

$$\frac{d^2v}{dz^2} + \frac{P}{EI}v = \frac{d^2v_o}{dz^2}$$
 (13.32)

$$v_o = \sum_{n=1}^{\infty} A_n \sin \frac{n\pi z}{L}$$
 (13.33)

• substituting in eq (13.32):

$$\frac{d^2v}{dz^2} + \frac{P}{EI}v = -\sum_{n=1}^{\infty} \left(\frac{n\pi}{L}\right)^2 A_n \sin\frac{n\pi z}{L}$$
(14.1)

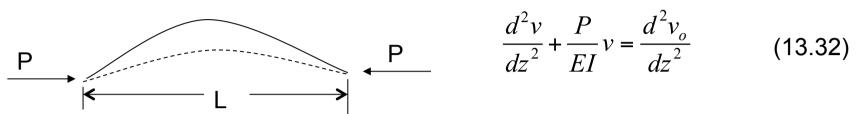
• to find the particular solution of (14.1) we try

$$v_p = \sum_{n=1}^{\infty} C_n \sin \frac{n\pi z}{L} \tag{14.2}$$

• substituting in (14.1) and solving for C<sub>n</sub>:

$$C_n = -\frac{\left(\frac{n\pi}{L}\right)^2 A_n}{\frac{P}{EI} - \left(\frac{n\pi}{L}\right)^2} = \frac{\left(\frac{n\pi}{L}\right)^2 A_n}{\left(\frac{n\pi}{L}\right)^2 - \frac{P}{EI}} = \frac{n^2 A_n}{n^2 - \frac{P}{EI}}$$

$$= P_{cr} \text{ for ss beam!}$$
(14.3)



 combining the homogeneous and particular solutions, eqs (13.7), (14.2) and (14.3), the complete expression for v is obtained:

$$v = A\cos\sqrt{\frac{P}{EI}}z + B\sin\sqrt{\frac{P}{EI}}z + \sum_{n=1}^{\infty} \frac{n^{2}A_{n}}{n^{2} - \frac{P}{P_{cr}}}\sin\frac{n\pi z}{L}$$
(14.4)

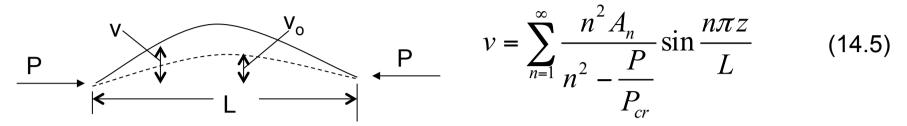
apply now the BC's that v=0 at z=0 and z=L

• at z=0: A=0; at z=L  $B\sin\sqrt{\frac{P}{EI}}L=0$  => either B=0 or P=0 or  $\frac{P}{EI}=\frac{n^2\pi^2}{L^2}$  buckling condition but the beam is

$$v = \sum_{n=1}^{\infty} \frac{n^2 A_n}{n^2 - \frac{P}{P_{cr}}} \sin \frac{n\pi z}{L}$$
 (14.5)

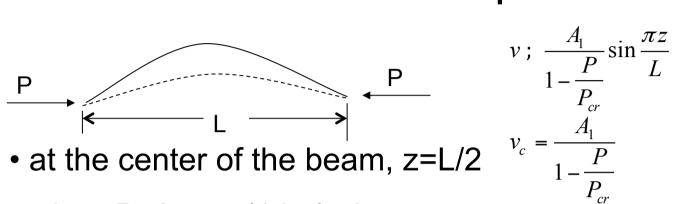
of little

interest



- some points of interest:
  - this solution is valid for  $P \le P_{cr}$ ; for  $P > P_{cr}$  one must modify it to account for large deflections
  - unlike the case of a straight ss beam where the solution for v has one unknown constant, here, v is completely determined; (for any value of P, the beam attains a stable equilibrium position) ( $A_n$  is known because  $v_o$  is known)
  - the denominator in (14.5) is increasing very rapidly as n increases; so terms for n>1 are much smaller than for n=1; therefore:

$$v : \frac{A_1}{1 - \frac{P}{P_{cr}}} \sin \frac{\pi z}{L}$$
 (14.6)



$$v; \frac{A_1}{1 - \frac{P}{P_{cr}}} \sin \frac{\pi z}{L}$$
 (14.6)

- (14.7)
- when P=0, eq. (14.7) gives  $v_{s}(P=0) = A_{s}$

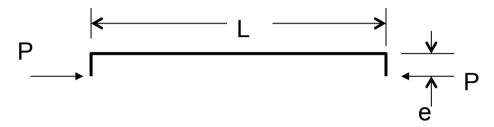
i.e., A₁ is the center deflection of the unloaded beam, which can be measured experimentally

