```
In [36]:
```

```
omega, t, omega0, x0, v0=var('omega, t, omega0, x0, v0')
x=function('x')(t)
print("A:")
eq1=diff(x,t,2)+x*omega0^2==0
show(eq1)
show(desolve(eq1, [x, t]))
print("B:")
assume(omega0 > 0)
sol(t, omega0, x0, v0) = desolve(eq1, [x, t], [0, x0, v0])
show(sol)
print("C:")
omega0=sqrt(981/39.24)
show(omega0)
x0 = 0.15
sol(t) = sol(t, omega0, x0, 0)
show(sol)
plot(sol(t),t,0,10)
```

A:

$$\omega_{0}^{2}x\left(t
ight) +rac{\partial^{2}}{\left(\partial t
ight) ^{2}}x\left(t
ight) =0$$

$$K_2\cos(\omega_0 t) + K_1\sin(\omega_0 t)$$

B:

 $(t,\omega_0,x_0,v_0) \\ \mapsto$

1

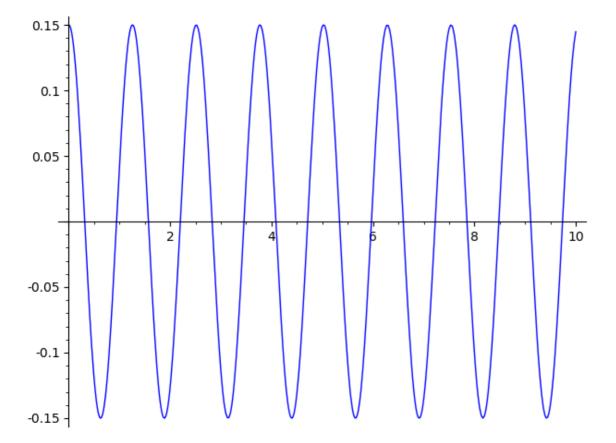
F

C:

5.000000000000000

 $t \mapsto racksquare$

Out[36]:



```
In [6]:
```

```
x0, v0, 1, omega0, t=var('x0, v0, 1, omega0, t')
x = function('x')(t)
print("A:")
eq1=diff(x,t,2)+1*diff(x,t)+x*omega0^2==0
show (eq1)
assume (1^2 > 4*omega0^2)
sol(t, 1, omega0, x0, v0) = desolve(eq1, [x, t])
show(sol)
print("B:")
sol(t, 1, omega0, x0, v0) = desolve(eq1, [x, t], [0, x0, v0])
show(sol)
sol(t) = sol(t, 25, 10, 1, 5)
show(sol)
show(plot(sol(t),t,0,10))
print("C:")
forget()
eq2=diff(x,t,2)+diff(x,t)*2*omega0+x*omega0^2==0
show(eq2)
assume(omega0 > 0)
sol(t, omega0) = desolve(eq2, [x, t])
show(sol)
print("D:")
sol(t, omega0, x0, v0) = desolve(eq2, [x, t], [0, x0, v0])
show(sol)
sol(t) = sol(t, 20, 10, 1, 5)
show(sol)
show(plot(sol(t), t, 0, 10))
print("E:")
assume (1^2 < 4*omega0^2)
sol(t, l, omega0) = desolve(eq1, [x, t])
show(sol)
print("F:")
sol(t, 1, omega0, x0, v0) = desolve(eq1, [x, t], [0, x0, v0])
show(sol)
sol(t) = sol(t, 5, 10, 1, 5)
show(sol)
show(plot(sol(t),t,0,10))
A:
```

$$\omega_{0}^{2}x\left(t
ight) +lrac{\partial }{\partial t}x\left(t
ight) +rac{\partial ^{2}}{\left(\partial t
ight) ^{2}}x\left(t
ight) =0$$

 (t,l,ω_0,x_0,v_0) \mapsto B:

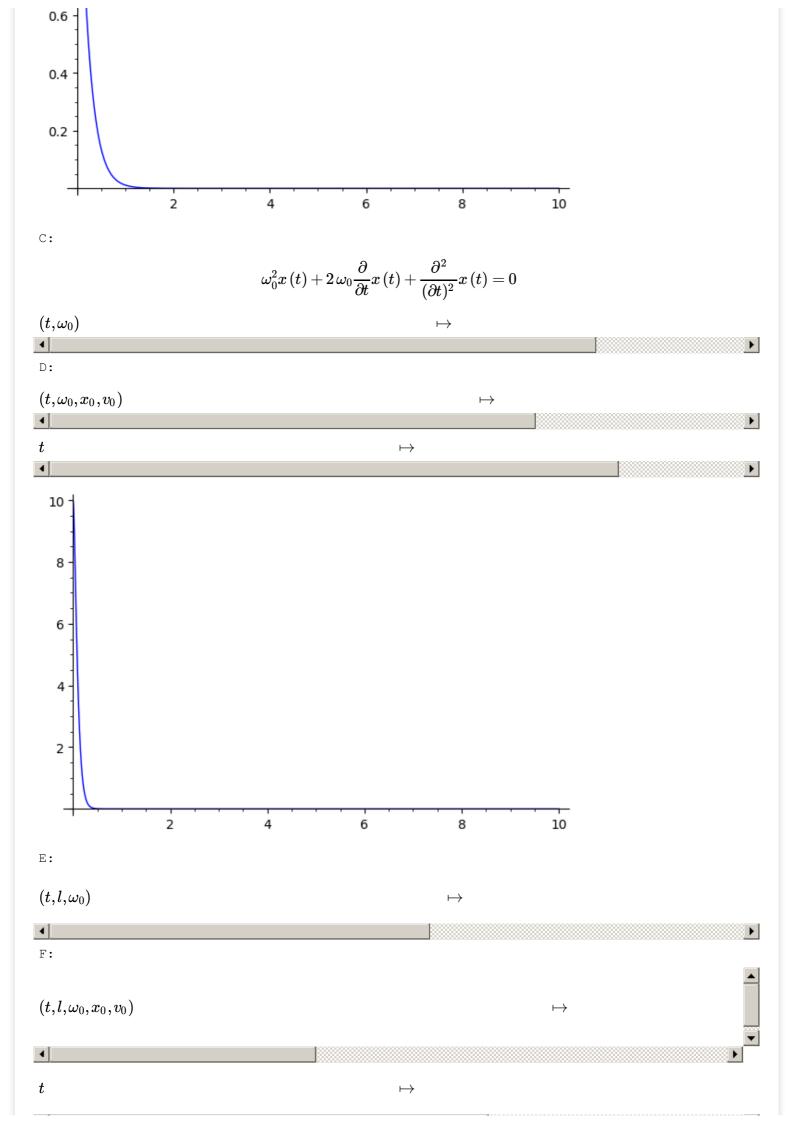
4

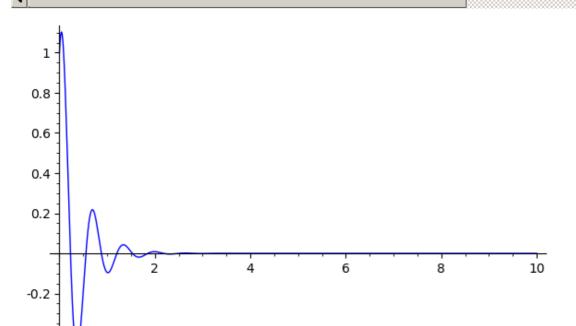
 \mapsto

 $t \mapsto$

0.8

 (t,l,ω_0,x_0,v_0)





In [72]:

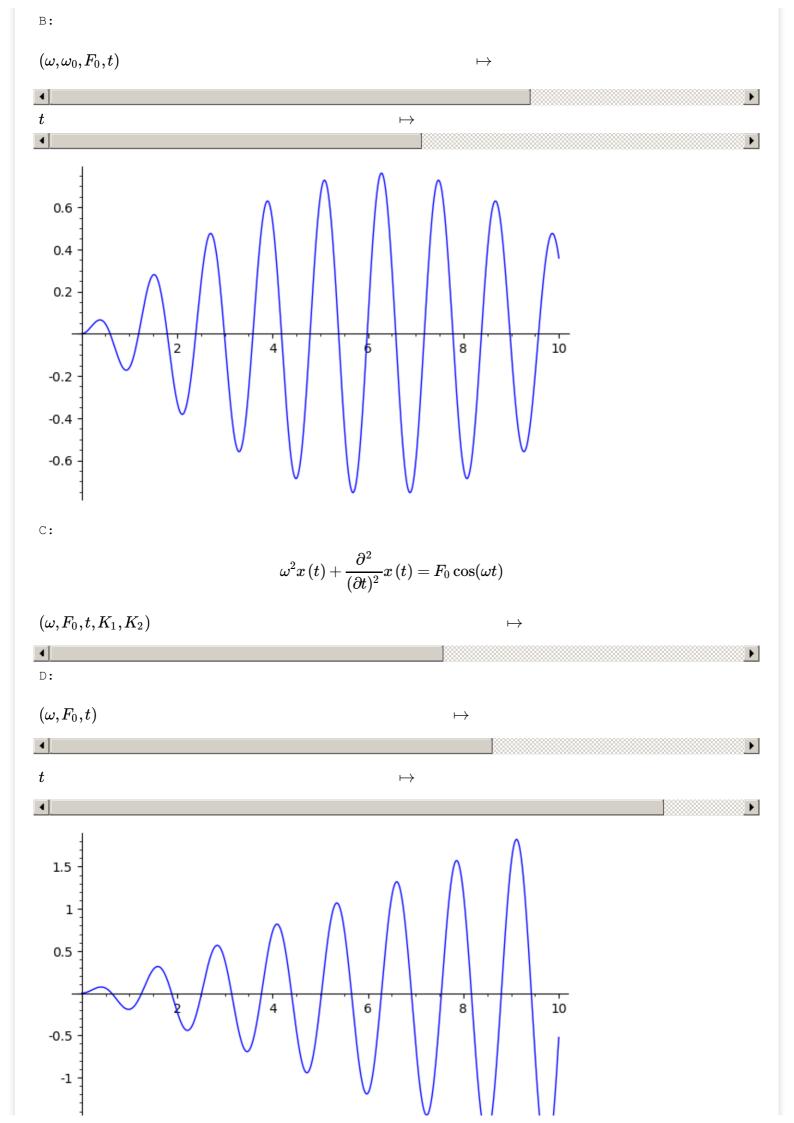
```
forget()
omega, omega0, t, F0=var('omega, omega0, t, F0')
x=function('x')(t)
eq=diff(x,t,2)+omega0^2*x==F0*cos(omega*t)
show(eq)
print("A:")
assume(omega0 > 0)
sol(omega, omega0, F0, t, K1, K2) = desolve(eq, [x, t])
show(sol)
print("B:")
sol(omega, omega0, F0, t) = desolve(eq, [x, t], [0, 0, 0])
show(sol)
sol(t) = sol(5.5, 5, 2, t)
show(sol)
show(plot(sol(t),t,0,10))
print("C:")
assume(omega==omega0)
eq=eq.substitute(omega0==omega)
show(eq)
sol(omega, F0, t, K1, K2) = desolve(eq, [x, t])
show(sol)
print("D:")
sol(omega, F0, t) = desolve(eq, [x, t], [0, 0, 0])
show(sol)
sol(t) = sol(5, 2, t)
show(sol)
show(plot(sol(t), t, 0, 10))
print("E:")
eq=diff(x, t, 2)+omega0^2*x==F0*cos(omega*t)
y(t, omega) = desolve(eq, [x, t], [0, 0, 0])
show(y)
eq=eq.substitute(omega==omega0)
show(eq)
show(limit(y,omega=omega0)==desolve(eq, [x, t], [0, 0, 0]).simplify full())\\
```

$$\omega_{0}^{2}x\left(t
ight)+rac{\partial^{2}}{\left(\partial t
ight)^{2}}x\left(t
ight)=F_{0}\cos(\omega t)$$

A:

$$(\omega,\omega_0,F_0,t,K_1,K_2) \hspace{1cm} \mapsto$$

4



E: $(t,\omega) \qquad \qquad \mapsto \\ \omega_0^2 x(t) + \frac{\partial^2}{(\partial t)^2} x(t) = F_0 \cos(\omega_0 t) \\ (t,\omega) \qquad \qquad \mapsto$