

Economics 144

Economic Forecasting

Lecture 2

Modeling and Forecasting Trend (Part I)

Dr. Randall R. Rojas

Today's Class

- Loss Function
- Modeling Trend
 - Linear
 - Quadratic
 - Log-linear
 - Exponential
- Model Selection
- R Demo

Loss Function 1 of 4

- Good forecasts lead to good decisions!
→ Strong link between forecasts and decisions.
- Example: You started a firm and need to decide (now) how much inventory to hold going into the next sales period.


Strategy

Demand is high → build inventory
Demand is low → reduce inventory

Loss Function 2 of 4

 Loss 	Demand High	Demand Low
Build Inventory	0	\$10,000
Reduce Inventory	\$10,000	0

Symmetric Loss Structure: Both bad outcomes have the same loss.

 Loss 	Demand High	Demand Low
Build Inventory	0	\$10,000
Reduce Inventory	\$20,000	0



Asymmetric Loss Structure: Outcomes have different losses.

Loss Function 3 of 4

- For every decision-making problem, there is an associated loss structure; for each decision/outcome pair, there is an associated loss.

$$\text{Loss} \begin{cases} 0 \rightarrow \text{Correct Decision} \\ >0 \rightarrow \text{Incorrect Decision} \end{cases}$$

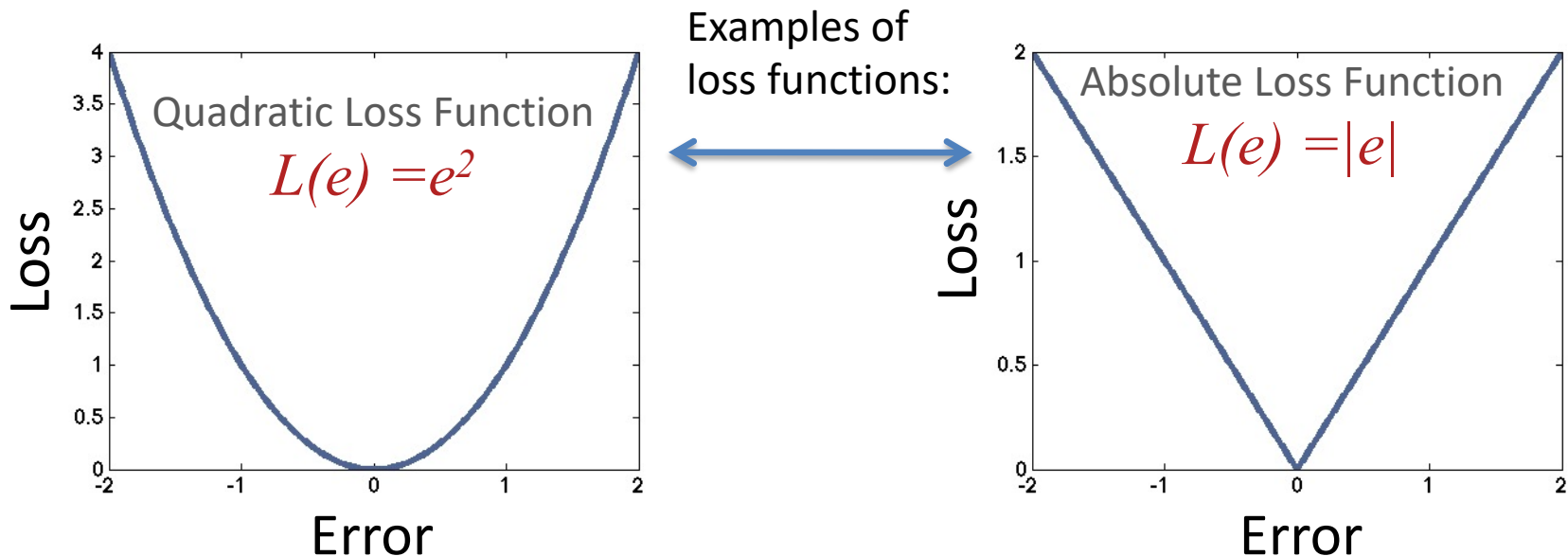
We could also forecast the sales!

 Loss 	High Actual Sales	Low Actual Sales
High Forecasted Sales	0	\$10,000
Low Forecasted Sales	\$10,000	0

Forecasting with Symmetric Loss: Both bad forecasts have the same loss.

