

Rob J Hyndman

Forecasting using



6. ETS models

[OTexts.com/fpp/7/](https://otexts.com/fpp/7/)

Outline

- 1 Exponential smoothing methods so far**
- 2 Holt-Winters' seasonal method
- 3 Taxonomy of exponential smoothing methods
- 4 Exponential smoothing state space models

Exponential smoothing methods

- Simple exponential smoothing: no trend.

`ses(x)`

- Holt's method: linear trend.

`holt(x)`

- Exponential trend method.

`holt(x, exponential=TRUE)`

- Damped trend method.

`holt(x, damped=TRUE)`

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`holt(x, damped=TRUE, exponential=TRUE)`

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Holt-Winters additive method

- Holt and Winters extended Holt's method to capture seasonality.
- Three smoothing equations—one for the level, one for trend, and one for seasonality.
- Parameters: $0 \leq \alpha \leq 1$, $0 \leq \beta^* \leq 1$, $0 \leq \gamma \leq 1 - \alpha$ and $m = \text{period of seasonality}$.

Holt-Winters additive method

$$\hat{y}_{t+h|t} = \ell_t + hb_t + s_{t-m+h_m^*}$$

$$\ell_t = \alpha(y_t - s_{t-m}) + (1 - \alpha)(\ell_{t-1} + b_{t-1})$$

$$b_t = \beta^*(\ell_t - \ell_{t-1}) + (1 - \beta^*)b_{t-1}$$

$$s_t = \gamma(y_t - \ell_{t-1} - b_{t-1}) + (1 - \gamma)s_{t-m}$$

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Holt-Winters additive method

$$\hat{y}_{t+h|t} = \ell_t + hb_t + s_{t-m+h_m^+}$$

ETS takes holt-winter building block
and allow for more combinations
- ETS - 15 combinations

$$\ell_t = \alpha(y_t - s_{t-m}) + (1 - \alpha)(\ell_{t-1} + b_{t-1})$$

$$b_t = \beta^*(\ell_t - \ell_{t-1}) + (1 - \beta^*)b_{t-1}$$

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$$s_t = \gamma(y_t - \ell_{t-1} - b_{t-1}) + (1 - \gamma)s_{t-m}$$

$$h_m^+ = \lfloor (h - 1) \bmod m \rfloor + 1$$

Holt-Winters multiplicative method

Holt-Winters multiplicative method

$$\hat{y}_{t+h|t} = (\ell_t + hb_t)s_{t-m+h_m^+}$$

$$\ell_t = \alpha(y_t/s_{t-m}) + (1 - \alpha)(\ell_{t-1} + b_{t-1})$$

$$b_t = \beta^*(\ell_t - \ell_{t-1}) + (1 - \beta^*)b_{t-1}$$

$$s_t = \gamma(y_t/(\ell_{t-1} + b_{t-1})) + (1 - \gamma)s_{t-m}$$

- Most textbooks use $s_t = \gamma(y_t/\ell_t) + (1 - \gamma)s_{t-m}$
- We optimize for $\alpha, \beta^*, \gamma, \ell_0, b_0, s_0, s_{-1}, \dots, s_{1-m}$.

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$$\hat{y}_{t+h|t} = (\ell_t + hb_t)s_{t-m+h_m^+}$$

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- We optimize for $\alpha, \beta^*, \gamma, \ell_0, b_0, s_0, s_{-1}, \dots, s_{1-m}$.

Damped Holt-Winters method

Damped Holt-Winters multiplicative method

$$\hat{y}_{t+h|t} = [\ell_t + (1 + \phi + \phi^2 + \dots + \phi^{h-1})b_t]s_{t-m+h_m^+}$$

$$\ell_t = \alpha(y_t/s_{t-m}) + (1 - \alpha)(\ell_{t-1} + \phi b_{t-1})$$

$$b_t = \beta^*(\ell_t - \ell_{t-1}) + (1 - \beta^*)\phi b_{t-1}$$

$$s_t = \gamma[y_t/(\ell_{t-1} + \phi b_{t-1})] + (1 - \gamma)s_{t-m}$$

- This is often the single most accurate forecasting method for seasonal data.

