

Ch. 7: Fourier Transforms

Fourier Transform

- A Fourier transform converts a physical-space (or time series) representation of a function into frequency space
 - Equivalent representation of the function, but gives a new window into its behavior.
 - Inverse operation exists

$$F(k) = \int_{-\infty}^{\infty} f(x)e^{-2\pi ixk}dx \qquad f(x) = \int_{-\infty}^{\infty} F(k)e^{2\pi ixk}dx$$

 You can think of F(k) as being the amount of the function f represented by frequency k

Fourier Transform

- For discrete data, the discrete analog of the Fourier transform gives:
 - Amplitude and phase at discrete frequencies (wavenumbers)
 - Allows for an investigation into the periodicity of the discrete data
 - Allows for filtering in frequency space
 - Can simplify the solution of PDEs: derivatives change into multiplications in frequency space

Discrete Fourier Transform

$$F(k) = \int_{-\infty}^{\infty} f(x)e^{-2\pi ixk}dx$$

$$f(x) = \int_{-\infty}^{\infty} F(k)e^{2\pi ixk}dx$$

- The discrete Fourier transform (DFT) operates on discrete data
 - Usually we have evenly-spaced, real data.
 - For example, a time-series from an experiment
 - Simulation data for a velocity field
- DFT transforms the N spatial/temporal points into N frequency points. Transform = F_k ; Inverse f_n .

$$F_k = \sum_{n=0}^{N-1} f_n e^{-2\pi i nk/N} \qquad f_n = \frac{1}{N} \sum_{n=0}^{N-1} F_k e^{2\pi i nk/N}$$

Notation

$$F_k = \sum_{n=0}^{N-1} f_n e^{-2\pi i nk/N} \quad f_n = \frac{1}{N} \sum_{n=0}^{N-1} F_k e^{2\pi i nk/N}$$

- Many different notations are used in various textbooks and papers.
 - Original function: f(x) or f(t)
 - Transformed function: $F(k), \mathcal{F}(k), \hat{f}(n)$
- For the discrete version:
 - Original function: f_n
 - Transformed function: $F_k, \mathcal{F}_k, \hat{f}_k$

Real space vs. frequency space

- What are the significance of the real and imaginary parts?
 - Recall that we are integrating with $e^{-2\pi ikx}$
 - Euler's formula: $e^{ix} = \cos x + i \sin x$
 - Real part represents the cosine terms, symmetric functions
 - Imaginary part represents the sine terms, asymmetric functions
 - · Can also think in terms of an amplitude and a phase

• If
$$f_n$$
 is real, then $\operatorname{Re}(F_k) = \sum_{n=0}^{N-1} f_n \cos\left(\frac{2\pi nk}{N}\right)$ $\operatorname{Im}(F_k) = \sum_{n=0}^{N-1} f_n \sin\left(\frac{2\pi nk}{N}\right)$

DFT Example

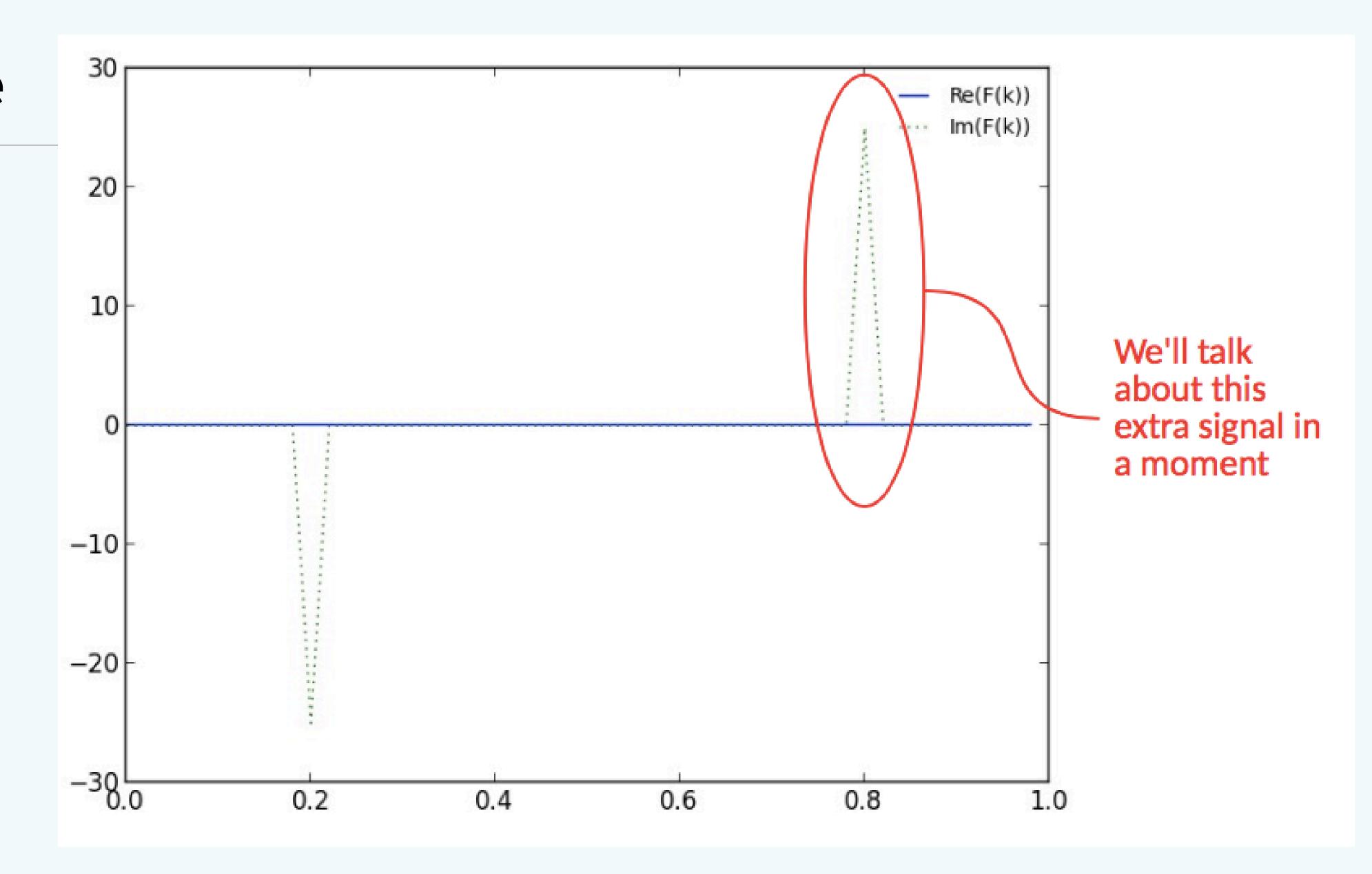
$$F_k = \sum_{n=0}^{N-1} f_n e^{-2\pi i n k/N}$$

- Implementing the discrete Fourier transform is straightforward
 - Double sum: for each wavenumber, we sum over all the spatial points

```
def dft(f_n):
    N = len(f_n)
    f_k = np.zeros(N, dtype=np.complex128)
    for k in range(N):
        for n in range(N):
        f_k += f_n[n] * np.exp(-2*np.pi*1j*n*k/N)
    return f_k
```

DFT Example

• DFT of $\sin(2\pi f_0x)$ with $f_0 = 0.2$



Frequencies

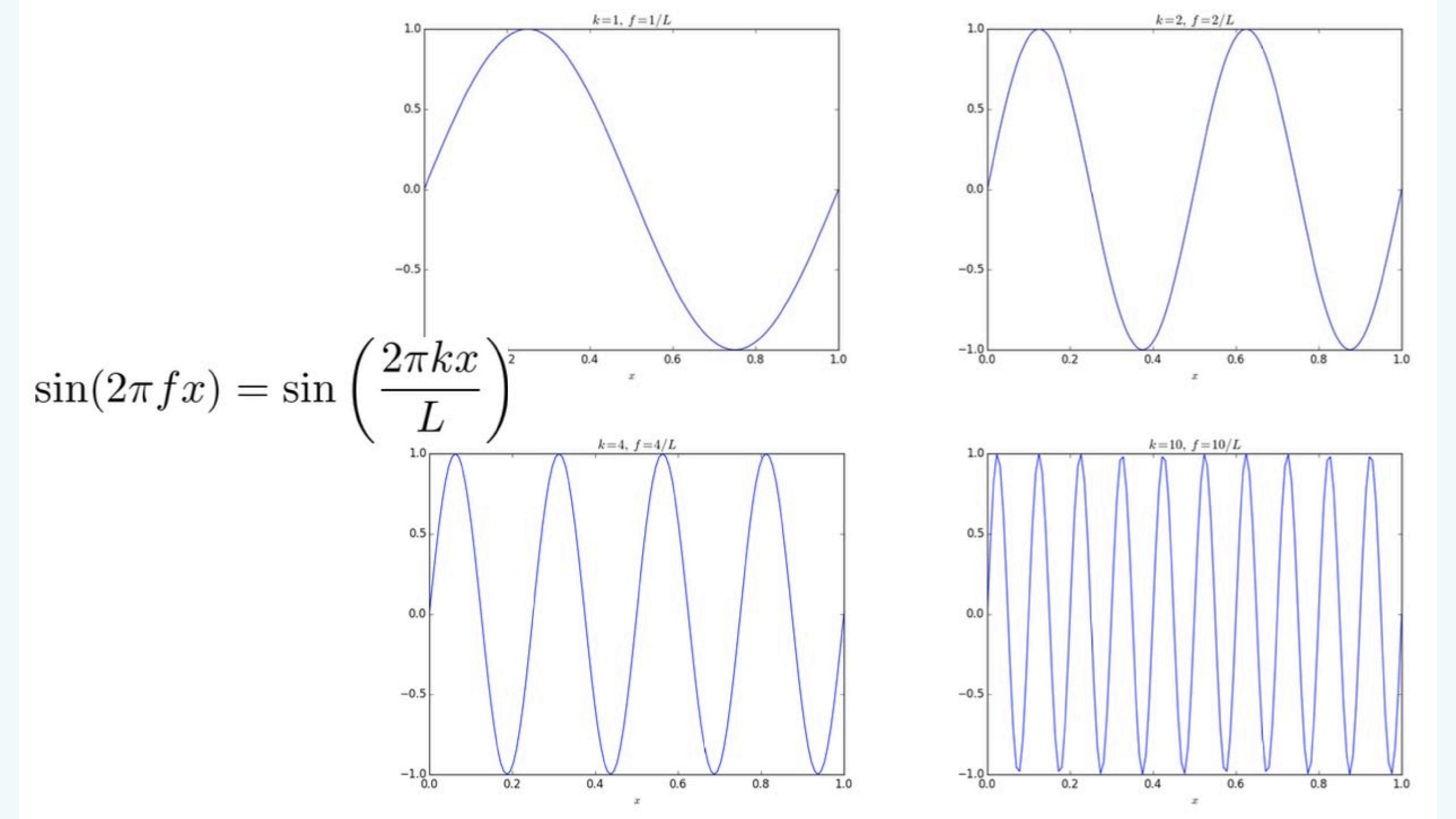
- Note that in the DFT, nowhere does the physical coordinate value x_n , enter instead, we just look at the index n itself
 - This assumes that the data is regular gridded
- In this index space, the smallest wavelength is from one cell to the next, and the smallest frequency is 1/N
 - Note that this means that if we add points to our data, then we open up higher and higher frequencies (in terms of index space)

