

# AS Electronics PIC Project - Calculator

## Design Brief:

This project's goal is the development of a calculator which supports the four basic arithmetic operations. It is capable of displaying inputs, outputs and any errors that may arise during calculation on a decimal display. It accepts input via a standard numeric keypad.

## Specification:

- Accurately Add, Subtract, Multiply and Divide integers using 16bits of storage
- Subtraction should accurately display results with negative and positive answers
- Division should display the integer part of the result and notify if there was a remainder
- The previous calculation's result will automatically be used as one of the next operations left operand, after floor and absolute value functions are applied
- Pressing Equals after a calculation will repeat the operation using the previous right operand and the previous result as the left operand
- 16bit overflows and math errors will be reported on the display using the F and E characters respectively
- Dual stage reset: First press clears the currently displayed value but maintains values stored in memory. Second press clears all values.

## Bill Of Materials:

- 3x PIC16F627A
- 2x 3-digit Kingbright BC56-12EWA numeric Display
- 16x Push Buttons
- 16x 330 Ohm Resistors
- 6x 10k Ohm Resistors
- 3x 12k Ohm Resistors

## Principal of Operation:

### Overview:

PIC #1 takes input from a single clear button and a 3x5 array of buttons in the shape of a keypad, using multiplexing on the three columns. The layout is shown to the left.

After performing the calculation PIC #1, the desired output is sent out from PIC #1 to PIC #2 and PIC #3 using a serial bus. PIC #2 handles one of the 3-digit displays and PIC #3 handles the other 3-digit display. To accommodate for the limited number of pins on each PIC the displays are driven using multiplexing.

7	8	9
4	5	6
1	2	3
+	0	=
-	/	*

Keypad Layout

Button	7	6	5	4	3	2	1	0	Sum
-	1	0	0	0	0	1	0	0	132
/	1	0	0	0	0	0	1	0	130
*	1	0	0	0	0	0	0	1	129
+	0	1	0	0	0	1	0	0	68
0	0	1	0	0	0	0	1	0	66
=	0	1	0	0	0	0	0	1	65
1	0	0	1	0	0	1	0	0	36
2	0	0	1	0	0	0	1	0	64
3	0	0	1	0	0	0	0	1	33
4	0	0	0	1	0	1	0	0	20
5	0	0	0	1	0	0	1	0	18
6	0	0	0	1	0	0	0	1	17
7	0	0	0	0	1	1	0	0	12
8	0	0	0	0	1	0	1	0	10
9	0	0	0	0	1	0	0	1	9

### Input:

To accommodate for the limited number of pins on a PIC16F627A the buttons inputs are multiplexed in 3 columns of 5. Each column is connected to one of the 3 least significant bits of PORTB, and each of the rows to the 5 most significant bits. PIC #1 repeatedly flashes a single column high while keeping the other column low. It then looks for changes on the 5 most significant bits of PORTB to indicate a button was pressed. Additionally before each cycle PIC#1 pools the clear button (A7). This happens in the main loop in the code.

Which 2 PORTB pins where high when this happens determine which button was pressed. Decoding of this information takes place in the button\_decode subroutine, which redirects the program flow to an appropriate "act" subroutine. Placed to the left is the table of PORTB values for each button. The top row indicates pin numbers of the PORTB register.

### Output:

PIC #2 and PIC #3 each control one 3-digit display, and run identical code. A display module refers to the PIC 3-digit display combo. Each display module has 3 input pins Prog (A5), Clock(A4) and Data(A6) and 1 output pin (A7). The first 3 are connected to PIC #1 pins A0, A2, A2 respectively. This allows us to daisy chain many (in the case of this project 2) display modules by connecting all Prog pins together, all Clock pins together, and plugging one module's Output pin into the next's Data input. They behave much like 24bit shift registers with the additional function of multiplexing on 8 parallel outputs to the display while Prog pin is low. When Prog is high, a low pulse on the Clock pin shifts all values over by one bit, taking a new bit from Data pin and shifting out the old one to the Output pin. As

PICs #2,3 run at a much faster frequency of 4 MHz as opposed to PIC#1's 48 kHz no delay code is needed on PIC#1

## **Subroutine Descriptions:**

### **PIC #1**

main - loop in which PIC waits for user input from button array via multiplexing or via clear button. This loop is executed while idle, and is the first non-initialization subroutine run

Button\_decode - decodes values of PORTB and determines which button does what. It redirects program flow to "act" subroutines which correspond 1 to 1 to the buttons

[0-9]\_act - loads the respective digit value into store register and goes to shift\_digits.

[add/sub/mul/div]\_act - Runs any previously buffered calculation (equivalent to pressing equals before any other operator), remembers which operator was pressed in the operator register (0=add 1=sub 2=mul 3=div) and ensures the left operand is correct.

equ\_act - Prepares registers for calculation, by ensuring operands are in correct places based on if the press is a repeat of the previous operation. Then It calls equ\_function for calculation and write\_value for display.

Shift\_digits - updates value\_hi and lo registers based on button press. It multiplies the current value by 10 and adds the value of store to append a digit the the end

equ\_function - redirects program flow to subroutines performing arithmetic functions based on the value of the operator register.

Actual\_add - Implements 16bit addition using standard methods and carry bits

actual\_mul - Implements 16bit multiplication using a long multiplication in base 2

actual\_sub - Implements 16bit subtraction using standard methods and borrow bits

actual\_div - Implements 16bit integer division using repeated subtraction

Write\_value - Uses serial data transfer to communicate with PICs #2,3 to display the required value on the display

Segment\_look - A lookup table containing the shapes of digits 0-9 on a numeric display

Multi\_key - Handles the rare occurrence of the PIC begin unable to discern which press was first if two buttons are pressed simultaneously

Unexpected\_error - Handles math undefined errors and previously unpredicted errors

