



Web Based Terrain Modeller

MSc in Computational and Software Techniques in Engineering
Digital Signal and Image Processing

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www.cranfield.ac.uk



Outline

- 1 Problem**
- 2 Relevant Background**
- 3 Methodology**
- 4 Software**
- 5 Demonstration**
- 6 Benchmarks**
- 7 Conclusion & Further Work**



Problem

Functional Requirements

- Procedurally generate detailed terrains
- Use a CAD surface as a base

Technical Requirements

- Web-based
- Based on fractal geometry

Additional Requirements

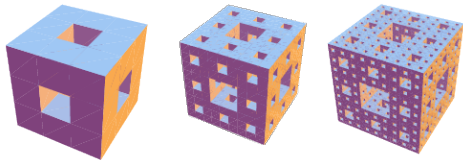
- Real-time editing

Relevant Background

Fractals



*in Weisstein, Eric W. "Koch Snowflake." From MathWorld – A Wolfram Web Resource.
<http://mathworld.wolfram.com/KochSnowflake.html>*



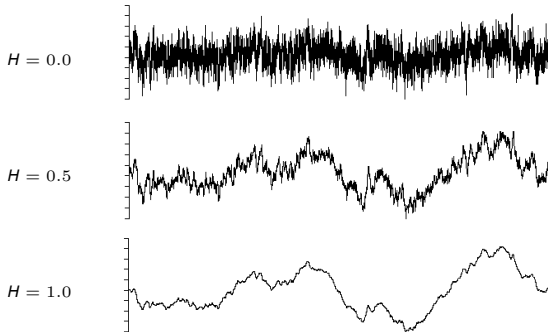
*in Weisstein, Eric W. "Menger Sponge." From MathWorld – A Wolfram Web Resource.
<http://mathworld.wolfram.com/MengerSponge.html>*

Relevant Background

Fractional Brownian Motion (fBm)

$$D_f = D_E + 1 - H$$

D_f Fractal dimension
 D_E Euclidean dimension
 H Hurst Exponent

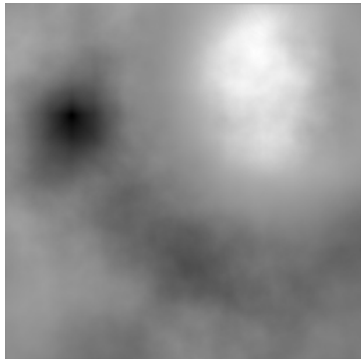


in <http://paulbourke.net/fractals/noise/>

Terrain Representation

Height Map

- Two dimensional array
- Each position saves an altitude value
- Can be saved as a grayscale image

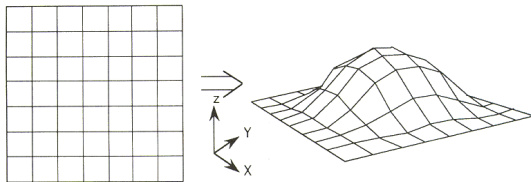


Example of height map

Terrain Representation

Regular Grid

- Wireframe processing
- Rendering



in <http://wtlab.iis.u-tokyo.ac.jp/wataru/lecture/rsgis/rsnote/cp6/cp6-10.htm>



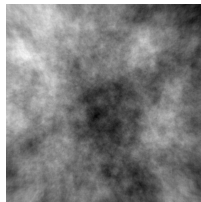
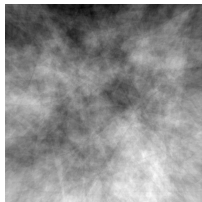
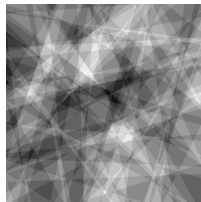
Relevant Background

