

## 1 Preliminaries

- (a) (i) Upon seeing the realization of  $x_i$ , the agent's posterior is

$$\boxed{N\left(\frac{\kappa_\theta \mu + \kappa_x x_i}{\kappa_\theta + \kappa_x}, \frac{1}{\kappa_\theta + \kappa_x}\right)}$$

- (ii) Since  $\xi_i$  is normal with mean 0,  $\int \xi_i di = 0$ . So, we can compute the aggregate action:

$$\begin{aligned}\bar{a} &\equiv \int a_i di \\ &= \int \mathbb{E}[\theta \mid x_i] di \\ &= \int \frac{\kappa_\theta \mu + \kappa_x x_i}{\kappa_\theta + \kappa_x} di \\ &= \frac{\kappa_\theta \mu}{\kappa_\theta + \kappa_x} + \frac{\kappa_x}{\kappa_\theta + \kappa_x} \int (\theta + \xi_i) di \\ &= \boxed{\frac{\kappa_\theta \mu + \kappa_x \theta}{\kappa_\theta + \kappa_x}}\end{aligned}$$

- (b) (i) Upon observing the realizations of  $x_i$  and  $y$ , the private and public signals, the agent's posterior is

$$N\left(\frac{\kappa_x x_i + \kappa_y y}{\kappa_x + \kappa_y}, \frac{1}{\kappa_x + \kappa_y}\right)$$

- (ii) The aggregate action is:

$$\begin{aligned}\bar{a} &= \int a_i di \\ &= \int \mathbb{E}_i[\theta] di \\ &= \int \frac{\kappa_x x_i + \kappa_y y}{\kappa_x + \kappa_y} di \\ &= \frac{\kappa_x \theta + \kappa_y (\theta + \varepsilon)}{\kappa_x + \kappa_y} \\ &= \theta + \frac{\kappa_y \varepsilon}{\kappa_x + \kappa_y}\end{aligned}$$

- (c) In the private-only setup (a), aggregate action will end up being a weighted average of the true mean of  $\theta$  and the actual draw of  $\theta$ . In the setup with a public signal, the action is  $\theta$  plus a weighted-down amount of the public signal. In the private setup, however, aggregate action will tend to  $\mu$  as the precision of the public signal deteriorates; in the public one, aggregate action will tend to the public signal. In the first setup, the signal pulls aggregate action towards the fundamental. With the public signal, the aggregate action is pulled away!

## 2 Currency Attacks and Government Intervention

- (a) When the agent is trying to decide between the two actions, what matters is the difference in the payoff between the two actions. Under the original payoff structure, this is

$$\begin{aligned} U(1, A, \theta) - U(0, A, \theta) &= \begin{cases} 1 - c & \text{if } R = 1 \\ 1 - c - 1 & \text{if } R = 0 \end{cases} \\ &= \begin{cases} 1 - c & \text{if } R = 1 \\ -c & \text{if } R = 0 \end{cases} \\ &= 1 \cdot (\mathbb{1}_{R=1} - c) - 0 \cdot (\mathbb{1}_{R=1} - c). \end{aligned}$$

That is, the relative payoffs under the original payoff structure are the same as they would be under the formula  $a_i(\mathbb{1}_{R=1} - c)$ , which results in the standard payoff matrix:

	$R = 1$	$R = 0$
$a_i = 1$	$1 - c$	$-c$
$a_i = 0$	$0$	$0$

- (b) Ok, let's start by fixing  $e$  and a public signal  $y$ . I'll focus on a threshold equilibrium like we did in class. I'm looking for a strategy,  $x^*(e, y)$ , such that agents will attack iff

$$x \leq x^*(e, y).$$

This implies that everyone with a private signal above  $x^*(e, y)$  doesn't attack, and vice versa. So, the aggregate size of the attack is decreasing in  $\theta$ . This implies that there exists some threshold  $\theta^*(e, y)$  such that there is a regime change iff

$$\theta \leq \theta^*(e, y).$$

Now, let's compute these. Start by characterizing  $\theta^*$ , given  $x^*$ . Note that since  $x \sim N(\theta, 1/\beta)$ , we know that  $\sqrt{\beta}(x - \theta) \sim N(0, 1)$ . So, the size of the attack is the mass of agents receiving a signal below  $x^*$ , or:

$$A(\theta, e, y) = \Phi\left(\sqrt{\beta}(x^*(e, y) - \theta)\right). \quad (1)$$

