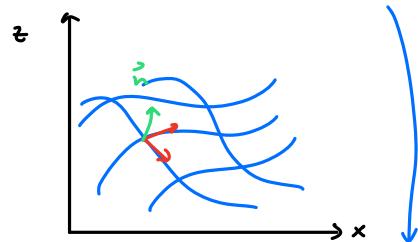


## Metoda karakteristika

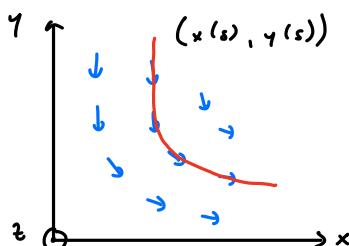
$$A(x, y, z) \frac{\partial z}{\partial x} + B(x, y, z) \frac{\partial z}{\partial y} = C(x, y, z) ; \quad z = z(x, y)$$



$$\tilde{D}_x = (1, 0, z_0) \quad \tilde{D}_y = (0, 1, z_0)$$

$$\tilde{n} = \tilde{D}_x \times \tilde{D}_y = \begin{pmatrix} 1 & 0 & z_0 \\ 0 & 1 & z_0 \\ 0 & 0 & 1 \end{pmatrix} = (-z_0, -z_0, 1)$$

$$\text{Eulerovitva: } \tilde{n} \cdot \tilde{F} = 0, \quad \tilde{F} = (A, B, C)$$



Metoda karakteristika: využíváme si na zářečku točky  
in sledujeme polyn

$$\frac{dx}{ds} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial s} = \frac{\partial z}{\partial x} A + \frac{\partial z}{\partial y} B = C$$

### ① Burgersova rovnice

$$\text{řešeno } g(x, t), \text{ když zadajíme rychlosti: } \frac{\partial g}{\partial t} + g \frac{\partial g}{\partial x} = 0$$

$$\text{z.č. pos. } g(x, 0) = \begin{cases} a^2 - x^2; & |x| > a \\ 0; & |x| \leq a \end{cases} \quad x(s), t(s) \quad \hookrightarrow A=1, \quad B=g, \quad C=0$$

$$\frac{dg}{ds} = 0 \quad \frac{dx}{ds} = g \quad \frac{dt}{ds} = 1 \quad \Rightarrow \quad t = s + D \quad \begin{matrix} 0 \\ \downarrow \end{matrix} \quad (\text{lakó fto veden} \\ \text{b. do svého lezení} \\ \text{v čase})$$

$$g(x(s), t(s)) = g(x(0), t(0)) = g(x_0, 0) \quad \times$$

$$\hookrightarrow \frac{dx}{ds} = g(x_0, 0) \Rightarrow x = g(x_0, 0)t + E \quad [ \text{ a pri } t=0 \text{ je } x_0 \Rightarrow E=x_0 ]$$

$$\textcircled{a} \quad |x_0| > a \quad \Rightarrow \quad x = x_0$$

$$\textcircled{b} \quad |x_0| \leq a \quad \Rightarrow \quad x = (a^2 - x_0^2)^{1/2}t + x_0 \quad \Rightarrow \quad x = a^2t - x_0^2t + x_0 \\ x_0^2t - x_0 - a^2t + x_0 = 0$$

Příjmo kvadratickou rovnici

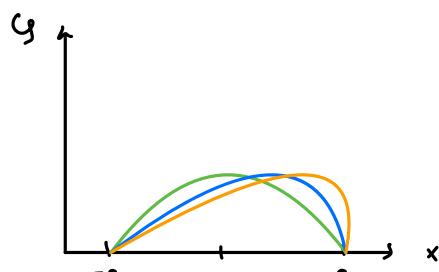
$$x_0 = \frac{1 \pm \sqrt{1 - 4t(x - a^2t)}}{2t}$$

To děláme u  $\textcolor{red}{x}$ , když je výroba, koliky je bilo na řešení:

$$g(x, t) = g(x, 0) = a^2 - x_0^2 = a^2 - \left( \frac{1 \pm \sqrt{1 - 4t(x - a^2t)}}{2t} \right)^2$$

Pouze pozor!

$$g(x, t) = \begin{cases} a^2 - \left( \frac{1 \pm \sqrt{1 - 4t(x - a^2t)}}{2t} \right)^2; & |x| > a \\ 0; & |x| \leq a \end{cases}$$



$$A = A(x, y)$$

$$Af_{xx} + Bf_{xy} + Cf_{yy} + Df_x + Ef_y + Ff = G$$

Karakteristike

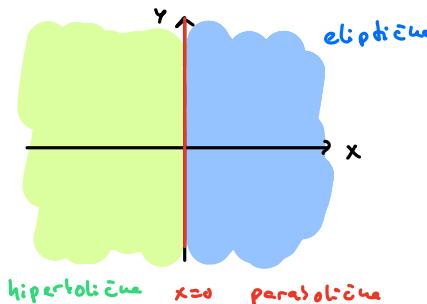
$$\frac{dy}{dx} = \frac{1}{2A} (B \pm \sqrt{B^2 - 4AC})$$



$\geq 0$	Hiperbolične	$f_{yy} - f_{xx} \geq 0$	Vat. en.
$= 0$	Parabolične	$f_y - f_{xx} = 0$	dif. en.
$< 0$	Elipsične	$f_{xx} + f_{yy} > 0$	Poissonova en.

② Klasificiraj en., pojedi karakteristike i po transformaciji u kanonsku obliku

$$xu_{xx} + uu_{yy} = x^2 \quad \rightarrow A = x, B = 1, C = x^2 \quad B^2 - 4AC = 0 - 4x \cdot 1 = -4x$$



Karakteristike:

$$\frac{dy}{dx} = \frac{1}{2x} (0 \pm \sqrt{-4x}) = \pm \frac{1}{\sqrt{-x}}$$

$$y = \int dy = \pm \int \frac{dx}{\sqrt{-x}} = \mp 2\sqrt{-x} + k$$

$$\text{Vektorimo novi mreznici} \quad \xi = y + 2\sqrt{-x}, \eta = y - 2\sqrt{-x}$$

$$u = u(\xi(x, y), \eta(x, y)) \quad \eta = \frac{y + \xi}{2}$$

$$\xi - \eta = 4\sqrt{-x} \quad x = -\left(\frac{\xi - \eta}{4}\right)^2$$

$$\Rightarrow \frac{\partial u}{\partial x} = \frac{\partial u}{\partial \xi} \frac{\partial \xi}{\partial x} + \frac{\partial u}{\partial \eta} \frac{\partial \eta}{\partial x}$$

$$\begin{aligned} \frac{\partial^2 u}{\partial x^2} &= \frac{\partial}{\partial \xi} \left( \frac{\partial u}{\partial \xi} \right) \frac{\partial \xi}{\partial x} + \frac{\partial}{\partial \eta} \left( \frac{\partial u}{\partial \xi} \right) \frac{\partial \eta}{\partial x} + \frac{\partial}{\partial \xi} \left( \frac{\partial u}{\partial \eta} \right) \frac{\partial \xi}{\partial x} + \frac{\partial}{\partial \eta} \left( \frac{\partial u}{\partial \eta} \right) \frac{\partial \eta}{\partial x} = \\ &= \left( \frac{\partial^2 u}{\partial \xi^2} \frac{\partial \xi}{\partial x} + \frac{\partial^2 u}{\partial \eta \partial \xi} \frac{\partial \eta}{\partial x} \right) \frac{\partial \xi}{\partial x} + \frac{\partial \xi}{\partial \eta} \frac{\partial^2 u}{\partial x^2} + \\ &\quad + \left( \frac{\partial^2 u}{\partial \eta^2} \frac{\partial \xi}{\partial x} + \frac{\partial^2 u}{\partial \xi \partial \eta} \frac{\partial \eta}{\partial x} \right) \frac{\partial \eta}{\partial x} + \frac{\partial \eta}{\partial \xi} \frac{\partial^2 u}{\partial x^2} \end{aligned}$$

$$\frac{\partial \xi}{\partial x} = \frac{-1}{\sqrt{-x}} \quad \frac{\partial \xi}{\partial \eta} = 1 \quad \frac{\partial^2 \xi}{\partial x^2} = -\frac{1}{2x\sqrt{-x}}$$

$$\frac{\partial \eta}{\partial x} = \frac{1}{\sqrt{-x}} \quad \frac{\partial \eta}{\partial \xi} = 1 \quad \frac{\partial^2 \eta}{\partial x^2} = 0 \quad \frac{\partial \eta}{\partial \xi} = 0$$

$$\frac{\partial^2 u}{\partial x \partial \eta} = 0 \quad \frac{\partial^2 u}{\partial \eta \partial \xi} = 0 \quad \frac{\partial^2 u}{\partial x^2} = +\frac{1}{2x\sqrt{-x}}$$

Vstavljam vse v en. \*

$$\begin{aligned} &x \left[ \left( \frac{\partial^2 u}{\partial \xi^2} \frac{-1}{\sqrt{-x}} + \frac{\partial^2 u}{\partial \eta \partial \xi} \frac{1}{\sqrt{-x}} \right) \frac{-1}{\sqrt{-x}} + \frac{\partial u}{\partial \xi} \frac{-1}{2x\sqrt{-x}} + \left( \frac{\partial^2 u}{\partial \xi \partial \eta} \frac{-1}{\sqrt{-x}} + \frac{\partial^2 u}{\partial \eta^2} \frac{1}{\sqrt{-x}} \right) \frac{1}{\sqrt{-x}} \right. \\ &\quad \left. + \frac{\partial u}{\partial \eta} \frac{1}{2x\sqrt{-x}} \right] + \left[ \left( \frac{\partial^2 u}{\partial \xi^2} + \frac{\partial^2 u}{\partial \eta \partial \xi} \right) + \frac{\partial u}{\partial \xi} \cdot 0 + \left( \frac{\partial^2 u}{\partial \xi \partial \eta} + \frac{\partial^2 u}{\partial \eta^2} \right) + \frac{\partial u}{\partial \eta} \cdot 0 \right] = x^2 \end{aligned}$$

$$\Rightarrow 4 \frac{\partial^2 u}{\partial \eta \partial \xi} - \frac{2}{\xi - \eta} \frac{\partial u}{\partial \xi} + \frac{2}{\xi - \eta} \frac{\partial u}{\partial \eta} = (\xi - \eta)^4$$

$$\alpha = \frac{1}{2} (\varsigma + \eta) \quad \beta = \frac{1}{2} (\varsigma - \eta)$$

$\Rightarrow$  Na koncu dostane

$$4 \frac{\partial^2 u}{\partial z \partial \bar{z}} = \frac{\partial^2 u}{\partial z^2} - \frac{\partial^2 u}{\partial \bar{z}^2}$$

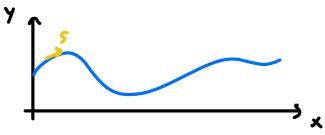
$$\frac{\partial u}{\partial z} = \frac{1}{2} \frac{\partial u}{\partial z} + \frac{1}{2} \frac{\partial u}{\partial \bar{z}}$$

$$\frac{\partial u}{\partial \bar{z}} = \frac{1}{2} \frac{\partial u}{\partial z} - \frac{1}{2} \frac{\partial u}{\partial \bar{z}}$$

$$\Rightarrow \frac{\partial^2 u}{\partial z^2} - \frac{\partial^2 u}{\partial \bar{z}^2} - \frac{1}{4} \left( \frac{\partial u}{\partial z} + \frac{\partial u}{\partial \bar{z}} \right) + \frac{1}{4} \left( \frac{\partial u}{\partial z} - \frac{\partial u}{\partial \bar{z}} \right) = \left( \frac{\beta}{2} \right)^4$$

$$\Rightarrow \frac{\partial^2 u}{\partial z^2} - \frac{\partial^2 u}{\partial \bar{z}^2} - \frac{1}{\beta} \frac{\partial u}{\partial z} = \left( \frac{\beta}{2} \right)^4$$

### Eukleidská struktura

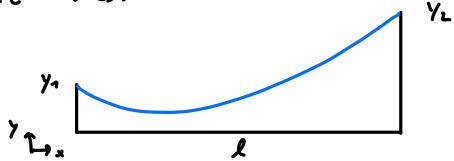


$$\begin{aligned} g_{xx} &= \frac{d}{ds} \left( F(s) \frac{dx}{ds} \right) + f^x \\ g_{yy} &= \frac{d}{ds} \left( F(s) \frac{dy}{ds} \right) + f^y \end{aligned}$$

↑   ↑  
dolíčivé součetné                         rostoté zaná sil

$$ds^2 = dx^2 + dy^2$$

### ③ Visečí most



dolíčivé  $L$ , masa  $M$ , zanima nás obličeje

$$\begin{aligned} 0 &= \frac{d}{ds} \left( F \frac{dx}{ds} \right) + f^x \\ 0 &= \frac{d}{ds} \left( F \frac{dy}{ds} \right) + f^y \end{aligned}$$

$$f^x = 0 \quad f^y = \frac{dF_{yy}}{ds} = - \frac{\partial dm}{ds} = - \frac{gM}{L} \frac{dx}{ds}$$

$$\begin{aligned} \frac{d}{ds} \left( F \frac{dx}{ds} \right) &= 0 \quad \Rightarrow F(s) \frac{dx}{ds} = F_0 \\ \frac{d}{ds} \left( F \frac{dy}{ds} \right) - \frac{gM}{L} \frac{dx}{ds} &= 0 \end{aligned}$$

$$\frac{d}{ds} \left( F_0 \frac{dx}{ds} \frac{dy}{ds} \right) - \frac{gM}{L} \frac{dx}{ds} = 0$$

$$\frac{d}{ds} \frac{dy}{dx} - \frac{gM}{L F_0} \frac{dx}{ds} = 0$$

$$\frac{dy}{dx} - \frac{d}{ds} \left( \frac{dy}{dx} \right) - \frac{gM}{L F_0} \frac{dx}{ds} = 0$$

$$\frac{d^2 y}{dx^2} = \frac{gM}{L F_0}$$

$$\frac{dy}{dx} = \underbrace{\frac{gM}{L F_0}}_{M/F_0} x + C$$

$$y = \frac{gM}{2 L F_0} x^2 + Cx + D$$

$$F_0, C, D = ?$$

$$\text{Posuči pogoj: } y(0) = y_0 \quad y(\ell) = y_\ell$$

$$\hookrightarrow D = y_0$$

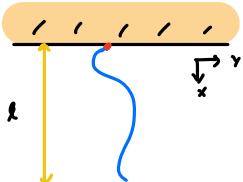
$$y_\ell = \frac{\mu \ell^2}{2 F_0} + C \ell + y_0$$

$$L = \int ds = \int \sqrt{dx^2 + dy^2} = \int_0^\ell \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx$$

$$L = \int_0^\ell \sqrt{1 + \left(\frac{\mu}{F_0} x + c\right)^2} dx$$

...  
...

(b) Majhne vibracije visoke strume



$\zeta$  sestotek

$\lambda$  dolžina

$dy/dx$

$x \in [0, \ell]$

- Lastni vibracijski nadomini?

