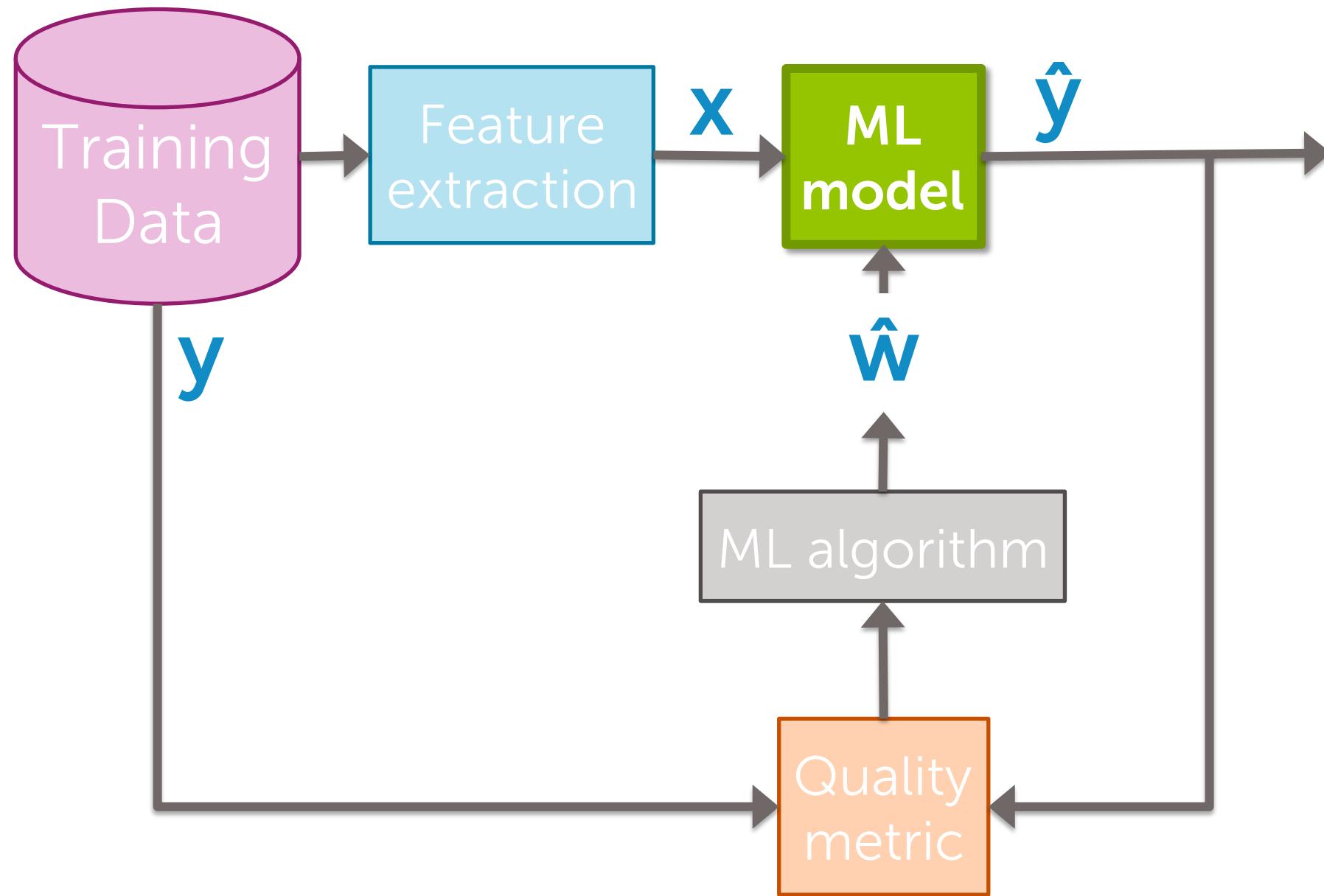
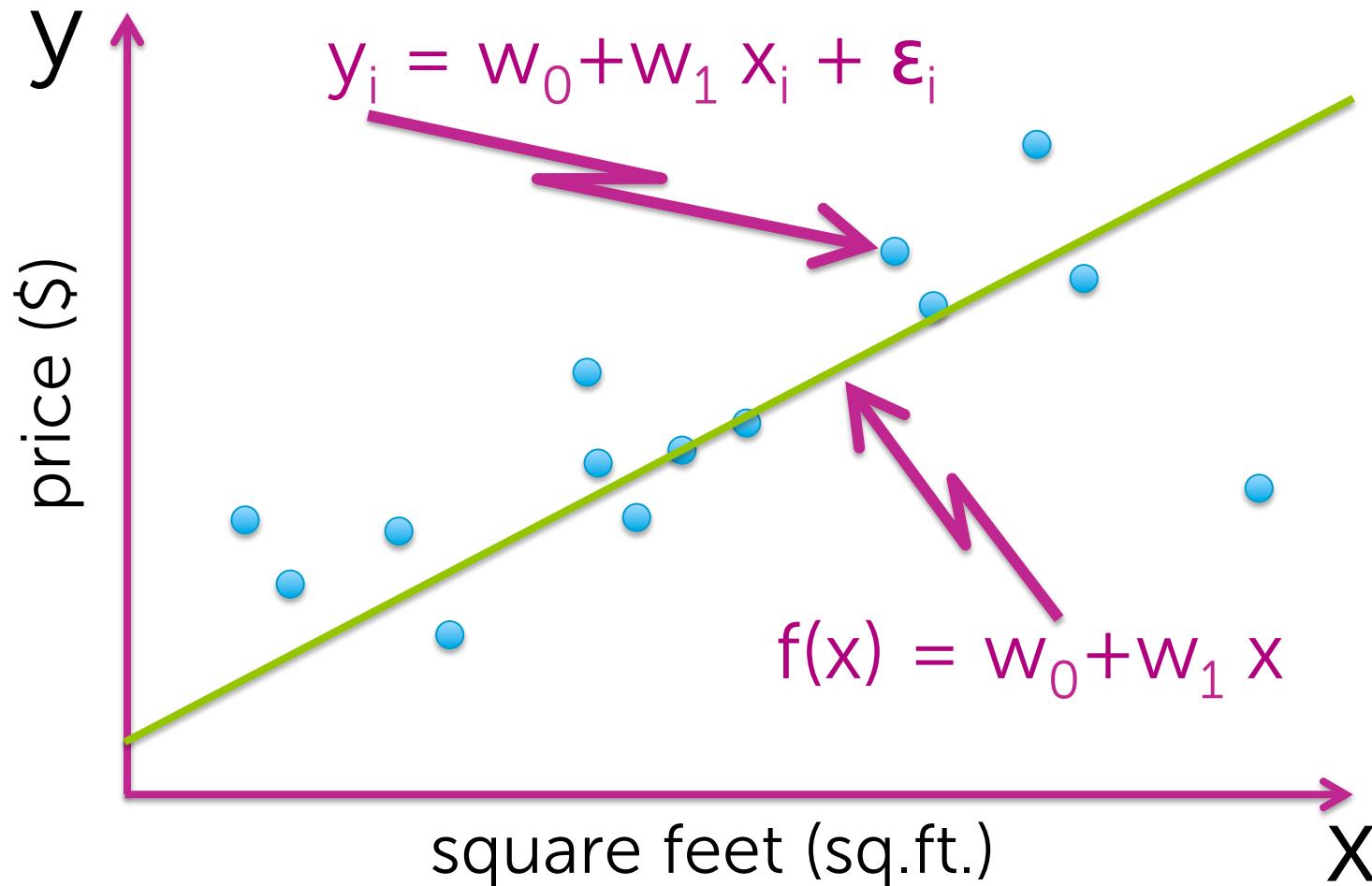


Multiple Regression: Linear regression with multiple features

Emily Fox & Carlos Guestrin
Machine Learning Specialization
University of Washington



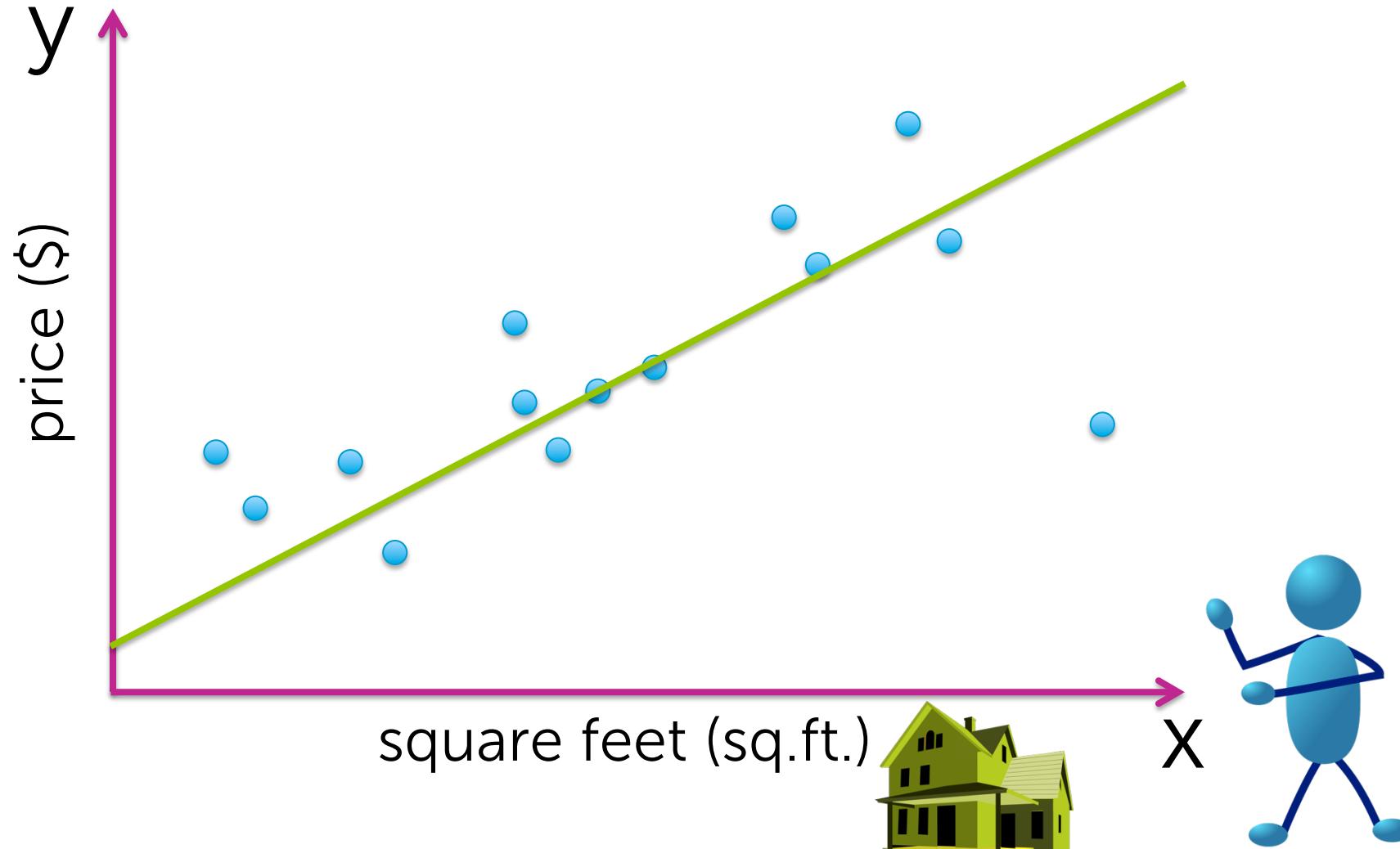
Simple linear regression model



More complex functions of a single input

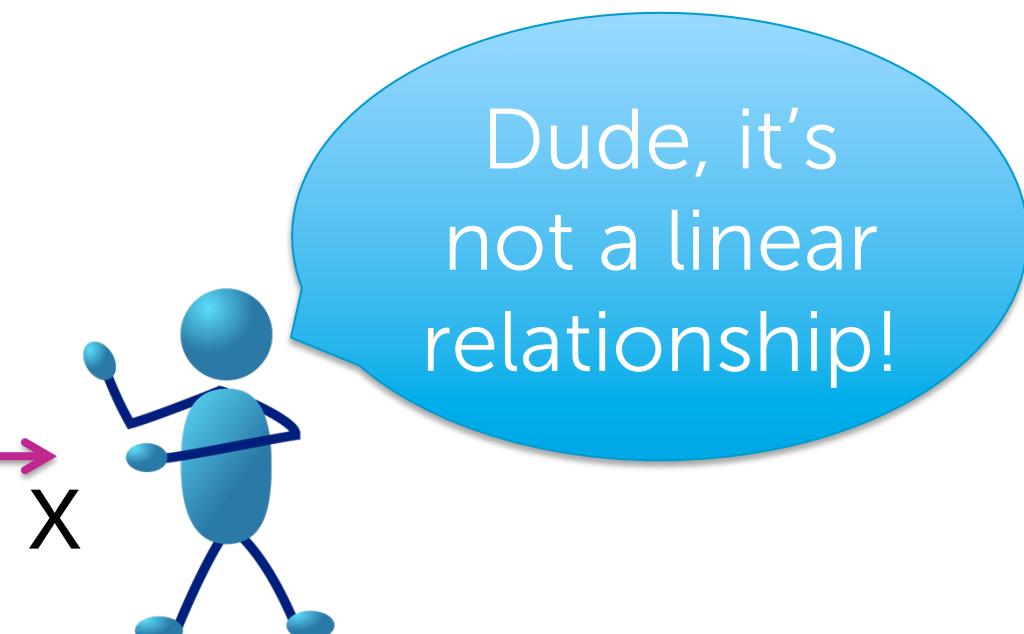
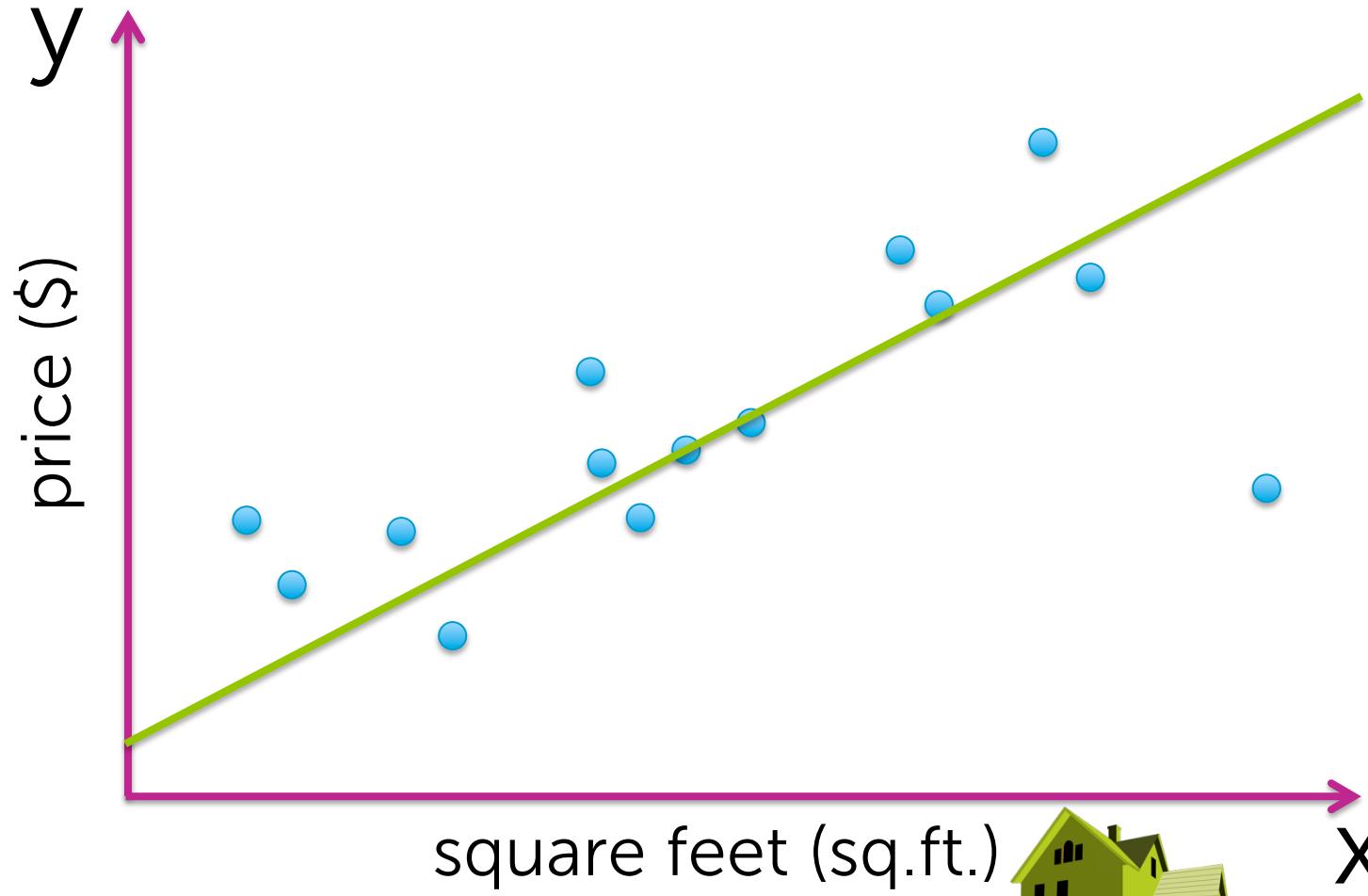
Polynomial regression

Fit data with a line or ... ?

