S5D9 SPI Bus Example (R_SPI Framework Version)

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https://www.miketechuniverse.com

E2 Studio 5.4.0.023
SSP 1.3.0

s5d9_lab_spi (PMOD)

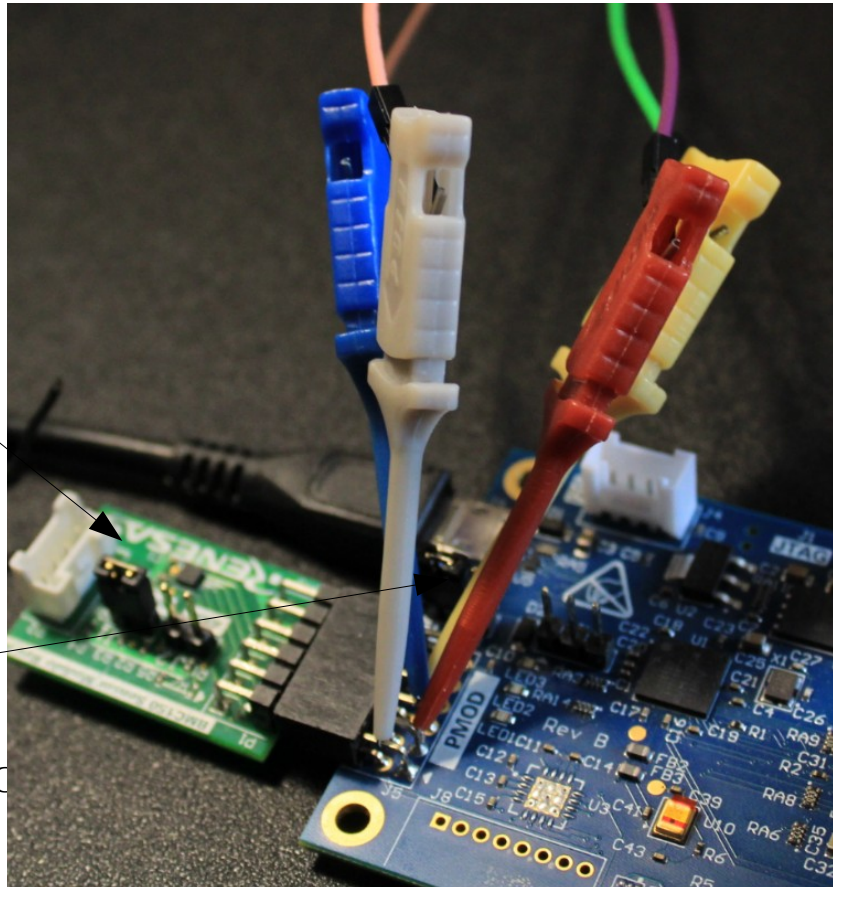
1. Use PMOD J5
2. SSP 1.3.0
3. E2 studio Version: 5.4.0.023

Project Summary

Board:	S5D9_IOT_ENABLER
Device:	R7FS5D97E2A01CLK
Toolchain:	GCC ARM Embedded
Toolchain Version:	4.9.3.20150529
SSP Version:	1.3.0

Selected software components:

Jumper close for SPI Mode

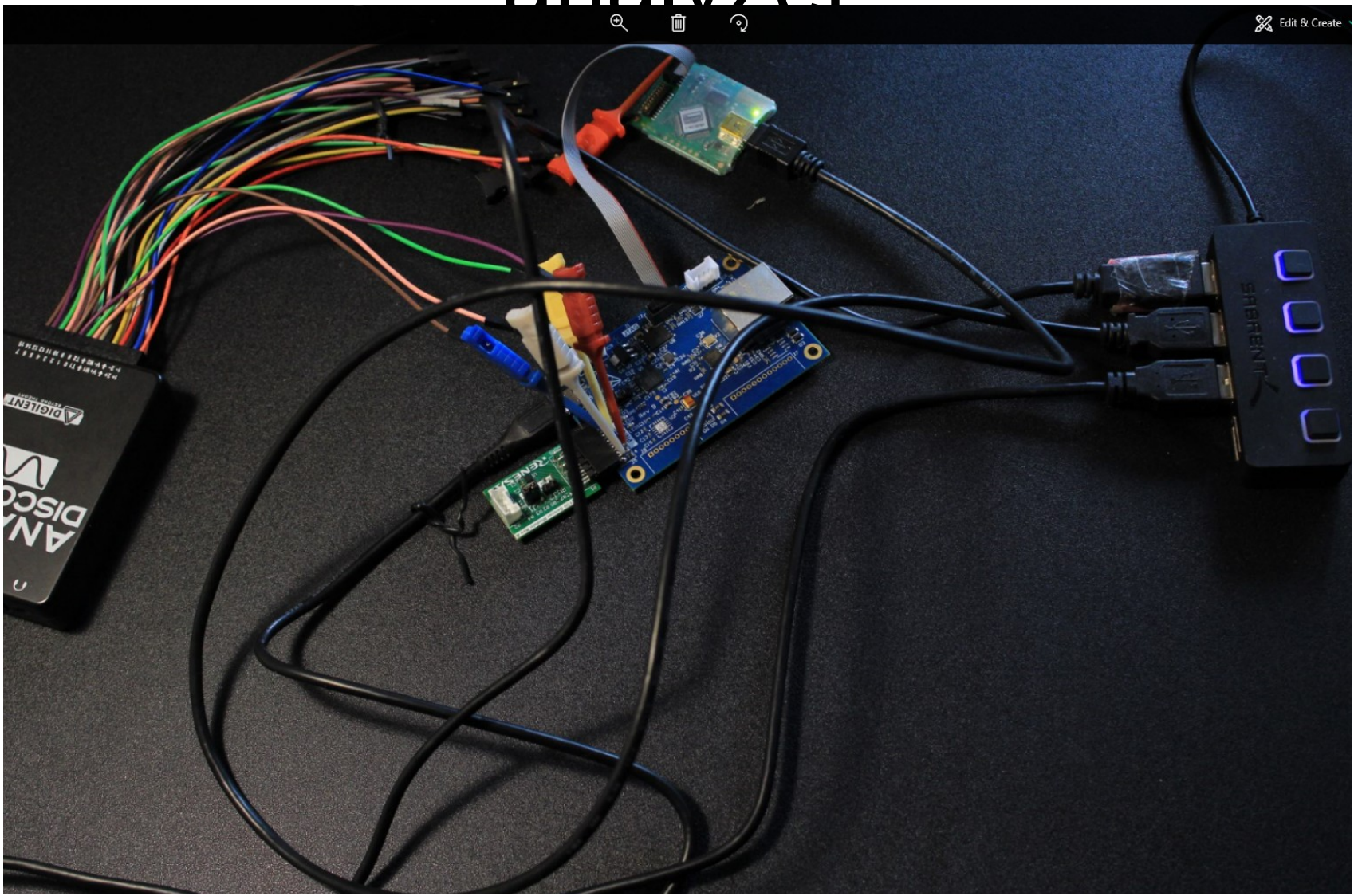


D0 P1 CSB
D2 P2 MOSI
D3 P3 MISO
D1 P4 CK
P5 GND
P6 VCC = 3.3V (due to JMP)

