy Configuration tool interface. The 'USB Device Configuration' section is expanded, and the 'Class Code' property is highlighted in pink. The value for 'Class Code' is 'Miscellaneous'. A red arrow points from the 'Class Code' label to the 'Miscellaneous' value.

Property	Value
Module USB Device Configuration	
Vendor ID	0x045B
Product ID	0x0000
Device Release Number	0x0000
Index of Manufacturer String Descriptor	0x00
Index of Product String Descriptor	0x00
Index of Serial Number String Descriptor	0x00
Class Code	Miscellaneous
Index of String Descriptor describing this configuration	0x00
Size of USB Descriptor in bytes for this configuration (Modify this value only for Vendor-specific configurations)	0x00
Number of Interfaces (Modify this value only for Vendor-specific configurations)	0x00
Self-Powered	Enable
Remote Wakeup	Disable
Maximum Power Consumption (in 2mA units)	50

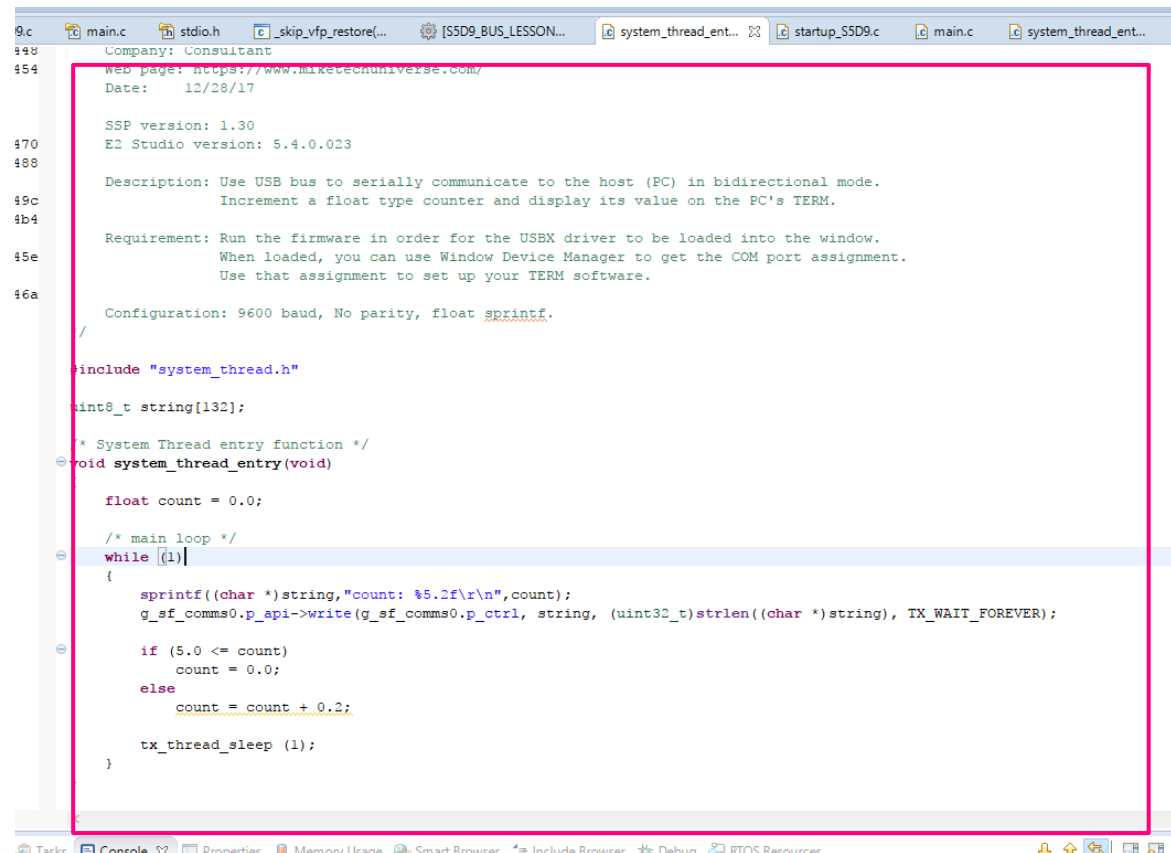
Choose Renesas Tool Settings



Check the box for float printf support



System Thread's forever loop.



```
9.c main.c stdio.h _skip_vfp_restore(...) [SSD9_BUS_LESSON...] system_thread_ent... startup_SSD9.c main.c system_thread_ent...
148 Company: Consultant
154 Web page: https://www.mikrotechniverse.com/
    Date: 12/28/17

    SSP version: 1.30
    E2 Studio version: 5.4.0.023

    Description: Use USB bus to serially communicate to the host (PC) in bidirectional mode.
