0201

○現在の目的は,

Enddevice からの 16 進数のデータを、 Coordinator が受信して 16 進数のまま表示させる. 以下は Enddevice から送信する際使用する Write 関数である.

PDUM u16APduInstanceWriteNBO

uint16 PDUM_u16APduInstanceWriteNBO(

PDUM_thAPduInstance hAPduInst, uint16 u16Pos, const char *szFormat, ...);

Description

This function writes the specified data values into the specified APDU instance. The byte position of the start of the data (least significant byte) in the APDU instance must be specified, as well as the format of the data.

The data values are written into the APDU instance at the specified position in packed network byte order (little-endian). The input data values should be in host byte order (big-endian for the JN51xx device).

Parameters

hAPdulnst Handle of the APDU instance to write the data into

u32Pos The starting p

The starting position (least significant byte) of the data within

the APDU instance

*szFormat Format string of the data:

b 8-bit byte

h 16-bit half-word (short integer)

w 32-bit word

I 64-bit long-word (long integer) a\xnn nn (hex) bytes of data (array) p\xnnnn (hex) bytes of packing

Variable list of data values described by the format string

Note that the compiler will not correctly interpret the format string "alxnnb" for a data array followed by a single byte, e.g. "alx0ab". In this case, to ensure that the 'b' (for byte) is not interpreted as a hex value, use the format "alxnn" "b", e.g. "alx0a" "b".

以下は Coordinator が受信する際使用する Read 関数である.

PDUM_u16APduInstanceReadNBO

uint16 PDUM_u16APduInstanceReadNBO(

PDUM_thAPduInstance hAPduInst, uint16 u16Pos, const char *szFormat, void *pvStruct);

Description

This function reads data from the specified APDU instance and inserts the data into a C structure. The byte position of the start (least significant byte) of the data in the APDU instance must be specified, as well as the format of the data.

Data is read from the APDU instance in packed network byte order (little-endian) and translated into unpacked host byte order for the C structure (big-endian for the JN51xx device).

Parameters

hAPdulnst Handle of APDU instance to read the data from

32Pos The starting position (least significant byte) of the data within the APDU

*szFormat Format string of the data:

b 8-bit byte

h 16-bit half-word (short integer)

w 32-bit word

I 64-bit long-word (long integer) a\xnn nn (hex) bytes of data (array) p\xnn nn (hex) bytes of packing

*pvStruct Pointer to C structure to receive the data

Note that the compiler will not correctly interpret the format string "a\xnnb" for a data array followed by a single byte, e.g. "a\x0ab". In this case, to ensure that the 'b' (for byte) is not interpreted as a hex value, use the format "a\xnn" "b", e.g. "a\x0a" "b".

[Enddevice]

<u>u160ffset</u> += PDUM_u16APduInstanceWriteNBO(hAPduInst, <u>u160ffset</u>, "a\x08", TxByte); 16進数センサデータ

TxByte[]には 16 進数のセンサデータが格納されてある. これはラズパイの方で表示させ, 確認済み.

[Coordinator]

```
uint32_t Rxbyte[32];
uint32_t *RxbytePointer;
RxbytePointer = &Rxbyte;

DBG_vPrintf(TRACE_APP, "received data16:");

//受信した16進数
u16bytesread = PDUM_u16APduInstanceReadNBO(sStackEvent.uEvent.sApsDataIndEvent.hAPduInst,0,"a\x08",RxbytePointer);

DBG_vPrintf(TRACE_APP, "%02x", RxbytePointer);
```

PDUM_u16APduInstanceReadNBO 関数の第3引数は 8byte の array のため, a¥x08 第4引数はポインタにして実装した.

しかし, ここでの Rxbyte[]には何も格納されてないプログラムのようになっている.そのため,この Rxbyte[]に受信データを格納したいが,

PDUM_u16APduInstanceReadNBO 関数はポインターの仕様であるため, Rxbyte[]と直に格納できない.

[結果]

○センサデータの array を送受信するのではなく、1 byte ずつ送信するよう実装をする.

[Enddevice]

```
u160ffset += PDUM_u16APduInstanceWriteNBO(hAPduInst, u160ffset,"b", 0x01); //1byte
PDUM_eAPduInstanceSetPayloadSize(hAPduInst, u160ffset);
DBG_vPrintf(TRUE, "Size : %d\nSending : ", PDUM_u16APduInstanceGetPayloadSize(hAPduInst));
```

PDUM_u16APduInstanceWriteNBO 関数の第3引数を b にし, 0x01 を送信する.

[Coordinator]

u16bytesread = PDUM_u16APduInstanceReadNBO(sStackEvent.uEvent.sApsDataIndEvent.hAPduInst,0,"b",RxbytePointer); //1byte
DBG_vPrintf(TRACE_APP, "%02x", RxbytePointer);

[結果]

「1 | を確認できた.

○次に 4byte ずつ送信できるよう実装した.

1. [Enddevice]

```
uint32 buffer = 1023;

//u160ffset += PDUM_u16APduInstanceWriteNBO(hAPduInst, u160ffset, "a\x08", TxByte); 16進数センサデータ

u160ffset += PDUM_u16APduInstanceWriteNBO(hAPduInst, u160ffset, "w", buffer);
```

[結果]

2. [Enddevice]

```
uint32_t buffer = 111222333;
```

//u160ffset += PDUM_u16APduInstanceWriteNBO(hAPduInst, u160ffset,"a\x08",TxByte); 16進数センサデータu160ffset += PDUM_u16APduInstanceWriteNBO(hAPduInst, u160ffset,"w", buffer);

[結果]

○スケジュール

~2/15 16 進数でセンサデータ表示と 10 進数変換

~2/22 10 台のマルチホップで実験

2/27 牡蠣の養殖場で実証実験