

Theoretical Guide

Miguel Nogueira

1 Math

MOD = 998 ' 244 ' 353

PI = acos(-1)

1.1 Logarithm

$$\log_b mn = \log_b m + \log_b n \quad \log_b \frac{m}{n} = \log_b m - \log_b n \quad \log_b n^p = p \log_b n$$

$$\log_b \sqrt[q]{n} = \frac{1}{q} \log_b n \quad \log_b n = \log_a n \log_b a \quad b^{\log_b k} = k$$

$$\log_b a = \frac{\log_c a}{\log_c b} \quad \log_b a = \frac{1}{\log_a b} \quad \log_b a \log_a c = \log_b c$$

$$\log_b 1 = 0 \quad \log_b b = 1$$

2 Identities

$$\sum_{i=1}^n i = \frac{n(n+1)}{2} \quad \sum_{i=1}^n i^2 = \frac{n(n+1)(2n+1)}{6} \quad \sum_{i=1}^n i^3 = \left(\frac{n(n+1)}{2} \right)^2$$

$$\sum_{i=1}^n \frac{1}{i} \approx \log n \quad \sum_{i=0}^{\infty} \frac{1}{2^i} = 2$$

3 Number Theory

$$(a+b) \bmod m = (a \bmod m + b \bmod m) \bmod m$$

$$(a-b) \bmod m = (a \bmod m - b \bmod m) \bmod m$$

$$(a \times b) \bmod m = ((a \bmod m) \times (b \bmod m)) \bmod m$$

$$a^b \bmod m = (a \bmod m)^b \bmod m$$

$$a \equiv b \pmod{m} \iff (b-a) | m$$

$$\gcd(a_1, a_2, a_3, a_4) = \gcd(a_1, \gcd(a_2, \gcd(a_3, a_4)))$$

$$\text{lcm}(a, b) \times \gcd(a, b) = a \times b$$

$$\text{lcm}(a, b) = \frac{a \times b}{\gcd(a, b)} = \frac{a}{\gcd(a, b)} \times b$$

3.1 Some Primes

$$\begin{array}{ccccccccc} 999999937 & 1000000007 & 1000000009 & 1000000021 & 1000000033 & & & & \\ 10^{18} - 11 & 10^{18} + 3 & 2305843009213693951 & = 2^{61} - 1 & & & & & \\ 998244353 = 119 \times 2^{23} + 1 & 10^6 + 3 & & & & & & & \\ 105524448595307659 & 139218122939170727 & 117897066297233441 & & & & & & \\ 257900257981 & 584598951247 & 989509930063 & 105539556781 & & & & & \\ 998244353 & 754974721 & 167772161 & 188244827 & 205587737 & & & & \\ 555130769 & 809747989 & 572255561 & 396588799 & 327208423 & & & & \\ 773840099 & 207936359 & 952818871 & 935456867 & 670948771 & & & & \end{array}$$

3.2 Number of Divisors

The number of divisors of n is about $\sqrt[3]{n}$.

n	6	60	360	5040	55440	720720	4324320	21621600
$d(n)$	4	12	24	60	120	240	384	576

Given the prime factorization of some number n :

$$n = p_1^{a_1} \cdot p_2^{a_2} \cdot p_3^{a_3}$$

The number of divisors will be $(a_1 + 1)(a_2 + 1)(a_3 + 1)$.

3.3 Large Prime Gaps

For numbers until 10^9 the largest gap is 400.
For numbers until 10^{18} the largest gap is 1500.

3.4 Fermat's Theorems

Let P be a prime number and a an integer, then:

$$a^p \equiv a \pmod{p}$$

$$a^{p-1} \equiv 1 \pmod{p}$$

Lemma: Let p be a prime number and a and b integers, then:

$$(a + b)^p \equiv a^p + b^p \pmod{p}$$

Lemma: Let p be a prime number and a an integer. The inverse of a modulo p is a^{p-2} :

$$a^{-1} \equiv a^{p-2} \pmod{p}$$

3.5 Chicken McNugget Theorem

The Chicken McNugget Theorem states that for any two relatively prime positive integers m, n , the greatest integer that cannot be written in the form $am + bn$ for nonnegative integers a, b is $mn - m - n$.

A consequence of the theorem is that there are exactly $\frac{(m-1)(n-1)}{2}$ positive integers which cannot be expressed in the form $am + bn$. The proof is based on the fact that in each pair of the form $(k, mn - m - n - k)$, exactly one element is expressible.

