Grammar

Types

$$\tau \coloneqq \sigma \mid r \mid \alpha$$

Base Types

$$\sigma \coloneqq \text{float} \mid \sigma \times \sigma \mid \eta \cdot \sigma \mid \sigma \to \sigma$$

Natural Numbers

$$\eta = 0 \mid 1 \mid \dots$$

Range

$$r \coloneqq \eta .. \eta$$

Term

 $t \coloneqq \text{fl} \mid p \mid \text{for } i : r \text{ in } t \mid \text{let } x \coloneqq t \text{ in } t \mid (t,t) \mid \text{if } t \le \eta \text{ then } t \text{ else } t \mid t + t \mid t * t \mid t - t \mid t/t \mid t \mid \lambda x.t$

• i and x are identifiers.

Literal

$$\mathrm{fl} \coloneqq 0.0 \mid -4.21 \mid 523.215 \mid \dots$$

Place Expression

$$p \coloneqq x \mid p[t] \mid p.\mathrm{fst} \mid p.\mathrm{snd}$$

Environment

Type Environment

$$\Gamma \coloneqq \bullet \mid \Gamma, (x : \tau)$$

Kind Environment

$$\Delta = \bullet \mid \Delta, \alpha$$

Constraints

$$C = \bullet \mid C, (\tau \sqsubseteq \tau)$$

Typing Rules

$$\frac{\alpha \text{ fresh } \Delta, \alpha; \Gamma, (x:\alpha) \vdash t : \sigma_2 \mid C, (\alpha \sqsubseteq \sigma_1)}{\Delta; \Gamma \vdash \lambda x.t : \sigma_1 \rightarrow \sigma_2 \mid C} \\ \Delta; \Gamma \vdash \lambda x.t : \sigma_1 \rightarrow \sigma_2 \mid C \\ \Delta; \Gamma \vdash \lambda x.t_1 : \sigma_1 \rightarrow \sigma_2 \mid C \\ \Delta; \Gamma \vdash (\lambda x.t_1)t_2 : \sigma_2 \mid C$$

$$\frac{\Delta; \Gamma \vdash \lambda x.t_1 : \sigma_1 \rightarrow \sigma_2 \mid C \\ \Delta; \Gamma \vdash t_1 : \text{float } \Gamma \vdash t_r : \text{float } \text{op} \in \{+, -, *, /\}}{\Gamma \vdash t_l \text{ op} t_r : \text{float }} \\ \frac{\Gamma \vdash t_l : \text{float } \Gamma \vdash t_r : \text{float } \text{op} \in \{+, -, *, /\}}{\Gamma \vdash t_l \text{ op} t_r : \text{float }} \\ \frac{x : \sigma \in \Gamma}{\Gamma \vdash t_l : \sigma} T\text{-VAR} \\ \frac{\Gamma \vdash t : \sigma \quad \Gamma, (x : \sigma) \vdash t_{\text{body}} : \sigma_{\text{body}}}{\Gamma \vdash \text{body}} T\text{-LET} \\ \frac{\Gamma \vdash \text{tet} \ x := t \text{ in} \ t_{\text{body}} : \sigma_{\text{body}}}{\Gamma \vdash \text{body}} T\text{-ET} \\ \frac{\eta_l . \eta_r : \text{ok} \quad \Gamma, (i : \eta_l . \eta_r) \vdash t_{\text{body}} : \sigma}{\Gamma \vdash \text{tor} \ i : \eta_l . \eta_r \text{ in} \ t_{\text{body}}} T\text{-FOR} \\ \frac{\Gamma \vdash t : \eta_t . \sigma \quad \Gamma \vdash t_{\text{index}} : \eta_l . \eta_r \quad \eta_r < \eta_t}{\Gamma \vdash \text{tor} \ i : \eta_l . \eta_r \quad \eta_r < \eta_t} T\text{-INDEX-RANGE} \\ \frac{\Gamma \vdash t : \eta_t \cdot \sigma \quad \Gamma \vdash t_{\text{index}} : \eta_l . \eta_r \quad \eta_r < \eta_t}{\Gamma \vdash t : \eta_l \cdot \sigma_1} T\text{-FST} \\ \frac{\Gamma \vdash t : \sigma_1 \times \sigma_2}{\Gamma \vdash t : \text{fst} : \sigma_1} T\text{-SND} \\ \frac{\Gamma \vdash t : \eta_l . \eta_r \quad r_{\text{then}}}{\Gamma \vdash t : \text{sod}} \frac{\sigma_2}{\Gamma} T\text{-SND} \\ \Gamma \vdash t : \eta_l . \eta_r \quad r_{\text{then}} = \eta_l . \min(\eta, \eta_r) \quad r_{\text{else}} = (\min(\eta, \eta_r) + 1) . \eta_r}{\Gamma \vdash \text{then}} : \sigma \quad \Gamma, (t : r_{\text{else}}) \vdash t_{\text{else}} : \sigma} \\ \frac{\Gamma \vdash t : \eta_l . \eta_r \quad \eta_r \leq \eta \quad \Gamma \vdash t_{\text{then}}} \text{-sod} \quad \Gamma. THEN-ONLY} \\ \frac{\Gamma \vdash t : \eta_l . \eta_r \quad \eta_r \leq \eta \quad \Gamma \vdash t_{\text{then}}} : \sigma \quad T. THEN-ONLY} \\ \frac{\Delta; \Gamma \vdash \tau : \tau_{\text{los}} \cdot \tau_{\text{los}} \cdot \tau_{\text{los}} \cdot \tau_{\text{los}}}{\tau \vdash \tau_{\text{then}}} : \sigma \quad T. THEN-ONLY} \\ \frac{\Delta; \Gamma \vdash \tau_{\text{los}} \cdot \tau_{\text{los}} \cdot \tau_{\text{los}} \cdot \tau_{\text{los}} \cdot \tau_{\text{los}}}{\tau_{\text{los}} \cdot \tau_{\text{los}}} \quad \tau_{\text{los}} \cdot \tau_{\text{los}} \cdot \tau_{\text{los}}} \quad \tau_{\text{los}} \cdot \tau_{\text{los}} \cdot \tau_{\text{los}}} \quad \tau_{\text{los}} \cdot \tau_{\text{los}} \cdot \tau_{\text{los}} \cdot \tau_{\text{los}} \cdot \tau_{\text{los}} \cdot \tau_{\text{los}} \cdot \tau_{\text{los}}} \quad \tau_{\text{los}} \cdot \tau_{\text{los}}} \quad \tau_{\text{los}} \cdot \tau_{\text{los}}} \quad \tau_{\text{los}} \cdot \tau_{\text{los}} \cdot \tau_{\text{los}} \cdot \tau_{\text{los}} \cdot \tau_{\text{los}} \cdot \tau$$

 $\Gamma \vdash \text{if } t \leq \eta \text{ then } t_{\text{then}} \text{ else } t_{\text{else}} : \sigma$

Well-formedness Rule and Type Relation

$$\begin{split} &\frac{\eta_0 \leq \eta_1}{\eta_0..\eta_1: \text{ok}} \text{W-RANGE} \\ &\frac{\eta_1 \geq \eta_2 \quad \sigma_1 \sqsubseteq \sigma_2}{\eta_1 \cdot \sigma_1 \sqsubseteq \eta_2 \cdot \sigma_2} \text{T-SUB} \\ &\frac{\text{T-SUB-FLOAT}}{\text{float} \sqsubseteq \text{float}} \end{split}$$

Auxillary Definitions $length(\eta_0..\eta_1) = \eta_1 - \eta_0 + 1$