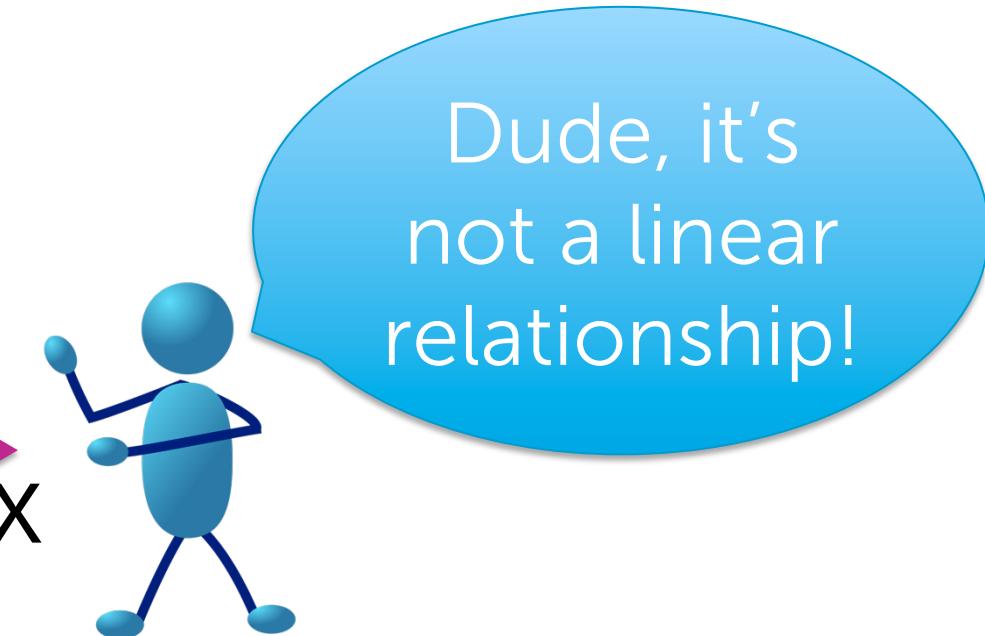
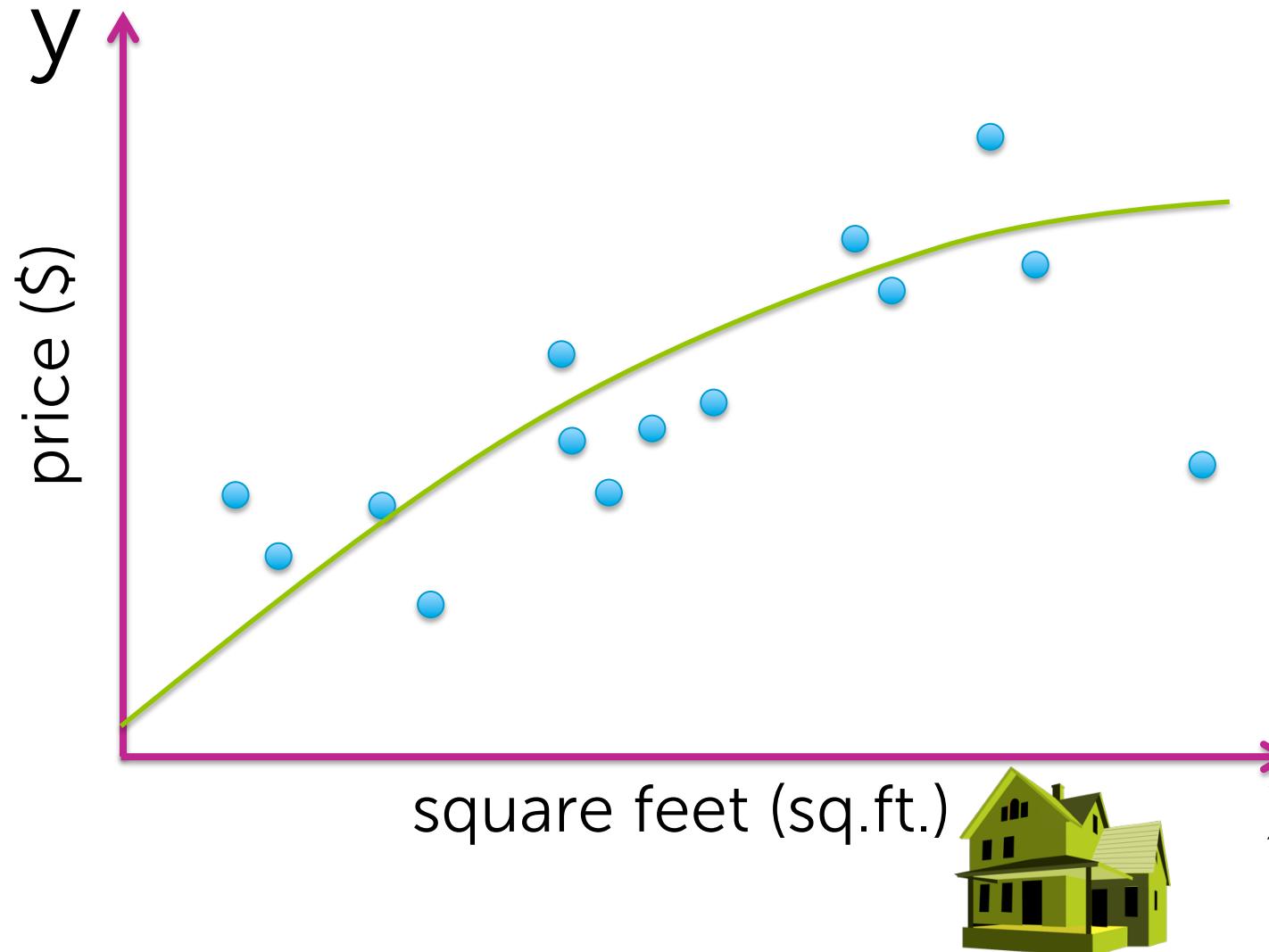


You show
your friend
your analysis

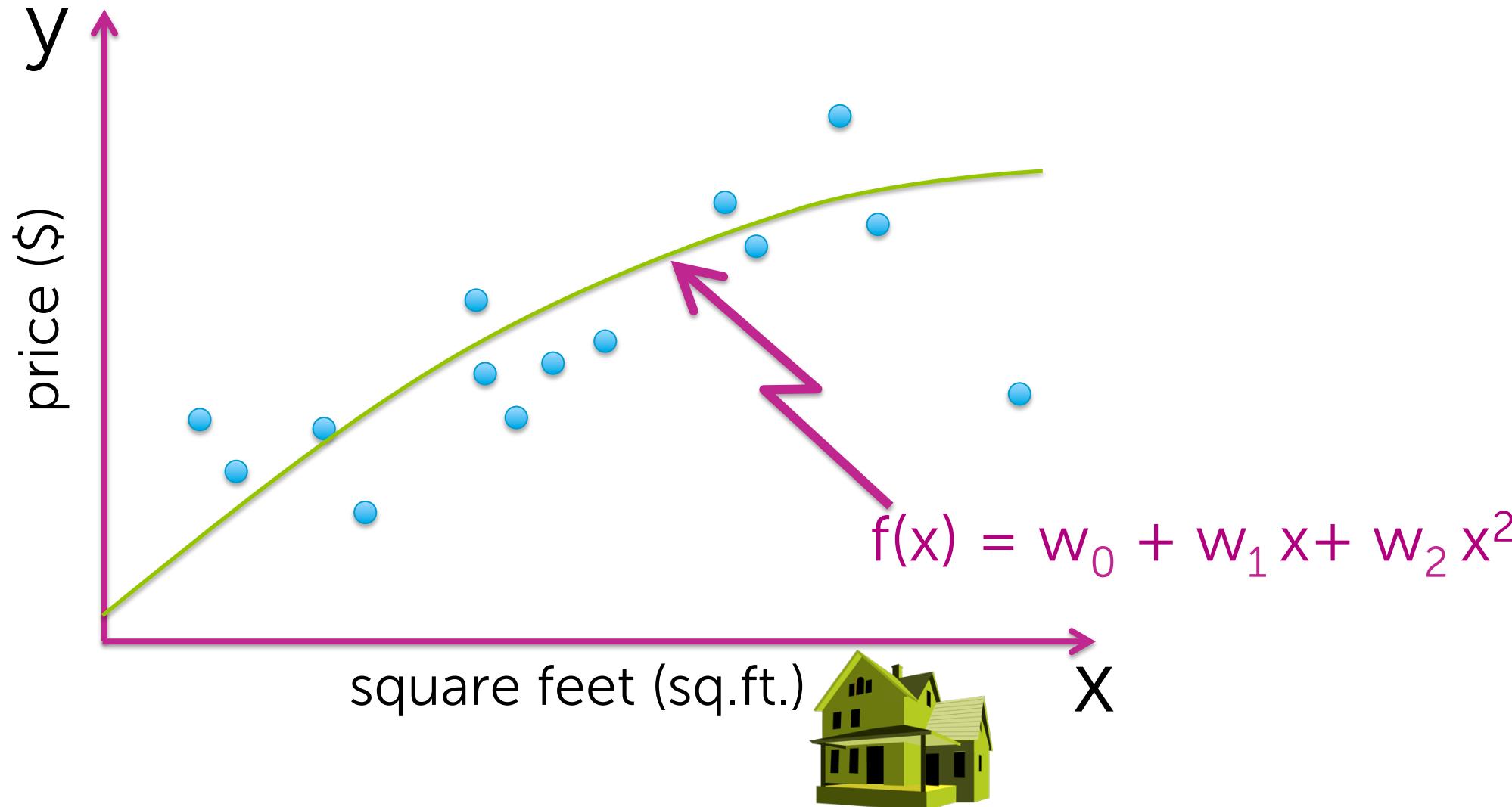
Fit data with a line or ... ?



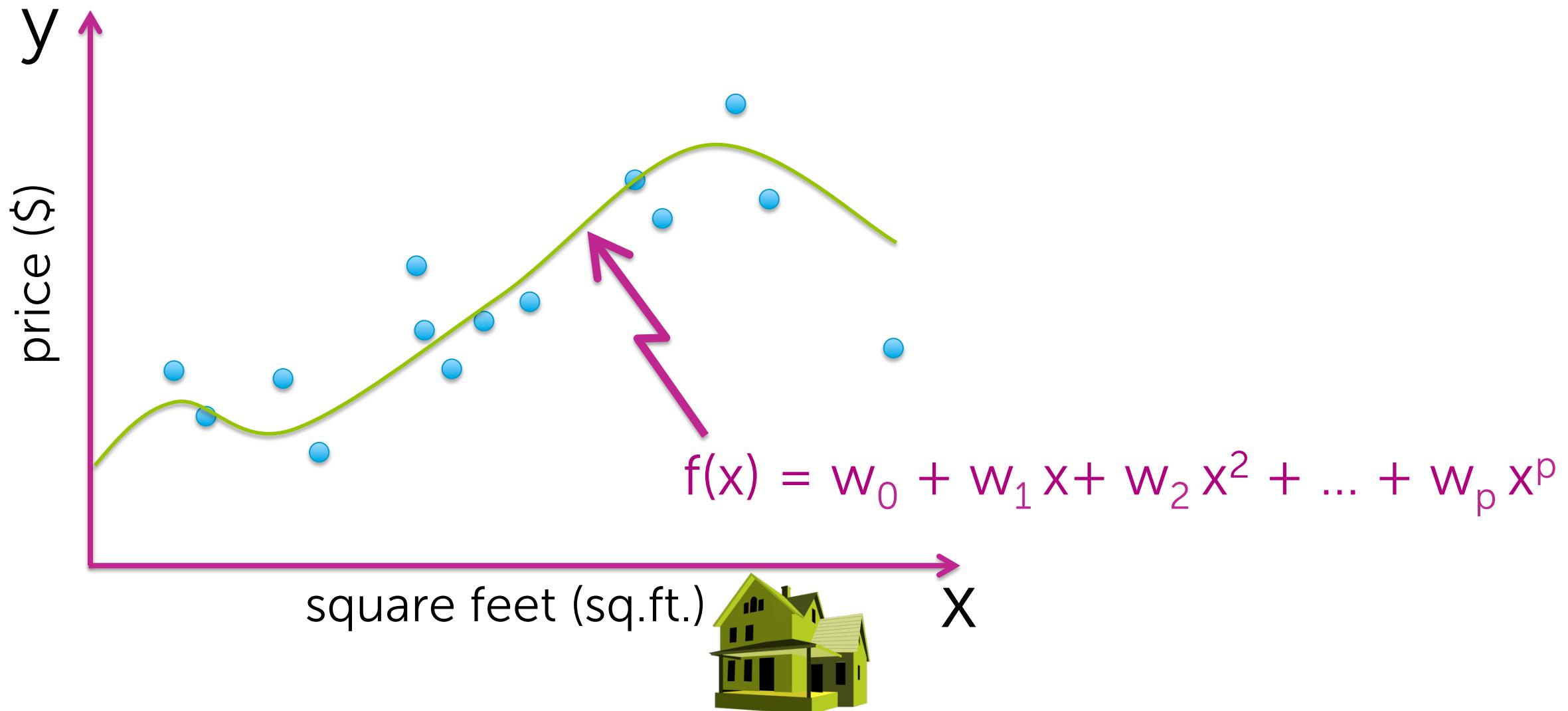
What about a quadratic function?



What about a quadratic function?



Even higher order polynomial



Polynomial regression

Model:

$$y_i = w_0 + w_1 x_i + w_2 x_i^2 + \dots + w_p x_i^p + \epsilon_i$$

treat as different **features**

feature 1 = 1 (constant) parameter 1 = w_0

feature 2 = x

parameter 2 = w_1

feature 3 = x^2

parameter 3 = w_2

...

...