Frequencies

Clearly there is a physical scale for the frequency

$$u_k = \frac{k}{N} \cdot \frac{1}{\Delta x} = \frac{k}{N} \cdot \frac{N}{L}$$

- Lowest frequency: 1/L
- Highest frequency: $\sim 1/\Delta x$



Frequencies

• k = 0 is special:

$$Re(F_0) = \sum_{n=0}^{N-1} f_n \cos\left(\frac{2\pi n0}{N}\right) = \sum_{n=0}^{N-1} f_n$$

$$Im(F_0) = \sum_{n=0}^{N-1} f_n \sin\left(\frac{2\pi n0}{N}\right) = 0$$

This is sometimes called the DC offset

FFT = DFT

- The Fast Fourier Transfer (FFT) is equivalent to the discrete Fourier transform
 - Faster because of special symmetries exploited in performing sums
 - The calculation expense scale as (N log N) instead of (N²)
- We won't investigate how FFTs work, but there are details in the book

Normalization

 Normalization of the forward and inverse transforms follows from Parseval's theorem:

$$\int_{-\infty}^{\infty} |f(x)|^2 dx = \int_{-\infty}^{\infty} |F(k)|^2 dk$$

• Discrete form (taking $\Delta x = 1$ and $\Delta k = 1/N$)

$$\sum_{n=0}^{N-1} |f_n|^2 = \frac{1}{N} \sum_{k=1}^{N-1} |F(k)|^2$$

• The definition of the inverse transformation compatible with this condition is

$$f_n = \frac{1}{N} \sum_{k=0}^{N} F_k e^{2\pi i n k/N}$$

Normalization

- To illustrate this, consider the transform of 1
 - Analytically: $f(x) = 1 \iff F(k) = \delta(k)$
 - Discrete transform:

$$F_k = \sum_{n=0}^{N-1} 1 \cdot e^{-2\pi i k n/N} = \sum_{n=0}^{N-1} \left[\cos(2\pi k n/N) + i \sin(2\pi k n/N) \right]$$

- For k = 0, cos(0) = 1, sin(0) = 0, so $F_0 = N$
- For k > 0, we are essentially doing a discrete sum of the cosine and sine using equally-spaced points, and the sum is always over a multiple of a full wavelength, therefore $F_K = 0$.

Normalization

Discrete inverse transform:

$$f_n = \frac{1}{N} \sum_{k=0}^{N-1} F_k e^{2\pi i nk/N} = \frac{1}{N} N e^{2\pi i n0/N} = 1$$

- When plotting, we want to put the physical scale back in, as well as make the correspondence to the continuous representation
 - Already saw how to put the wave numbers into a physical frequency
 - Rewrite inverse equation

$$f_n = \frac{1}{N} \sum_{k=0}^{N-1} F_k e^{2\pi i n k/N} = \sum_{k=0}^{N-1} \left(\frac{F_k}{N} \right) e^{2\pi i n k/N}$$

Plot this

• Another interpretation: $F_k/N \Leftrightarrow F_k dk$

Real space vs. frequency space

- Imagine transforming a real-valued function f with N data points
 - The FFT of f will have N/2 complex data points
 - Same amount of information in each case, but each complex point corresponds to 2 real numbers
 - This is a consequence of the analytic Fourier transform satisfying
 - $F(-k) = F^*(k)$ if f(x) is real

Real space vs. Frequency space

- Most FFT routines will return N complex points half of them are duplicate, that is, they don't add to the information content
 - Often, there are specific implementations optimized for the case where the function is real (e.g. rfft)
- This affects normalization (note k=0 different)
- This is also referred to as aliasing.
- The maximum frequency, $1/(2\Delta x)$, is called the Nyquist frequency.

Power spectrum

The power spectrum is simply defined as:

$$P(k) = |F(k)|^2 = F(k)F^*(k)$$

- It is a single number showing the importance or weight of a given wavenumber
- Also useful to look at the phase at each wavenumber

Python / Numpy's FFT

- numpy.fft: https://docs.scipy.org/doc/numpy/reference/routines.fft.html
- fft/ifft: 1D data
 - By design, the k=0,...,N/2 data is first, followed by the negative frequencies. The latter are not relevant for a real-valued f(x)
 - k-values can be obtained from fftfreq(n)
 - fftshift(x) shifts the k=0 to the center of the spectrum
- rfft/irfft: 1D real-valued functions. Basically the same as fft/ifft but doesn't return negative frequencies
- 2D and N-D routines are analogously defined

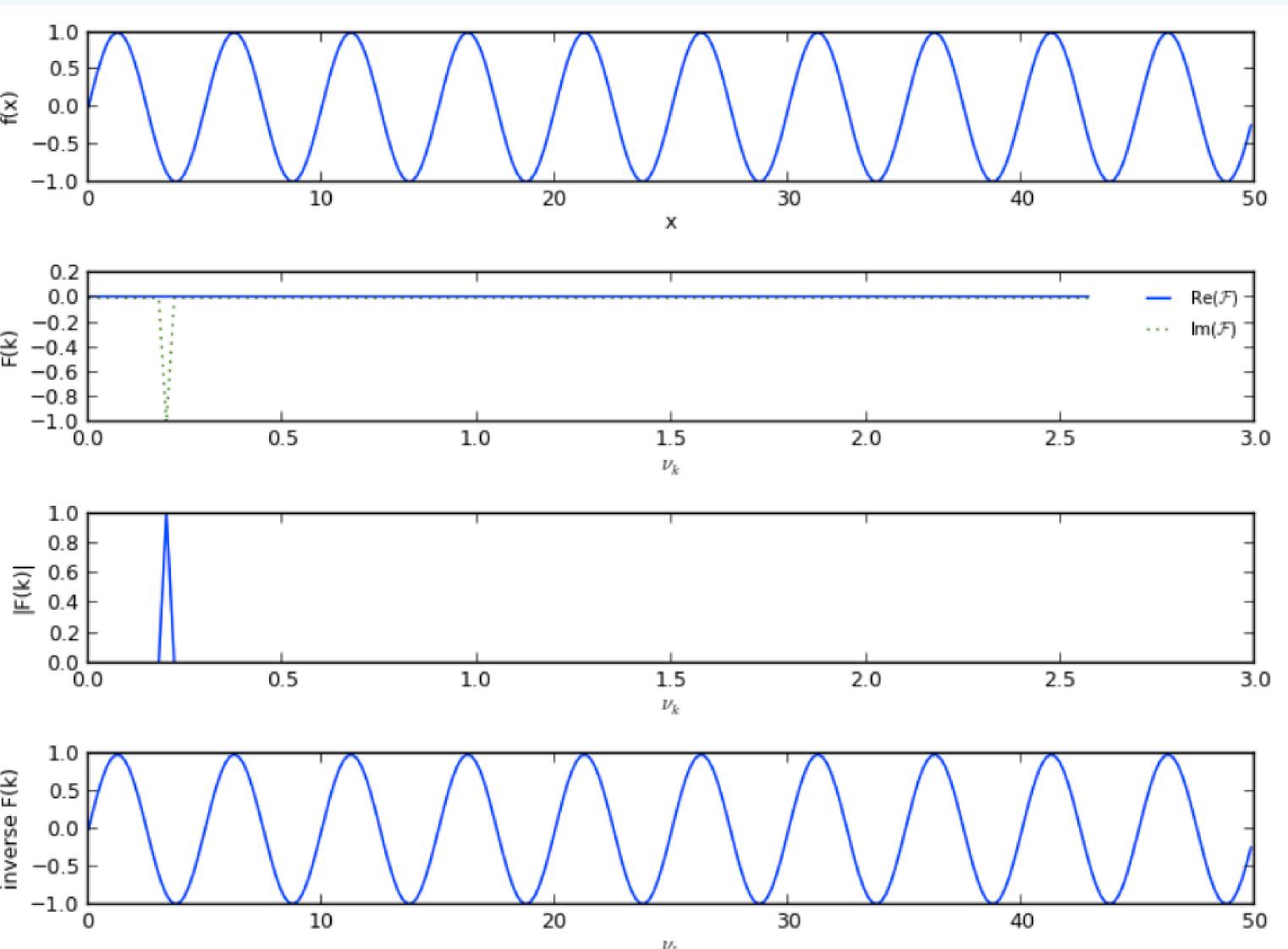
Python's FFT

- It's always a good idea to run some simple tests to make sure the FFT is behaving the way you'd expect
 - sin(2πf₀x) should be purely imaginary at a single wavenumber
 - cos(2πf₀x) should be purely real at a single wavenumber
 - $sin(2\pi f_0x + \pi/4)$ should have equal magnitude real and imaginary parts at a single wavenumber

Example: Single Frequency Sine Function

 ΔM

- Transform a single mode sine ($f_0 = 0.2$) and inverse transform back do you get the original result (to roundoff errors)?
- Notice that the since sine is odd, the FFT is only nonzero in the imaginary component.