- Časovni razvoj

$$\begin{aligned} \text{Majhni odvrti: } & \left\{ \begin{array}{l} ds^2 = dx^2 + dy^2 \\ ds = dx + O(dy^2) \end{array} \right. \\ & \end{aligned}$$

$$\zeta_{x_{tt}} = \frac{d}{ds} \left( F(s) \frac{dx}{ds} \right) + f^x = \zeta_g$$

$$0 = \frac{d}{dx} F + \zeta_g$$

$$F = -\zeta_g x + C \quad \text{R.P.} \quad F(0) = \zeta_g \lambda$$

$$\zeta_g \lambda = C \Rightarrow F = \zeta_g (\lambda - x)$$

$$\zeta_{y_{tt}} = \frac{\partial}{\partial x} \left( F \frac{\partial y}{\partial x} \right) + f^y$$

$$\zeta_{y_{tt}} = \zeta_g \frac{\partial}{\partial x} \left( (\lambda - x) \frac{\partial y}{\partial x} \right)$$

$$\frac{1}{\zeta} \zeta_{y_{tt}} = -y_x + (\lambda - x) y_{xx}$$

$$\frac{1}{\zeta} R \ddot{T} = -R' T + (\lambda - x) R'' T \quad | : RT$$

$$\underbrace{\frac{1}{\zeta} \frac{\ddot{T}}{T}}_{\text{konst.}} = -\underbrace{\frac{R'}{R}}_{\text{konst.}} + (\lambda - x) \underbrace{\frac{R''}{R}}_{\text{konst.}} = -\omega^2$$

$$\frac{1}{\zeta} \frac{\ddot{T}}{T} = -\omega^2$$

$$-\frac{R'}{R} + (\lambda - x) \frac{R''}{R} = -\omega^2$$

$$\ddot{T} = -\omega^2 \zeta T$$

$$(\lambda - x) R'' - R' + \omega^2 R = 0$$

Separiacija spremenljivk:  
 $\zeta(x, t) = R(x) T(t)$

$$T = A \sin(\sqrt{\zeta} \omega t) + B \cos(\sqrt{\zeta} \omega t)$$

$$! z = \sqrt{1 - \frac{x}{\lambda}}$$

$$\frac{dR}{dx} = \frac{dR}{dz} \frac{dz}{dx} = \frac{dR}{dz} \frac{-\frac{1}{\lambda}}{\sqrt{1 - \frac{x}{\lambda}}} = -\frac{1}{2\lambda z} \frac{dR}{dz}$$

$$\frac{d^2 R}{dx^2} = \frac{d}{dx} \frac{d}{dz} \left( -\frac{1}{2\lambda z} \frac{dR}{dz} \right) = -\frac{1}{2\lambda z} \left( \frac{1}{2\lambda z^2} \frac{dR}{dz} - \frac{1}{2\lambda z} \frac{d^2 R}{dz^2} \right)$$

$$-\lambda \frac{1}{\zeta} \left( \frac{1}{2\lambda z^2} \frac{dR}{dz} - \frac{1}{2\lambda z} \frac{d^2 R}{dz^2} \right) + \frac{1}{2\lambda z} \frac{dR}{dz} + \omega^2 R = 0$$

$$-\frac{1}{4\lambda z} \frac{dR}{dz} + \frac{1}{4\lambda} \frac{d^2 R}{dz^2} + \frac{1}{2\lambda z} \frac{dR}{dz} + \omega^2 R = 0$$

$$\begin{aligned} & \text{Besselove DE} \\ & z^2 \frac{d^2 u}{dz^2} + z \frac{du}{dz} + (z^2 - n^2) u = 0 \\ & u(z) = A J_n(z) + B Y_n(z) \end{aligned}$$

$$\frac{1}{4L} \frac{d^2 R}{dz^2} + \frac{1}{4L} \frac{dR}{dt} + \omega^2 R = 0 \quad / \cdot z^2 \cdot 4L$$

$$z^2 \frac{d^2 R}{dz^2} + z \frac{dR}{dt} + \omega^2 4L z^2 R = 0 \quad z \rightarrow 2\omega L z$$

$$n=0$$

$$R = C J_0(2\omega L z) + D Y_0(2\omega L z); \quad z = \sqrt{1-\frac{x}{L}}$$

by moment  $\Rightarrow D=0$

$$Y_m = J_0(2\omega_m \sqrt{L-x})(A_m \sin(\sqrt{\omega_m} \omega t) + B_m \cos(\sqrt{\omega_m} \omega t))$$

$$Y = \sum_{m=1}^{\infty} Y_m$$

④ Valovna enačba

$$G_L x_{tt} = \frac{d}{ds} \left( F(s) \frac{dx}{ds} \right)$$

$$G_L y_{tt} = \frac{d}{ds} \left( F(s) \frac{dy}{ds} \right) \Rightarrow G_L y_{tt} = F \frac{d^2 y}{ds^2} \Rightarrow y_{tt} - c^2 y_{xx} = 0$$

$$c^2 = \frac{F}{G_L}$$

$$\text{če } dx \approx ds \quad dy \approx 1$$

d'Alembertova ročica (na nehomogeni struni)

$$u(x,0), \quad u'(x,0)$$

Prijeti  $u(x,t) = \frac{1}{2} (u(x-ct,0) + u(x+ct,0)) + \frac{1}{2c} \int_{x-ct}^{x+ct} u_t(z,0) dz$

⑤ Pojemne homogene struni



$\Rightarrow$  a)  $u(0,t) = 0$   
 $\Rightarrow$  b)  $u'(0,t) = 0 \Rightarrow u(x,0) = \tilde{u}(x,0) + \tilde{u}_t(x,0)$

b)  $u(x,t) = \begin{cases} \tilde{u}(x,t) & x>0 \\ 0 & x<0 \end{cases}$

$$u(x,0) = \tilde{u}(x,0) - \tilde{u}(-x,0) \quad \text{liho preverljivo}$$

$$u_t(x,0) = \tilde{u}_t(x,0) - \tilde{u}_t(-x,0)$$

d'Alembert  $u(x,t) = \frac{1}{2} (\tilde{u}(x-ct,0) - \tilde{u}(-x+ct,0) + \tilde{u}(x+ct,0) - \tilde{u}(-x-ct,0))$

$$+ \frac{1}{2c} \int_{x-ct}^{x+ct} \tilde{u}_t(z,0) dz - \frac{1}{2c} \int_{-x-ct}^{-x+ct} \tilde{u}_t(z,0) dz$$

$\int_{x-ct}^{x+ct} dz - \int_{-x-ct}^{-x+ct} dz = \int_0^{2ct}$

$$z=a \quad t>0 \quad u=0$$

$$u(x,t) = \begin{cases} \frac{1}{2} (-\tilde{u}(-x+ct,0) + \tilde{u}(x+ct,0)) + \frac{1}{2c} \int_{-x+ct}^{x+ct} \tilde{u}_t(z,0) dz & x < ct \\ \frac{1}{2} (\tilde{u}(x+ct,0) + \tilde{u}(x-ct,0)) + \frac{1}{2c} \int_{x-ct}^{x+ct} \tilde{u}_t(z,0) dz & x > ct \end{cases}$$

⑥ Masa na struni



$$G_{v,F}$$

$$\omega, k$$

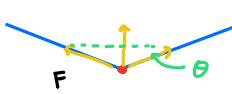
$$u_1 = e^{i(kx - \omega t)} + R e^{i(-kx - \omega t)}$$

$$u_2 = T e^{i(kx - \omega t)}$$

$$RP \quad u_1(0, t) = u_2(0, t)$$

$$\bullet m \ddot{u}(t) = F \left( \frac{\partial u}{\partial x} \Big|_0 - \frac{\partial u}{\partial x} \Big|_0 \right)$$

$$u(t) = u_1(0, t) = u_2(0, t)$$



$$\sin \theta = \frac{F_y}{F} \approx \theta \quad \tan \theta = \frac{\frac{\partial u}{\partial x}}{F} \approx \theta$$

$$e^{-i\omega t} + R e^{i\omega t} = T e^{i\omega t}$$

$$1 + R = T$$

$$u = T e^{i\omega t}$$

$$T m (-\omega^2) e^{-i\omega t} = F (T i k e^{-i\omega t} - i k e^{-i\omega t} + R i k e^{-i\omega t})$$

$$-T m \omega^2 = F i k (T - 1 + R)$$

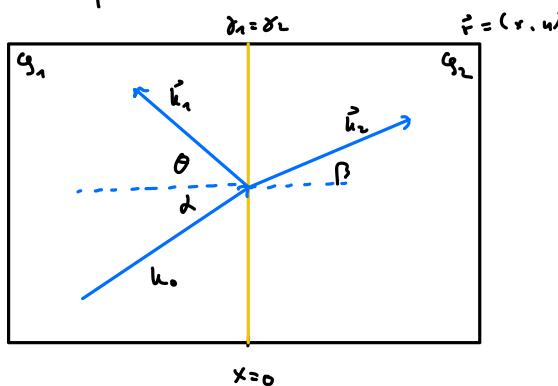
$$0 = \frac{F i k}{m \omega^2} (T - 1 + T - 1) + T$$

$$\frac{2 F i k}{m \omega^2} = T (2 \frac{F i k}{m \omega^2} + 1) \quad \omega = ck$$

$$T = \frac{1}{1 + \frac{m \omega^2}{2 i k F}} = \frac{1}{1 - i \frac{k}{k_0}} \quad \frac{m \omega^2}{2 i k F} = \frac{m c^2 k}{2 i F} = \frac{k}{i k_0}$$

$$R = T - 1 = \frac{i \frac{k}{k_0}}{1 - i \frac{k}{k_0}} = \frac{-1}{1 + i \frac{k_0}{k}}$$

⑦ Odboj valovanja na opni



frekvencija enaka na obeh straneh

z = (x, u)

$$z_{ttt}(x, y, t) - c^2 \nabla^2 z(x, y, t) = 0$$

$$c^2 = \frac{y^2}{g} \quad \text{povertina nepristop} \\ \text{povertina sestop}$$

$$z_1 = e^{i(k_0 \hat{x} - \omega t)} + R e^{i(k_0 \hat{x} - \omega t)} \\ z_2 = T e^{i(k_0 \hat{x} - \omega t)}$$

$$R.P. \quad z_1(0, t) = z_2(0, t)$$

$$\text{Vemo} \quad F^y = y^2 \frac{\partial z}{\partial x}$$

$$F_1^y = F_2^y \\ \frac{\partial z_1}{\partial x}(0, y, t) = \frac{\partial z_2}{\partial x}(0, y, t)$$

Faza in amplituda se morata ujemati

$$\omega^2 = c^2 \vec{k} \cdot \vec{k}$$

$$k_0 \sin \alpha = k_1 \sin \theta = k_2 \sin \beta \quad 1 + R = T$$

$$k_0 \sin \alpha = k_2 \sin \beta \Rightarrow \frac{\omega}{c_1} \sin \alpha = \frac{\omega}{c_2} \sin \beta \Rightarrow \frac{\sin \alpha}{\sin \beta} = \frac{c_2}{c_1}$$

$$k_0 \cos \alpha e^{i(k_0 y \sin \theta - \omega t)} - R k_0 \cos \theta e^{i(k_0 y \sin \theta - \omega t)} = T k_0 \cos \beta e^{i(k_0 y \sin \beta - \omega t)}$$

$$k_0 \cos \alpha - R k_0 \cos \theta = T k_0 \cos \beta$$

$$k_0 (\cos \alpha - R \cos \theta) = (1+R) k_0 \cos \beta$$

$$k_0 \cos \alpha (1-R) = (1+R) k_0 \sqrt{1-\sin^2 \beta}$$

$$\cos \alpha (1-R) = (1+R) \frac{c_\beta}{c_\alpha} \sqrt{1 - \frac{c_\alpha^2}{c_\beta^2} \sin^2 \alpha}$$

$$1-R = (1+R) \frac{1}{\cos \alpha} \sqrt{\frac{c_\alpha^2}{c_\beta^2} - \sin^2 \alpha}$$

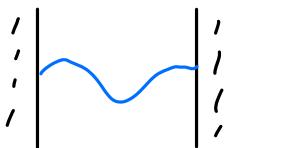
$$1-R = D + R D$$

$$R(D-1) = D-1$$

$$R = \frac{1-D}{1+D} \quad T = \frac{2}{1+D}$$

DN un stetig je strenge werte  $\Rightarrow F_1, g_L$

⑦



$$u_{tt} = c^2 u_{xx}$$

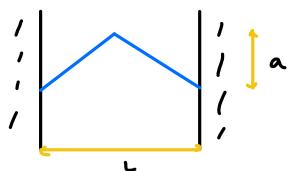
$$u(x,t) = \sum X_n T_n$$

$$T_n = A_n \cos \omega_n t + B_n \sin \omega_n t$$

$$X_n = C_n \cos k_n x + D_n \sin k_n x$$

$$\omega_n = c k_n$$

⑧



$$u(0,t) = u(L,t) = 0$$

$$u(x,0) = \begin{cases} \frac{2a}{L} x & ; x \leq L/2 \\ -\frac{2a}{L} x + 2a & ; L/2 \leq x \leq L \end{cases}$$

$$\Rightarrow C_n = 0 \quad u(x,t) = \sum \sin k_n x (A_n \cos \omega_n t + B_n \sin \omega_n t)$$

$$k_n = \frac{n\pi}{L}$$

$$u(x,0) = \sum_n A_n \sin k_n x \quad | \int \sin k_n x \, dx$$

$$\int_0^L u(x,0) \sin k_n x \, dx = A_n \frac{L}{2} \quad \Rightarrow D_n = 0$$

$$\int_0^{L/2} \frac{2a}{L} x \sin k_n x \, dx + \int_{L/2}^L \left(2a - \frac{2a}{L} x\right) \sin k_n x \, dx = A_n \frac{L}{2}$$

$$\frac{2a}{L} \int_0^{L/2} x \sin k_n x \, dx + \frac{2a}{L} \int_{L/2}^L (L-x) \sin k_n x \, dx = A_n \frac{L}{2}$$

$$\frac{2a}{L} \left[ -x \cos k_n x + \frac{1}{k_n} \sin k_n x \right]_0^{L/2} + \frac{2a}{L} L \frac{1}{k_n} \cos k_n x \Big|_{L/2}^L$$

$$+ \frac{2a}{L} \left( \frac{x}{k_n} \cos k_n x - \frac{1}{k_n^2} \sin k_n x \right) \Big|_{L/2}^L = A_n \frac{L}{2}$$

$$\int x \sin k_n x \, dx =$$

$$x = u \quad \sin k_n x \, dx = du \\ du = d(u) = -\frac{1}{k_n} \cos k_n x \, dx = -v$$

$$= -\frac{x}{k_n} \cos k_n x + \frac{1}{k_n^2} \sin k_n x$$

⋮

$$A_n = \begin{cases} 0 & ; n \text{ odd} \\ \frac{8a}{\pi^2 n^2} (-1)^{\frac{n-1}{2}} & \end{cases}$$

## ⑨ Struna & maso

Lastun sijavem / mazini?



$$\text{Rovn po goj:} \\ u(0,t) = 0 \Rightarrow C_n = 0$$

$$m \frac{d^2 u}{dt^2}(L,t) = -F \frac{du}{dx}$$

$$F_s = -F \frac{du}{dx}$$

T napetost u struni

$$u(x,t) = \sum X_n T_n$$

$$T_n = A_n \cos \omega_n t + B_n \sin \omega_n t$$

$$X_n = C_n \cos k_n x + D_n \sin k_n x$$

$$u(x,t) = \sum_n \sin k_n x (A_n \cos \omega_n t + B_n \sin \omega_n t)$$

$$u_{tt} = \sum_n \sin k_n x (-A_n \omega_n^2 \cos \omega_n t - B_n \omega_n^2 \sin \omega_n t)$$

