Executive Summary

This document walks through the steps to get a Radio Bridge Indoor Temperature and Humidity Sensor (RBS305-ATH-US) connected to the Helium network, connected to Cayenne myDevices, and capturing data in a Google Sheet via a Pipedream workflow. The document also covers how to change the mode of the sensor from the default mode (triggering on temperature or humidity crossing a threshold) to triggering on a change in temperature or humidity.

Steps

- 1. Add the device to the console and get data flowing
- 2. Apply a decoder function to the device in the Helium Console so you can see/access the sensor data in the payload
- 3. Change the mode of the sensor
- 4. Build a Cayenne myDevices Integration so you can see the sensor data in Cayenne
- 5. Build a Google Sheet integration so you can see/log/share the sensor data in a spreadsheet

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References

ID	Topic	Reference	Description	
1	Radio	https://radiobridge.com/products/wireless-	Documentation Download page	
	Bridge	air-temperature-and-humidity-sensor	Lora Connection Guide	
		1. How to Connect LoRaWAN Sensors.pdf	2. User Guide for the RBS305-ATH-US	
		2. Wireless Air Temp and Humidity Sensor	3. User Guide for sensor messages	
		User Guide.pdf	common to all Radio Bridge sensors	
		3. Common Sensor Messages.pdf	4. Decoder function source code	
		4. https://github.com/RadioBridge/Packet-	5. Support Article on Downlink	

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RBS305-ATH-US_HeliumQuickStart

		Decoder/blob/master/radio bridge packe t_decoder.js 5. https://support.radiobridge.com/portal/e_n/kb/articles/how-do-i-create-a-downlink-configuration-for-an-air-temperature-and-humidity-sensor	messages for Radio Bridge Sensor RBS305-ATH-US	
2	Helium	 https://developer.helium.com/console/ad ding-devices https://developer.helium.com/console/functions https://developer.helium.com/console/integrations/mydevices-cayenne-integration https://developer.helium.com/console/labels https://developer.helium.com/console/integrations/http#downlink-tool-example 	 How to add a device to the console How to create a decoder function How to set up a Cayenne dashboard for your Helium Devices Organizing and Connecting with Labels Using the Helium Downlink tool 	
3	Pipedream	 https://github.com/mikedsp/helium/blob/master/MyDocuments/HowTo_BrowanTB HH100 to GoogleSheet-SHARE.pdf https://pipedream.com/@dangermikeb/pipedreamint_rbs305-p_OKCdkK 	 HowTo Guide - How to get data from a Browan TBHH100 temperature and humidity sensor to flow in real time to a Google Sheet. Mike's Pipedream workflow for the RBS305-AUTH-US sensor 	
4	LoRaWAN	https://lora- developers.semtech.com/uploads/documents /files/LoRaWAN Class A Devices In Depth Downloadable.pdf	About Class A Devices	
5	Base64 Converter	https://base64.guru/converter/decode/hex	Web tool for converting numbers from one format to another	
6	Mike's GitHub Document Repository	https://github.com/mikedsp/helium/tree/mas ter/MyDocuments 1. https://github.com/mikedsp/helium/b lob/master/MyDocuments/RBS305- ATH-US payloadAnalysis.pdf 2. https://github.com/mikedsp/helium/b lob/master/MyDocuments/HowTo Br owanTBHH100 to GoogleSheet- SHARE.pdf 3. https://github.com/mikedsp/helium/b lob/master/MyDocuments/20201016	Document repository for various HowTo and Quick Start documents about working with IoT sensors in the Helium network 1. Manual decoding of some messages from the Radio Bridge sensor 2. Detailed instructions for getting data from a TBHH100 sensor logging into a Google Sheet using a Pipedream workflow 3. Spreadsheet with data collected from the RBS305-ATH-US sensor as well as from a TBHV110 sensor 4. Spreadsheet with data collected from the RBS305-ATH-US sensor	

Add the Device to the Helium Console

Using the Helium instructions at the following URL, add the device to your Helium Console:

https://developer.helium.com/console/adding-devices

Section 9 of the Radio Bridge document, *How to Connect LoRaWAN Sensors.pdf*, will help you find the DevEUI, AppEUI, and App Key information. If you read the Radio Bridge document, you'll see that Radio Bridge has its own Console that allows you to register your device and to integrate it with various public networks (Things Network, SENET, LORIOT, and more). Unfortunately, the Helium Network was not supported by the Radio Bridge Console at the time this document was written.

My device came with a small magnet that when placed next to a specific location on the device, triggers the device to send a packet. This is how I triggered the activation. Then I used the in-and-out of the freezer trick to initiate temperature changes to trigger additional uplink messages.

9. THIRD-PARTY NETWORK SERVER

This section provides the information required to connect the LoRaWAN sensors to a third party LoRaWAN network server not otherwise described in this document. The network server may reside on the gateway itself or in the cloud, and the server may push the data to the Radio Bridge console or another third-party application.

9.1. Sensor to Network Server

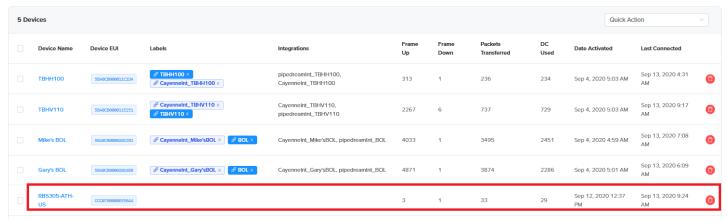
The LoRaWAN network server must use the connectivity parameters shown in the following table.

Table 7 LoRaWAN Parameters

LoRaWAN Parameter	Description
Activation Method	OTA (over the air activation). The sensor will send a join request and expect a join accept before any other messages can be sent.
Device EUI	This is the ID on the label located on the sensor itself. The barcode provided can also be used to read the Device EUI.
Application EUI	See the section on AppEUI/JoinEUI above. This can be customized in the factory for production orders, but most customers simply use this default.
Application Key	This is the Key on the label located on the sensor itself. The barcode provided can also be used to read the Application Key.

(above) Section 9 from the Radio Bridge manual, How to Connect LoRaWAN Sensors.pdf





(above) RBS305-ATH-US added to the Console and data is flowing

(above) Data from the sensor in the Console debug window. Because there is no decoder function, the payload is not decoded.

Apply a Decoder to the Device

Using the Helium instructions at the following URL, create a decoder function and apply it to the device:

• https://developer.helium.com/console/functions

Fortunately, Radio Bridge has provided decoder source code in the following GitHub repository:

https://github.com/RadioBridge/Packet-Decoder/blob/master/radio bridge packet decoder.js

Here are the steps to go through:

- 1. Create a label called 'RBS305'
- 2. Create a new custom function
 - a. Name it 'RBS305decoderFunction' to make it easy to identify in the Console
 - b. Copy and paste in the function code from the Radio Bridge GitHub repository at https://github.com/RadioBridge/Packet-Decoder/blob/master/radio_bridge_packet_decoder.js

Appendix B of this document show my complete custom decoder function source code.

- c. Apply the 'RBS305' label to the function
- 3. Go back to the Devices tab of the Console and apply the 'RBS305' label from the previous step to the RBS305-ATH-US device
- 4. While looking at the device in the Console, turn on the debugger and wait for data to flow
 Hint: Move the device into or out of your freezer to trigger a temperature event. Even doing that, it took
 about 10-15 minutes before I started seeing data in the debugger
- 5. Once the Console/debugger receives a data packet from the device, verify you can see the decoded data, which should look similar to screenshot below

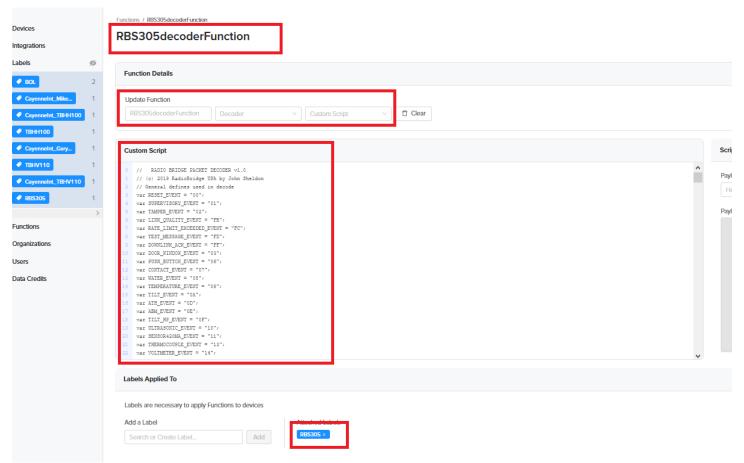
(above) Decoded data in the Console debugger from the RBS305-ATH-US device.

In the console debug screenshot above, part of the deoded message is cut off. Appendix A of this document has a copy of the entire JSON message. The complete decoded Message is shown below.