Loss Function 4 of 4

- **Forecast Error (e)**: Difference between the realization (y) and the previously made forecast(\hat{y}) $\rightarrow e = y - \hat{y}$
- **Loss Function ($L(e)$)**: Loss associated with a forecast. Must satisfy: (1) $L(0)=0$, (2) $L(e)$ is continuous, and (3) $L(e)$ is increasing on each side of the origin.



Modeling Trend

- **Trend**: Is slow , long-run evolution in the variables that we want to model and forecast.
- Deterministic Trend: Trend evolves in a perfectly predictable way.
- To characterize a particular trend, we need a model. For example, in the case of linear regression, the model is: $y_t = \beta_0 + \beta_1 x_t$
- Often, given the broad range of time scales encountered in time-series, it is convenient to adopt one common time variable (*time dummy or time trend*) such that: $TIME^* = (1, 2, \dots, T)$ where $TIME=1$ is the first period of the sample, and so on.

*The notation convention is $TIME_t = t$.

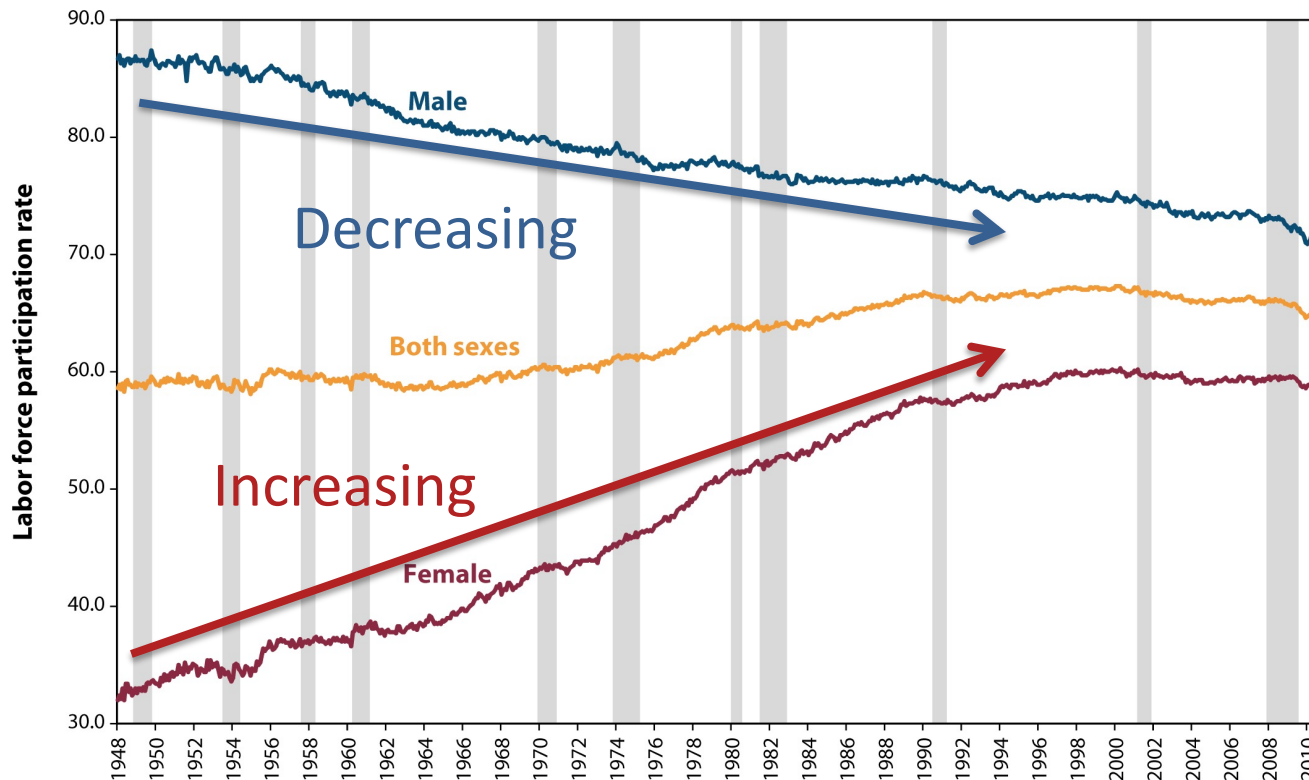
Modeling Trend (Linear) 1 of 4

Women's gains increase size of American workforce

Labor force participation rate of population age 16 and older, by gender



<http://stateofworkingamerica.org/charts/labor-force-participation-rate-of-population-age-16-and-older-by-gender/>