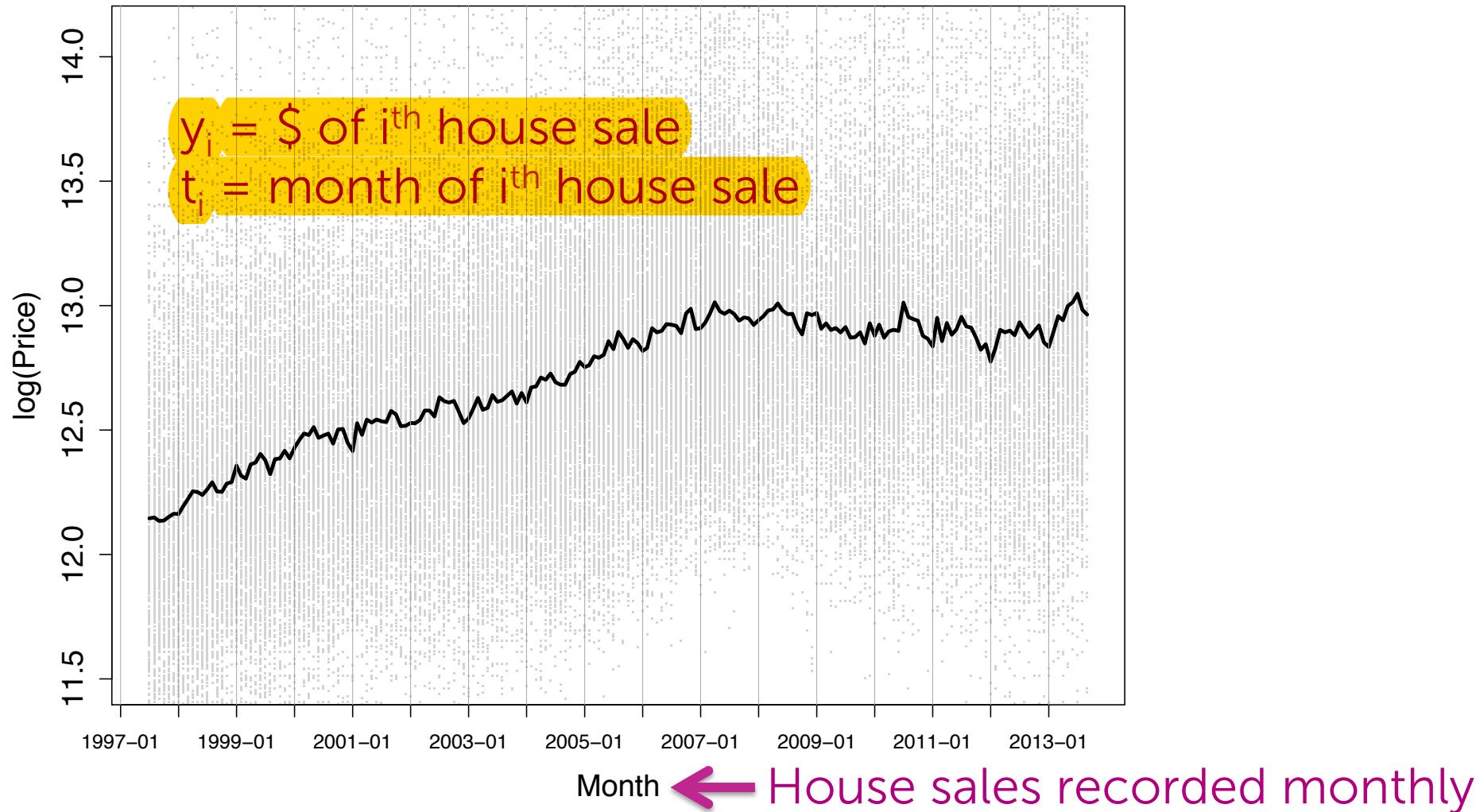
feature $p+1 = x^p$

parameter $p+1 = w_p$

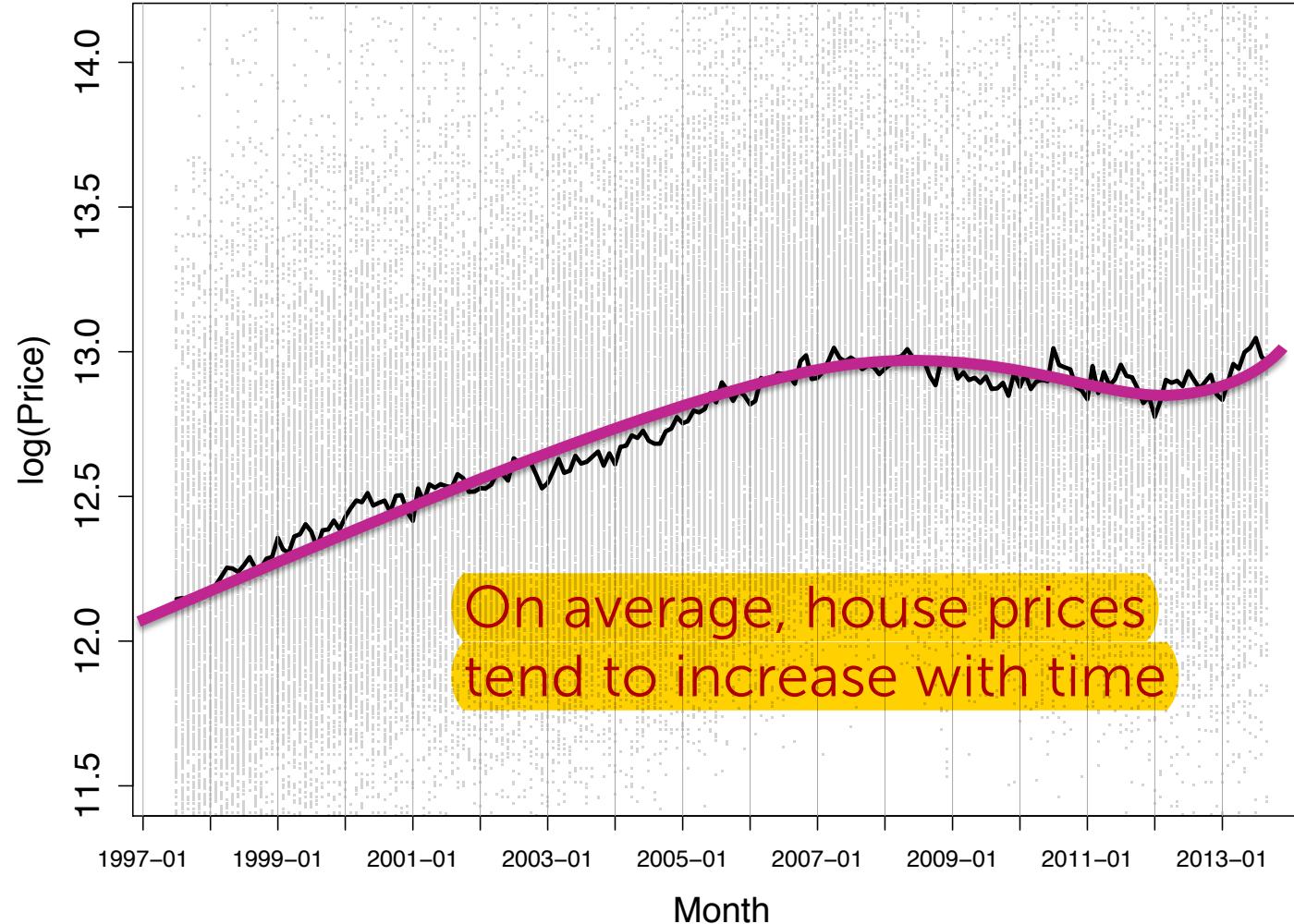


Other functions of one input

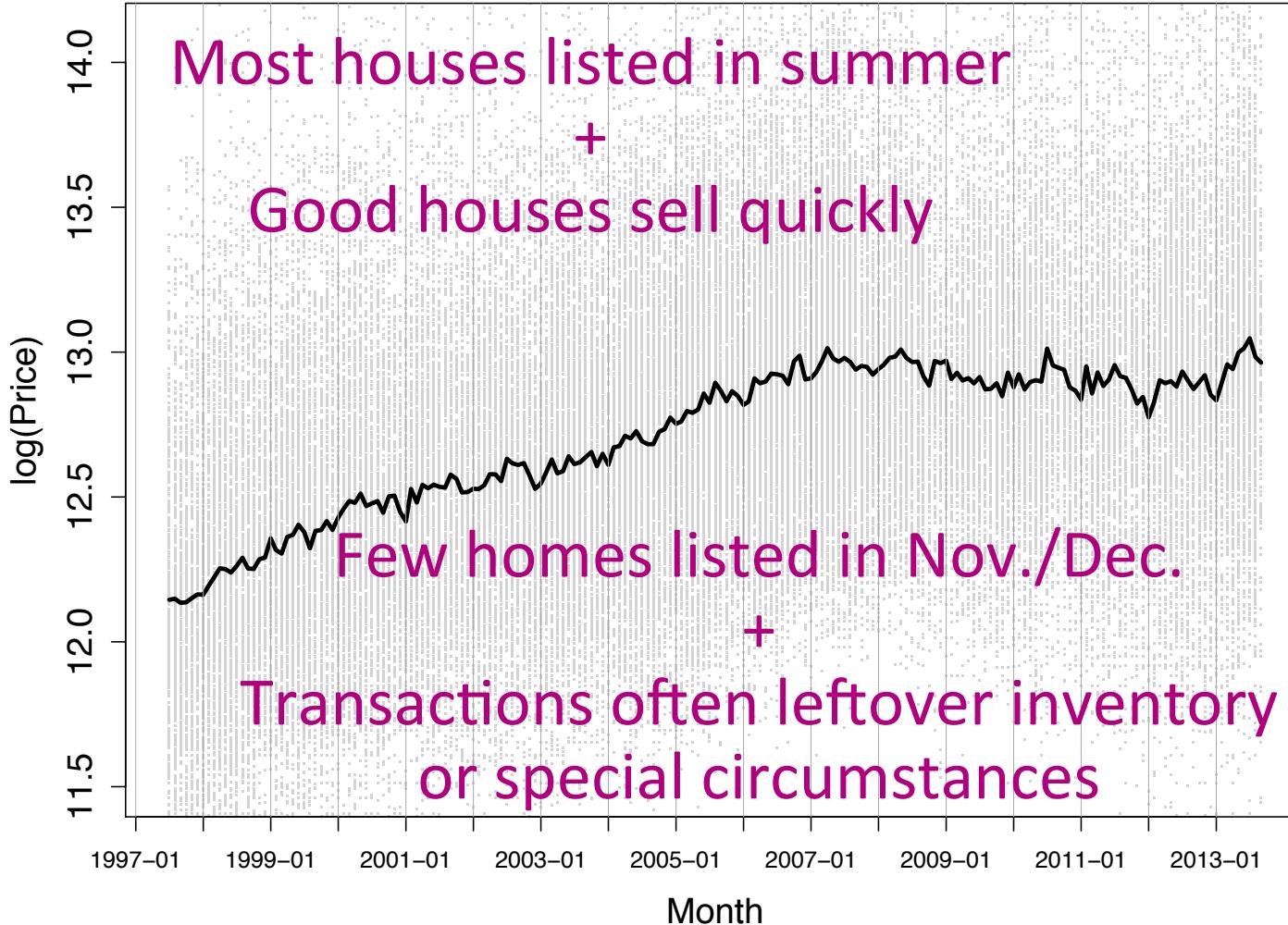
Motivating application: Detrending time series



Trends over time



Seasonality



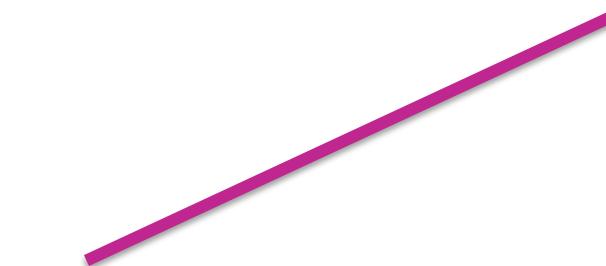
An example detrending

Model:

$$y_i = w_0 + w_1 t_i + w_2 \sin(2\pi t_i / 12 - \Phi) + \epsilon_i$$

Linear trend

Seasonal component =
Sinusoid with period 12
(resets annually)



Trigonometric identity: $\sin(a-b) = \sin(a)\cos(b) - \cos(a)\sin(b)$

$$\rightarrow \sin(2\pi t_i / 12 - \Phi) = \sin(2\pi t_i / 12)\cos(\Phi) - \cos(2\pi t_i / 12)\sin(\Phi)$$



An example detrending

Equivalently,

$$y_i = w_0 + w_1 t_i + w_2 \sin(2\pi t_i / 12) + w_3 \cos(2\pi t_i / 12) + \epsilon_i$$

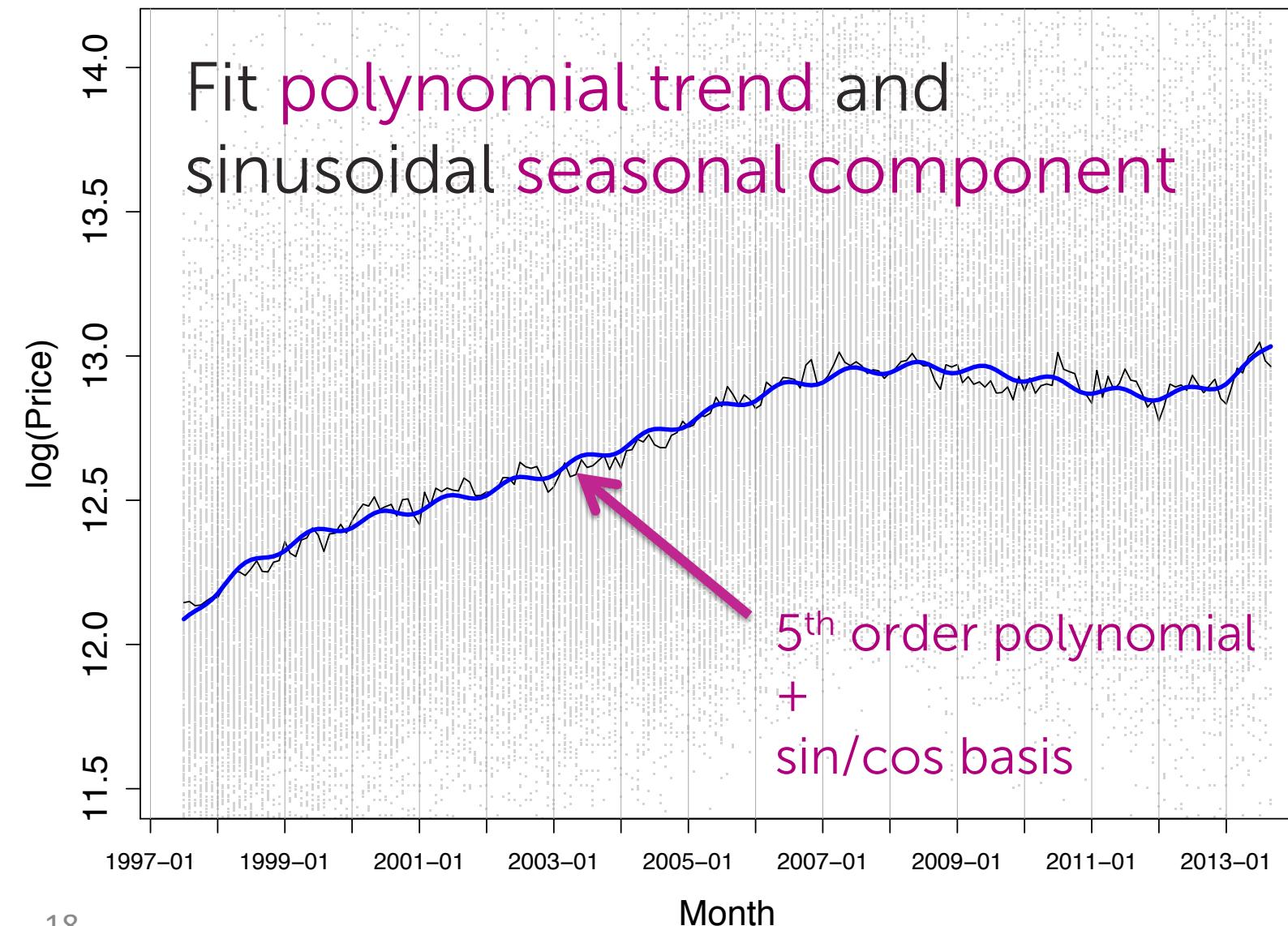
feature 1 = 1 (constant)

feature 2 = t

feature 3 = sin(2πt/12)