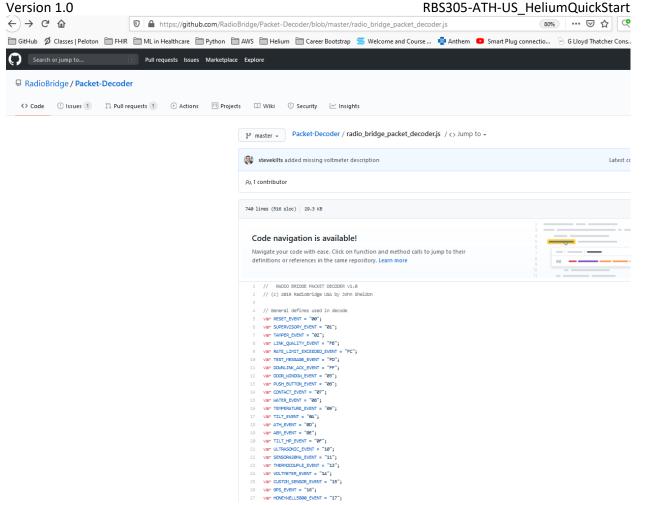
```
"decoded": {
```

```
"payload": {
    "Message": "Event: Air Temperature/Humidity, ATH Event: Temperature has Fallen Below Lower Threshold,
Temperature: 9.9, Humidity: 15.6, Packet Counter: 9, Protocol Version: 1"
},
"status": "success"
```

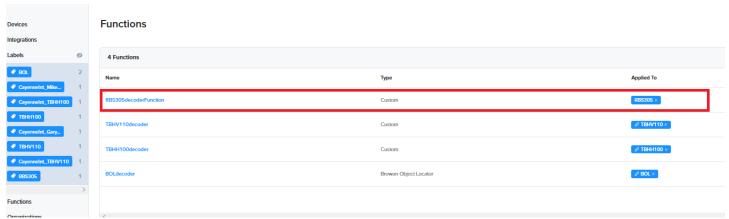
The screenshots below illustrate some of the steps above.



(above) Creating new decoder function called, RBS305decoderFunction, with label, RBS305.

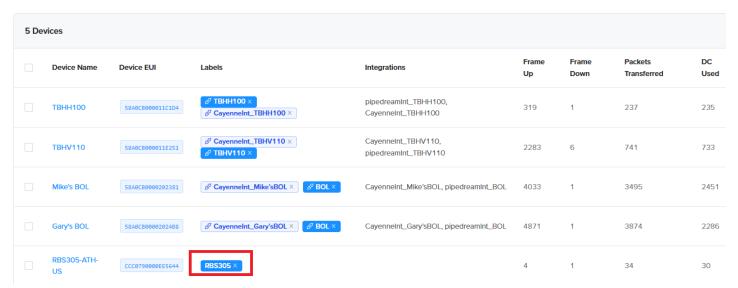


(above) Looking at the Generic decoder source code from the Radio Bridge GitHub repository



(above) The RBS305decoderFunction in the Function list of the Helium Console

Devices



(above) RBS305 label applied to the RBS305-ATH-US device

Radio Bridge Decoder Debug

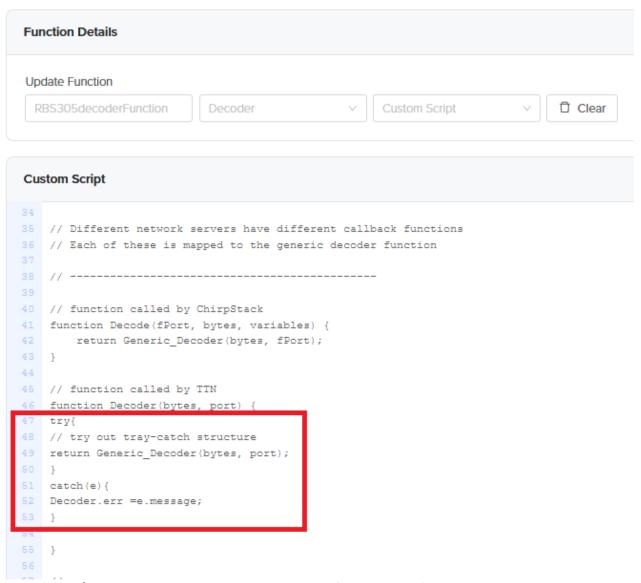
From 9/13 - 9/16/20, the Helium Console debug window was showing some received messages with a decoded function status of error. There was a discussion on this topic in the console Discord channel, with the following suggestion: try{ your code goes here } catch (e) { decoded.err = e.message; }

I added this the try/catch block to my decoder function, but since I did that, I haven't seen any more decoder errors in the debug window, so I am not sure *why* I was getting the errors in the first place.

The screenshot below shows the try/catch block added to the decoder function.

The document, RBS305-ATH-US_payloadAnalysis.doc, shows some of the Json with the errors (and a success).

RBS305decoderFunction



(above) A try/catch structure put around the contents of the Decoder function

Radio Bridge Console post to Helium Discord Console Channel

Below is the message I posted to the Helium Discord server querying if anyone had been able to interface the Helium Console to the Radio Bridge Console. Unfortunately, I didn't see any responses.

Q: Has anyone been able to successfully connect the Helium network to the Radio Bridge console using a Helium HTTP integration to a Radio Bridge Console 3rd Party Integration (see section 9.2 in the attached document - How to Connect LoRaWAN Sensors.pdf) and/or the Radio Bridge Console Callback API?

For the past few weeks, I've been working with a Radio Bridge indoor temp/humidity sensor (RBS305-AUTH-US). After constructing a downlink message by hand, I was able to use the Helium Console downlink capability to configure the device to send measurements once an hour rather than the default threshold mode. I have not been able to get the device to send message on changes in temperature and so far Radio Bridge Support has not been much help. What would make it **much** easier to control the device would be to use Radio Bridge's own console which handles message decoding and encoding. Unfortunately, while the Radio Bridge Console is set up for integrations to sigfox, machineQ, the Things Network, and more — it is **NOT** set up for integrations to the Helium Network. A support person from Radio Bridge indicated that is coming soon, but that doesn't help me now.

Change Mode of Sensor from 'Threshold' to 'Report on Change'

The Browan temperature and humidity sensors are defaulted to the following triggers:

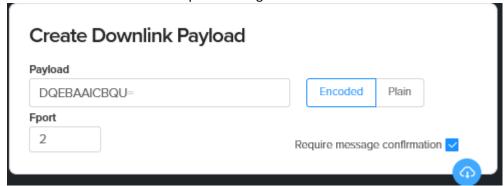
• 60-minute inactivity, ±2 °C delta, ±5 %RH Delta

The RBS305-ATH-US sensor is defaulted to a threshold trigger mode rather than a report on change configuration mode. From section 6.2.1 in the Sensor User guide, the default thresholds for the radio bridge sensor are as follows;

- Lower temperature threshold. Default 10 degrees C.
- Upper temperature threshold. Default 40 degrees C.
- Lower humidity threshold. Default 40% relative humidity.
- Upper humidity threshold. Default 60% relative humidity.

So that we can compare the performance of the sensors, we're going to program the RBS305 to have the same trigger as the Browan devices. To accomplish this, we're going to do the 6 steps listed below. Details on the steps are provided **after** step 6.

- 1. Construct the downlink configuration message content
 - a. Construct the message content in hex format
 - i. 0D 01 01 00 02 02 05 05 = 60-minute inactivity, ±2 °C delta, ±5 %RH Delta
 - b. Convert the message content to Base 64
 - i. DQEBAAICBQU=
- 2. Prepare to send the Message
 - a. Open up a new instance of the Helium Console and go to the Downlink form for the device
 - b. Fill in the 'Create Downlink Payload' form in the Helium Console
 - i. Payload = DQEBAAICBQU=
 - ii. Set Fport = 2
 - iii. Check the 'Require message confirmation' box



- 3. Reset the device with the magnet
 - a. In a different Helium Console window, go to the device and enable the debugger
 - b. Put the magnet by the appropriate place on the side of the device
 - c. Watch the Helium debugger, waiting for a Supervisory event to appear
- 4. Send the downlink message
 - a. When the supervisory event appears in the debugger window, trigger the downlink message in the Helium Console window from step 2
 - b. If you don't see a response in the debug window within 10 seconds, trigger the downlink message again
- 5. Validate uplink response

If the device accepted and understood the downlink message, you should receive a Downlink Ack message with a 'Message Valid' response in the Debug window. The message I received in the Console debug window is shown below.

```
"Message": "Event: Downlink Acknowledge, Downlink: Message Valid, Packet Counter: 4, Protocol Version: 1"
```

6. Initiate a temperature change to validate the device is operating as expected

To test whether the device is sending messages upon a change in temperature or humidity, put the device into (or take it out of) your freezer. The message I received in the Console debug window is shown below.

```
"Message": "Event: Air Temperature/Humidity, ATH Event: Temperature Report-
on-Change Decrease, Temperature: 14.5, Humidity: 11.2, Packet Counter: 14,
Protocol Version: 1"
```

The sub sections below provide useful details on the previous 6 steps.

Understanding when the RBS305-ATH-US device is listening for Downlink Messages

The paragraph below is from the LoRaWAN reference. It says that a Class A device listens for a downlink message one or two seconds after the uplink.

End devices in a LoRaWAN network come in three classes: Class A, Class B and Class C. While end devices can always send uplinks at will, the device's class determines when it can receive downlinks. The class also determines a device's energy efficiency. The more energy efficient a device, the longer the battery life. An In-depth Look at LoRaWAN® Class A Devices semtech.com/LoRa Page 3 of 12 Technical Paper Proprietary November 2019 Semtech All end devices must support Class A ("Aloha") communications. Class A end devices spend most of their time in sleep mode. Because LoRaWAN is not a "slotted" protocol, end devices can communicate with the network server any time there is a change in a sensor reading or when a timer fires. Basically, they can wake up and talk to the server at any moment. After the device sends an uplink, it "listens" for a message from the network one and two seconds after the uplink (receive windows) before going back to sleep. Class A is the most energy efficient and results in the longest battery life.