• if  $\delta$  is the center deflection under load =  $v_c$ - $A_1$ , using eq. (14.7) we get:

$$\delta = v_c - A_1 = \frac{A_1}{1 - \frac{P}{P_{cr}}} - A_1 \Rightarrow \delta = \frac{A_1 P_{cr}}{P_{cr} - P} - A_1 \Rightarrow \delta P_{cr} - \delta P = A_1 P_{cr} - A_1 P_{cr} + A_1 P \Rightarrow \delta = \delta \frac{P_{cr}}{P} - A_1 \quad (14.8)$$

i.e. a plot of center deflection  $\delta$  versus  $\delta/P$  is a straight line with slope the buckling load P<sub>cr</sub> (this kind of plot is called a Southwell plot)

• (b) the load is applied a small distance e from the neutral axis of the beam



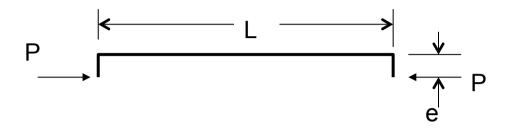
• of primary importance here are the boundary conditions:

- v=0 at z=0 and z=L  
- M=Pe at z=0 and z=L  
P
$$M = P(e+v(z))$$

• these are **four** conditions and, therefore, we need a fourth order differential equation!

note that Megson (section 8.3) uses a 2<sup>nd</sup> order differential equation but uses a reduced set of boundary conditions that he knows will work but it is a bit arbitrary

5



• we have already derived the fourth order diff. eqn. for such problems when we dealt with buckling of a clamped beam; eq (13.20):

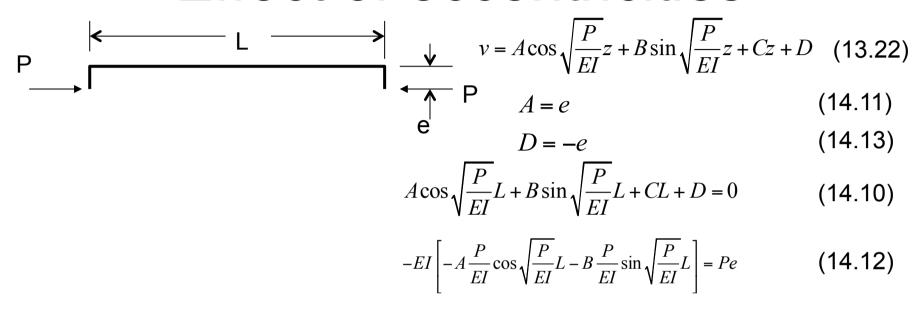
$$\frac{d^4v}{dz^4} + \frac{P}{EI}\frac{d^2v}{dz^2} = 0$$
 (13.20)

• to which we also found the general solution, eq. (13.22)

$$v = A\cos\sqrt{\frac{P}{EI}}z + B\sin\sqrt{\frac{P}{EI}}z + Cz + D$$
 (13.22)

P 
$$\rightarrow$$
 P  $\rightarrow$  P  $\rightarrow$ 

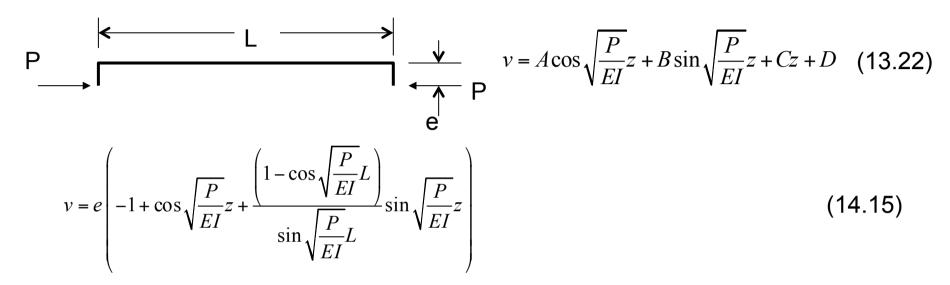
- the BC v=0 at z=0 gives: A+D=0 (14.9)
- the BC v=0 at z=L gives:  $A\cos\sqrt{\frac{P}{EI}}L + B\sin\sqrt{\frac{P}{EI}}L + CL + D = 0$  (14.10)
- the BC M=Pe at z=0 gives:  $-EI\frac{d^2v(0)}{dz^2} = Pe \Rightarrow -EI\left(-A\frac{P}{EI}\right) = Pe \Rightarrow A = e$
- the BC M=Pe at z=L gives:  $_{-EI}\left[-A\frac{P}{EI}\cos\sqrt{\frac{P}{EI}}L B\frac{P}{EI}\sin\sqrt{\frac{P}{EI}}L\right] = Pe$  (14.11)
- now from (14.11) and (14.9): D = -A = -e (14.13)



• from (14.12), knowing A from (14.11) can find B:

$$B = e^{\frac{\left(1 - \cos\sqrt{\frac{P}{EI}}L\right)}{\sin\sqrt{\frac{P}{EI}}L}}$$
(14.13)

- then, substituting in (14.10) we find C: C = 0 (14.14)
- collecting everything in the expression for v (13.22):



note that Megson has an expression that looks different but is, actually, identical to (14.15); the above expression is easier to use in practice but Megson's is simpler