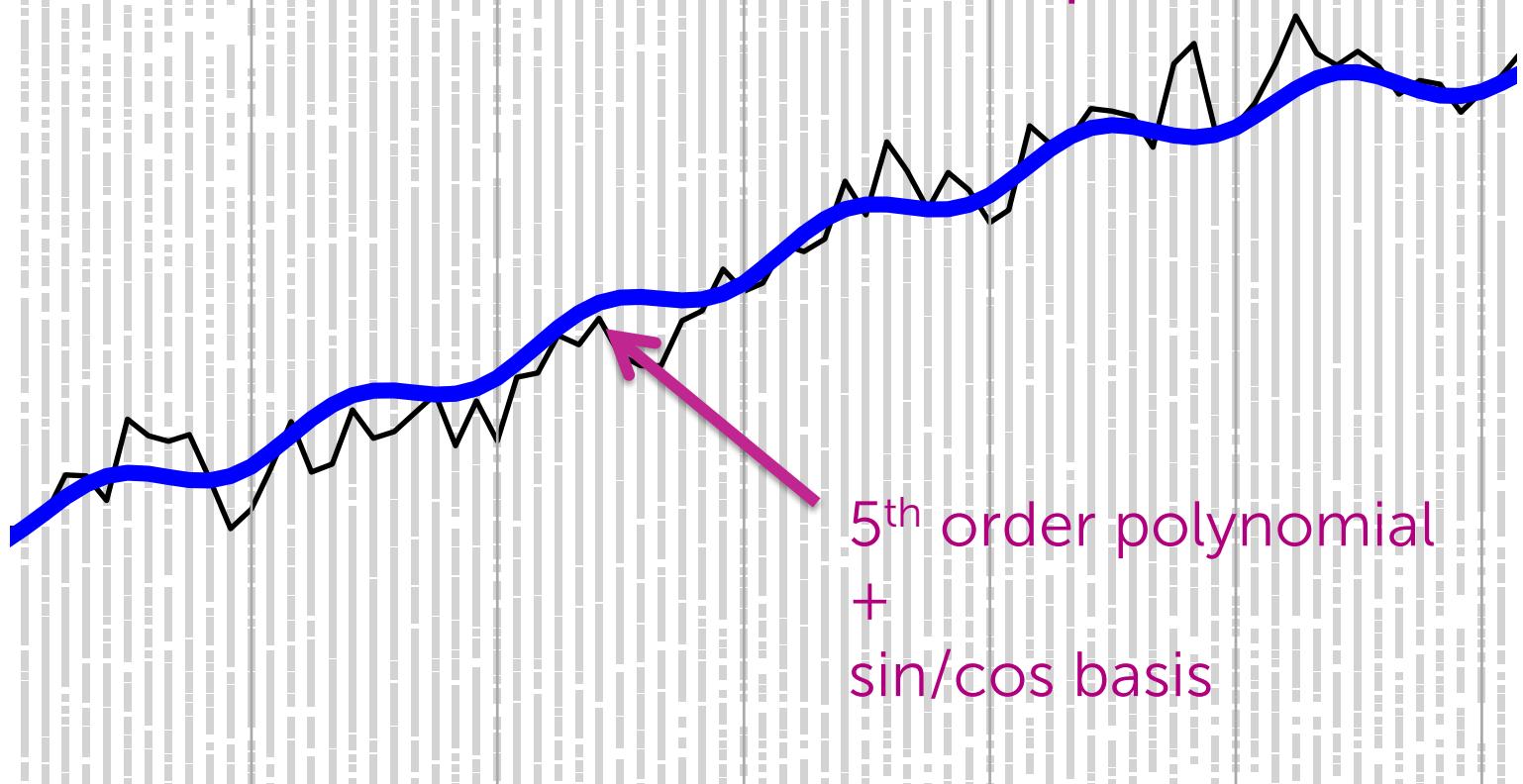
feature 4 = cos(2πt/12)

Detrended housing data

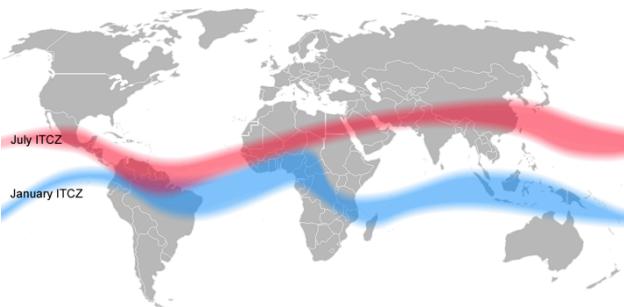


Zoom in...

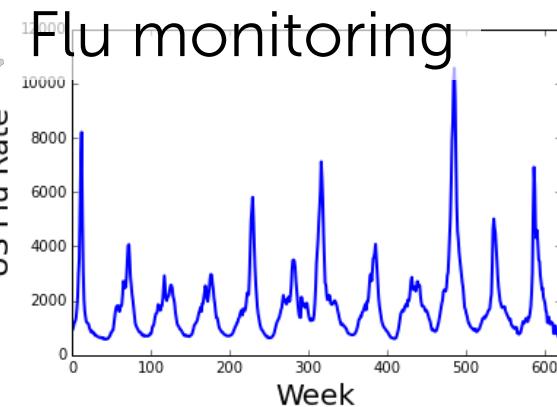
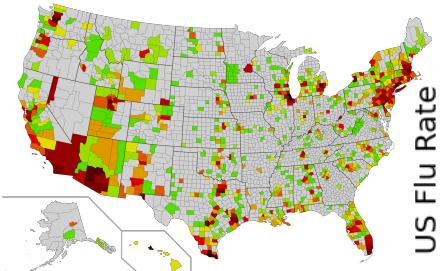
Fit polynomial trend and sinusoidal seasonal component



Other examples of seasonality



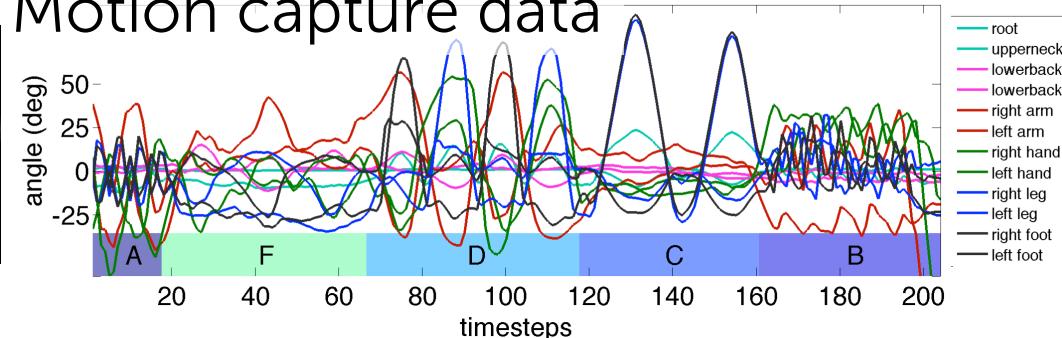
Weather modeling
(e.g., temperature, rainfall)



Demand forecasting
(e.g., jacket purchases)



Motion capture data



More generally... 

Generic basis expansion

Model:

$$\begin{aligned}y_i &= w_0 h_0(x_i) + w_1 h_1(x_i) + \dots + w_D h_D(x_i) + \varepsilon_i \\&= \sum_{j=0}^D w_j h_j(x_i) + \varepsilon_i\end{aligned}$$

jth regression coefficient or weight

jth feature



Generic basis expansion

Model:

$$\begin{aligned}y_i &= w_0 h_0(x_i) + w_1 h_1(x_i) + \dots + w_D h_D(x_i) + \varepsilon_i \\&= \sum_{j=0}^D w_j h_j(x_i) + \varepsilon_i\end{aligned}$$

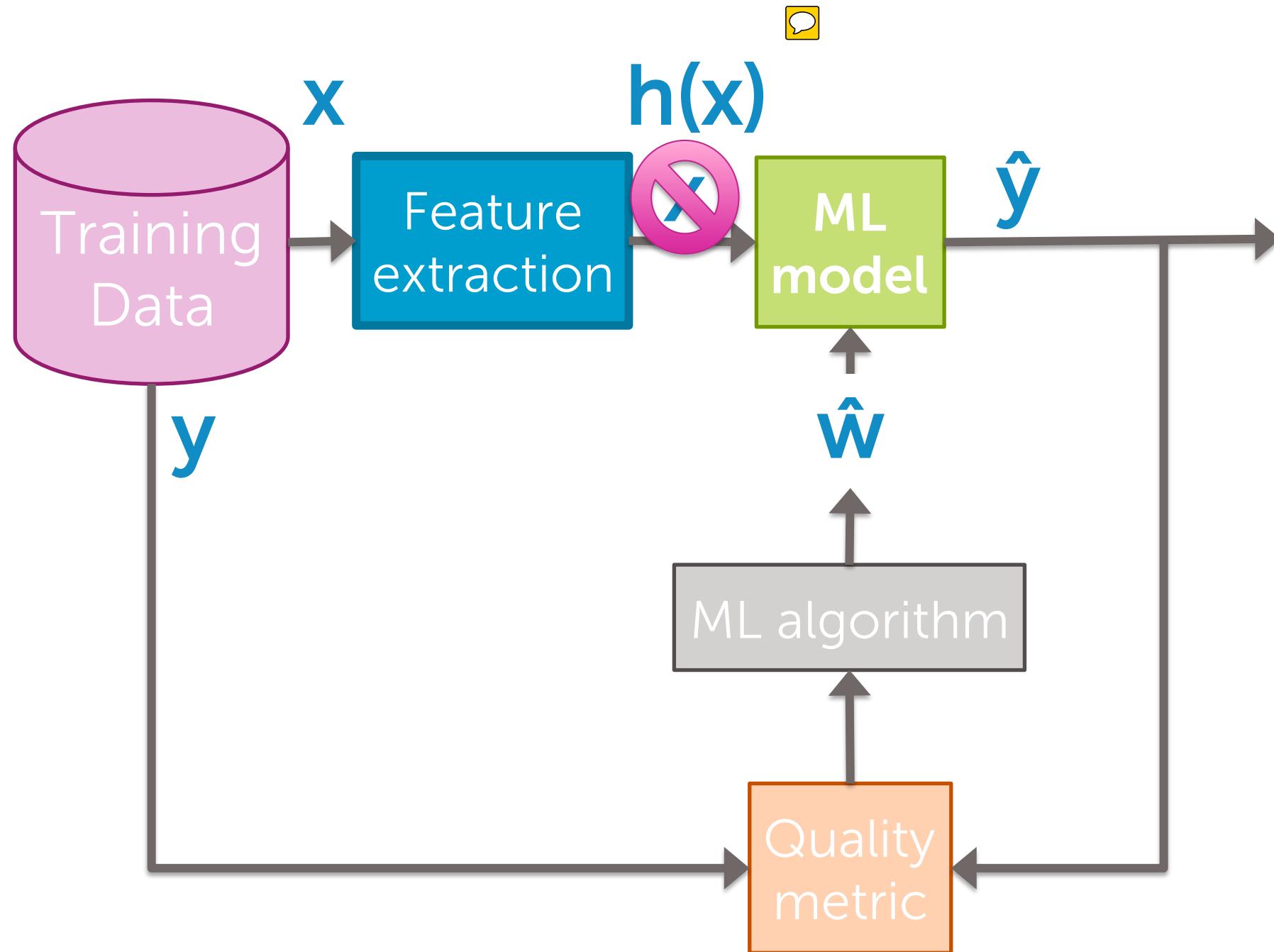
feature 1 = $h_0(x)$... often 1 (constant)

feature 2 = $h_1(x)$... e.g., x

feature 3 = $h_2(x)$... e.g., x^2 or $\sin(2\pi x/12)$

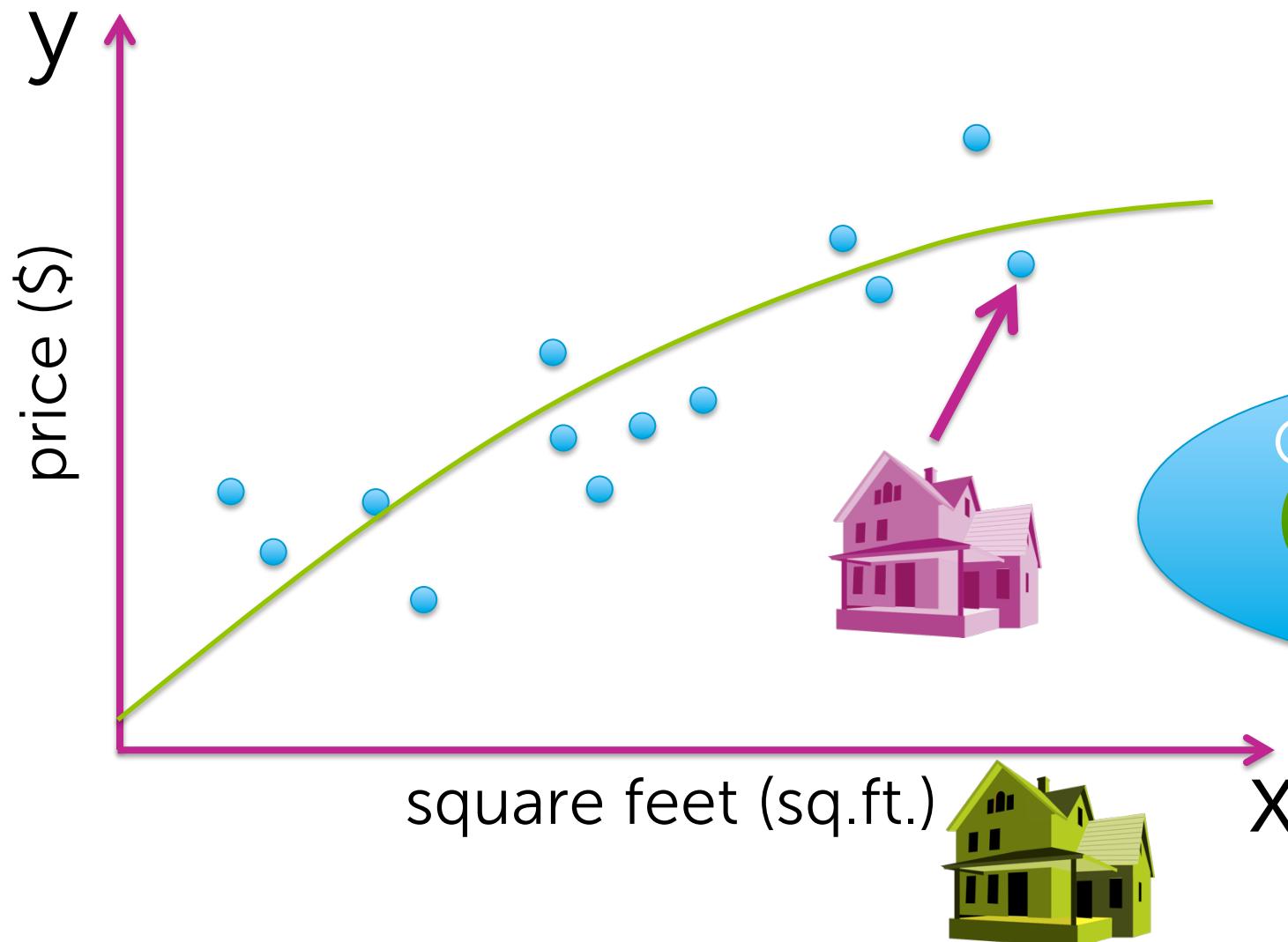
...