If the aggregate size of the attack is above  $\theta + e$ , then regime shift occurs. So, the regime-change threshold is the solution to:

$$A(\theta^*(e, y), e, y) = \theta^*(e, y) + e \quad (2)$$

So, combining (1) and (2), we have

$$\begin{aligned} \Phi^{-1}(\theta^*(e, y) + e) &= \sqrt{\beta}(x^*(e, y) - \theta) \\ \implies x^*(e, y) &= \frac{1}{\sqrt{\beta}}\Phi^{-1}(\theta^*(e, y) + e) + \theta^*(e, y) \end{aligned} \quad (3)$$

Next, given  $\theta^*$ , we want to characterize  $x^*$ . First, note that the posterior distribution of  $\theta$ , having seen the two signals, is

$$\theta|_{x,y} \sim N\left(\frac{\beta}{\eta}x + \frac{\alpha}{\eta}y, \frac{1}{\eta}\right) \implies \sqrt{\eta}\left(\theta_{x,y} - \left(\frac{\beta}{\eta}x + \frac{\alpha}{\eta}y\right)\right) \sim \Phi$$

where  $\eta \equiv \beta + \alpha$ . Payoffs are of the form  $a_i(\mathbb{1}_{R=1} - c)$ , and the person is indifferent at the threshold—that is, the expected payoff from attacking is equal to the payoff from not attacking:

$$\begin{aligned} \underbrace{0}_{\text{Not Attack}} &= \underbrace{\mathbb{E}[u(1, A(\theta, e, y), \theta) \mid x^*(e, y), y]}_{\text{Attack}} \\ &= a_i(\mathbb{P}[\theta \leq \theta^*(e, y)] - c) \\ &= a_i\left(\Phi\left[\sqrt{\eta}\left(\theta^*(e, y) - \left(\frac{\beta}{\eta}x^*(e, y) + \frac{\alpha}{\eta}y\right)\right)\right] - c\right) \\ \implies c &= 1 - \Phi\left[\sqrt{\eta}\left(\frac{\beta}{\eta}x^*(e, y) + \frac{\alpha}{\eta}y - \theta^*(e, y)\right)\right] \\ &= 1 - \Phi\left[\sqrt{\eta}\left(\frac{\beta}{\eta}\left[\frac{1}{\sqrt{\beta}}\Phi^{-1}(\theta^*(e, y) + e) + \theta^*(e, y)\right] + \frac{\alpha}{\eta}y - \theta^*(e, y)\right)\right] \quad \text{by (3)} \\ \implies \frac{1}{\sqrt{\eta}}\Phi^{-1}(1 - c) &= \theta^*(e, y)\left[\frac{\beta}{\eta} - 1\right] + \frac{\alpha}{\eta}y + \frac{\sqrt{\beta}}{\eta}\Phi^{-1}(\theta^*(e, y) + e) \\ &= \theta^*(e, y)\left[\frac{-\alpha}{\eta}\right] + \frac{\alpha}{\eta}y + \frac{\sqrt{\beta}}{\eta}\Phi^{-1}(\theta^*(e, y) + e) \\ \implies \underbrace{\left(\sqrt{\frac{\eta}{\beta}}\right)\Phi^{-1}(1 - c)}_g &= \underbrace{\frac{\alpha}{\sqrt{\beta}}[y - \theta^*(e, y)] + \Phi^{-1}(\theta^*(e, y) + e)}_{G(\theta^*(e, y), y)} \quad \text{mult. by } \frac{\eta}{\sqrt{\beta}} \end{aligned}$$

Now, I claim that there's a monotone equilibrium characterizes by  $\theta^*(e, y)$  and  $x^*(e, y)$  where  $\theta^*$  is implicitly defined by  $G(\theta^*(e, y), y) = g$  as in the previous expression, and  $x^*$  is as in (3). Let's verify that there is some point at which  $G = g$ . I claim that the point is somewhere between  $[-e, 1 - e]$ . Because, for fixed  $e$  and  $y$ ,  $G$  is continuous in  $\theta$ , and we know that

$$\begin{aligned} G(-e, y) &= \frac{\alpha}{\sqrt{\beta}}y + \Phi^{-1}(-e + e) = -\infty \\ \text{and } G(1 - e, y) &= \frac{\alpha}{\sqrt{\beta}}y + \Phi^{-1}(1 - e + e) = \infty \end{aligned}$$

that is,  $G$  goes off to negative infinity to the left, and positive infinity to the right, so by the IVT, it must intersect  $g$  at some point in between. (This is cool—the government can control the threshold!)

