

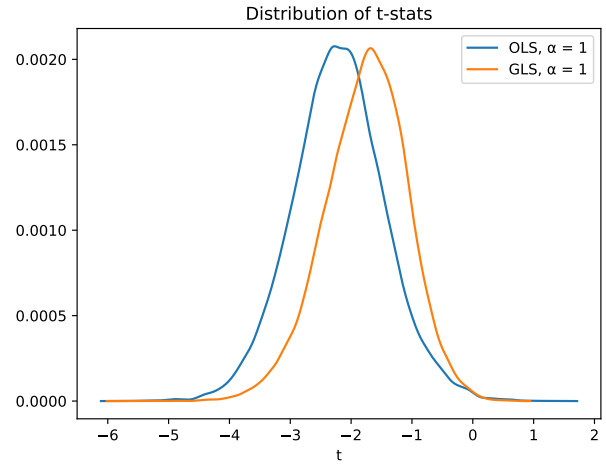
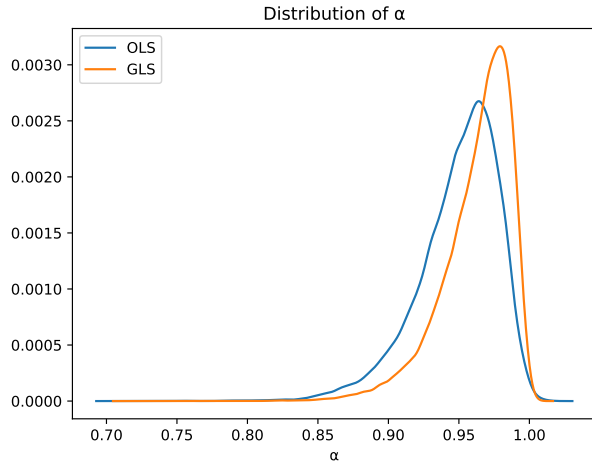
**Q1.** In the first panel, I plot the distribution of  $\hat{\alpha}$  (not sure what the normalization  $T(\hat{\alpha} - 1)$  means). In the second panel, I plot the t-stats constructed as follows.

- OLS: Estimate  $y_t = a + \beta t + \alpha y_{t-1} + \text{error}_t$ , then

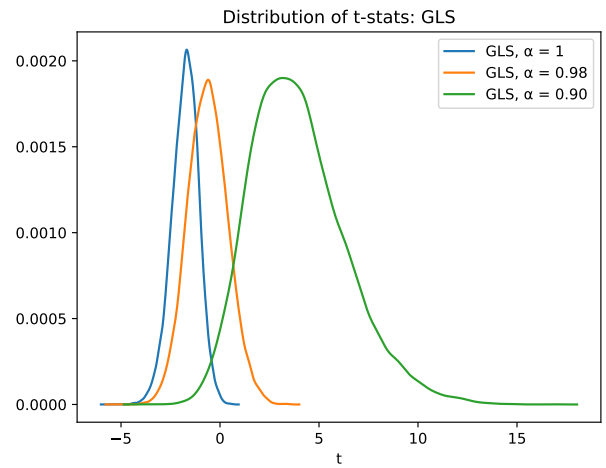
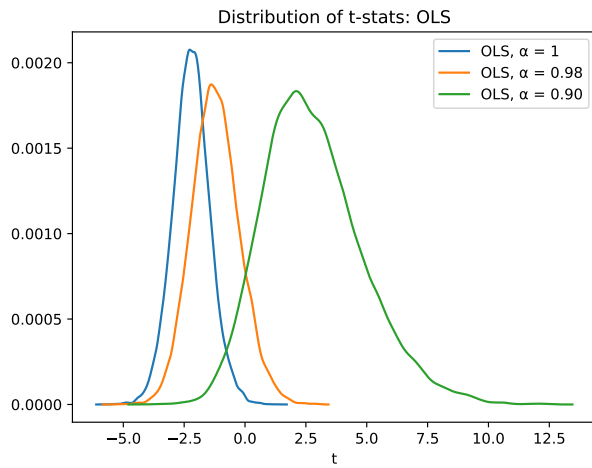
$$t_{\text{OLS}} \equiv \frac{\hat{\alpha} - 1}{\sqrt{\frac{\sum_{t=1}^T y_t^2}{T}}}$$

- GLS: Estimate  $y_t^d = \alpha_G y_{t-1}^d + \text{error}_t$ , then

$$t_{\text{GLS}} \equiv \frac{\hat{\alpha}_G - 1}{\sqrt{\frac{\sum_{t=1}^T (y_t^d)^2}{T}}}$$