A confusing array of methods?

- All these methods can be confusing!
- How to choose between them?
- The ETS framework provides an automatic way of selecting the best method.
- It was developed to solve the problem of automatically forecasting pharmaceutical sales across thousands of products.

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Exponential smoothing methods

Trend Component		Seasonal Component		
		N (None)	A (Additive)	M (Multiplicative)
N	(None)	N,N	N,A	N,M
A	(Additive)	A,N	A,A	A,M
A _d	(Additive damped)	A _d ,N	A _d ,A	A _d ,M
M	(Multiplicative)	M,N	M,A	M,M
M _d	(Multiplicative damped)	M _d ,N	M _d ,A	M _d ,M

Damped - when trend flattens after increasing

Three letters - none, additive, multiplicative
- ETS run through all of these

Exponential smoothing methods

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(N,N): Simple exponential smoothing

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(A,A): Additive Holt-Winters' method

Missing level

Exponential smoothing methods

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There are 15 separate exponential smoothing methods.

R functions

- `ses()` implements method (N,N)
- `holt()` implements methods (A,N),
(A_d,N), (M,N), (M_d,N)
- `hw()` implements methods (A,A), (A_d,A),
(A,M), (A_d,M), (M,M), (M_d,M).

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Exponential smoothing

- Until recently, there has been no stochastic modelling framework incorporating likelihood calculation, prediction intervals, etc.
- Ord, Koehler & Snyder (JASA, 1997) and Hyndman, Koehler, Snyder and Grose (IJF, 2002) showed that all ES methods (including non-linear methods) are optimal forecasts from innovations state space models.
- Hyndman et al. (2008) provides a comprehensive and up-to-date survey of area.

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- The forecast package implements the state space framework.

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- Ord, Koehler & Snyder (JAS 1998) and Hyndman, Koehler, Snyder & Granger (2002) showed that all ES methods (including non-linear methods) are equivalent to innovations state space models.
- Hyndman et al. (2008) produced the `forecast` package in R, which provides a comprehensive and up-to-date framework for forecasting with ES.
- The `forecast` package implements the state space framework.

Springer Series in Statistics

Rob J. Hyndman · Anne B. Koehler
J. Keith Ord · Ralph D. Snyder

Forecasting with Exponential Smoothing

The State Space Approach

 Springer

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- The **forecast** package implements the state space framework.

Exponential smoothing

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A _d	(Additive damped)	A _d ,N	A _d ,A	A _d ,M
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General notation *ETS(Error,Trend,Seasonal)*

Exponential smoothing

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Exponential Smoothing

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General notation **ETS**(*Error,Trend,Seasonal*)
ExponenTial Smoother

ETS(A,N,N): Simple exponential smoothing with additive errors

Exponential smoothing

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General notation **ETS**(*Error,Trend,Seasonal*)
ExponentTial **S**moother

ETS(A,A,N): Holt's linear method with additive errors

Exponential smoothing

		Seasonal Component		
		N (None)	A (Additive)	M (Multiplicative)
N	(None)	N,N	N,A	N,M
A	(Additive)	A,N	A,A	A,M
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General notation **ETS**(*Error,Trend,Seasonal*)
ExponenTial Smoother

ETS(A,A,A): Additive Holt-Winters' method with additive errors

Exponential smoothing

		Seasonal Component		
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A	(Additive)	A,N	A,A	A,M
A _d	(Additive damped)	A _d ,N	A _d ,A	A _d ,M
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General notation **ETS**(*Error,Trend,Seasonal*)
ExponenTial Smoother

ETS(M,A,M): Multiplicative Holt-Winters' method
 with multiplicative errors

Exponential smoothing

		Seasonal Component		
		N (None)	A (Additive)	M (Multiplicative)
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General notation **ETS**(*Error,Trend,Seasonal*)
ExponenTial Smoother

ETS(A,A_d,N): Damped trend method with additive errors

Exponential smoothing

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General notation **ETS**(*Error,Trend,Seasonal*)
ExponenTial Smoothering

