

S5D9 SPI Bus Example (R_SPI Framework Version)

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<https://www.miketechuniverse.com>

E2 Studio 5.4.0.023
SSP 1.3.0

s5d9_lab_spi (PMOD)

1. Use PMOD J5
2. SSP 1.3.0
3. E2 studio Version: 5.4.0.023

Project Summary

Board: S5D9_IOT_ENABLER
Device: R7FS5D97E2A01CLK
Toolchain: GCC ARM Embedded
Toolchain Version: 4.9.3.20150529
SSP Version: 1.3.0

Selected software components:

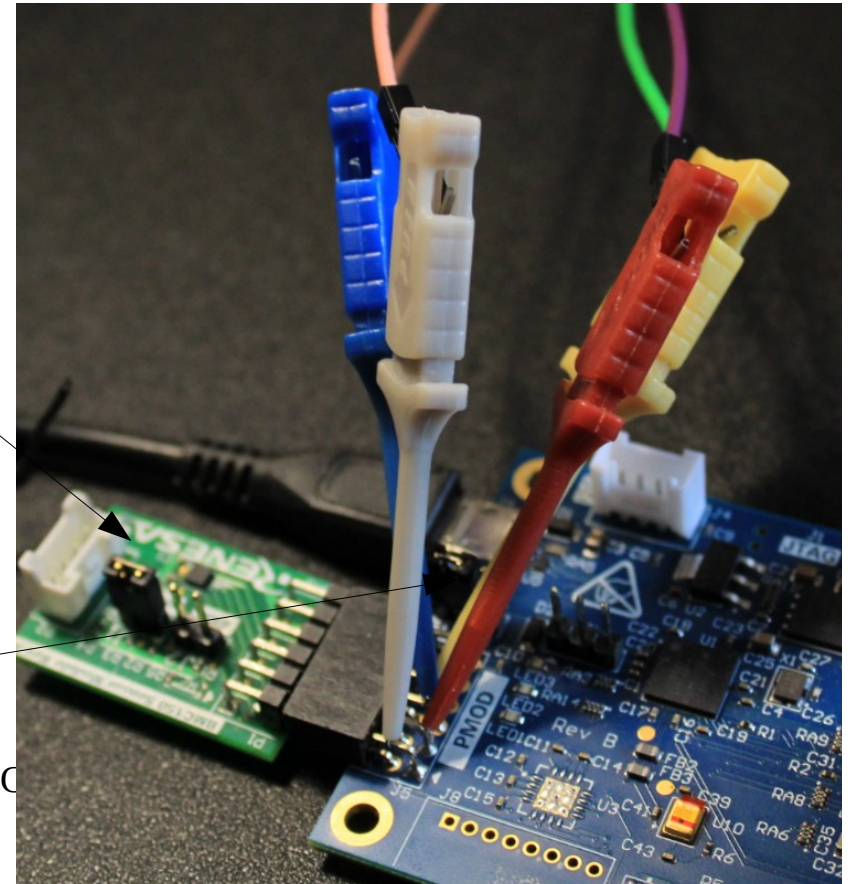


Jumper close for SPI Mode

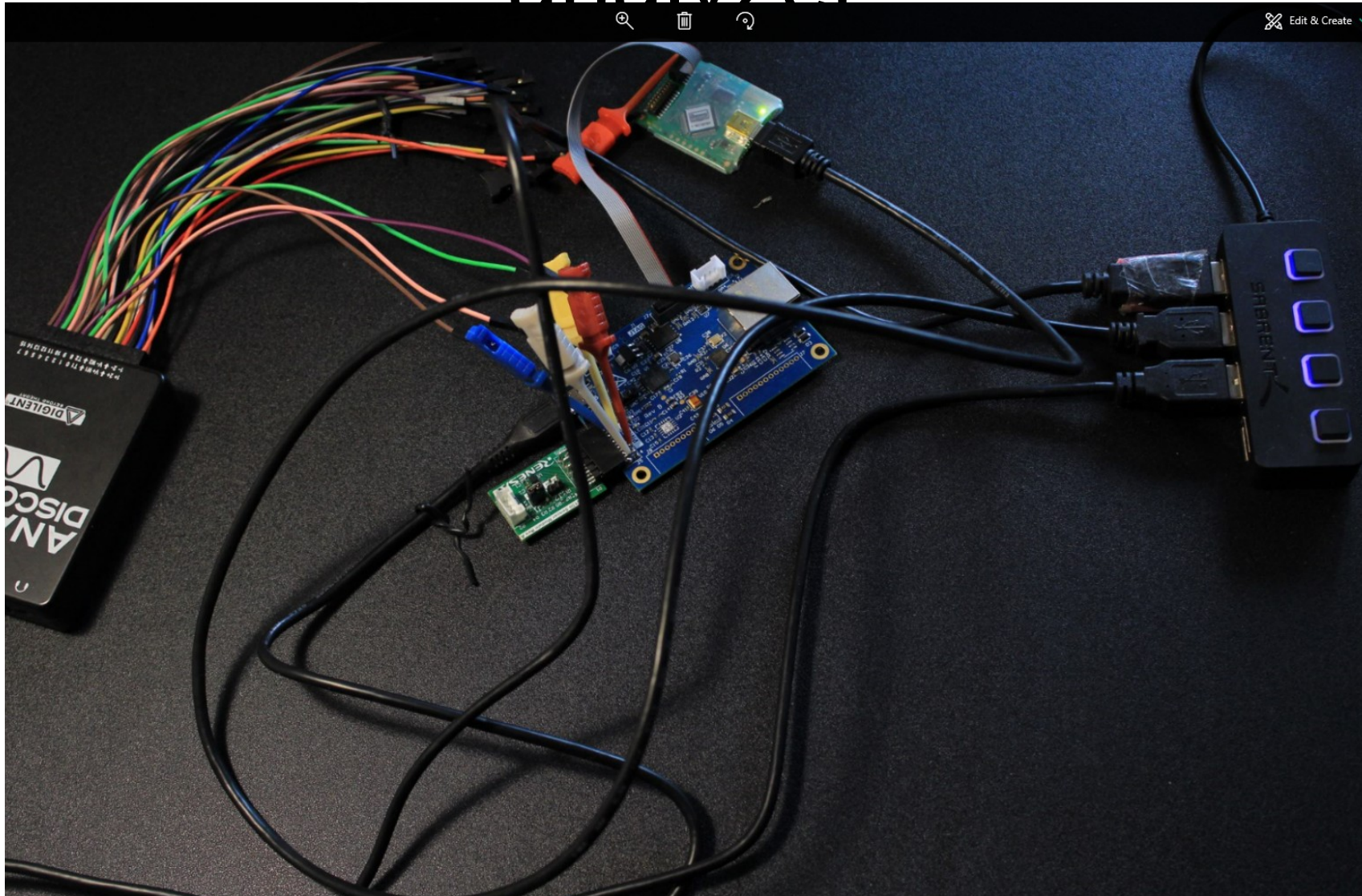
D0 P1 CSB
D2 P2 MOSI
D3 P3 MISO
D1 P4 CK
P5 GND
P6 VCC = 3.3V (due to JMP)