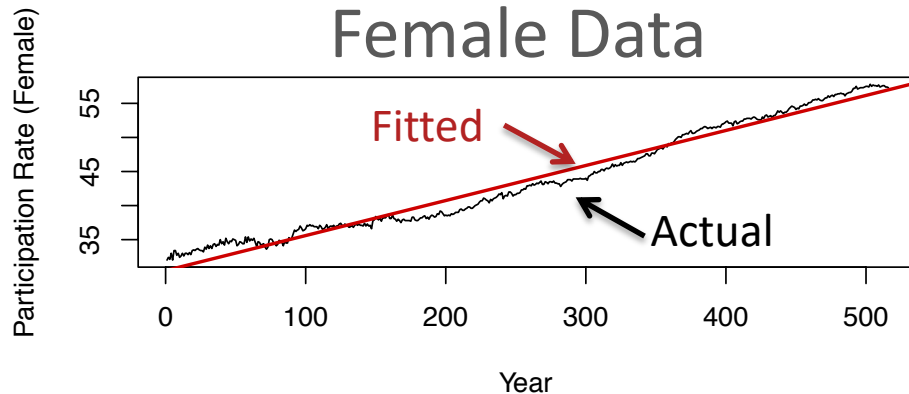


Note: Shaded areas denote recession.

Source: Bureau of Labor Statistics, Current Population Survey.

$$\text{Model: } T_t = \beta_0 + \beta_1 \text{ TIME}_t$$

Modeling Trend (Linear) 2 of 4



Call:
lm(formula = female ~ TIME)

Residuals:

Min	1Q	Median	3Q	Max
-2.3959	-1.1994	0.2523	1.0177	2.6321

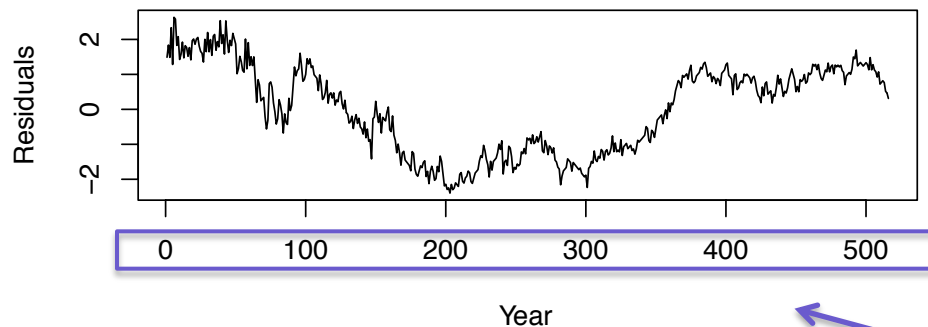
Coefficients:

	Estimate	Std. Error	t value	Pr(> t)
(Intercept)	3.046e+01	1.107e-01	275.1	<2e-16 ***
TIME	5.141e-02	3.712e-04	138.5	<2e-16 ***

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

$$Fem_Part_Rate = 30.46 + 0.051T$$

Residual standard error: 1.256 on 514 degrees of freedom
Multiple R-squared: 0.9739, Adjusted R-squared: 0.9739
F-statistic: 1.919e+04 on 1 and 514 DF, p-value: < 2.2e-16

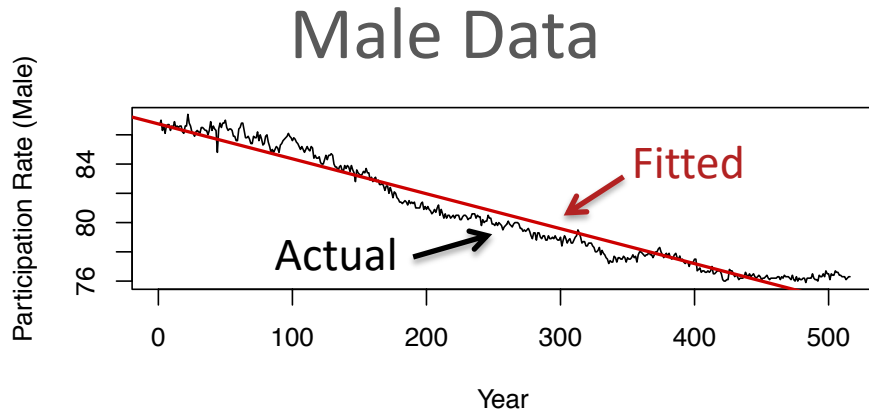


$R^2 = 0.97 \rightarrow$ Excellent!

