Miguel A. Solís Cid

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RESEARCH Interests

EDUCATION

adaptive control, reinforcement learning, robotics.

Universidad Técnica Federico Santa Maria, Valparaíso, Chile

Dr.Eng., Informatics, April, 2017.

- Dissertation Topic: "Reinforcement Learning on Control Systems with Unobserved States".
- Advisor: Héctor Allende / Manuel Olivares

M.Sc., Electronics, August, 2012.

- Masters Project: "State estimation of systems observed over erasure channels".
- Advisor: Eduardo Silva

Electronics Engineering, August, 2012.

CAREER EXPERIENCE

Universidad Católica del Norte, Antofagasta, Chile

Interim Academic July, 2018 - today

Full-time position for Computing & Systems Engineering Dept.

Courses:

• Operating Systems,

2019, 02-2018

• Robotics Fundamentals,

02-2019, 02-2018

• Internet of Things,

01-2019

Universidad Andrés Bello, Viña del Mar, Chile

Instructor April, 2017 - June, 2018

Full-time position for Informatics Department at Engineering Faculty.

Academic Assessment Score: 4.0/5

Part-time Lecturer August, 2013 - March, 2017

Courses:

• INF-1202 Computers Architecture, 01-2018, 01-2017, 01-2016.

• INS-121 Computer Programming I (Python 2.7), 01-2018, 01-2014.

• ICF-122 Programming Fundamentals (C), 02-2017.

• INF-1203 Operating Systems, 02-2017, 02-2016, 02-2015.

• ITC-1701 Computer Networks, 01-2017, 01-2016, 01-2015.

• INS-243 Smart City Apps (co-taught), 01-2017, 01-2016.

Undergraduate Supervision

Advisor for undergraduate thesis on informatics engineering.

• Indoor Control: Sistema de monitoreo y control para cultivos de interior - Javier León	2017.
• Control de acceso dactilar - Gabriel Contreras	2017.
• Conversando con R.I.T.A. (Robotic Internet of Things Assistant) - Gonzalo Burgos	2017.
• Laboratorio remoto de robótica educativa - Gonzalo Contreras	2018.

Universidad Técnica Federico Santa Maria, Valparaíso, Chile

Part-time Lecturer August, 2012 - June, 2018 Co-taught undergraduate level courses for first-year students. Shared responsibility for lectures, exams and grades.

• IWI-131 Computer Programming (Python 2.7.x),

01-2018, 2017, 2016, 2015, 01-2014, 2013, 02-2012.

• IWG-101 Introduction to Informatics Engineering,

02-2013.

Undergraduate Supervision

Co-advisor for undergraduate thesis on informatics engineering.

 Generación de estrategia defensiva en RoboCup SSL con aprendizaje reforzado Franco Ollino

2016.

PUBLICATIONS

Journal Articles (WoS indexed)

- [1] M.A. Solis, M. Olivares and H. Allende. A Switched Control Strategy for Swing-Up and State Regulation for the Rotary Inverted Pendulum. Studies in Informatics and Control, 28(1): 45-54, 2019. ISSN 1220-1766.
- [2] M.A. Solis, M. Olivares and H. Allende. Stabilizing Dynamic State Feedback Controller Synthesis: A Reinforcement Learning Approach. Studies in Informatics and Control, 25(2): 245-254, 2016. ISSN 1220-1766.
- [3] E.I. Silva and M.A. Solis, 'An alternative look at the constant-gain Kalman filter for state estimation over erasure channels', IEEE Transactions on Automatic Control, 58(12): 3259-3265, 2013. ISSN 0018-9286.

Book Chapters

[1] O. Silva and M.A. Solis, 'Evolutionary Function Approximation for Gait Generation on Legged Robots'. Nature-Inspired Computing for Control Systems, Springer, 2016. Editor: Hiram Ponce. DOI: 10.1007/978-3-319-26230-7.

Conference Proceedings (Scopus indexed)

- [1] F. Ollino, M.A. Solis and H. Allende, 'Batch Reinforcement Learning on a RoboCup SSL keep-away strategy learning problem'. Proceedings of the 4th Congress on Robotics and Neuroscience, 2018.
- [2] P. Navarrete, C.J. Nettle, C. Oliva and M.A. Solis, 'Fostering Science and Technology Interest in Children with Educational Robot Kits'. Proceedings of the 13rd IEEE Latin American Robotics Symposium, 2016.