Constructing the Downlink Message

To construct the downlink message, we're going to use the information in <u>this Radio Bridge Support Article</u> with additional context from sections 6.2.2 and 6.2.3 in *Wireless Air Temp and Humidity Sensor User Guide.pdf*.

Report on Change Configuration Example:

0D 01 8F 00 0A 0F 05 14

0D	Downlink Message Type (Air Temp & Humidity = 0x0D)	
01	Reporting Mode (Report On Change = 0x01)	
8F	Periodic Reporting (15 minutes = 0x8F)	
00	Not Used	
0A	Temperature Increase (10 degrees $C = 0x0A$)	
0F	Temperature Decrease (15 degrees C = 0x0F)	
05	Humidity Increase (5% = 0x05)	
14	Humidity Decrease (20% = 0x14)	

If the configuration is successful the sensor will respond with a **Downlink Acknowledge** message: (above) Screenshot from this Radio Bridge Support Article

0D 01 01 00 02 02 05 05 = 60-minute inactivity, ±2 °C delta, ±5 %RH Delta

Byte Value	Description
0D	Downlink Message Type (Air Temp & Humidity = 0x0D)
01	Reporting Mode (Report On Change = 0x01)
01	Periodic Reporting (1 hour = 0x01)
00	Not used
02	Temperature Increase (2 degrees C = 0x02)
02	Temperature Decrease (2 degrees C = 0x02)
05	Humidity Increase (5% = 0x05)
05	Humidity Decrease (5% = 0x05)

Converting the Downlink Message from Hex to Base64 in Preparation for Putting the Message into the Helium Downlink form

ALERT - Be careful when using the Base64 Converter (Reference 5).

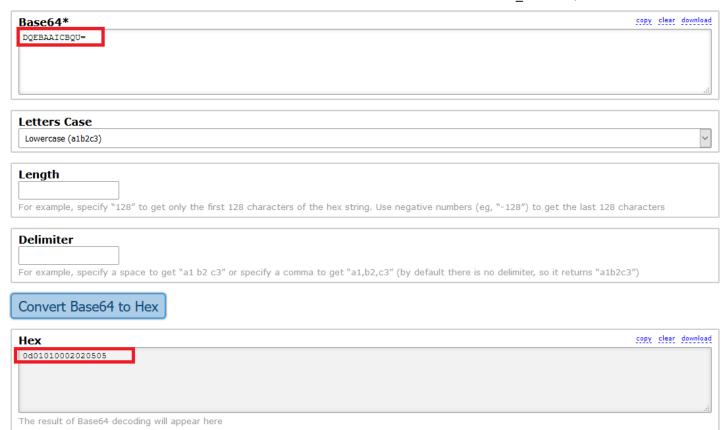
This is where I got into trouble the first time I reprogrammed the device. I did an incorrect conversion of 0D 01 01 00 02 02 05 05 into Base64. Specifically, the first time I added an extra 0 at the end of my hex string when I placed the string into the converter to make the converter work. The sensor device accepted the Base64 message I generated this way, but was only sending uplink messages every hour; not on temperature or humidity changes. I tried the conversion again several days later and this time was able to do it without adding the extra 0 at the end of the hex string, and that gave me a different Base64 payload to download.

Take the hex string from above, 0D 01 01 00 02 02 05 05, and paste it into <u>Hex to Base 64</u> to convert to Base64 format. The Base64 formatted string is what will be put into the Helium Console downlink form.



(above) Converting the hex string, 0D 01 01 00 02 02 05 05, into a Base64 string, DQEBAAICBQU=

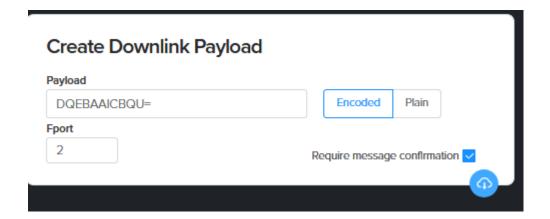
Confirm the result by converting the Base64 back into Hex using Base64 to Hex



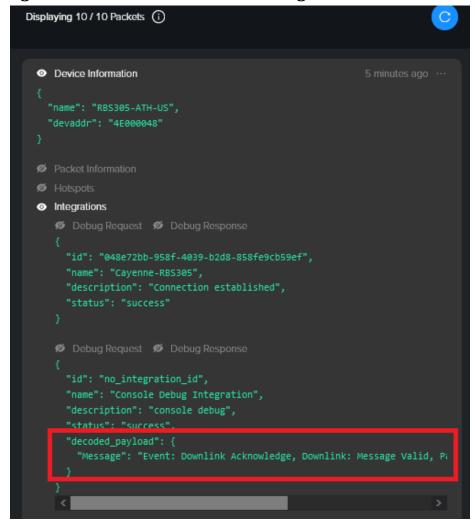
(above) Converting Base64 string back into Hex format to double check the Base64 value is legit

Preparing to Send the Downlink Message

Using the Helium instructions here: https://developer.helium.com/console/integrations/http#downlink-tool-example



Helium Debug Window - Download Ack Message



(above) Downlink Ack message with a 'message valid' confirmation of the downlink.

Debug Response

```
{
    "id": "048e72bb-958f-4039-b2d8-858fe9cb59ef",
    "name": "Cayenne-RBS305",
    "description": "Connection established",
    "status": "success"
}

Debug RequestDebug Response
{
    "id": "no_integration_id",
    "name": "Console Debug Integration",
    "description": "console debug",
    "status": "success",
    "decoded_payload": {
        "Message": "Event: Downlink Acknowledge, Downlink: Message Valid,
        Packet Counter: 4, Protocol Version: 1"
        }
}
```

(above) Complete text of the Debug Response from the Helium Debug Window

Build a Cayenne myDevices Integration

Using the instructions at the following URL, build a Cayenne myDevices integration for the device

• https://developer.helium.com/console/integrations/mydevices-cayenne-integration

Here are the steps to go through:

- 1. In the Helium Console, create a label called, RBS305-cayenne-int
- 2. In the Helium Console, apply the integration label, 'RBS305-cayenne-int' to the RBS305-ATH-US device

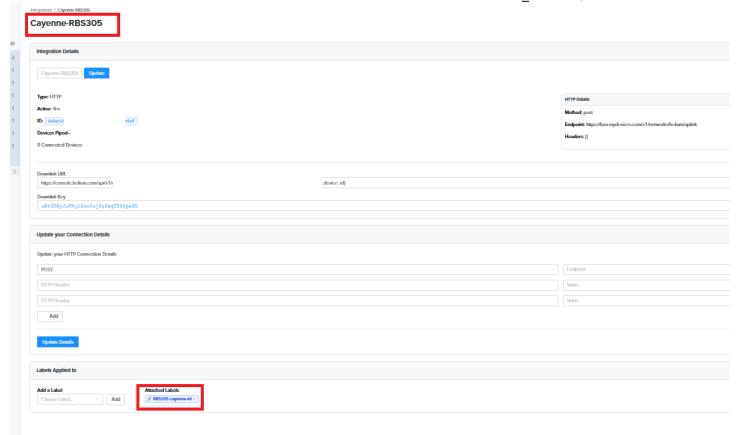
RBS305-AUTH-US to Cayenne Console Settings			
Console Object	Applied Label(s)		
Integration	Cayenne-RBS305	RBS305-cayenne-int	
Device	RBS305-ATH-US	RBS305-cayenne-int	

(above) Helium Console settings for the RBS305-to-Cayenne Integration

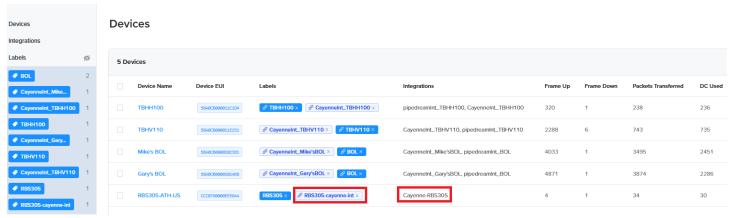
- 3. In the Helium Console, create a new Cayenne Integration
 - a. Name it 'Cayenne-RBS305'
 - b. Apply the label called 'RBS305-cayenne-int'
- 4. In the Cayenne Dashboard, add/create a new Device/Widget
 - a. Add new... > Devices & Widgets > Lora > Helium > Radio Bridge Air Temperature and Humidity Sensor
 - b. Change the default name to 'RBS305-ATH-US'
 - c. Add the DevEUI from the Helium Console
- 5. Wait for the data to flow into Cayenne

The screenshots below illustrate the steps above.

RBS305-ATH-US_HeliumQuickStart



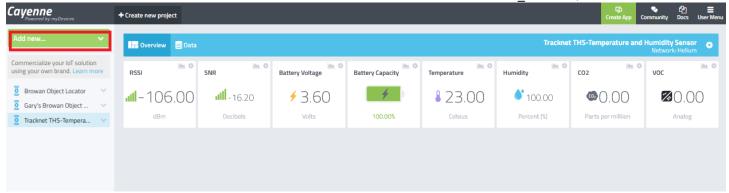
(above) the Cayenne-RBS305 integration has been created!