4 Graph

4.1 Graph

A Graph without an odd cycle is called an bipartite graph.

5 geometry

Geometry Identities and Transformations (Competitive Programming)

Basic Identities and Vector Operations

2D Geometry

- **Point Representation:** $P = (x, y)$
- **Vector from P_1 to P_2 :** $\vec{P_1P_2} = (x_2 - x_1, y_2 - y_1)$
- **Distance between two points $P_1(x_1, y_1)$ and $P_2(x_2, y_2)$:** $d = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$
- **Midpoint of a segment** connecting $P_1(x_1, y_1)$ and $P_2(x_2, y_2)$: $M = \left(\frac{x_1 + x_2}{2}, \frac{y_1 + y_2}{2}\right)$
- **Area of a triangle** with vertices $(x_1, y_1), (x_2, y_2), (x_3, y_3)$: $A = \frac{1}{2}|x_1(y_2 - y_3) + x_2(y_3 - y_1) + x_3(y_1 - y_2)|$
- **Signed Area of Triangle:** $\frac{1}{2}((x_2 - x_1)(y_3 - y_1) - (x_3 - x_1)(y_2 - y_1))$ (positive for CCW, negative for CW)
- **Cross Product (2D)** for vectors $\vec{A} = (x_1, y_1)$ and $\vec{B} = (x_2, y_2)$: $\vec{A} \times \vec{B} = x_1y_2 - x_2y_1$ (scalar value, positive if \vec{B} is CCW from \vec{A})
- **Dot Product (2D)** for vectors $\vec{A} = (x_1, y_1)$ and $\vec{B} = (x_2, y_2)$: $\vec{A} \cdot \vec{B} = x_1x_2 + y_1y_2 = |\vec{A}||\vec{B}|\cos\theta$

3D Geometry

- **Point Representation:** $P = (x, y, z)$
- **Vector from P_1 to P_2 :** $\vec{P_1P_2} = (x_2 - x_1, y_2 - y_1, z_2 - z_1)$
- **Distance between two points $P_1(x_1, y_1, z_1)$ and $P_2(x_2, y_2, z_2)$:** $d = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$
- **Dot Product (3D)** for vectors $\vec{A} = (x_1, y_1, z_1)$ and $\vec{B} = (x_2, y_2, z_2)$: $\vec{A} \cdot \vec{B} = x_1x_2 + y_1y_2 + z_1z_2 = |\vec{A}||\vec{B}|\cos\theta$
- **Cross Product (3D)** for vectors $\vec{A} = (x_1, y_1, z_1)$ and $\vec{B} = (x_2, y_2, z_2)$: $\vec{A} \times \vec{B} = (y_1z_2 - y_2z_1, x_2z_1 - x_1z_2, x_1y_2 - x_2y_1)$

- **Volume of Tetrahedron** with vertices P_0, P_1, P_2, P_3 : $\frac{1}{6}|\det(\vec{P_0P_1}, \vec{P_0P_2}, \vec{P_0P_3})|$ (scalar triple product)

Lines and Segments (2D)

- **Line Equation:** $Ax + By + C = 0$ (normal vector (A, B))
- **Slope:** $m = (y_2 - y_1)/(x_2 - x_1)$
- **Perpendicular Slope:** $-1/m$
- **Point-Slope Form:** $y - y_1 = m(x - x_1)$
- **Intersection of two lines** ($A_1x + B_1y + C_1 = 0$, $A_2x + B_2y + C_2 = 0$): $x = \frac{B_1C_2 - B_2C_1}{A_1B_2 - A_2B_1}$, $y = \frac{A_2C_1 - A_1C_2}{A_1B_2 - A_2B_1}$ (check for $A_1B_2 - A_2B_1 = 0$ for parallel/coincident lines)
- **Distance from a point** $P_0(x_0, y_0)$ **to line** $Ax + By + C = 0$: $d = \frac{|Ax_0 + By_0 + C|}{\sqrt{A^2 + B^2}}$
- **Orientation of three points** P_1, P_2, P_3 : Use cross product $\vec{P_1P_2} \times \vec{P_1P_3}$.
 - > 0 : Counter-clockwise (left turn)
 - < 0 : Clockwise (right turn)
 - $= 0$: Collinear
- **Segment Intersection:** Check orientation of (P_1, P_2, P_3) , (P_1, P_2, P_4) , (P_3, P_4, P_1) , (P_3, P_4, P_2) . Special handling for collinear segments.