Terrain Generation Methods

- Poisson Faulting
- Subdivision Methods
- Fourier Filtering
- Noise Synthesis

Terrain Generation Methods

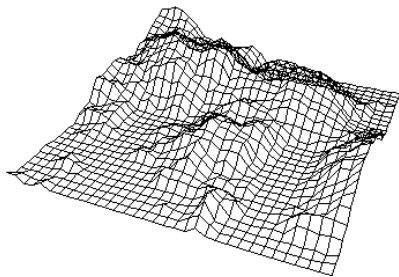
- **Poisson Faulting**
- Subdivision Methods
- Fourier Filtering
- Noise Synthesis



in <http://paulbourke.net/fractals/noise/>

Terrain Generation Methods

- Poisson Faulting
- **Subdivision Methods**
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Relevant Background

Terrain Generation Methods

- Poisson Faulting
- Subdivision Methods
- **Fourier Filtering**
- Noise Synthesis

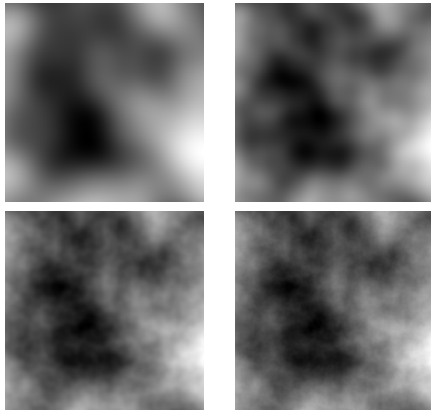
$$\beta = 1 + 2H \Leftrightarrow H = \frac{\beta - 1}{2}$$

$$D_f = D_E + 1 - H = D_E + \frac{3 - \beta}{2}$$

D_f Fractal dimension
 D_E Euclidean dimension
 H Hurst Exponent
 β Filter Power

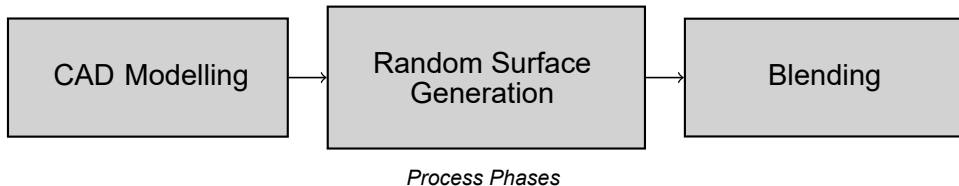
Terrain Generation Methods

- Poisson Faulting
- Subdivision Methods
- Fourier Filtering
- **Noise Synthesis**

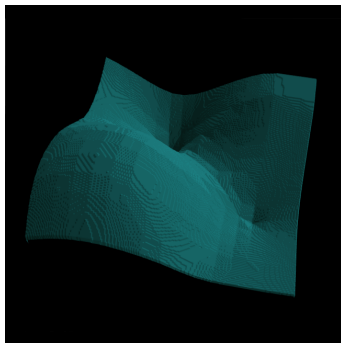
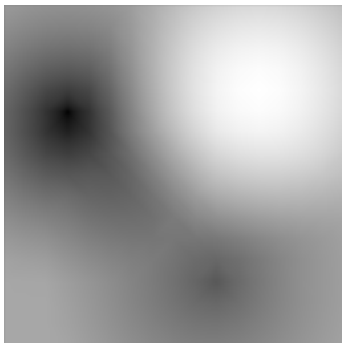