- (c) Now, for uniqueness. We need to figure out when it's the case that  $G$  is strictly increasing, and when it's possible that it decreases. So, let's look at its derivative:

$$\frac{\partial G(\theta, y)}{\partial \theta} = \frac{1}{\phi(\Phi^{-1}(\theta + e))} - \frac{\alpha}{\sqrt{\beta}}$$

So, because

$$\phi(\omega) \in \left[0, \frac{1}{\sqrt{2\pi}}\right], \text{ then } \frac{1}{\phi(\omega)} \in [\sqrt{2\pi}, \infty],$$

and the slope is only guaranteed to be positive throughout the support of  $\theta$  if

$$\frac{\alpha}{\sqrt{\beta}} < \sqrt{2\pi}$$

otherwise, there is a range of  $\theta(e, y)$  where the solution is not unique.

(d) Letting  $\beta \rightarrow \infty$  in the implicit definition for  $G$ , we have

$$\Phi^{-1}(1 - c) = \Phi^{-1}(\theta^*(e, y) + e) \implies 1 - c - e = \theta^*(e, y).$$

By letting  $\beta \rightarrow \infty$ , we are saying that the distribution of  $x_i$  collapses to unit mass at  $\theta$ ; individuals perfectly know  $\theta$ . Unsurprisingly, the threshold  $x^* = \theta^*$ .

The threshold no longer depends on the public signal. Everybody knows  $\theta$  perfectly, so there's no reason to think that an imperfect measure of  $\theta$  would change the equilibrium threshold value.

Now, this threshold is decreasing in  $e$  and  $c$ . Why? Well, if there were no costs to attacking and the government wasn't strengthening the regime, then agents would always attack.<sup>1</sup> By increasing the costs to attacking (increasing  $c$ ), or by making it harder for an attack to succeed (increasing  $e$ ), there are fewer values of the fundamental for which agents will attack. That is, if it's less likely that an attack will be profitable, agents will require seeing a weaker fundamental. Since there's no strategic complementarity effect here, we only need to think about fundamentals.

(e) The (benevolent) government wants to maximize the utility of non-attackers; it wants the attack to not go through. But it also has to pay a cost. And it knows what will happen in the second stage conditional on its own efforts,  $e$ . Remember that, since  $\beta \rightarrow 0$ , everyone either attacks or doesn't attack, based on their private signal. Unfortunately, the government only imperfectly measures  $\theta$ . Therefore, the government's objective function is:

$$\begin{aligned} \mathbb{E}v(\theta, A) - e^2 &= \mathbb{P}[A \leq \theta + e] - e^2 \\ &= \mathbb{P}[\theta < 1 - c - e] - e^2 \end{aligned}$$

Ok, I see why it is easier to assume  $\alpha \rightarrow \infty$ —I don't know how to find the posterior distribution of  $\theta \mid y$ . So, now we're assuming that the government knows  $\theta$ . They know that everyone will attack if  $\theta < 1 - c - e$ . But now we're in this silly case where everyone knows  $\theta$ .

If  $\theta \geq 1 - c$ , then the government can't do anything because everyone will attack regardless—their best response is to set  $e = 0$ . If  $\theta < 1 - c$ , then the cheapest way to people to not attack is to set  $e = 1 - c - \theta$ . If they do this, they spend  $e$ , but get utility of 1. So, this is worth it if

$$\begin{aligned} 1 - (1 - c - \theta)^2 &> 0 \\ \iff 1 &> |1 - c - \theta| \\ \iff 1 &> 1 - c - \theta \text{ and } 1 > -1 + c + \theta \\ \iff \theta &> -c \text{ and } 2 - c > \theta \end{aligned}$$

So, they should spend the money for  $\theta \in (-c, 2 - c)$ .