Circles (2D)

- **Equation:** $(x - h)^2 + (y - k)^2 = r^2$, center (h, k) , radius r .
- **Area:** $A = \pi r^2$
- **Circumference:** $C = 2\pi r$
- **Distance between two circle centers:** $d = \sqrt{(h_2 - h_1)^2 + (k_2 - k_1)^2}$
- **Intersection of two circles:**
 - $d > r_1 + r_2$: No intersection (disjoint)
 - $d = r_1 + r_2$: One intersection point (external tangent)
 - $|r_1 - r_2| < d < r_1 + r_2$: Two intersection points

- $d = |r_1 - r_2|$: One intersection point (internal tangent)
- $d < |r_1 - r_2|$: No intersection (one inside other)
- $d = 0$ and $r_1 = r_2$: Coincident circles (infinite points)

Polygon Properties (2D)

- **Area of a simple polygon** with vertices $(x_0, y_0), \dots, (x_{n-1}, y_{n-1})$ (Shoelace Formula): $A = \frac{1}{2} \left| \sum_{i=0}^{n-1} (x_i y_{i+1} - x_{i+1} y_i) \right|$, where $(x_n, y_n) = (x_0, y_0)$. (Sum of cross products: $\sum_{i=0}^{n-1} \vec{OP_i} \times \vec{OP_{i+1}}$ where O is origin)
- **Convex Polygon:** All internal angles are less than or equal to 180° .
- **Concave Polygon:** Has at least one internal angle greater than 180° .
- **Point in Polygon Test (Ray Casting):** Draw a ray from the point in any direction (e.g., positive x-axis) and count intersections with polygon edges. If odd, point is inside; if even, outside. Handle horizontal edges and vertices carefully.
- **Point in Convex Polygon Test:** Check if the point is consistently on one side (e.g., left) of all directed edges of the polygon.

Convex Hull (2D)

- The smallest convex polygon enclosing a given set of points.
- Algorithms: Graham Scan ($O(N \log N)$), Monotone Chain ($O(N \log N)$).
- **Graham Scan steps:**
 1. Find lowest-most (and leftmost if ties) point P_0 .
 2. Sort all other points by angle with P_0 (or cross product $\vec{P_0P_i} \times \vec{P_0P_j}$).
 3. Iterate through sorted points, maintaining a stack. If new point creates a right turn with top two stack points, pop from stack until left turn.

Sweep Line Algorithms

- Used for problems involving geometric objects (segments, rectangles) where a vertical (or horizontal) line sweeps across the plane.
- Often involves a 'std::set' or segment tree to maintain active objects on the sweep line.

Floating Point Precision Issues

- Use a small epsilon ($\varepsilon \approx 10^{-9}$ to 10^{-12}) for comparisons instead of direct equality:
 - $a == b \Rightarrow |a - b| < \varepsilon$
 - $a < b \Rightarrow a < b - \varepsilon$
 - $a > b \Rightarrow a > b + \varepsilon$
- Prefer integer arithmetic where possible (e.g., use cross products for collinearity/orientation instead of slopes).

Geometric Transformations (2D Homogeneous Coordinates)

A point (x, y) is represented as a column vector $\begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$.

Translation by (t_x, t_y)

$$T = \begin{pmatrix} 1 & 0 & t_x \\ 0 & 1 & t_y \\ 0 & 0 & 1 \end{pmatrix}$$

Scaling by (s_x, s_y) relative to origin

$$S = \begin{pmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Rotation by angle θ relative to origin (counter-clockwise)

$$R = \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Shear

- X-Shear (parallel to x-axis, factor k_x): $Sh_x = \begin{pmatrix} 1 & k_x & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

- Y-Shear (parallel to y-axis, factor k_y): $Sh_y = \begin{pmatrix} 1 & 0 & 0 \\ k_y & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

Reflection

- Across X-axis: $Ref_x = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

- Across Y-axis: $Ref_y = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

- Across origin: $Ref_O = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

- Across line $y = x$: $Ref_{y=x} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

Geometric Transformations (3D Homogeneous Coordinates)

A point (x, y, z) is represented as a column vector $\begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix}$.

