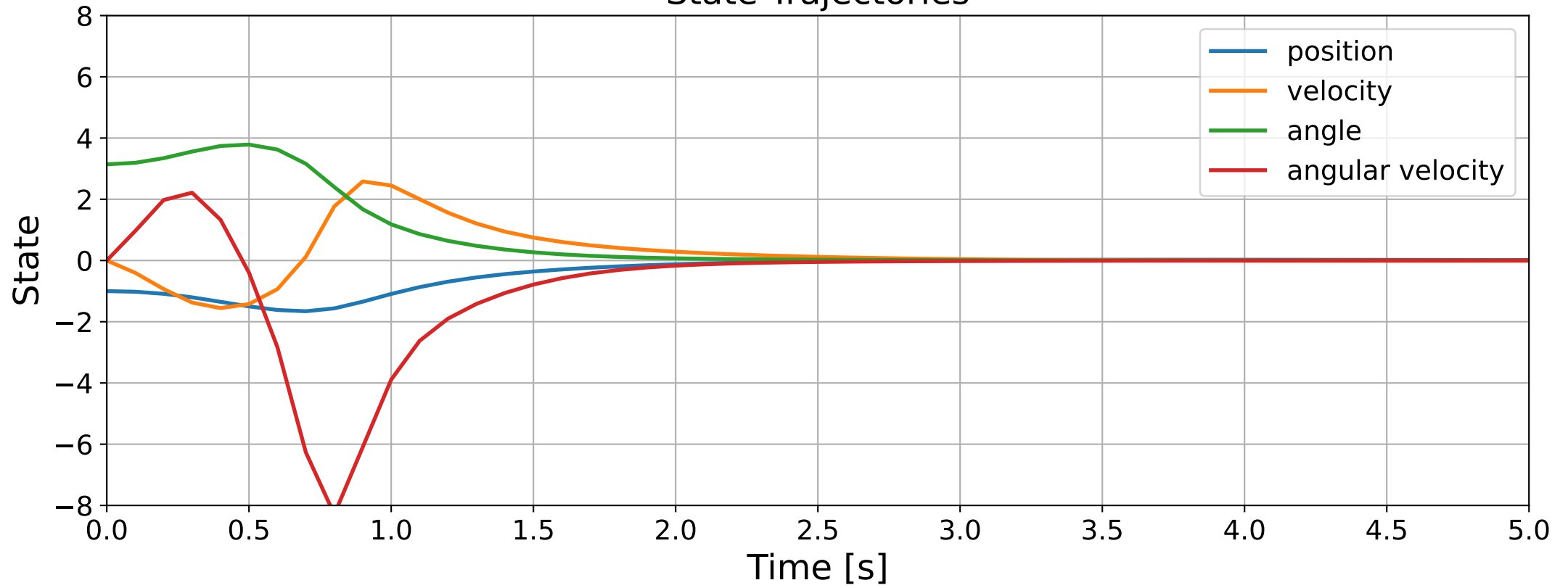


### State Trajectories



### Control Trajectory