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<sup>1</sup>Well, as long as it is profitable—that is,  $\theta \leq 1$ .

### 3 Typicality of Beliefs

- (a) An agent choosing  $a_i = 0$  is guaranteed to get 0. It's individually rational to choose  $a_i = 1$  iff

$$\theta + A > 0 \implies \theta > -A$$

Since  $A \in [0, 1]$ , then it is rational to choose  $a_i = 1$  iff  $\theta > -1$ . So, the two equilibria are:

$$\begin{array}{ll} \theta \leq -1 & a_i = 0, \quad \forall i \\ \theta > -1 & a_i = 1, \quad \forall i \end{array}$$

(If you believed that, say, only  $\frac{1}{2}$  of people would invest, then it would be rational to not invest; but then  $A = 0$ , so, this isn't an equilibrium.)

- (b) I've got a hunch that there's going to be some threshold rule in which the threshold is  $\frac{1}{2}$ , but let's see. I'm going to posit that there's some threshold  $x^*$  such that if  $x_i < x^*$ , then agent  $i$  will choose to invest. So, at the threshold, the agent is indifferent between investing and not investing. That is,

$$\begin{aligned} 0 &= \mathbb{E}[\theta + A \mid x_i^*] \\ &= x_i^* + \mathbb{E}\left[\int a_i di \mid x_i^*\right] \\ &= x_i^* + \frac{1}{2} \\ \implies &\boxed{x_i^* = -\frac{1}{2}} \end{aligned}$$

The agent is following the threshold, and she believes that everyone else is. When she gets  $x_i^*$ , she thinks "well, half of the people got above  $x_i^*$ , and half got below. So, half are going to invest, half aren't. That's what happens with the integral.

Suppose you received  $x_i > x^*$ , but decided not to invest. Then you would get 0. Your expected value from investing would be

$$\mathbb{E}[A + \theta] = \mathbb{E}[A] + x_i > \frac{1}{2} + x_i > \frac{1}{2} + x^* = 0$$

positive.<sup>2</sup> So, there's no incentive to deviate.

- (c) The posterior distribution of  $\theta$  is

$$\theta \mid x_i, z \sim N\left(\frac{\alpha}{\eta}x_i + \frac{\beta}{\eta}z, \frac{1}{\eta}\right)$$

where  $\eta \equiv \alpha + \beta$ . The distribution of  $\theta + \nu_j \mid x_i$  is

$$\theta + \nu_j \mid x_i \sim N\left(\frac{\alpha}{\eta}x_i + \frac{\beta}{\eta}z, \frac{1}{\eta} + \frac{1}{\alpha}\right) \stackrel{d}{=} \left(\frac{\alpha}{\eta}x_i + \frac{\beta}{\eta}z, \frac{2\alpha + \beta}{\eta\alpha}\right)$$

So that

$$\sqrt{\frac{\eta\alpha}{2\alpha + \beta}} \left[ \theta + \nu_j - \left( \frac{\alpha}{\eta}x_i + \frac{\beta}{\eta}z \right) \right] \sim N(0, 1)$$

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<sup>2</sup>You think half of the people are above you and following the threshold strategy, so  $\mathbb{E}[A] > \frac{1}{2}$

Thus,

$$\begin{aligned}\mathbb{P}[x_j < x_i \mid x_i] &= \mathbb{P}[\theta + \nu_j < x_i \mid x_i] \\ &= \Phi \left\{ \sqrt{\frac{\eta\alpha}{2\alpha + \beta}} \left[ x_i - \left( \frac{\alpha}{\eta} x_i + \frac{\beta}{\eta} z \right) \right] \right\}\end{aligned}$$

Ugh. Let's just go with "the other is symmetric."

