# Renormalization of Soft Symmetry Improved 2PIEA gap equations in the Hartree-Fock approximation

Supplement to thesis Chapter 5 "Soft Symmetry Improvement"

Mathematica notebook to compute couter-terms for the Hartree-Fock truncation of the SSI-2PIEA

Author: Michael Brown

## Hartree-Fock

ClearAll[qeom, neom, intrules, msbarrules, mq2soln, cteq, cts,  $\delta m$ ,  $\delta \lambda$ ];

#### Hartree-Fock gap equations with counterterms

Goldstone equation of motion. Quantities in reference to the paper are:

p is the four-momentum flowing through the propagators  $\Delta_G^{-1}$  and  $\Delta_N^{-1}$ ,

mg2 is the Goldstone mass squared  $m_G^2$ ,

mn2 is the Higgs mass squared  $m_H^2$ ,

Z and  $Z\Delta$  are the wavefunction a propagator renormalization constants,

 $m^2$  is the (renormalized) Lagrangian mass parameter,  $\delta m_0^2$ ,  $\delta m_1^2$  are its counter-terms,

 $\lambda$  is the (renormalized) four point coupling,

 $\delta\lambda_0$ ,  $\delta\lambda_{1a}$ ,  $\delta\lambda_{1b}$ ,  $\delta\lambda_{2a}$ ,  $\delta\lambda_{2b}$  are the independent coupling counter-terms,

v is the scalar field vacuum expectation value,

ħ is the reduced Planck constant,

n is the number of fields in the O(n) symmetry group,

 $\xi$  is the stiffness parameter,

 $\epsilon$  is the solution of the Goldstone zero mode equation,

ssi =  $\frac{1}{VBm_c^2} \left(\frac{1}{\epsilon} - 1\right)$  is the soft symmetry improvement term in the propagator eoms,

ssi2 =  $\frac{1}{\xi}$  (n-1) 2  $(m_G^2 \epsilon)^2$  is the other soft symmetry improvement term in the vev eom,

t∞g, t∞n are the divergent tadpole integrals for the Goldstone, Higgs resp.,

tfing, tfinn are the finite parts of the tadpoles for the Goldstone, Higgs resp.

Vev equation of motion

$$\begin{aligned} \mathbf{veom} &= \mathbf{Z}\Delta^{-1} \, \left(\mathbf{m}^2 + \delta \mathbf{m_0}^2\right) \, \mathbf{v} + \frac{\lambda + \delta \lambda_0}{6} \, \mathbf{v}^3 + \frac{\hbar}{6} \, \mathbf{Z}\Delta \, \left(\mathbf{n} - 1\right) \, \left(\lambda + \delta \lambda_{1\,a}\right) \, \mathbf{v} \, \left(\mathsf{t} \infty \mathbf{g} + \mathsf{tfing} + \mathsf{ssi}\right) \, + \\ & \frac{\hbar}{6} \, \mathbf{Z}\Delta \, \left(3 \, \lambda + \delta \lambda_{1\,a} + 2 \, \delta \lambda_{1\,b}\right) \, \mathbf{v} \, \left(\mathsf{t} \infty \mathbf{n} + \mathsf{tfinn}\right) + \mathbf{v} \, \mathsf{ssi2} \end{aligned}$$

Goldstone equation of motion

$$\begin{aligned} \text{geom} &= p^2 - mg2 = Z \ Z\Delta \ p^2 - m^2 - \delta m_1^2 - Z\Delta \ \frac{\lambda + \delta \lambda_{1 \ a}}{6} \ v^2 - \\ &\frac{\hbar}{6} \left( \left( n + 1 \right) \lambda + \left( n - 1 \right) \delta \lambda_{2 \ a} + 2 \ \delta \lambda_{2 \ b} \right) \ Z\Delta^2 \ \left( \text{t} \infty \text{g} + \text{tfing} + \text{ssi} \right) - \frac{\hbar}{6} \ \left( \lambda + \delta \lambda_{2 \ a} \right) \ Z\Delta^2 \ \left( \text{t} \infty \text{n} + \text{tfinn} \right) \end{aligned}$$

Higgs equation of motion

$$\begin{aligned} \text{neom} &= p^2 - \text{mn2} = \text{Z} \; \text{Z}\Delta \; p^2 - \text{m}^2 - \delta \text{m}_1{}^2 - \text{Z}\Delta \; \text{v}^2 \; \frac{\left(3\;\lambda + \delta\lambda_{1\,a} + 2\;\delta\lambda_{1\,b}\right)}{6} \; - \\ & \frac{\hbar}{6} \; \left(\lambda + \delta\lambda_{2\,a}\right) \; \left(\text{n} - 1\right) \; \text{Z}\Delta^2 \; \left(\text{t}\infty \text{g} + \text{tfing} + \text{ssi}\right) - \frac{\hbar}{6} \; \left(3\;\lambda + \delta\lambda_{2\,a} + 2\;\delta\lambda_{2\,b}\right) \; \text{Z}\Delta^2 \; \left(\text{t}\infty \text{n} + \text{tfinn}\right) \end{aligned}$$

#### Infinite parts of tadpoles in MSbar

MSbar rules for 4 - 2  $\epsilon$  dimensions

```
msbarrules = \{t \infty g \rightarrow \kappa mg2, t \infty n \rightarrow \kappa mn2\}
```