SPI Example by Michael C

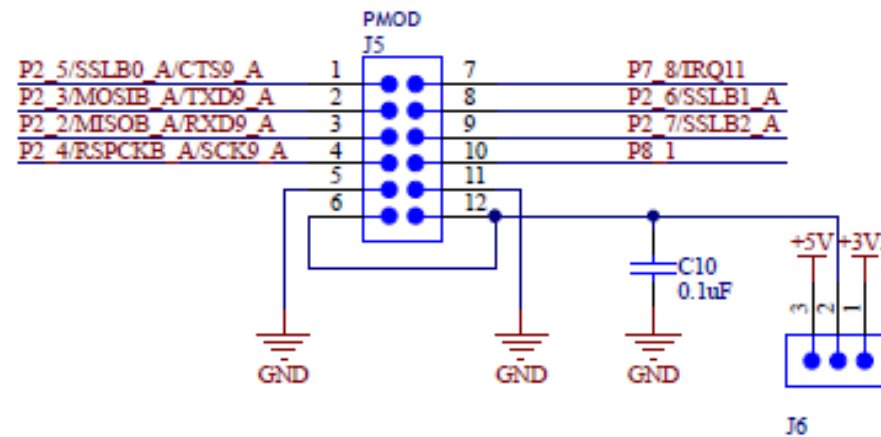
Px = PMOD pin, Dx = Scope pin



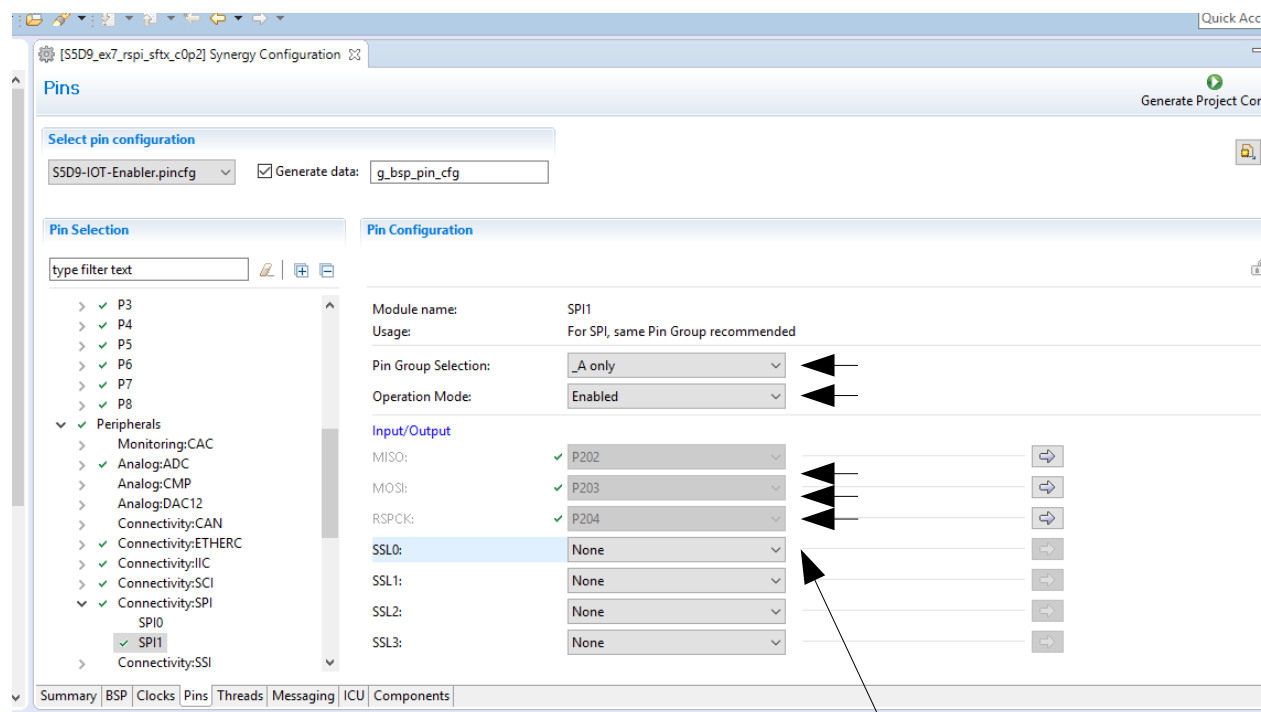
The complete setup with the logic analyzer