There are 30 separate models in the ETS framework

Innovations state space models

SES

$$\hat{y}_{t+1|t} = \ell_t$$

$$\ell_t = \alpha y_t + (1 - \alpha)\ell_{t-1}$$

Innovations state space models

SES

$$\hat{y}_{t+1|t} = l_t$$

$$l_t = \alpha y_t + (1 - \alpha)l_{t-1}$$

If $\varepsilon_t = y_t - \hat{y}_{t-1|t}$
 $\sim \text{NID}(0, \sigma^2)$, then

ETS(A,N,N)

$$y_t = l_{t-1} + \varepsilon_t$$

$$\begin{aligned} l_t &= \alpha y_t + (1 - \alpha)l_{t-1} \\ &= l_{t-1} + \alpha \varepsilon_t \end{aligned}$$

Innovations state space models

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$$\begin{aligned} l_t &= \alpha y_t + (1 - \alpha)l_{t-1} \\ &= l_{t-1} + \alpha \varepsilon_t \end{aligned}$$

If $\varepsilon_t = (y_t - \hat{y}_{t-1|t})/\hat{y}_{t-1|t}$
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ETS(M,N,N)

$$y_t = l_{t-1}(1 + \varepsilon_t)$$

$$\begin{aligned} l_t &= \alpha y_t + (1 - \alpha)l_{t-1} \\ &= l_{t-1}(1 + \alpha \varepsilon_t) \end{aligned}$$

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ETS(A,N,N)

$$y_t = \ell_{t-1} + \varepsilon_t$$

$$\begin{aligned}\ell_t &= \alpha y_t + (1 - \alpha)\ell_{t-1} \\ &= \ell_{t-1} + \alpha\varepsilon_t\end{aligned}$$

ETS(M,N,N)

$$y_t = \ell_{t-1}(1 + \varepsilon_t)$$

$$\begin{aligned}\ell_t &= \alpha y_t + (1 - \alpha)\ell_{t-1} \\ &= \ell_{t-1}(1 + \alpha\varepsilon_t)\end{aligned}$$

All exponential smoothing methods can be written using analogous state space equations.

Innovations state space models

- All the methods can be written in this state space form.
- Prediction intervals can be obtained by simulating many future sample paths.
- For many models, the prediction intervals can be obtained analytically as well.
- Additive and multiplicative versions give the same point forecasts.
- Estimation is handled via maximizing the likelihood of the data given the model.

Innovations state space models

Example: Holt-Winters' multiplicative seasonal method

ETS(M,A,M)

$$y_t = (\ell_{t-1} + b_{t-1})s_{t-m}(1 + \varepsilon_t)$$

$$\ell_t = (\ell_{t-1} + b_{t-1})(1 + \alpha\varepsilon_t)$$

$$b_t = b_{t-1} + \beta(\ell_{t-1} + b_{t-1})\varepsilon_t$$

$$s_t = s_{t-m}(1 + \gamma\varepsilon_t)$$

where $\beta = \alpha\beta^*$.

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Akaike's Information Criterion

$$\text{AIC} = -2 \log(\text{Likelihood}) + 2p$$

where p is the number of estimated parameters in the model.

- *Minimizing* the AIC gives the best model for prediction.

AIC corrected (for small sample bias)

$$\text{AIC}_c = \text{AIC} + \frac{2(p+1)(p+2)}{n-p}$$

Schwartz' Bayesian IC

$$\text{BIC} = \text{AIC} + p(\log(n) - 2)$$

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Exponential smoothing

From Hyndman et al. (2008):

- Apply each of 30 methods that are appropriate to the data. Estimate parameters and initial values using MLE.
- Select best method using AIC.
- Produce forecasts using best method.
- Obtain prediction intervals using underlying state space model.

Method performed very well in M3 competition.