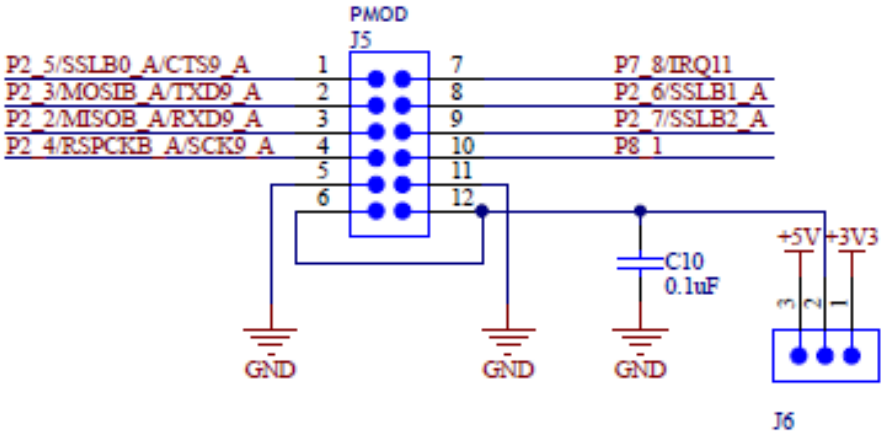
SPI Example by Michael C

Px = PMOD pin, Dx = Scope pin

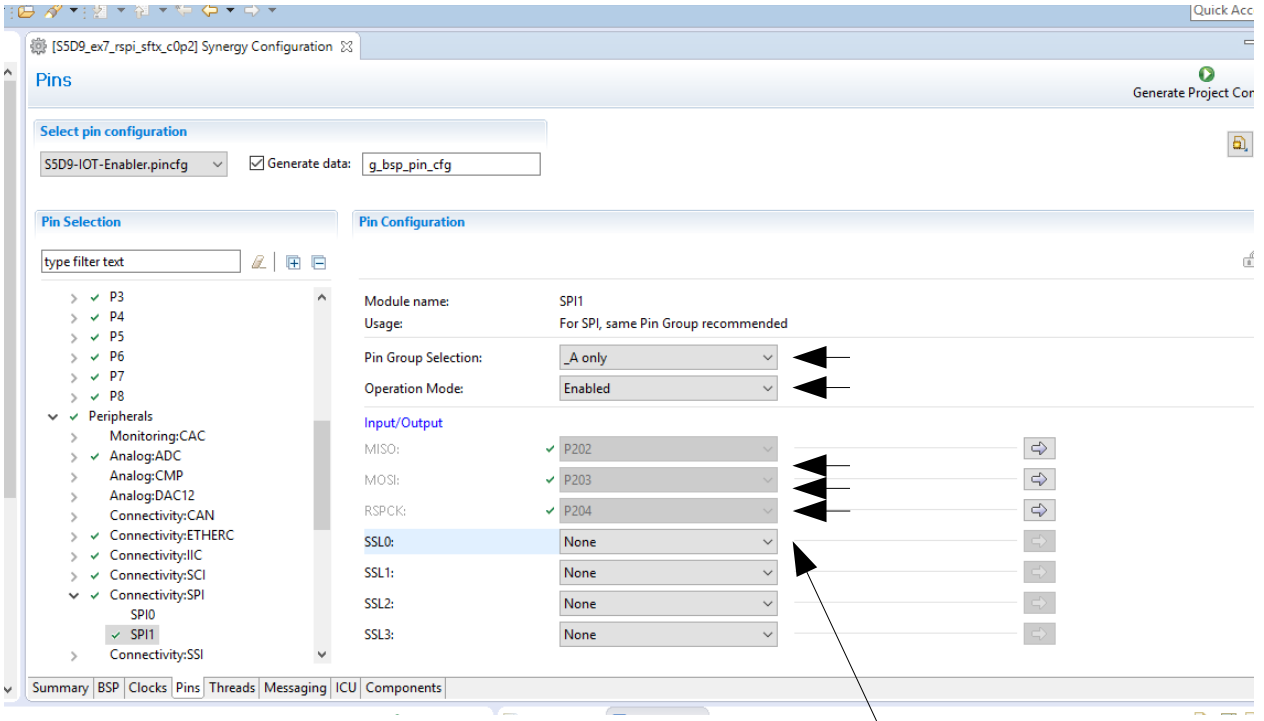
The complete setup with the logic analyzer