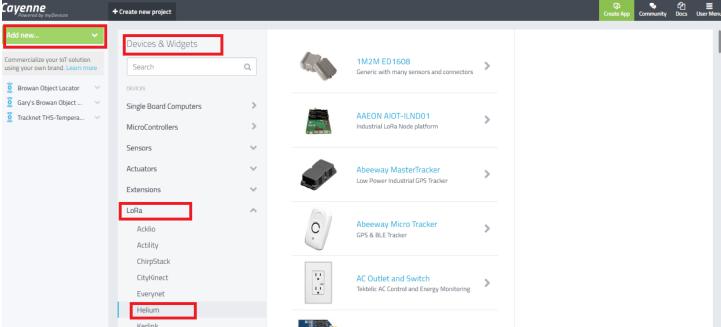
(above) RBS305-ATH-US device with the Cayenne integration applied through the RBS305_cayenne_int label

Version 1.0

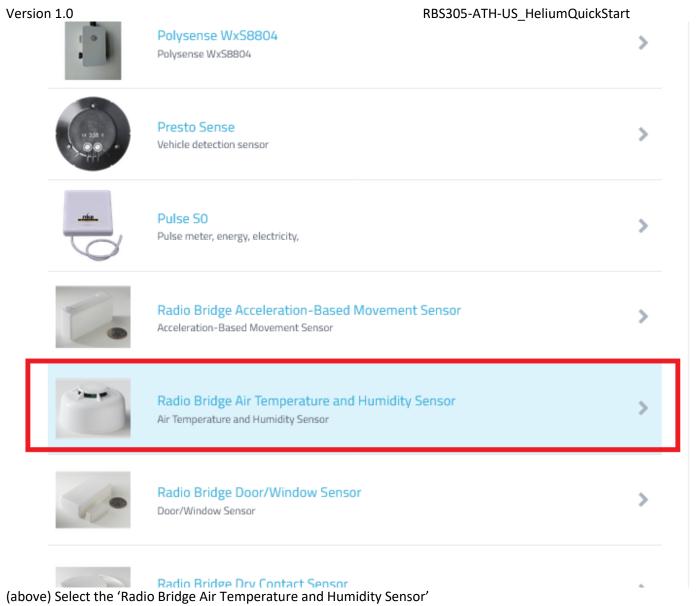
RBS305-ATH-US_HeliumQuickStart



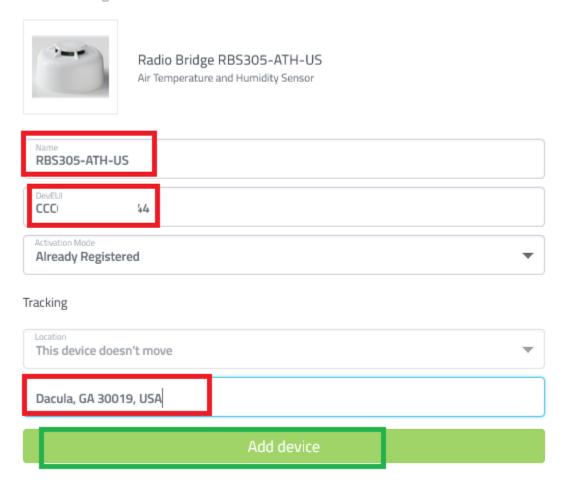
(above) Log into your Cayenne Dashboard and select the 'Add new...' button



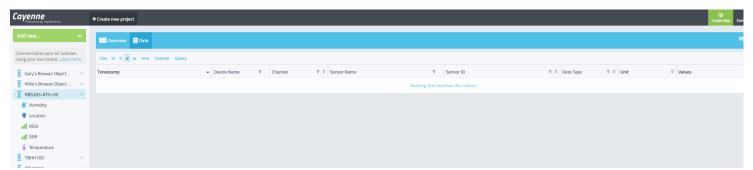
(above) Add new... > Devices & Widgets > Lora > Helium



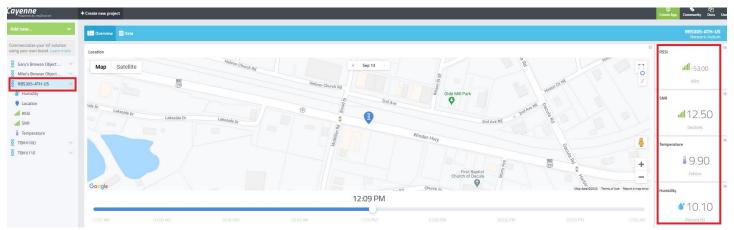
Enter Settings



(above) Entering the settings for the device



(above) The RBS305-ATH-US device has been added to your Cayenne dashboard and is waiting for data to come over



(above) Cayenne Dashboard showing Overview of data from the RBS305-ATH-US device – this is the most recent set of received measurements. Note – the device does not send location information, by the Cayenne Device Setup insisted I enter a location, so I put in 'Dacula, GA 30019 USA' and that is what is showing up in the map above.

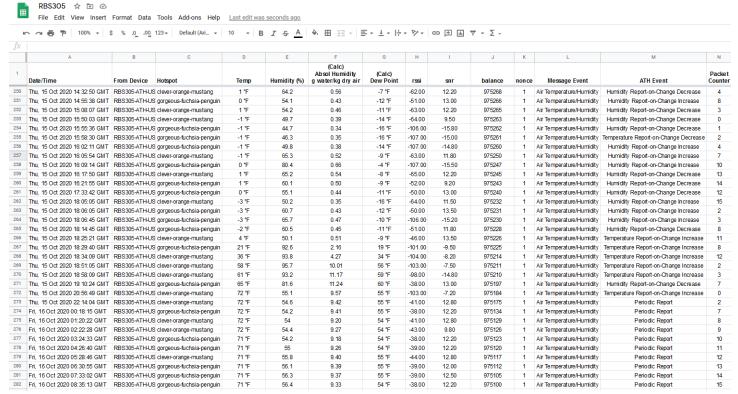


(above) Cayenne Dashboard showing measurements received from the RBS305-AUTH-US device. The device sends different types of events; some are status events and don't contain temperature or humidity information. You can see that in the data sent at 11:37 in the screenshot above.

Build a Google Sheet integration

Using the process described in Reference 6.2, <code>HowTo_BrowanTBHH100_to_GoogleSheet-SHARE.pdf</code>, build the following data flow to produce a spreadsheet like the one shown below.

• RBS305-ATH-US > Helium Hotspot > Helium Console/Network > Pipedream > Google Sheet



(above) Google Sheet receiving data from the RBS305-ATH-US sensor

Very Important: When creating the Custom HTTP Integration in the Helium Console to send data to Pipedream, it is critical that the label you apply to the Integration be created **BEFORE** you attach the label to the Integration. If you create the label for the Integration while you are creating the Integration, and then apply that label to the device on the Helium Console, Pipedream will NOT get decoded data. I made this mistake when building Pipedream integrations for my other sensors, the TBHH100 and the TBHV110.

The HowTo instructions for the TBHH100 device can be found in GitHub here:

https://github.com/mikedsp/helium/blob/master/MyDocuments/HowTo BrowanTBHH100 to GoogleSheet-SHARE.pdf

Two Excel files with some collected data can be found in GitHub at the URL below. The excel file was created by saving a copy of the Google Sheet that is capturing the sensor data.

https://github.com/mikedsp/helium/blob/master/MyDocuments/20201016_TempHumidity-SensorCompare.xlsx https://github.com/mikedsp/helium/blob/master/MyDocuments/20201020_RBS305data.xlsx

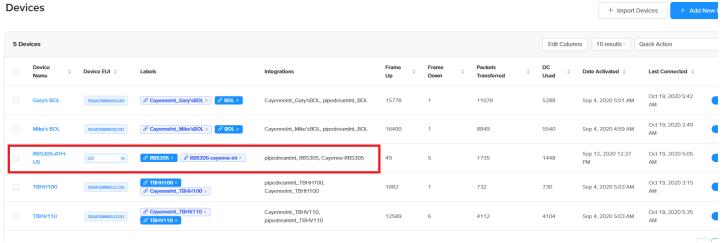
A public version of the Pipedream workflow can be found here:

https://pipedream.com/@dangermikeb/pipedreamint rbs305-p OKCdkK

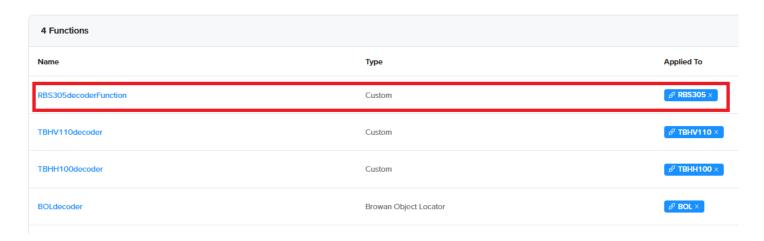
High level steps are as follows

- 1. Get the RBS305-ATH-US set up in the Helium Console
 - a. Create then apply a decoder function to the device so you can read/decode the data from the device
 - i. Use a label called RBS305 to apply the decoder to the device
- 2. In Pipedream, create a pipedream endpoint (via a new Pipedream Workflow)
 - a. Go to the Workflow tab in Pipedream
 - b. Create a new workflow and set "HTTP/Webhook" as the trigger
 - i. Name = RBS305-ATH-US to Google Sheet
- 3. Create an HTTP Integration in the Helium Console
 - a. Integration Name = pipedreamint_RBS305
 - b. Use the URL from the pipedream endpoint in the previous step
 - c. Use the RBS305 label to connect the integration to the RBS305-ATH-US device and its decoder function
- 4. Verify that Data is flowing from the RBS305-ATH-US > Helium Console/Network > Pipedream workflow
- 5. Create a Google Sheet
 - a. Make 1 column for each sensor payload data element you see (or are interested in) when looking at the device in the Helium Console with debug turned on
- 6. Complete the development of the Pipedream workflow
 - a. Make the connection to your Google Sheet
 - b. Drop the data received from the trigger step into a step that connects to your Google Sheet
- 7. (optional) Do some data manipulation of the sensor data in the Pipedream workflow to make it read better in the Google sheet, e.g. the sensor is sending the timestamp in Unix
- 8. (optional) Enjoy the sensor data flowing into your Google Sheet. Share the Sheet with a friend.