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fit <- ets(ausbeer)
fit2 <- ets(ausbeer,model="AAA",damped=FALSE)
fcast1 <- forecast(fit, h=20)
fcast2 <- forecast(fit2, h=20)
```

```
ets(y, model="ZZZ", damped=NULL, alpha=NULL,
    beta=NULL, gamma=NULL, phi=NULL,
    additive.only=FALSE,
    lower=c(rep(0.0001,3),0.80),
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Exponential smoothing

```
> fit  
ETS(M,Md,M)
```

Smoothing parameters:

```
alpha = 0.1776  
beta  = 0.0454  
gamma = 0.1947  
phi   = 0.9549
```

Initial states:

```
l = 263.8531  
b = 0.9997  
s = 1.1856 0.9109 0.8612 1.0423
```

sigma: 0.0356

AIC	AICc	BIC
2272.549	2273.444	2302.715

Exponential smoothing

```
> fit2  
ETS(A,A,A)
```

Smoothing parameters:

alpha = 0.2079

beta = 0.0304

gamma = 0.2483

Initial states:

l = 255.6559

b = 0.5687

s = 52.3841 -27.1061 -37.6758 12.3978

sigma: 15.9053

AIC	AICc	BIC
2312.768	2313.481	2339.583

Exponential smoothing

`ets()` function

- Automatically chooses a model by default using the AIC, AICc or BIC.
- Can handle any combination of trend, seasonality and damping
- Produces prediction intervals for every model
- Ensures the parameters are admissible (equivalent to invertible)
- Produces an object of class `ets`.

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Exponential smoothing

ets objects

- **Methods:** `coef()`, `plot()`, `summary()`, `residuals()`, `fitted()`, `simulate()` and `forecast()`
- `plot()` function shows time plots of the original time series along with the extracted components (level, growth and seasonal).