- [3] G.A. Ahumada, C.J. Nettle and M.A. Solis, 'Accelerating Q-learning through Kalman Filter Estimations applied in a RoboCup SSL Simulation', Proceedings of the 10th IEEE Latin American Robotics Symposium, 2013.
- [4] E.I. Silva and M.A. Solis, 'An approach to stationary state estimation with missing data', Proceedings of the 9th IEEE International Conference on Control & Automation, 2011.

Projects

R&D Funding

[1] 19PAEI02-115402 Programa de apoyo para la generacin de Emprendimientos en IoT, Smart City and Smart Industry.

Funded by CORFO.

Project leader (2019)

[2] DI-1303-16/RG Self-aware and self-organizing things for reconfiguring Web mashups of things during runtime.

Funded by UNAB.

 $\mathbf{Co-researcher} \tag{2016-2017}$

 $[3]\ {\rm FDI}\ 2011$ and ${\rm FDI}\ 2012$ (students projects line) Equipo Robo Cup F-180. Funded by Mineduc.

Project leader (2012-2013)

INVITED TALKS

- [1] Aprendizaje reforzado: conceptos básicos y aplicaciones en robótica. VIII Escuela de Invierno para la Divulgación de la Robótica, Neurociencia y Nanotecnología. UTFSM August, 2014.
- [2] Introducción práctica al aprendizaje reforzado en aplicaciones de robótica. 4to Congreso de Robótica y Neurociencia (CRoNe 2018). UTFSM, Chile November, 2018.
- [3] Herramientas para cómputo y visualización de datos en python 3.x. 4to Congreso de Robótica y Neurociencia (CRoNe 2018). UTFSM, Chile November, 2018.
- [4] Introducción al aprendizaje reforzado con Jupyterhub. XIX Congreso Internacional de Informática y Sistemas (CIIS 2018). UNJBG, Perú November, 2018.
- [5] Aprendizaje reforzado en sistemas de control. IX Congreso Internacional de Computacin e Informtica del Norte de Chile (INFONOR 2018), Track Congreso Infonor & Tecnologías Emergentes. UNAP, Chile September, 2018.
- [6] Conceptos básicos de aprendizaje reforzado y sus aplicaciones en robótica.IX Congreso Internacional de Computacin e Informtica del Norte de Chile (INFONOR 2018), Track Robótica y Automática. UNAP, Chile September, 2018.
- [7] Aprendizaje reforzado: conceptos básicos y aplicaciones en robótica. Tutorial XIII Escuela de Verano de Inteligencia Computacional (EVIC 2017). UV, Chile December, 2017.
- [8] Numpy y herramientas de visualización en python. Workshop 3er Congreso de Robótica y Neurociencia (CRoNe 2017). UTFSM, Chile October, 2017.

SCIENTIFIC ACTIVITIES

Editorial Activities

Member of the Editorial Board for Mathematics and Computer Science journal.
 ISSN: 2575-6036
 Nov. 2018 - Nov. 2020

Reviews

- IEEE Latin American Transactions
- SSCI 2019: IEEE Symposium Series on Computational Intelligence
- CRoNe 2019: 5th Congress on Robotics and Neuroscience
- INFONOR 2019: 10th International Conference on Computing and Informatics in Northern Chile
- CRoNe 2018: 4th Congress on Robotics and Neuroscience
- WDKE 2018: II Workshop on Data and Knowledge Engineering
- SSN 2018: IV School on Systems and Networks
- TICXED 2018: XIX Congreso Chileno de TICS para la Educación
- WDKE 2017: I Workshop on Data and Knowledge Engineering

Jury Committee (invited)