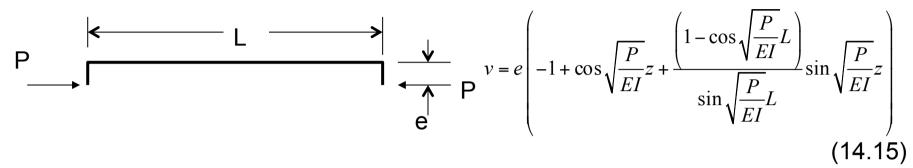
• for the mathematically inclined, to show equivalence of our expression with that of Megson, the following are needed:

$$\cos x = 1 - 2\sin^2 \frac{x}{2}$$

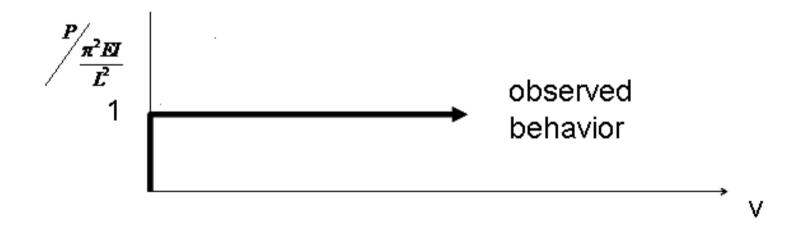
$$\sin x = 2\sin \frac{x}{2}\cos \frac{x}{2}$$

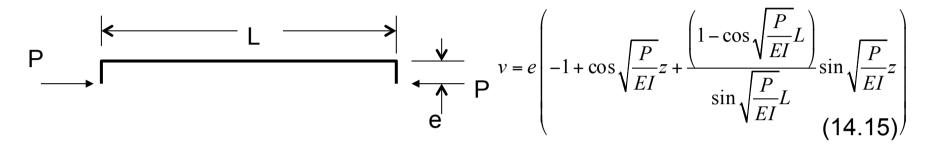
$$\therefore \frac{1 - \cos x}{\sin x} = \tan \frac{x}{2}$$

etc.



• in the previous lecture we saw that for a perfect column (no eccentricities):

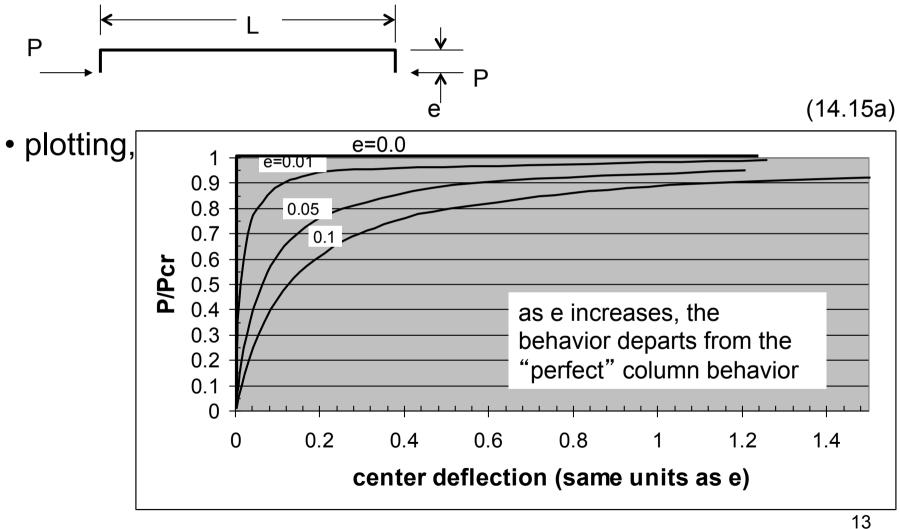




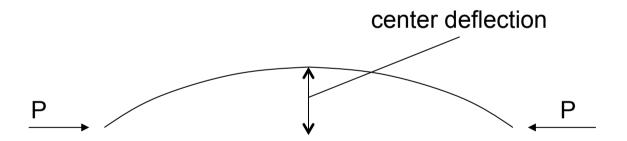
- now, with eccentricities present, a plot of P/P<sub>cr</sub> versus beam center deflection can be obtained
- to do that we need to rearrange the expression for v slightly; using  $\pi^2 EI$

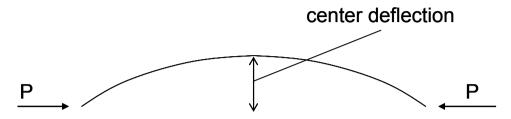
$$P_{crit} = \frac{\pi^2 EI}{L^2} \tag{13.9}$$

- we can write:  $\sqrt{\frac{P}{EI}}L = \sqrt{\frac{P}{EIP_{cr}}} \frac{\pi^2 EI}{L^2} L = \pi \sqrt{\frac{P}{P_{cr}}}$ (14.16)
- and using that, we can rewrite eq. (14.15) as:



 An aluminum beam (E=69 GPa) of length 1 m is under a compressive load P. When P=1000 N, the center deflection of the beam is 1 mm. When P= 2500 N, the center deflection is 3 mm.
 Determine the moment of inertia of the beam.