feature $D+1 = h_D(x)$... e.g., x^p

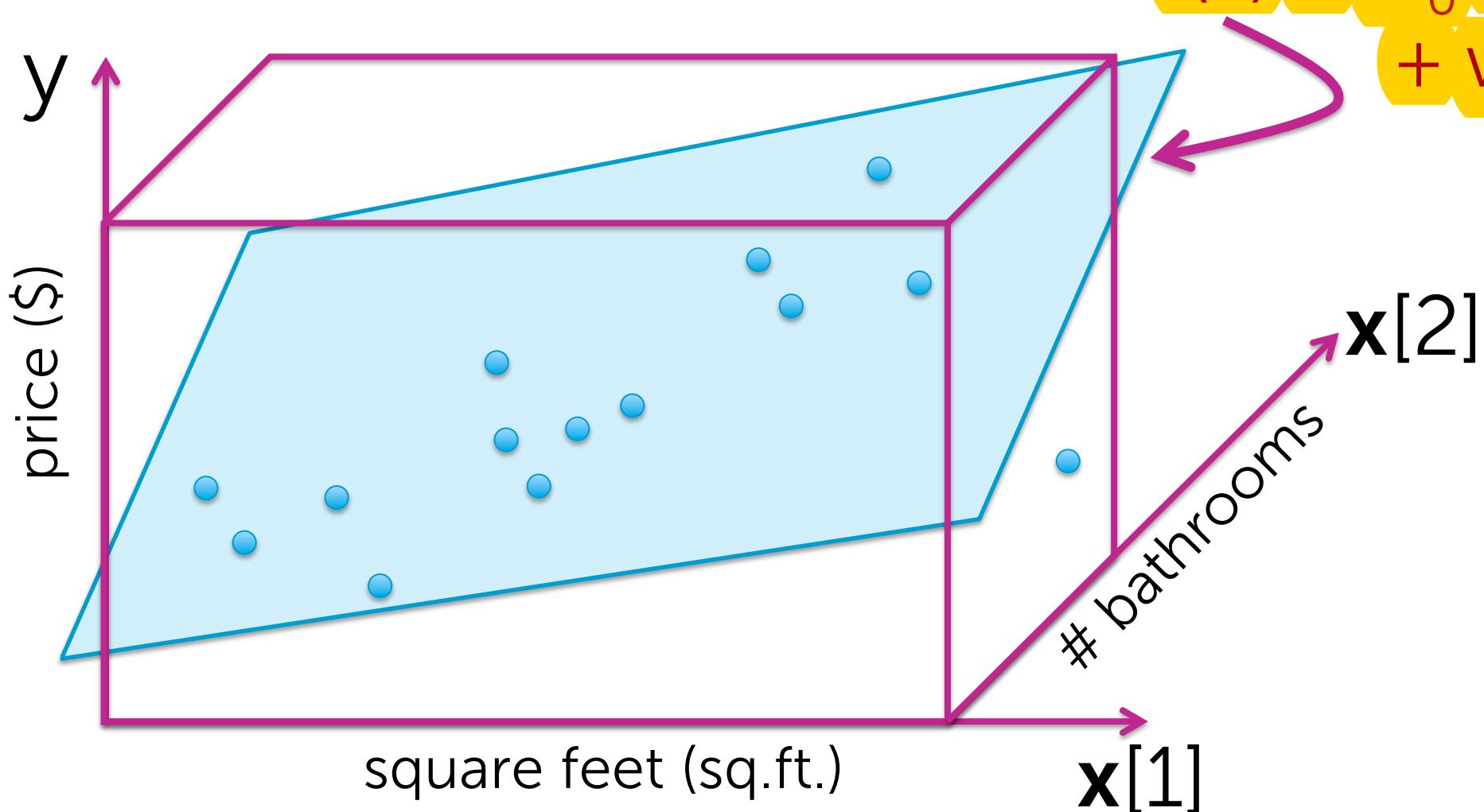


Incorporating multiple inputs

Predictions just based on house size



Add more inputs

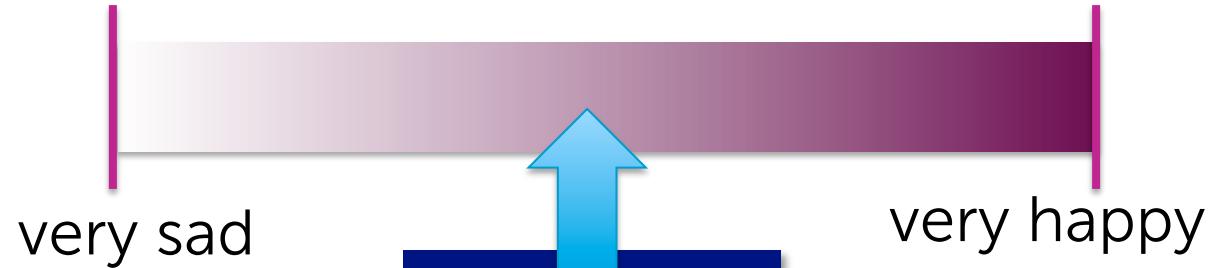


$$f(\mathbf{x}) = w_0 + w_1 \text{sq.ft.} + w_2 \# \text{bath}$$

Many possible inputs

- Square feet
- # bathrooms
- # bedrooms
- Lot size
- Year built
- ...

Reading your mind



Features are
brain region
intensities

General notation

Output: $y \leftarrow$ scalar

Inputs: $\mathbf{x} = (\mathbf{x}[1], \mathbf{x}[2], \dots, \mathbf{x}[d])$ 

 d-dim vector

Notational conventions:

$\mathbf{x}[j]$ = j^{th} input (scalar)

$h_j(\mathbf{x})$ = j^{th} feature (scalar)

\mathbf{x}_i = input of i^{th} data point (vector)

$\mathbf{x}_i[j]$ = j^{th} input of i^{th} data point (scalar)

Simple hyperplane



Model:

$$y_i = w_0 + w_1 x_i[1] + \dots + w_d x_i[d] + \epsilon_i$$

feature 1 = 1

feature 2 = $x[1]$... e.g., sq. ft.

feature 3 = $x[2]$... e.g., #bath

...

feature $d+1 = x[d]$... e.g., lot size

More generically...

D-dimensional curve



Model:

$$y_i = w_0 h_0(\mathbf{x}_i) + w_1 h_1(\mathbf{x}_i) + \dots + w_D h_D(\mathbf{x}_i) + \epsilon_i$$
$$= \sum_{j=0}^D w_j h_j(\mathbf{x}_i) + \epsilon_i$$

feature 1 = $h_0(\mathbf{x})$... e.g., 1

feature 2 = $h_1(\mathbf{x})$... e.g., $\mathbf{x}[1]$ = sq. ft.

feature 3 = $h_2(\mathbf{x})$... e.g., $\mathbf{x}[2]$ = #bath

or, $\log(\mathbf{x}[7]) \mathbf{x}[2] = \log(\#bed) \times \#bath$

...

feature $D+1 = h_D(\mathbf{x})$... some other function of $\mathbf{x}[1], \dots, \mathbf{x}[d]$

More on notation

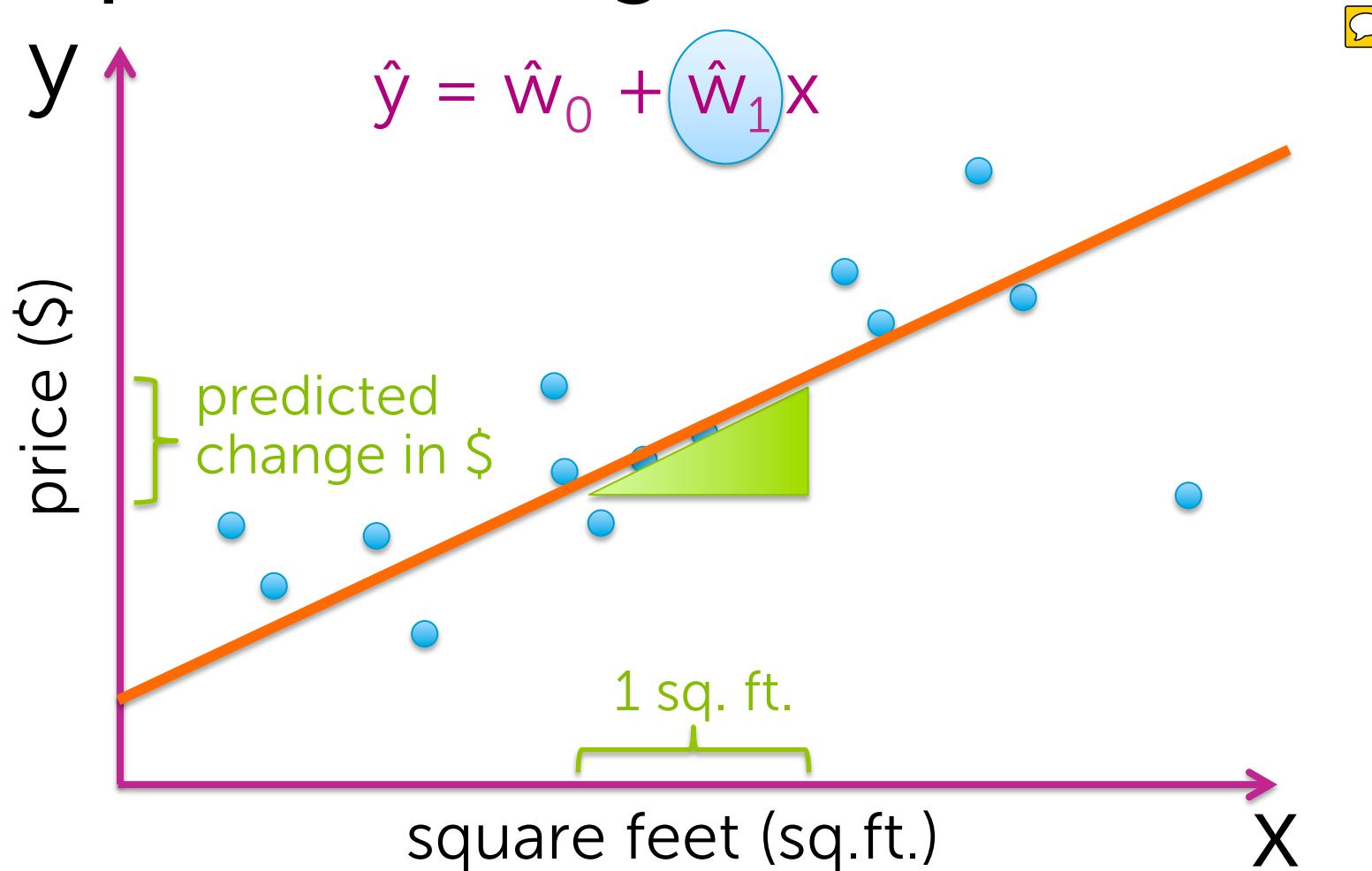
observations (\mathbf{x}_i, y_i) : N

inputs $\mathbf{x}[j]$: d

features $h_j(\mathbf{x})$: D

Interpreting the fitted function

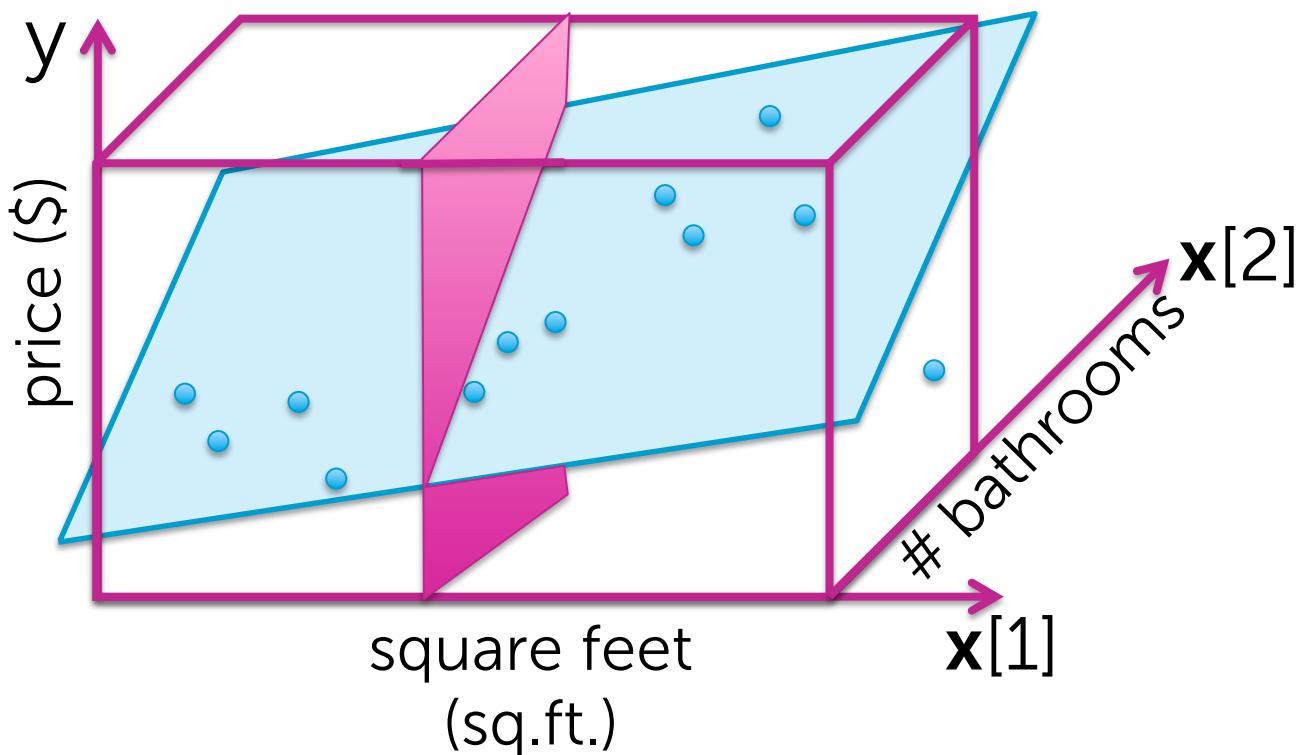
Interpreting the coefficients – Simple linear regression