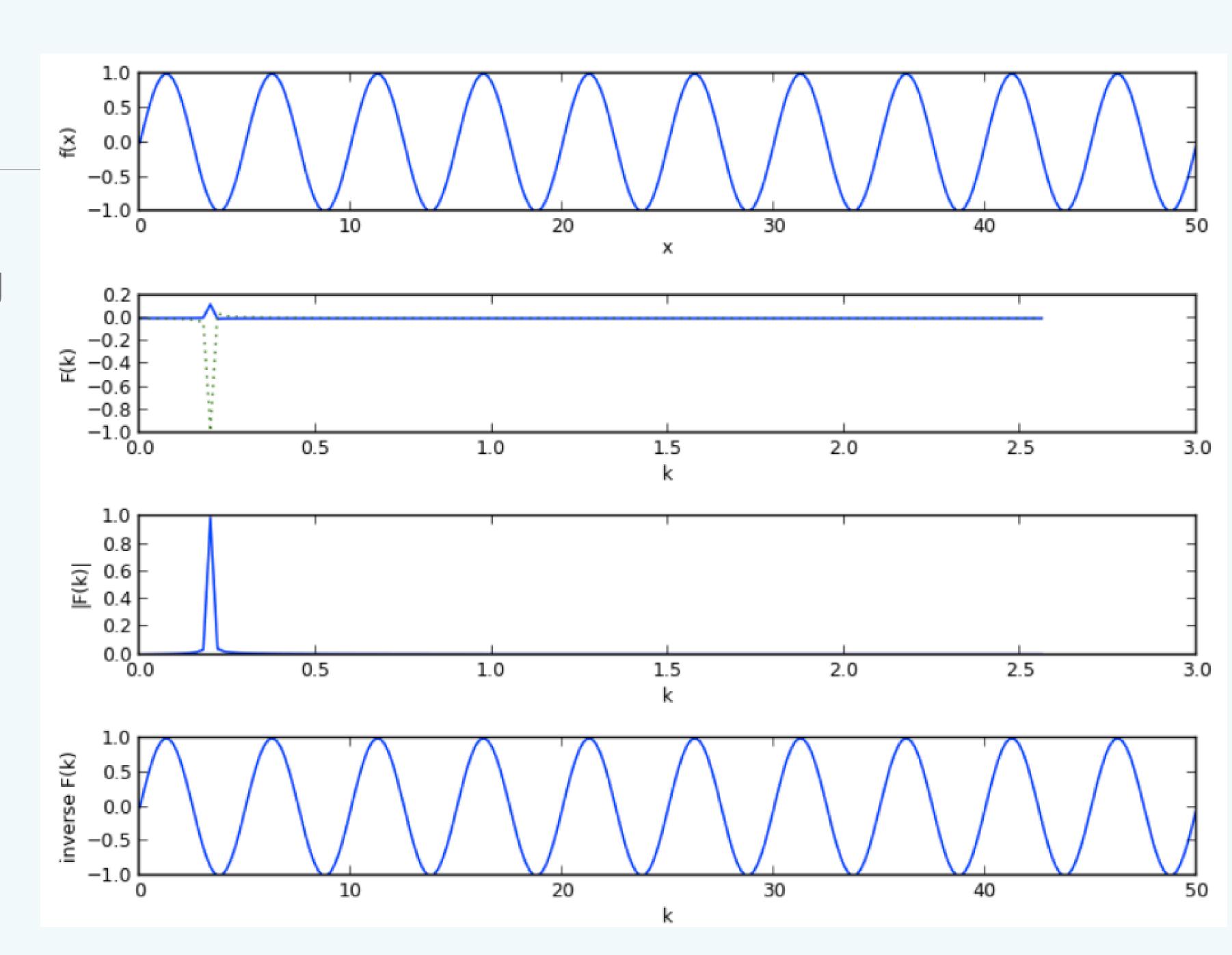


Sample points

- Be careful about how you define the points
 - The FFT considers the data without any spatial coordinates it just considers the distance in terms of the number of points
 - Using the Numpy linspace() routine puts a point at both the start and end of the interval
 - e.g. np.linspace(0, 1, 5) = [0.0.25 0.5 0.75 1.]
 - The FFT routine treats the first and last point as distinct
 - If you define $sin(2\pi x)$ on these data, the first and last points will be equivalent, and the FFT picks up an extra (non-periodic) signal
 - Instead, do np.linspace(0, 1, 5 endpoint=False)

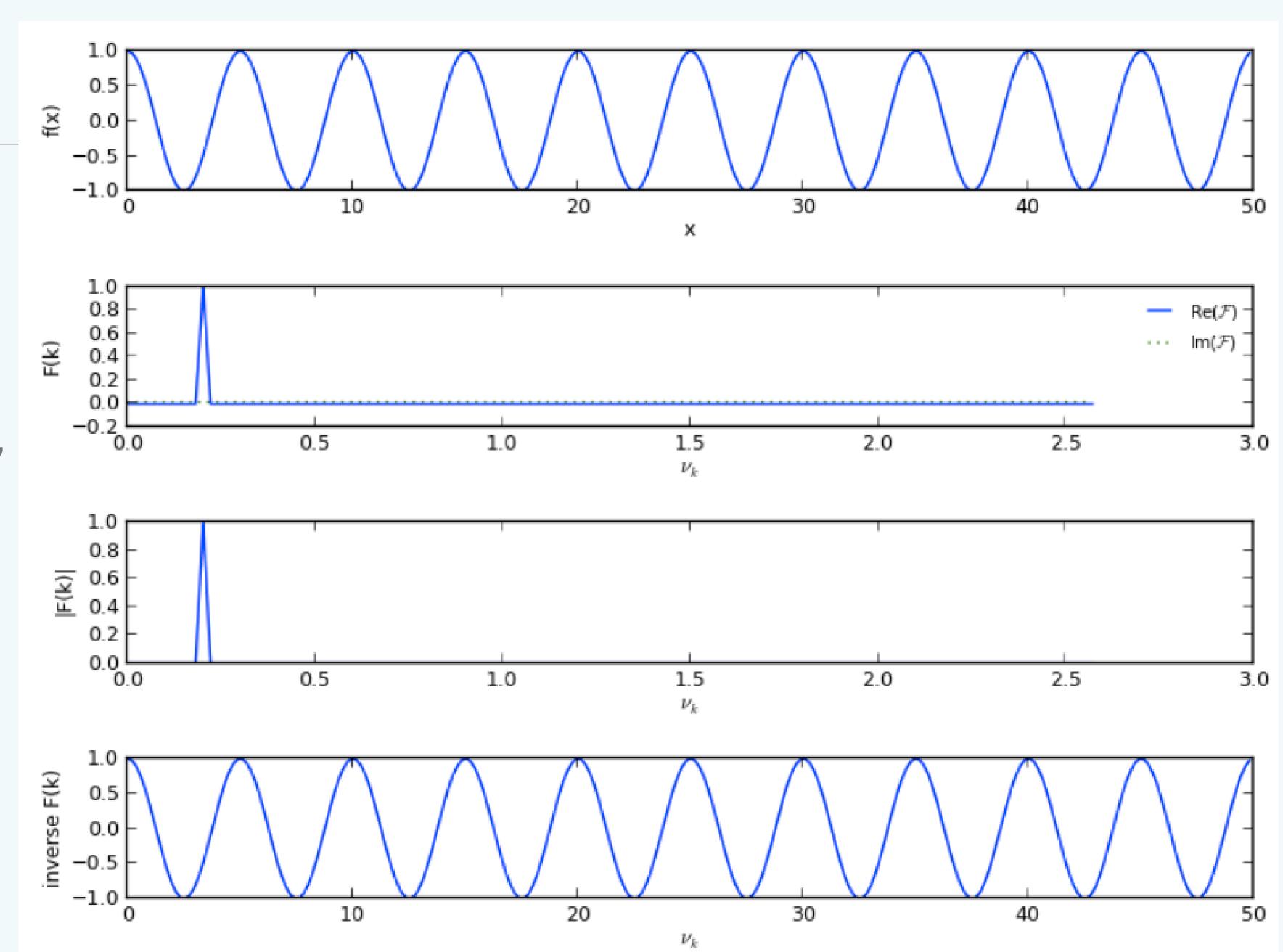
Sample points (periodicity)

- FFT with np.linspace, putting a point at both endpoints.
- Note the blip in the real portion of the FFT.