Perlin Noise Synthesis with 1, 2, 4 and 8 octaves

Overview

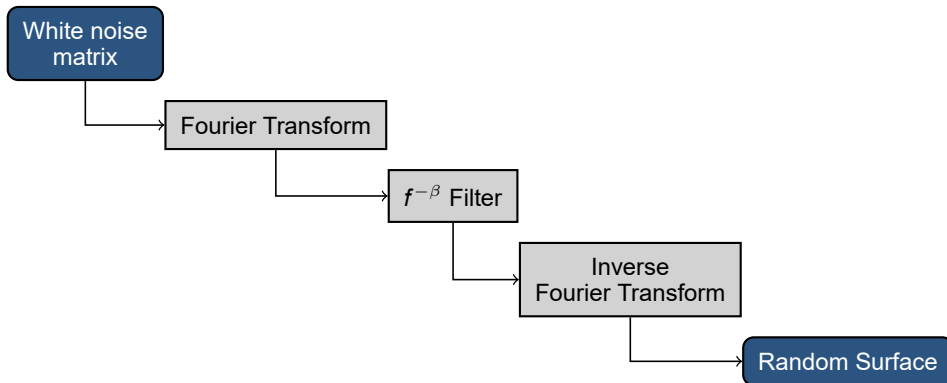


CAD Modelling



Example output from CAD Modelling Phase

Random Surface Generation - Fourier Filtering

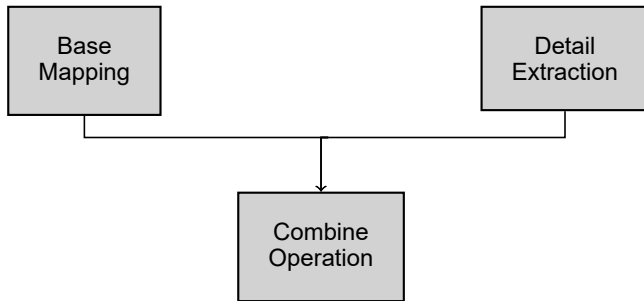


Random Surface Generation - Noise Synthesis

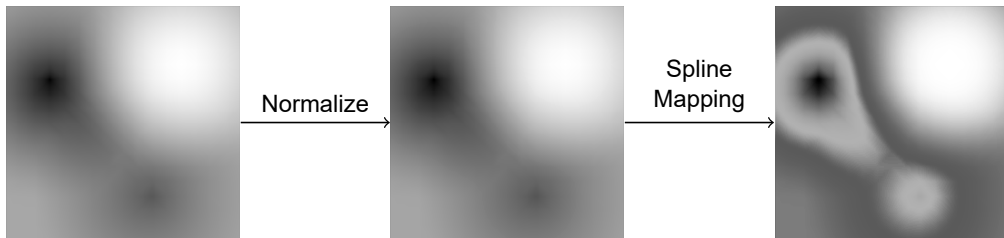
$$\frac{\sum_{i=0}^{O-1} \text{noise}(x \times L^i + B, y \times L^i + B) \times P^i}{\sum_{i=0}^{O-1} P^i}$$

O	octaves	Number of frequencies
L	lacunarity	Gap between successive frequencies
P	persistence	Contribution gap between successive octaves
B	base	Frequency displacement
	noise	Noise function (eg. Perlin or Simplex)