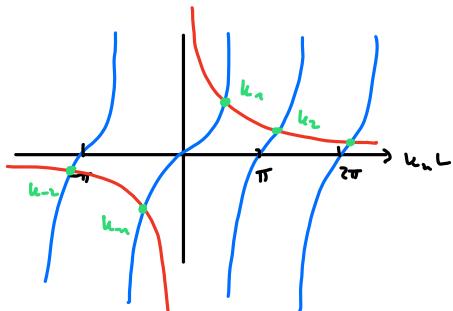
$$u_x = \sum_n k_n \cos k_n x (A_n \cos \omega_n t + B_n \sin \omega_n t)$$

$$\sum_n \sin k_n x (-A_n \omega_n^2 \cos \omega_n t - B_n \omega_n^2 \sin \omega_n t) = -\frac{E}{m} \sum_n k_n \cos k_n x (A_n \cos \omega_n t + B_n \sin \omega_n t)$$

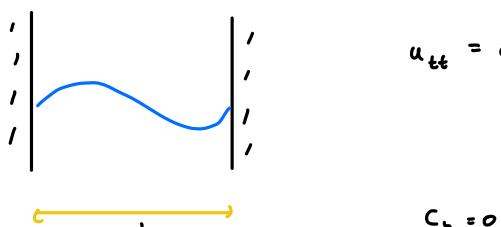
$$A_n : \quad \omega_n^2 (A_n \cos \omega_n t + B_n \sin \omega_n t) = \frac{E}{m} k_n \frac{\cos k_n x}{\sin k_n x} (A_n \cos \omega_n t + B_n \sin \omega_n t)$$

$$\tan k_n x = \frac{\omega_n^2}{k_n}$$

$$\tan k_n x = \frac{k_0}{k_n}$$



## ⑩ Struna & zunanja sila



$$u_{tt} = c^2 u_{xx} + f(x,t)$$

$$f(x,t) = f_0 \cos(\omega t)$$

$$C_n = 0$$

$$X_n(x) = \sqrt{\frac{2}{L}} \sin k_n x \quad k_n = \frac{n\pi}{L}$$

$$f(x,t) = \sum_n X_n(x) f_n(t) \quad | \int X_n dx$$

$$\int_0^L f(x,t) X_n dx = f_n(t)$$

$$\int_0^L f_0 \cos \omega t \sqrt{\frac{2}{L}} \sin k_n x dx = f_n(t)$$

$$f_n(t) = f_0 \frac{\sqrt{2L}}{n\pi} (1 - (-1)^n) \cos \omega t$$

$$f = \sum_n \frac{2f_0}{\pi} (1 - (-1)^n) \cos \omega t \sin k_n x$$

$$u = \sum_n \sin k_n x (A_n \cos \omega_n t + B_n \sin \omega_n t)$$

$$u_{tt} = c^2 u_{xx} + f$$

$$\int_0^L \sum_n \sin k_n x (-A_n \omega_n^2 \cos \omega_n t - B_n \omega_n^2 \sin \omega_n t) = \sum_n (-k_n^2 \sin k_n x) (A_n \cos \omega_n t + B_n \sin \omega_n t) \stackrel{?}{=} \int_0^L (1 - (-1)^n) \cos \omega t \sin k_n x$$

$$A_n \cos \omega_n t + B_n \sin \omega_n t = \underbrace{A_n \cos \omega_n t + B_n \sin \omega_n t}_{u_n} - \frac{2f_0}{\omega_n^2 \pi} \int_0^L (1 - (-1)^n) \cos \omega t$$

$$\ddot{u}_n(t) = u_n(t) + f_n \cos(\omega t)$$

$$u = \underbrace{(A_n \cos \omega_n t + B_n \sin \omega_n t)}_{u_{\text{Hom}}} + \underbrace{u^{\text{part}}}_{u^{\text{part}}}$$

$$u^{\text{part}} = C_n \sin \omega t + D_n \cos \omega t$$

$$-C_n \omega^2 \sin \omega t - D_n \omega^2 \cos \omega t = \bar{u}_n (C_n \sin \omega t + D_n \cos \omega t) + f_n \cos(\omega t)$$

$$(C_n \sin \omega t + D_n \cos \omega t) (\omega_n^2 - \omega^2) = f_n \cos(\omega t)$$

$$C_n = 0 \quad D_n = \frac{f_n}{\omega_n^2 - \omega^2} \quad \bar{C}_n \quad \omega^2 \neq \omega_n^2$$

$$u_{\text{part}} = \frac{f_n}{\omega_n^2 - \omega^2} \cos \omega t$$

$$\bar{C}_n \quad \omega_n = \omega$$

$$u_{\text{part}} = t (C_n' \sin \omega t + D_n' \cos \omega t)$$

$$u_t = C_n' \sin \omega t + D_n' \cos \omega t + t (C_n' \omega \cos \omega t - D_n' \omega \sin \omega t)$$

$$u_{tt} = C_n' \omega \cos \omega t - D_n' \omega \sin \omega t + C_n' \omega \cos \omega t - D_n' \omega \sin \omega t + t (-C_n' \omega^2 \sin \omega t - D_n' \omega^2 \cos \omega t)$$

$$\ddot{u} = -c^2 u + f$$

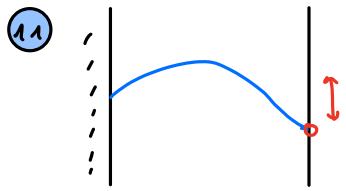
$$2C_n' \omega \cos \omega t - 2D_n' \omega \sin \omega t + t (-C_n' \omega^2 \sin \omega t - D_n' \omega^2 \cos \omega t) = -\omega_n^2 t (C_n' \sin \omega t + D_n' \cos \omega t) + f_n \cos \omega t$$

$$2C_n' \omega \cos \omega t - 2D_n' \omega \sin \omega t = f_n \cos \omega t$$

$$D_n' = 0 \quad C_n' = \frac{f_n}{2\omega}$$

$$\Rightarrow u_{\text{part}} = \frac{f_n}{2\omega} t \sin \omega t$$

$$u(x,t) = \sum_n \int_0^L \sin k_n x (A_n \cos \omega_n t + B_n \sin \omega_n t + \begin{cases} \frac{f_n}{\omega_n^2 - \omega^2} \cos \omega t & \omega_n \neq \omega \\ \frac{f_n}{2\omega} t \sin \omega t & \omega_n = \omega \end{cases})$$



$$u(0, t) = 0 \\ u(L, t) = U_0 \cos \omega t \quad \text{uzsākums}$$

$$u_{tt} = c^2 u_{xx}$$

$$\tilde{u}(x, t) = u(x, t) - \frac{x}{L} U_0 \cos \omega t \quad \text{trik}$$

$$\tilde{u}(0, t) = 0 \\ \tilde{u}(L, t) = 0$$

$$\tilde{u}_{tt} = \frac{x}{L} U_0 \omega^2 \cos \omega t = c^2 \tilde{u}_{xx}$$

$$\tilde{u}_{tt} = c^2 \tilde{u}_{xx} + \frac{x}{L} U_0 \omega^2 \cos \omega t$$

: postopch eac hst pri projigi ualogi

### 11 Difuzijskie eaqābe

$$\frac{\partial T}{\partial t} = D \nabla^2 T + \frac{g}{c_s c_p} \quad \text{izviri topothe (uzņemums gostota)}$$

### 12 Toplotni valovi:

$$T_z = T_0 e^{i \omega t}$$

$$\frac{\partial T}{\partial t} = D \nabla^2 T \quad \text{R.P. } T(0, t) = T_0 e^{i \omega t}$$

$$\downarrow z$$

$$\text{Nastāvus } T(z, t) = f(z) e^{i \omega t}$$

$$T(z, t) = ?$$

$$f(z) i \omega e^{i \omega t} = D f'' e^{i \omega t}$$

$$f'' - \frac{i \omega}{D} f = 0$$

$$f = A \sin \omega_c z + B \cos \omega_c z = A e^{i \omega_c z} + B e^{-i \omega_c z}$$

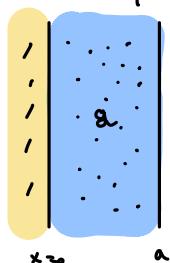
$$\text{R.P. } A + B = T_0$$

$$A \approx 0 \quad f(z \rightarrow \infty) \ll \infty$$

$$\Rightarrow T = T_0 e^{i \omega t} e^{-\sqrt{\frac{D}{\omega}} z} \quad \Gamma_i = \frac{1}{\sqrt{2}} (1+i)$$

$$T = T_0 \Re(e^{i \omega t - \sqrt{\frac{D}{\omega}} (\ln \omega) z}) = T_0 e^{-\sqrt{\frac{D}{\omega}} z} \omega (w t - \sqrt{\frac{D}{\omega}} z)$$

### 13 Radiacijsko oklajanje



$$T(x) = ?$$

$$\frac{\partial T}{\partial x} = -\frac{g}{c_s c_p \sigma}$$

$$\text{izolejījīs} \\ \text{R.P. } \left. \frac{\partial T}{\partial x} \right|_{x=x_0} = 0 \quad \text{② } j = \sigma T^4 \Big|_{x=x_0} - \sigma T_e^4 = -\lambda \left. \frac{\partial T}{\partial x} \right|_{x=x_0}$$

$$\text{zāne manino}$$

$$\frac{\partial T}{\partial x} = -\frac{g x}{c_s c_p \sigma} + C$$

$$\text{R.P. } 0 = 0 + C \Rightarrow C = 0$$

$$\text{konektivitāts}$$

$$T = -\frac{g x^2}{2 c_s c_p \sigma} + C x + E$$

$$\text{R.P. } -\lambda \left. \frac{\partial T}{\partial x} \right|_{x=a} = \sigma (T^4 \Big|_{x=a} - T_e^4)$$

$$\text{uzpītē}$$

$$\Rightarrow E = \pm \sqrt{\frac{g \lambda q}{\sigma c_s c_p \sigma} + T_e^4} + \frac{g a^2}{2 c_s c_p \sigma}$$

$$\text{sevijs ēruse klase}$$

$$\Rightarrow T = -\frac{g}{2 c_s c_p \sigma} x^2 \pm \sqrt{\frac{g \lambda q}{\sigma c_s c_p \sigma} + T_e^4} + \frac{g a^2}{2 c_s c_p \sigma}$$

1) Greenova funkcija za difuzijsko enačbo

$$\begin{aligned} \mathcal{L}(u(\vec{r}, t)) &= f(\vec{r}, t) \\ \mathcal{L} &= \frac{\partial}{\partial t} - D \nabla^2 \end{aligned}$$

$$D \text{f. en.}$$

$$\mathcal{L} G(\vec{r}, t - \tau) = \delta(\vec{r} - \vec{r}_0) \delta(t - \tau)$$

Greenova funkcija

Složeno rešitev



$$\begin{aligned} u(\vec{r}, t) &= \int_{-\infty}^t d\tau \int_D d\vec{r}_0 G(\vec{r}, \vec{r}_0, t - \tau) f(\vec{r}_0, \tau) \\ &\quad + \int_0^t d\tau \int_D d\vec{r}_0 u_0(\vec{r}_0) G(\vec{r}, \vec{r}_0, \tau) \\ &\quad - \int_{-\infty}^t d\tau \int_D d\vec{r}_0 g(\vec{r}_0, \tau) \frac{\partial G}{\partial \vec{r}}(\vec{r}, \vec{r}_0, t - \tau) dS \end{aligned}$$

nekonvergent

začetni posoj  
ročni posoj

Greenova funkcija za difuzijo v 1D prostoru

$$G(x, x_0, t) = \frac{1}{\sqrt{4\pi Dt}} e^{-(x-x_0)^2/4Dt}$$

2) Točkovna sestavna polica

$(x_0, t_0)$

$T(x, t) = ?$



OS x, t to zanesno sestavno polico v  $x_0$ .

$$\frac{\partial T}{\partial t} = D \nabla^2 T + f(x, t) \quad f(x, t) = h \delta(x - x_0) H(t - t_0)$$

$$T(x, t) = \int_{-\infty}^t d\tau \int_{-\infty}^{\infty} dz \frac{1}{\sqrt{4\pi D(t-\tau)}} e^{-\frac{(x-z)^2}{4D(t-\tau)}} h \delta(x - x_0) H(t - \tau)$$

$$= \int_{t_0}^t \frac{h}{\sqrt{4\pi D(t-\tau)}} e^{-\frac{(x-z)^2}{4D(t-\tau)}} dz$$

$$\text{Načrtovan } z = \frac{x - z_0}{\sqrt{4D(t - \tau)}}$$

$$= \int_{z_0}^{\infty} \frac{z h}{\sqrt{4\pi}} e^{-\frac{z^2}{4}} \frac{dz}{z^2} = \frac{(x - x_0)^2 h}{2D\sqrt{\pi}}$$

$$dz = \frac{x - z_0}{\sqrt{4D(t - \tau)}} \left( -\frac{1}{z} \right) (-dz)$$

$$= \frac{(x - x_0)^2 h}{2D\sqrt{\pi}} \int_{z_0}^{\infty} \frac{e^{-z^2}}{z^2} dz =$$

$$dz = \frac{x - z_0}{4\sqrt{D(t - \tau)}} \frac{1}{2} dz$$

$$\text{Prej podeli } dv = \frac{dz}{z^2} \quad v = -\frac{1}{z} \quad \text{pri } \operatorname{erf}(x) = 2 \int_0^x e^{-z^2} dz$$

$$u = e^{-z^2} \quad du = -2z e^{-z^2} dz$$

$$\operatorname{erf}(x) = 2 \int_0^x e^{-z^2} dz$$

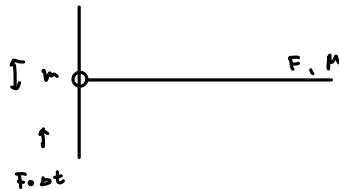
$$= \frac{(x - x_0)^2 h}{2D\sqrt{\pi}} \left( -\frac{1}{z} e^{-z^2} \Big|_{z_0}^{\infty} - 2 \int_{z_0}^{\infty} e^{-z^2} dz \right)$$

$$= \frac{(x - x_0)^2 h}{2D\sqrt{\pi}} \left( \frac{e^{-z_0^2}}{z_0} - \sqrt{\pi} \left( \operatorname{erf}(\infty) - \operatorname{erf}(z_0) \right) \right)$$

$$= \frac{h(x - x_0)^2}{2D\sqrt{\pi}} \left( \frac{e^{-z_0^2}}{z_0} - \sqrt{\pi} (1 - \operatorname{erf}(z_0)) \right)$$

$$z_0 = \frac{x - x_0}{\sqrt{4D(t - \tau)}}$$

(u) Volokujška nalogia



$$\begin{aligned} c^2 u_{xx} &= u_{tt} & c^2 &= \frac{F}{m} \\ \text{z.g.} \quad u(x, 0) &= 0 \\ u_t(x, 0) &= \begin{cases} \frac{F \cdot x_0}{m} = v_0 & x > 0 \\ 0 & x < 0 \end{cases} \\ \text{R.P.} \quad u_{tt} &= F \frac{\partial u}{\partial x} \Big|_{x=0} (+) \end{aligned}$$

$$u(x, t) = f(x - ct) + g(x + ct)$$

$$\begin{aligned} x > 0 \quad & \bullet \quad 0 = f(x) + g(x) \\ & \bullet \quad -c f'(x) + c g'(x) = 0 \\ & \quad f'(x) - g'(x) = 0 \end{aligned}$$

$$-f'(x) = -g'(x) = c$$

$$u(x, t) = \begin{cases} f(x - ct) + c & x - ct \leq 0 \\ 0 & x - ct > 0 \end{cases}$$

