EE2410 Data Structure Coding HW #5 – Graphs (Chapter 6) due date 6/9/2024 (Sun.), 23:59

You should submit:

- (a) All your source codes (C++ file).
- (b) Show the execution trace of your program, i.e., write a client main() to demonstrate all functions you designed using example data.

Submit your homework before the deadline (midnight of 6/9). Fail to comply (**late** homework) will have **ZERO** score. **Copy** homework will have **ZERO** score on both parties and **SERIOUS** consequences.

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1. (40%)

Graph (linked adjacency list), BFS, DFS, connected components, Computing dfn and low:

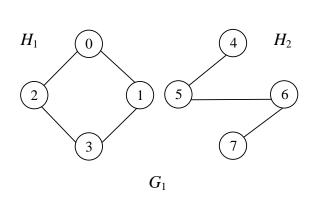
Write a C++ program to perform the following basic graph functions: (assume the graph is represented using linked adjacency list.)

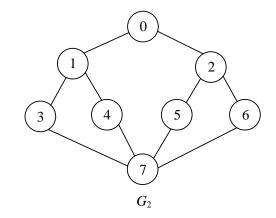
- (a) BFS(v) (Prog. 6.2) (v: starting vertex. You need to output the vertices visited in BFS order)
- (b) DFS(v) (Prog. 6.1) (v: starting vertex. You need to output the vertices visited in DFS order)
- (c) Component() (Prog. 6.3 where OutputNewComponent() can be simplified to just output the vertices of the component)
- (d) DfnLow() (Prog. 6.4, 6.5) (Display the computed dfn[i] and low[i] of the graph and the articulation points found) on a linked adjacency list based graph. Add whatever you think necessary to your class Graph to implement the required functions, e.g., setup functions for setting up various graphs required.

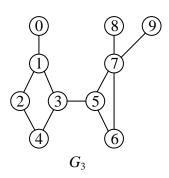
Show your results using the following three graphs (G_1 , G_2 , and G_3) in your program. The main() would contain similar codes segment shown below. BFS and DFS should start from 3 vertices: 0, 3, 7, respectively as shown in the code segment.

```
Graph g1(8),g2(8),g3(10);
g1.Setup1();
//BFS
g1.BFS(0);
g1.BFS(3);
g1.BFS(7);
//DFS
g1.DFS(0);
g1.DFS(3);
g1.DFS(7);
//Components & DfnLow
```

g1.Components(); g1.DfnLow(3);







```
G2:
 C:\c++\data_structure\hw5\si X
                               BFS:
G1:
                               Begin at vertex 0:
BFS:
                               01234567
Begin at vertex 0:
                               Begin at vertex 3:
0 1 2 3
                               3 1 7 0 4 5 6 2
Begin at vertex 3:
                               Begin at vertex 7:
3 1 2 0
                               73456120
Begin at vertex 7:
7654
                               DFS:
                               Begin at vertex 0:
DFS:
Begin at vertex 0:
                               0 1 3 7 4 5 2 6
0 1 3 2
                               Begin at vertex 3:
Begin at vertex 3:
                               3 1 0 2 5 7 4 6
3 1 0 2
                               Begin at vertex 7:
Begin at vertex 7:
                               73102564
7654
                               Components:
Components:
0 1 3 2
                               0 1 3 7 4 5 2 6
4567
                               DfnLow:
DfnLow:
                               Begin at vertex 1:
Begin at vertex 3:
                                   i:01234567
   i:01234567
                               dfn[i]: 2 1 3 6 7 4 8 5
dfn[i]: 3 2 4 1 0 0 0 0
                               low[i]: 1 1 1 1 1 1 3 1
low[i]: 1 1 1 1 0 0 0 0
```

```
G3:
BFS:
Begin at vertex 0:
0123456789
Begin at vertex 3:
3145026789
Begin at vertex 7:
7568931402
DFS:
Begin at vertex 0:
0124356789
Begin at vertex 3:
3 1 0 2 4 5 6 7 8 9
Begin at vertex 7:
7531024689
Components:
0124356789
DfnLow:
Begin at vertex 3:
   i:0123456789
dfn[i]: 3 2 4 1 5 6 7 8 9 10
low[i]: 3 1 1 1 1 6 6 6 9 10
Process returned 0 (0x0)
                       execution time : 0.040 s
Press any key to continue.
```

2. (30%)