Example: Single Frequency Cosine

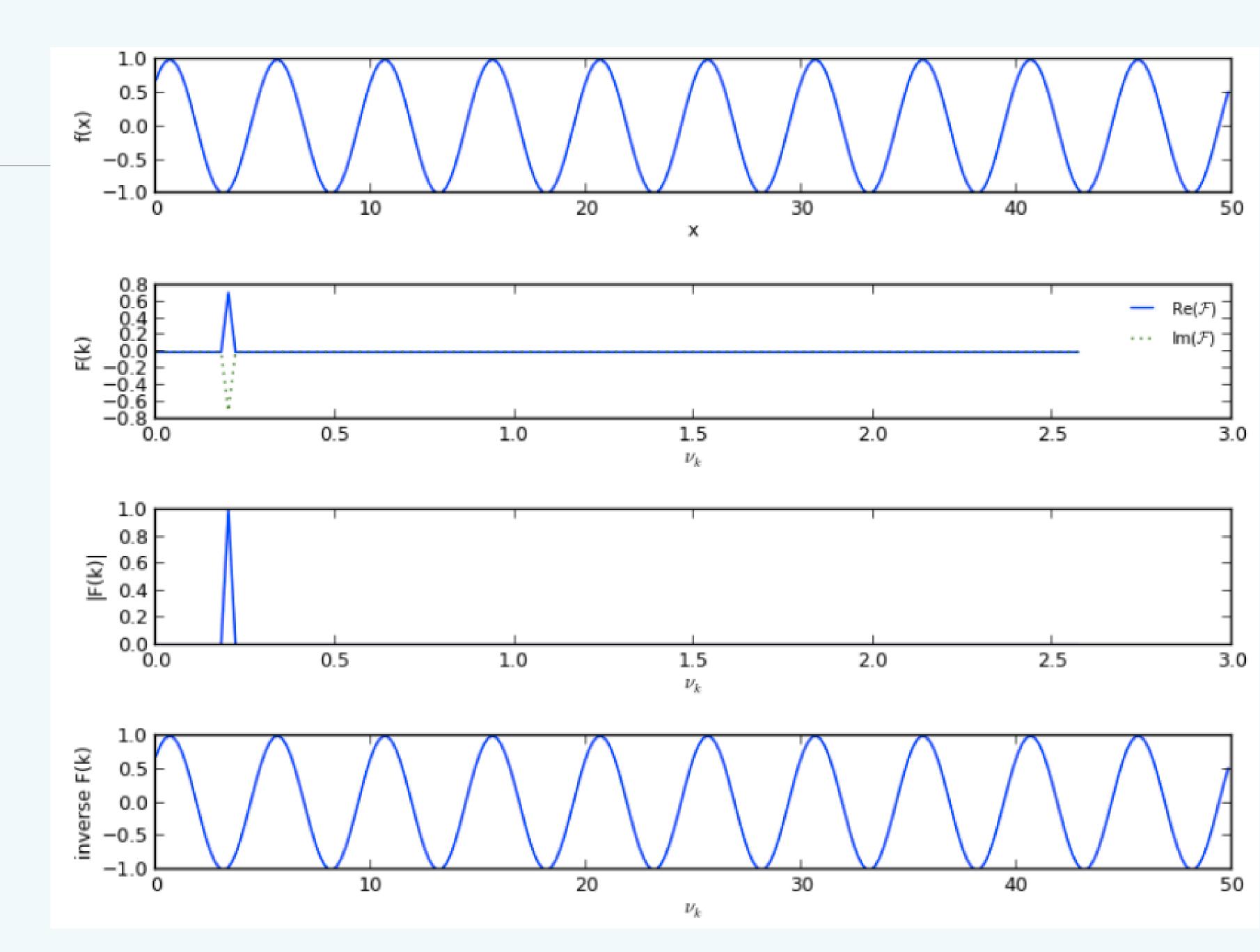
- "Opposite" of the sine
- Notice that the since cosine is even, the FFT is only nonzero in the real component.
- Also note the normalization (+ instead of -)



Example: Phase Shift

- Amplitude and phase. Consider: $\sin(2\pi f_0 x + \pi/4)$
- Phase

$$\phi = \tan^{-1} \left[\frac{\operatorname{Im}(F_k)}{\operatorname{Re}(F_k)} \right]$$



Example: Filtering

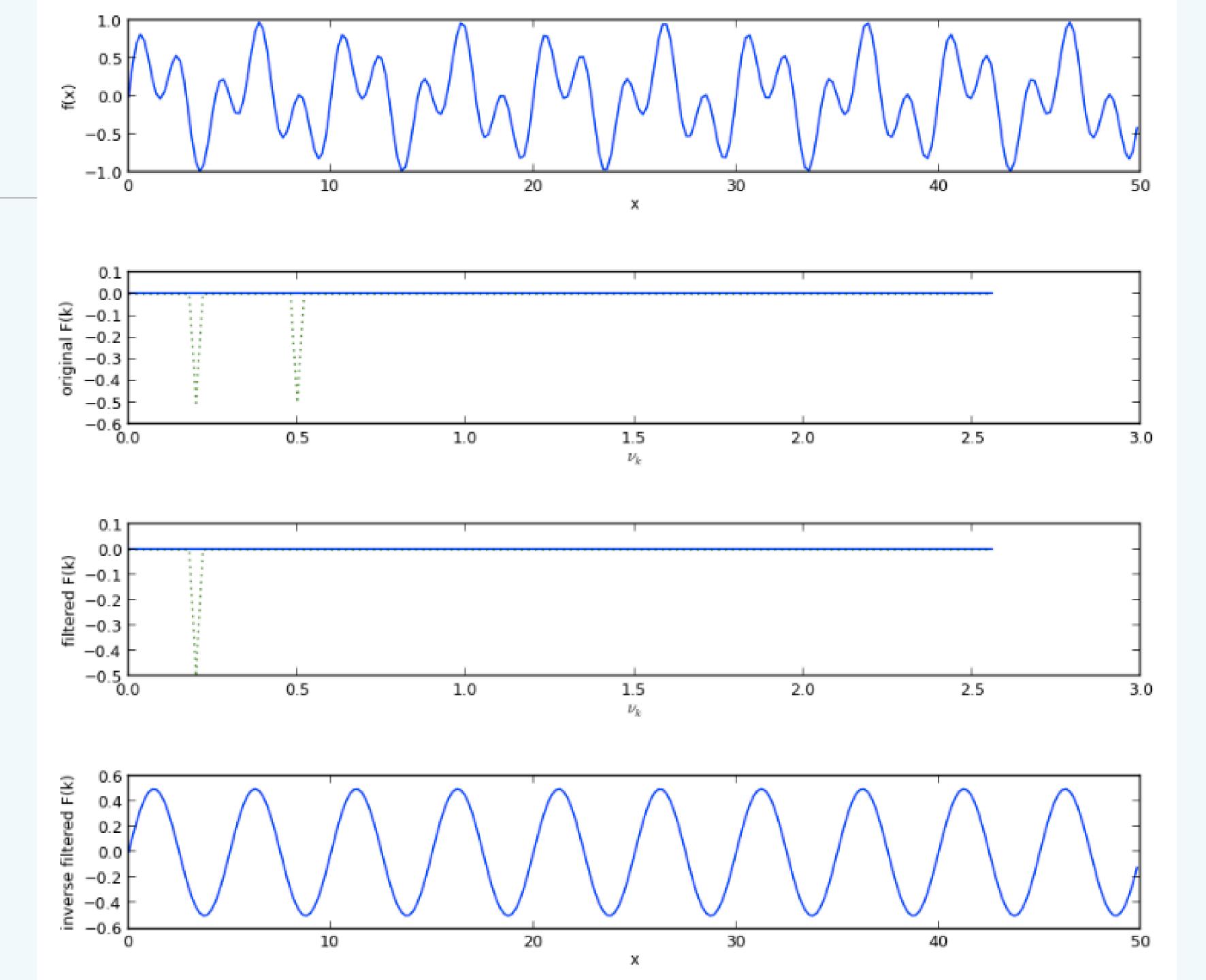
- In frequency-space, we can filter out high or low frequency components.
- Consider:

$$f(x) = \frac{1}{2} \left[\sin(2\pi f_0 x) + \sin(2\pi f_1 x) \right]$$

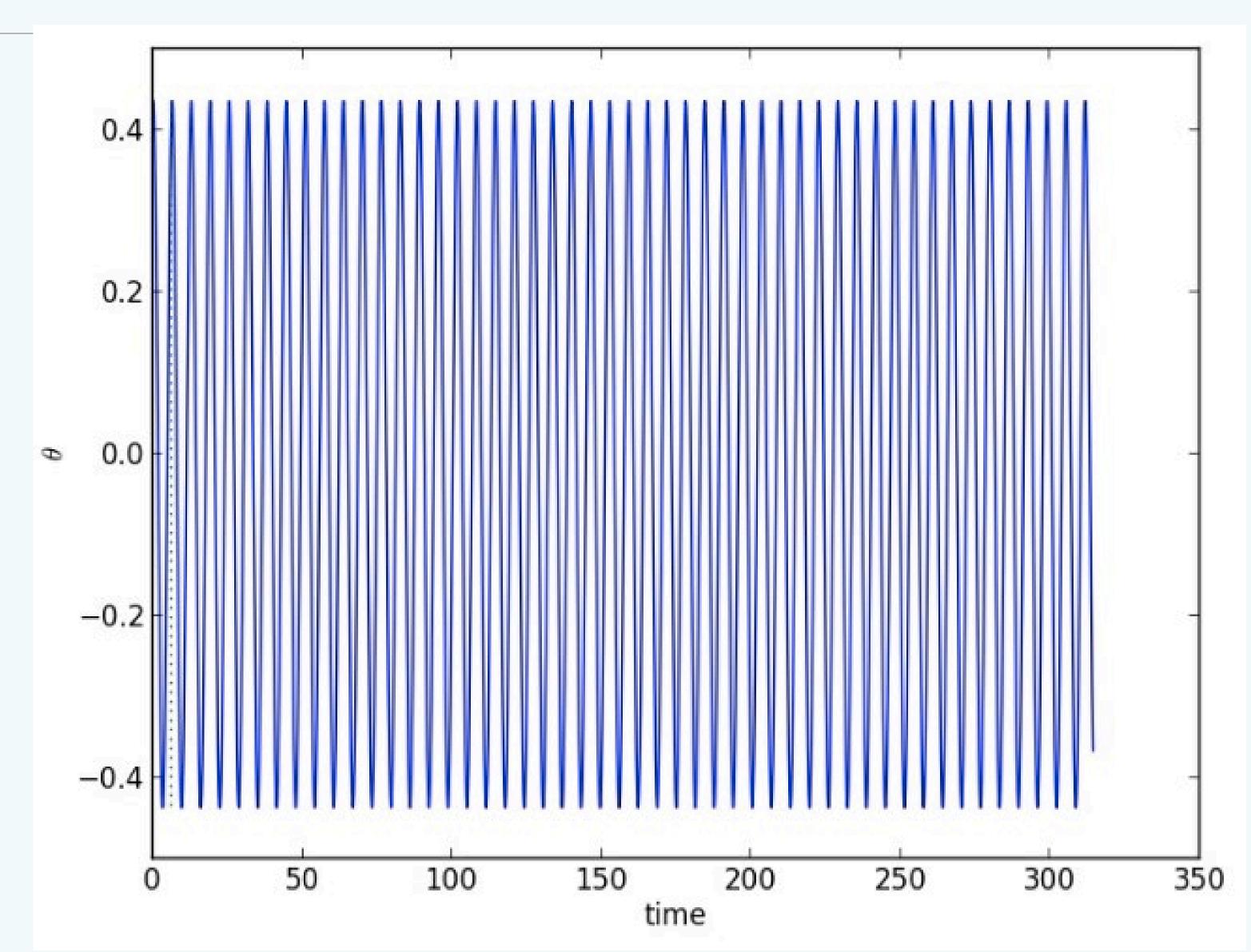
• with $f_0 = 0.2$ and $f_1 = 0.5$

Example: Filtering

- Remove the higher frequency component from F(k)
- Take the inverse FFT to recover the filtered data

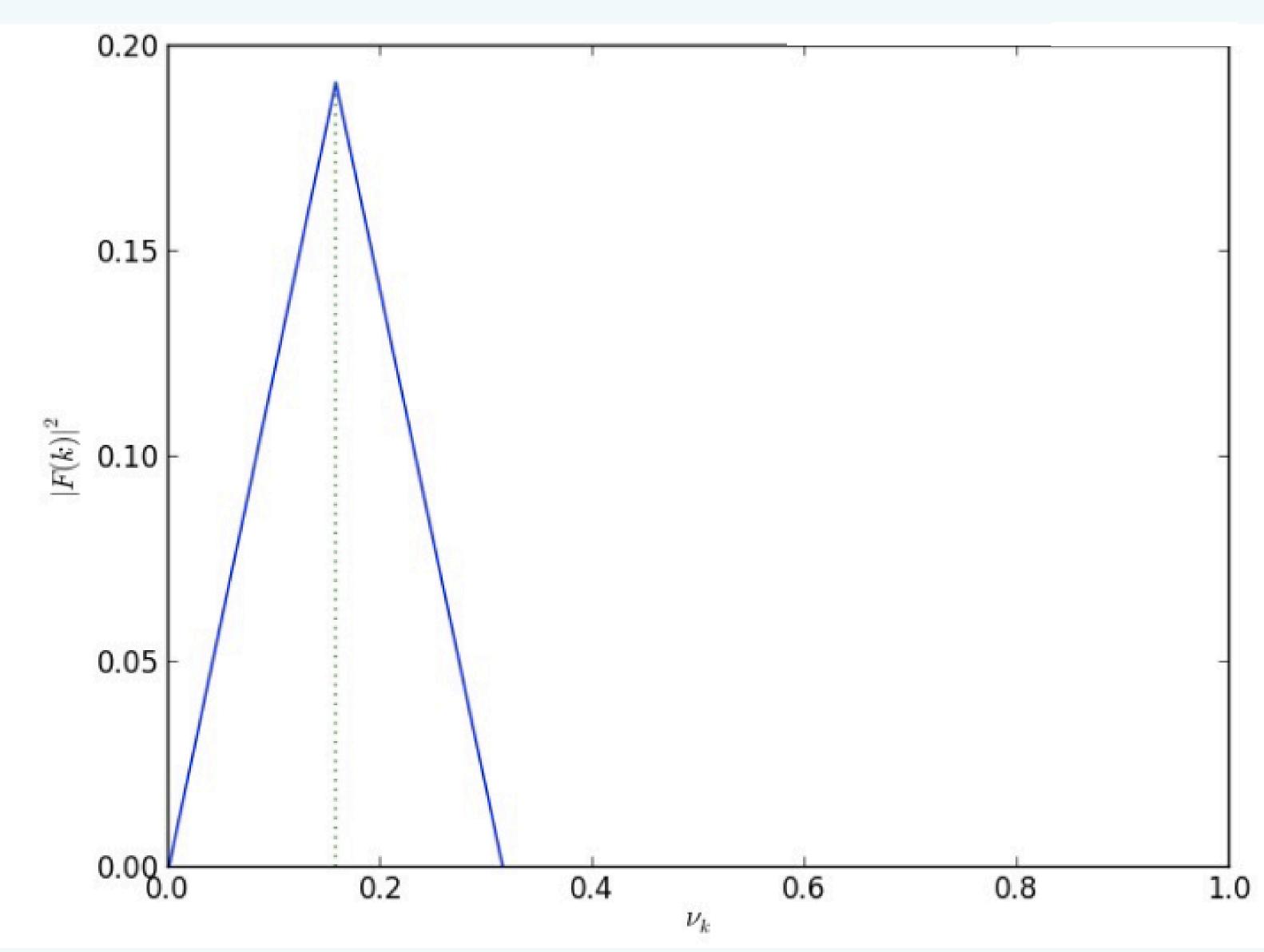


- Consider a simple pendulum
- Finite-amplitude system
- The following solution is a numerical one
- 50 periods are integrated
- Take the initial angle $\theta_0 = 25^{\circ}$



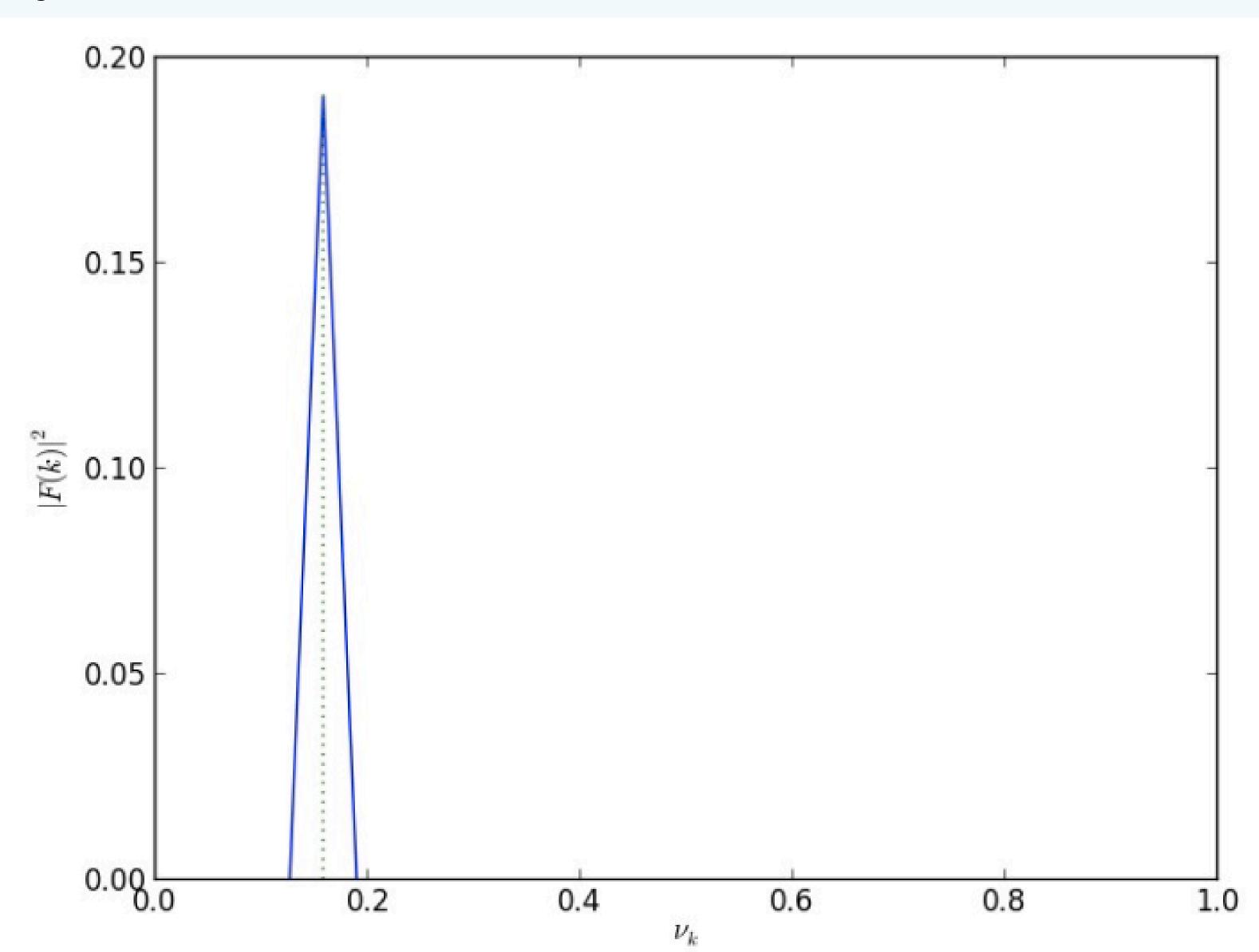
- Let's look at the power spectrum, |F(k)|², of the first period
- Dotted line is the analytical frequency estimate:

$$f^{-1} = T = 2\pi \sqrt{\frac{L}{g}} \left(1 + \frac{\theta_0}{16} \right)$$



- First 5 periods
- Dotted line is the analytical frequency estimate:

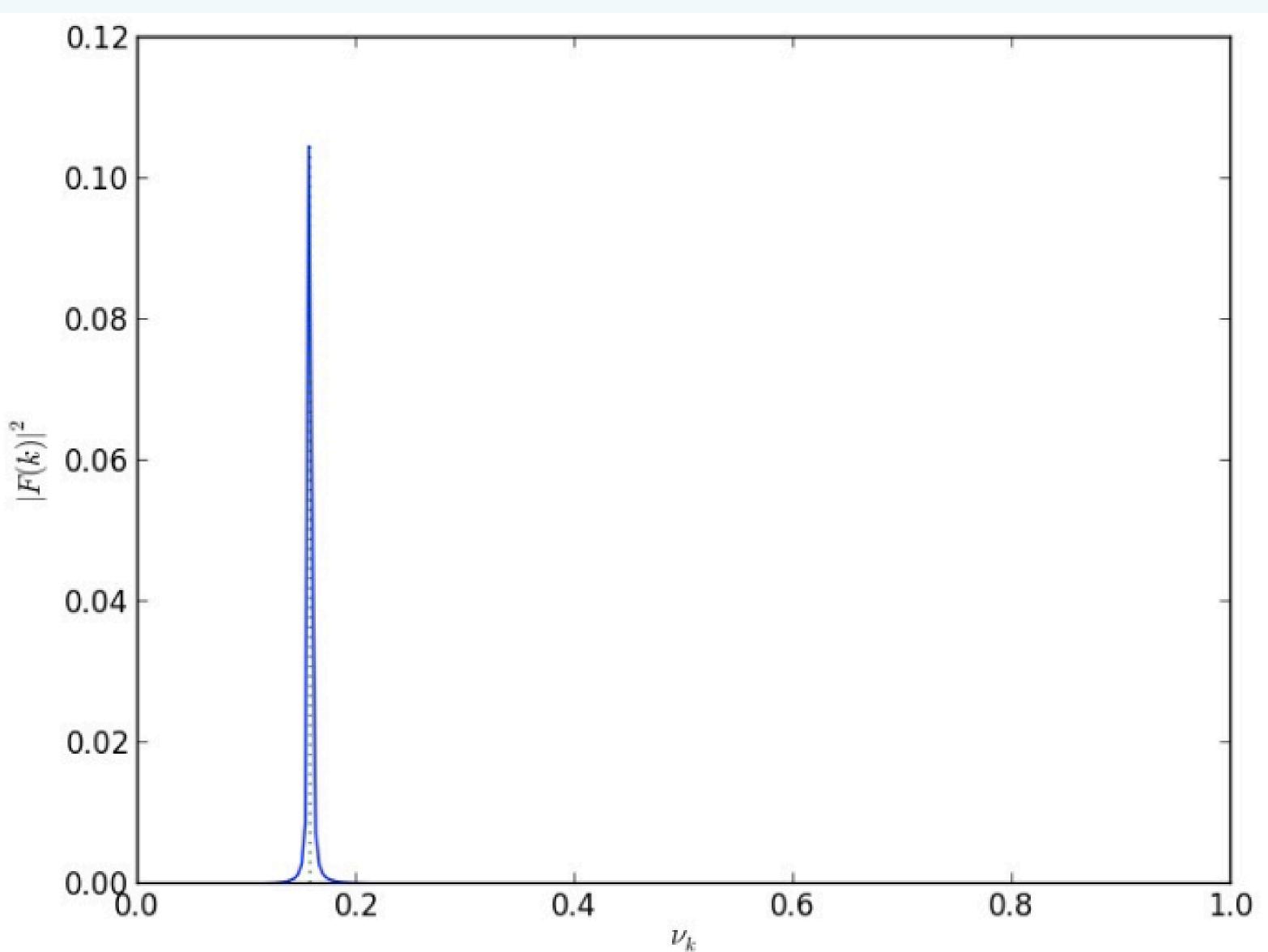
$$f^{-1} = T = 2\pi \sqrt{\frac{L}{g}} \left(1 + \frac{\theta_0}{16} \right) \quad = 0.10$$



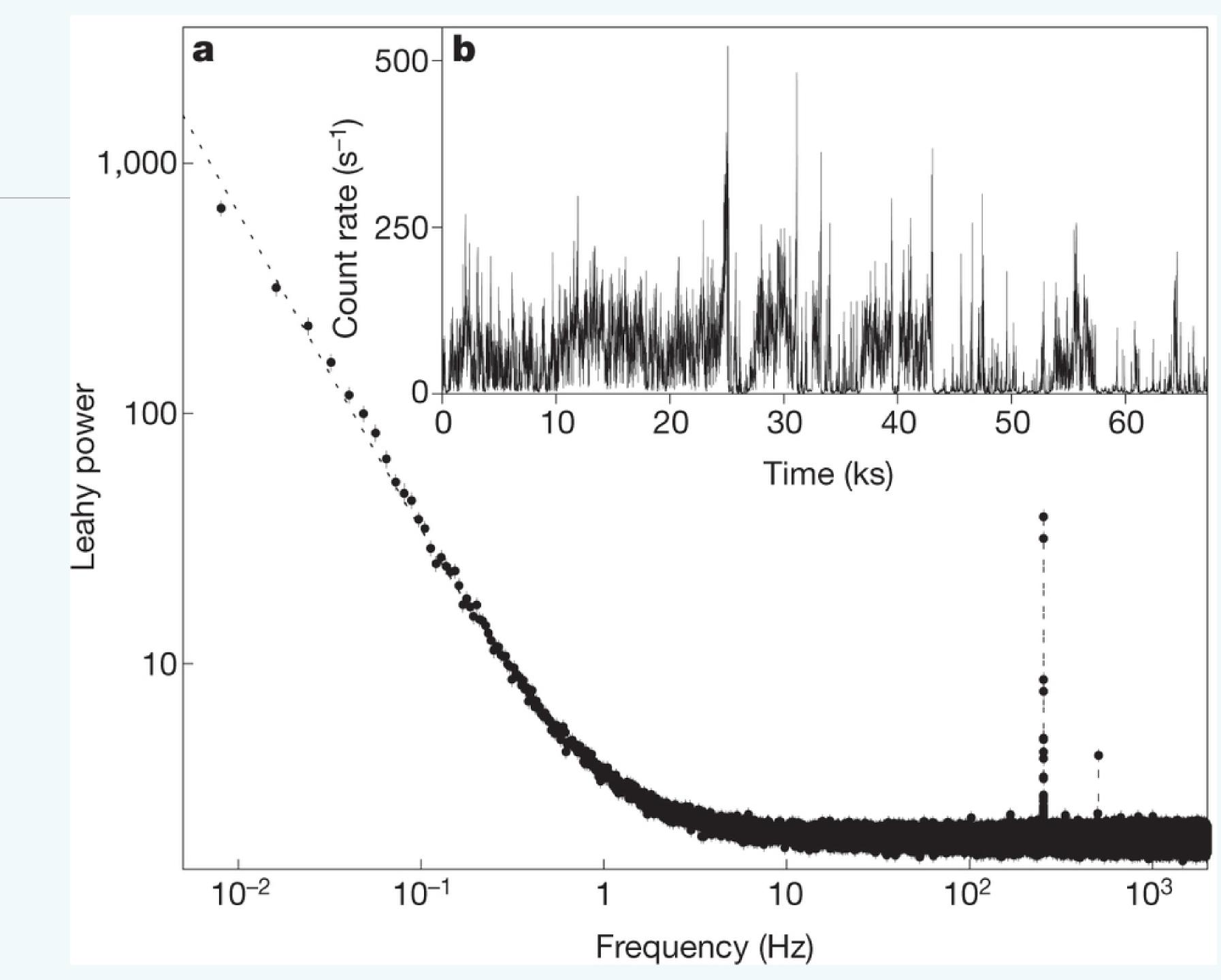
- All 50 periods
- Dotted line is the analytical frequency estimate:

$$f^{-1} = T = 2\pi \sqrt{\frac{L}{g}} \left(1 + \frac{\theta_0}{16} \right) \stackrel{\text{T}}{=} 0.06$$

Smoothing at the base is from numerical error



- Astrophysical example from an X-ray emitting pulsar (spinning neutron star) time-series
- Credit