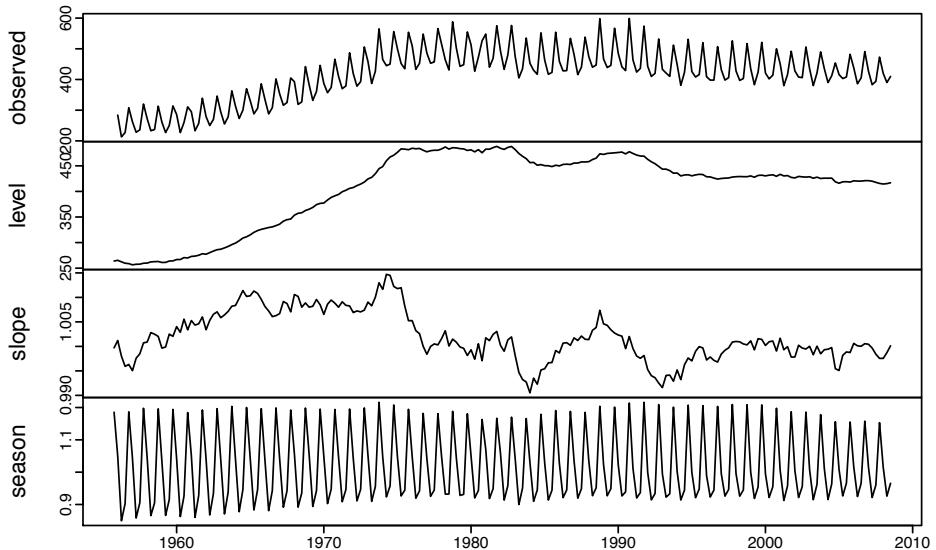
Exponential smoothing

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Exponential smoothing

`plot(fit)`
Decomposition by ETS(M,Md,M) method



Goodness-of-fit

```
> accuracy(fit)
```

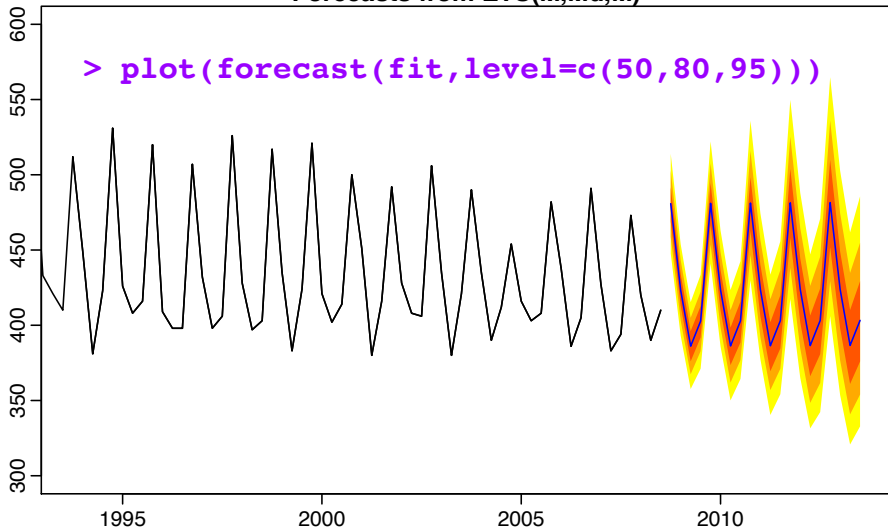
ME	RMSE	MAE	MPE	MAPE	MASE
0.17847	15.48781	11.77800	0.07204	2.81921	0.20705

```
> accuracy(fit2)
```

ME	RMSE	MAE	MPE	MAPE	MASE
-0.11711	15.90526	12.18930	-0.03765	2.91255	0.21428

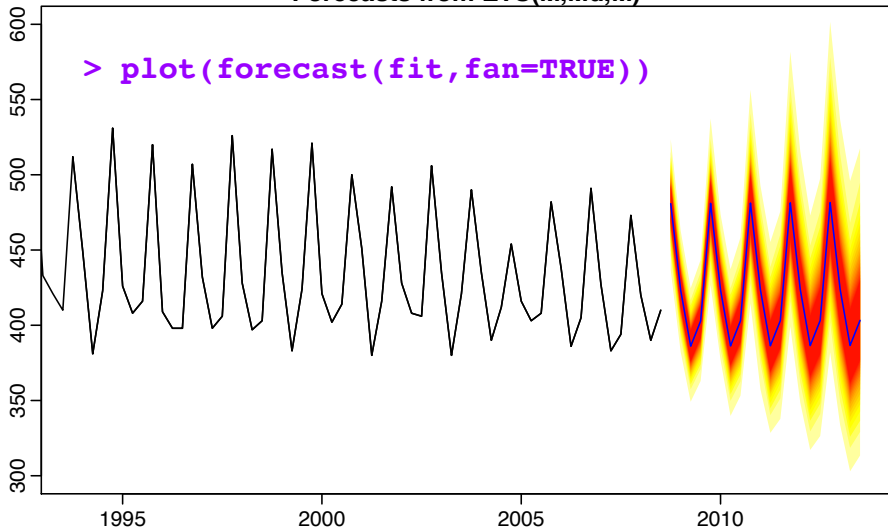
Forecast intervals

Forecasts from ETS(M,Md,M)



Forecast intervals

Forecasts from ETS(M,Md,M)



Exponential smoothing

`ets()` function also allows refitting model to new data set.

```
> usfit <- ets(usnetelec[1:45])
> test <- ets(usnetelec[46:55], model = usfit)

> accuracy(test)
      ME      RMSE      MAE      MPE      MAPE      MASE
-3.35419 58.02763 43.85545 -0.07624  1.18483  0.52452

> accuracy(forecast(usfit,10), usnetelec[46:55])
      ME      RMSE      MAE      MPE      MAPE      MASE
40.7034  61.2075  46.3246  1.0980  1.2620  0.6776
```

Unstable models

- ETS(M,M,A)
- ETS(M,M_d,A)
- ETS(A,N,M)
- ETS(A,A,M)
- ETS(A,A_d,M)
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- $ETS(A,M_d,A)$
- $ETS(A,M_d,M)$

In practice, the models work fine for short- to medium-term forecasts provided the data are strictly positive.

Forecastability conditions

```
ets(y, model="ZZZ", damped=NULL, alpha=NULL,
    beta=NULL, gamma=NULL, phi=NULL,
    additive.only=FALSE,
    lower=c(rep(0.0001,3),0.80),
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    opt.crit=c("lik","amse","mse","sigma"),
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```

The magic `forecast()` function

- `forecast` returns forecasts when applied to an `ets` object (or the output from many other time series models).
- If you use `forecast` directly on data, it will select an ETS model automatically and then return forecasts.

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