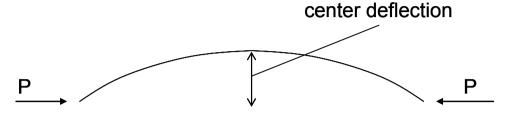


$$P_1$$
=1kN,  $v_1(L/2)$ =0.001 m  
 $P_2$ =3kN,  $v_2(L/2)$ =0.003 m

$$v_{1} = e \left( -1 + \cos \frac{\pi}{2} \sqrt{\frac{P_{1}}{P_{cr}}} + \frac{\left( 1 - \cos \pi \sqrt{\frac{P_{1}}{P_{cr}}} \right)}{\sin \pi \sqrt{\frac{P_{1}}{P_{cr}}}} \sin \frac{\pi}{2} \sqrt{\frac{P_{1}}{P_{cr}}} \right)$$

$$v_{2} = e \left( -1 + \cos \frac{\pi}{2} \sqrt{\frac{P_{2}}{P_{cr}}} + \frac{\left( 1 - \cos \pi \sqrt{\frac{P_{2}}{P_{cr}}} \right)}{\sin \pi \sqrt{\frac{P_{2}}{P_{cr}}}} \sin \frac{\pi}{2} \sqrt{\frac{P_{2}}{P_{cr}}} \right)$$

Divide one equation by the other to eliminate eccentricity e



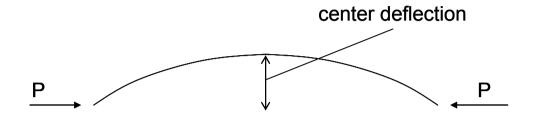
$$P_1=1kN$$
,  $v_1(L/2)=0.001 m$   
 $P_2=3kN$ ,  $v_2(L/2)=0.003 m$ 

$$\frac{v_{1}}{v_{2}} = \frac{-1 + \cos\frac{\pi}{2}\sqrt{\frac{P_{1}}{P_{cr}}} + \frac{\left(1 - \cos\pi\sqrt{\frac{P_{1}}{P_{cr}}}\right)}{\sin\pi\sqrt{\frac{P_{1}}{P_{cr}}}}\sin\frac{\pi}{2}\sqrt{\frac{P_{1}}{P_{cr}}}}{\sin\pi\sqrt{\frac{P_{2}}{P_{cr}}}}\sin\frac{\pi}{2}\sqrt{\frac{P_{2}}{P_{cr}}}$$

$$-1 + \cos\frac{\pi}{2}\sqrt{\frac{P_{2}}{P_{cr}}} + \frac{\left(1 - \cos\pi\sqrt{\frac{P_{2}}{P_{cr}}}\right)}{\sin\pi\sqrt{\frac{P_{2}}{P_{cr}}}}\sin\frac{\pi}{2}\sqrt{\frac{P_{2}}{P_{cr}}}$$

In this equation we know  $v_1$ ,  $v_2$ ,  $P_1$ , and  $P_2$ . The only unknown is  $P_{cr}$ 

• the equation is solved numerically (e.g. pick a value of P<sub>cr</sub>, evaluate RHS, compare to LHS, and keep adjusting



- solving:  $P_{cr} = 3594 \text{ N}$
- but, for a simply supported beam under compression, we know from eq (13.9):

$$P_{crit} = \frac{\pi^2 EI}{L^2} \tag{13.9}$$

• setting P<sub>cr</sub>=3594 N, E=69 GPa, and L=1 m, and solving for I:

$$I = \frac{P_{cr}L^2}{\pi^2 E} = 5.278 \times 10^{-9} \, m^4$$



• the principle of minimum potential energy (revisited in lecture 13):

If the displacements in a body satisfy compatibility and the displacement boundary conditions then if the body is in equilibrium the total potential energy is minimized

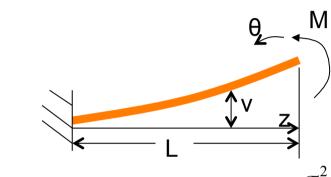
• the idea is to get some approximate expression for the displacements of the beam during buckling, minimize the energy, and hope for the best...



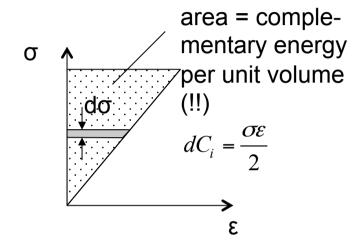
- first, we need to find an expression for the total potential energy of the beam
- total potential energy = internal strain energy Work done by force P