Do you see anything wrong?

Time : 1948-1990

Modeling Trend (Linear) 3 of 4



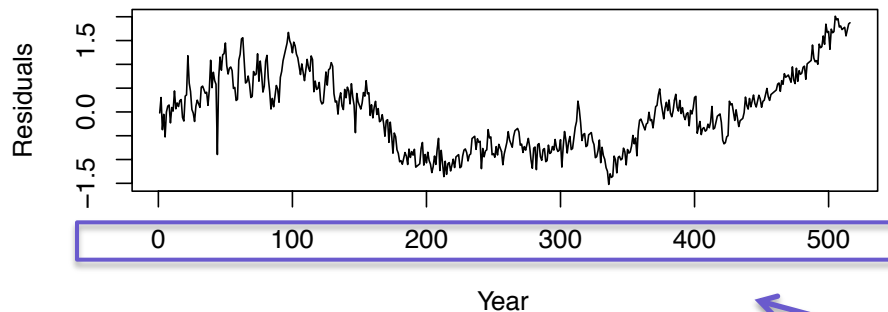
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Call:
lm(formula = male ~ TIME)

Residuals:
    Min       1Q   Median       3Q      Max
-1.52321 -0.70824 -0.00946  0.51965  2.01150

Coefficients:
              Estimate Std. Error t value Pr(>|t|)
(Intercept) 86.7448867  0.0699255  1240.5  <2e-16 ***
TIME        -0.0238740  0.0002344  -101.9  <2e-16 ***
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Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
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$$Male_Part_Rate = 86.75 - 0.024T$$

Residual standard error: 0.793 on 514 degrees of freedom
 Multiple R-squared: 0.9528, Adjusted R-squared: 0.9527
 F-statistic: 1.038e+04 on 1 and 514 DF, p-value: < 2.2e-16

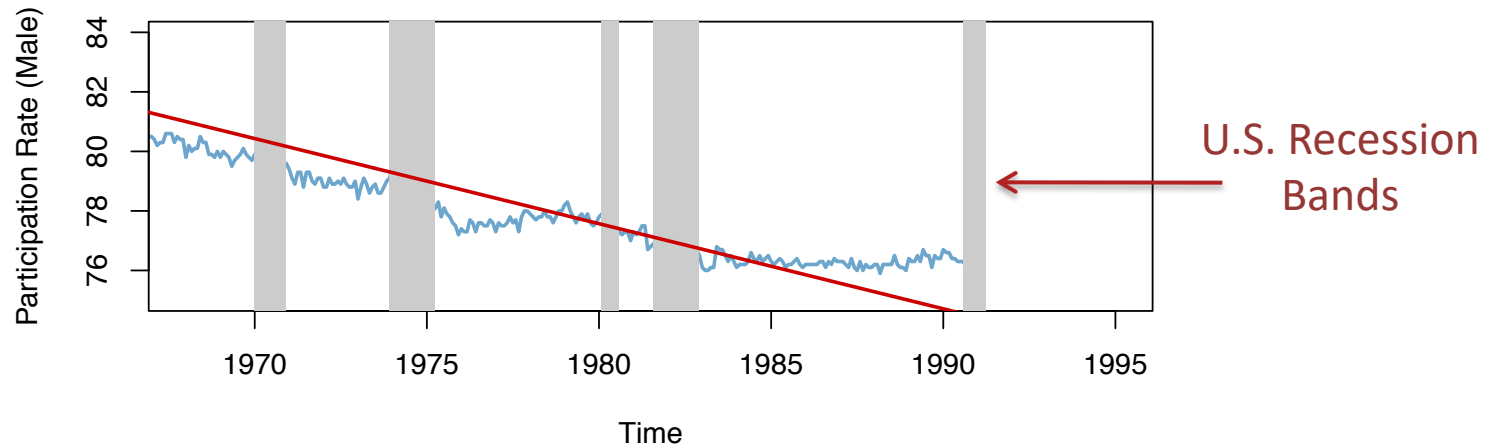


$R^2 = 0.95 \rightarrow$ Excellent!