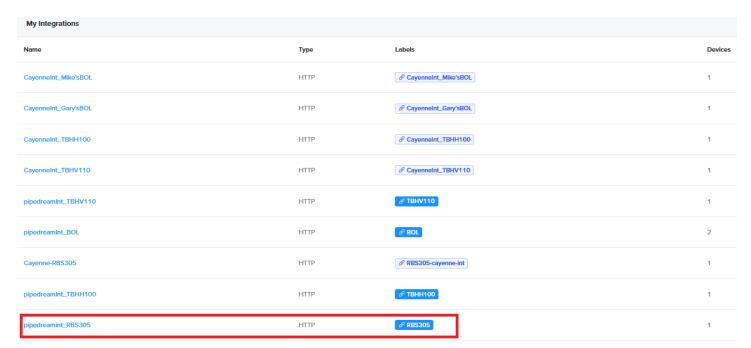
The next few pages contain screenshots of some of the steps above.



(above) RBS305-ATH-US Sensor set up in the Helium Console with integrations for Cayenne and Pipedream

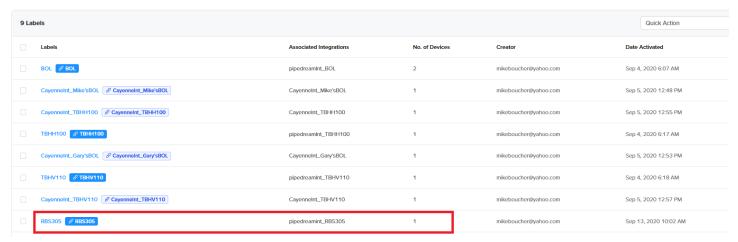


(above) Functions tab of Helium Console – showing the custom decoder created for the RBS305-ATH-US device, attached to the device with the RBS305 label

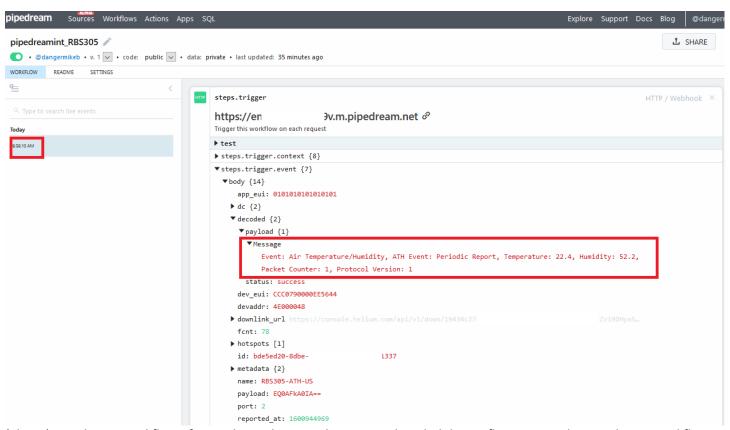


(above) Integrations tab of Helium Console – showing the custom HTTP integration created for the RBS305-ATH-US device, attached with the RBS305 label

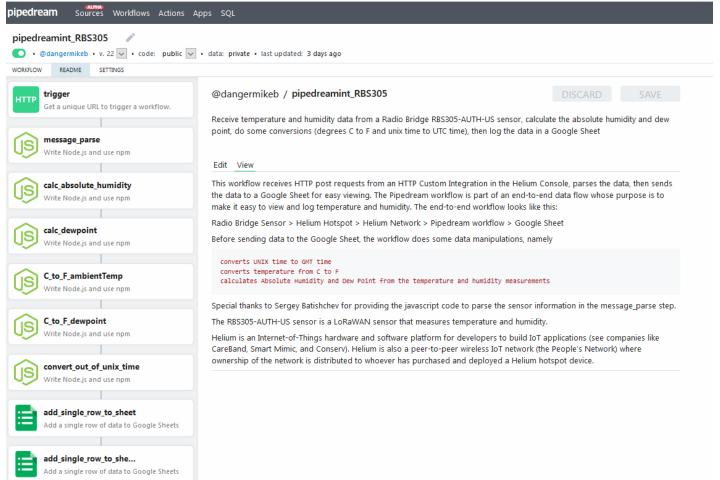




(above) Labels tab of Helium Console – showing the label, RBS305, associated to the pipedreamint_RBS305 integration

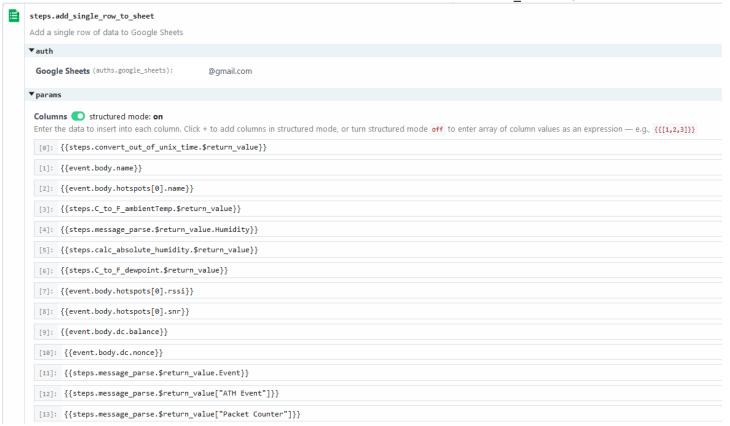


(above) Pipedream workflow after High Level Step 4 above – i.e. decoded data is flowing into the Pipedream workflow. Message ATH Event type = Periodic Report. Notice that the payload is 1 long message String. It's not easy to extract the individual data elements from this format, so we'll use a subsequent step to convert the string into an array.

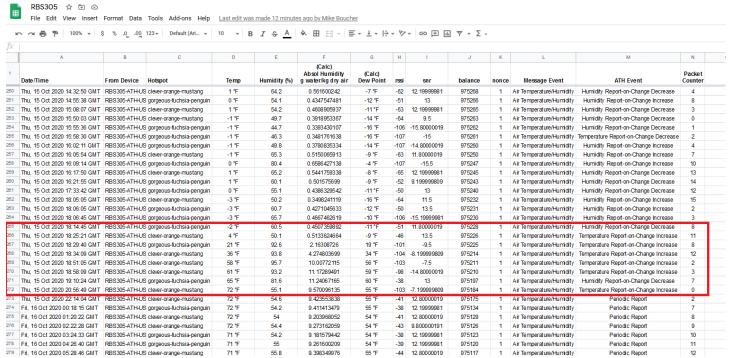


(above) Pipedream workflow after high level step 7 – showing all the steps in the workflow. A brief explanation of each step is provided below:

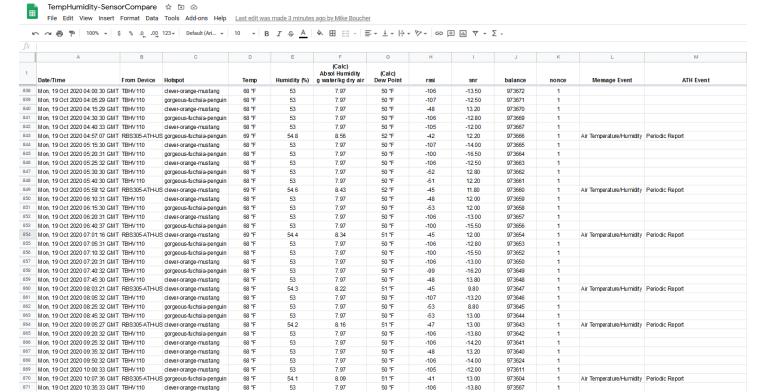
- trigger receives the message from the Helium network
- message_parse converts the sensor payload information from 1 long string into an array for easy access to each informational element. Special thanks to Sergey Batishchev for providing the JavaScript code.
- Calc_absolute_humidity calculates the absolute humidity from sensor temperature and relative humidity values
- Calc_dewpoint calculates the dew point from the sensor's temperature and relative humidity values
- C to F ambientTemp converts the sensor's temperature value from Celsius to Fahrenheit
- C to F dewpoint converts the dew point calculation from Celsius to Fahrenheit
- Convert_out_of_unix_time converts the sensor time stamp value from a Unix value to a GMT value
- Add_single_row_to_sheet pushes data to my Radio Bridge Google Sheet
- Add_single_row_to_sheet-SensorCompare pushes data to a different Google Sheet called TempHumidity-SensorCompare, which is also receiving data from TBHV110 sensor



(above) Pipedream workflow step used to drop the data into a row in the Google Sheet. The step, message_parse, was where the data received in the trigger step was converted from a single String into an array.