PMOD Schematic

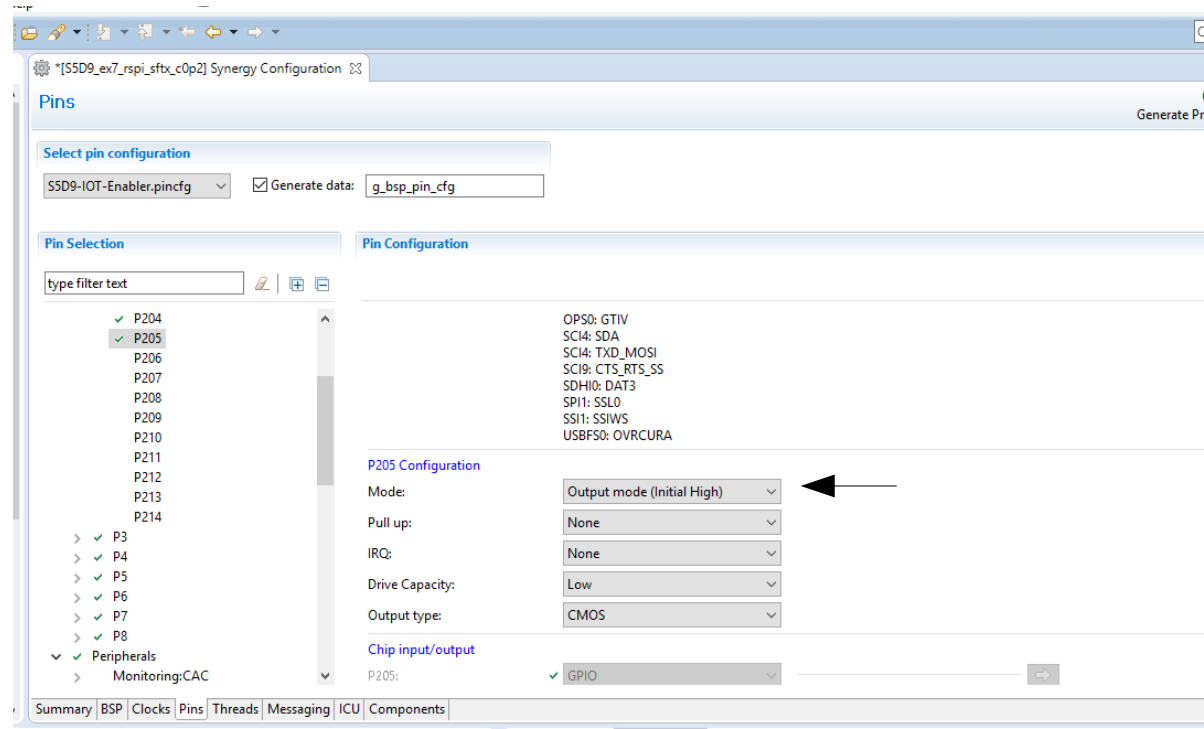


SPI1 (channel 1 !!!)