Shortest paths: single source/all destination nonnegative weights (Dijkstra), single source/all destination negative weights DAG (Bellman-Ford), all pairs shortest paths (Floyd)

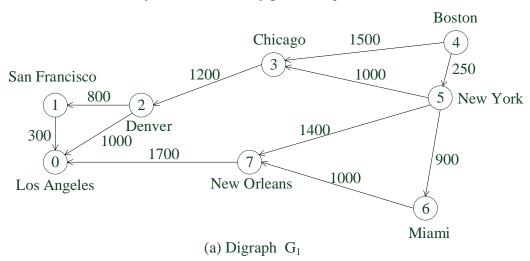
Write a C++ program to perform some basic graph functions:

- (a) Single source/all destination nonnegative weights (Dijkstra) (Prog. 6.8)
- (b) Single source/all destination negative weights DAG (Bellman-Ford) (Prog. 6.9)
- (c) All pairs DAG shortest paths (Floyd) (Prog. 6.10)

Assume the graph is represented using weighted adjacency matrix. Add whatever you think necessary to your class Graph to implement the required functions, such as setups for setting up various graphs required and display corresponding adjacency matrix of the graph.

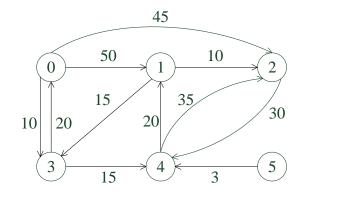
You should demonstrate your code by applying these three functions to graphs given below. For (a) Single source/all destination nonnegative weights (Dijkstra), modify Prog. 6.8 to generate results like Fig. 6.28 in textbook (shown below) and output the computed "paths".

You need to demonstrate your code of (a) by processing: G₁, G₁', and G₁" shown below.



	Vertex selected	Distance							
Iteration		LA	SF	DEN	CHI	BOST	NY	MIA	NO
		[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]
Initial		∞	∞	∞	1500	0	250	∞	∞
1	5	∞	∞	∞	1250	0	250	1150	1650
2	6	∞	∞	∞	1250	0	250	1150	1650
3	3	∞	∞	2450	1250	0	250	1150	1650
4	7	3350	∞	2450	1250	0	250	1150	1650
5	2	3350	3350	2450	1250	0	250	1150	1650
6	1	3350	3350	2450	1250	0	250	1150	1650

Fig. 6.28



路徑 長度

10

1) 0, 3

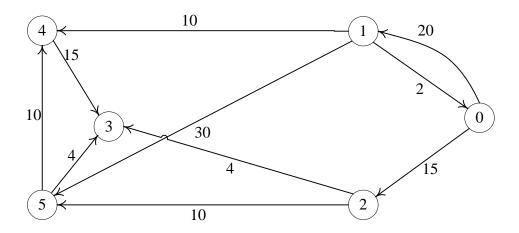
2) 0, 3, 4 25

3) 0, 3, 4, 1 45

4) 0, 2 45

(a) Digraph G_1 '

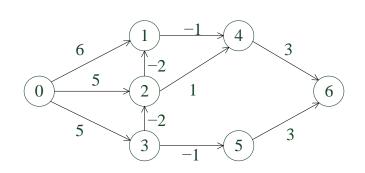
(b) 從 0 出發的最短路徑



(a) G₁". Find shortest paths from vertex 0 to all remaining vertices.

For (b) Single source/all destination negative weights DAG (Bellman-Ford), modify Prog. 6.9 to display results like Fig. 6.31(b) shown below.

You need to demonstrate your code of (b) by processing: G2 and G2' shown below.



(a) Digraph G₂

		dist ^k [7]						
k	0	1	2	3	4	5	6	
1	0	6	5	5	∞	∞	∞	
2	0	3	3	5	5	4	∞	
3	0	1	3	5	2	4	7	
4	0	1	3	5	0	4	5	
5	0	1	3	5	0	4	3	
6	0	1	3	5	0	4	3	

(b) $dist^k$

Fig. 6.31

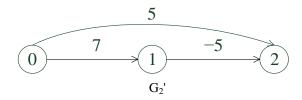


Fig. 6.29

For (c) All pairs DAG shortest paths (Floyd), modify Prog. 6.10 to display results like Fig. 6.32 shown below. You need to demonstrate your code of (c) by processing G_3 (below in Fig. 6.32(a)) and G_2 (above in Fig. 6.31(a)).

