

TARGET TOSTTON, TARGET LEGONITHM ENGINEER

Shandong University, No. 17923, Jingshi Road, Jinan, Shandong

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Education

SDU (Shandong University, 985, 211)

Jinan, Shandong

M.E. CANDIDATE IN CONTROL SCIENCE AND ENGINEERING

Sep. 2020 - Now

- Researched on Medical Image Registration and Navigation of Puncture Surgery Robot
- Implemented related works using deep Learning methods

CUMT (China University of Mining and Technology, 211)

Xuzhou, Jiangsu

B.E. IN ELECTRONIC INFORMATION ENGINEERING

Sep. 2016 - June. 2020

- D.E. IN ELECTRONIC IN ORMATION ENGIN
- GPA: 4.06/5RANK: 24/254

Skills

Programming Python, C/C++, LaTeX, git; Experience in Python and Qt development

Deep Learning Pytorch, Tensorflow; Familiar with registration, generation and other CV algorithms

Languages English; Proficient in reading foreign papers and technical documents

Experience _____

National key R&D Development

Shandong University

DEVELOPMENT AND VALIDATION OF A MINIMALLY INVASIVE ROBOT SYSTEM FOR PARTICLE IMPLANTATION BRACHYTHERAPY

Apr. 2020 - Now

- Undertook the Research topic "Intraoperative Visual Guidance of Dynamic Multi-modality Fusion" as a key member of the project team.
- · Developed several medical image deep learning-based registration algorithm applied for CT and multi-modality MR images.
- · Implemented a navigation and execution robot system for surgical which performed image guided puncture operation.
- Actualized the project management such as system integration commissoning, project declaration cooperation and demand scheduling.

[1] Research on medical image registration based on deep learning

PUBLISHED 4 CONFERENCE PAPERS AND APPLIED FOR 1 PATENT.

Registration Methods for 4D CT of Lung Based on Temporal-Spatial Features.

- Developed a Temporal-Spatial Features fusion registration method to make up the absence of temporal characteristics in existing methods.
- Designed a novel temporal modeling module inserted into the bottleneck layer of UNet to process motion information .
- Proposed a Dual-stream registration Pipeline to fit the relationship between data and network.
- $\bullet \ \ \text{Achieved significant improvement results. Realated works published on BioCAS\,2022\,(in\,oral).}$

Multimodal Medical Image Registration based on Multi Metric Fusion

- Developed a multi metric registrion method combined intra-modality similarity and structure code metric to optimize network in a more global perspective.
- Extracted structure information from multimodal images by image dsentanglement as multimodal similarity metric.
- Designed fusion strategy for dual-metric registration model optimization with both intra-modality similarity and structure code.
- Outperformed on translation-based and single metric registration methods. Realated works published on ISBI 2022.

2 Development of surgical robot system with visual guidance

DEVELOPMENT OF ROBOT SYSTEM, NAVIGATION, AND RELATED SOFTWARE

- Build the surgical navigation and execution system which takes NDI as the scene camera, UR5 as the executive mechanism, and Qt to design
- Standardized the navigation system functions, completed the calibration process of image, scene camera and robot.
- Realized TCP/IP communication with equipment for the exchange of tracking and guidance data
- Designed GUI for the functions of surgical navigation, dynamic display, and robot execution control.

3 | Project process organization and management

COORDINATION AMONG TOPICS, PROJECT DOCUMENT WRITING AND INTEGRATION

- Wrote and integrated project declaration and sci-tech report.
- Coordinated with other units of the project to integrate the puncture robot system.
- $\bullet \ \ \text{Familiar with the planning, navigation, execution and clinical operation of the puncture surgery robot.}$

School Committees & Honors_____

SCHOOL COMMITTEES

2016-2020, Class Monitor/Student Union President/Student Assistant of University President

CUMT

Honors

2020/2021 Scholarship for Outstanding Students/Academic Scholarship, less than 30% in SDU

2020 **Excellent graduates**, less than 5% in CUMT

2019 **Excellent student cadres**, less than 1‰ in Jiangsu Province

SDU CUMT Jiangsu Education Department CUMT

2018/2019 Excellent student cadres, less than 5% in CUMT

Pub List_

- [1] **Y. Ji**, Z. Zhu and Y. Wei, "A One-Shot Lung 4D-CT Image Registration Method with Temporal-Spatial Features," 2022 IEEE Biomedical Circuits and Systems Conference (BioCAS), 2022 (Oral)
- [2] **Y. Ji**, Z. Zhu and Y. Wei, "Fusion-Based Multimodal Medical Image Registration Combining Inter-Modality Metric and Disentanglement," 2022 IEEE 19th International Symposium on Biomedical Imaging (ISBI), 2022
- Substantive Examination)

[3] Y. Wei, Y. Ji, "Multimodal medical image registration method and system based on multi standard fusion," 202210095355.8(

- [4] Z. Zhu, Y. Ji and Y. Wei, "Multi-Resolution Medical Image Registration with Dynamic Convolution," 2022 IEEE Biomedical Circuits and Systems Conference (BioCAS), 2022
- [5] Z. Zhu, **Y. Ji** and Y. Wei, "Lung CT image registration based on end-to-end unsupervised learning," 2021 6th International Conference on Communication, Image and Signal Processing (CCISP), 2021