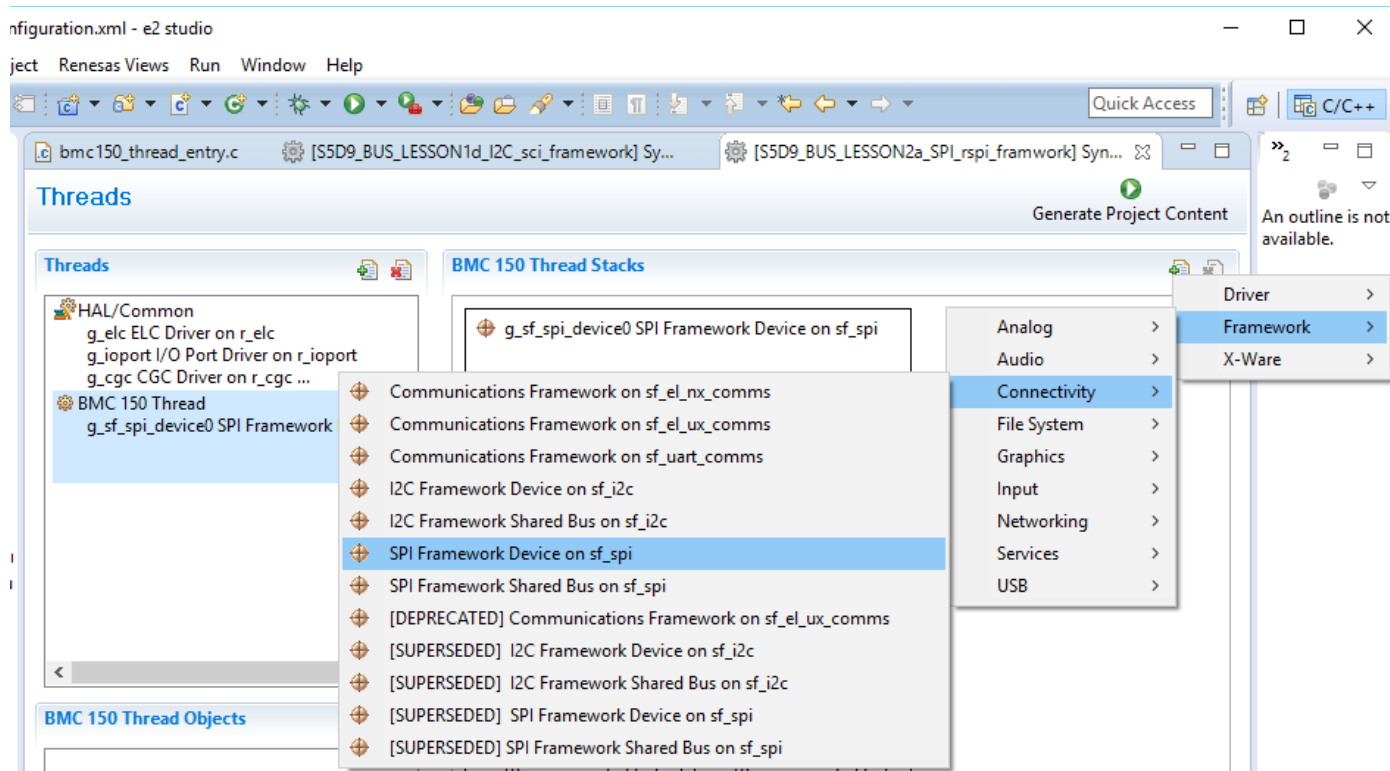


SSL0 is set to None because P2_5 will be controlled separately as a GPIO output pin.

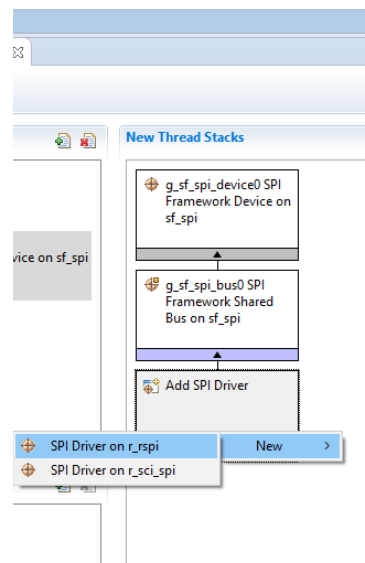
SSL0 (GPIO output mode)