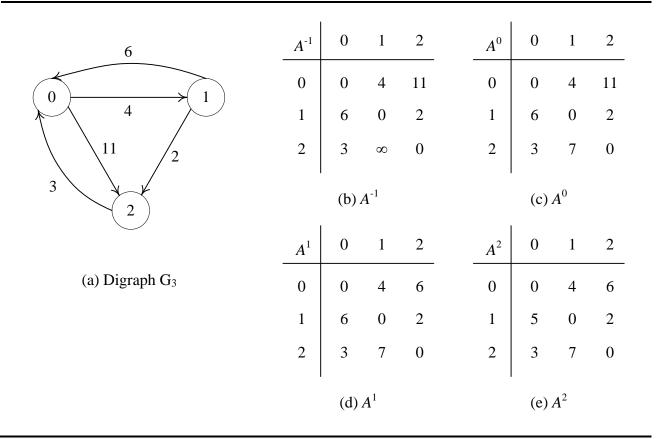


Fig. 6.

```
C:\c++\data_structure\hw5\si X
 'i' means infinte
 (a):
 G1:
 Path: 4->5; Distance: 250
 Path: 4->5->6; Distance: 1150
 Path: 4->5->3; Distance: 1250
 Path: 4->5->7; Distance: 1650
 Path: 4->5->3->2; Distance: 2450
 Path: 4->5->3->2->1; Distance: 3250
 Path: 4->5->7->0; Distance: 3350
 G1':
 Path: 0->3; Distance: 10
 Path: 0->3->4; Distance: 25
 Path: 0->3->4->1; Distance: 45
 Path: 0->2; Distance: 45
 G1'':
 Path: 0->2; Distance: 15
Path: 0->2->3; Distance: 19
 Path: 0->1; Distance: 20
 Path: 0->2->5; Distance: 25
 Path: 0->1->4; Distance: 30
(b):
G2:
    0
        1
                3
                    4
                         5
                             6
1
    0
        6
            5
                5
                     i
                         i
                             i
2
3
4
    0
        3
            3
                5
                     5
                         4
                             i
    0
      1
            3
                5
                     2
                         4
                            7
            3
                    0
                         4
    0
        1
                5
                            5
5
        1
            3
    0
                5
                    0
                         4
                             3
            3
                5
                            3
    0
        1
                    0
                         4
G2':
   0
        1
            2
```

(c):

(c):							
G3:							
A(-1)	Θ	1	2				
Θ	Θ	4	11				
1	6	9					
			2				
2	3	i	0				
A0	Θ	1	2				
Θ	0	4	11				
1	6	0	2				
2	3	7	0				
A1	0	1	2				
0	0	4	6				
1	6	0	2				
2	3	7	9				
_	•	•	•				
A2	Θ	1	2				
A2	0						
Θ	 Θ	4	6				
1	5	0	2				
2	3	7	0				
G2:							
A(-1)	0	1	2	3	4	5	6
Θ	0	6	5	5	i	i i	i i
1	0 i	Θ	i	i	-1	i	i
2	i	-2	0	i	1	i	i
3	i	i	-2	0	i	-1	i
4	i	i	-2 i	i	0	i	3
5	i i	i	i	i	i	9	3
6	i	i	i	i	i	i	9
U	_	_	_	_	_	_	U
40	Θ	1	2	2	4	5	6
A0	U	1	2	3	4	5	6
					- <u>;</u>	·	·
0	9	6	5	5	i	i	i
1	i	0	i	i	-1	i	i
2	i	-2	0	i	1	i	i
3	i	i	-2	0	i	-1	i
4	i	i	i	i	0	i	3
5	i	i	i	i	i	0	3
6	i	i	i	i	i	i	0