### Internal strain energy for a beam in bending

#### Beam under bending moment M



we know  $\sigma = E\varepsilon \Rightarrow \varepsilon = \frac{\sigma}{E}$  so  $dC_i = \frac{\sigma^2}{2E}$ 



from bending theory, lecture 2,  $\sigma_z = -\frac{My}{I}$ 

combining the two:  $dC_i = \frac{M^2 y^2}{2EI^2}$ 

then,  $C_i = \iint_{vol} \frac{dC_i}{2EI^2} = \iiint_{vol} \frac{M^2y^2}{2EI^2} dxdydz$  but, by definition,  $\iint_{vol} y^2 dxdy = I$ 

therefore, 
$$C_i = \int_0^L \frac{M^2}{2EI} dz$$

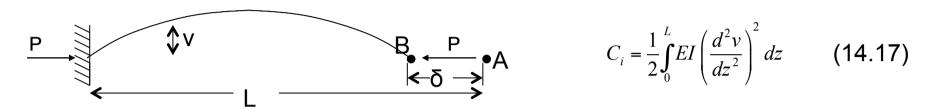


- this expression is in terms of the moment; as the theorem of min potential energy suggests, we must express everything in terms of displacements
- from the basic moment-curvature relationship (13.3) for beams:

$$M = -EI\frac{d^2v}{dz^2} \tag{13.3}$$

using this to substitute:

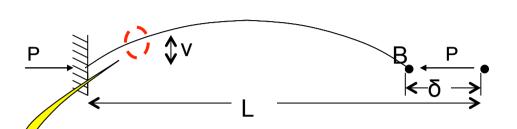
$$C_{i} = \frac{1}{2} \int_{0}^{L} EI\left(\frac{d^{2}v}{dz^{2}}\right)^{2} dz$$
 (14.17)



- need to also determine the work done by P
- assuming the beam is stationary at the left end, all the work is done by P acting on the right end; if the undeformed position of the right end was at A and, under load moved to B, a displacement δ, the work done by P is:

$$W = P\delta \tag{14.18}$$

 which must be expressed in terms of v (in order to make use of the principle of minimum potential energy)



$$C_{i} = \frac{1}{2} \int_{0}^{L} EI\left(\frac{d^{2}v}{dz^{2}}\right)^{2} dz \qquad (14.17)$$

$$W = P\delta \qquad (14.18)$$

$$W = P\delta \tag{14.18}$$

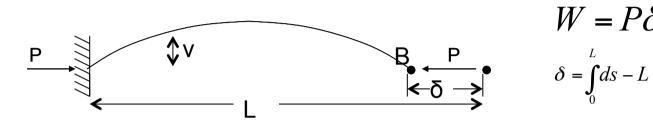
$$\delta = \int_0^L ds - L \tag{14.19}$$

• consider an element of arc length ds of the deformed beam:
$$ds \int_{0}^{L} ds - L$$

$$ds = \sqrt{dz^{2} + dv^{2}} = dz \sqrt{1 + \left(\frac{dv}{dz}\right)^{2}}$$
(14.19)

 very close to the buckling load, the deflections are small and the quantity  $(dv/dz)^2$  is very small; so (14.20) can be expanded in a Taylor series and use only the first term:

$$\sqrt{1 + \left(\frac{dv}{dz}\right)^{2}}; 1 + \left[\frac{1}{2} \frac{1}{\sqrt{1 + \left(\frac{dv}{dz}\right)^{2}}}\right]_{dv/dz=0} \left(\frac{dv}{dz}\right)^{2} + \dots = 1 + \frac{1}{2} \left(\frac{dv}{dz}\right)^{2}$$
(14.21)



$$W = P\delta \tag{14.18}$$

$$\delta = \int_{0}^{L} ds - L \tag{14.19}$$

$$ds = \sqrt{dz^2 + dv^2} = dz \sqrt{1 + \left(\frac{dv}{dz}\right)^2}$$
 (14.20)

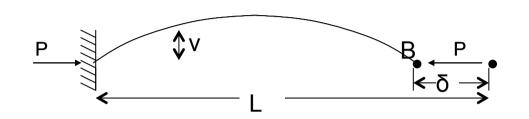
$$\sqrt{1 + \left(\frac{dv}{dz}\right)^{2}}; 1 + \left[\frac{1}{2} \frac{1}{\sqrt{1 + \left(\frac{dv}{dz}\right)^{2}}}\right]_{dv/dz=0} \left(\frac{dv}{dz}\right)^{2} + \dots = 1 + \frac{1}{2} \left(\frac{dv}{dz}\right)^{2}$$
(14.21)

• combining (14.21), (14.20), and (14.19) we get:

$$\delta = \int_{0}^{L} \left[ 1 + \frac{1}{2} \left( \frac{dv}{dz} \right)^{2} \right] dz - L = \int_{0}^{L} \frac{1}{2} \left( \frac{dv}{dz} \right)^{2} dz \tag{14.22}$$