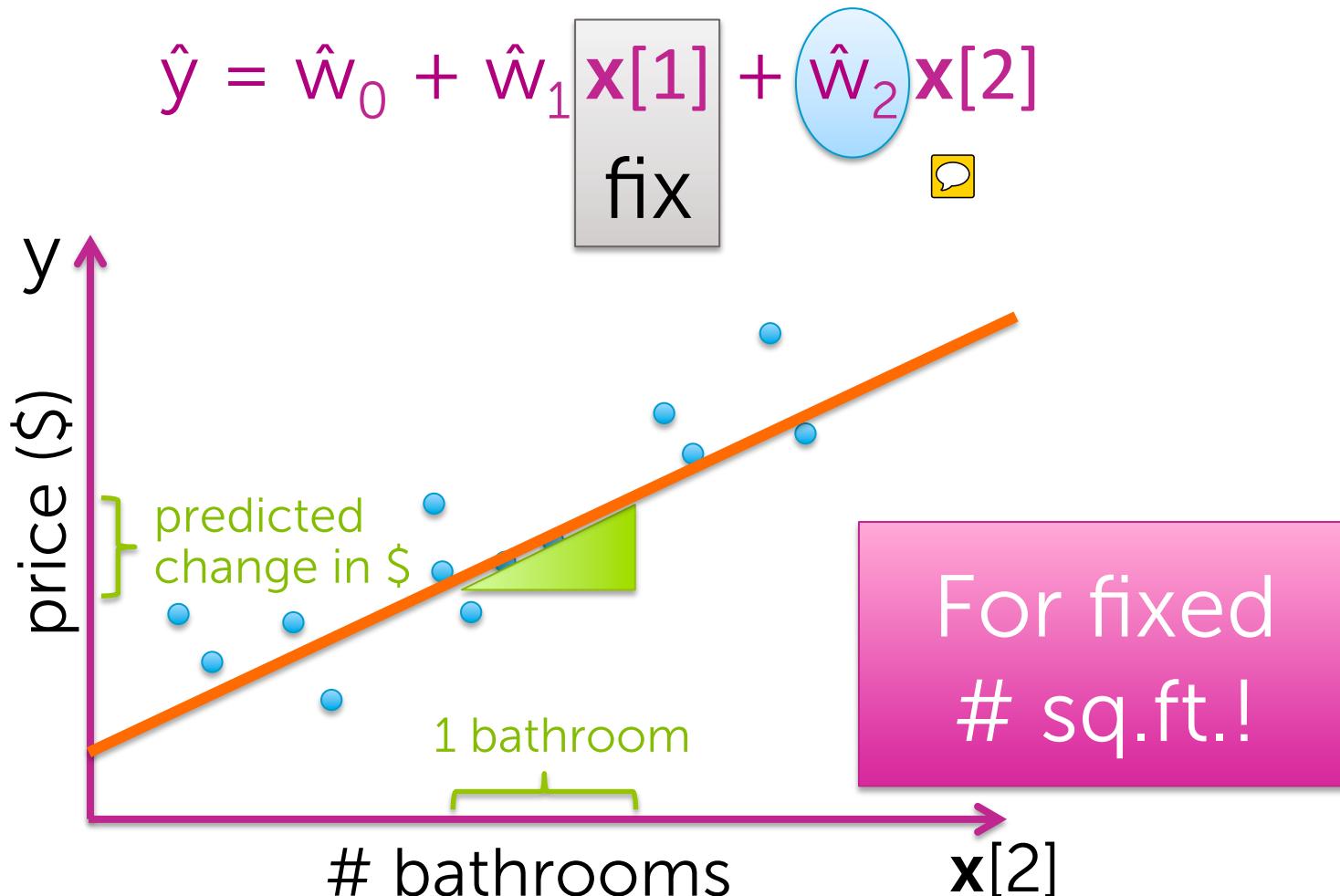
Interpreting the coefficients – Two linear features

$$\hat{y} = \hat{w}_0 + \hat{w}_1 x[1] + \hat{w}_2 x[2]$$

fix



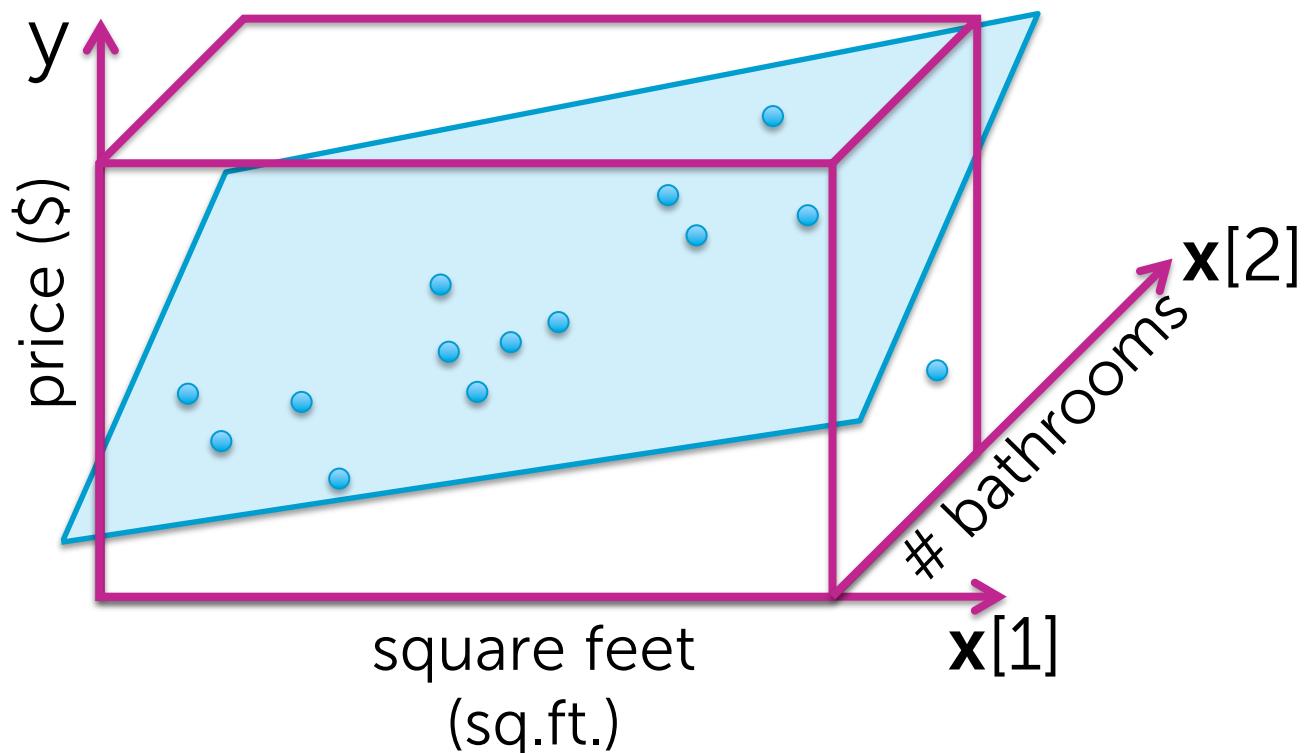
Interpreting the coefficients – Two linear features



Interpreting the coefficients – Multiple linear features

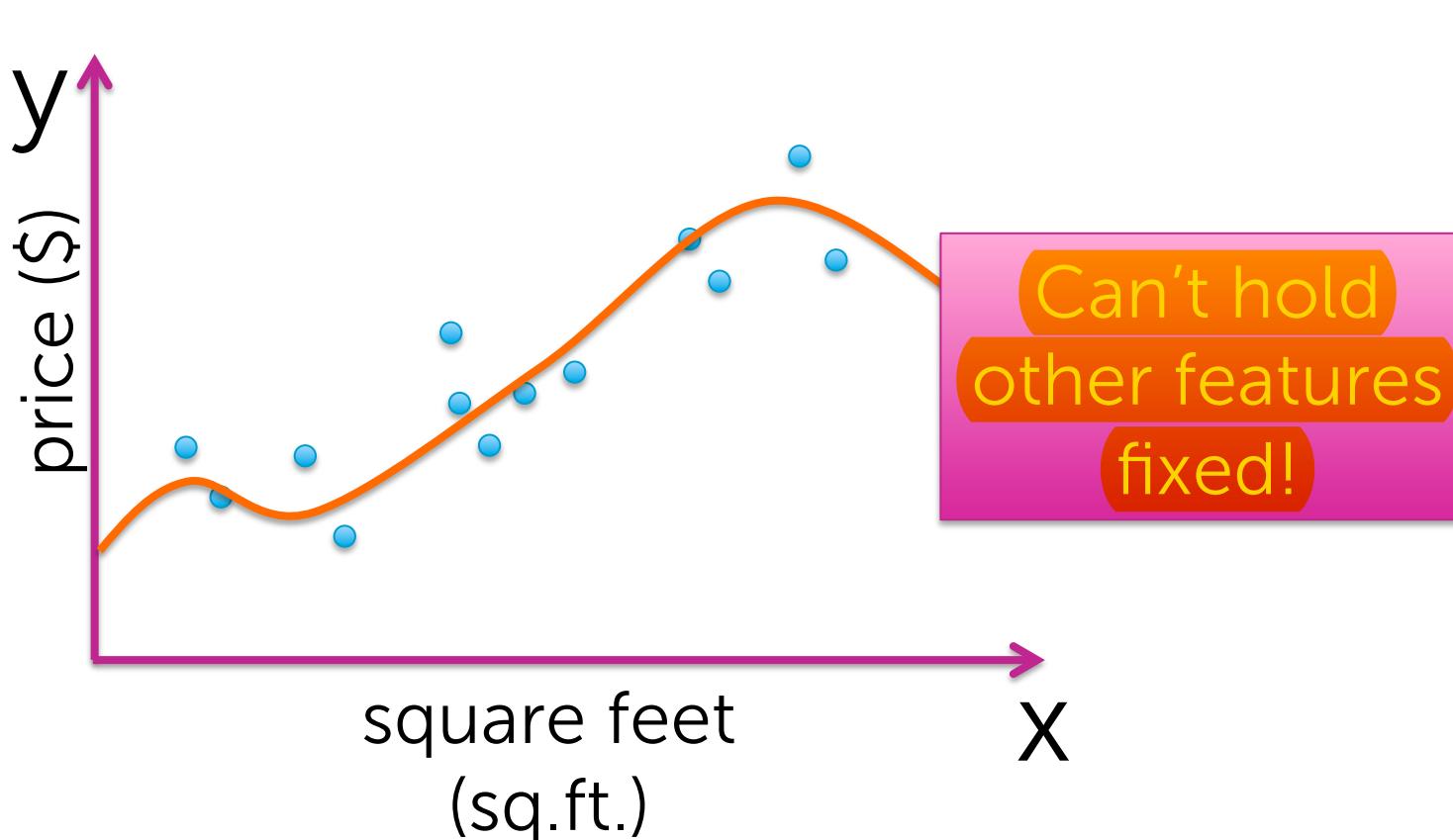
$$\hat{y} = \hat{w}_0 + \hat{w}_1 \mathbf{x}[1] + \dots + \hat{w}_j \mathbf{x}[j] + \dots + \hat{w}_d \mathbf{x}[d]$$

fix fix fix fix

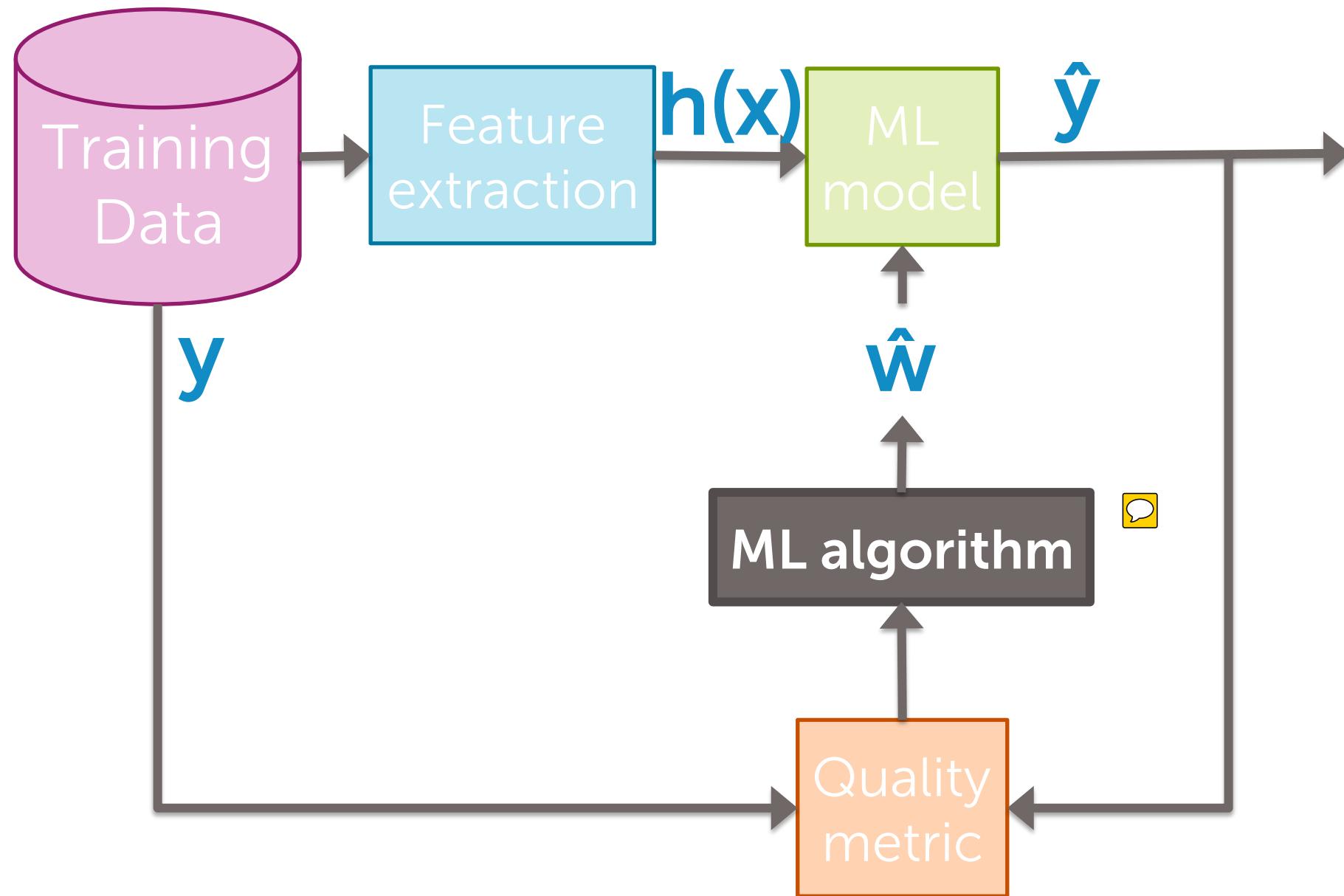


Interpreting the coefficients- Polynomial regression

$$\hat{y} = \hat{w}_0 + \hat{w}_1 x + \dots + \hat{w}_j x^j + \dots + \hat{w}_p x^p$$



Fitting D-dimensional curves



Step 1:

Rewrite the regression model

Rewrite in matrix notation

For observation i

$$y_i = \sum_{j=0}^D w_j h_j(x_i) + \epsilon_i$$

$$y_i = \begin{bmatrix} w_0 & w_1 & w_2 & \dots & w_D \end{bmatrix}$$

$$= w_0 h_0(x_i) + w_1 h_1(x_i) + \dots + w_D h_D(x_i)$$

scalar

$$= w^\top h(x_i) + \epsilon_i$$

$$h(x_i) = \begin{bmatrix} h_0(x_i) \\ h_1(x_i) \\ h_2(x_i) \\ \vdots \\ h_D(x_i) \end{bmatrix}$$

$$h^\top(x_i) = \begin{bmatrix} h_0(x_i) & h_1(x_i) & \dots & h_D(x_i) \end{bmatrix}$$
$$= h_0(x_i) w_0 + h_1(x_i) w_1 + \dots + h_D(x_i) w_D + \epsilon_i$$

$$w = \begin{bmatrix} w_0 \\ w_1 \\ \vdots \\ w_D \end{bmatrix}$$

Rewrite in matrix notation



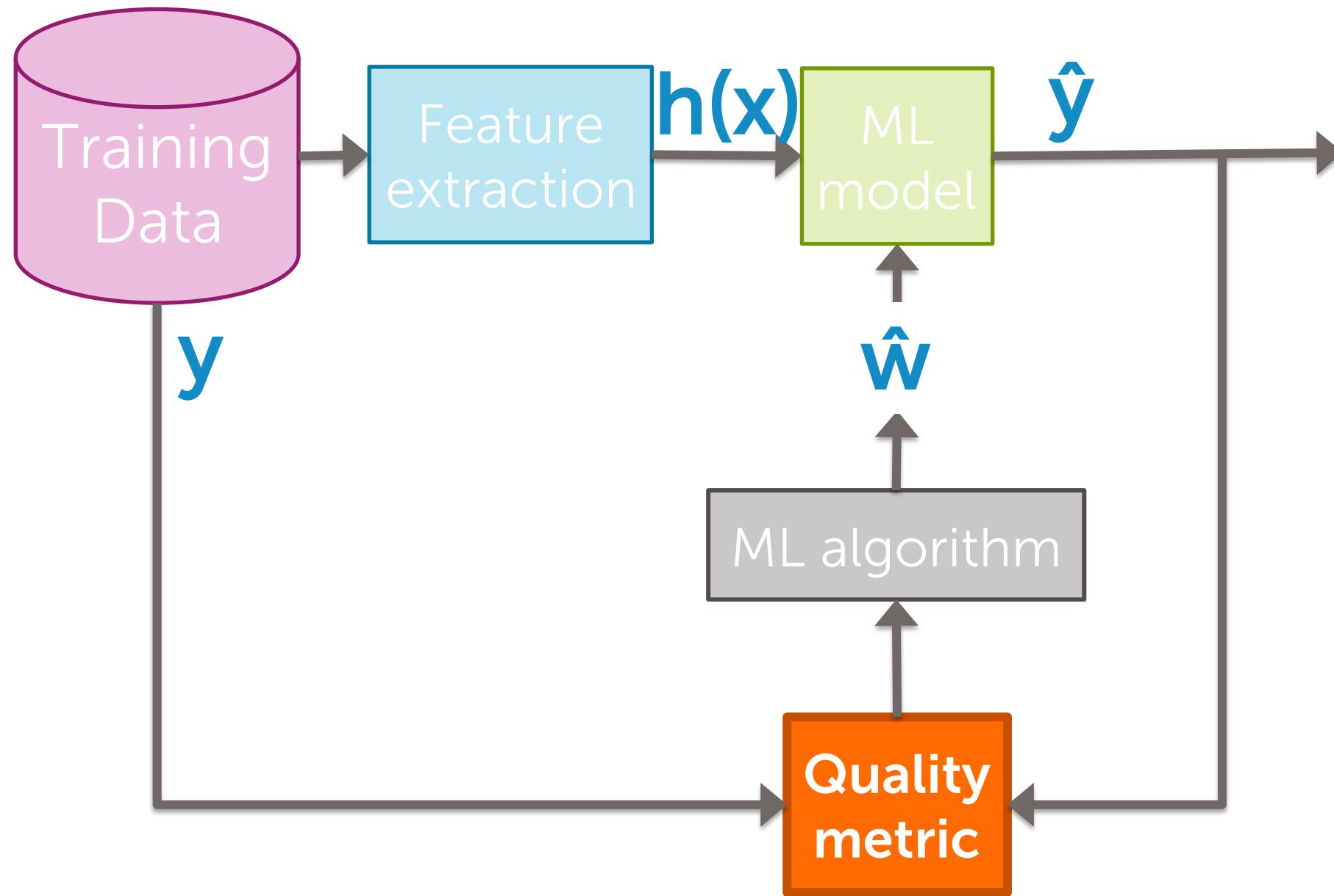
For all observations together

$$\begin{matrix} \mathbf{y} \\ \mathbf{y}_1 \\ \mathbf{y}_2 \\ \mathbf{y}_3 \\ \vdots \\ \vdots \\ \mathbf{y}_N \end{matrix} = \mathbf{H} \begin{matrix} \mathbf{w} \\ w_0 \\ w_1 \\ w_2 \\ \vdots \\ w_D \end{matrix} + \begin{matrix} \mathbf{\epsilon} \\ \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \\ \vdots \\ \vdots \\ \epsilon_N \end{matrix}$$

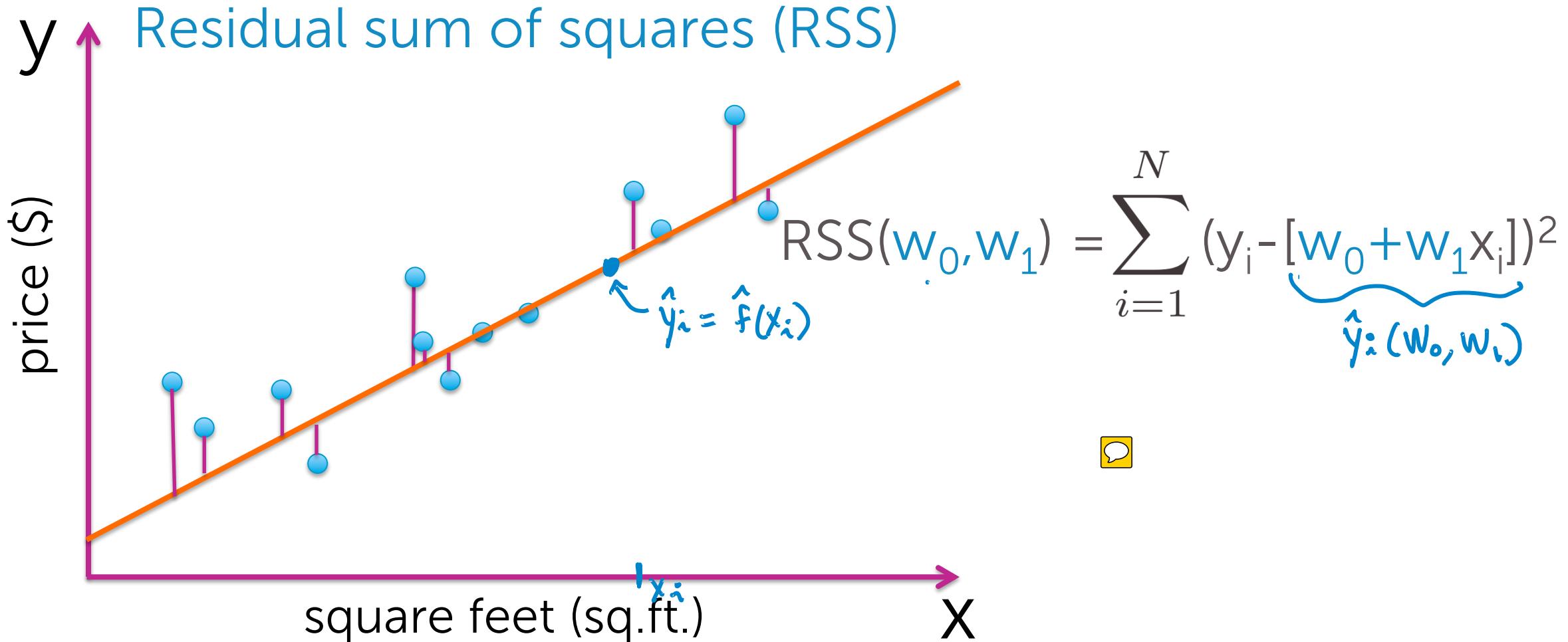
$\Rightarrow \boxed{\mathbf{y} = \mathbf{H}\mathbf{w} + \mathbf{\epsilon}}$

Annotations: A blue arrow labeled $h^T(x_i)$ points from the top row of the matrix \mathbf{H} to the column vector \mathbf{w} . A blue bracket under the matrix \mathbf{H} is labeled H .

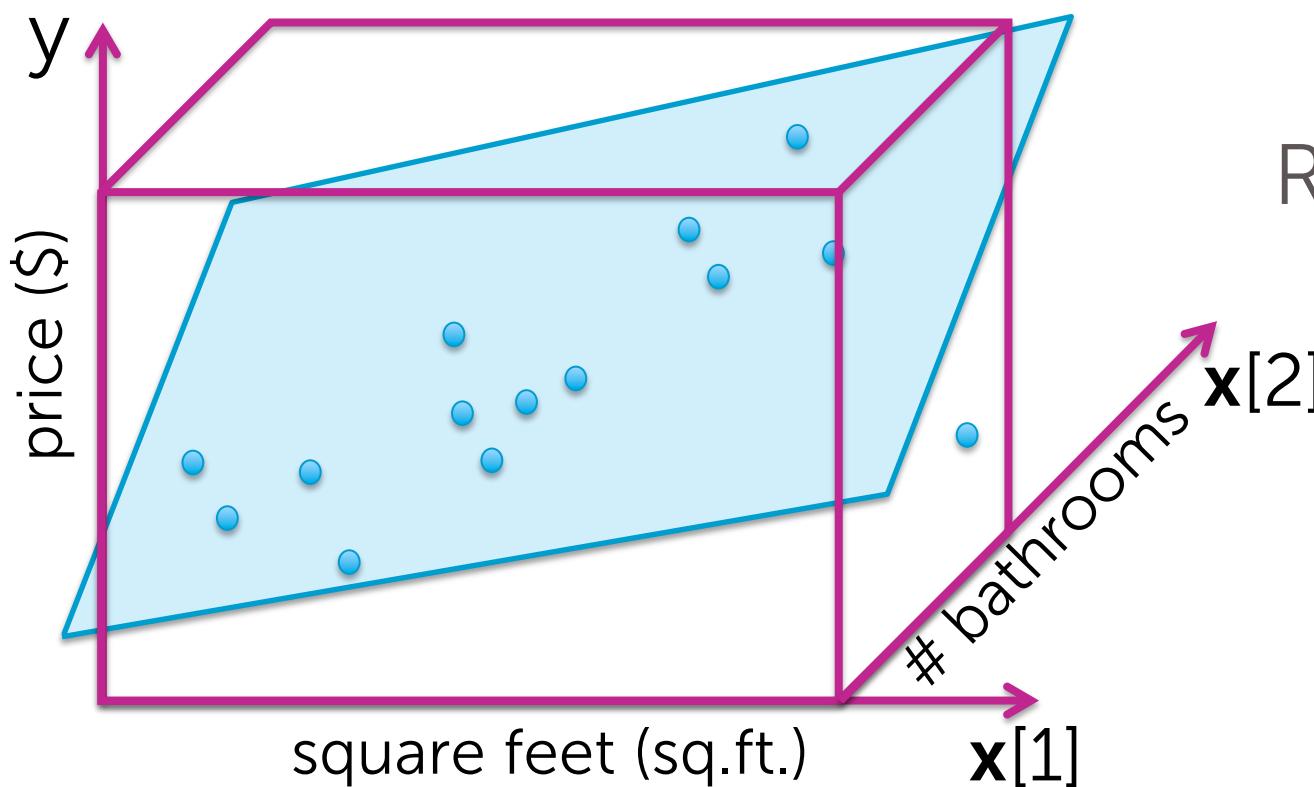
Step 2: Compute the cost



"Cost" of using a given line



RSS for multiple regression



言论

$$\text{RSS}(\underline{\mathbf{w}}) = \sum_{i=1}^N (y_i - \hat{y}_i(\underline{\mathbf{w}}))^2$$

言论

$$\hat{y}_i = \begin{bmatrix} h_0(x_i) & h_1(x_i) & \dots & h_D(x_i) \end{bmatrix} \underline{\mathbf{w}}$$

$\underline{\mathbf{w}}$

w_0
 w_1
 w_2
 \vdots
 w_D

RSS in matrix notation

$$\text{RSS}(\mathbf{w}) = \sum_{i=1}^N (y_i - h(\mathbf{x}_i)^T \mathbf{w})^2$$
$$= (\mathbf{y} - \mathbf{H}\mathbf{w})^T (\mathbf{y} - \mathbf{H}\mathbf{w})$$

Why? (part 1)

$$\begin{matrix} \hat{\mathbf{y}} \\ \vdots \\ \hat{y}_1 \\ \hat{y}_2 \\ \vdots \\ \hat{y}_N \end{matrix} = \mathbf{H} \begin{matrix} w_0 \\ w_1 \\ \vdots \\ w_D \end{matrix}$$

$$\hat{\mathbf{y}} = \mathbf{H}\mathbf{w}$$
$$(\mathbf{y} - \mathbf{H}\mathbf{w}) = (\mathbf{y} - \hat{\mathbf{y}}) = \begin{bmatrix} \text{residual}_1 \\ \text{residual}_2 \\ \vdots \\ \text{residual}_N \end{bmatrix} = \begin{bmatrix} y_1 - \hat{y}_1 \\ y_2 - \hat{y}_2 \\ \vdots \\ y_N - \hat{y}_N \end{bmatrix}$$

RSS in matrix notation

$$\text{RSS}(\mathbf{w}) = \sum_{i=1}^N (y_i - h(\mathbf{x}_i)^\top \mathbf{w})^2$$
$$= (\mathbf{y} - \mathbf{H}\mathbf{w})^\top (\mathbf{y} - \mathbf{H}\mathbf{w})$$

Why? (part 2)

residual ₁	residual ₂	residual ₃	...	residual _N
-----------------------	-----------------------	-----------------------	-----	-----------------------

residual ₁
residual ₂
residual ₃
...
residual _N

$$\begin{aligned} & (\text{residual}_1^2 + \text{residual}_2^2 + \dots + \text{residual}_N^2) \\ &= \sum_{i=1}^N \text{residual}_i^2 \\ &\triangleq \text{RSS}(\mathbf{w}) \end{aligned}$$

Step 3:

Take the gradient

Gradient of RSS

$$\nabla_{\mathbf{w}} \text{RSS}(\mathbf{w}) = \nabla [(\mathbf{y} - \mathbf{H}\mathbf{w})^\top (\mathbf{y} - \mathbf{H}\mathbf{w})]$$
$$= -2\mathbf{H}^\top (\mathbf{y} - \mathbf{H}\mathbf{w})$$



Why? By analogy to 1D case:

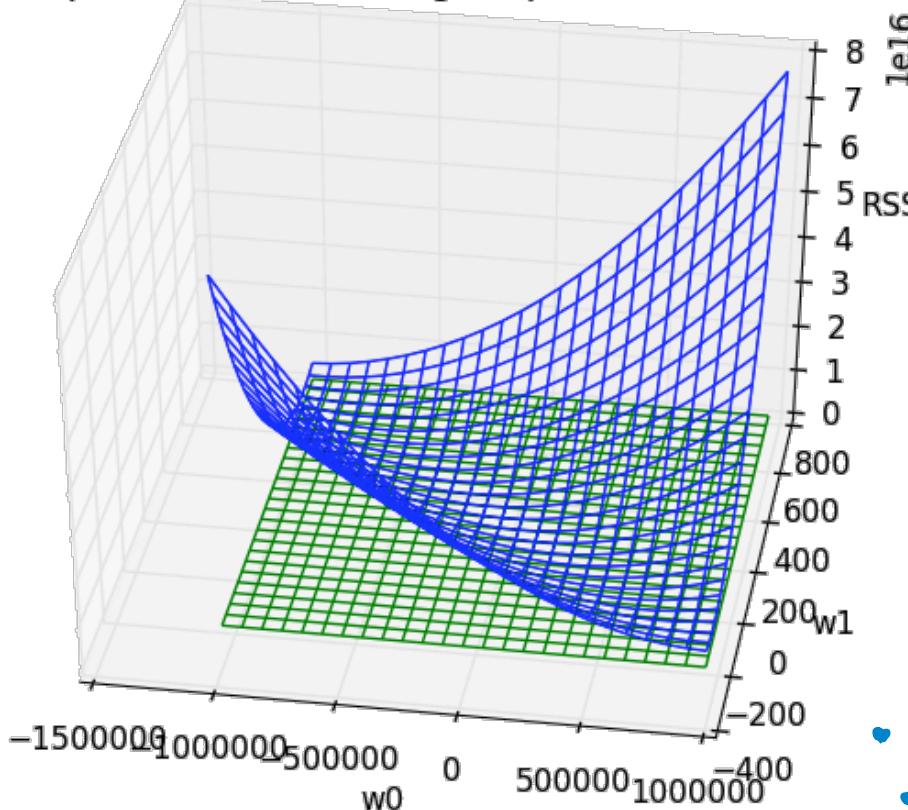
$$\frac{d}{dw} (y-hw)(y-hw) = \frac{d}{dw} (y-hw)^2 = 2 \cdot (y-hw)' (-h)$$
$$= -2h(y-hw)$$

scalars

Step 4, Approach 1: Set the gradient = 0

Closed-form solution

3D plot of RSS with tangent plane at minimum



$$\begin{matrix} \bullet & A^{-1}A = I \\ \bullet & IV = V \\ \bullet & IV = V \end{matrix}$$

$$\nabla \text{RSS}(\mathbf{w}) = -2\mathbf{H}^T(\mathbf{y} - \mathbf{H}\mathbf{w}) = 0$$

