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Anomaly Detection

Latest Submission Grade 100%

1.

For which of the following problems would anomaly detection be a suitable algorithm?

1 / 1 point

- ☐ From a large set of hospital patient records, predict which patients have a particular disease (say, the flu).
- ☐ Given data from credit card transactions, classify each transaction according to type of purchase (for example: food, transportation, clothing).
- ☒ In a computer chip fabrication plant, identify microchips that might be defective.

✔ Correct

The defective chips are the anomalies you are looking for by modeling the properties of non-defective chips.

☒ From a large set of primary care patient records, identify individuals who might have unusual health conditions.

✔ Correct

Since you are just looking for unusual conditions instead of a particular disease, this is a good application of anomaly detection.

2.

Suppose you have trained an anomaly detection system that flags anomalies when $p(x)$ is less than ε , and you find on the cross-validation set that it has too many false positives (flagging too many things as anomalies). What should you do?

1 / 1 point

☐ Increase ε

☒ Decrease ε

✔ Correct

By decreasing ε , you will flag fewer anomalies, as desired.

3.

Suppose you are developing an anomaly detection system to catch manufacturing defects in airplane engines. You model uses

1 / 1 point

$$p(x) = \prod_{j=1}^n p(x_j; \mu_j, \sigma_j^2).$$

You have two features x_1 = vibration intensity, and x_2 = heat generated. Both x_1 and x_2 take on values between 0 and 1 (and are strictly greater than 0), and for most "normal" engines you expect that $x_1 \approx x_2$. One of the suspected anomalies is that a flawed engine may vibrate very intensely even without generating much heat (large x_1 , small x_2), even though the particular values of x_1 and x_2 may not fall outside their typical ranges of values. What additional feature x_3 should you create to capture these types of anomalies:

- ☒ $x_3 = \frac{x_1}{x_2}$
- ☐ $x_3 = x_1^2 \times x_2$
- ☐ $x_3 = x_1 + x_2$
- ☐ $x_3 = x_1 \times x_2$

✔ Correct

This is correct, as it will take on large values for anomalous examples and smaller values for normal examples.

4.

Which of the following are true? Check all that apply.

1 / 1 point

☐ In a typical anomaly detection setting, we have a large number of anomalous examples, and a relatively small number of normal/non-anomalous examples.

☐ When evaluating an anomaly detection algorithm on the cross validation set (containing some positive and some negative examples), classification accuracy is usually a good evaluation metric to use.

☒ When developing an anomaly detection system, it is often useful to select an appropriate numerical performance metric to evaluate the effectiveness of the learning algorithm.

✔ Correct

You should have a good evaluation metric, so you can evaluate changes to the model such as new features.

☒ In anomaly detection, we fit a model $p(x)$ to a set of negative ($y = 0$) examples, without using any positive examples we may have collected of previously observed anomalies.

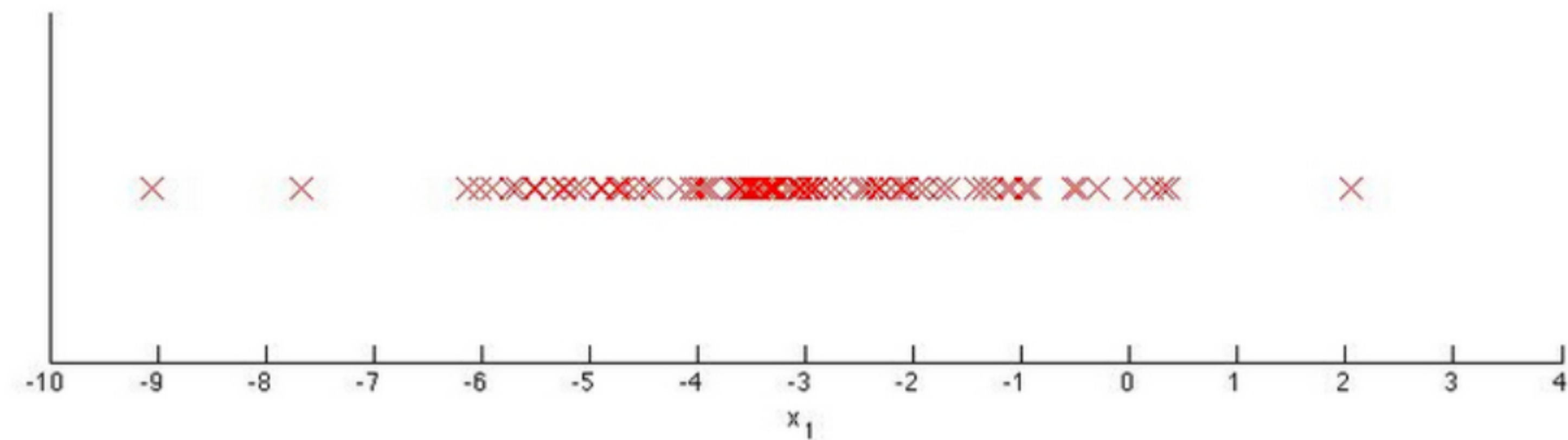
✔ Correct

We want to model "normal" examples, so we only use negative examples in training.

5.

You have a 1-D dataset $\{x^{(1)}, \dots, x^{(m)}\}$ and you want to detect outliers in the dataset. You first plot the dataset and it looks like this:

1 / 1 point



Suppose you fit the gaussian distribution parameters μ_1 and σ_1^2 to this dataset. Which of the following values for μ_1 and σ_1^2 might you get?

☒ $\mu_1 = -3, \sigma_1^2 = 4$

☐ $\mu_1 = -6, \sigma_1^2 = 4$

☐ $\mu_1 = -3, \sigma_1^2 = 2$

☐ $\mu_1 = -6, \sigma_1^2 = 2$

✔ Correct

This is correct, as the data are centered around -3 and tail most of the points lie in [-5, -1].