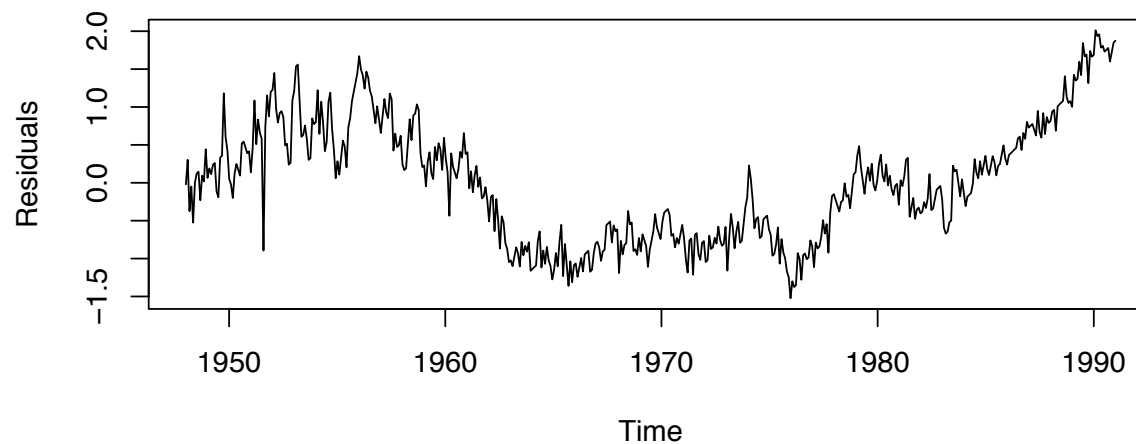
Do you see anything wrong?

Time : 1948-1990

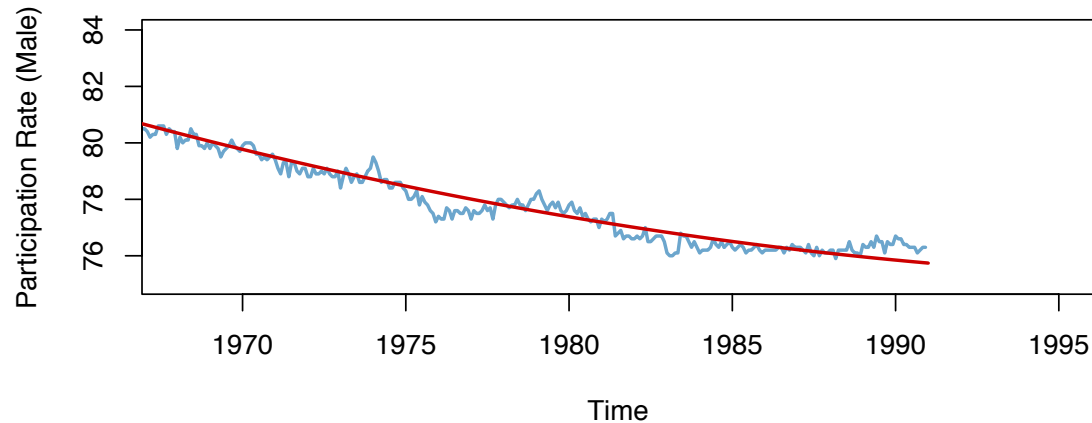
Modeling Trend (Linear) 4 of 4



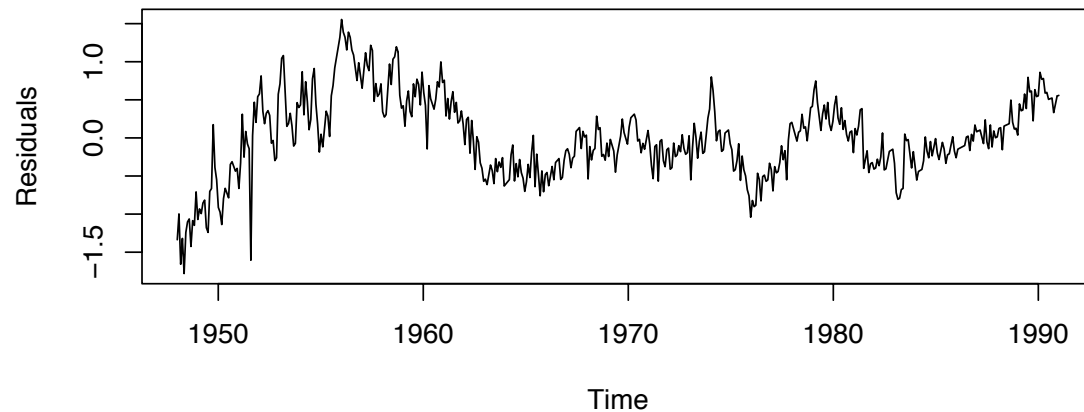
$$\text{Model: } T_t = \beta_0 + \beta_1 \text{ TIME}_t$$