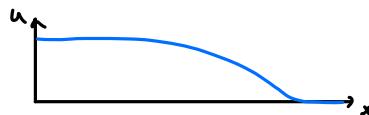
V R.P.

$$m \ddot{u} = f''(-ct) = F f'(-ct) \quad \xi = \frac{m \omega}{F}$$

$$f(-ct) = A e^{-ct/\xi} + B$$

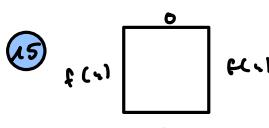
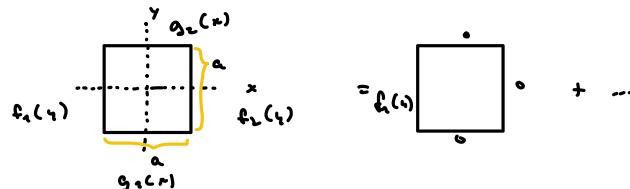
$$\begin{aligned} x - ct &\leq 0 \\ \Rightarrow u(x, t) &= A e^{x-ct/\xi} + B + c \\ 0 &= A + B + c \\ v_0 &= -A \frac{c}{\xi} \end{aligned}$$

$$u(x, t) = \begin{cases} \frac{v_0}{c} \xi (1 - e^{x-ct/\xi}) & x - ct \leq 0 \\ 0 & x - ct > 0 \end{cases}$$



(T) Laplaceova enačba

$$\nabla^2 \varphi = 0$$



$$\nabla^2 \varphi = \frac{\partial^2}{\partial x^2} \varphi + \frac{\partial^2}{\partial y^2} \varphi = 0$$

$$\varphi(x, y \pm \frac{a}{2}) = 0$$

$$\varphi(x \pm \frac{a}{2}, y) = f(z)$$

$$f(z) = \underbrace{\frac{f(y) + f(-y)}{2}}_{\text{sod}} + \underbrace{\frac{f(z) - f(-z)}{2}}_{\text{lil}}$$

V našem primeru f = sod

$$\frac{x^n}{m^n} + \frac{y^n}{-n^n} = 0$$

$$Y'' + \omega^2 Y = 0$$

$$Y = \sum_n A_n \sin \omega_n y + B_n \cos \omega_n y$$

$$\Rightarrow A_n = 0$$

$$\gamma(-\frac{\pi}{2}) = \gamma(\frac{\pi}{2}) = \sum_n b_n \cos m \frac{\pi}{2} = 0$$

$$m_n \frac{\pi}{2} = (n + 1/2)\pi \\ m_n = \frac{2\pi}{\alpha} (n + 1/2)$$

$$x'' - m^2 x = 0$$

$$x = \sum_n c_n \sin \frac{2\pi}{\alpha} (n + 1/2) x + d_n \cos \frac{2\pi}{\alpha} (n + 1/2) x$$

$$\text{Vorw. } f(\frac{\pi}{2}) = f(-\frac{\pi}{2}) \quad \text{s.d.z.} \Rightarrow c_n = 0$$

$$\Rightarrow q(x,y) = \sum_{n=0}^{\infty} A_n \cos \frac{2\pi}{\alpha} (n + 1/2) y \cdot \cos \frac{2\pi}{\alpha} (n + 1/2) x$$

$$q(\frac{\pi}{2}, y) = \sum_{n=0}^{\infty} A_n \cos \frac{2\pi}{\alpha} (n + 1/2) y \cdot \cos (\pi(n + 1/2)) = f(y)$$

$$\int_{-\pi/2}^{\pi/2} f(y) \cos \left( \frac{2\pi}{\alpha} (n + 1/2) y \right) dy = \sum_{n=0}^{\infty} A_n \cos (\pi(n + 1/2)) \delta_{n,0} \quad \frac{\alpha}{2} \int_{-\pi/2}^{\pi/2} \cos^2 \left( \frac{2\pi}{\alpha} (n + 1/2) y \right) dy = \frac{\pi}{2}$$

$$A_0 = \frac{\int_{-\pi/2}^{\pi/2} f(y) \cos \left( \frac{2\pi}{\alpha} (n + 1/2) y \right) dy}{\frac{\pi}{2} \cos (\pi(n + 1/2))}$$

### ⑤ Hydrodynamika - Navier-Stokesova rovnice

$$\rho \left( \frac{\partial \vec{v}}{\partial t} \right) = \rho \vec{f} - \nabla p + \eta \nabla \cdot \vec{v} + (\zeta + \frac{n}{3}) \nabla (\nabla \cdot \vec{v}) \quad \text{Ohnoudu svisleho kolizne}$$

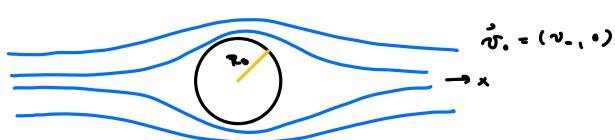
$\uparrow$   $\uparrow$   $\uparrow$   
 gravitacni sila tlak viskositet volumicka rozsvernost

$$\frac{\partial \rho}{\partial t} = -\rho \nabla \cdot \vec{v} \quad \text{Ohnoudu mase}$$

$$\frac{\partial \rho}{\partial t} = \frac{\partial \rho}{\partial t} + (\vec{v} \cdot \nabla) \rho$$

$$\text{Neutrální tokosíň } \nabla \cdot \vec{v} = 0$$

### ⑥ Skalar v toku



$$\vec{v}(r, \varphi) = ?$$

Předpoklady:

-stationerního stojané  $\frac{\partial \vec{v}}{\partial t} = 0$

-neutrálního tokosíň  $\nabla \cdot \vec{v} = 0$

-bezvýplňového tokosíň  $\nabla \times \vec{v} = 0$

Konvenciou poli  $\vec{v} = -\nabla \Phi$   
tokovní potenciál

$$\Rightarrow 0 = \nabla \cdot \vec{v} = -\nabla^2 \Phi$$

V cylindrické koordináty

$$\vec{v}(r, \varphi) = v_r(r, \varphi) \hat{e}_r + v_\varphi(r, \varphi) \hat{e}_\varphi$$

$$\text{R.P. } v_r(\varphi_0, \varphi) = 0 \rightarrow \frac{\partial \Phi}{\partial r}(r_0, \varphi) = 0$$

$$\vec{v}(r \rightarrow \infty, \varphi) = v_\infty \hat{e}_x \quad \Phi(r, \varphi) = -v_\infty r$$

$$\Phi(r, \varphi) = -v_\infty r \cos \varphi$$

$$\nabla \Phi = \frac{\partial \Phi}{\partial r} \hat{e}_r + \frac{1}{r} \frac{\partial \Phi}{\partial \varphi} \hat{e}_\varphi$$

Splasme reicher  $\nabla^2 \psi = 0$  u. zylindrische Koordinaten

$$\phi(r, u) = (A_0 + B_0 r u) (a_n + b_n u) + \sum_{n=1}^{\infty} (A_n r^n - r B_n \frac{1}{r^n}) (C_n \sin u \ell + D_n \cos u \ell)$$

$\Rightarrow$   $u \neq 0$

$$\phi(r \rightarrow \infty, u) = \sum_{n=1}^{\infty} A_n r^n D_n \cos u \ell = -v_0 r \cos u$$

$$A_n = 0, n \neq 1 \quad A_1 + D_1 \cos u \ell = -v_0 r \cos u$$

$$\phi(r, u) = -v_0 \cos u \ell r + \sum_{n=1}^{\infty} D_n \cos u \ell \frac{1}{r^n}$$

$$\frac{\partial \phi}{\partial r} \Big|_{R_0} = 0 = -v_0 \cos u \ell + \sum D_n \cos u \ell (-n) \frac{1}{r^{n+1}} \Big|_{R_0}$$

$$\tilde{D}_1 = -v_0 R_0$$

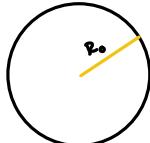
$$\Rightarrow \phi(r, u) = -v_0 \cos u \ell r - v_0 R_0 \cos u \ell \frac{1}{r}$$

$$\vec{\phi}(r, u) = -v_0 \cos u \ell \left( r + \frac{R_0}{r} \right)$$

$$\vec{v} = -\nabla \phi = -\frac{\partial \phi}{\partial r} \hat{e}_r - \frac{1}{r} \frac{\partial \phi}{\partial u} \hat{e}_u$$

$$= v_0 \left( 1 - \frac{R_0}{r^2} \right) \cos u \ell \hat{e}_r - v_0 \left( 1 + \frac{R_0}{r^2} \right) \sin u \ell \hat{e}_u$$

17) Kalku zu obreiste opne pochke pod lastu tzo



$$\nabla^2 u + \frac{f}{\gamma} = \frac{1}{c^2} \frac{\partial^2 u}{\partial t^2}$$

" stationar step "

$$\rho = \frac{dF_0}{ds} = -\frac{dH}{ds} g = -\mu g$$

$\mu$  paratielna sestota

$$\nabla^2 u = \frac{\mu g}{\gamma} \quad \text{Cylindrische Koordinaten}$$

$$u(r, u) \rightarrow u(r) \quad \text{zeroedi sinutige}$$

$$\text{R.P. } u(R_0, u) = 0$$

$$\nabla^2 u = \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) = \frac{\mu g}{\gamma}$$

$$\frac{1}{r} \frac{d}{dr} \left( r u' \right) = \frac{\mu g}{\gamma}$$

$$\int d \left( r \frac{\partial u}{\partial r} \right) = \int r \frac{\mu g}{\gamma} dr$$

R.P.  $C = 0$  na fizikalne hr

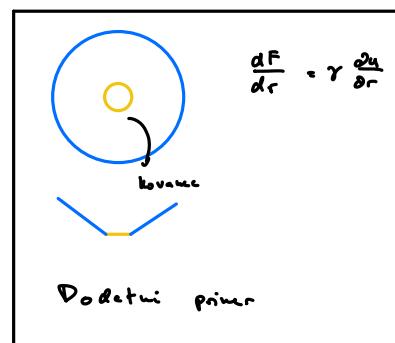
$$D = -\frac{R_0 \mu g}{\gamma}$$

$$u = \frac{\mu g}{4\gamma} (r^2 - R_0^2)$$

$$r \frac{\partial u}{\partial r} = \frac{r^2}{2} \frac{\mu g}{\gamma} + C$$

$$u = \int \frac{r^2}{2} \frac{\mu g}{\gamma} + \frac{C}{r} dr$$

$$u = \frac{r^2}{4} \frac{\mu g}{\gamma} + C \ln r + D$$

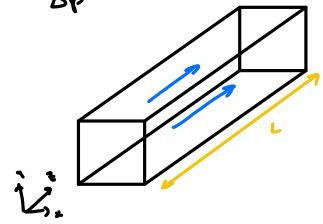


19

Partik. schwi. aus

Q ... volumensli. partik. schwi. aus?

DP



o. col w

$$q \left( \frac{\partial \vec{v}}{\partial t} \right) = q \vec{f} - \nabla p + \eta \nabla^2 \vec{v} + (s + \frac{n}{\rho}) \nabla(\rho \vec{v})$$

$$\frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \nabla) \vec{v}$$

o je viskosität

o nestrichgrenzsch.

stationär  
statisch

$$\nabla p = \begin{bmatrix} 0 \\ 0 \\ \frac{\partial p}{\partial L} \end{bmatrix}$$

$$q \left( \vec{v} \cdot \nabla \right) \vec{v} = - \frac{\partial p}{\partial z} \hat{e}_z + \eta \nabla^2 \vec{v}$$

$$\text{Sintaxis: } \vec{v} = (0, 0, v(x, y))$$

$$\text{RP: } v(z=0) = 0 \quad \text{zuordn. viskositätswert}$$

$$\text{u. } v(0, y) = v(1, y) = v(x, 0) = v(x, 1) = 0$$

$$q \left( v \approx \frac{\partial}{\partial z} (0, 0, v(x, y)) \right) = - \frac{\partial p}{\partial z} \hat{e}_z + \eta \nabla^2 (0, 0, v(x, y))$$

$$\nabla^2 \begin{bmatrix} 0 \\ 0 \\ v \end{bmatrix} = \frac{\partial^2}{\partial z^2} \begin{bmatrix} 0 \\ 0 \\ v \end{bmatrix}$$

$$z: \quad \frac{\partial v}{\partial x} + \frac{\partial v}{\partial y} = \frac{\partial p}{\partial z} \quad z(x, y) = x(u) y(v)$$

$$\text{linear. losch. verhältnis zu vel. } \nabla^2 z = -\lambda^2 z$$

$$x'' + \lambda^2 x = 0 \quad X = A \sin \lambda x + B \cos \lambda x$$

$$\text{RP: } v(0, y) = 0 \quad \text{u.}$$

$$v(1, y) = 0 \quad a \lambda_x = n \pi \quad \lambda_x = \frac{n \pi}{a}$$

$$\Rightarrow X_n = A_n \sin \frac{n \pi}{a} x$$

$$y'' + \lambda_y^2 y = 0 \quad \Rightarrow Y_m = C_m \sin \frac{m \pi}{a} y$$

$$\Rightarrow z = \sum_{n,m} \tilde{C}_{nm} \sin \frac{n \pi}{a} x \sin \frac{m \pi}{a} y$$

$$\nabla^2 z = \frac{\partial^2 z}{\partial x^2} + \frac{\partial^2 z}{\partial y^2} + \frac{\partial^2 z}{\partial z^2} = \sum_{n,m} \tilde{C}_{nm} \underbrace{\left( -\left( \frac{n \pi}{a} \right)^2 - \left( \frac{m \pi}{a} \right)^2 \right)}_{\left( -\frac{\partial^2}{\partial z^2} (n^2 + m^2) \right)} \sin \frac{n \pi}{a} x \sin \frac{m \pi}{a} y$$

$$\text{Resulution: } \nabla^2 z = \frac{\partial^2}{\partial z^2}$$

$$\left| \int_0^a \sin \frac{n \pi}{a} x dx \right|^2 \sin \frac{m \pi}{a} y dy$$

$$\sum_{n,m} \tilde{C}_{nm} \left( -\frac{\pi^2}{a^2} (n^2 + m^2) \right) \left( \frac{\pi^2}{a^2} \right) \delta_{nm} \delta_{nm} = \frac{\partial^2}{\partial z^2} \int_0^a \sin \frac{n \pi}{a} x dx \int_0^a \sin \frac{m \pi}{a} y dy$$

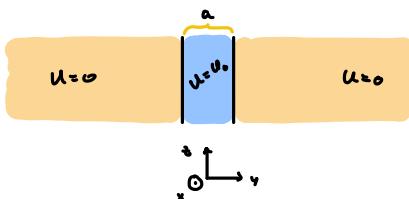
$$- \tilde{C}_{nn} \frac{\pi^2}{a^2} (n^2 + n^2) = \frac{\partial^2}{\partial z^2} \frac{a}{n \pi} (1 - \cos n \pi) \frac{a}{n \pi} (1 - \cos n \pi)$$

$$\tilde{C}_{nn} = - \frac{\partial^2}{\partial z^2} \frac{a^2}{n^2 \pi^2} \frac{1}{n^2 + n^2} (1 - (-1)^n) (1 - (-1)^n)$$

$$\rightarrow v_n(x, y) = - \frac{4 a^2 \infty}{\pi^4 L^2} \sum_{n,m} \frac{(1 - (-1)^n)(1 - (-1)^n)}{n^2 + m^2} \sin \frac{n \pi}{a} x \sin \frac{m \pi}{a} y$$

$$Q = \iiint_{\text{V}} dx dy dz v_n(x, y) \approx Q \sim \frac{a^4 \Delta p}{L^2}$$