• and substituting in eq. (14.18),

$$W = P \int_0^L \frac{1}{2} \left(\frac{dv}{dz}\right)^2 dz \tag{14.23}$$



Total energy=C<sub>i</sub>-W

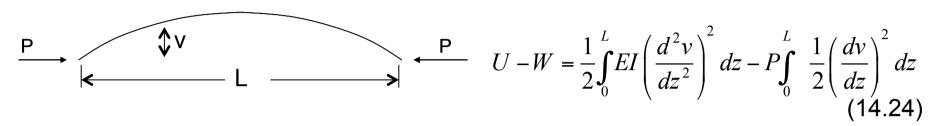
$$C_{i} = \frac{1}{2} \int_{0}^{L} EI \left(\frac{d^{2}v}{dz^{2}}\right)^{2} dz \qquad (14.17)$$

$$W = P \int_0^L \frac{1}{2} \left(\frac{dv}{dz}\right)^2 dz \qquad (14.23)$$

• finally, the total potential energy for a beam buckling under compressive load P is given by

$$U - W = \frac{1}{2} \int_{0}^{L} EI \left(\frac{d^{2}v}{dz^{2}}\right)^{2} dz - P \int_{0}^{L} \frac{1}{2} \left(\frac{dv}{dz}\right)^{2} dz$$
 (14.24)

• if we knew v exactly, then (14.24) would be minimized; but if we knew it exactly we would not have to calculate the energy anyway (the problem would be solved)



- suppose now that  $v = \sum_{n=1}^{\infty} A_n \sin \frac{n\pi z}{L}$  where  $A_n$  are unknown constants
  - note that this expression satisfies the simply-supported BC's that v=0 at z=0 and z=L
  - note also that, from Fourier series theory, this expression for v can reproduce any continuous function and, therefore, also the exact solution
  - since we do not know  $A_n$ , but we know that the energy must be minimized, we choose to minimize U-W with respect to  $A_n$

need to evaluate the integrals in U-W:

$$\frac{dv}{dz} = \sum_{n=1}^{\infty} A_n \frac{n\pi}{L} \cos \frac{n\pi z}{L} \tag{14.25}$$

$$\left(\frac{dv}{dz}\right)^2 = \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} A_n A_m \frac{n\pi}{L} \frac{m\pi}{L} \cos \frac{n\pi z}{L} \cos \frac{m\pi z}{L} \quad \text{same as writing the two series next to}$$
each other with different indices (14.26)

$$\int_{0}^{L} \left(\frac{dv}{dz}\right)^{2} dz = \int_{0}^{L} \sum_{n=1}^{\infty} A_{n}^{2} \frac{n^{2} \pi^{2}}{L^{2}} \left(\cos \frac{n \pi z}{L}\right)^{2} dz \text{ because}$$
 (14.27)

note Megson skips
$$\int_{-L}^{L} \cos \frac{m\pi z}{L} \cos \frac{m\pi z}{L} dz = 0 \quad when \quad m \neq n$$
dozens of steps here! (14.28)

then, using

$$\int_{0}^{L} \left(\cos\frac{n\pi z}{L}\right)^{2} dz = \int_{0}^{L} \frac{1}{2} \left(1 + \cos\frac{2n\pi z}{L}\right) dz = \frac{1}{2} \left[z + \frac{L}{2n\pi} \sin\frac{2n\pi z}{L}\right]_{0}^{L} = \frac{L}{2}$$
(14.29)

• we get: 
$$\int_{0}^{L} \left(\frac{dv}{dz}\right)^{2} dz = \sum_{n=1}^{\infty} A_{n}^{2} \frac{n^{2} \pi^{2}}{L^{2}} \frac{L}{2} = \sum_{n=1}^{\infty} A_{n}^{2} \frac{n^{2} \pi^{2}}{2L}$$
 (14.30)

similarly for the U term,

$$\frac{d^2v}{dz^2} = -\sum_{n=1}^{\infty} A_n \left(\frac{n\pi}{L}\right)^2 \sin\frac{n\pi z}{L} \tag{14.31}$$

$$\left(\frac{d^2v}{dz^2}\right)^2 = \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} A_n A_m \left(\frac{n\pi}{L}\right)^2 \left(\frac{m\pi}{L}\right)^2 \sin\frac{n\pi z}{L} \sin\frac{m\pi z}{L}$$
(14.32)

and

$$\int_{0}^{L} \left(\frac{d^{2}v}{dz^{2}}\right)^{2} dz = \int_{0}^{L} \sum_{n=1}^{\infty} A_{n}^{2} \left(\frac{n\pi}{L}\right)^{4} \left(\sin\frac{n\pi z}{L}\right)^{2} dz$$
 (14.33)

because 
$$\int_{0}^{L} \sin \frac{n\pi z}{L} \sin \frac{m\pi z}{L} dz = 0 \quad when \quad m \neq n$$
 (14.34)

• then, using 
$$\int_{0}^{L} \left( \sin \frac{n\pi z}{L} \right)^{2} dz = \int_{0}^{L} \frac{1}{2} \left( 1 - \cos \frac{2n\pi z}{L} \right) dz = \frac{1}{2} \left[ z - \frac{L}{2n\pi} \sin \frac{2n\pi z}{L} \right]_{0}^{L} = \frac{L}{2}$$
 (14.35)

• we get: 
$$\int_{0}^{L} \left(\frac{d^{2}v}{dz^{2}}\right)^{2} dz = \sum_{n=1}^{\infty} A_{n}^{2} \left(\frac{n\pi}{L}\right)^{4} \frac{L}{2} = \sum_{n=1}^{\infty} A_{n}^{2} \frac{n^{4}\pi^{4}}{2L^{3}}$$
 (14.36)