PMOD Schematic

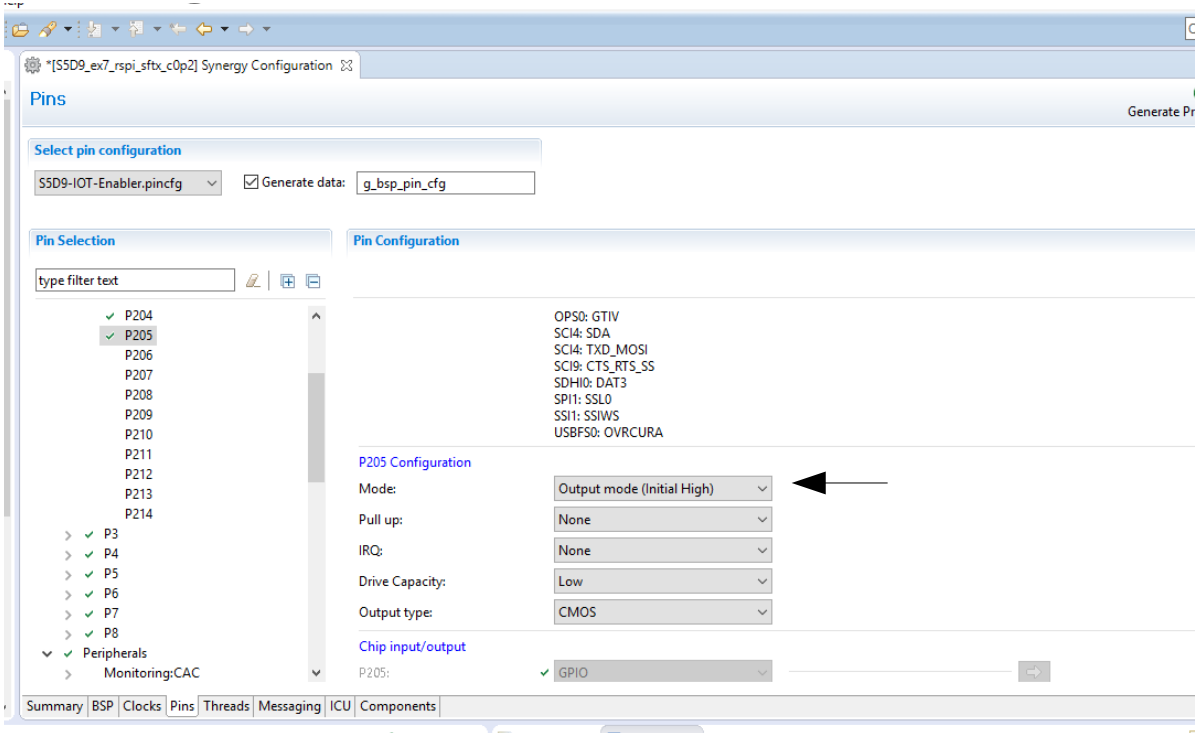


SPI1 (channel 1 !!!)