Overflow - Handles cases in which numbers are too big to be stored in 16bits

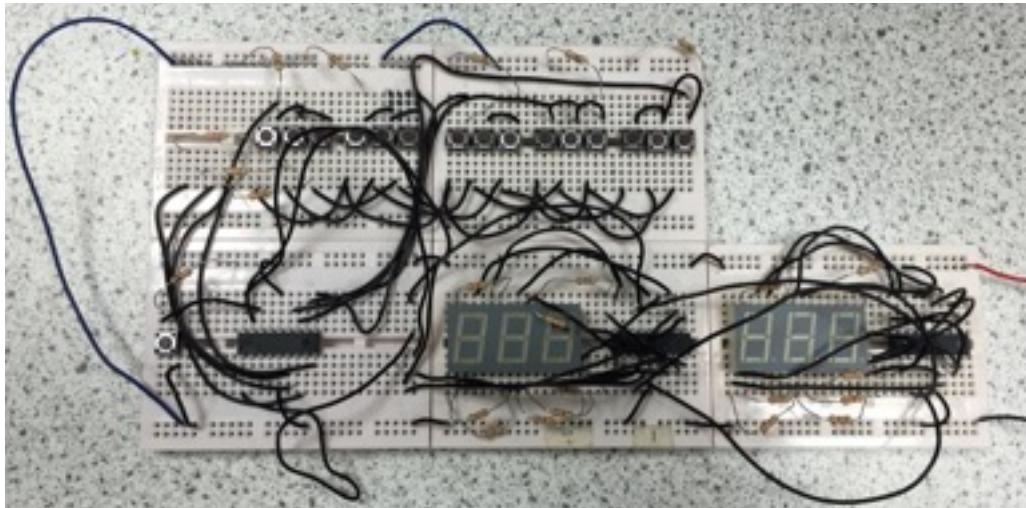
### **PIC# 2,3**

main - Loop that multiplexes the 3 digits while no data is being sent

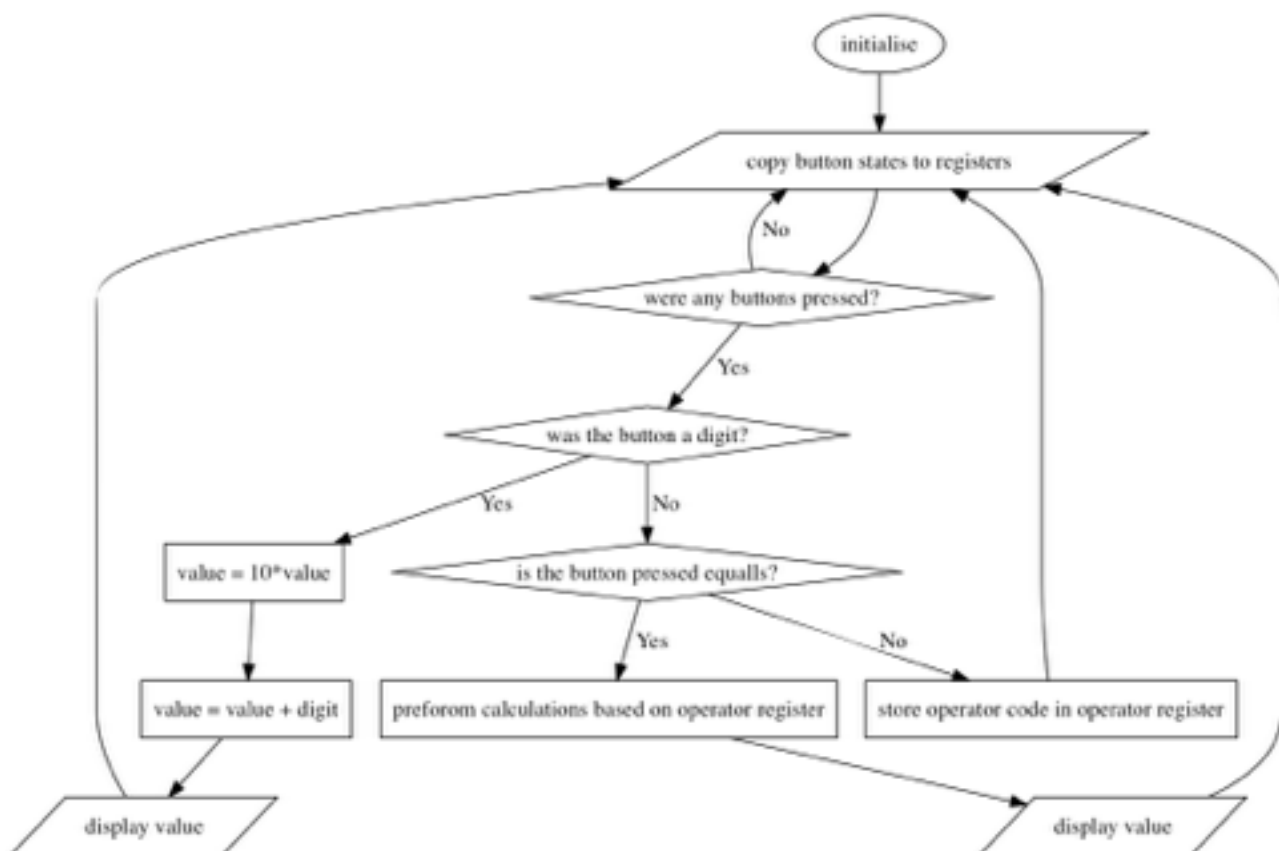
prog - Code that received serial data and stores in in dig\_one dig\_two dig\_three registers

Delay - Time waisting loop which changes the multiplexing duty cycles allowing human eyes to correctly perceive the display

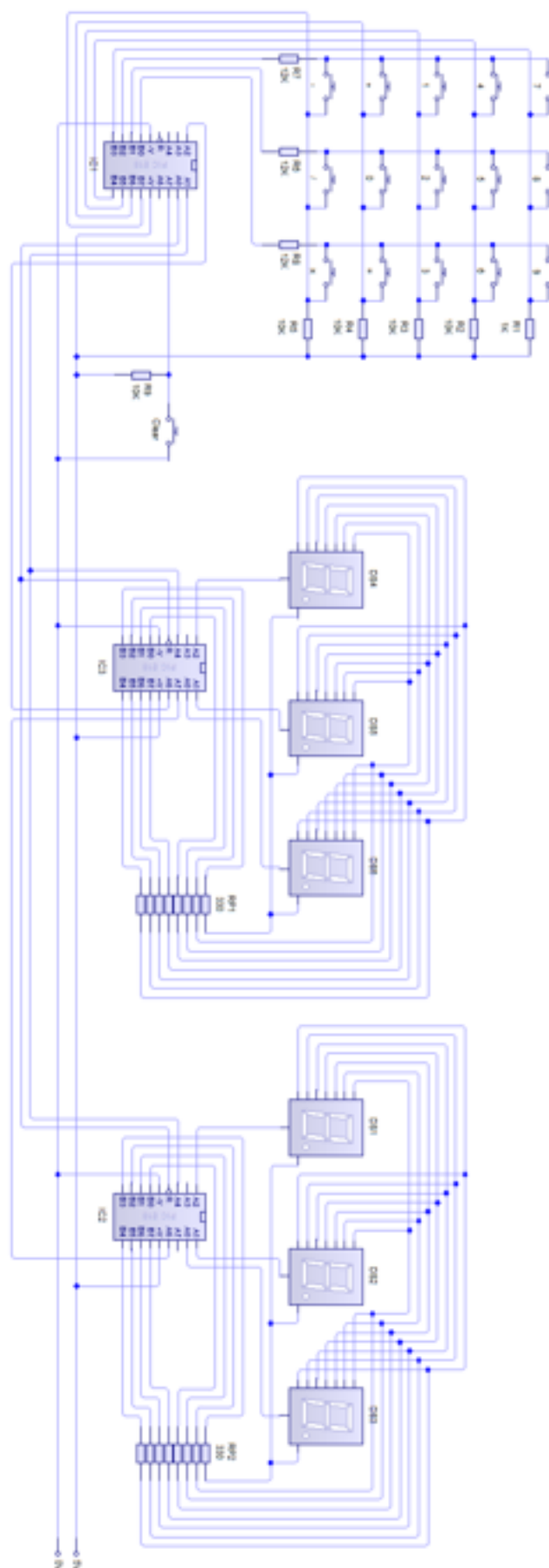
### Picture of Breadboard layout:



### FlowChart of PIC #1 Program:



### Circuit Diagram:



## Testing:

-Simple Addition:  
Button order:  $2 + 2 =$   
Expected Output: 4



-Exact Division:  
Button order:  $50 / 5 =$   
Expected Output: 10



-All Clear:  
BO:  $5 + 223$  CLR CLR 2 =  
Expected Output: 2



-Addition with carry:  
Button order:  $255 + 2 =$   
Expected Output: 267



-Remainder Division:  
Button order:  $51 / 5 =$   
Expected Output: 10r.



-Overflow:  
Button order:  $256 * 256 =$   
Expected Output: (First Character) F.



-Subtraction Positive:  
Button order:  $300 - 3 =$   
Expected Output: 297



-Maths Error:  
Button order:  $3 / 0 =$   
Expected Output: (First Character) E.



-Subtraction Negative:  
Button order:  $10 - 30 =$   
Expected Output: -20



-Auto Evaluation:  
Button order:  $2 * 6 + 4 =$   
Expected Output: 16



-Multiplication:  
Button order:  $4 * 8 =$   
Expected Output: 32



-Repeat operation:  
Button order:  $4 + 3 ==$   
Expected Output: 10



-Multiplication with carry:  
Button order:  $201 * 199 =$   
Expected Output: 39999



-Clear:  
BO:  $5 + 223$  CLR CLR 2 =  
Expected Output: 7



```

;-----;
; PIC#1 Code ;
;-----;
; Program title: 4 operator calculator ;
;-----;
; Written by: Michal Adamkiewicz ;
;-----;
; Date: 19th September 2014 ;
;-----;
; Version: 1.0 ;
;-----;
; Device: PIC16F627A ;
;-----;
; Oscillator: Internal 48 kHz ;
;-----;

```

```

LIST P=PIC16F627A
;select device
;Tells MPLAB what processor IC is being used

```

```

INCLUDE c:\program files (x86)\microchip\MPASM Suite
\P16F627A.inc
;include header file
;from default location
;tells the MPLAB where to find the files

```

```

__config 0x3F10
;sets config to; internal I/O, no watchdog,Power
;up timer on, master Reset off,
;no brown-out, no LV program, no read protect,
;no code protect

```

```

;-----;
; DEFINE REGISTERS ;
;-----;

```

```

        cblock 0x20
temp
temp_value_lo
Temp_value_hi
;temporary registers used in loop
counting and space for calculations
Operator
store
;stores code for the next operation
to execute

value_hi
value_lo
;stores currently displayed value

old_value_hi
old_value_lo
;stores non displayed operand

```

```

out_value_lo
out_value_hi

                                ;temporary registers used in
                                calculations

update_flag

                                ;contains various bit flags:
                                0-screen update 7-minus sign
                                6-temp storage 5-operator repeat
                                ;4-remainder note
                                3-all clear counter
                                2-multiplication overflow

                                flag

rep_value_lo
rep_value_hi

                                ;store values for repeated
                                operations

                                endc

                                ;INITIALIZATION

MOVLW d'07'
MOVWF CMCON                    ;disable comparators
init    BSF STATUS, RP0        ;select bank1 for setup
        BCF PCON, OSCF         ;selects 48 kHz oscillator
        MOVLW b'11111000'      ;configure PORTB for button
                                multiplexing

        MOVWF TRISB
        MOVLW b'10000000'
        MOVWF TRISA            ;configure PORTA for clear of A7 and
                                A0,1,2 as display outputs
                                ;PORTA 0=clear 1=clock 2=data,
                                7=clear

        BCF STATUS, RP0        ;return to bank0 for program
                                operation

        BSF PORTA,0            ;prime display modules
                                ;clear registers to prevent ghosting
                                from previous runs

        CLRF temp
        CLRF temp_value_lo
        CLRF temp_value_hi
        CLRF store
        CLRF operator
        CLRF value_hi
        CLRF value_lo
        CLRF old_value_hi
        CLRF old_value_lo
        CLRF out_value_lo
        CLRF out_value_hi
        CLRF rep_value_lo
        CLRF rep_value_hi
        CLRF update_flag

main                                ;wait for till input loop -
                                multiplexes buttons

```



```

BCF PORTA,0           ;display values
CLRF PORTB            ;sets all multiplex columns off
BTFSC PORTA,7         ;check if clear button was pressed
GOTO no_clear_calc
clear_debounce BTFSS PORTA,7
GOTO clear_debounce
BTFSC update_flag,3   ;test how many times clear button
                      ;was pressed

GOTO all_clear
BSF update_flag,3     ;count one button press
CLRF value_lo         ;if yes clear all relevant registers
CLRF value_hi
CLRF operator
BCF update_flag,0
CALL write_value       ;will leave 0 character
GOTO no_clear_calc
all_clear             ;second time button was pressed
CLRF value_lo         ;if yes clear all relevant registers
CLRF value_hi
CLRF old_value_lo
CLRF old_value_hi
CLRF rep_value_lo
CLRF rep_value_hi
CLRF operator
CLRF update_flag
CLRF store            ;Artificially prepare for
                      ;write_value

BSF PORTA,0
CALL no_negative      ;Clear all characters
no_clear_calc        ;no clear took place
BSF PORTB,0          ;Enable left column for multiplexing
MOVF PORTB,W         ;copy inputs to temp
MOVWF temp
XORLW D'1'
BTFSC STATUS, Z      ;check if button was pressed
GOTO bone            ;button not pressed
bpone MOVF PORTB,W    ;debouncing loop- wait till unpress
XORLW D'1'
BTFSS STATUS, Z      ;button unpressed?
GOTO bpone
GOTO button_decode   ;decode button code functionality
bone BCF PORTB,0      ;Disable left column for
                      ;multiplexing

BSF PORTB,1          ;Enable centre column for
                      ;multiplexing
MOVF PORTB,W         ;copy inputs to W
MOVWF temp
XORLW D'2'
BTFSC STATUS, Z      ;check if button was pressed
GOTO btwo           ;button not pressed
bptwo MOVF PORTB,W    ;debouncing loop- wait till unpress
XORLW D'2'