## 19 Elektrostatisik



$$U(x, y, z) = ?$$

$$\nabla \cdot \vec{E} = \frac{\partial}{\partial x} = 0$$

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} = 0 \Rightarrow \vec{E} = -\nabla U$$

$$\Rightarrow \nabla^2 U = 0$$

R-V.

$$U(x=0, y, z) = \begin{cases} 0 & ; 1 \leq \frac{y}{z} \leq \frac{a}{2} \\ U_0 & ; 1 \leq \frac{y}{z} < \frac{a}{2} \end{cases}$$

$$U(x, y) = X(x) Y(y)$$

$$X' Y + Y' X = 0$$

$$U(x \rightarrow \infty) < \infty$$

$$\frac{x''}{x} = -\frac{Y''}{Y} = k^2$$

$$X'' - k^2 X = 0$$

$$Y'' + k^2 Y = 0$$

$$X = A e^{-kx} + B e^{kx}$$

$$Y = C e^{iky} + D e^{-iky}$$

$$X \geq 0$$

$$RPL \quad A = 0$$

Sinus-Kosinus-Anteil, sonst ist

$$X_k = B_k e^{-ikx}$$

$$Y(y) = Y(-y) \Rightarrow C = D$$

$$U(x, y) = \int_{-\infty}^{\infty} D(k) e^{-ikx} (e^{iky} + e^{-iky}) dk$$

$$C_k \quad k \mapsto -k \Rightarrow D(k) = D(-k) \Rightarrow D(k) e^{iky} + D(-k) e^{-iky} = C(k) e^{iky}$$

$$\int \int e^{iky} dy$$

$$U(x=0, y) = \int_{-\infty}^{\infty} C(k) e^{iky} dk = \begin{cases} 0 & |k| \geq \frac{a}{2} \\ U_0 & |k| < \frac{a}{2} \end{cases}$$

$$\int e^{iky} dy = 2\pi \delta(k)$$

$$= \int C(k) \delta(k - k') 2\pi dk = C(k') 2\pi$$

$$\int_{-a/2}^{a/2} e^{-ik'y} U_0 dk = \frac{U_0}{ik'} (e^{-ik' a/2} - e^{ik' a/2}) = \frac{2U_0}{ik'} \sin\left(\frac{k' a}{2}\right)$$

$$\Rightarrow C(k) = \frac{U_0 \sin\left(\frac{k a}{2}\right)}{\pi k}$$

$$\Rightarrow U(x, y) = \int_{-\infty}^{\infty} \frac{U_0 \sin\left(\frac{k a}{2}\right)}{\pi k} e^{-ikx} e^{iky} dk$$

$$= \int \frac{U_0 \sin\left(\frac{k a}{2}\right)}{\pi k} e^{-ikx} (\cos ky + i \sin ky) dk =$$

$$= 2 \frac{U_0}{\pi} \int_0^{\infty} \frac{\sin\left(\frac{k a}{2}\right)}{k} \cos ky e^{-kx} dk$$

r

$$I(z) = \frac{2U_0}{\pi} \int_0^{\infty} \sin\left(\frac{k a}{2}\right) \cos ky e^{-kz} dk$$

$$U(x, y) = \int_x^{\infty} I(z) dz \xrightarrow{\frac{d}{dx}} -I'(x) = \frac{dy}{dx}$$

$$\sin u \cos v = \frac{1}{2} (\sin(u+v) - \sin(u-v))$$

$$\int_0^{\infty} \sin ks e^{-kz} dk = \frac{s}{s^2 + z^2}$$

$$I(z) = \frac{2u_0}{\pi} \int_0^{\infty} \frac{1}{2} (\sin k(\frac{z}{2} + u) - \sin k(\frac{z}{2} - u)) e^{-ku} dz$$

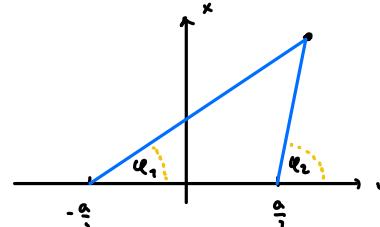
$$= \frac{u_0}{\pi} \left( \frac{\frac{z}{2} + u}{(\frac{z}{2} + u)^2 + k^2} - \frac{\frac{z}{2} - u}{(\frac{z}{2} - u)^2 + k^2} \right)$$

$$U(x, u) = - \int I dz = \frac{u_0}{\pi} \left( \arctan \frac{z}{\frac{z}{2} + u} - \arctan \frac{z}{\frac{z}{2} - u} \right) \Big|_{z=0}^x =$$

$$= \frac{u_0}{\pi} \left( \frac{\pi}{2} - \arctan \frac{x}{\frac{z}{2} + u} - \frac{\pi}{2} + \arctan \frac{x}{\frac{z}{2} - u} \right)$$

$$U(x, u) = \frac{u_0}{\pi} \left( \arctan \frac{x}{\frac{z}{2} + u} - \arctan \frac{x}{\frac{z}{2} - u} \right)$$

$$U(x_1, u_1) = -\frac{u_0}{\pi} (u_1 + u_2)$$



Nachstehend  $U(x, u) = \int_0^x c(k) e^{-ku} e^{iky} dk$

⑤ Helmholz'sche Gleichung

$$\nabla^2 f + k^2 f = 0$$

$$u_{ttt} = c^2 \nabla^2 u$$

$$u = T(t) R(r)$$

$$\frac{T''}{T} = c^2 \frac{\nabla^2 R}{R} = -\omega^2$$

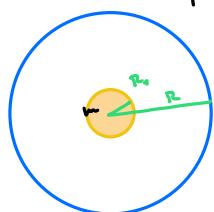
$$T = A e^{i\omega t} + B e^{-i\omega t}$$

$$\nabla^2 R + \omega^2 R = 0$$

Rechteck  $v$  zylindrischen Koordinaten

$$P(u, r) = \sum_{n=0}^{\infty} (A_n J_n(kr) + B_n Y_n(kr)) (C_n \cos \omega t + D_n \sin \omega t)$$

⑥ Osnovnoe nizhneje oprie v meso



$$\omega_0 = ?$$

$$Za mimo nizhneje veličinu možemo napisati$$

$$c^2 \nabla^2 u = u_{ttt} \quad \tilde{c} = \frac{Y}{\mu}$$

$$u(r, \theta, t) = f(r, \theta) e^{-i\omega t}$$

Osnovni nizhni  $f(r, \theta) \rightarrow f(r)$

$$Mu slike \quad \frac{dF}{dr} = \gamma \frac{du}{dr}$$

$$\text{RP} \quad u(R, \theta) = 0 \\ mu_{ttt} = 2\pi R_0 \gamma \frac{du}{dr} \Big|_{r=R_0} \quad \begin{array}{l} \text{(+) nizhni } \alpha \text{ i visoki } \\ \text{(-) nizhni } \alpha \text{ i visoki } \end{array}$$

$$c^2 \nabla^2 u = u_{ttt}$$

$$\nabla^2 f_r = \frac{1}{r} \frac{\partial}{\partial r} (r \frac{\partial f}{\partial r})$$

$$c^2 \frac{1}{r} \frac{\partial}{\partial r} (r \frac{\partial f}{\partial r}) e^{-i\omega t} = f(-\omega) e^{-i\omega t}$$

$$\omega = kc$$

$$\underbrace{\frac{1}{r} \frac{\partial}{\partial r} (r \frac{\partial f}{\partial r})}_{c^2} + k^2 f = 0$$

Neodruckn. und  
4 k 20 n=0

$$f(r) = A J_0(kr) + B Y_0(kr)$$

$$\text{TP} \quad 0 = A J_0(kR) + B Y_0(kR) \quad B = -A \frac{J_0(kR)}{Y_0(kR)}$$

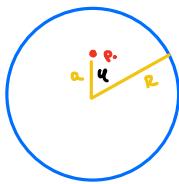
$$M(-\omega^2) (A J_0(kR) + B Y_0(kR)) e^{-i\omega t} = 2\pi R \nu Y e^{i\omega t} (A k J_1(kR) + B k Y_1(kR))$$

$$A \left( J_0(kR) - \frac{J_0(kR)}{Y_0(kR)} Y_0(kR) \right) = - \frac{2\pi R \nu Y}{\rho k c^2} A \left( J_1(kR) - \frac{J_0(kR)}{Y_0(kR)} Y_1(kR) \right)$$

Region unverändert

(2)

Boden



ob t=0 2 momentan p\_0 senkt sich auf boden, u(r, q, t)=?

$$\frac{1}{\rho} \nabla^2 u = u_{ttt}$$

$$\text{RP} \quad u(r, q, t) = 0$$

$$\text{ZP} \quad u(r, q, 0) = 0$$

$$u(r, q, 0) = \frac{c_0}{r} \delta(r-a) \delta(q) = \frac{p_0}{\sigma r} \delta(r-a) \delta(q)$$

zusätzl.  $\delta$

$$\begin{aligned} \sigma \int u r dr dq &= p_0 \\ \sigma \int \frac{c_0}{r} \delta(r-a) \delta(q) r dr dq &= p_0 \\ \sigma c_0 &= p_0 \quad c_0 = p_0 / \sigma \end{aligned}$$

$$u(r, q, t) = r(t) R(r, q)$$

$$\partial_r^2 T \nabla^2 R = \ddot{T} R$$

$$\sigma \frac{\partial^2 R}{\rho} = \ddot{T} = -\omega^2$$

$$\nabla^2 R + k^2 R = 0 \quad \ddot{T} = -\omega^2 T \quad T = A \sin \omega t + B \cos \omega t$$

$$R = \sum_{n=0}^{\infty} (A_n J_n(kr) + B_n Y_n(kr)) (C_n \cos \omega t + D_n \sin \omega t)$$

$B_n = 0$   $Y_n$  ist pol. u. nicht symmetrisch

$D_n = 0$   $k_n q \rightarrow -q$  sin. trip.

$$R = \sum_{n=0}^{\infty} E_n J_n(kr) \cos \omega t$$

$$T(r, q) = 0 = \sum_{n=0}^{\infty} E_n J_n(kr) \cos \omega t$$

$=$

$$k_{np} = \frac{s_{np}}{R} \quad p-f. \text{ mit } J_n$$

$$R(r, q) = \sum_{n,p} E_{np} J_n\left(\frac{s_{np}}{R} r\right) \cos \omega t$$

$$u(r, q, t) = \sum_{n,p} E_{np} J_n\left(\frac{s_{np}}{R} r\right) \cos \omega t (\sin \omega_{np} t + A_{np} \cos \omega_{np} t)$$

$$u(r, q, 0) = 0 \Rightarrow A_{np} = 0$$

$$\int_0^r \times J_m(\times i_{mp}) J_m(\times i_{mp}) dr = \frac{\delta p r}{2} J_{m+n}^2(i_{mp})$$

$$U(r, \theta, \phi) = \sum_n E_n J_n\left(\frac{i_{mp}}{R} r\right) \cos n\theta \quad \omega_n, \underbrace{\cos n\phi}_1 = \frac{p_0}{\sigma r} \delta(r-a) \delta(\theta)$$

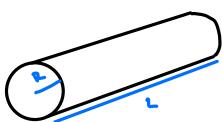
$$\therefore \int_0^R r J_n\left(\frac{i_{mp}}{R} r\right) dr \int_0^{2\pi} \cos n\theta$$

$$\frac{p_0}{\sigma} \frac{n J_n\left(\frac{i_{mp}}{R} a\right)}{a} = \sum_n \pi E_n \frac{\delta p r}{2} J_{m+n}^2(i_{mp}) \delta_{mn}$$

$$\frac{p_0}{\sigma} J_n\left(\frac{i_{mp}}{R} a\right) = \pi E_{n,p} \frac{1}{2} J_{m+n}^2(i_{mp}) R^2 \omega_n,$$

$$E_{n,p} = \frac{2p_0}{\sigma \pi R^2 \omega_n} \frac{J_n\left(\frac{i_{mp}}{R} a\right)}{J_{m+n}^2(i_{mp})}$$

(22) Praktik shohi atmosfer cov



$$v_r, v_\theta$$

- a)  $\nabla p$
- b)  $\nabla p e^{i\omega t}$

metrische \(\nabla v\)

$$g_i \left( \frac{\partial v}{\partial x^i} + (\vec{v} \cdot \vec{\nabla}) v \right) = -\nabla p + \eta \nabla^2 v + g \hat{F}$$

stetig 0

$$\text{Simplifiziert } \vec{v} = \vec{v}(r, t) = (v_r, v_\theta, v_z(r, t)) = \hat{e}_r v_r(r, t)$$

$$\nabla p = (0, 0, \frac{\partial p}{L})$$

$$\nabla p \quad \nabla p(R, \theta, t) = 0$$

④

$$\frac{\partial p}{L} = \eta \nabla^2 v_z(r)$$

$$\frac{\partial p}{L} = \frac{1}{r} \frac{\partial}{\partial r} r \frac{\partial v_z}{\partial r}$$

$$\int \frac{\partial p}{L} r dr = r \frac{\partial v_z}{\partial r}$$

$$\int \frac{\partial p}{L} r + \frac{C}{r} dr = v_z$$

$$v_z = \frac{Dp}{4L\eta} r^2 + C \ln r + D$$

linear division r \(\rightarrow 0\)

$$\text{R.P.} \quad D = \frac{Dp R^2}{4L\eta} \rightarrow 0 \quad D = -\frac{Dp R^2}{4L\eta}$$

$$v_z = \frac{Dp}{4L\eta} (r^2 - R^2)$$

$$\text{b) } 3 \frac{\partial v_z}{\partial t} = -\frac{Dp}{L} e^{i\omega t} + \eta \nabla^2 v_z$$

$$v_z = \bar{v}_z(r) e^{i\omega t}$$

$$i\omega g R e^{i\omega t} = -\frac{Dp}{L} e^{i\omega t} + \eta e^{i\omega t} \nabla^2 R$$

$$\nabla^2 R - \frac{i\omega g}{\eta} R = \frac{Dp}{L\eta}$$

$$\tilde{w}^2 = -\frac{i\omega g}{\eta}$$

$$\nabla^2 R + k^2 R = \frac{Dp}{L\eta}$$

$$SPL \sim \text{width} \quad \Omega = R_{\text{max}} + R_{\text{min}}$$

## Homogenes rechteck

$$\nabla^2 R_u + h^2 R_u = 0$$

Wurzeln  $R$  in funk.  $\Omega \rightarrow$  keiner pri.  $m=0$  oszilliert

$$R_+(r) = A J_0(hr) + B Y_0(hr)$$

$\stackrel{!}{\rightarrow}$  divergen  $\rightarrow r \rightarrow 0$

Durchkanten rechteck

$$R_0 = C$$

$$0 + h^2 C = \frac{\Delta p}{L_h} \quad C = \frac{\Delta p}{L_h h^2}$$

$$\Rightarrow R = A J_0(hr) + \frac{\Delta p}{L_h h^2} = A J_0(hr) + \frac{\Delta p i}{g_{WL}}$$