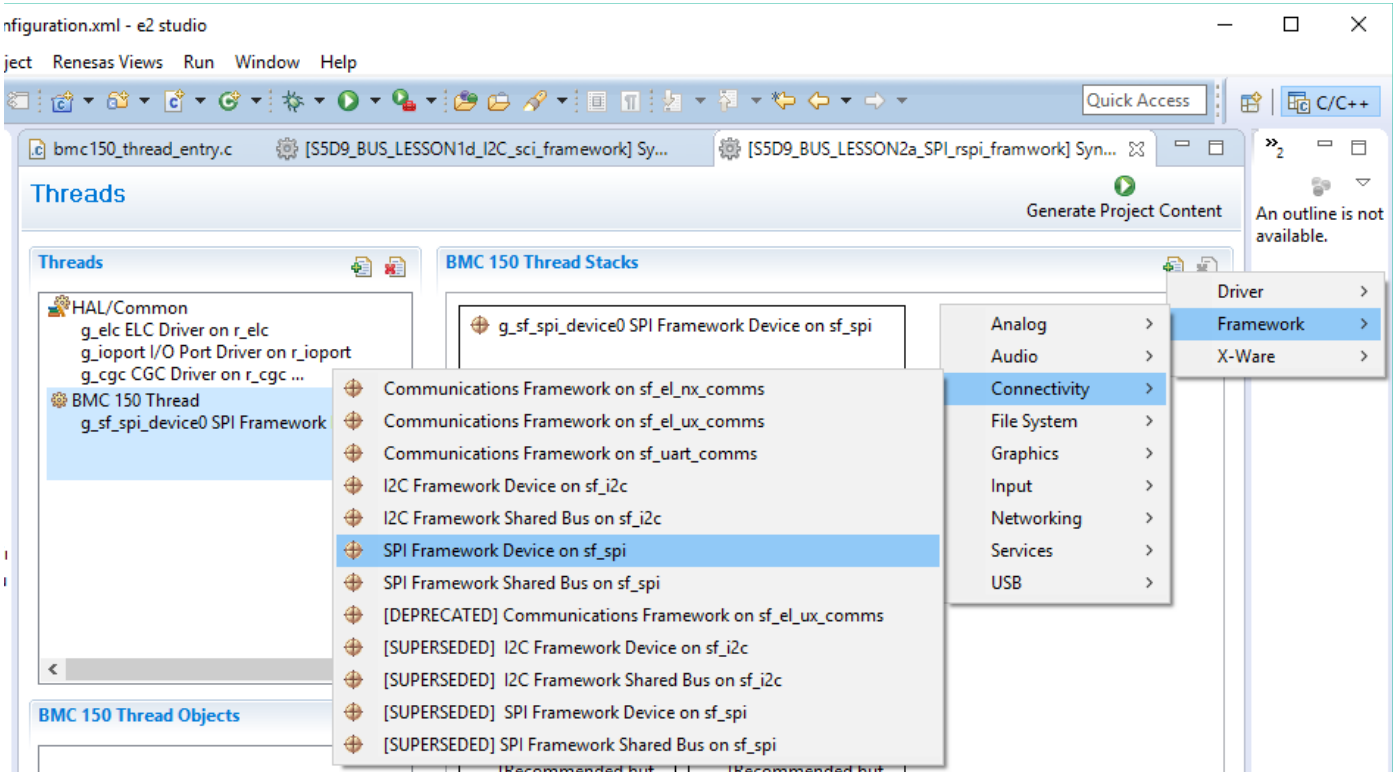


SSL0 is set to None because P2_5 will be controlled separately as a GPIO output pin.

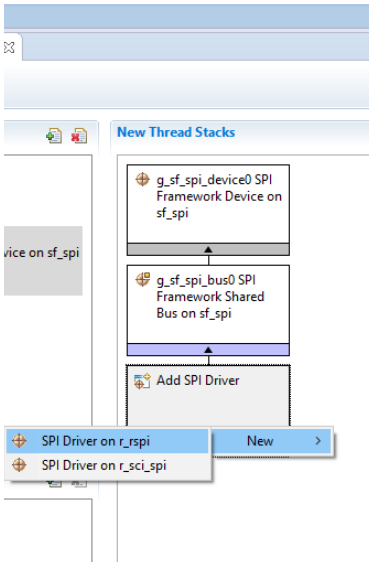
SSL0 (GPIO output mode)



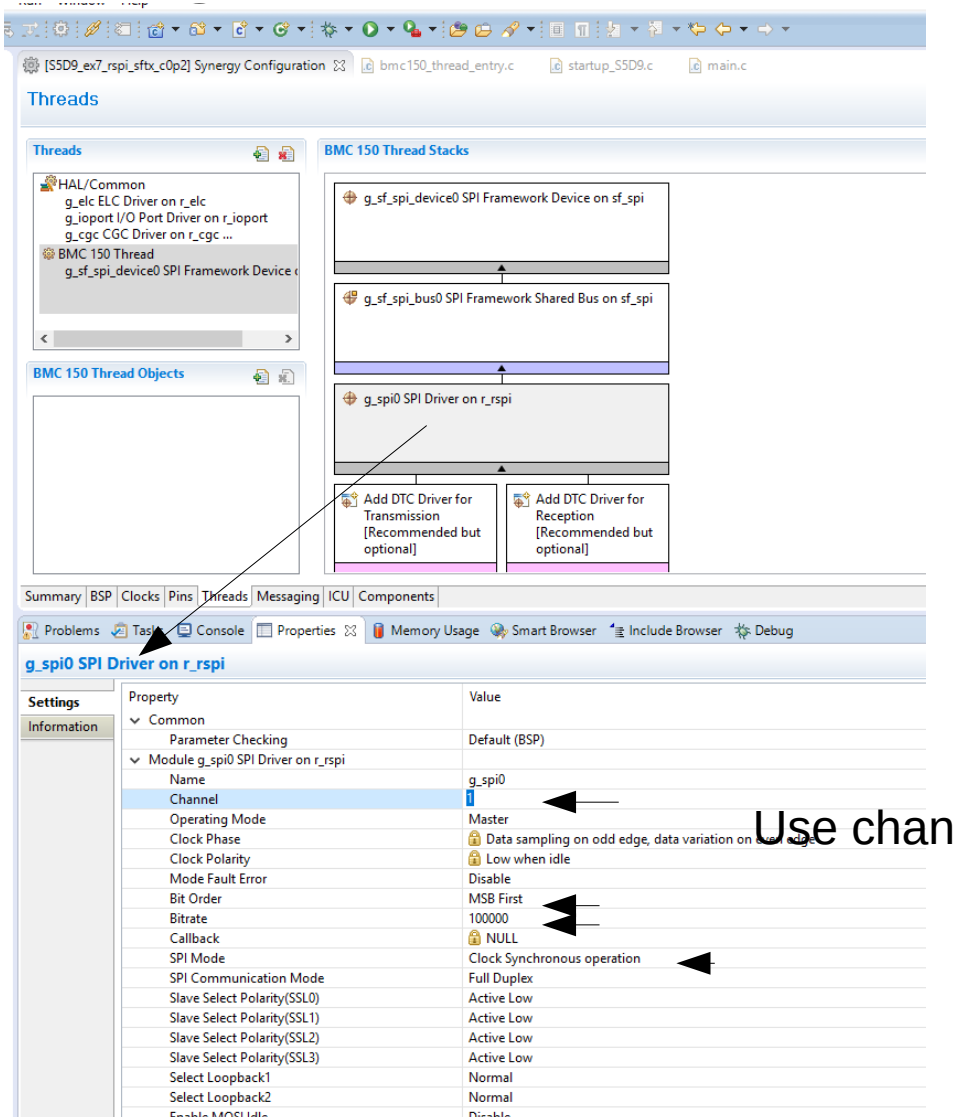
Create a new Thread and SPI Framework Device