Α0	0	1	2	3	4	5	6
0 1 2 3 4 5	0 i i i i	6 0 -2 i i	5 i 0 -2 i i	5 i 0 i	i -1 1 i 0	i i i -1 i 0	i i i 3 3
A1	Θ	1	2	3	4	5	6
0 1 2 3 4 5 6	0 i i i i i	6 0 -2 i i i	5 i 0 -2 i i	5 i 0 i i 3	5 -1 -3 i 0 i	i i i -1 i 0 i	i i i i 3 3
 0 1 2 3 4 5	0 i i i i	3 0 -2 -4 i	5 i 0 -2 i i	5 i 0 i	2 -1 -3 -5 0 i	i i i -1 i 0	i i i 3 3
A3 0	0 0	1	2 3	3 5	4 0	5 4	6 i
1 2 3 4 5	i i i i i	0 -2 -4 i	i 0 -2 i i	i 0 i i	-1 -3 -5 0 i	i i -1 i 0	i i 3 3
A4 	<u> </u>	1	2	3	4	5	6
0 1 2 3 4 5	0 i i i i i	1 0 -2 -4 i	3 i 0 -2 i i	5 i 0 i i	0 -1 -3 -5 0 i	4 i -1 i 0	3 2 0 -2 3 3
A5 	0 	1	2	3	4	5	6
0 1 2 3 4 5	0 i i i i	1 0 -2 -4 i i	3 i 0 -2 i i	5 i 0 i i	0 -1 -3 -5 0 i	4 i -1 i 0	3 2 0 -2 3 9
A6	0	1	2	3	4	5	6
0 1 2 3 4 5	0 i i i i	1 0 -2 -4 i i	3 i 0 -2 i i	5 i 0 i i	0 -1 -3 -5 0 i	4 i -1 i 0	3 2 0 -2 3 3

3. (30%)

Write a C++ program that inputs (or setups) an AOE network and outputs the following:

- (a) Topological order
- (b) The earliest and latest times of all events (ee[i], le[i])
- (c) The earliest and latest times of all activities (e[k], l[k])
- (d) A table of all activities with their early and late times together with their slack and critical activities like Figure 6.41.
- (e) The critical network
- (f) Whether or not the project length can be reduced by speeding a single activity. If so, then by how much?

Use Figure 6.39 and 6.44 as two AOE examples to illustrate your results.

	最早時間	最晚時間	餘裕	臨界度
Activity	e	l	l - e	l - e = 0
a_1	0	0	0	Yes
a_2	0	2	2	No
a_3	0	3	3	No
$ $ a_4	6	6	0	Yes
a_5	4	6	2	No
a_6	5	8	3	No
$ a_7 $	7	7	0	Yes
$ a_8 $	7	7	0	Yes
a_9	7	10	3	No
a_{10}	16	16	0	Yes
a_{11}	14	14	0	Yes

Figure 6.41

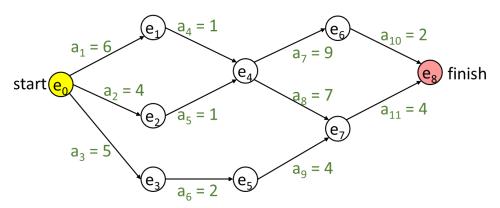


Figure 6.39

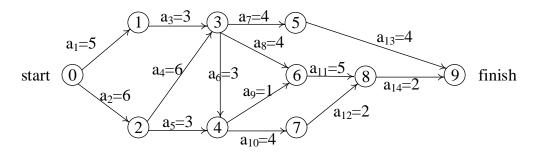


Figure 6.44

```
C:\c++\data_structure\hw5\fi × + \
Fig 6.39:
Topological order:
0 3 5 2 1 4 7 6 8
Earliest event time:
vertex: 0 1 2 3 4 5 6 7 8
ee: 0 6 4 5 7 7 16 14 18
ee: 0 6 4 Latest event time: vertex: 0 1 2 le: 0 6 6
                                     .
3
8
                                            4 5 6 7 8
7 10 16 14 18
Activity table:
Activity Earliest Latest Slack Criticality
                                                   02302300
   1
2
3
4
5
6
7
8
9
10
11
                9
6
4
5
7
7
16
14
                                  2
6
6
7
7
10
16
                                                                    0
0
1
0
                                                   3
0
0
                                                                     0
Critical path (represented by activity number): 1 4 7 8 10 11
Fig 6.44:
Topological order:
0 2 1 3 5 4 7 6 8 9
Earliest event time:

vertex: 0 1 2 3 4 5 6 7 8 9
ee: 0 5 6 12 15 16 16 19 21 23

Latest event time:

vertex: 0 1 2 3 4 5 6 7 8 9
le: 0 9 6 12 15 19 16 19 21 23
Activity table:
Activity Earliest Latest Slack Criticality
                0
5
6
12
12
15
15
16
19
16
21
                                  4

9

6

12

15

12

15

16

19

21
                                                   40406030000030
   1
2
3
4
5
6
7
8
9
10
11
12
13
                                                                     1
0
1
0
1
Critical path (represented by activity number): 2 4 6 8 9 10 11 12 14
Process returned 0 (0x0) execution time : 0.037 s Press any key to continue.
```