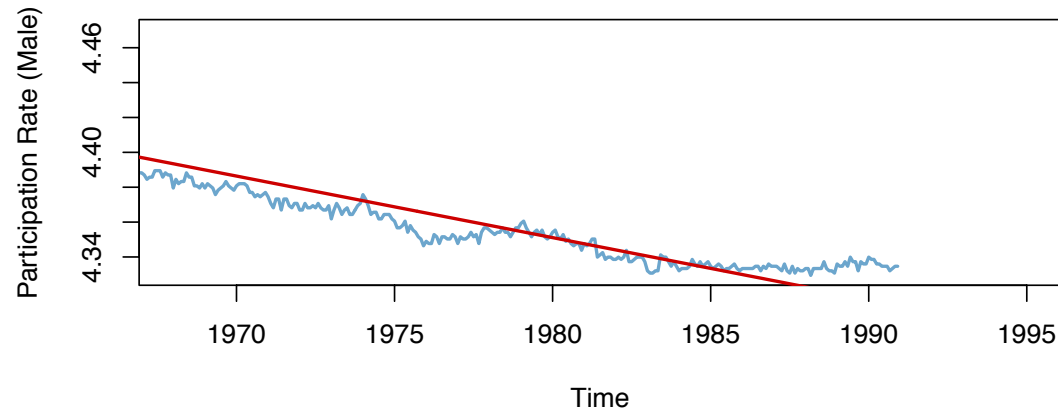
Modeling Trend (Quadratic)



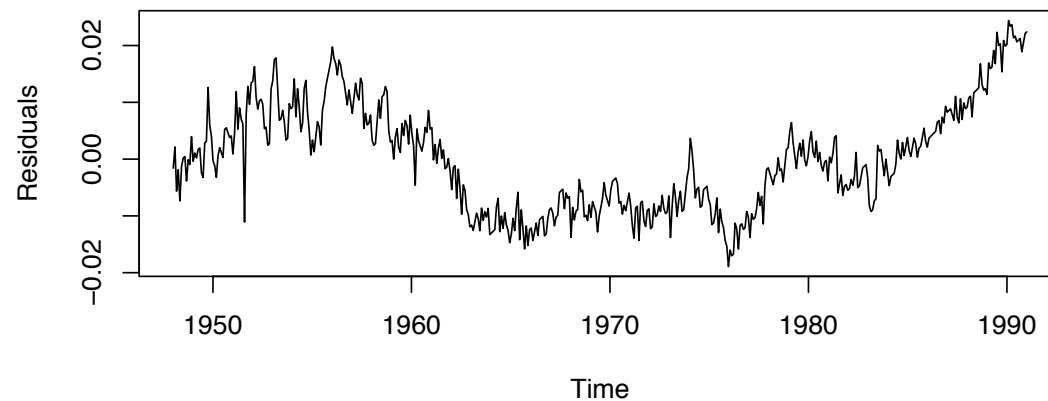
$$\text{Model: } T_t = \beta_0 + \beta_1 \text{ TIME}_t + \beta_2 \text{ TIME}^2$$



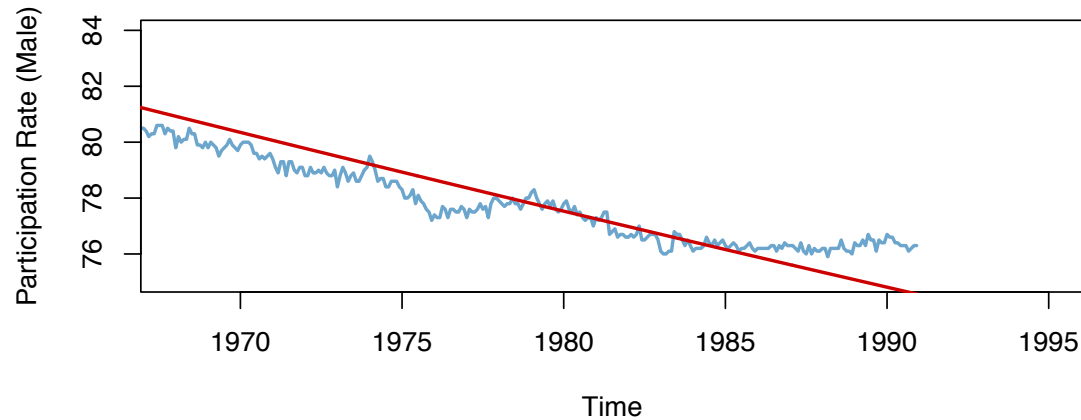
Modeling Trend (Log-Linear)