• in this expression,  $A_n$  are still unknown; to determine them, minimize the energy with respect to the  $A_n$ :

$$\frac{\partial(U - W)}{\partial A_n} = 0 \tag{14.38}$$

$$U - W = EI \sum_{n=1}^{\infty} A_n^2 \frac{n^4 \pi^4}{4L^3} - P \sum_{n=1}^{\infty} A_n^2 \frac{n^2 \pi^2}{4L}$$
 (14.37)
$$\frac{\partial (U - W)}{\partial A_n} = 0$$
 (14.38)

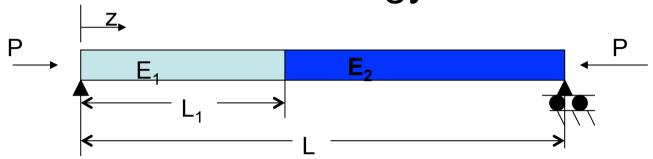
• from (14.38), differentiating (14.37) (note that the summations disappear!):

$$2EIA_{n}\frac{n^{4}\pi^{4}}{4L^{3}} - 2PA_{n}\frac{n^{2}\pi^{2}}{4L} = 0 \Rightarrow A_{n}\left(\frac{EIn^{2}\pi^{2}}{L^{2}} - P\right) = 0$$
(14.39)

• either A<sub>n</sub>=0 which means the beam does not buckle, only compresses (trivial solution), or,

$$\left(\frac{E\ln^2\pi^2}{L^2} - P\right) \Rightarrow P = \frac{n^2\pi^2EI}{L^2} \tag{13.9}$$

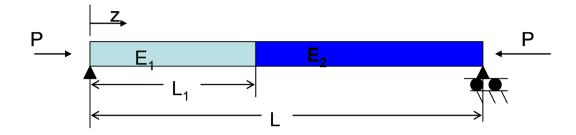
which is exactly the same as eq. (13.9) we got before for an ss beam!!



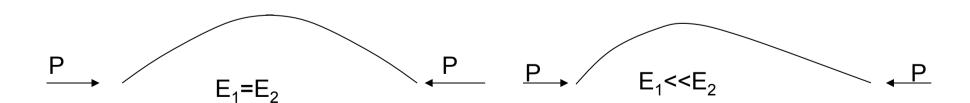
- consider now a beam of length L made of two materials welded together with Young's moduli  $E_1$  and  $E_2$  respectively but with moments of inertia  $I_1 = I_2 = I$
- to determine the buckling load, assume an approximate expression for v:

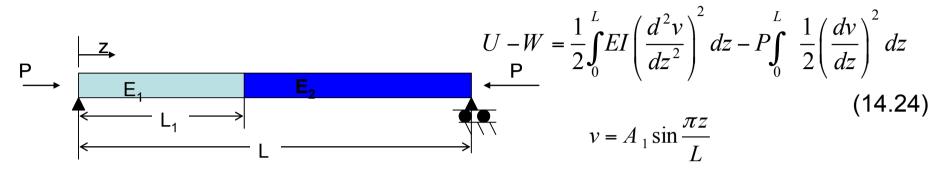
$$v = A_1 \sin \frac{\pi z}{L}$$
 where  $A_1$  is an unknown constant

 note that for the method to work, v must satisfy the boundary conditions (v=0 at z=0 and z=L)



• our assumed expression for the deflection is approximate because (for one thing), it is perfectly symmetric with respect to the beam mid-point which assumes the stiffnesses  $E_1$  and  $E_2$  are about the same





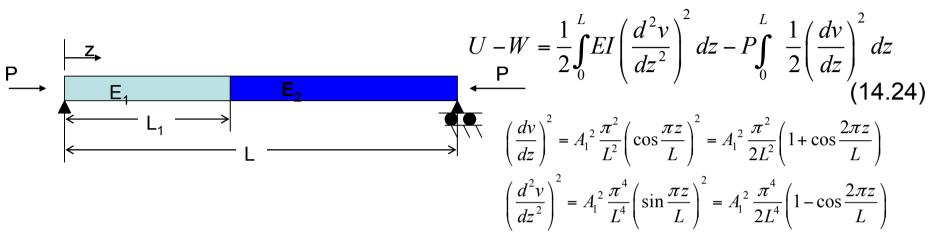
• to substitute in eq (14.24) we need:

$$\frac{dv}{dz} = A_1 \frac{\pi}{L} \cos \frac{\pi z}{L}$$

$$\frac{d^2v}{dz^2} = -A_1 \left(\frac{\pi}{L}\right)^2 \sin \frac{\pi z}{L}$$

squaring these terms:

$$\left(\frac{dv}{dz}\right)^{2} = A_{1}^{2} \frac{\pi^{2}}{L^{2}} \left(\cos\frac{\pi z}{L}\right)^{2} = A_{1}^{2} \frac{\pi^{2}}{2L^{2}} \left(1 + \cos\frac{2\pi z}{L}\right)$$
$$\left(\frac{d^{2}v}{dz^{2}}\right)^{2} = A_{1}^{2} \frac{\pi^{4}}{L^{4}} \left(\sin\frac{\pi z}{L}\right)^{2} = A_{1}^{2} \frac{\pi^{4}}{2L^{4}} \left(1 - \cos\frac{2\pi z}{L}\right)$$