(above) Screenshot of the RBS305 Google Sheet receiving data from the Pipedream workflow. In rows 250-261, the sensor was in a freezer. The rows highlighted in red show how the sensor behaved when the sensor was removed from the freezer and placed in the living room.



(above) Screenshot of the Google Sheet used to capture data from the RBS305-ATH-US and TBHV110 sensors. The purpose of this sheet is to compare sensor performance.

Appendix A – RBS305-ATH-US Decoder Function

Radio Bridge provides a generic decoder function (i.e. a decoder that supports multiple sensors) at the following GitHub repository: https://github.com/RadioBridge/Packet-Decoder/blob/master/radio bridge packet decoder.js

That is what I am using – with the addition of a try/catch structure inside the Decoder function.

Below is a copy-n-paste of the contents of the Script I am using. Note that I chose **not** to try to remove the portions of the function that were for different sensors. I chose this approach simply because I didn't want to fix something that was already working.

```
// RADIO BRIDGE PACKET DECODER v1.0
// (c) 2019 RadioBridge USA by John Sheldon
// General defines used in decode
var RESET_EVENT = "00";
var SUPERVISORY EVENT = "01";
var TAMPER EVENT = "02";
var LINK QUALITY EVENT = "FB";
var RATE_LIMIT_EXCEEDED_EVENT = "FC";
var TEST_MESSAGE_EVENT = "FD";
var DOWNLINK ACK EVENT = "FF";
var DOOR_WINDOW_EVENT = "03";
var PUSH BUTTON EVENT = "06";
var CONTACT EVENT = "07";
var WATER_EVENT = "08";
var TEMPERATURE_EVENT = "09";
var TILT EVENT = "OA";
var ATH_EVENT = "0D";
var ABM EVENT = "OE";
var TILT HP EVENT = "OF";
var ULTRASONIC_EVENT = "10";
var SENSOR420MA_EVENT = "11";
var THERMOCOUPLE EVENT = "13";
var VOLTMETER_EVENT = "14";
var CUSTOM SENSOR EVENT = "15";
var GPS EVENT = "16":
var HONEYWELL5800_EVENT = "17";
var MAGNETOMETER EVENT = "18";
var VIBRATION_LB_EVENT = "19";
var VIBRATION HB_EVENT = "1A";
// Different network servers have different callback functions
// Each of these is mapped to the generic decoder function
// function called by ChirpStack
function Decode(fPort, bytes, variables) {
  return Generic Decoder(bytes, fPort);
// function called by TTN
function Decoder(bytes, port) {
// try out tray-catch structure
return Generic_Decoder(bytes, port);
```

```
Version 1.0
catch(e){
Decoder.err = e.message;
// The generic decode function called by one of the above network server specific callbacks
function Generic_Decoder(bytes, port) {
  // data structure which contains decoded messages
  var decoded = {};
  // The first byte contains the protocol version (upper nibble) and packet counter (lower nibble)
  ProtocolVersion = (bytes[0] >> 4) & 0x0f;
  PacketCounter = bytes[0] & 0x0f;
  // the event type is defined in the second byte
  EventType = Hex(bytes[1]);
  // the rest of the message decode is dependent on the type of event
  switch (EventType) {
    case RESET_EVENT:
      decoded.Message = "Event: Reset";
      // third byte is device type, convert to hex format for case statement
      DeviceTypeByte = Hex(bytes[2]);
      // device types are enumerated below
      switch (DeviceTypeByte) {
        case "01": DeviceType = "Door/Window Sensor"; break;
        case "02": DeviceType = "Door/Window High Security"; break;
        case "03": DeviceType = "Contact Sensor"; break;
        case "04": DeviceType = "No-Probe Temperature Sensor"; break;
        case "05": DeviceType = "External-Probe Temperature Sensor"; break;
        case "06": DeviceType = "Single Push Button"; break;
        case "07": DeviceType = "Dual Push Button"; break;
        case "08": DeviceType = "Acceleration-Based Movement Sensor"; break;
        case "09": DeviceType = "Tilt Sensor"; break;
        case "OA": DeviceType = "Water Sensor"; break;
        case "OB": DeviceType = "Tank Level Float Sensor"; break;
        case "OC": DeviceType = "Glass Break Sensor"; break;
        case "OD": DeviceType = "Ambient Light Sensor"; break;
        case "OE": DeviceType = "Air Temperature and Humidity Sensor"; break;
        case "OF": DeviceType = "High-Precision Tilt Sensor"; break;
        case "10": DeviceType = "Ultrasonic Level Sensor"; break;
        case "11": DeviceType = "4-20mA Current Loop Sensor"; break;
        case "12": DeviceType = "Ext-Probe Air Temp and Humidity Sensor"; break;
        case "13": DeviceType = "Thermocouple Temperature Sensor"; break;
        case "14": DeviceType = "Voltage Sensor"; break;
        case "15": DeviceType = "Custom Sensor"; break;
        case "16": DeviceType = "GPS"; break;
        case "17": DeviceType = "Honeywell 5800 Bridge"; break;
        case "18": DeviceType = "Magnetometer"; break;
        case "19": DeviceType = "Vibration Sensor - Low Frequency"; break;
```

```
case "1A": DeviceType = "Vibration Sensor - High Frequency"; break;
    default: DeviceType = "Device Undefined"; break;
  decoded.Message += ", Device Type: " + DeviceType;
  // the hardware version has the major version in the upper nibble, and the minor version in the lower nibble
  HardwareVersion = ((bytes[3] >> 4) \& 0x0f) + "." + (bytes[3] & 0x0f);
  decoded.Message += ", Hardware Version: v" + HardwareVersion;
  // the firmware version has two different formats depending on the most significant bit
  FirmwareFormat = (bytes[4] >> 7) & 0x01;
  // FirmwareFormat of 0 is old format, 1 is new format
  // old format is has two sections x.y
  // new format has three sections x.y.z
  if (FirmwareFormat == 0)
    FirmwareVerison = bytes[4] + "." + bytes[5];
    Firmware Verison = ((bytes[4] >> 2) \& 0x1F) + "." + ((bytes[4] \& 0x03) + ((bytes[5] >> 5) \& 0x07)) + "." + (bytes[5] \& 0x1F);
  decoded.Message += ", Firmware Version: v" + FirmwareVerison;
  break;
//========= SUPERVISORY EVENT ===========
case SUPERVISORY_EVENT:
  decoded.Message = "Event: Supervisory";
  // note that the sensor state in the supervisory message is being depreciated, so those are not decoded here
  // battery voltage is in the format x.y volts where x is upper nibble and y is lower nibble
  BatteryLevel = ((bytes[4] >> 4) & 0x0f) + "." + (bytes[4] & 0x0f);
  decoded.Message += ", Battery Voltage: " + BatteryLevel + "V";
  // the accumulation count is a 16-bit value
  AccumulationCount = (bytes[9] * 256) + bytes[10];
  decoded.Message += ", Accumulation Count: " + AccumulationCount;
  // decode bits for error code byte
  TamperSinceLastReset = (bytes[2] >> 4) & 0x01;
  decoded.Message += ", Tamper Since Last Reset: " + TamperSinceLastReset;
  CurrentTamperState = (bytes[2] >> 3) & 0x01;
  decoded.Message += ", Current Tamper State: " + CurrentTamperState;
  ErrorWithLastDownlink = (bytes[2] >> 2) & 0x01;
  decoded.Message += ", Error With Last Downlink: " + ErrorWithLastDownlink;
  BatteryLow = (bytes[2] >> 1) & 0x01;
  decoded.Message += ", Battery Low: " + BatteryLow;
  RadioCommError = bytes[2] & 0x01;
  decoded.Message += ", Radio Comm Error: " + RadioCommError;
  break;
```

```
//========= TAMPER EVENT ==========
case TAMPER EVENT:
 decoded.Message = "Event: Tamper";
 TamperState = bytes[2];
 // tamper state is 0 for open, 1 for closed
 if (TamperState == 0)
   decoded.Message += ", State: Open";
 else
   decoded.Message += ", State: Closed";
 break;
//=========== LINK QUALITY EVENT ===========
case LINK_QUALITY_EVENT:
 decoded.Message = "Event: Link Quality";
 CurrentSubBand = bytes[2];
 decoded.Message += ", Current Sub-Band: " + CurrentSubBand;
 RSSILastDownlink = bytes[3];
 decoded.Message += ", RSSI of Last Downlink: " + RSSILastDownlink;
 SNRLastDownlink = bytes[4];
 decoded.Message += ", SNR of Last Downlink: " + SNRLastDownlink;
 break;
case RATE_LIMIT_EXCEEDED_EVENT:
 // this feature is depreciated so it is not decoded here
 decoded.Message = "Event: Rate Limit Exceeded. Depreciated Event And Not Decoded Here";
 break;
//====== TEST MESSAGE EVENT ==========