```

```

        BTFSS STATUS, Z           ;button unpressed?
        GOTO bptwo
        GOTO button_decode       ;decode button code functionality
btwo BCF PORTB,1                 ;Disable centre column for
                                multiplexing
        BSF PORTB,2              ;Enable centre column for
                                multiplexing
        MOVF PORTB,W             ;copy inputs to W
        MOVWF temp
        XORLW D'4'
        BTFSC STATUS, Z         ;check if button was pressed
        GOTO bthr               ;button not pressed
bpthr MOVF PORTB,W              ;debouncing loop- wait till unpress
        XORLW D'4'
        BTFSS STATUS, Z         ;button unpressed?
        GOTO bpthr
        GOTO button_decode       ;decode button code functionality
bthr BCF PORTB,2                ;Disable right column for
                                multiplexing
        GOTO main                ;loop while awaiting input

segment_look ADDWF PCL,F         ;Appearances of characters on screen
                                ;7-Decimal Point
        RETLW b'01011111'       ;0
        RETLW b'00000101'       ;1
        RETLW b'01110110'       ;2
        RETLW b'01110101'       ;3
        RETLW b'00101101'       ;4
        RETLW b'01111001'       ;5
        RETLW b'01111011'       ;6
        RETLW b'01000101'       ;7
        RETLW b'01111111'       ;8
        RETLW b'01111101'       ;9
        GOTO unexpected_error    ;something unpredicted happened

button_decode                    ;subroutine decodes button codes
        BCF update_flag,3        ;resets clear counter
        BTFSS update_flag,0      ;test if previous button press was
                                operator and value needs clearing

        GOTO no_update
        BCF update_flag,0        ;clear flag
        CLRF value_hi            ;clear value
        CLRF value_lo

no_update
        MOVF temp,w
        XORLW D'132'
        BTFSC STATUS,Z          ;does temp match the buttons code?
        GOTO sub_act
        MOVF temp,w
        XORLW D'130'
        BTFSC STATUS,Z          ;does temp match the buttons code?
        GOTO div_act

```

MOVF temp,w	
XORLW D'129'	
BTFSC STATUS,Z	;does temp match the buttons code?
GOTO mul_act	
MOVF temp,w	
XORLW D'68'	
BTFSC STATUS,Z	;does temp match the buttons code?
GOTO add_act	
MOVF temp,w	
XORLW D'66'	
BTFSC STATUS,Z	;does temp match the buttons code?
GOTO zero_act	
MOVF temp,w	
XORLW D'65'	
BTFSC STATUS,Z	;does temp match the buttons code?
GOTO equ_act	
MOVF temp,w	
XORLW D'36'	
BTFSC STATUS,Z	;does temp match the buttons code?
GOTO one_act	
MOVF temp,w	
XORLW D'34'	
BTFSC STATUS,Z	;does temp match the buttons code?
GOTO two_act	
MOVF temp,w	
XORLW D'33'	
BTFSC STATUS,Z	;does temp match the buttons code?
GOTO three_act	
MOVF temp,w	
XORLW D'20'	
BTFSC STATUS,Z	;does temp match the buttons code?
GOTO four_act	
MOVF temp,w	
XORLW D'18'	
BTFSC STATUS,Z	;does temp match the buttons code?
GOTO five_act	
MOVF temp,w	
XORLW D'17'	
BTFSC STATUS,Z	;does temp match the buttons code?
GOTO six_act	
MOVF temp,w	
XORLW D'12'	
BTFSC STATUS,Z	;does temp match the buttons code?
GOTO seven_act	
MOVF temp,w	
XORLW D'10'	
BTFSC STATUS,Z	;does temp match the buttons code?
GOTO eight_act	
MOVF temp,w	
XORLW D'9'	
BTFSC STATUS,Z	;does temp match the buttons code?
GOTO nine_act	

```

        GOTO multi_key                ;more than 1 button was pressed,
                                      display error code

equ_act
    BTFSC update_flag,5              ;was equals pressed twice?
    GOTO equ_act_rep
    BSF update_flag,5                ;notify that previous button press
                                      was equals
    MOVFW value_lo                    ;store current argument for future
                                      double press

    MOVWF rep_value_lo
    MOVFW value_hi
    MOVWF rep_value_hi
    CALL equ_function                 ;run appropriate calculation
    CALL write_value                  ;push value to display
    GOTO main                         ;return to main loop
equ_act_rep                           ;Equals double press
    MOVFW value_lo                    ;use value as old argument
    MOVWF old_value_lo
    MOVFW value_hi
    MOVWF old_value_hi
    MOVFW rep_value_lo                ;used rep_value as current argument
    MOVFW value_lo
    MOVFW rep_value_hi
    MOVWF value_hi
    CALL equ_function                 ;run appropriate calculation
    CALL write_value                  ;push value to display
    GOTO main                         ;RETURN to main loop

mul_act
    BTFSC update_flag,5              ;stops in auto-calculating repeated
                                      operation
    GOTO mul_rep_skip
    CALL equ_function                 ;If yes calculate them
    CALL write_value                  ;And display them
mul_rep_skip
    BCF update_flag,5                ;Resets repetition flag
    MOVLW D'2'                       ;remember which operator is active
                                      in register

    MOVWF operator
    MOVF value_hi, W                  ;move value to old_value to be used
                                      a previous argument

    MOVWF old_value_hi
    MOVF value_lo, W
    MOVWF old_value_lo
    BSF update_flag,0                ;clear value next time button is
                                      presed
    GOTO main                         ;wait for button input

div_act
    BTFSC update_flag,5              ;stops in auto-calculating repeated
                                      operation