- 2019. (M.Sc. on Informatics Engineering). Félix Nilo, Navegación de un vehículo autónomo flotante (ASV) de bajo costo en un entorno semiestructurado.
 Universidad Católica del Norte, Departamento de Ingeniería en Sistemas y Computación Director de Tesis: M.Sc. Ricardo Pérez.
- 2019. (M.Sc. on Informatics Engineering). Carolina Silva, Diseño, caracterización y fabricación de una pinza robótica interconectable modular con robótica blanda.
 - Universidad Católica del Norte, Departamento de Ingeniería en Sistemas y Computación Director de Tesis: Dr. José Gallardo.
- 2019. (M.Sc. on Electronics Engineering). Hans Lehnert, Mecanismos Bio-Inspirados Aplicados a Tareas de Navegación en Agentes Artificiales.
 - Universidad Técnica Federico Santa María, Departamento de Electrónica Director de Tesis: Dr. María José Escobar.
- 2017. (M.Sc. on Biomedical Engineering). Alvaro Jara, Reproducción de la altitud barométrica del centro de masa de una persona a partir de videos de caídas
 Universidad de Valparaíso, Escuela de Ing. Civil Biomédica
 Director de Tesis: Dr. Pablo Reyes.

Organizing Committee of Conferences

- General Chair of Latin American Summer School on Cognitive Robotics 2020
- General Chair of CRoNe 2016: 2nd Congress on Robotics and Neuroscience
- General Chair of CRoNe 2015: 1st Congress on Robotics and Neuroscience

Program Committee of Conferences

- Workshops Chair of IEEE ICDL-EpiRob 2020: International Conference on Development and Learning, and on Epigenetic Robotics
- CRoNe 2019: 5th Congress on Robotics and Neuroscience
- (Emergent Technologies Track) Co-chair at INFONOR 2019: 10th International Conference on Computing and Informatics in Northern Chile
- CRoNe 2018: 4th Congress on Robotics and Neuroscience
- WDKE 2018: II Workshop on Data and Knowledge Engineering at INFONOR 2018
- TICXED 2018: XIX Congreso Chileno de TICS para la Educación at JCCC 2018

Awards and Honors

- Academic Excellence Award, Graduate School, Universidad Técnica Federico Santa María 2017
- Doctoral Scholarship, Universidad Técnica Federico Santa María 2012 2017
- Scientific Research Initiation Program, Universidad Técnica Federico Santa María 2015
- Visiting Scholar, University of Texas at Arlington
 Learning and Adaptive Robotics Lab.
 Supervisor: Dr. Manfred Huber
- Master in Science Scholarship, Universidad Técnica Federico Santa María 2010 2012
- Scientific Research Initiation Program, Universidad Técnica Federico Santa María 2011
- List of Honor of Students of Universidad Técnica Federico Santa María 2009 2012

ENGLISH SKILLS

• TOEFL: Sept., 2016

Skill	Level
Reading	High (22-30)
Listening	Intermediate (14-21)
Speaking	Intermediate (14-21)
Writing	Intermediate (14-21)

• Total score: 80

Computer Skills • Robotics Simulators: RobotinoSIM, Roboguide. • Languages: C, Python, Matlab, some use of Unix shell scripts, LabView, LATEX. Miscellaneous • Technical Consultant 2019 - today Asesorías y Servicios Tribológicos del Norte Grande S.A. • Volunteer adviser at Investigación Científica Escolar 2019 PAR Explora Antofagasta • Microdegrees program Coordinator 2017 - today http://www.innovacionyrobotica.com/microgrados 2017 • Competitive Programming Coach UNAB - Olimpiadas Chilenas de Informática 2016 - 2018 • Technical Consultant http://www.centrosteam.com Oct. 27-29, 2016 • Co-organizer Latin American Robotics Week http://www.roboticsweekLA.com • Speaker at Vocational workshops for school students entitled 'Educación Futuro' Sept. 2015 Universidad Andrés Bello • Member of 'Equipo RoboCup', Innovación y Robótica Estudiantil, UTFSM 2011 - 2014 • Member of 'Equipo Lego', Innovación y Robótica Estudiantil, UTFSM 2009 - 2011 Professional • IA-LATAM, Member 2019 - today Affiliations • IEEE Technical Committee on Neuro-Robotics Systems, Member 2019 - today

• Centro de Innovación y Robótica, General Secretary

• IEEE, Member

• IEEE RAS (Robotics and Automation Society), Member

2017 - today

2014 - today

2011 - today