

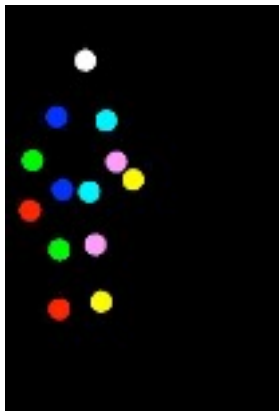
20

Method - Architecture

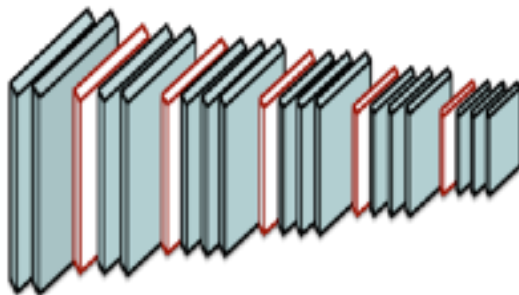
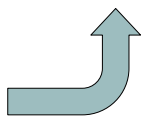
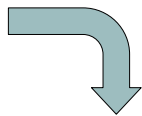




Frame t
input



Frame $t-1$
predicted pose



HumanPoseTracker



Frame t
output pose

3chan nns es

14charnes

14cnnre3

prediction

with `argmax`

warp with optical
flow (frame $t-1$ to
frame t)

Method - Previous Frame Pose Synthesis

Method - Architecture