```

```

        GOTO div_rep_skip
        CALL equ_function           ;If yes calculate them
        CALL write_value           ;And display them
div_rep_skip
        BCF update_flag,5          ;Resets repetition flag
        MOVLW D'3'                 ;remember which operator is active
                                   in register

        MOVWF operator
        MOVF value_hi, W           ;move value to old_value to be used
                                   a previous argument

        MOVWF old_value_hi
        MOVF value_lo, W
        MOVWF old_value_lo
        BSF update_flag,0          ;clear value next time button is
                                   pressed

        GOTO main                  ;wait for button input

sub_act
        BTFSC update_flag,5        ;stops in auto-calculating repeated
                                   operation

        GOTO sub_rep_skip
        CALL equ_function           ;If yes calculate them
        CALL write_value           ;And display them
sub_rep_skip
        BCF update_flag,5          ;Resets repetition flag
        MOVLW D'1'                 ;remember which operator is active
                                   in register

        MOVWF operator
        MOVF value_hi, W           ;move value to old_value to be used
                                   a previous argument

        MOVWF old_value_hi
        MOVF value_lo, W
        MOVWF old_value_lo
        BSF update_flag,0          ;clear value next time button is
                                   pressed

        GOTO main                  ;wait for button input

add_act
        BTFSC update_flag,5        ;stops in auto-calculating repeated
                                   operation

        GOTO add_rep_skip
        CALL equ_function           ;If yes calculate them
        CALL write_value           ;And display them
add_rep_skip
        BCF update_flag,5          ;Resets repetition flag
        MOVLW D'0'                 ;remember which operator is active
                                   in register

        MOVWF operator
        MOVF value_hi, W           ;move value to old_value to be used
                                   a previous argument

        MOVWF old_value_hi
        MOVF value_lo, W

```

MOVWF old_value_lo	
BSF update_flag,0	;clear value next time button is pressed
GOTO main	;wait for button input
one_act MOVLW D'1'	;copy digit to store and append to end of value base10
MOVWF store	
GOTO shift_digits	
two_act MOVLW D'2'	;copy digit to store and append to end of value base10
MOVWF store	
GOTO shift_digits	
three_act MOVLW D'3'	;copy digit to store and append to end of value base10
MOVWF store	
GOTO shift_digits	
four_act MOVLW D'4'	;copy digit to store and append to end of value base10
MOVWF store	
GOTO shift_digits	
five_act MOVLW D'5'	;copy digit to store and append to end of value base10
MOVWF store	
GOTO shift_digits	
six_act MOVLW D'6'	;copy digit to store and append to end of value base10
MOVWF store	
GOTO shift_digits	
seven_act MOVLW D'7'	;copy digit to store and append to end of value base10
MOVWF store	
GOTO shift_digits	
eight_act MOVLW D'8'	;copy digit to store and append to end of value base10
MOVWF store	
GOTO shift_digits	
nine_act MOVLW D'9'	;copy digit to store and append to end of value base10
MOVWF store	
GOTO shift_digits	
zero_act MOVLW D'0'	;copy digit to store and append to end of value base10
MOVWF store	
GOTO shift_digits	
shift_digits	
	;Multiply by 10 by Multiplying by 2,8 and adding
	;Multiply by 2, by register rotation
CLRF temp	
RLF value_lo, F	;2*
BCF value_lo,0	;ensures zero is shifted in

```

BTFSC STATUS, C           ;uses temp as carry flag holder
BSF temp,0
RLF value_hi, F           ;2*
BCF value_lo,0            ;ensures zero is shifted in
BTFSC STATUS,C           ;test to ensure number is in 16bit
                           range

GOTO overflow
BTFSC temp,0              ;carry bit in temporary flag
BSF value_hi,0            ;
                           ;keep temp_value for later addition

MOVF value_lo, W
MOVWF temp_value_lo
MOVF value_hi, W
MOVWF temp_value_hi

                           ;Multiply by 4, by register rotation

CLRF temp
RLF value_lo, F           ;2*
BCF value_lo,0            ;ensures zero is shifted in
BTFSC STATUS, C           ;uses temp as carry flag holder
BSF temp,0
RLF value_hi, F           ;2*
BCF value_hi,0            ;ensures zero is shifted in
BTFSC STATUS,C           ;test to ensure number is in 16bit
                           range

GOTO overflow
BTFSC temp,0              ;carry bit in temporary flag
BSF value_hi,0            ;

                           ;Multiply by 8, by register rotation

CLRF temp
RLF value_lo, F           ;2*
BCF value_lo,0            ;ensures zero is shifted in
BTFSC STATUS, C           ;uses temp as carry flag holder
BSF temp,0
RLF value_hi, F           ;2*
BCF value_hi,0            ;ensures zero is shifted in
BTFSC STATUS,C           ;test to ensure number is in 16bit
                           range

GOTO overflow
BTFSC temp,0              ;carry bit in temporary flag
BSF value_hi,0            ;

                           ;Add x*2 + x*8 to make 10*x

MOVF temp_value_lo,W
ADDWF value_lo,F          ;Add lowest bits
BTFSS STATUS,C            ;Test for carry to higher bits
GOTO shift_digits_no_overflow;No carry
INCF temp_value_hi, F      ;increment hi from carry
BTFSC STATUS,Z            ;if carry out occurred
                           temp_value_hi==0
GOTO overflow              ;display overflow error
shift_digits_no_overflow
MOVF temp_value_hi,W      ;Add higher byte
ADDWF value_hi,F

```

```

BTFSC STATUS,C           ;test for overflow
GOTO overflow

                                ;Add digit stored in store
                                ;Add store to value
MOVF store,W
ADDWF value_lo,F
MOVLW d'0'               ;Trick for conditional increment and
                                test without labels
BTFSC STATUS,C           ;If carry, add 1 instead of 0
MOVLW d'1'
ADDWF value_hi,F         ;Add 1 or 0 to execute or not
                                execute carry
BTFSC STATUS,C           ;Test for overflow
GOTO overflow
CALL write_value         ;update displayed value
GOTO main                ;RETURN to main loop

equ_function              ;Actually does the execution of
                                calculating functions
MOVF operator,W          ;Tests if operator matches + code
XORLW D'0'
BTFSC STATUS, Z           ;If yes go to designated subroutine
GOTO actual_add
MOVF operator,W          ;Tests if operator matches - code
XORLW D'1'
BTFSC STATUS, Z           ;If yes go to designated subroutine
GOTO actual_sub
MOVF operator,W          ;Tests if operator matches * code
XORLW D'2'
BTFSC STATUS, Z           ;If yes go to designated subroutine
GOTO actual_mul
MOVF operator,W          ;Tests if operator matches / code
XORLW D'3'
BTFSC STATUS, Z           ;If yes go to designated subroutine
GOTO actual_div
GOTO unexpected_error     ;Abnormal operator code, display
                                error code
back_to_equ_function RETURN ;After calculations RETURN to CALL
                                point

actual_add                ;subroutine for adding old_value and
                                value
MOVF old_value_lo,W      ;Add low bytes
ADDWF value_lo,F
BTFSS STATUS, C           ;Test if carry out of low byte
                                occurred
GOTO add_no_carry
INCF old_value_hi, F      ;Execute carry
BTFSC STATUS,Z           ;If hi byte carried out it==0
GOTO overflow            ;display overflow code
add_no_carry
MOVF old_value_hi,W      ;Add hi bytes
ADDWF value_hi,F