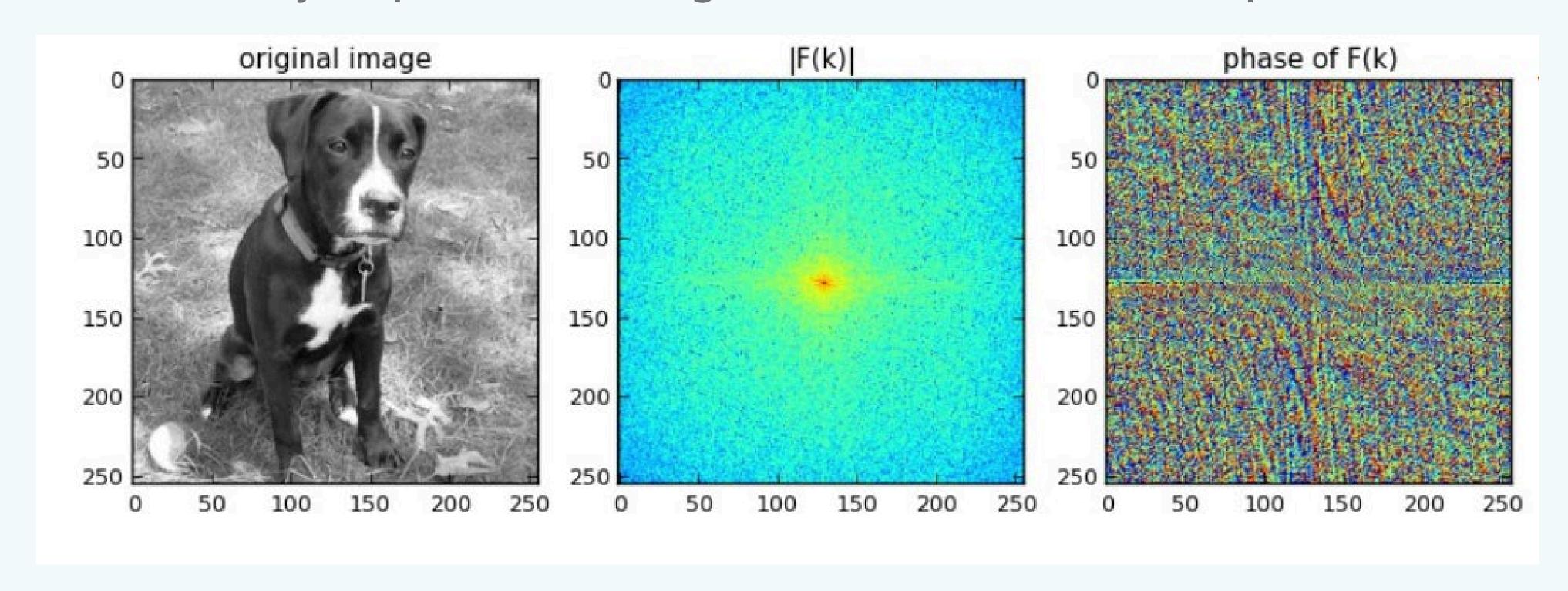
Multi-dimensional FFTs decompose into a sequence of one-dimensional FFTs

$$F_{k_x,k_y} = \sum_{m=0}^{N_x - 1} \sum_{n=0}^{N_y - 1} f_{mn} e^{-2\pi i (k_x m/N_x + k_y n/N_y)}$$

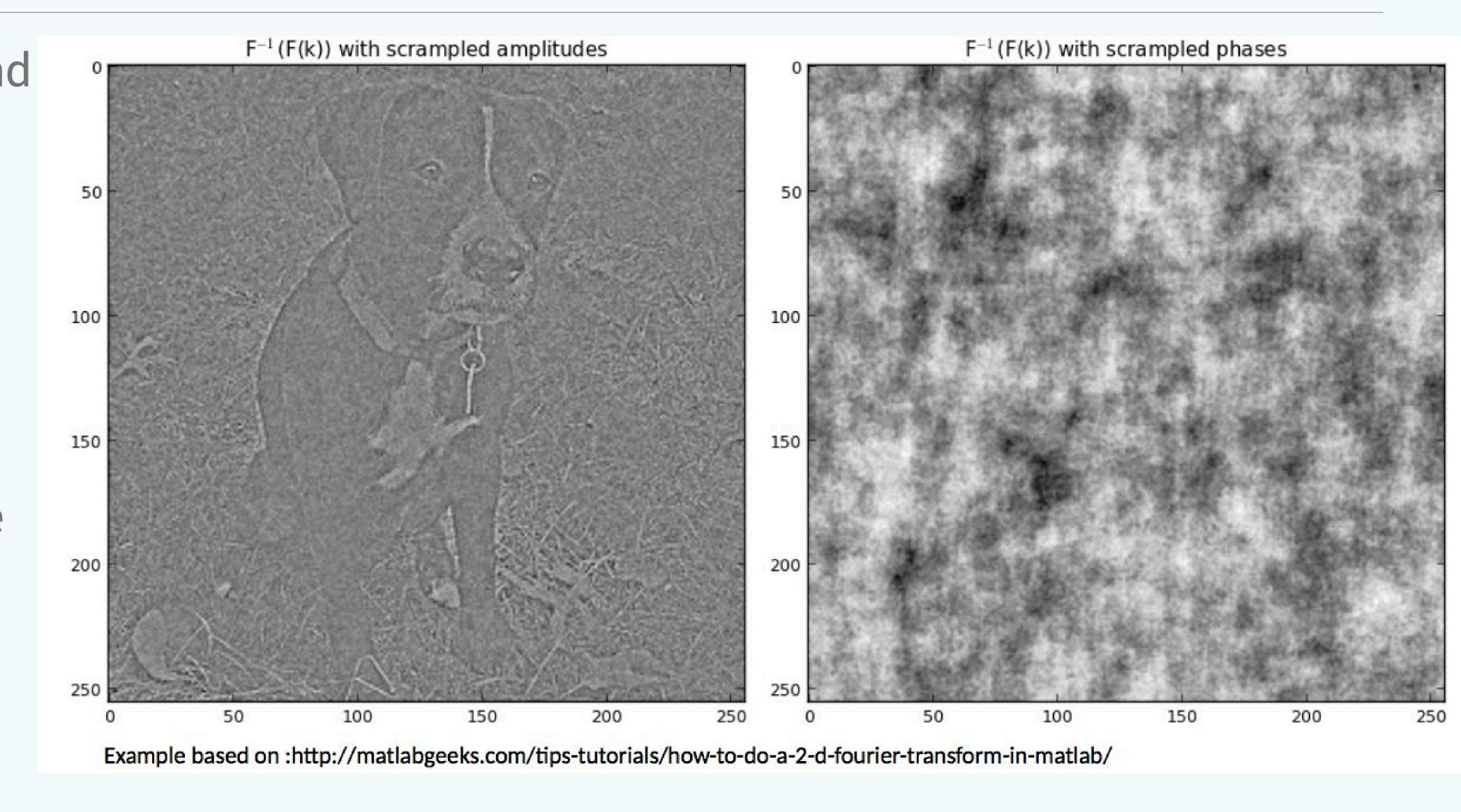
$$= \sum_{m=0}^{N_x - 1} e^{-2\pi i k_x m/N_x} \sum_{n=0}^{N_y - 1} f_{mn} e^{-2\pi i k_y n/N_y}$$

Transform in the y-direction

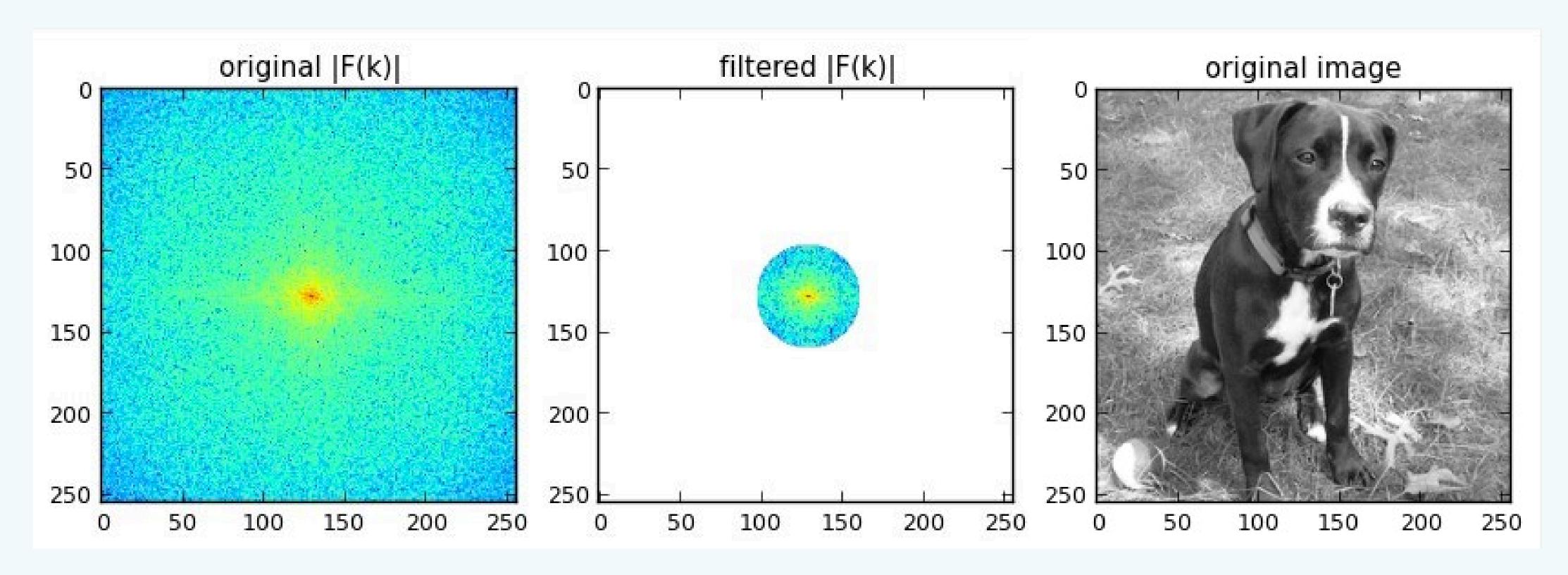
- To visualize what's going on, we need to look at both the amplitude and the phase
 - Note that only 1 quadrant is significant because our input was real.