Translation by (t_x, t_y, t_z)

$$T = \begin{pmatrix} 1 & 0 & 0 & t_x \\ 0 & 1 & 0 & t_y \\ 0 & 0 & 1 & t_z \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Scaling by (s_x, s_y, s_z) relative to origin

$$S = \begin{pmatrix} s_x & 0 & 0 & 0 \\ 0 & s_y & 0 & 0 \\ 0 & 0 & s_z & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Rotation by angle θ (counter-clockwise)

- About X-axis: $R_x(\theta) = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \theta & -\sin \theta & 0 \\ 0 & \sin \theta & \cos \theta & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$
- About Y-axis: $R_y(\theta) = \begin{pmatrix} \cos \theta & 0 & \sin \theta & 0 \\ 0 & 1 & 0 & 0 \\ -\sin \theta & 0 & \cos \theta & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$
- About Z-axis: $R_z(\theta) = \begin{pmatrix} \cos \theta & -\sin \theta & 0 & 0 \\ \sin \theta & \cos \theta & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$

6 Counting Problems**Math, Counting, and Number Theory (Competitive Programming)****Combinatorics and Counting**

- **Factorial:** $n! = n \times (n-1) \times \cdots \times 1$; $0! = 1$.
- **Permutations (arrangements without repetition):** $P(n, k) = \frac{n!}{(n-k)!}$
- **Combinations (selections without repetition):** $C(n, k) = \binom{n}{k} = \frac{n!}{k!(n-k)!}$
- **Binomial Theorem:** $(x+y)^n = \sum_{k=0}^n \binom{n}{k} x^{n-k} y^k$
- **Pascal's Identity:** $\binom{n}{k} = \binom{n-1}{k-1} + \binom{n-1}{k}$
- **Stars and Bars:** Number of ways to distribute n identical items into k distinct bins (or non-negative integer solutions to $x_1 + \cdots + x_k = n$):

$$\binom{n+k-1}{k-1} \quad \text{or} \quad \binom{n+k-1}{n}$$

Use Case: Find the number of ways to put 10 identical candies into 3 distinct bags. $\left(\binom{10+3-1}{3-1} = \binom{12}{2}\right)$

• **Vandermonde's Identity:**

$$\sum_{k=0}^r \binom{m}{k} \binom{n}{r-k} = \binom{m+n}{r}$$

Use Case: Choosing r people from a group of m men and n women. The LHS sums ways to choose k men and $r-k$ women.

• **Catalan Numbers (C_n):** Explicit formula:

$$C_n = \frac{1}{n+1} \binom{2n}{n}$$

Recursive formula:

$$C_0 = 1, \quad C_{n+1} = \sum_{i=0}^n C_i C_{n-i} \quad \text{for } n \geq 0$$

Applications:

- Number of Dyck paths of length $2n$ (paths from $(0,0)$ to (n,n) using only right/up steps that don't go above $y=x$).
- Number of ways to correctly parenthesize n pairs of parentheses.
- Number of full binary trees with $n+1$ leaves.

Use Case: How many ways to form a balanced sequence of 3 pairs of parentheses? ($C_3 = 5$)

• **Inclusion-Exclusion Principle:** For two sets:

$$|A \cup B| = |A| + |B| - |A \cap B|$$

For n sets: $|\bigcup_{i=1}^n A_i| = \sum |A_i| - \sum_{i < j} |A_i \cap A_j| + \sum_{i < j < k} |A_i \cap A_j \cap A_k| - \cdots + (-1)^{n-1} |A_1 \cap \cdots \cap A_n|$ *Use Case:* Count numbers up to 100 divisible by 2 or 3. ($|A_2 \cup A_3| = |A_2| + |A_3| - |A_2 \cap A_3|$).

- **Pigeonhole Principle:** If N items are put into K bins, then at least one bin must contain $\lceil N/K \rceil$ items. *Use Case:* In any group of 13 people, at least two must share the same birth month.
- **Permutations with Repetitions:** Number of distinct permutations of n objects where there are k_1 identical objects of type 1, k_2 identical objects of type 2, ..., k_r identical objects of type r (and $k_1 + \cdots + k_r = n$):

$$\frac{n!}{k_1! k_2! \cdots k_r!}$$

Use Case: How many distinct permutations of the letters in "MISSISSIPPI"? ($\frac{11!}{1!4!4!2!}$)

- **r-Permutations:** Number of ways to arrange r items chosen from n distinct items ($P(n, r)$):

$$P(n, r) = \frac{n!}{(n-r)!}$$

Use Case: Number of ways to award gold, silver, and bronze medals to 10 runners. ($P(10, 3) = \frac{10!}{7!}$)