

# Setup - Installation of Vitis on Ubuntu

Vitis has the most documentation on linux and Ubuntu is one of the recommended platforms. This setup tutorial shows you how to:

Install Vitis — Contains Vitis IDE, Vitis HLS, Vivado and Vivado HLS, Install OpenCL Client Driver — OpenCL drivers, Install the Xilinx Runtime — XRT for OpenCL, Install the appropriate platform (we install U200 by Xilinx)

Based off of (and heavily borrows from)

<https://www.hackster.io/news/microzed-chronicles-vitis-acceleration-creating-a-vm-setup-363946fb4ede>

Download Vitis from here: <https://www.xilinx.com/products/design-tools/vitis.html>

Download the following OpenCL drivers:

```
sudo apt install ocl-icd-libopencl1 sudo apt install opencl-headers
```

```
sudo apt install ocl-icd-opencl-dev
```

Install xilinx runtime (dpkg file) from here:

[https://www.xilinx.com/bin/public/openDownload?filename=xrt\\_201920.2.3.1301\\_18.04-xrt.deb](https://www.xilinx.com/bin/public/openDownload?filename=xrt_201920.2.3.1301_18.04-xrt.deb)

Install the target device (dpkg file) from here:

[https://www.xilinx.com/products/boards-and-kits/alveo/u200.html#xrt1804\\_20191\\_xdma](https://www.xilinx.com/products/boards-and-kits/alveo/u200.html#xrt1804_20191_xdma)

The dpkg files need to be installed with `sudo apt install <dpkg_file_name>.dpkg`

To check if everything is installed correctly

```
git clone https://github.com/Xilinx/Vitis-Tutorials.git
cd Vitis-Tutorials/docs/my-first-program/reference-files
g++ -I$XILINX_XRT/include/ -I$XILINX_VIVADO/include/ -Wall -O0 -g -std=c++11
./src/host.cpp -o 'host' -L$XILINX_XRT/lib/ -lOpenCL -lpthread -lrt -lstdc++
```

This should run with no error.

## Bug Fixes

On Ubuntu 18.04, if you get the following error: **../src/host.cpp:47:10: fatal error:**  
CL/cl2.hpp: No such file or directory

- Then unzip

<https://www.xilinx.com/member/forms/download/design-license-xef.html?filename=rdf0476-zcu111-rf-dc-eval-tool-2019-2.zip>

And run

```
cp
$(download_location)/rdf0476-zcu111-rf-dc-eval-tool-2019-2/pl/MTSDesign_8x8/pre-built/rfso
c_trd/zcu111_rfsoc_trd_wrapper.xsa
$(vitis_install_location)/2019.2/data/embeddedsw/lib/fixed_hwplatforms
```

- If Vitis is asking for XILINX\_VITIS to be set, then run the following:  
source opt/xilinx/xrt/setup.sh