(d) I cannot believe this worked.

$$\begin{aligned}\mathbb{P}[x_j < x_i \mid x_i] &= \Phi \left\{ \sqrt{\frac{\eta\alpha}{2\alpha + \beta}} \left[ x_i - \left( \frac{\alpha}{\eta} x_i + \frac{\beta}{\eta} z \right) \right] \right\} \\ &= \Phi \left\{ \sqrt{\frac{\alpha^2 + \alpha\beta}{2\alpha + \beta}} \left[ x_i - \left( \frac{\alpha}{\alpha + \beta} x_i + \frac{\beta}{\alpha + \beta} z \right) \right] \right\} \\ &= \Phi \{ \infty [x_i - x_i] \} \\ &= \Phi(\infty \cdot 0) \\ &= \Phi(0) \\ &= \frac{1}{2}.\end{aligned}$$

That's some questionable math if I ever did see it. As for Morris-Shin, we definitely have arbitrarily small private noise, so we definitely have uniqueness. So it's good that I found uniqueness above.

(e) If the agent believes that those at the threshold will not break their indifference in favor of not investing, then we have one threshold equilibrium characterized by the following indifference point:

$$\begin{aligned}0 &= \mathbb{E}[\theta + A \mid x_i^*] \\ &= x_i^* + \mathbb{E}[A \mid x_i^*] \\ &= x_i^* + \frac{1}{2}(1 - \lambda) \\ \implies x_i^* &= -\frac{1}{2}(1 - \lambda).\end{aligned}$$

And the other with:

$$\begin{aligned}0 &= \mathbb{E}[\theta + A \mid x_i^*] \\ &= x_i^* + \lambda \frac{1}{2}(1 - \lambda) \\ \implies x_i^* &= -\lambda - \frac{1}{2}(1 - \lambda).\end{aligned}$$

When  $\lambda \rightarrow 0$ , there is only one equilibrium with the threshold strategy equal to that from part (a): people think they're exactly in the middle of the signals.

With  $\lambda \rightarrow 1$ , the person thinks that everyone is like them. When this is the case, there are two equilibria: one with  $x^* = -1$ , and one with  $x^* = 0$ . In the first equilibrium, people invest with  $x_i > -1$ , and they believe that everyone else has the same signal and is investing, so they must either all invest and  $A = 1$ . But, with  $A = 1$ , expected payoffs are 0. This seems less stable than the other threshold equilibrium...

## 4 Investment and Complementary

- (a) An equilibrium in this game is given by a demand function for the asset,  $k_j(x_j, p)$ ; an effort function  $\ell_i(x_i, p)$ ; and a price function  $p = P(\theta, \varepsilon)$  such that:

1. traders maximize utility,

$$k_j(x_j, p) \in \operatorname{argmax}_{k_j} -\mathbb{E} \left[ \exp \{ -\gamma(w_0 + (R - p)k_j) \} \middle| x_j, p \right], \quad \forall j,$$

2. entrepreneurs maximize utility,

$$\ell_i(x_i, p) \in \operatorname{argmax}_{\ell_i} \mathbb{E} \left[ R\ell_i - \frac{1}{2}\ell_i^2 \middle| x_i, p \right], \quad \forall i,$$

3. and markets clear,

$$K = \varepsilon.$$

$K \equiv \int k_i di$  is aggregate demand; aggregate supply is denoted by  $\varepsilon \sim N(0, \sigma_\varepsilon^2)$ ; the return to effort is  $R \equiv (1 - \beta)\theta + \beta L$ ; and aggregate effort is  $L = \int \ell_i di$ . Let's impose a symmetric equilibrium whereby

$$\begin{aligned} k(x, p) &\equiv k_j(x, p), \quad \forall j \\ \ell(x, p) &\equiv \ell_i(x, p), \quad \forall i. \end{aligned}$$

- (b) We conjecture that  $p = P(\theta, \varepsilon) = \theta + \lambda \varepsilon$ .

$$p = \theta + \lambda \varepsilon \sim N \left( \theta, \frac{\lambda^2}{\kappa_\varepsilon} \right) \equiv N \left( \theta, \frac{1}{\kappa_p} \right)$$

The entrepreneur's posterior distribution of  $\theta$  is

$$\theta | x_i, p \sim N \left( \frac{\kappa_x}{\kappa_x + \kappa_p} x_i + \frac{\kappa_p}{\kappa_x + \kappa_p} p, \frac{1}{\kappa_x + \kappa_p} \right)$$