PP

$$R(r, t) = 0$$

$$0 = A J_0(hr) + \frac{\Delta p i}{g_{WL}}$$

$$A = -\frac{\Delta p i}{g_{WL} J_0(hr)}$$

$$v_z(r, t) = \operatorname{Re} \left( e^{i\omega t} \frac{\Delta p i}{g_{WL}} \left( 1 - \frac{J_0(hr)}{J_0(hr)} \right) \right) \quad h^2 = -\frac{i\omega^2}{\eta}$$

$$J_0(ax) = 1 - \frac{a^2 x^2}{4} + O(x^4)$$

zu meiste k. oz. w. das sind exakte rechteck kant v.  $\textcircled{c}$

(u)

(e)

$$\boxed{T_0}$$

Tv

$$\nabla^2 T = \frac{dT}{dt}$$

$$T|_{\partial D} = T_v$$

$$T(x, y, z, t) = ?$$

$$\tilde{T} \rightarrow T - T_v \quad \tilde{T}|_{\partial D} = 0$$

$$T = X Y Z \sim(t)$$

$$\frac{x''}{x} + \frac{y''}{y} + \frac{z''}{z} - \frac{1}{\alpha} \frac{z'}{z} = -\lambda^2 = -\lambda_x^2 - \lambda_y^2 - \lambda_z^2$$

$$\sim(t) = A e^{-t \lambda^2}$$



$$\frac{x''}{x} = -\lambda_x^2$$

$$x = B \sin \lambda_x x + C \cos \lambda_x x$$

$$\sin \lambda_x a = 0 \quad \lambda_x a = n\pi$$

$$\lambda_x = \frac{n\pi}{a}$$

$$\Rightarrow T = \sum_{n \in \mathbb{Z}} c_{n \in \mathbb{Z}} \sin \frac{n\pi}{a} x \sin \frac{n\pi}{a} y \sin \frac{n\pi}{a} z e^{-\frac{n^2}{a} (\omega^2 + \omega_x^2 + \omega_y^2)} e^{i n \omega t}$$

$$T(t=0) = T_0 - T_v = \sum_{n \in \mathbb{Z}} c_{n \in \mathbb{Z}} \sin \frac{n\pi}{a} x \sin \frac{n\pi}{a} y \sin \frac{n\pi}{a} z$$

$$c_{n \in \mathbb{Z}} = (T_0 - T_v) \left(\frac{2}{\pi}\right)^3 \left(\frac{a}{\pi}\right)^3 \frac{1}{n \in \mathbb{Z}} (1 - (-1)^n)(1 - (-1)^n)(1 - (-1)^n)$$

$$\int_0^a \sin \frac{n\pi}{a} x dx$$

$$T = T_0 + c_{\text{even}} \sin \frac{\pi}{a} x \sin \frac{\pi}{a} y \sin \frac{\pi}{a} z e^{-j k_0 (\frac{\pi}{a})^2}$$

④  $-\lambda \frac{\partial T}{\partial z} = j$        $\nabla^2 T = 0$   
 $T_{00} = T_0 \rightarrow 0$        $T = X \times Y \times Z$

$$\frac{x''}{x} + \frac{y''}{y} = -\frac{z''}{z} = -\lambda_u^2 - \lambda_w^2 = -(\frac{\pi}{a})^2 (u^2 + w^2)$$

$$X = \sin \frac{n\pi}{a} x \quad Y = \sin \frac{m\pi}{a} y$$

$$Z'' = -(\frac{\pi}{a})^2 (u^2 + w^2)$$

$Z = A_{uw} \sin \frac{\pi}{a} \sqrt{u^2 + w^2} z + B_{uw} \cosh \frac{\pi}{a} \sqrt{u^2 + w^2} z$

$$T(x, y, z) = \sum_{u,w} c_{uw} \sin \frac{n\pi}{a} x \sin \frac{m\pi}{a} y \sin \frac{\pi}{a} \sqrt{u^2 + w^2} z$$

$$-\lambda \frac{\partial T}{\partial z} \Big|_a = j$$

$$-\frac{j}{\lambda} = \sum_{u,w} c_{uw} \frac{\pi}{a} \sqrt{u^2 + w^2} \sin \frac{n\pi}{a} x \sin \frac{m\pi}{a} y \cosh \left( \frac{\pi}{a} \sqrt{u^2 + w^2} a \right)$$

$$- \frac{(l-m-n)(l+m)}{n!m!} \frac{j}{\lambda} \left( \frac{\pi}{a} \right)^2 c_{u,w} \frac{\pi}{a} \sqrt{u^2 + w^2} \left( \frac{a}{z} \right)^2 \cosh \left( \frac{\pi}{a} \sqrt{u^2 + w^2} a \right)$$

⑤ Helmholtzové rovnice v sférických koordinátoch

$$\nabla^2 f + \lambda f = 0 \quad f = R(r) Y_l(\theta, \phi)$$

$$\nabla^2 f = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial f}{\partial r} \right) - \frac{l^2}{r^2} f \quad L^2 = -\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial}{\partial \theta} \right) - \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2}$$

$$L^2 Y_l(\theta, \phi) = l(l+1) Y_l(\theta, \phi)$$

$$Y_l = \sqrt{\frac{(2l+1)}{4\pi} \frac{(l-m)!}{(l+m)!}} P_l^m(\cos \theta) e^{im\phi}$$

$$\int_0^\pi d\theta \int_0^\pi d\cos \theta \quad Y_l^{l'} Y_l^{l''} = \delta_{ll'} \delta_{mm'}$$

$$r: \quad \frac{1}{r^2} \frac{\partial^2}{\partial r^2} \left( r^2 \frac{\partial f}{\partial r} \right) - \frac{l(l+1)}{r^2} f + \lambda f = 0$$

$$R(r) = A j_l(\sqrt{\lambda} r) + B y_l(\sqrt{\lambda} r)$$

$j_l$   
sferická  
Besselova  
funkcia

$y_l$   
sferická  
Neumannova  
funkcia

$$j_l(r) = \sqrt{\frac{\pi}{2r}} J_{l+\frac{1}{2}, l}(r) \quad y_l(r) = \sqrt{\frac{\pi}{2r}} Y_{l+\frac{1}{2}, l}(r)$$

$$j_0 = \frac{\sin x}{x} \quad y_0 = -\frac{\cos x}{x}$$

Orthogonalita  $\Rightarrow$   $\int_0^\infty r^2 j_0(r) y_0(r) dr = 0$

$$\partial_r j_0 = 0$$

$$\nabla^2 f = 0$$

$$R(r) = A_2 r^2 + B_2 \frac{1}{r^2}$$

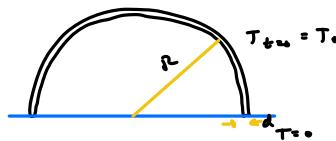
$$P_n(x) = \frac{1}{2^n n!} \frac{d^n}{dx^n} (x^2 - 1)^n$$

$$\int_0^\pi P_n(\cos \theta) P_m(\cos \theta) d\cos \theta = \frac{2}{2n+1} \delta_{nm}$$

$$P_0 = 1 \quad P_1 = x \quad P_2 = \frac{1}{2}(3x^2 - 1)$$

(23)

Polkugelna lösung



dCR

$T(i, t) = ?$

$\nabla^2 T = \frac{\partial^2 T}{\partial r^2}$

$\frac{\nabla^2 \Theta}{\Theta} = \frac{1}{r^2} \frac{\pi^2}{\lambda^2} = -\lambda$

$T = T(\theta) \quad \text{h. j. o. k.}$   
 $= \Theta(\theta) \tau(t) \quad \text{in der symmetrie}$

$\nabla^2 \Theta + \lambda \Theta = 0$

$\tau = A e^{-D \lambda t}$

$\Theta(\theta) \sim P_l^0(\cos \theta)$

$T = \sum_{l=0}^{\infty} A_l P_l^0(\cos \theta) e^{-D \frac{l(l+1)}{r^2} t}$

$\text{P.P. } T(\pm \frac{\pi}{2}, t) = 0$

$0 = \sum_l A_l P_l^0(0) e^{-D \frac{l(l+1)}{r^2} t}$

lösung mit  $P_l^0(0)$ 

Von links oben im Bild ist es wichtig zu wissen.

 $\Rightarrow$  Von links unten ist es auch 0.

$\text{Z.B. } T(\theta, 0) = T_0$

$T_0 = \sum_{l=0}^{\infty} A_l P_l^0(\cos \theta) \quad / \int_0^\pi P_l^0(\cos \theta) d \cos \theta$

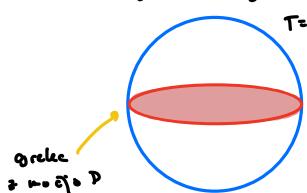
$T_0 \int_0^\pi P_l^0(\cos \theta) d \cos \theta = \sum_{l=0}^{\infty} \int_0^\pi A_l P_l^0(\cos \theta) P_l^0(\cos \theta) d \cos \theta$   
links links  $\Rightarrow$  sod.  $\Rightarrow \int_0^\pi = \int_0^\pi$

$T_0 \int_0^\pi P_l^0(\cos \theta) d \cos \theta = \frac{2}{2l+1} \frac{1}{2} A_l$

Für  $l=0$  zu weiteren folgen dasselbe eben ja h. d.  $l=1$ 

$T_0 \int_0^\pi x d\theta = \frac{A_1}{2}$

$\frac{2}{2} T_0 = A_1 \quad T = \frac{2T_0}{2} \cos \theta e^{-\frac{2D}{r^2} t}$

(24) Kugel  $\approx$  grüßenstationär:  $T = ?$ 

$\nabla^2 T + \frac{g}{g_{CP}} = 0$

$\nabla^2 T = -\frac{g(r)}{g_{CP} D}$

$g(r) = g_0 \cdot \sigma(r) = g_0 \frac{\sigma(\cos \theta)}{r^2} =$

$= g_0 \frac{\sigma(\cos \theta)}{r}$

$$P = \int g_0 dV = g_0 \iiint_{r=0}^R \frac{r^2 dr d\theta}{r} d(\cos\theta) \delta(\cos\theta)$$

$$= g_0 \frac{R^3}{3} 2\pi \cdot 1$$

$$g_0 = \frac{P}{\pi R^3}$$

Symmetrie:  $T = T(r, \theta) \Rightarrow m = 0$

$$T = \sum_l (A_l j_l (\lambda r + \beta_l \gamma_l \ln r) P_l (\cos\theta))$$

divergiert für  $r \rightarrow 0$

R.P.:  $T(r=R, \theta) = 0$

$$0 = \sum_l A_l j_l (\underbrace{\lambda R}_{=0}) P_l (\cos\theta)$$

$$\lambda = \frac{s_{l,n}}{R^2}$$

unterteilt nach

$$\Rightarrow T = \sum_{l,n} A_{l,n} j_{l,n} \left( \frac{s_{l,n}}{R} \right) P_l (\cos\theta)$$

Merkmales  $j_{l,n}$  zu den Skalaren  $\rho_{l,n}$  führt:  $\nabla^2 T = - \frac{\rho_{l,n}}{D g_0}$

$$\nabla^2 T = -\lambda T = -\sum_{l,n} \frac{s_{l,n}^2}{R^2} A_{l,n} j_{l,n} \left( \frac{s_{l,n}}{R} \right) P_l (\cos\theta) = -\frac{\rho_{l,n}}{D g_0} \frac{\partial^2 (r \cos\theta)}{\partial r^2}$$

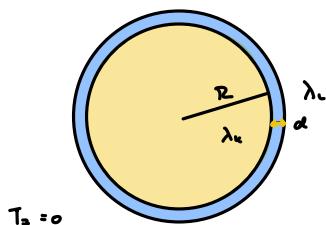
$$A_{l,n} = \frac{s_{l,n}^2}{R^2} \frac{2}{2l+1} \int_0^R j_{l,n} \left( \frac{s_{l,n}}{R} r \right) j_{l,n} \left( \frac{s_{l,n}}{R} r \right) r^2 dr = \frac{\rho_{l,n}}{D g_0} \int_0^1 \delta(\cos\theta) P_l (\cos\theta) d(\cos\theta) \int_0^R j_{l,n} \left( \frac{s_{l,n}}{R} r \right) r^2 dr$$

$$P_l(0) \quad \int_0^R j_{l,n} \left( \frac{s_{l,n}}{R} r \right) r^2 dr$$

$$A_{l,n} = \frac{P(2l+1)}{\lambda_{l,n} R^2 \pi^2 D g_0} \frac{P_l(0)}{2} \int_0^R r^2 j_{l,n} \left( \frac{s_{l,n}}{R} r \right) dr$$

(25) Kugel mit Innenkern

$d \ll R$   $T \approx$  folgen Zähle



$$T(z, t) \rightarrow T(r, t) \quad t \gg 1$$

$$\text{RP. } j \Big|_{r=r} = \lambda_L \frac{(T(R, t) - 0)}{d} \quad \text{tut sich hierbei}$$

$$j \Big|_{r=R} = -\lambda_L \frac{\partial T}{\partial r} \Big|_{r=R}$$

$$T(R, t) = -\frac{\lambda_L d}{\lambda_L} \frac{\partial T}{\partial r} \Big|_{r=R}$$

$$\frac{\partial T}{\partial t} = D \nabla^2 T \quad T = \tau(t) f(r)$$

$$\frac{1}{\theta} \frac{d\tau}{dt} = \frac{D^2 f}{r^2} = -\omega^2$$

$$\nabla^2 f + k^2 f = 0$$

$$r' = -k^2 d t$$

$$f = A j_0(kr) + B Y_0(kr)$$

$\downarrow$  diverges  $\propto r \rightarrow 0$

$$r' = e^{-k^2 dt}$$

$$T(r, t) = A j_0(kr) e^{-k^2 dt}$$

$$j_0(x) = \frac{\sin x}{x}$$

$$\text{RP. } A \frac{\sin kr}{kr} \Big| e^{-k^2 dt} = - \frac{\lambda_h d}{\lambda_L} \frac{1}{kr} \left( \frac{k \cos kr}{r} - \frac{\sin kr}{r^2} \right) \Big|_{r=2} e^{-k^2 dt} A$$

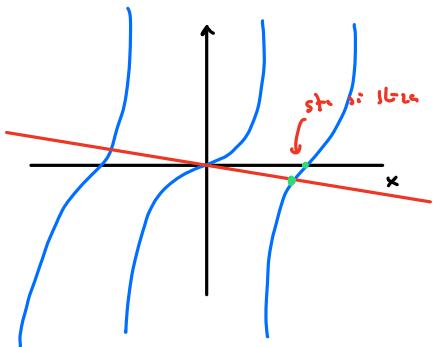
$$\sin kr = - \frac{\lambda_h d}{\lambda_L} (k R \cos kr - \sin kr)$$

$$\tan kr \left( 1 - \frac{\lambda_h d}{\lambda_L R} \right) = - \frac{\lambda_h d}{\lambda_L} \frac{1}{R} k R$$

$$\tan kr = \frac{1}{-\frac{\lambda_h R}{\lambda_L d} \frac{1}{k R} + \frac{1}{k R}}$$

$$\tan kr = \frac{1}{1 - \frac{\lambda_h R}{\lambda_L d}} \frac{1}{k R}$$

$d \ll r$



$$(1 - \frac{1}{d}) \tan x = x$$

$$x = kR$$

$$\text{mögliche Werte} \Rightarrow k$$

## ① Greenova funkcija

$$\mathcal{L} u(\tau) = f(\tau)$$

$$\mathcal{L} G(\tau, \tau_0) = \delta(\tau - \tau_0)$$

↳ linearni operator

$$\text{Rešenje: } u(\tau) = \int G(\tau, \tau_0) f(\tau_0) d^3 \tau_0$$

$$\text{Laplace } \mathcal{L} = \nabla^2$$

2D

$$G = \frac{1}{2\pi} \ln |\tau - \tau_0|$$

3D

$$G = -\frac{1}{4\pi} \frac{1}{|\tau - \tau_0|}$$

$$\text{Hanklove funkcija} \quad H_d^{(n,s)} = \int_d \frac{1}{z} i^n Y_s$$

$$\text{Helmholz } \mathcal{L} = \nabla^2 - k^2$$

2D

$$G = \begin{cases} -\frac{i}{k} H_0^{(1)}(k|\tau - \tau_0|) & \text{upodni valovi} \\ \frac{i}{k} H_0^{(2)}(k|\tau - \tau_0|) & \text{valovi unazad} \\ \frac{1}{k} Y_0(k|\tau - \tau_0|) & \text{stoperi valovi} \end{cases}$$