Solve for \mathbf{w} :

$$-2\cancel{\mathbf{H}^T} \mathbf{y} + \cancel{2\mathbf{H}^T} \mathbf{H} \hat{\mathbf{w}} = 0$$

$$\mathbf{H}^T \mathbf{H} \hat{\mathbf{w}} = \mathbf{H}^T \mathbf{y}$$

$$\underbrace{(\mathbf{H}^T \mathbf{H})^{-1}}_{I} \mathbf{H}^T \hat{\mathbf{w}} = (\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H}^T \mathbf{y}$$

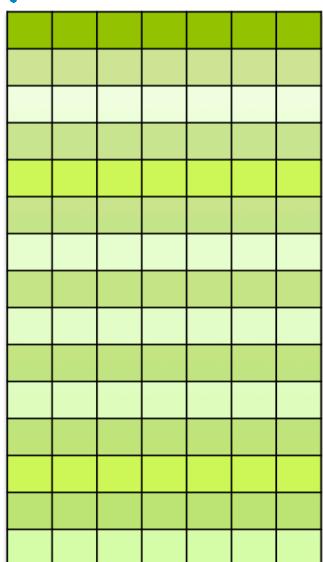
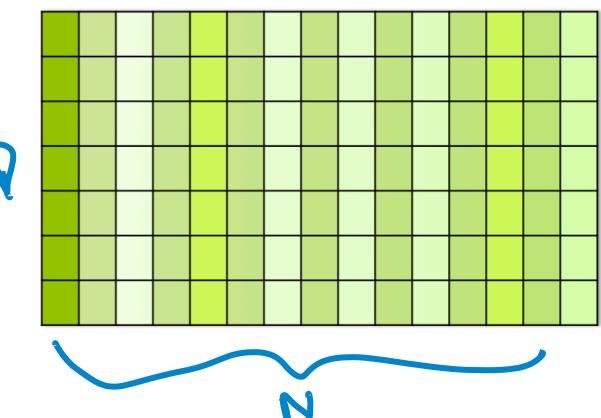
$$\hat{\mathbf{w}} = (\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H}^T \mathbf{y}$$

Closed-form solution

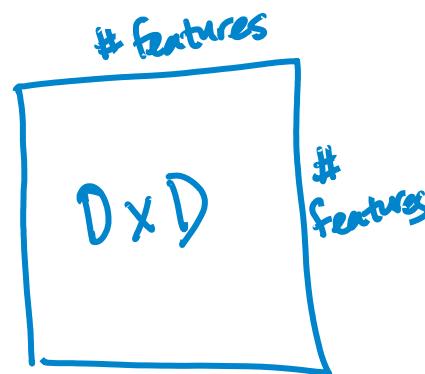
$$\hat{\mathbf{w}} = (\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H}^T \mathbf{y}$$



features = D



obs = N



Invertible if:

In most cases is

$N > D$

really,
of linearly
ind. observations



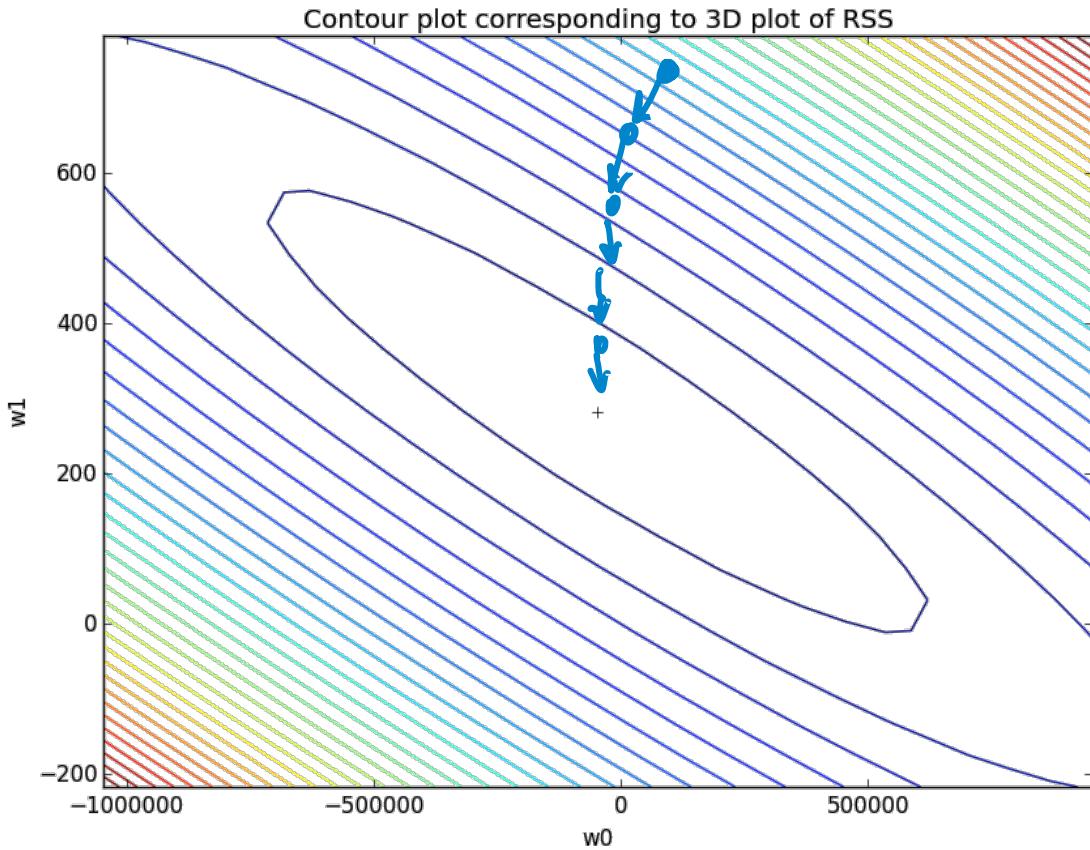
Complexity of inverse:

$O(D^3)$



Step 4, Approach 2: Gradient descent

Gradient descent



while not converged

$$\mathbf{w}^{(t+1)} \leftarrow \mathbf{w}^{(t)} - \eta \nabla \text{RSS}(\mathbf{w}^{(t)})$$
$$= \mathbf{w}^{(t)} + 2\eta \mathbf{H}^T (\mathbf{y} - \mathbf{H}\mathbf{w}^{(t)})$$
$$\hat{\mathbf{y}}(\mathbf{w}^{(t)})$$

Feature-by-feature update



$$\text{RSS}(\mathbf{w}) = \sum_{i=1}^N (y_i - h(\mathbf{x}_i)^T \mathbf{w})^2$$
$$= \sum_{i=1}^N (y_i - w_0 h_0(x_i) - w_1 h_1(x_i) - \dots - w_D h_D(x_i))^2$$

Partial with respect to w_j .

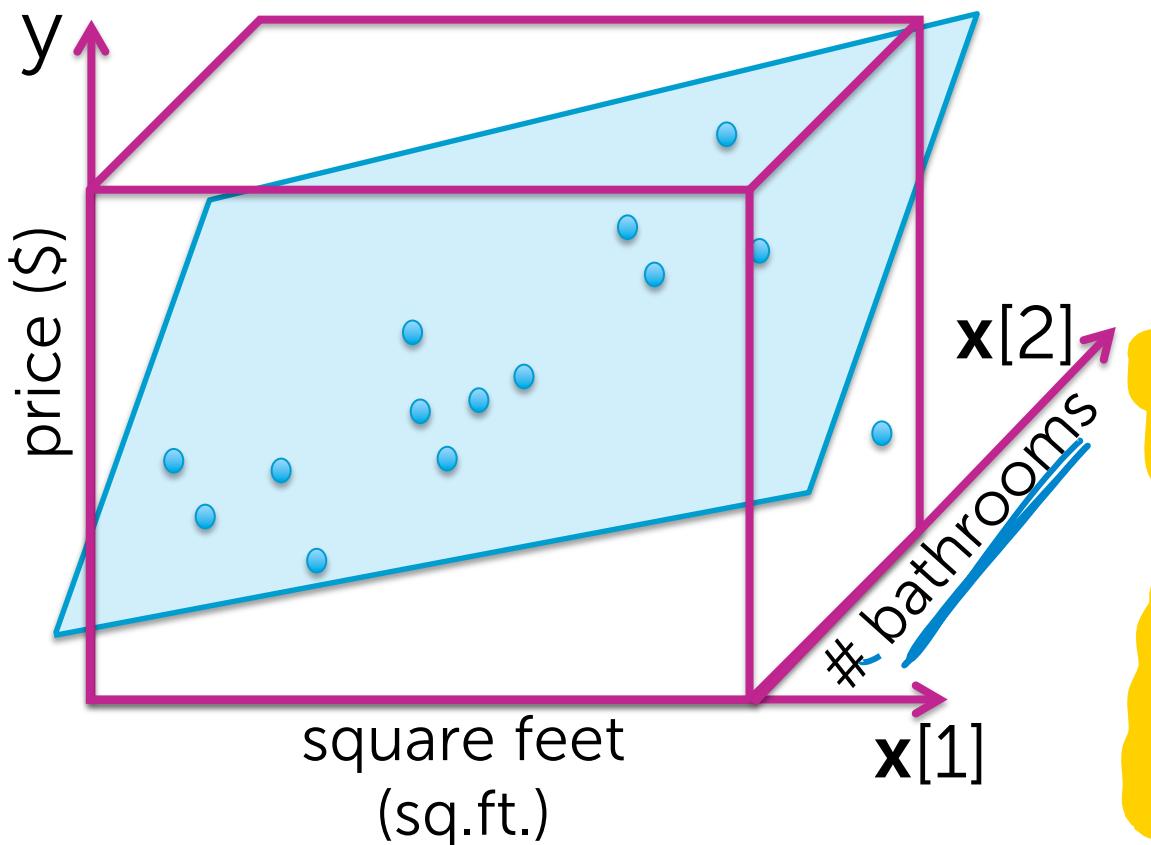
$$\begin{aligned} & \sum_{i=1}^N 2(y_i - w_0 h_0(x_i) - w_1 h_1(x_i) - \dots - w_D h_D(x_i)) \\ & \quad \cdot (-\underline{h_j(x_i)}) \\ &= -2 \sum_{i=1}^N h_j(x_i) (y_i - h(\mathbf{x}_i)^T \mathbf{w}) \end{aligned}$$

Update to j^{th} feature weight:

$$w_j^{(t+1)} \leftarrow w_j^{(t)} - \eta \left(-2 \sum_{i=1}^N h_j(x_i) (y_i - \underbrace{h^T(\mathbf{x}_i) \mathbf{w}^{(t)}}_{\hat{y}_i(\mathbf{w}^{(t)})}) \right)$$



Interpreting elementwise

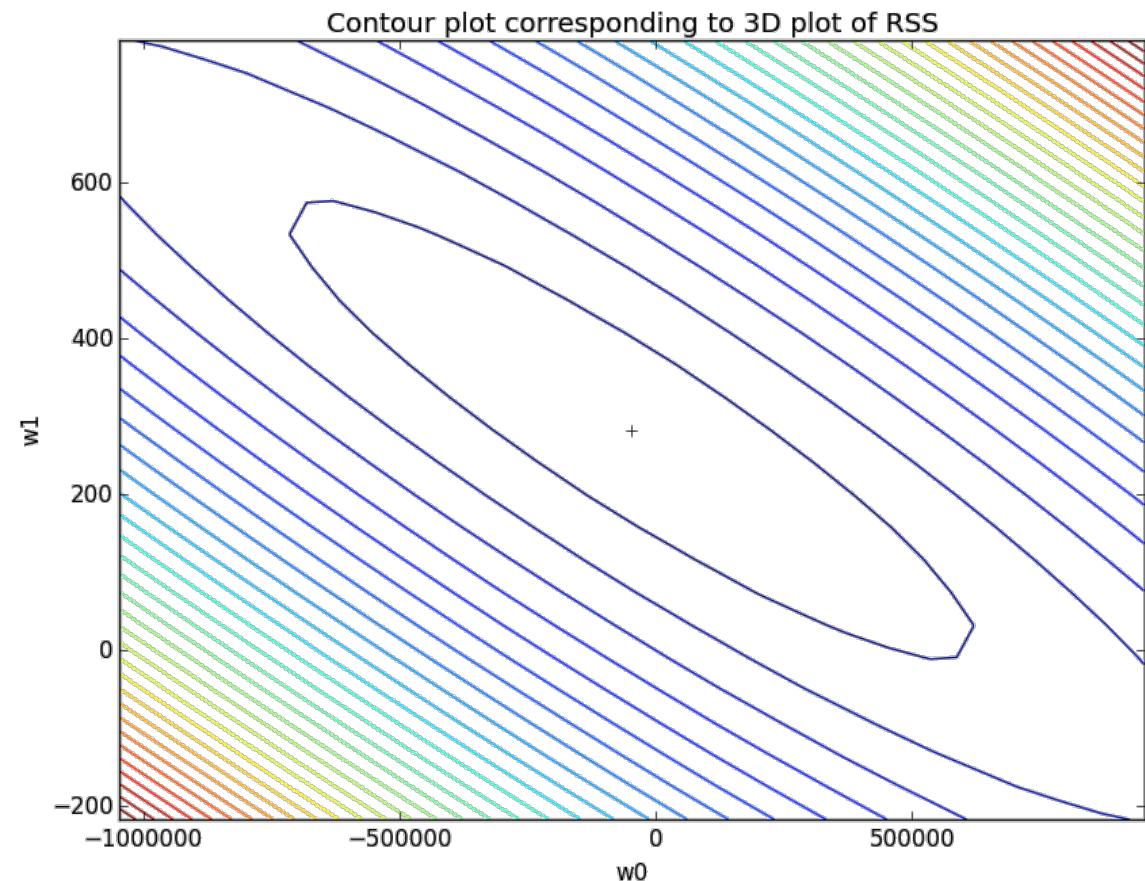


Update to j^{th} feature weight:

$$w_j^{(t+1)} \leftarrow w_j^{(t)} + 2n \sum_{i=1}^N h_j(x_i)(y_i - \hat{y}_i(w^{(t)}))$$

If underestimating impact of #bath ($\hat{w}_j^{(t)}$ is too small)
then $(y_i - \hat{y}_i(w^{(t)}))$ on average
weighted by #bath will be positive
 $\Rightarrow w_j^{(t+1)} > w_j^{(t)}$ (increase)

Summary of gradient descent for multiple regression



```
init  $\mathbf{w}^{(1)} = \mathbf{0}$  (or randomly, or smartly),  $t = 1$ 
while  $\|\nabla \text{RSS}(\mathbf{w}^{(t)})\| > \epsilon$  tolerance
    for  $j = 0, \dots, D$ 
        partial[j] =  $-2 \sum_{i=1}^N h_j(\mathbf{x}_i)(y_i - \hat{y}_i(\mathbf{w}^{(t)}))$ 
         $\mathbf{w}_j^{(t+1)} \leftarrow \mathbf{w}_j^{(t)} - \eta \text{partial}[j]$ 
    t  $\leftarrow t + 1$ 
```

An extremely useful algorithm



Summary for multiple linear regression

What you can do now...

- Describe polynomial regression
- Detrend a time series using trend and seasonal components
- Write a regression model using multiple inputs or features thereof
- Cast both polynomial regression and regression with multiple inputs as regression with multiple features
- Calculate a goodness-of-fit metric (e.g., RSS)
- Estimate model parameters of a general multiple regression model to minimize RSS:
 - In closed form
 - Using an iterative gradient descent algorithm
- Interpret the coefficients of a non-featurized multiple regression fit
- Exploit the estimated model to form predictions
- Explain applications of multiple regression beyond house price modeling