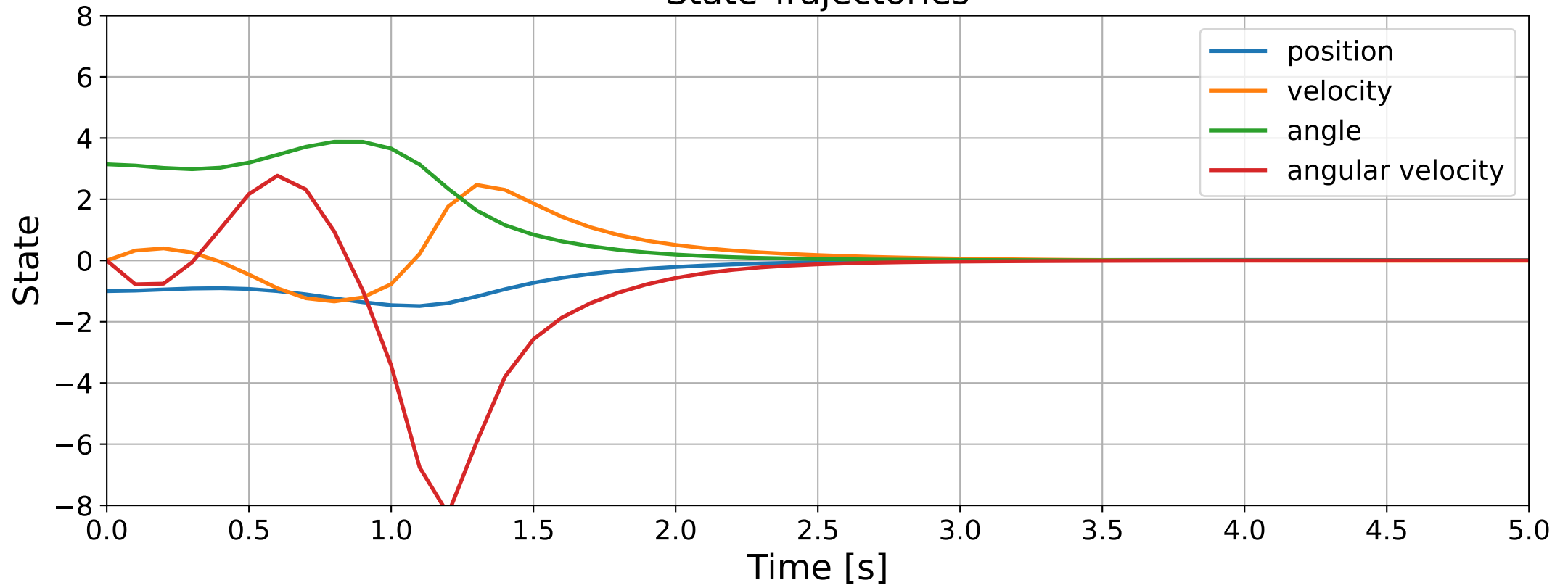


State Trajectories



Control Trajectory