```



```

    BTFSC STATUS, C           ;Test if overflow occurred
    GOTO overflow
    GOTO back_to_equ_function ;equ_function for display and
                             further RETURN

actual_mul                    ;Multiplication via binary algorithm
    MOVFW value_lo            ;keep value in temp_value for
                             manipulation
    MOVWF temp_value_lo
    MOVFW value_hi
    MOVWF temp_value_hi
    CLRF value_hi             ;clear value - it will be used as
                             output
    CLRF value_lo
    CLRF temp                 ;temp will count number of bit
                             shifts executed - target 16
    BCF update_flag,2
mul_loop_bit
    INCF temp,F               ;increment loop counter
    BTFSS temp_value_lo,0     ;Tests lowest bit to see if value is
                             to be added
    GOTO mul_no_add           ;Adds old_value to value

    BTFSC update_flag,2
    GOTO overflow
    MOVF old_value_lo,W       ;Adds lower bytes
    ADDWF value_lo,F
    BTFSS STATUS, C           ;Tests for carry
    GOTO mul_no_carry
    INCF value_hi, F           ;Executes carry to hi byte
    BTFSC STATUS,Z            ;Tests if 16bit overflow occurred
    GOTO overflow
mul_no_carry
    MOVF old_value_hi,W       ;Added high bytes
    ADDWF value_hi,F
    BTFSC STATUS, C           ;Tests if 16bit overflow occurred
    GOTO overflow
mul_no_add
                             ;Multiplies old_value by 2
    RLF old_value_lo,F         ;rotate lower byte
    RLF old_value_hi,F         ;rotate higher byte - carry handled
                             by STATUS,C
    BTFSC STATUS,C            ;Test if 16bit overflow occurred
    BSF update_flag,2
    BCF old_value_lo,0         ;Ensure new bit is==0
    RRF temp_value_hi,F       ;Prepare new bit for conditional
                             addition
    RRF temp_value_lo,F
    BCF temp_value_hi,7        ;Ensure new bit is=0-not necessary
                             but keeps code nice
    MOVFW temp                ;Testing if loop run 16 times
    XORLW d'16'

```

```

        BTFSS STATUS,Z                ;If no repeat
        GOTO mul_loop_bit
end_mul GOTO back_to_equ_function
                                ;equ_function for display and
                                further RETURN

actual_sub
    BCF update_flag,7                ;clears the minus sign flag
    MOVF value_lo,W                  ;subtracts low bytes
    SUBWF old_value_lo, F
    BTFSC STATUS, C                  ;tests if borrow occurred
    GOTO sub_no_carry
    DECF old_value_hi, F              ;borrows bit from high byte
    MOVFW old_value_hi
    XORLW d'255'                     ;Tests if borrow there was something
                                    to borrow from

    BTFSC STATUS,Z
    BSF update_flag,7                ;If no then set minus sign
sub_no_carry
    MOVF value_hi,W                  ;Subtracts high bytes
    SUBWF old_value_hi, F
    BTFSS STATUS, C                  ;If borrow occurred - nothing to
    borrow from
    BSF update_flag,7                ;Set minus sign
    BTFSS update_flag,7              ;Test if numbers need to be adjusted
    for minus
    GOTO sub_no_neg

                                    ;Execute two's compliment conversion
    if minus is present
    MOVFW old_value_lo                ;XOR with 11111111 == flip all bits
    XORLW d'255'                     ;this is twos compliment notation
    MOVWF old_value_lo
    MOVFW old_value_hi                ;XOR with 11111111 == flip all bits
    XORLW d'255'                     ;this is twos compliment notation
    MOVWF old_value_hi
    INCF old_value_lo,F               ;Compensate for zero not being
    negative by adding 1

    BTFSC STATUS,Z
    INCF old_value_hi
sub_no_neg
    MOVF old_value_lo, W              ;Store result in value so it will be
    displayed

    MOVWF value_lo
    MOVF old_value_hi, W
    MOVWF value_hi
sub_end GOTO back_to_equ_function
                                ;equ_function for display and
                                further RETURN

actual_div                        ;Division via repeated subtraction
    MOVFW value_lo                    ;Test if lower byte of right operand
    is ==0

```

```

XORLW d'0'
BTFSS STATUS,Z
GOTO no_div_zero
MOVFW value_hi                ;Test if higher byte of right
                                operand is ==0

XORLW d'0'
BTFSC STATUS,Z
GOTO unexpected_error        ;Output an Error as division by 0 is
                                undefined

no_div_zero
    MOVFW value_lo            ;copy value to temp_value for
                                manipulation
    MOVWF temp_value_lo
    MOVFW value_hi
    MOVWF temp_value_hi
    CLRF value_lo             ;value will be used as output
    CLRF value_hi

div_sub_loop
    MOVFW temp_value_lo        ;Subtract lower bytes
    SUBWF old_value_lo,F
    BTFSC STATUS,C             ;Check for a borrow from high byte
    GOTO div_no_borrow
    DECF old_value_hi,F        ;Borrow from high byte
    MOVFW old_value_hi
    XORLW d'255'              ;Test if high byte went negative
    BTFSC STATUS,Z
    GOTO div_sub_end           ;If yes GOTO ending

div_no_borrow
    MOVFW temp_value_hi        ;Subtract higher bytes
    SUBWF old_value_hi,F
    BTFSS STATUS,C             ;Check if result went negative -
                                borrow from non existent byte

    GOTO div_sub_end
    INCF value_lo,F            ;Increment counter on number of
                                successful subtractions

    BTFSC STATUS,Z
    INCF value_hi,F            ;Carry into high byte
    GOTO div_sub_loop

div_sub_end
    MOVFW temp_value_lo        ;fix offset in low byte for one too
                                many subtractions

    ADDWF old_value_lo,F
    BTFSC STATUS,C             ;carry addition to high byte
    INCF old_value_hi,F
    MOVFW temp_value_hi        ;fix offset in high byte for one too
                                many subtractions

    ADDWF old_value_hi,F
    BCF update_flag,4          ;Remainder flag=0
    MOVFW old_value_lo
    XORLW d'0'                ;Test if division was exact in low
                                byte

