```
view_frames Result

Recorded at time: 1466811001.023
```

base_link

Broadcaster: /robot_state_publisher
Average rate: 50.197 Hz
Most recent transform: 1466811001.512 (-0.489 sec old)
Buffer length: 4.960 sec

ptu_base_link

Broadcaster: /robot_state_publisher
Average rate: 50.197 Hz
Most recent transform: 1466811001.512 (-0.489 sec old)
Buffer length: 4.960 sec

ptu_pan_link

Broadcaster: /robot_state_publisher
Average rate: 10.205 Hz
Most recent transform: 1466811000.934 (0.089 sec old)
Buffer length: 4.801 sec

ptu_tilt_link

Broadcaster: /robot_state_publisher
Average rate: 10.205 Hz
Most recent transform: 1466811000.934 (0.089 sec old)
Buffer length: 4.801 sec

ptu_tilted_link

Broadcaster: /robot_state_publisher
Average rate: 50.197 Hz
Most recent transform: 1466811001.512 (-0.489 sec old)
Buffer length: 4.960 sec

ptu_mount_link

Broadcaster: /hand_eye_connector
Average rate: 2.226 Hz
Most recent transform: 1466811000.876 (0.147 sec old)
Buffer length: 4.493 sec

kinect2_rgb_optical_frame

Broadcaster: /aruco_tracker
Average rate: 30.000 Hz
Most recent transform: 1466811001.008 (0.015 sec old)
Buffer length: 4.967 sec

aruco_marker_frame