 To understand what the magnitude and phase influence, here we scrape each of them in turn and take inverse of it.



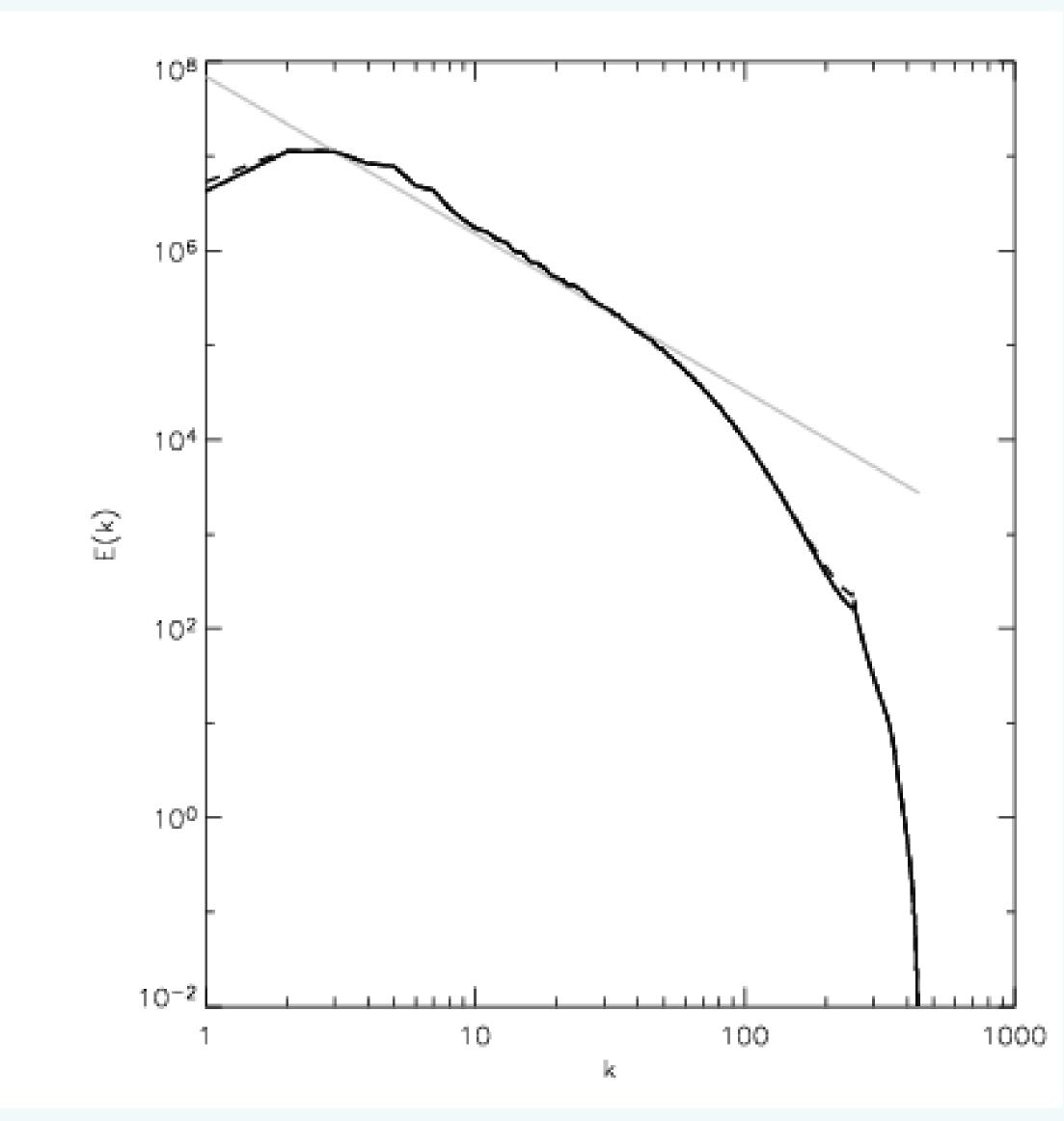
In phase space, we can filter out frequency components to do image processing



Example: Turbulence

 The power spectrum of the velocity field is used to understand the turbulent energy cascade.

$$E(K) = \int_{K=|k|} [\hat{u}^2(k) + \hat{v}^2(k) + \hat{w}^2(k)]$$
$$k^2 = k_x^2 + k_y^2 + k_z^2$$



What is the FFT really doing?

 Consider our expression for the discrete Fourier transform, but let's group the odd and even terms

$$F_k = \sum_{n=0}^{N-1} f_n e^{-2\pi i k n/N}$$

$$= \sum_{r=0}^{N/2-1} f_{2r} e^{-2\pi i k (2r)/N} + \sum_{r=0}^{N/2-1} f_{2r+1} e^{-2\pi i k (2r+1)/N}$$

Now look at the even terms:

$$E_k \equiv \sum_{r=0}^{N/2-1} f_{2r} e^{-2\pi i k(2r)/N} = \sum_{r=0}^{N/2-1} f_{2r} e^{-2\pi i kr/(N/2)}$$

DFT of the N/2 even samples

What is the FFT really doing?

Now the odd terms:

$$\sum_{r=0}^{N/2-1} f_{2r+1} e^{-2\pi i k(2r+1)/N} = e^{-2\pi i k/N} \sum_{r=0}^{N/2-1} f_{2r+1} e^{-2\pi i k r/(N/2)}$$
$$= e^{-2\pi i k/N} O_k$$

- O_k is the just the DFT of the N/2 odd samples
- . Define: $\omega^k \equiv e^{-2\pi i k/N}; \quad F_k = E_k + \omega^k O_k$
- In doing this, we went from FFTs involving N samples to 2 FFTs with N/2 samples → the number of wave numbers is also halved.

FFTs

- Periodicity tells us that $F_{k+N/2} = E_k \omega^k O_k$
- E_k and O_k are simply periodic with N/2
- We can apply this decomposition recursively
- Let's consider the case where N = 2^m

$$E_k \equiv \sum_{r=0}^{N/2-1} f_{2r} e^{-2\pi i k r / (N/2)}$$

$$O_k \equiv \sum_{r=0}^{N/2-1} f_{2r+1} e^{-2\pi i k r/(N/2)}$$

FFTs

- Consider 8 samples: $f_n = \{f_0, f_1, f_2, f_3, f_4, f_5, f_6, f_7\}$
 - There are 3 levels that we break this down
- Level 3:
 - This is the final answer. We want F_k for k = 0...7
 - Express this in terms of the FFTs of the even and odd terms

$$F_k = \mathcal{F}_k(f_0, f_2, f_4, f_6) + \omega^k \mathcal{F}_k(f_1, f_3, f_5, f_7)$$

 This is defined for k=0...3 since that's what the FFTs of each N/2 set of samples is defined with

$$F_k = \mathcal{F}_k(f_0, f_2, f_4, f_6) + \omega^k \mathcal{F}_k(f_1, f_3, f_5, f_7)$$

• The other half of the frequencies (k = 4...7):

$$F_{k+N/2} = \mathcal{F}_k(f_0, f_2, f_4, f_6) - \omega^k \mathcal{F}_k(f_1, f_3, f_5, f_7)$$

- So 2 FFTs of 4 samples each gives us the FFT of 8 samples defined over 8 wavenumbers.
- Apply this recursively...

FFTs

- · Eventually we get down to N FFTs of 1 sample each $\, \mathcal{F}_0(f_n) = f_n \,$
- We get the acceleration over the DFT by applying this recursively
 - Consider N = 2^m samples, decomposing them m times
 - At the lowest level, we will be considering FFTs of a single sample

$$F_0 = f_0 e^{-2\pi i k 0/N} = f_0$$

- The DFT of a single sample is just the sample itself
- At each of these levels, we have much smaller FFTs to consider, so we save on a lot of work.
- Putting it all together, the computational work scales as O(N log N)

```
def fft(f_n):
    N = len(f_n)
    if N == 1:
        return f_n
    else:
        # split into even and odd and find the FFTs of each half
        f_{even} = f_n[0:N:2]
        f_{odd} = f_{n[1:N:2]}
        F_{even} = fft(f_{even})
        F_{odd} = fft(f_{odd})
        # combine them. Each half has N/2 wavenumbers, but due to
        # periodicity, we can compute N wavenumbers
        omega = np.exp(-2*np.pi*1j/N)
        # allocate space for the frequency components
        F_k = np.zeros((N), dtype=np.complex128)
        for k in range(N/2):
            F_k[k] = F_even[k] + omega**k * F_odd[k]
            F_k[N/2 + k] = F_even[k] - omega**k * F_odd[k]
return F_k
```

Beyond data analysis

- So far we've focused on using the FFT for data analysis
- We can also use it directly for solving (some) partial differential equations (Chapter 9).
- Consider the Poisson equation: $\dfrac{d^2\phi_n}{dx^2}=f_n$
- Express in terms of the FFTs

$$\phi(x) = \int \Phi(k)e^{-2\pi ikx}dk$$
$$f(x) = \int F(k)e^{-2\pi ikx}dk$$

Beyond data analysis

$$\phi(x) = \int \Phi(k)e^{-2\pi ikx}dk$$
$$f(x) = \int F(k)e^{-2\pi ikx}dk$$

Easy to differentiate:

$$\frac{d^2\phi(x)}{dx^2} = -4\pi^2 k^2 \int \Phi(k) e^{-2\pi i k x} dk$$

- Then: $-4\pi^2 k^2 \Phi(k) = F(k)$
- . Easy to solve: $\Phi(k) = -\frac{F(k)}{4\pi^2 k^2}$
- Solve algebraically in Fourier space and then transform back
 - Only works for certain boundary conditions