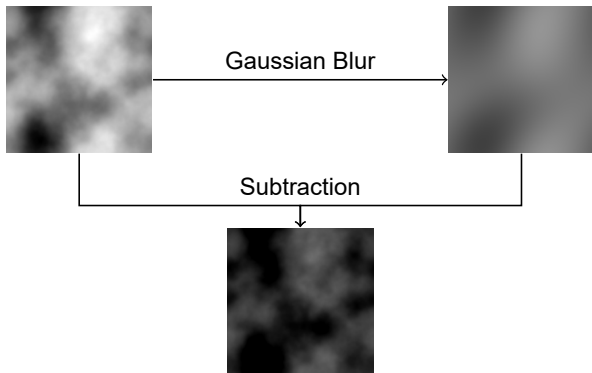
Blending Process



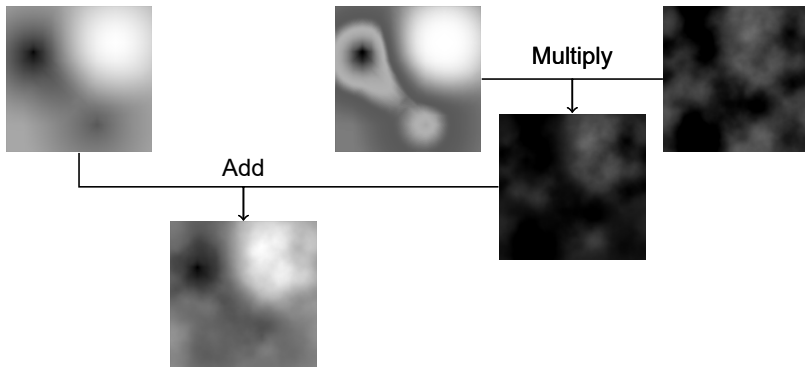
Blending Process - Base Mapping



Blending Process - Detail Extraction



Blending Process - Combine Operation





Software

Technologies



three.js





Software

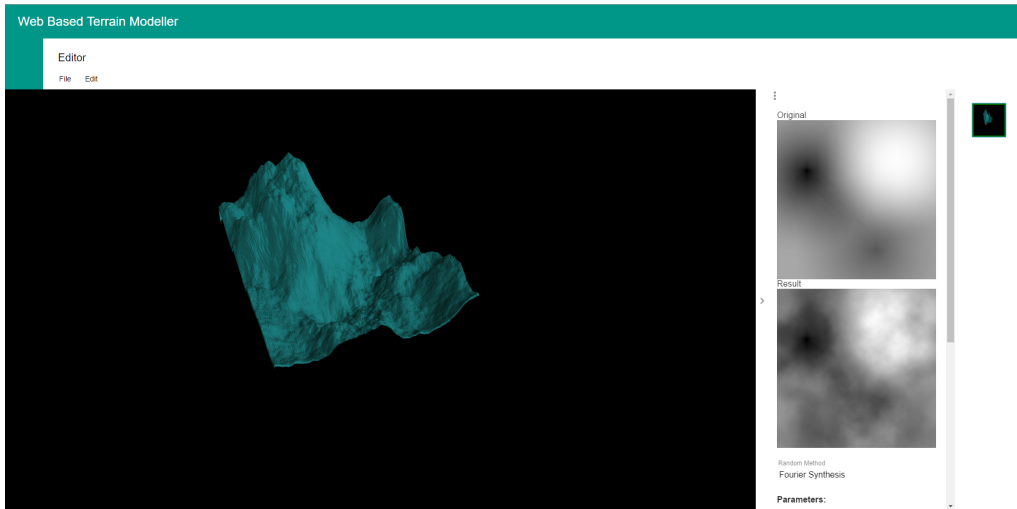
GPU Computations

Technical Details

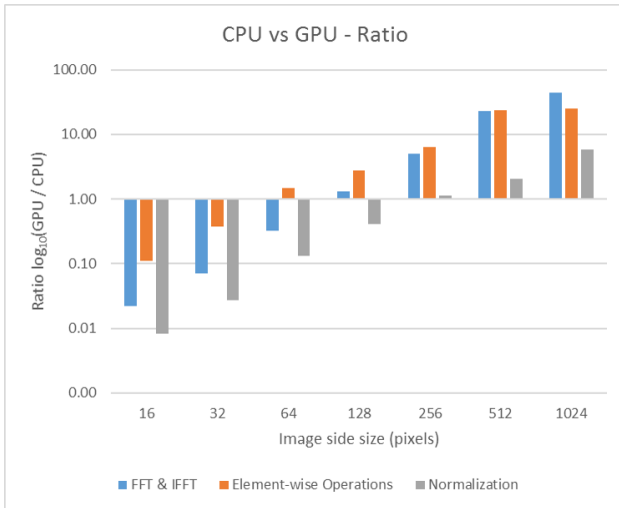
- WebGL 2
- Render to Texture
- Floating-point textures

Features

- FFT and IFFT
- Element-wise operations
- Matrix Normalization



Benchmarks





Conclusion & Further Work

What has been done

- Hybrid Process for terrain modelling
- Web-based implementation
- WebGL 2 used for computations

Future Work

- Different detail extraction methods
- Real world data