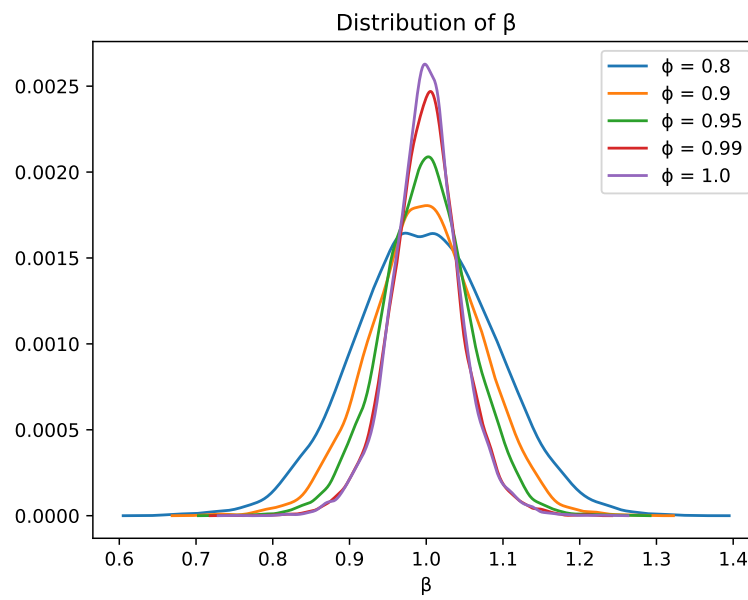
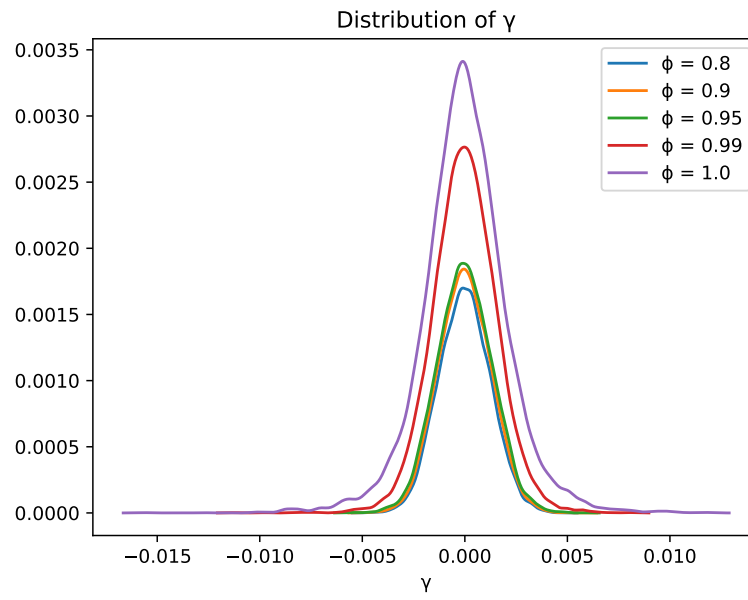