3D

$$G = \begin{cases} \frac{1}{4\pi |\tau - \tau_0|} e^{\pm ik|\tau - \tau_0|} & \text{potrebiti valovi} \\ \frac{e^{ik|\tau - \tau_0|}}{2\pi |\tau - \tau_0|} & \end{cases}$$

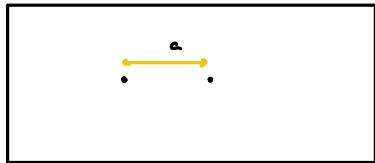
$$\text{Di funzije } \mathcal{L} = \frac{\partial}{\partial t} - D \nabla^2$$

$$G = H(t) \left( \frac{1}{4\pi D t} \right)^{n/2} e^{-|\tau - \tau_0|^2 / 4Dt}$$

N-dim

2G

Membrane



$$\text{Totale Verzerrung} = e^{i\omega t}$$

$$u(r \rightarrow \infty, t) = ?$$

$$u_{ttt} = c^2 \partial^2 u + \underbrace{f(\vec{r}, t)}_{\text{verzerrung}}$$

$$f(\vec{r}, t) = A_0 \frac{(\delta^2(\vec{r} - (0, 0)) - \delta^2(\vec{r} - (a, 0)))}{F(z)} e^{i\omega t}$$

$$\nabla \cdot \text{dichten} \quad u = R(\vec{r}) e^{i\omega t}$$

$$(i\omega)^2 R e^{i\omega t} = c^2 \partial_z^2 R + F e^{i\omega t}$$

$$\Rightarrow \partial_z^2 R + k^2 R = -\frac{F}{c^2} \quad | \text{ Helmholtz}$$

$$-\frac{A_0}{c^2} \underbrace{(G(\vec{r}, (0, 0)) - G(\vec{r}, (a, 0)))}_{\text{antiforce}} = -\frac{A_0}{c^2} (\delta^2(\vec{r} - (0, 0)) - \delta^2(\vec{r} - (a, 0)))$$

$$\Rightarrow R = -\frac{A_0}{c^2} (G(\vec{r}, (0, 0)) - G(\vec{r}, (a, 0)))$$

$$(1+x)^2 = 1 + 2x$$

$$= -\frac{A_0 i}{4c^2} \left( H_0^{(1)}(k \underbrace{\sqrt{x^2 + a^2}}_{\sqrt{x^2 + k^2}}) - H_0^{(1)}(k \underbrace{\sqrt{(\vec{r}-\vec{a})^2 + q^2}}_{\sqrt{(x-a)^2 + q^2}}) \right)$$

$$= \sqrt{(x^2 + a^2)} \left( 1 - \frac{2x a}{x^2 + a^2} + \frac{1}{x^2 + a^2} \right)$$

$$= r \left( 1 - \frac{2a}{r^2} \right)$$

$$-\frac{A_0 i}{4c^2} \underbrace{(H_0^{(1)}(kr) - H_0^{(1)}(kr(1 - \frac{2a}{r^2})))}_{H_0^{(1)}(kr) \left( -kr \frac{2a}{r^2} \right)}$$

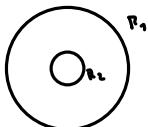
$$\frac{d}{dt} H_n^{(1)}(z) = \frac{i H_n^{(1)}(z)}{z} - H_{n+1}^{(1)}(z)$$

$$H_n^{(1)}(z) \sim (-i)^n \frac{e^{-iz}}{z}$$

$$R = \frac{A_0 i x a k}{c^2 r} H_0^{(1)}(kr) \doteq \frac{A_0 x a}{4c^2 r^2} e^{-ikr}$$

$$u(r, \varphi, t) = \frac{A_0 a}{4c^2} \frac{\cos \varphi}{r} e^{i(\omega t - kr)}$$

(K)



$$\frac{\partial u}{\partial r} = c^2 \partial^2 u$$

$$u(r, \varphi, t) = f(r, \varphi) e^{i\omega t}$$

$$-\omega^2 f = c^2 \partial^2 f$$

$$\nabla^2 f + k^2 f = 0 \quad k = \frac{\omega}{c}$$

$$\text{RP.} \quad u(r_1, \varphi, t) = 0$$

$$0 = m u_{ttt} \Big|_{r=r_1} = 2\pi R_1 \frac{\partial u}{\partial r} \Big|_{r=R_1} \Rightarrow \frac{\partial u}{\partial r} \Big|_{r=R_1} = 0$$

$$u = \sum_m (A_m J_m(k_r r) + D_m Y_m(k_r r)) (C_m \cos \omega t + D_m \sin \omega t)$$

$$\text{RP.} \quad A_m J_m'(k_r r_1) + D_m Y_m'(k_r r_1) = 0$$

$$A_m k_r J_m'(k_r r_1) + D_m k_r Y_m'(k_r r_1) = 0$$

$$B_m = -A_m \frac{J_m(k_r r_1)}{Y_m'(k_r r_1)}$$

$$\underbrace{\begin{bmatrix} J_m & Y_m \\ J_m' & Y_m' \end{bmatrix}}_M \begin{bmatrix} A_m \\ D_m \end{bmatrix} = 0$$

$$\det M = 0 \Rightarrow J_m(k_m R_n) Y_m'(k_m R_n) = J_m'(k_m R_n) Y_m(k_m R_n)$$

$k_{m,n}$

$$u = \sum_{m=0}^{\infty} \sum_{n=0}^{\infty} A_{mn} \left( J_m(k_m r) - \frac{J_m(k_m R_n)}{Y_m(k_m R_n)} Y_m(k_m r) \right) (C_m \cos \omega t + D_m \sin \omega t)$$

(b)

$$m=0$$

$$k_0 R_n = \xi_{0n}$$

$$\omega_0 = \frac{\xi_{0n}}{R_n} c = 562 \text{ Hz}$$

(c)

$$R_2 \ll R_1 \quad m=0$$

$$\det M \approx 0 \Rightarrow J_0(k_0 R_n) Y_0(k_0 R_2) = Y_0(k_0 R_n) J_0(k_0 R_2)$$

$$k_0 R_n = \xi_{0n} + \Delta k R_n$$

$$J_0(\xi_{0n} + \Delta k R_n) = Y_0(\xi_{0n} + k_0 R_n) \frac{J_0(\xi_{0n} \frac{R_n}{R_2} + \Delta k R_n)}{Y_0(\xi_{0n} \frac{R_n}{R_2} + \Delta k R_n)}$$

$$J_0(\xi_{0n}) + J_0'(\xi_{0n}) \Delta k R_n = (Y_0(\xi_{0n}) + \dots) \frac{\frac{1}{2} \xi_{0n} \frac{R_n}{R_2}}{\frac{1}{2} \xi_{0n} \frac{R_n}{R_2}}$$

$$\Delta k R_n = \frac{\xi_{0n}^2 \pi}{4} \left( \frac{R_n}{R_2} \right)^2 \frac{Y_0(\xi_{0n})}{J_0(\xi_{0n})}$$

$$\Delta \omega = \Delta k c = \frac{\xi_{0n}^2 \pi}{4} c \frac{R_n^2}{R_2^2} \frac{Y_0(\xi_{0n})}{J_0(\xi_{0n})} = 17.9 \text{ Hz}$$

(T) Greenove funkcijske na končni domeni

$$\mathcal{L} G(\vec{r}, \vec{r}_0) = \delta(\vec{r} - \vec{r}_0)$$

Greenove identitete

$\frac{\partial}{\partial \vec{n}}$  ad

$$\int_D u \nabla^2 v - u \nabla^2 v \, dV = \oint_{\partial D} u \frac{\partial v}{\partial \vec{n}} - v \frac{\partial u}{\partial \vec{n}} \, d\vec{s}$$

smerni  
odnos v  
smerni normale

$$\mathcal{L} f = \nabla^2 f = 0$$

zabej:

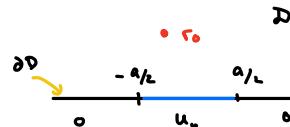
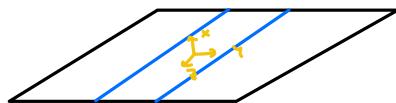
$$G_\infty \rightarrow G|_{\partial D} = 0, \text{ da } u \rightarrow f, v \rightarrow G$$

$$\int_D G \nabla^2 f - f \nabla^2 G \, dV = \oint_{\partial D} G \frac{\partial f}{\partial \vec{n}} - f \frac{\partial G}{\partial \vec{n}} \, d\vec{s}$$

" in reha

$$f(\vec{r}) = \oint_{\partial D} f(\vec{r}_0) \frac{\partial G(\vec{r}, \vec{r}_0)}{\partial \vec{n}_0} \, d\vec{s}$$

27



nachleitende trah

$U(x=3a/4, z) = ?$

• trapeziale

$RP \quad U(0, y, z) = \begin{cases} u_0 & |y| < \frac{a}{2} \\ 0 & |y| > \frac{a}{2} \end{cases}$

$\nabla^2 U = 0$

$U(x, y, z) \rightarrow U(x, y)$

Grenzen zu Laplacean v 2D

$G_{xy} = \frac{1}{\pi} \ln |z - z_0|$

$G(x, y, x_0, y_0) = \frac{1}{2\pi} \ln |(x - x_0) - (y - y_0)| - \frac{1}{2\pi} \ln |(x + x_0) - (y + y_0)|$

$= \frac{1}{4\pi} \ln \frac{(x - x_0)^2 + (y - y_0)^2}{(x + x_0)^2 + (y + y_0)^2}$

$f(z) = \oint_D f(z_0) \frac{\partial G(z, z_0)}{\partial \bar{z}} dz$

$u(z) = \int_{-\infty}^{\infty} U(0, y_0) (-1) \frac{\partial G(x, y_0, x_0, y_0)}{\partial x_0} \Big|_{x_0=0} dy_0 = \dots$

$$\begin{aligned} \frac{\partial G}{\partial x_0} \Big|_{x_0=0} &= \dots = \frac{1}{4\pi} \frac{-4x}{x^2 + (y - y_0)^2} \\ &\dots = + \int_{-a/2}^{a/2} u_0 \frac{1}{\pi} \frac{x}{x^2 + (y - y_0)^2} dy_0 = \frac{u_0}{\pi} \int_{\frac{y-y_0}{x}}^{\frac{y+y_0}{x}} \frac{1}{1+t^2} dt = \frac{u_0}{\pi} \arctan z = \\ &\times dt = - dy_0 \\ &= \frac{u_0}{\pi} \left( \arctan \frac{y_0 - y}{x} + \arctan \frac{y_0 + y}{x} \right) \end{aligned}$$

① Laplace v 2D

$\nabla^2 f = 0 \quad \text{Harmonische Funktionen}$

$g(x, y) = u(x, y) + i v(x, y)$

⇒ holomorphe  $\Leftrightarrow$  Cauchy-Riemann-Gleichungen

$u_x = v_y$

$u_y = -v_x$

$\nabla^2 u = u_{xx} + u_{yy} = v_{xy} - v_{yx} = 0$

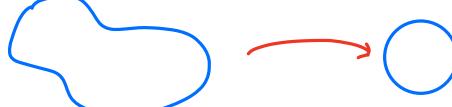
$\nabla^2 v = v_{xx} + v_{yy} = -u_{xy} + u_{yx} = 0$

Konformität invarianz



Riemann steht zu problem

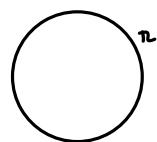
Vsaké pôsobenie pouzrelo oderte možnosti v C rovnako je kôľko konformné presliskat v obojt kres.



Möbiusova peruková  $f: \mathbb{C} \cup \{\infty\} \rightarrow \mathbb{C} \cup \{\infty\}$

$$f(z) = \frac{az + b}{cz + d} \quad ad - bc \neq 0$$

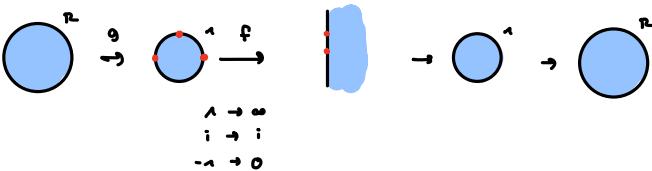
29) Greenova funkcia Laplaceova chyba u. trouhy



$$\nabla^2 G(\vec{r}, \vec{r}_0) = \delta(\vec{r} - \vec{r}_0)$$

$$G|_{|\vec{r}|=R} = \text{konst}$$

$$G(\vec{r}, \vec{r}_0) = ?$$



$$g(z) = \frac{z}{R}$$

$$c+d=0 \quad c=-d$$

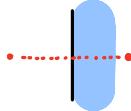
$$-a+b=0 \quad a=b$$

$$i = \frac{ai+b}{ci+d} > \frac{a(i+\alpha)}{c(i-\alpha)}$$

$$a = i c \frac{(i-\alpha)}{(i+\alpha)} = ci \frac{(i-\alpha)(-i+\alpha)}{2} = \\ = c \frac{i}{2} (1 + i + i - \alpha) = -c$$

$$\Rightarrow f = \frac{az+b}{cz+d} = \frac{a(z+\alpha)}{c(z-\alpha)} = -\frac{z+\alpha}{z-\alpha} = \frac{1+z}{1-z}$$

Iskalo Greenova funkcia  $\tilde{G}_{\infty}$ .



$$\tilde{G}(\vec{r}, \vec{r}_0) = \frac{1}{2\pi} \ln \left| \frac{\vec{r} - \vec{r}_0}{\vec{r} - \vec{r}'_0} \right| \quad \vec{r}_0 = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} \quad \vec{r}'_0 = \begin{pmatrix} -x_0 \\ y_0 \end{pmatrix}$$

$$f \circ g(O^R) = | \quad g^{-1} \circ f^{-1}(|) = O^R$$

$$f^{-1}: \quad z = \frac{1+u}{1-u} \quad (1-u)z = 1+u \\ u = \frac{z-1}{z+1}$$

$$(a, 0) \quad (a_0, 0) \\ \downarrow f \circ g \quad \uparrow (f \circ g)^{-1} \\ (x_0, y_0) \xrightarrow{\text{zrccejtej}} (-x_0, y_0)$$

:

$$G^{(0)}(\vec{r}, a, 0) = G_\infty(\vec{r}, (a, 0)) - G_\infty(\vec{r}, (\frac{R^2}{a}, 0))$$

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## Difuzija na konačnom intervalu