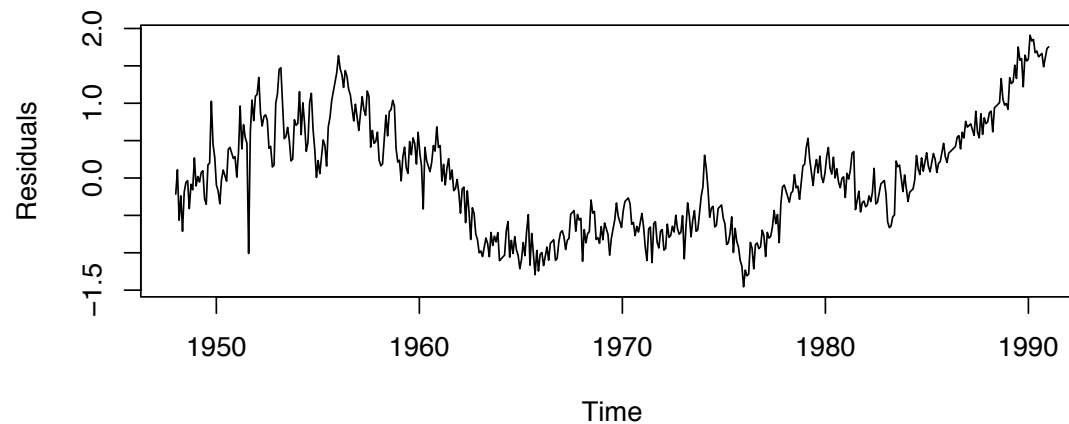
$$\text{Model: } \log(T_t) = \beta_0 + \beta_1 \text{ TIME}_t$$



Modeling Trend (Exponential)



$$\text{Model: } T_t = \beta_0 e^{\beta_1 TIME} E_t$$




Model Selection via AIC and BIC

Model	df	AIC	BIC
Linear	3	1229.0482	1241.7865
Quadratic	4	808.3932	825.3776
Log-Linear	3	-3361.0625	-3348.3242
Exponential	3	1160.3758	1173.1141

The smaller the AIC/BIC value, the better the model.

Both AIC and BIC select the **quadratic** fit as the preferred model.

Forecasting Trend 1 of 2

- **Example** (Point Forecast): Initially at T , and want to use a trend model to forecast the *h-step-ahead* value.
- Assume a linear trend: $y_t = \beta_0 + \beta_1 TIME_t + \varepsilon_t$
- At time $T+h$: $y_{T+h} = \beta_0 + \beta_1 TIME_{T+h} + \varepsilon_{T+h}$ ~ 0 (zero-mean random noise)
- Point forecast: $y_{T+h,T} = \beta_0 + \beta_1 TIME_{T+h}$
 Forecast is for $t = T+h$ but based on $t = T$
- However, β_0 and β_1 are unknown. **Solution**: replace them with their LS estimates $\hat{\beta}_0$ and $\hat{\beta}_1$.
- Point Forecast: $\hat{y}_{T+h,T} = \hat{\beta}_0 + \hat{\beta}_1 TIME_{T+h}$

Forecasting Trend 2 of 2

- **Example** (Interval Forecast): Same idea as before. Assume the trend regression disturbance is normally distributed, then:
 - Interval Forecast: $y_{T+h,T} \pm z^* \sigma$
 - In practice, use: $\hat{y}_{T+h,T} \pm z^* \hat{\sigma}$
- **Example** (Density Forecast): Same idea, yet again!
 - Density Forecast: $\mathcal{N}(y_{T+h,T}, \sigma^2)$
 - In practice, use: $\mathcal{N}(\hat{y}_{T+h,T}, \hat{\sigma}^2)$

Forecasting Trend (Example)