case TEST_MESSAGE_EVENT:
 // this feature is depreciated so it is not decoded here
 decoded.Message = "Event: Test Message. Depreciated Event And Not Decoded Here";
 break;
//======== DOOR/WINDOW EVENT =============
case DOOR_WINDOW_EVENT:
 decoded.Message = "Event: Door/Window";
 SensorState = bytes[2];
 // 0 is closed, 1 is open
 if (SensorState == 0)
   decoded.Message += ", State: Closed";
   decoded.Message += ", State: Open";
 break;
```

```
//======= PUSH BUTTON EVENT =========
case PUSH_BUTTON_EVENT:
 decoded.Message = "Event: Push Button";
 ButtonID = Hex(bytes[2]);
 switch (ButtonID) {
   // 01 and 02 used on two button
   case "01": ButtonReference = "Button 1"; break;
   case "02": ButtonReference = "Button 2"; break;
   // 03 is single button
   case "03": ButtonReference = "Button 1"; break;
   // 12 when both buttons pressed on two button
   case "12": ButtonReference = "Both Buttons"; break;
   default: ButtonReference = "Undefined"; break;
 decoded.Message += ", Button ID: " + ButtonReference;
 ButtonState = bytes[3];
 switch (ButtonState) {
   case 0: SensorStateDescription = "Pressed"; break;
   case 1: SensorStateDescription = "Released"; break;
   case 2: SensorStateDescription = "Held"; break;
   default: SensorStateDescription = "Undefined"; break;
 decoded.Message += ", Button State: " + SensorStateDescription;
case CONTACT_EVENT:
 decoded.Message = "Event: Dry Contact";
 ContactState = bytes[2];
 // if state byte is 0 then shorted, if 1 then opened
 if (ContactState == 0)
   SensorState = "Contacts Shorted";
   SensorState = "Contacts Opened";
 decoded.Message += ", Sensor State: " + SensorState;
 break;
case WATER_EVENT:
 decoded.Message = "Event: Water";
 SensorState = bytes[2];
 if (SensorState == 0)
    decoded.Message += ", State: Water Present";
 else
    decoded.Message += ", State: Water Not Present";
```

```
WaterRelativeResistance = bytes[3];
 decoded.Message += ", Relative Resistance: " + WaterRelativeResistance;
 break;
case TEMPERATURE EVENT:
 decoded.Message = "Event: Temperature";
 TemperatureEvent = bytes[2];
 switch (TemperatureEvent) {
   case 0: TemperatureEventDescription = "Periodic Report"; break;
   case 1: TemperatureEventDescription = "Temperature Over Upper Threshold"; break;
   case 2: TemperatureEventDescription = "Temperature Under Lower Threshold"; break;
   case 3: TemperatureEventDescription = "Temperature Report-on-Change Increase"; break;
   case 4: TemperatureEventDescription = "Temperature Report-on-Change Decrease"; break;
   default: TemperatureEventDescription = "Undefined"; break;
 decoded.Message += ", Temperature Event: " + TemperatureEventDescription;
 // current temperature reading
 CurrentTemperature = Convert(bytes[3], 0);
 decoded.Message += ", Current Temperature: " + CurrentTemperature;
 // relative temp measurement for use with an alternative calibration table
 RelativeMeasurement = Convert(bytes[4], 0);
 decoded.Message += ", Relative Measurement: " + RelativeMeasurement;
 break;
case TILT_EVENT:
 decoded.Message = "Event: Tilt";
 TiltEvent = bytes[2];
 switch (TiltEvent) {
   case 0: TiltEventDescription = "Transitioned to Vertical"; break;
   case 1: TiltEventDescription = "Transitioned to Horizontal"; break;
   case 2: TiltEventDescription = "Report-on-Change Toward Vertical"; break;
   case 3: TiltEventDescription = "Report-on-Change Toward Horizontal"; break;
   default: TiltEventDescription = "Undefined"; break;
 decoded.Message += ", Tilt Event: " + TiltEventDescription;
 TiltAngle = bytes[3];
 decoded.Message += ", Tilt Angle: " + TiltAngle;
 break;
case ATH_EVENT:
```

```
decoded.Message = "Event: Air Temperature/Humidity";
 ATHEvent = bytes[2];
 switch (ATHEvent) {
    case 0: ATHDescription = "Periodic Report"; break;
    case 1: ATHDescription = "Temperature has Risen Above Upper Threshold"; break;
    case 2: ATHDescription = "Temperature has Fallen Below Lower Threshold"; break;
    case 3: ATHDescription = "Temperature Report-on-Change Increase"; break;
    case 4: ATHDescription = "Temperature Report-on-Change Decrease"; break;
    case 5: ATHDescription = "Humidity has Risen Above Upper Threshold"; break;
    case 6: ATHDescription = "Humidity has Fallen Below Lower Threshold"; break;
    case 7: ATHDescription = "Humidity Report-on-Change Increase"; break;
    case 8: ATHDescription = "Humidity Report-on-Change Decrease"; break;
    default: ATHDescription = "Undefined"; break;
 decoded.Message += ", ATH Event: " + ATHDescription;
 // integer and fractional values between two bytes
 Temperature = Convert((bytes[3]) + ((bytes[4] >> 4) / 10), 1);
 decoded.Message += ", Temperature: " + Temperature;
 // integer and fractional values between two bytes
 Humidity = +(bytes[5] + ((bytes[6] >> 4) / 10)).toFixed(1);
 decoded.Message += ", Humidity: " + Humidity;
 break;
// ====== ACCELERATION MOVEMENT EVENT ========
case ABM_EVENT:
 decoded.Message = "Event: Acceleration-Based Movement";
 ABMEvent = bytes[2];
 if (ABMEvent == 0)
    ABMEventDescription = "Movement Started";
    ABMEventDescription = "Movement Stopped";
 decoded.Message += ", ABM Event: " + ABMEventDescription;
 break;
//====== HIGH-PRECISION TILT EVENT =========
case TILT_HP_EVENT:
 decoded.Message = "Event: High-Precision Tilt";
 TiltEvent = bytes[2];
 switch (TiltEvent) {
    case 0: TiltEventDescription = "Periodic Report"; break;
    case 1: TiltEventDescription = "Transitioned Toward O-Degree Vertical Orientation"; break;
    case 2: TiltEventDescription = "Transitioned Away From 0-Degree Vertical Orientation"; break;
    case 3: TiltEventDescription = "Report-on-Change Toward 0-Degree Vertical Orientation"; break;
    case 4: TiltEventDescription = "Report-on-Change Away From 0-Degree Vertical Orientation"; break;
    default: TiltEventDescription = "Undefined"; break;
```

```
decoded.Message += ", Tilt HP Event: " + TiltEventDescription;
 // integer and fractional values between two bytes
 Angle = +(bytes[3] + (bytes[4] / 10)).toFixed(1);
 decoded.Message = ", Angle: " + Angle;
 Temperature = Convert(bytes[5], 0);
 decoded.Message = ", Temperature: " + Temperature;
 break;
case ULTRASONIC_EVENT:
 decoded.Message = "Event: Ultrasonic Level";
 UltrasonicEvent = bytes[2];
 switch (UltrasonicEvent) {
   case 0: UltrasonicEventDescription = "Periodic Report"; break;
   case 1: UltrasonicEventDescription = "Distance has Risen Above Upper Threshold"; break;
   case 2: UltrasonicEventDescription = "Distance has Fallen Below Lower Threshold"; break;
   case 3: UltrasonicEventDescription = "Report-on-Change Increase"; break;
   case 4: UltrasonicEventDescription = "Report-on-Change Decrease"; break;
   default: UltrasonicEventDescription = "Undefined"; break;
 decoded.Message += ", Ultrasonic Event: " + UltrasonicEventDescription;
 // distance is calculated across 16-bits
 Distance = ((bytes[3] * 256) + bytes[4]);
 decoded.Message += ", Distance: " + Distance;
 break;
case SENSOR420MA_EVENT:
 decoded.Message = "Event: 4-20mA";
 Sensor420mAEvent = bytes[2];
 switch (Sensor420mAEvent) {
   case 0: Sensor420mAEventDescription = "Periodic Report"; break;
   case 1: Sensor420mAEventDescription = "Analog Value has Risen Above Upper Threshold"; break;
   case 2: Sensor420mAEventDescription = "Analog Value has Fallen Below Lower Threshold"; break;
   case 3: Sensor420mAEventDescription = "Report on Change Increase"; break;
   case 4: Sensor420mAEventDescription = "Report on Change Decrease"; break;
    default: Sensor420mAEventDescription = "Undefined"; break;
 decoded.Message += ", 4-20mA Event: " + Sensor420mAEventDescription;
 // calculatec across 16-bits, convert from units of 10uA to mA
 Analog420 Measurement = ((bytes[3] * 256) + bytes[4]) / 100;
 decoded.Message += ", Current Measurement in mA: " + Analog420Measurement;
 break;
// ========== THERMOCOUPLE EVENT ===========
```