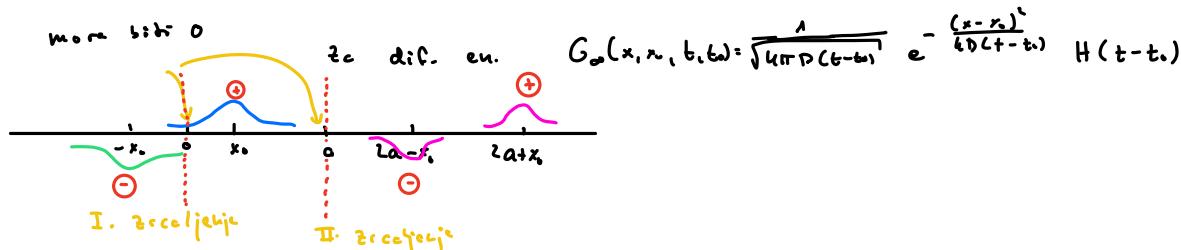
$$0 \leq x \leq a$$

$$\frac{\partial T}{\partial t} = D \frac{\partial^2 T}{\partial x^2}$$

$$T(0, t) = T(a, t) = 0$$

$$T(x_0, 0) = \delta(x - x_0)$$

$$T(x, t) = ?$$



... zrcaljenje ponavlja se nekonačno brojputa

Poziceje

$$+ x_0 + n 2a$$

$$- x_0 + m 2a$$

$$G = \sum_{n=-\infty}^{\infty} G_n(x, x_0 + n 2a, t, t_0) - \sum_{m=-\infty}^{\infty} G_m(x, -x_0 + m 2a, t, t_0)$$

$$= \frac{1}{\sqrt{4\pi D(t-t_0)}} H(t-t_0) \sum_{n=-\infty}^{\infty} e^{-[(x-x_0-2na)^2 - (x+x_0-2na)^2] / 4D(t-t_0)}$$

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Lloydovo zrcalo



gladina vode

početna energija teh

$$\bar{j}(\vec{r}) := \text{te} \quad \vec{r} + \infty$$

- izvor gde je  $\vec{z} = \vec{a}$
- s počekom  $w$

$$\frac{1}{c^2} \frac{\partial^2}{\partial t^2} \delta p = \nabla^2 \delta p + A \delta(\vec{r} - a \hat{e}_z) e^{i \omega t}$$

$$\delta p = P(\vec{r}) e^{i \omega t}$$

$$-\frac{\omega^2}{c^2} \frac{\partial^2}{\partial t^2} P = \nabla^2 P + A \delta(\vec{r} - a \hat{e}_z)$$

Helmholzova

enavija

$$P(\vec{r}) = 0 \quad \text{ne gladini konstante H.H.}$$

① Akustika

stiskivo, neviskozno

$$\rho \frac{\partial u}{\partial t} = -\nabla p$$

$$\frac{\partial q}{\partial t} + \nabla \cdot (\vec{v} q) = 0$$

majke perturbacije

$$p(\vec{r}, t) = p_0 + \delta p(\vec{r}, t)$$

$$q(\vec{r}, t) = q_0 + \delta q(\vec{r}, t)$$

Adiabatska relacija

$$\frac{\delta q}{q_0} = K, \quad \delta p$$

$$\Rightarrow \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \delta p = \nabla^2 \delta p \quad c^2 = \frac{1}{\rho_0 K}$$

$$\text{časova} \quad \tilde{j} = \frac{1}{i} \operatorname{Re}(\delta p \vec{v}^*)$$

kompleksno

$$\begin{array}{c} \bullet \quad \circ \\ \hline \circ \quad \bullet \end{array}$$

$$\text{2. Hel.} \quad G_\infty(\vec{r}, \vec{r}_0) = -\frac{1}{4\pi i(\vec{r}-\vec{r}_0)} e^{i k |\vec{r}-\vec{r}_0|}$$

$$\Rightarrow P(\vec{r}) = -A G_\infty(\vec{r}, a \hat{e}_z) + A G_\infty(\vec{r}, -a \hat{e}_z)$$

$$P(\vec{r}) = A \frac{e^{i k (\vec{r} - a \hat{e}_z)}}{4\pi i(\vec{r} - a \hat{e}_z)} - A \frac{e^{i k (\vec{r} + a \hat{e}_z)}}{4\pi i(\vec{r} + a \hat{e}_z)}$$

$$\vec{r}^\pm = |\vec{r} \pm a \hat{e}_z| = \sqrt{x^2 + y^2 + (z \pm a)^2} = \sqrt{x^2 + y^2 + z^2 \pm 2az + a^2} = r \sqrt{1 \pm \frac{2az \pm a^2}{r^2}} = r \left( 1 \pm \frac{1}{2} \frac{2ac \cos \theta}{r} \right) = r \pm a \cos \theta$$

$$\delta p = e^{i \omega t} A \left( \frac{e^{i k r}}{4\pi r} - \frac{e^{i k r}}{4\pi r} \right)$$

Lösung  $\vec{v}(\vec{r})$

$$\frac{\partial \vec{v}}{\partial t} = \frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \nabla) \vec{v}$$

$\Rightarrow$  akelotus Liniest  $\propto$   
vol. spezif.

$$q_0 \frac{\partial \vec{v}}{\partial t} = - \nabla \Phi_0 \quad \vec{v} = e^{i\omega t} \vec{V}(\vec{r})$$

$$i\omega q_0 \vec{V}(\vec{r}) = - \nabla \Phi(\vec{r}) \Leftrightarrow \vec{V}(\vec{r}) = \frac{i\omega \Phi(\vec{r})}{q_0}$$

$$\nabla \Phi = \frac{\partial \Phi}{\partial r} \hat{e}_r + \frac{1}{r} \frac{\partial \Phi}{\partial \theta} \hat{e}_\theta + \frac{1}{r \sin \theta} \frac{\partial \Phi}{\partial \phi} \hat{e}_\phi$$

$$\frac{\partial \Phi}{\partial r} = 1 \quad \frac{\partial \Phi}{\partial \theta} = 0 \quad \frac{\partial \Phi}{\partial \phi} = \pm \text{const.} \quad \text{durch stram } \frac{\partial}{\partial r} \sim 0$$

$$\vec{v}(\vec{r}, t) = \frac{A}{4\pi q_0} e^{i\omega t} \left( \left( e^{ikr} \frac{j_k}{r} - e^{-ikr} \frac{j_k}{r} \right) \hat{e}_r + e^{ikr} \frac{\hat{e}_\phi}{r^2} + \frac{e^{-ikr}}{r^2} \right) \hat{e}_r + \hat{e}_\phi \mathcal{O}(\vec{r})$$

$$\vec{v}(\vec{r}, t) = - \frac{A}{4\pi q_0 c} e^{i\omega t} \left( \frac{e^{ikr}}{r} - \frac{e^{-ikr}}{r} \right) \hat{e}_r$$

$$\vec{F}_E = - \frac{1}{c} \frac{A^2}{(4\pi)^2 q_0 c} \hat{e}_r \text{Re} \left( \frac{e^{ikr}}{r} - \frac{e^{-ikr}}{r} \right) \left( \frac{e^{ikr}}{r} - \frac{e^{-ikr}}{r} \right)$$

$$= - \frac{A^2 \hat{e}_r}{32\pi^2 q_0 c} \text{Re} \left( \frac{1}{r^2} + \frac{1}{r^2} - \frac{2 \cos(kr - \pi)}{r^2} \right)$$

$$= - \frac{A^2 \hat{e}_r}{32\pi^2 q_0 c} \frac{2}{r^2} (1 - \cos(kr - \pi))$$

3.1 Separation in Raum



$$\frac{1}{c} \frac{\partial^2 \Phi}{\partial t^2} = \nabla^2 \Phi \quad \text{Liniest potenziell}$$

$$\text{R.P. } \frac{\partial \Phi}{\partial r} \Big|_{r=a} = 0$$

$$\Phi(\vec{r}, t) = \Phi_i + \Phi_s = e^{i(kr - \omega t)} + \Phi_s \quad \Phi_s = ?$$

$$\text{Rausch rausch. } e^{ikr} \rightarrow \sum_{l=0}^{\infty} (2l+1) i^l j_l(kr) P_l(\cos \theta)$$

sphärische Drosselung f.

hauptsache fund. - harmon. potenziell verloren

$$\text{Nachsch. zu rausch. } \Phi_s = e^{i\omega t} \sum_l c_l P_l(\cos \theta) h_l^{(n)}(kr)$$

$$\Phi_i = e^{i(kr - \omega t)} = \sum_{l=0}^{\infty} (2l+1) i^l j_l(kr) P_l(\cos \theta) e^{i\omega t}$$

$$\text{R.P. } \frac{\partial \Phi}{\partial r} \Big|_{r=a} = 0 = \sum_{l=0}^{\infty} (2l+1) i^l j'_l(kr) k P_l(\cos \theta) + \sum_{l=0}^{\infty} c_l h_l^{(n)}(kr) k P_l(\cos \theta)$$

$$c_l = - (2l+1) i^l \frac{j_l'(kr)}{h_l^{(n)'}(kr)}$$

V lib  $k_0 \rightarrow 0, r \rightarrow \infty$

$$\text{Velj. } \frac{j_0'(k_0)}{h_0'(k_0)} = i \frac{(k_0)^2}{\gamma} \quad \frac{j_0'(k_0)}{h_0'(k_0)} = -i \frac{(k_0)^2}{c} \quad h_0^{(n)}(z) \approx -\frac{i}{\pi} e^{iz} \quad h_0^{(n)}(z) \sim -\frac{1}{\pi} e^{iz}$$

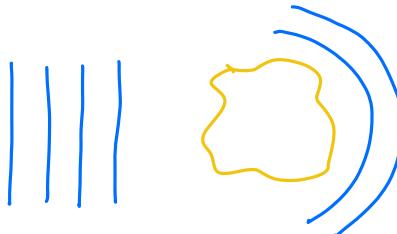
$$a_s = e^{-i\omega t} \left( -\frac{j_0'(k_0)}{h_0^{(n)}(k_0)} h_0(k_0) - 3 \frac{j_0'(k_0)}{h_0'(k_0)} i h_n(k_0) \cos \theta \right)$$

$$= e^{-i\omega t} \left( -i \frac{(k_0)^2}{\gamma} \left( +\frac{1}{h_0} \right) e^{ikr} - 3 \left( +\frac{i}{\pi} \right) (k_0)^2 i \left( -\frac{1}{h_0} \right) e^{ikr} \cos \theta \right)$$

$$= -e^{-i(\omega t - kr)} \frac{k^2 \alpha^2}{\gamma r} \left( 1 - \frac{3}{\pi} \cos \theta \right)$$

### T Sipalna teorija

$$-\frac{\hbar^2}{2m} \nabla^2 \psi + V(r) \psi = E \psi$$



Lippmann-Schwinger

$$\psi(\vec{x}) = e^{i\vec{k}\cdot\vec{x}} + \int d^3y G(\vec{x}-\vec{y}, k) V(\vec{y}) \psi_k(\vec{y}) \quad \text{Integralgleichung}$$

$$G(\vec{x}) = -\frac{m}{2\pi\hbar^2} \frac{e^{i|\vec{k}| |\vec{x}|}}{|\vec{x}|}$$

Bornova serija

$$\psi_k^{(0)}(\vec{x}) = 0 \quad \psi_k^{(n+1)}(\vec{x}) = e^{i\vec{k}\cdot\vec{x}} + K \psi_k^{(n)}(\vec{x})$$

$$K f(\vec{x}) = \int d^3y G(\vec{x}-\vec{y}) V(\vec{y}) f(\vec{y})$$

$$\frac{d\vec{g}_i}{d\vec{x}_i} = \frac{1/j_i}{1/j_i} \vec{v}_i$$



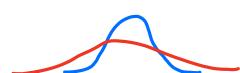
$$\frac{d\vec{g}_i}{d\vec{x}_i} (\vec{k}, \vec{k}') = |f(\vec{k} - \vec{k}')|^2$$

$$f(\vec{k} - \vec{k}') = -\frac{n}{2\pi\hbar^2} \int d^3y V(\vec{y}) e^{i(\vec{k} - \vec{k}') \cdot \vec{y}}$$

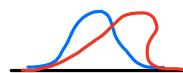
### T Nelinearne PDE

disperzija  $\rightarrow$  nelinearnost

$$\frac{\partial u}{\partial t} = \sigma^2 u$$



$$\frac{\partial u}{\partial t} = u \frac{\partial u}{\partial x} \quad \text{Burgers' eq.}$$



NLS, sine-Gordon, LL,  
KdV enačbe  
burgers  
difuzija

$$u_t - 6u u_x + u_{xxx} = 0$$

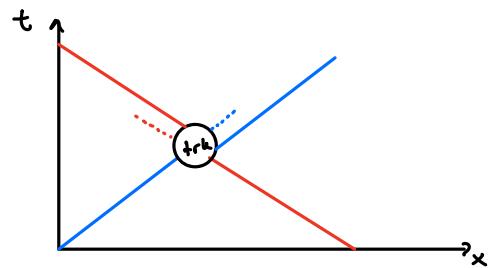
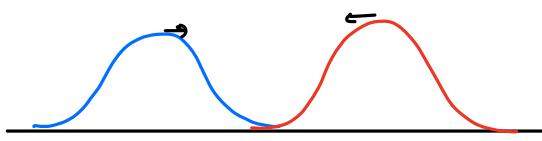


Fusija za volvovnic pri  
nizki glosini

Resitev so soliton:

$$u(x, t) = \frac{c}{ch^2(\sqrt{2c}(x - ct - x_0))}$$

Vorj se zwei der je treten den solitonen



Klein-Gordon  $\leftrightarrow$  sine-Gordon

$$H = \frac{1}{2} \int dx (\pi^2 + \varphi_x^2 + m^2 \varphi^2) ; \quad \xrightarrow{\rho \rightarrow 0} H = \int dx (\pi^2 + \varphi_x^2) + \frac{m}{\rho} (1 - \cos \varphi)$$

$$\pi(x) = \varphi_t(x)$$

$$\{ \varphi(x), \pi(y) \} = \delta(x-y)$$

$$KG: \quad \varphi_{tt} - \varphi_{xx} + m^2 \varphi = 0$$

$$SG: \quad \varphi_{tt} - \varphi_{xx} + \frac{m}{\rho} \sin \varphi = 0$$

$$\frac{df}{dt} = \{ f, H \}$$

KG

$$\varphi(x, 0) \xrightarrow{\text{Fourier}} \hat{\varphi}(k, 0)$$

$$\varphi(x, t) = \frac{1}{2\pi} \int \hat{\varphi}(k, t) e^{ikx} dk$$

$$\frac{1}{2\pi} \int \partial_t^2 \hat{\varphi} e^{ikx} dk + k^2 \frac{1}{2\pi} \int \hat{\varphi} e^{ikx} dk + m^2 \frac{1}{2\pi} \int \hat{\varphi} e^{ikx} dk = 0$$

$$(\partial_t^2 + (k^2 + m^2)) \hat{\varphi}(k, t) = 0 \quad \text{Navadus DS}$$

$$\frac{\partial^2}{\partial t^2} \hat{\varphi} + \omega_k^2 \hat{\varphi} = 0$$

$$\hat{\varphi}(k, t) = A e^{i \omega_k t} + B e^{-i \omega_k t}$$

$$\begin{aligned} A &\text{ in } D \quad i \in \mathbb{R} \\ \rightarrow \text{Inverser Fourier} &\rightarrow \varphi(x, t) \end{aligned}$$

Podobno werden zu sG