Choose r_rspi driver for new



Change Properties



Use channel 1 since SPI1 is used

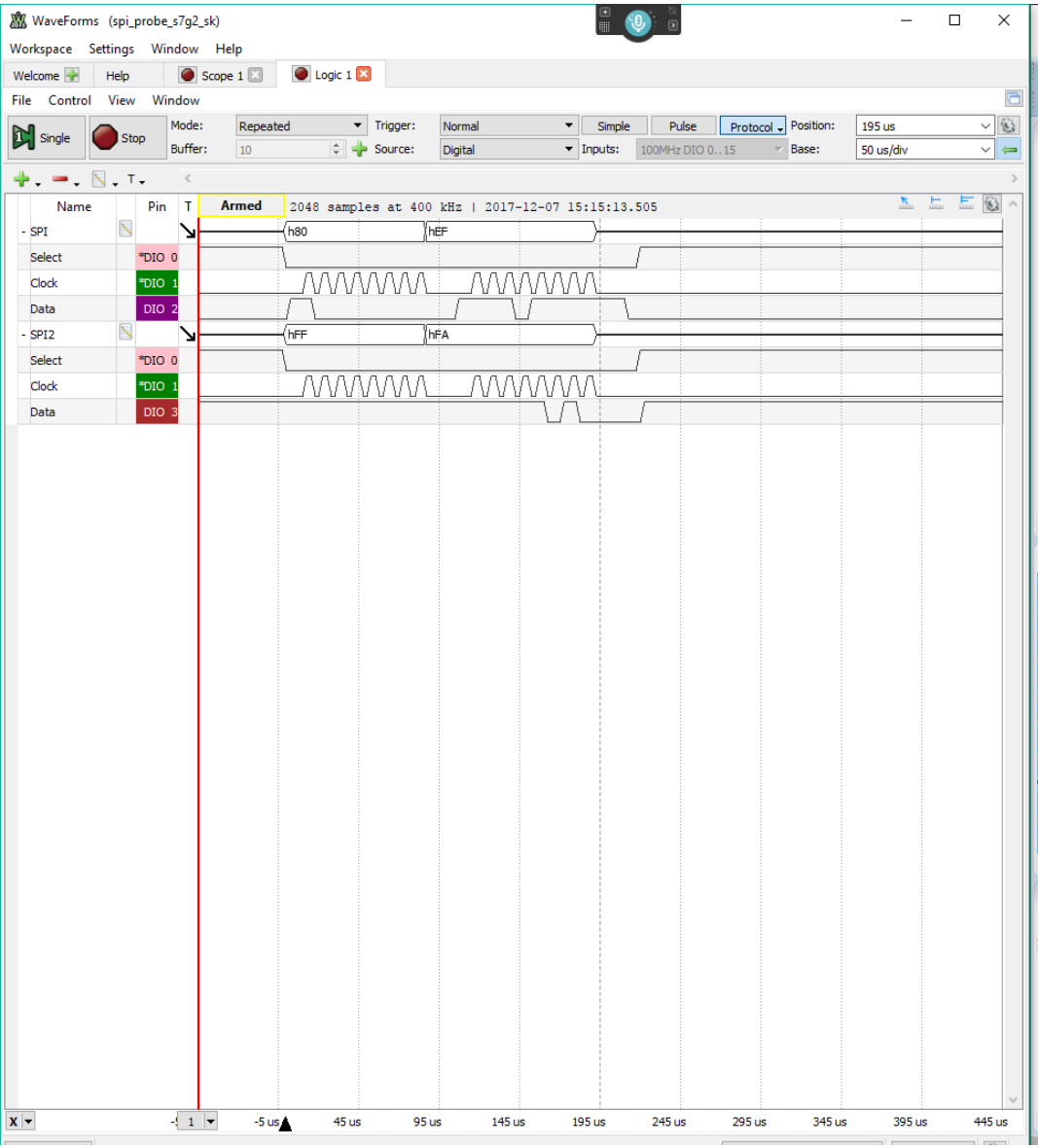
Main Code

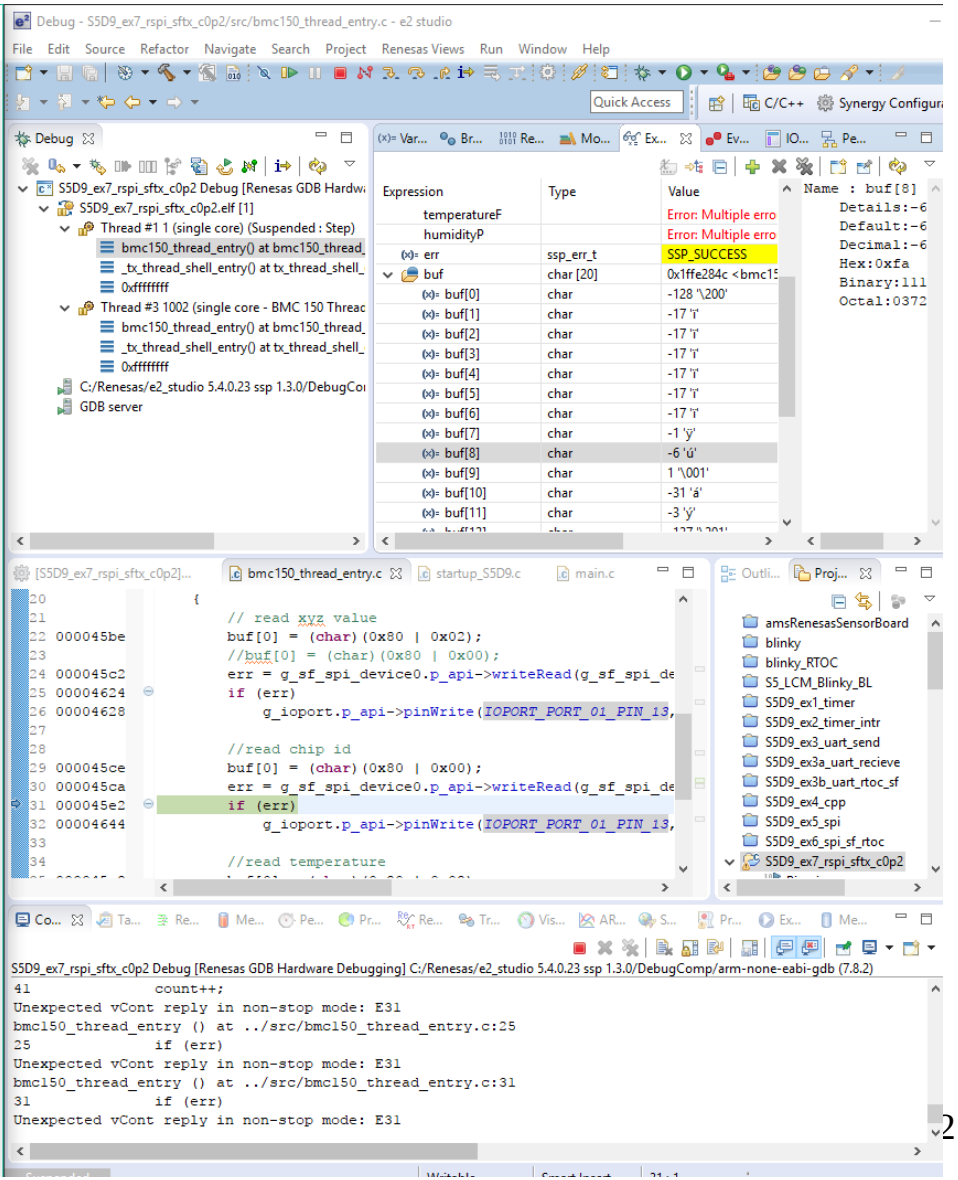
bmc150_thread_entry.c

```
*/


#include "bmc150_thread.h"

int count = 0;

/* BMC 150 Thread entry function */
void bmc150_thread_entry(void)
{
    char buf[20];
    ssp_err_t err;

    g_ioport.p_api->pinWrite(IOPORT_PORT_01_PIN_13, false);


    //read acceleration
    err = g_sf_spi_device0.p_api->open(g_sf_spi_device0.p_ctrl, g_sf_spi_device0.p_cfg);
    if (err)
        g_ioport.p_api->pinWrite(IOPORT_PORT_01_PIN_13, true);

    while (1)
    {
        // read xyz value
        buf[0] = (char)(0x80 | 0x02);
        //buf[0] = (char)(0x80 | 0x00);
        err = g_sf_spi_device0.p_api->writeRead(g_sf_spi_device0.p_ctrl, buf, &buf[7], 7, SPI_BIT_WIDTH_8_BITS, TX_WAIT_
        if (err)
            g_ioport.p_api->pinWrite(IOPORT_PORT_01_PIN_13, true);

        //read chip id
        buf[0] = (char)(0x80 | 0x00);
        err = g_sf_spi_device0.p_api->writeRead(g_sf_spi_device0.p_ctrl, buf, &buf[7], 2, SPI_BIT_WIDTH_8_BITS, TX_WAIT_
        if (err)
            g_ioport.p_api->pinWrite(IOPORT_PORT_01_PIN_13, true);

        //read temperature
        buf[0] = (char)(0x80 | 0x08);
        err = g_sf_spi_device0.p_api->writeRead(g_sf_spi_device0.p_ctrl, buf, &buf[7], 2, SPI_BIT_WIDTH_8_BITS, TX_WAIT_
        if (err)
            g_ioport.p_api->pinWrite(IOPORT_PORT_01_PIN_13, true);

        tx_thread_sleep (10);
        count++;

    }
}
```