Version 1.0

```
case THERMOCOUPLE_EVENT:
  decoded.Message = "Event: Thermocouple";
  ThermocoupleEvent = bytes[2];
  switch (ThermocoupleEvent) {
    case 0: ThermocoupleEventDescription = "Periodic Report"; break;
    case 1: ThermocoupleEventDescription = "Analog Value has Risen Above Upper Threshold"; break;
    case 2: ThermocoupleEventDescription = "Analog Value has Fallen Below Lower Threshold"; break;
    case 3: ThermocoupleEventDescription = "Report on Change Increase"; break;
    case 4: ThermocoupleEventDescription = "Report on Change Decrease"; break;
    default: ThermocoupleEventDescription = "Undefined"; break;
  decoded.Message += ", Thermocouple Event: " + ThermocoupleEventDescription;
  // decode is across 16-bits
  Temperature = parseInt(((bytes[3] * 256) + bytes[4]) / 16);
  decoded.Message += ", Temperature: " + Temperature + "°C";
  Faults = bytes[5];
  // decode each bit in the fault byte
  FaultColdOutsideRange = (Faults >> 7) & 0x01;
  FaultHotOutsideRange = (Faults >> 6) & 0x01;
  FaultColdAboveThresh = (Faults >> 5) & 0x01;
  FaultColdBelowThresh = (Faults >> 4) & 0x01;
  FaultTCTooHigh = (Faults >> 3) & 0x01;
  FaultTCTooLow = (Faults >> 2) & 0x01;
  FaultVoltageOutsideRange = (Faults >> 1) & 0x01;
  FaultOpenCircuit = Faults & 0x01;
  // Decode faults
  if (Faults == 0)
    decoded.Message += ", Fault: None";
  else {
    if (FaultColdOutsideRange)
      decoded.Message += ", Fault: The cold-Junction temperature is outside of the normal operating range";
    if (FaultHotOutsideRange)
      decoded.Message += ", Fault: The hot junction temperature is outside of the normal operating range";
    if (FaultColdAboveThresh)
      decoded.Message += ", Fault: The cold-Junction temperature is at or above than the cold-junction temperature high threshold";
    if (FaultColdBelowThresh)
      decoded. Message += ", Fault: The Cold-Junction temperature is lower than the cold-junction temperature low threshold";
    if (FaultTCTooHigh)
      decoded.Message += ", Fault: The thermocouple temperature is too high";
    if (FaultTCTooLow)
      decoded.Message += ", Fault: Thermocouple temperature is too low";
    if (FaultVoltageOutsideRange)
      decoded.Message += ", Fault: The input voltage is negative or greater than VDD";
    if (FaultOpenCircuit)
       decoded.Message += ", Fault: An open circuit such as broken thermocouple wires has been detected";
```

```
Version 1.0
     break;
    case VOLTMETER_EVENT:
     decoded.Message = "Event: Voltage Sensor";
     VoltmeterEvent = bytes[2];
     switch (VoltmeterEvent) {
       case 0: VoltmeterEventDescription = "Periodic Report"; break;
       case 1: VoltmeterEventDescription = "Voltage has Risen Above Upper Threshold"; break;
       case 2: VoltmeterEventDescription = "Voltage has Fallen Below Lower Threshold"; break;
       case 3: VoltmeterEventDescription = "Report on Change Increase"; break;
       case 4: VoltmeterEventDescription = "Report on Change Decrease"; break;
       default: VoltmeterEventDescription = "Undefined";
     decoded.Message += ", Voltage Sensor Event: " + VoltmeterEventDescription;
     // voltage is measured across 16-bits, convert from units of 10mV to V
     VoltageMeasurement = ((bytes[3] * 256) + bytes[4]) / 100;
     decoded.Message += ", Voltage: " + VoltageMeasurement + "V";
     break;
    case CUSTOM_SENSOR_EVENT:
     decoded.Message = "Event: Custom Sensor";
     // Custom sensors are not decoded here
     break;
   //======= VOLTMETER ANALOG EVENT ==========
    case GPS_EVENT:
     decoded.Message = "Event: GPS";
     GPSStatus = bytes[2];
     // decode status byte
     GPSValidFix = GPSStatus & 0x01;
     if (GPSValidFix == 0)
       GPSValidFixDescription = ", No Valid Fix";
     else
       GPSValidFixDescription = ", Valid Fix";
     decoded.Message += ", GPS Status: " + GPSValidFixDescription;
     // latitude and longitude calculated across 32 bits each, show 12 decimal places
     Latitude = toFixed((((bytes[3] * (2 ^ 24)) + (bytes[4] * (2 ^ 16)) + (bytes[5] * (2 ^ 8)) + bytes[6]) / (10 ^ 7)), 12);
     Latitude = toFixed((((bytes[7] * (2 ^ 24)) + (bytes[8] * (2 ^ 16)) + (bytes[9] * (2 ^ 8)) + bytes[10]) / (10 ^ 7)), 12);
```

```
decoded.Message += ", Latitude: " + Latitude + ", Longitude: " + Longitude;
  break;
case HONEYWELL5800_EVENT:
  decoded.Message = "Event: Honeywell 5800 Sensor Message";
  // honeywell sensor ID, 24-bits
  HWSensorID = (bytes[2] * (2 ^ 16)) + (bytes[3] * (2 ^ 8)) + bytes[4];
  decoded.Message += ", Honeywell Sensor ID: " + HWSensorID;
  HWEvent = bytes[5];
  switch (HWEvent) {
    case 0: HWEventDescription = "Status code"; break;
    case 1: HWEventDescription = "Error Code"; break;
    case 2: HWEventDescription = "Sensor Data Payload"; break;
    default: HWEventDescription = "Undefined"; break;
  decoded.Message += ", Honeywell Sensor Event: " + HWEventDescription;
  // represent the honeywell sensor payload in hex
  HWSensorPayload = Hex((bytes[6] * 256) + bytes[7]);
  decoded.Message += ", Sensor Payload: 0x" + HWSensorPayload;
  break;
//====== MAGNETOMETER EVENT =========
case MAGNETOMETER_EVENT:
  // TBD
  break;
//======== VIBRATION LOW BANDWIDTH EVENT ==========
case VIBRATION_LB_EVENT:
  decoded.Message = "Event: Vibration Low-Bandwidth";
  VibeEvent = bytes[2];
  switch (VibeEvent) {
    case 0: VibeEventDescription = "Low Frequency Periodic Report"; break;
    case 4: VibeEventDescription = "Low Frequency X-Axis Has Risen Above Upper Threshold"; break;
    case 5: VibeEventDescription = "Low Frequency X-Axis Has Fallen Below Lower Threshold"; break;
    case 6: VibeEventDescription = "Low Frequency Y-Axis Has Risen Above Upper Threshold"; break;
    case 7: VibeEventDescription = "Low Frequency Y-Axis Has Fallen Below Lower Threshold"; break;
    case 8: VibeEventDescription = "Low Frequency Z-Axis Has Risen Above Upper Threshold"; break;
    case 9: VibeEventDescription = "Low Frequency Z-Axis Has Fallen Below Lower Threshold"; break;
    case 11: VibeEventDescription = "Low Frequency Exceeded G-Force Range"; break;
    default: VibeEventDescription = "Undefined"; break;
```

```
decoded.Message += ", Vibration Event: " + VibeEventDescription;
 // X, Y, and Z velocities are 16-bits
 XVelocity = (bytes[3] * 256) + bytes[4];
 YVelocity = (bytes[5] * 256) + bytes[6];
 ZVelocity = (bytes[7] * 256) + bytes[8];
 decoded.Message += ", X-Axis Velocity: " + XVelocity + " inches/second";
 decoded.Message += ", Y-Axis Velocity: " + YVelocity + " inches/second";
 decoded.Message += ", Z-Axis Velocity: " + ZVelocity + " inches/second";
 // capture sign of temp
 VibeTemp = parseInt(bytes[9]);
 decoded.Message = ", Internal Temperature: " + VibeTemp + "°C";
 break;
// ========= VIBRATION HIGH BANDWIDTH EVENT ============
case VIBRATION_HB_EVENT:
 decoded.Message = "Event: Vibration Low-Bandwidth";
 VibeEvent = bytes[2];
 switch (VibeEvent) {
    case 1: VibeEventDescription = "High Frequency Periodic Report"; break;
    case 2: VibeEventDescription = "High Frequency Vibration Above Upper Threshold"; break;
    case 3: VibeEventDescription = "High Frequency Vibration Below Lower Threshold"; break;
    case 10: VibeEventDescription = "High Frequency Exceeded G-Force Range"; break;
    default: VibeEventDescription = "Undefined"; break;
 decoded.Message += ", Vibration Event: " + VibeEventDescription;
 // peak g-force
 PeakGForce = (bytes[3] * 256) + bytes[4];
 decoded.Message += ", Peak G-Force: " + PeakGForce;
 // capture sign of temp
 VibeTemp = parseInt(bytes[5]);
 decoded.Message = ", Internal Temperature: " + VibeTemp + "°C";
 break;
case DOWNLINK_ACK_EVENT:
 decoded.Message = "Event: Downlink Acknowledge";
 DownlinkEvent = bytes[2];
 if (DownlinkEvent == 1)
    DownlinkEventDescription = "Message Invalid";
 else
    DownlinkEventDescription = "Message Valid";
 decoded.Message += ", Downlink: " + DownlinkEventDescription;
```

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break;
                  // end of EventType Case
         // add packet counter and protocol version to the end of the decode
         decoded.Message += ", Packet Counter: " + PacketCounter;
         decoded.Message += ", Protocol Version: " + ProtocolVersion;
         return decoded;
function Hex(decimal) {
         decimal = ('0' + decimal.toString(16).toUpperCase()).slice(-2);
         return decimal;
function Convert(number, mode) {
         switch (mode) {
                  // for EXT-TEMP and NOP
                  case 0: if (number > 127) { result = number - 256 } else { result = number }; break
                  //for ATH temp
                  case \ 1: if (number > 127) \ \{ \ result = -+(number - 128). \\ to Fixed (1) \ \} \ else \ \{ \ result = +number. \\ to Fixed (1) \ \}; \ break \ for the property of the propert
         return result;
```