```

```

    BTFSS STATUS,Z
    BSF update_flag,4           ;Remainder flag=1
    MOVFW old_value_hi
    XORLW d'0'                  ;Test if division was exact in high
                                byte
    BTFSS STATUS,Z
    BSF update_flag,4
end_div GOTO back_to_equ_function

write_value                     ;writes value_hi,value_lo to the
                                display
    BSF PORTA,0                ;prepare display modules for data
                                transfer
    MOVF value_hi, W           ;use temp_value to prevent changing
                                value as it will be used in
                                calculations
    MOVWF temp_value_hi
    MOVF value_lo, W
    MOVWF temp_value_lo
    CLRF store                  ;store will count the number of
                                characters already displayed target-6
    BTFSS update_flag,4        ;Was division result exact or with a
                                remainder?
    GOTO no_remainder
    INCF store,F                ;Increment number of characters
                                displayed
    MOVLW b'10100010'          ;Display code for reminder -looks
                                like a r.
    MOVWF out_value_lo
    CLRF temp                   ;Temp will count number of bits
                                shifted - target 8 (7 segments +
                                decimal point)
shift_loop_remainder
    INCF temp,F                 ;Increment counter of bits shifted
                                out
    BCF PORTA,2                 ;Set data pin to 0
    BTFSC out_value_lo,0        ;If data pin is meant to be 1
    BSF PORTA,2                 ;make it 1
    BCF PORTA,1                 ;raise the clock - shift value
    RRF out_value_lo,F          ;prepare to shift out next bit
    BSF PORTA,1                 ;fall the clock
    MOVFW temp                  ;Tests if all 8 bits were shifted
                                out
    XORLW d'8'
    BTFSS STATUS,Z              ;If yes continue to next step
    GOTO shift_loop_remainder
no_remainder
    CLRF out_value_lo           ;out_value will store integer part
                                of division by 10
    CLRF out_value_hi           ;temp will store remainder of
                                division by 10

write_loop

```

```

INCF out_value_lo, F      ;counts the number of 10s subtracted
BTFSC STATUS,Z           ;carry when counting 10s
INCF out_value_hi, F      ;Division ensures no 16bit overflow
MOVLW D'10'
SUBWF temp_value_lo,F     ;actually subtracts the 10 from temp
BTFSC STATUS,C           ;checks if a borrow occurred
GOTO write_loop           ;Subtract another 10
MOVF temp_value_hi,W
BTFSC STATUS,Z           ;If all temp_value is <0 division
                           finishes. Must be zero at one point
                           as 10<255
GOTO write_digit_calc     ;Process done, move to next step
DECF temp_value_hi,F      ;borrow from hi byte
GOTO write_loop           ;Subtract another 10
write_digit_calc
MOVLW D'10'              ;Compensates for 10 subtracted to
                           make temp_value negative
ADDWF temp_value_lo,F
DECF out_value_lo,F       ;Compensates counter for added 10
MOVFW out_value_lo
XORLW d'255'             ;check borrow from hi byte
BTFSC STATUS,Z
DECF out_value_hi,F      ;Execute borrow from high
INCF store,F             ;Tracks number of characters written
                           to display
MOVFW temp_value_lo      ;Look up code for calculated
                           character
CALL segment_look        ;Access table
MOVWF temp_value_lo
CLRF temp                ;Temp will count number of bits
                           shifted - target 8 (7 segments +
                           decimal point)
shift_loop_main
INCF temp,F              ;Count number of bits shifted out
BCF PORTA,2              ;Copy temp_value_lo,0 into PORTA,2
BTFSC temp_value_lo,0
BSF PORTA,2
BCF PORTA,1              ;Raise the clock - shift value
RRF temp_value_lo,F      ;Prepare next bit in temp_value_lo
                           while waiting for display value
BSF PORTA,1              ;Fall the clock
MOVFW temp               ;Test if 8 bits already shifted out
XORLW d'8'
BTFSS STATUS,Z
GOTO shift_loop_main     ;If no shift out next bit
BCF update_flag,6        ;Clean bit for temporary bit flag
MOVF out_value_hi,W
MOVWF temp_value_hi      ;Copy low byte of integer part of
                           division by 10 for next division
BTFSC STATUS, Z          ;If ==0 to copy remember in
                           temporary flag
BSF update_flag,6

```

```

MOVWF out_value_lo, W
MOVWF temp_value_lo      ;Copy hi byte of integer part of
                           division by 10 for next division
BTFSS STATUS, Z          ;Test if ==0 for finishing condition
GOTO no_remainder        ;Run division loop again
BTFSS update_flag,6      ;If both hi and low byte ==0
                           continue to next section
GOTO no_remainder        ;Run division loop again
BTFSS update_flag,7      ;If minus sign flag clear then
GOTO no_negative         ;Don't display a minus
INCF store,F             ;Count number of characters written
MOVLW b'00100000'        ;Display code for a minus sign -
MOVWF temp_value_lo
CLRF temp                ;Temp will count number of bits
                           shifted - target 8 (7 segments +
                           decimal point)

shift_loop_neg
  INCF temp,F             ;Count number of bits shifted out
  BCF PORTA,2            ;Copy temp_value_lo,0 into PORTA,2
  BTFSC temp_value_lo,0
  BSF PORTA,2
  BCF PORTA,1            ;Raise the clock - shift value
  RRF temp_value_lo,F     ;Prepare next bit in temp_value_lo
                           while waiting for display value
  BSF PORTA,1            ;Fall the clock
  MOVFW temp             ;Test if 8 bits already shifted out
  XORLW d'8'
  BTFSS STATUS,Z
  GOTO shift_loop_neg    ;If no shift out next bit

no_negative
  BCF update_flag,7      ;Clear minus sign flag
  BCF update_flag,4      ;Clear reminder flag
  MOVFW store            ;Tests if all 6 characters are
                           written to
  XORLW d'6'
  BTFSC STATUS,Z
  RETURN                ;If yes: RETURN to CALL point
  INCF store,F           ;Count number of characters written
                           to display
  BCF PORTA,2            ;Shift outs b'00000000' - an empty
                           character
  CLRF temp              ;Temp will count number of bits
                           shifted - target 8 (7 segments +
                           decimal point)

shift_loop_null
  INCF temp,F            ;Count number of bits shifted out
  BCF PORTA,1            ;Raise the clock - shift value
                           ;Delay not need as display PIC runs
                           with a faster clock speed
  BSF PORTA,1            ;Fall the clock
  MOVFW temp             ;Test if 8 bits already shifted out
  XORLW d'8'