Create a new Thread and SPI Framework Device



Choose r_rsipi driver for new



Change Properties

The screenshot shows the Synergy Configuration tool interface. The top panel displays the 'Threads' and 'BMC 150 Thread Stacks' sections. The 'BMC 150 Thread Objects' section is empty. The bottom panel shows the 'Properties' window for the 'g_spi0 SPI Driver on r_rspi' component. The 'Channel' property is highlighted, and its value is '1'. The 'Operating Mode' property is set to 'Master'. The 'Clock Phase' property is set to 'Data sampling on odd edge, data variation on even edge'. The 'Clock Polarity' property is set to 'Low when idle'. The 'Mode Fault Error' property is set to 'Disable'. The 'Bit Order' property is set to 'MSB First'. The 'Bitrate' property is set to '100000'. The 'Callback' property is set to 'NULL'. The 'SPI Mode' property is set to 'Clock Synchronous operation'. The 'SPI Communication Mode' property is set to 'Full Duplex'. The 'Slave Select Polarity(SSL0)' property is set to 'Active Low'. The 'Slave Select Polarity(SSL1)' property is set to 'Active Low'. The 'Slave Select Polarity(SSL2)' property is set to 'Active Low'. The 'Slave Select Polarity(SSL3)' property is set to 'Active Low'. The 'Select Loopback1' property is set to 'Normal'. The 'Select Loopback2' property is set to 'Normal'. The 'Enable MOSI Idle' property is set to 'Disable'.

Property	Value
Common	
Parameter Checking	Default (BSP)
Module g_spi0 SPI Driver on r_rspi	
Name	g_spi0
Channel	1
Operating Mode	Master
Clock Phase	Data sampling on odd edge, data variation on even edge
Clock Polarity	Low when idle
Mode Fault Error	Disable
Bit Order	MSB First
Bitrate	100000
Callback	NULL
SPI Mode	Clock Synchronous operation
SPI Communication Mode	Full Duplex
Slave Select Polarity(SSL0)	Active Low
Slave Select Polarity(SSL1)	Active Low
Slave Select Polarity(SSL2)	Active Low
Slave Select Polarity(SSL3)	Active Low
Select Loopback1	Normal
Select Loopback2	Normal
Enable MOSI Idle	Disable

Use channel 1 since SPI1 is used

Main Code

```
bmc150_thread_entry.c
20
21
22
23 #include "bmc150_thread.h"
24
25 int count = 0;
26
27 /* BMC 150 Thread entry function */
28 void bmc150_thread_entry(void)
29 {
30     char buf[20];
31     ssp_err_t err;
32
33     g_ioport.p_api->pinWrite(IOPORT_PORT_01_PIN_13, false);
34
35
36     //read acceleration
37     err = g_sf_spi_device0.p_api->open(g_sf_spi_device0.p_ctrl, g_sf_spi_device0.p_cfg);
38     if (err)
39         g_ioport.p_api->pinWrite(IOPORT_PORT_01_PIN_13, true);
40
41     while (1)
42     {
43         // read XYZ value
44         buf[0] = (char)(0x80 | 0x02);
45         //buf[0] = (char)(0x80 | 0x00);
46         err = g_sf_spi_device0.p_api->writeRead(g_sf_spi_device0.p_ctrl, buf, &buf[7], 7, SPI_BIT_WIDTH_8_BITS, TX_WAIT_);
47         if (err)
48             g_ioport.p_api->pinWrite(IOPORT_PORT_01_PIN_13, true);
49
50         //read chip id
51         buf[0] = (char)(0x80 | 0x00);
52         err = g_sf_spi_device0.p_api->writeRead(g_sf_spi_device0.p_ctrl, buf, &buf[7], 2, SPI_BIT_WIDTH_8_BITS, TX_WAIT_);
53         if (err)
54             g_ioport.p_api->pinWrite(IOPORT_PORT_01_PIN_13, true);
55
56         //read temperature
57         buf[0] = (char)(0x80 | 0x08);
58         err = g_sf_spi_device0.p_api->writeRead(g_sf_spi_device0.p_ctrl, buf, &buf[7], 2, SPI_BIT_WIDTH_8_BITS, TX_WAIT_);
59         if (err)
60             g_ioport.p_api->pinWrite(IOPORT_PORT_01_PIN_13, true);
61
62         tx_thread_sleep(10);
63         count++;
64
65     }
66 }
```

ID Read