    Increment a float type counter and display its value on the PC's TERM.

    Requirement: Run the firmware in order for the USBX driver to be loaded into the window.
    When loaded, you can use Window Device Manager to get the COM port assignment.
    Use that assignment to set up your TERM software.

    Configuration: 9600 baud, No parity, float sprintf.
/

#include "system_thread.h"

uint8_t string[132];

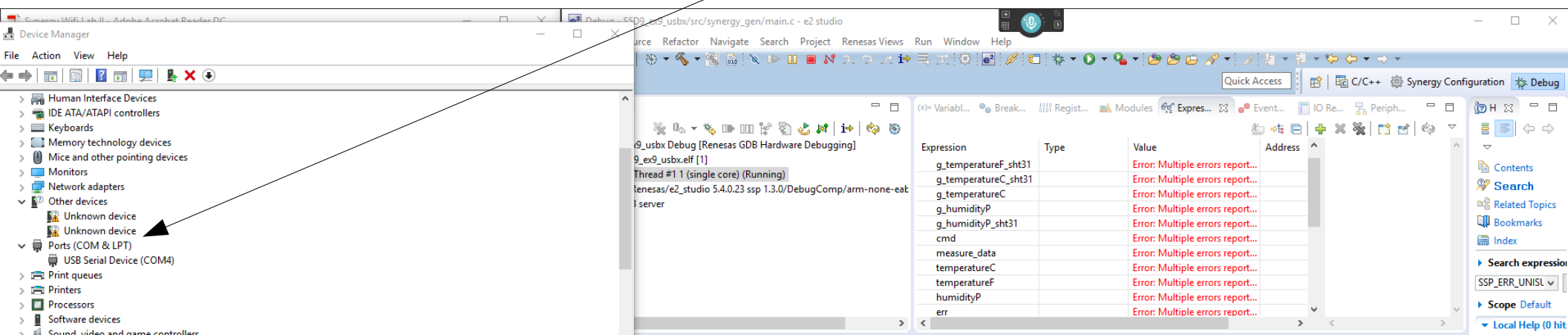
/* System Thread entry function */
void system_thread_entry(void)
{
    float count = 0.0;

    /* main loop */
    while (1)
    {
        sprintf((char *)string, "count: %5.2f\r\n", count);
        g_sf_comms0.p_api->write(g_sf_comms0.p_ctrl, string, (uint32_t)strlen((char *)string), TX_WAIT_FOREVER);

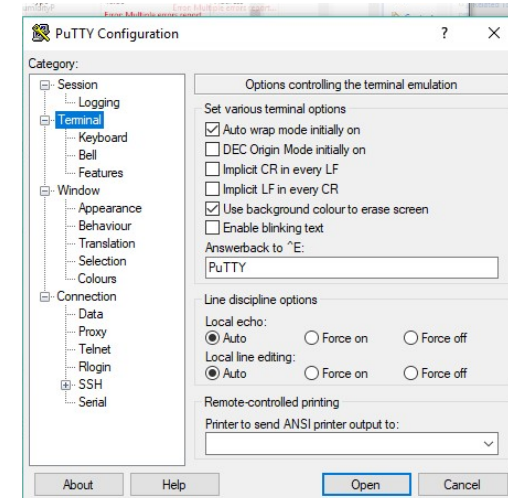
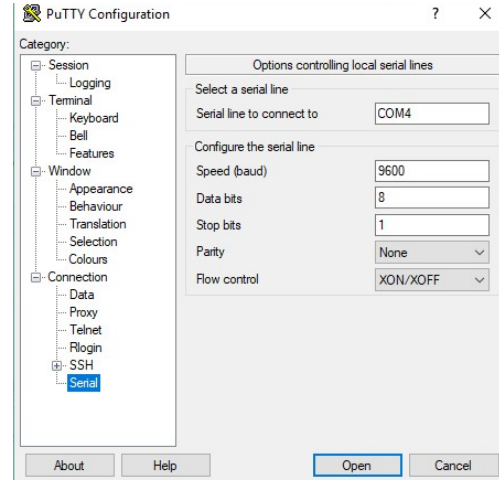
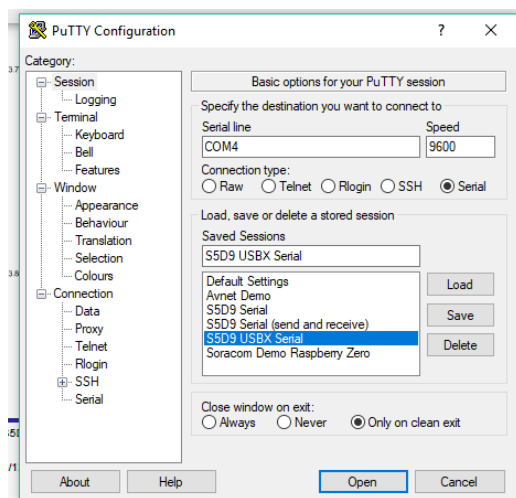
        if (5.0 <= count)
            count = 0.0;
        else
            count = count + 0.2;

        tx_thread_sleep (1);
    }
}
```

Run the firmware before you can see COM4



Serial port Setting



Run Serial Term Putty



```
COM4 - PuTTY
count: 2.60
count: 2.80
count: 3.00
count: 3.20
count: 3.40
count: 3.60
count: 3.80
count: 4.00
count: 4.20
count: 4.40
count: 4.60
count: 4.80
count: 5.00
count: 5.20
count: 0.00
count: 0.20
count: 0.40
count: 0.60
count: 0.80
count: 1.00
count: 1.20
count: 1.40
count: 1.60
c
```