```

```

    BTFSS STATUS,Z
    GOTO shift_loop_null      ;If no shift out next bit
    GOTO no_negative

                                ;Subroutines for handling exceptions
                                in the code

multi_key                      ;triggers when two buttons are
                                pressed simultaneously and PIC can't
                                distinguish them
    BSF PORTA,0                ;Prepare display modules for data
    MOVLW b'10001111'         ;multi key press code. Two Parallel
                                line followed by a period

    MOVWF temp_value_lo
    CLRF temp                  ;Temp will count number of bits
                                shifted - target 8 (7 segments +
                                decimal point)

shift_loop_multi
    INCF temp,F                ;Count number of bits shifted out
    BCF PORTA,2                ;Copy temp_value_lo,0 into PORTA,2
    BTFSC temp_value_lo,0
    BSF PORTA,2
    BCF PORTA,1                ;Raise the clock - shift value
    RRF temp_value_lo,F        ;Move to next bit in temp_value_lo
    BSF PORTA,1                ;Fall the clock
    MOVFW temp                 ;Test if 8 bits already shifted out
    XORLW d'8'
    BTFSS STATUS,Z
    GOTO shift_loop_multi     ;If no shift out next bit
    GOTO main                  ;resume normal operation

overflow                      ;Indicates program encountered a
                                16bit overflow while performing large
                                calculation
    BSF PORTA,0                ;Prepare display modules for data
    MOVLW b'11101010'         ;Display a F. symbol to indicate
                                operation Failed

    MOVWF temp_value_lo
    CLRF temp                  ;Temp will count number of bits
                                shifted - target 8 (7 segments +
                                decimal point)

shift_loop_overflow
    INCF temp,F                ;Count number of bits shifted out
    BCF PORTA,2                ;Copy temp_value_lo,0 into PORTA,2
    BTFSC temp_value_lo,0
    BSF PORTA,2
    BCF PORTA,1                ;Raise the clock - shift value
    RRF temp_value_lo,F        ;Move to next bit in temp_value_lo
    BSF PORTA,1                ;Fall the clock
    MOVFW temp                 ;Test if 8 bits already shifted out
    XORLW d'8'
    BTFSS STATUS,Z
    GOTO shift_loop_overflow  ;If no shift out next bit
    GOTO main                  ;resume normal operation

```

```

unexpected_error          ;Signifies a unclassified error
                           occurred. EG division by 0
    BSF PORTA,0            ;Prepare display modules for data
    MOVLW b'11111010'     ;Display a E. symbol to indicate and
                           Error
    MOVWF temp_value_lo
    CLRF temp              ;Temp will count number of bits
                           shifted - target 8 (7 segments +
                           decimal point)
shift_loop_error
    INCF temp,F            ;Count number of bits shifted out
    BCF PORTA,2            ;Copy temp_value_lo,0 into PORTA,2
    BTFSC temp_value_lo,0
    BSF PORTA,2
    BCF PORTA,1            ;Raise the clock - shift value
    RRF temp_value_lo,F    ;Move to next bit in temp_value_lo
    BSF PORTA,1            ;Fall the clock
    MOVFW temp             ;Test if 8 bits already shifted out
    XORLW d'8'
    BTFSS STATUS,Z
    GOTO shift_loop_error  ;If no shift out next bit
    GOTO main              ;resume normal operation

    END                    ;Opcode need for compilation. PIC
                           should never reach this

```



```

;-----;
; PIC#2,3 Code ;
;-----;
; Program title: 8-bit Multiplexing Shift Register ;
;-----;
; Written by: Michal Adamkiewicz ;
;-----;
; Date: 19th September 2014 ;
;-----;
; Version: 1.0 ;
;-----;
; Device: PIC16F627 ;
;-----;
; Oscillator: Internal 4 MHz ;
;-----;

```

```

LIST P=PIC16F627A ;select device
;Tells MPLAB what processor IC is being used

```

```

INCLUDE c:\program files (x86)\microchip\MPASM Suite
\P16F627A.inc
;include header file
;from default location
;tells the MPLAB where to find the files

```

```

__config 0x3F10
;sets config to; internal I/O, no watchdog,Power
;up timer on, master Reset off,
;no brown-out, no LV program, no read protect,
;no code protect

```

```

;-----;
; DEFINE REGISTERS ;
;-----;

```

```

cblock 0x20
    dig_one ;Three registers store what to be
            displayed on the 3 characters
    dig_two
    dig_three
    loop ;This stores the current loop time
endc

```

```

init
    MOVLW d'07'
    MOVWF CMCON ;Disable comparators
    BSF STATUS, RP0 ;select bank1 for setup
    BSF PCON, OSCF ;select 4 MHz
    MOVLW b'01110000'
    MOVWF TRISA ;set PortA as inputs on designated pins

```

```

    MOVLW b'00000000'
    MOVWF TRISB           ;set PortB all outputs
    BCF STATUS, RP0       ;return to bank0 for program operation

    CLRF dig_one           ;clear registers to prevent ghosting
    CLRF dig_two
    CLRF dig_three

main
    BTFSC PORTA,5          ;Test if Programing mode (shift in) was
                           activated
    GOTO prog

    BCF PORTA,2            ;Prepare pin to sink current from diodes
    MOVFW dig_three        ;Move stored values onto PORTB
    MOVWF PORTB
    MOVLW b'00011111'      ;Delay amount established experimentally
    MOVWF loop
    CALL delay             ;Delay ensures display is visible to
                           human eye
    BSF PORTA,2

    BCF PORTA,1            ;Prepare pin to sink current from diodes
    MOVFW dig_two          ;Move stored values onto PORTB
    MOVWF PORTB
    MOVLW b'00011111'      ;Delay amount established experimentally
    MOVWF loop
    CALL delay             ;Delay ensures display is visible to
                           human eye
    BSF PORTA,1

    BCF PORTA,0            ;Prepare pin to sink current from diodes
    MOVFW dig_one          ;Move stored values onto PORTB
    MOVWF PORTB
    MOVLW b'00011111'      ;Delay amount established experimentally
    MOVWF loop
    CALL delay             ;Delay ensures display is visible to
                           human eye
    BSF PORTA,0
    GOTO main              ;Loop back to top

prog                        ;Programing mode - PIC accepts serial data
    BTFSS PORTA,5          ;Test if Programing mode disabled
    GOTO main              ;return to multiplexing
    BTFSC PORTA,4          ;Wait for Clock pin to go low
    GOTO prog

wait BTFSS PORTA,4         ;Wait for it to go back to high
    GOTO wait

    RRF dig_three, F       ;Shift register over by one bit
    BCF dig_three,7        ;Ensures register has bit
    BTFSC dig_two,0        ;carried from next register

```

```

BSF dig_three,7

RRF dig_two, F      ;Shift register over by one bit
BCF dig_two,7       ;Ensures register has bit
BTFSC dig_one,0     ;carried from next register
BSF dig_two,7

RRF dig_one, F      ;Shift register over by one bit
BCF dig_one,7       ;Take the new bits value from
BTFSC PORTA,6       ;the Data Pin
BSF dig_one,7

BCF PORTA,7         ;Copy last bit to Output pin
BTFSC dig_three,0   ;for chaining to other modules
BSF PORTA,7

GOTO prog           ;Wait for another bit shift

delay DECFSZ loop, F ;Count down until zero
    GOTO delay
RETURN              ;end delay

END                 ;Opcode need for compilation. PIC should
                    never reach this

```