**Q2.** Here I plot the same t-stats as mentioned in the previous exercise, except I substitute 1 for 0.98 and 0.90.

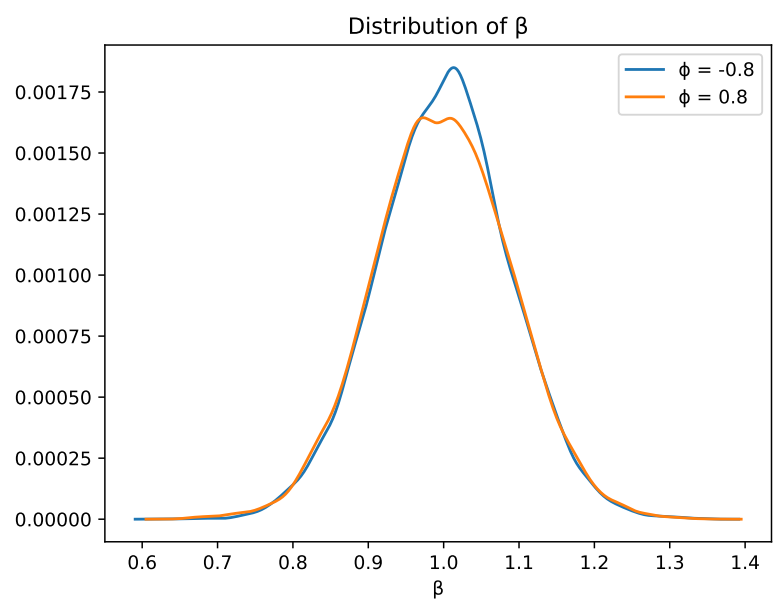
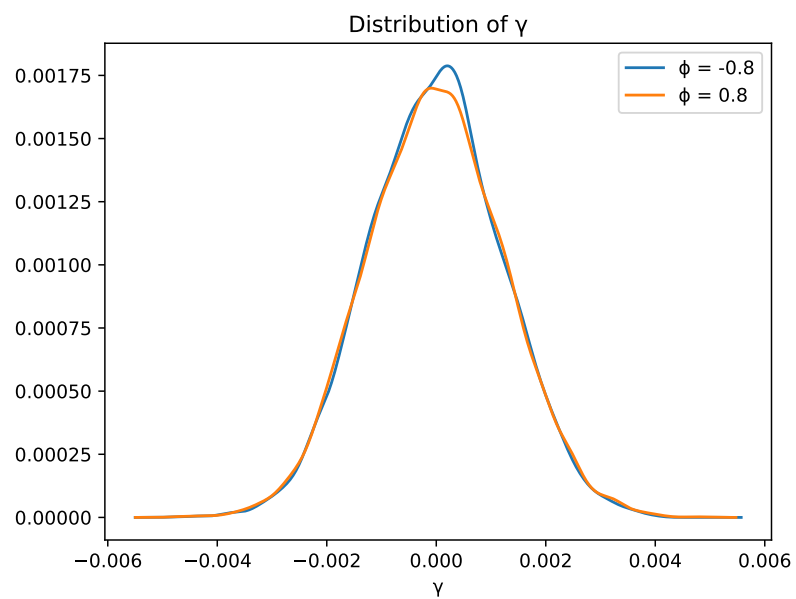


**Q3.** I set  $T = 200$  and performed 10,000 simulations for each value of  $\phi$ .

i.



ii.



Q4.

$$i. \quad y_{1t} - y_{1t-1} = r y_{2t} - r y_{2t-1} + u_{1t} - u_{1t-1}$$

$$\Rightarrow \Delta y_{1t} = r \Delta y_{2t} + \Delta u_{1t}$$

$$= r u_{2t} + (1-L) u_{1t}$$

$$\begin{bmatrix} \Delta y_{1t} \\ \Delta y_{2t} \end{bmatrix} = \begin{bmatrix} (1-L) & r \\ 0 & 1 \end{bmatrix} \begin{bmatrix} u_{1t} \\ u_{2t} \end{bmatrix}$$

So, the MA( $\infty$ ) representation is  $\Delta y_t = \Psi(L) u_t$   
with  $\Psi(L) \equiv \begin{bmatrix} 1-L & r \\ 0 & 1 \end{bmatrix}$

$$ii. \quad y_{1t} = r y_{2t} + u_{1t}$$

$$y_{2t} = y_{2t-1} + u_{2t}$$

$$y_t = \begin{bmatrix} 0 & r \\ 0 & 1 \end{bmatrix} y_t + u_t$$

$$\Rightarrow u_t = \begin{bmatrix} 1 & -r \\ 0 & 1-L \end{bmatrix} y_t$$

So, the AR( $\infty$ ) representation is  $\Phi(L) y_t = u_t$   
with  $\Phi(L) \equiv \begin{bmatrix} 1 & -r \\ 0 & 1-L \end{bmatrix}$

$$iii \quad \Delta y_{1t} = r \Delta y_{2t} + \Delta u_{1t} = r u_{2t} + u_{1t} - (y_{1t-1} - r y_{2t-1})$$

$$\Delta y_{2t} = u_{2t}$$

$$\begin{aligned} \Rightarrow \Delta y_t &= \begin{bmatrix} -1 & r \\ 0 & 0 \end{bmatrix} y_t + \begin{bmatrix} 1 & r \\ 0 & 1 \end{bmatrix} u_t \\ &= \underbrace{\begin{bmatrix} -1 \\ 0 \end{bmatrix}}_{\beta} \underbrace{\begin{bmatrix} 1 & -r \end{bmatrix}}_{\alpha'} y_t + \underbrace{\begin{bmatrix} 1 & r \\ 0 & 1 \end{bmatrix}}_{e_t} u_t \end{aligned}$$

So, the VECM representation is  $\Delta y_t = \beta \alpha' y_t + e_t$  with

$$\beta \equiv \begin{bmatrix} -1 \\ 0 \end{bmatrix}, \quad \alpha \equiv \begin{bmatrix} 1 \\ -r \end{bmatrix}, \quad e_t \equiv \begin{bmatrix} 1 & r \\ 0 & 1 \end{bmatrix} u_t$$