mouse double click

ID Read


WaveForms (spi_probe_s7g2_sk)
Armed
2048 samples at 400 kHz | 2017-12-07 15:15:13.505
SPI
Select
Clock
Data
SPI2
Select
Clock
Data
h80
hEF
hFF
hFA


Debug - S5D9_ex7_rspi_sftx_c0p2/src/bmc150_thread_entry.c - e2 studio
bmc150_thread_entry.c
buf[0] = (char)(0x80 | 0x02);
err = g_sf_spi_device0.p_api->writeRead(g_sf_spi_de
if (err)
g_ioport.p_api->pinWrite(IOPORT_PORT_01_PIN_13,
//read chip id
buf[0] = (char)(0x80 | 0x00);
err = g_sf_spi_device0.p_api->writeRead(g_sf_spi_de
if (err)
g_ioport.p_api->pinWrite(IOPORT_PORT_01_PIN_13,
//read temperature
S5D9_ex7_rspi_sftx_c0p2 Debug [Renas GDB Hardware Debugging] C:/Renas/e2_studio 5.4.0.23 ssp 1.3.0/DebugComp/arm-none-eabi-gdb (7.8.2)
Unexpected vCont reply in non-stop mode: E31
bmc150_thread_entry () at ../src/bmc150_thread_entry.c:25
Unexpected vCont reply in non-stop mode: E31
bmc150_thread_entry () at ../src/bmc150_thread_entry.c:31
Unexpected vCont reply in non-stop mode: E31