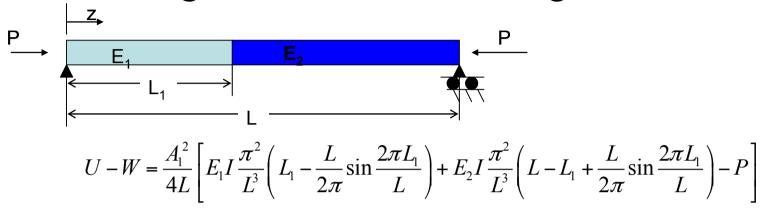
to integrate we notice the following:

$$\int_{a}^{b} \left(\frac{dv}{dz}\right)^{2} dz = A_{1}^{2} \frac{\pi^{2}}{2L^{2}} \int_{a}^{b} \left(1 + \cos\frac{2\pi z}{L}\right) dz = A_{1}^{2} \frac{\pi^{2}}{2L^{2}} \left[z + \frac{L}{2\pi} \sin\frac{2\pi z}{L}\right]_{a}^{b}$$

$$\int_{a}^{b} \left(\frac{d^{2}v}{dz^{2}}\right)^{2} dz = A_{1}^{2} \frac{\pi^{4}}{2L^{4}} \int_{a}^{b} \left(1 - \cos\frac{2\pi z}{L}\right) dz = A_{1}^{2} \frac{\pi^{4}}{2L^{4}} \left[1 - \frac{L}{2\pi} \sin\frac{2\pi z}{L}\right]_{a}^{b}$$

· substituting in the energy expression,

$$U - W = \frac{A_1^2}{4L} \left[ E_1 I \frac{\pi^2}{L^3} \left( L_1 - \frac{L}{2\pi} \sin \frac{2\pi L_1}{L} \right) + E_2 I \frac{\pi^2}{L^3} \left( L - L_1 + \frac{L}{2\pi} \sin \frac{2\pi L_1}{L} \right) - P \right]$$



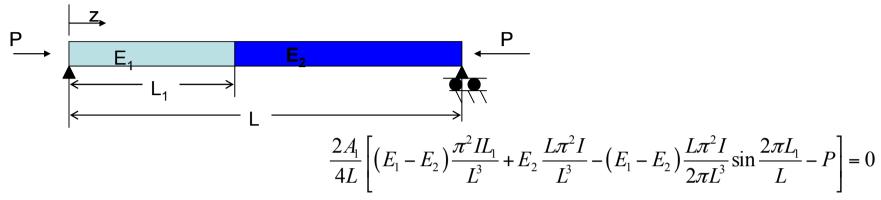
energy minimization implies:

$$\frac{d(U-W)}{dA_1} = 0$$

which, after some rearranging leads to,

$$\frac{2A_1}{4L} \left[ (E_1 - E_2) \frac{\pi^2 I L_1}{L^3} + E_2 \frac{L\pi^2 I}{L^3} - (E_1 - E_2) \frac{L\pi^2 I}{2\pi L^3} \sin \frac{2\pi L_1}{L} - P \right] = 0$$

• either A<sub>1</sub>=0, (trivial solution implying no buckling) or the quantity in brackets is zero



• therefore, the buckling load is given by:

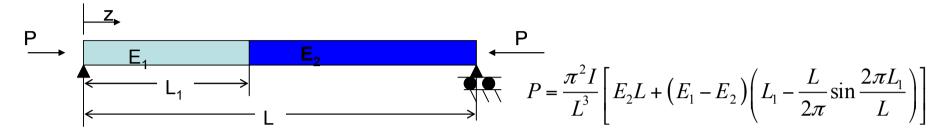
$$P = \frac{\pi^2 I}{L^3} \left[ E_2 L + \left( E_1 - E_2 \right) \left( L_1 - \frac{L}{2\pi} \sin \frac{2\pi L_1}{L} \right) \right]$$
 (approximate buckling load)

• special case 1: E<sub>1</sub>=E<sub>2</sub>=E; then:

$$P_{crit} = \frac{\pi^2 EI}{L^2}$$
 which is exactly the same expression we found before for the buckling load of a simply supported beam

special case 2: L<sub>1</sub>=0; then the entire beam is from mat'l

$$\frac{2}{P_{crit}} = \frac{\pi^2 E_2 I}{I^2}$$
 exactly as expected



• special case 3: L₁=L; the entire beam is from mat'l 1

$$P = \frac{\pi^2 I}{L^3} \left[ E_2 L + \left( E_1 - E_2 \right) L \right] = \frac{\pi^2 E_1 I}{L^2}$$
 exactly as expected