## How to Run Software Emulation and Hardware Emulation

In **vitis\_emulation/**, run the following for **Software Emulation**:

```
g++ -I$XILINX_XRT/include/ -I$XILINX_VIVADO/include/ -Wall -O0 -g -std=c++11 host.cpp
dense2.cpp dense1.cpp conv7.cpp conv6.cpp conv5.cpp conv4.cpp conv3.cpp conv2.cpp
conv1.cpp bnd2_a_b.cpp bnd1_a_b.cpp bn7_a_b.cpp bn6_a_b.cpp bn5_a_b.cpp
bn4_a_b.cpp bn3_a_b.cpp bn2_a_b.cpp bn1_a_b.cpp -o 'host' -L$XILINX_XRT/lib/
-lOpenCL -lpthread -lrt -lstdc++
```

```
v++ -t sw_emu --config design.cfg -c -k compute_network
-o'compute_network.xilinx_u200_xdma_201830_2.xo' 'tw_vgg10.cpp' 'tw_vgg10.h'
'pred_output.h' 'dense2.h' 'dense2.cpp' 'dense1.h' 'dense1.cpp' 'conv7.h' 'conv7.cpp' 'conv6.h'
'conv6.cpp' 'conv5.h' 'conv5.cpp' 'conv4.h' 'conv4.cpp' 'conv3.h' 'conv3.cpp' 'conv2.h'
```

```
'conv2.cpp' 'conv1.h' 'conv1.cpp' 'bnd2_a_b.h' 'bnd2_a_b.cpp' 'bnd1_a_b.h' 'bnd1_a_b.cpp'
'bn7_a_b.h' 'bn7_a_b.cpp' 'bn6_a_b.h' 'bn6_a_b.cpp' 'bn5_a_b.h' 'bn5_a_b.cpp' 'bn4_a_b.h'
'bn4_a_b.cpp' 'bn3_a_b.h' 'bn3_a_b.cpp' 'bn2_a_b.h' 'bn2_a_b.cpp' 'bn1_a_b.h'
'bn1_a_b.cpp' 'vgg_dense_3.h'
```

```
v++ -t sw_emu --config design.cfg -l -o'compute_network.xilinx_u200_xdma_201830_2.xclbin'
compute_network.xilinx_u200_xdma_201830_2.xo
```

```
emconfigutil --platform xilinx_u200_xdma_201830_2
export XCL_EMULATION_MODE=sw_emu
./host compute_network.xilinx_u200_xdma_201830_2.xo
```

**In vitis\_emulation/, run the following for Hardware Emulation (Warning: 2hour+ run time):**

```
v++ -t hw_emu --config design.cfg --save-temps -c -k compute_network
-o'compute_network.xilinx_u200_xdma_201830_2.xo' 'tw_vgg10.cpp' 'tw_vgg10.h'
'pred_output.h' 'dense2.h' 'dense2.cpp' 'dense1.h' 'dense1.cpp' 'conv7.h' 'conv7.cpp'
'conv6.h' 'conv6.cpp' 'conv5.h' 'conv5.cpp' 'conv4.h' 'conv4.cpp' 'conv3.h' 'conv3.cpp'
'conv2.h' 'conv2.cpp' 'conv1.h' 'conv1.cpp' 'bnd2_a_b.h' 'bnd2_a_b.cpp' 'bnd1_a_b.h'
'bnd1_a_b.cpp' 'bn7_a_b.h' 'bn7_a_b.cpp' 'bn6_a_b.h' 'bn6_a_b.cpp' 'bn5_a_b.h'
'bn5_a_b.cpp' 'bn4_a_b.h' 'bn4_a_b.cpp' 'bn3_a_b.h' 'bn3_a_b.cpp' 'bn2_a_b.h'
'bn2_a_b.cpp' 'bn1_a_b.h' 'bn1_a_b.cpp' 'vgg_dense_3.h'
```

```
v++ -t hw_emu --config design.cfg -l -o'compute_network.xilinx_u200_xdma_201830_2.xclbin'
compute_network.xilinx_u200_xdma_201830_2.xo
```

```
emconfigutil --platform xilinx_u200_xdma_201830_2
```

```
export XCL_EMULATION_MODE=hw_emu
```

```
./host compute_network.xilinx_u200_xdma_201830_2.xclbin
```

If we had the hardware, we could simply run:

```
unset XCL_EMULATION_MODE
```

```
./host compute_network.xilinx_u200_xdma_201830_2.xclbin
```

**This file (xclbin) can be run on chip, in an SD card.**

## Summary (so far)

To get to this point we had to create and run vitis host files (host.cpp/host.h) and a compute\_network kernel (tw\_cpp.c) in vitis\_emulation.

Then we ran in vitis on the **u200\_xdma\_201830\_2** target device.

Once officially supported by Xilinx, this will easily be ported to the ZCU111 platform simply by downloading the appropriate platform and changing the target device.