Let's further guess some linear forms for the equilibrium strategies:

$$\begin{aligned} L(\theta, p) &= \Phi_\theta \theta + \Phi_p p \\ \ell(x_i, p) &= \phi_x x_i + \phi_p p \end{aligned}$$

The FOC of the entrepreneur utility maximization is

$$\mathbb{E}_i[R] = \ell_i \iff (1 - \beta) \mathbb{E}[\theta | p, x_i] + \beta \Phi_\theta \mathbb{E}[\theta | p, x_i] + \beta \Phi_p p = \ell_i$$

Plugging in expectations yields:

$$\begin{aligned} \ell_i &= (1 - \beta + \beta \Phi_\theta) \left( \frac{\kappa_x}{\kappa_x + \kappa_p} x_i + \frac{\kappa_p}{\kappa_x + \kappa_p} p \right) + \beta \Phi_p p \\ &= \underbrace{(1 - \beta + \beta \Phi_\theta) \left( \frac{\kappa_x}{\kappa_x + \kappa_p} \right)}_{\phi_x} x_i + \underbrace{\left( \frac{(1 - \beta + \beta \Phi_\theta) \kappa_p}{\kappa_x + \kappa_p} + \beta \Phi_p \right)}_{\phi_p} p \end{aligned} \tag{4}$$

Aggregate effort is then given by

$$L(\theta, p) = \int \ell_i(x, p) f(x) dx = \int \phi_x x_i + \phi_p p \phi \left( \frac{x - \theta}{\sigma_x} \right) dx = \phi_x \theta + \phi_p p$$

So,  $\phi_x = \Phi_\theta$  and  $\phi_p = \Phi_p$ . Using this in (4) reveals

$$\begin{aligned}
\phi_x &= (1 - \beta + \beta\phi_x) \left( \frac{\kappa_x}{\kappa_x + \kappa_p} \right) \\
\Rightarrow \phi_x \left( 1 - \beta \left( \frac{\kappa_x}{\kappa_x + \kappa_p} \right) \right) &= (1 - \beta) \left( \frac{\kappa_x}{\kappa_x + \kappa_p} \right) \\
\Rightarrow \phi_x \left( \frac{(1 - \beta)\kappa_x + \kappa_p}{\kappa_x + \kappa_p} \right) &= (1 - \beta) \left( \frac{\kappa_x}{\kappa_x + \kappa_p} \right) \\
\Rightarrow \boxed{\phi_x = \frac{(1 - \beta)\kappa_x}{(1 - \beta)\kappa_x + \kappa_p}}
\end{aligned}$$

Again, using for to solve for  $\phi_p$  reveals:

$$\begin{aligned}
\phi_p &= \frac{(1 - \beta - \beta\Phi_\theta)\kappa_p}{\kappa_x + \kappa_p} + \beta\phi_p \\
\Rightarrow \phi_p &= \frac{1}{1 - \beta} \left( \frac{(1 - \beta)\kappa_p}{\kappa_x + \kappa_p} - \frac{\beta\kappa_p}{\kappa_x + \kappa_p} \phi_x \right) \\
\Rightarrow \phi_p &= \frac{\kappa_p}{\kappa_x + \kappa_p} - \frac{\beta\kappa_p}{\kappa_x + \kappa_p} \cdot \frac{\kappa_x}{(1 - \beta)\kappa_x + \kappa_p} \\
\Rightarrow \boxed{\phi_p = \frac{\kappa_p}{\kappa_x + \kappa_p} - \frac{\beta\kappa_p}{\kappa_x + \kappa_p} \cdot \frac{\kappa_x}{(1 - \beta)\kappa_x + \kappa_p}}
\end{aligned}$$

(c) This is all too ugly... something must be wrong.

$$R = (1 - \beta)\theta + \beta(\phi_x\theta + \phi_p p) = (1 - \beta + \beta\phi_x\theta) + \beta\phi_p p$$

$R$  depends on  $p$  through  $\phi_p$  only. How? Complicatedly. If  $p$  becomes arbitrarily precise, then  $R$  depends directly on  $p$  (with coefficient 1). If  $p$  becomes infinitely variable, then  $R$  does not depend on it.

(d)

(e)

(f)