### Sub in tadpole expressions, eliminate mn2 and solve for mg2

```
mg2soln = mg2 / .
   (geom /. msbarrules /. Solve[neom /. msbarrules, mn2][[1]] // Solve[#, mg2][[1]] &)
mn2soln = mn2 /. (neom /. msbarrules /. mg2 \rightarrow mg2soln // Solve[#, mn2][[1]] &)
```

#### Gather divergences proportional v, tfing and tfinn and set independently to zero

First we subtract the finite equation of motion, then gather coefficients of the remainder into a list and set each to zero (after some trimming and simplifying).

cteq = 
$$\left( \left( \text{CoefficientList} \left[ \text{mg2soln} + \left( -\text{m}^2 - \frac{\lambda}{6} \, \text{v}^2 - \frac{\hbar}{6} \, \left( \left( \text{n} + 1 \right) \, \lambda \right) \, \left( \text{tfing} + \text{ssi} \right) - \frac{\hbar}{6} \, \left( \lambda \right) \, \left( \text{tfinn} \right) \right), \\ \left\{ \text{p, v, tfing, tfinn} \right\} \right] / / \, \text{Flatten} \right) / / \\ \text{DeleteDuplicates } / / \, \text{Simplify} / / \, \text{FullSimplify} \right) = 0 \, / / \, \text{Thread}$$

cteq2 =  $\left(\left(\text{CoefficientList}\left[\text{mn2soln} + \left(-\text{m}^2 - \frac{\lambda}{2}\,\text{v}^2 - \frac{\hbar}{6}\,\left(\left(\text{n} - 1\right)\,\lambda\right)\,\left(\text{tfing} + \text{ssi}\right) - \frac{\hbar}{2}\,\left(\lambda\right)\,\left(\text{tfinn}\right)\right)\right)\right)$ {p, v, tfing, tfinn}] // Flatten // DeleteDuplicates // Simplify // FullSimplify == 0 // Thread

#### Solve for counterterms

```
cteqs = {cteq, cteq2} // Flatten // FullSimplify // DeleteDuplicates
 cts = \{\delta m_1^2, \delta \lambda_{1a}, \delta \lambda_{2a}, \delta \lambda_{1b}, \delta \lambda_{2b}, Z, Z\Delta\} /. Solve[cteqs,
                                            \{\delta m_1, \delta \lambda_{1a}, \delta \lambda_{2a}, \delta \lambda_{1b}, \delta \lambda_{2b}, Z, Z\Delta\} \} // FullSimplify // DeleteDuplicates
Z\Delta is redundant in this truncation, can remove it :
 cts /. Z\Delta \rightarrow 1 // FullSimplify
\texttt{mg2soln} \; / \; . \; \texttt{Solve[cteqs, } \{ \delta \texttt{m}_{\texttt{l}} \; , \; \delta \lambda_{\texttt{la}} \; , \; \delta \lambda_{\texttt{la}} \; , \; \delta \lambda_{\texttt{lb}} \; , \; \texttt{Z} \; , \; \texttt{Z} \Delta \} \; ] \; / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{FullSimplify} \; / / \; . \; \texttt{FullSimplify} \; / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{FullSimplify} \; / / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{FullSimplify} \; / / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{FullSimplify} \; / / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{FullSimplify} \; / / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{FullSimplify} \; / / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{FullSimplify} \; / / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{FullSimplify} \; / / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{FullSimplify} \; / / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{FullSimplify} \; / / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{FullSimplify} \; / / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{FullSimplify} \; / / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{FullSimplify} \; / / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{FullSimplify} \; / / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{FullSimplify} \; / / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{FullSimplify} \; / / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{FullSimplify} \; / / \; . \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \texttt{Z} \Delta \; \rightarrow \; 1 \; / / \; \Delta \; \rightarrow \; 1 \; / / \; \Delta \; \rightarrow \; 1 \; / / \; \Delta \; \rightarrow \; 1 \; / / \; \Delta \; \rightarrow \; 1 \; / / \; \Delta \; \rightarrow \; 1 \;
        DeleteDuplicates
mn2 / . (neom / .msbarrules / .mg2 \rightarrow mg2soln / .
                                                                             Solve[cteqs, \{\delta m_1, \delta \lambda_{1a}, \delta \lambda_{2a}, \delta \lambda_{1b}, \delta \lambda_{2b}, Z, Z\Delta\}] /. Z\Delta \rightarrow 1 // FullSimplify //
                                                  DeleteDuplicates) // Solve[#, mn2] &) // FullSimplify
 rnveom =
        veom /. \left\{ mg2 \rightarrow m^2 + \frac{\lambda}{c} v^2 + \frac{\hbar}{c} \left( \left( n+1 \right) \lambda \right) \left( tfing + ssi \right) + \frac{\hbar}{c} \left( \lambda \right) \left( tfinn \right), mn2 \rightarrow m^2 + \frac{\lambda}{c} v^2 + \frac{
                                                           \frac{\hbar}{\epsilon} \left( \left( n-1 \right) \lambda \right) \left( \text{tfing} + \text{ssi} \right) + \frac{\hbar}{2} \left( \lambda \right) \left( \text{tfinn} \right) \right\} // \text{Simplify} // \text{DeleteDuplicates}
 cteqs3 =
           ssi2) /. msbarrules /. \{mg2 \rightarrow m^2 + \frac{\lambda}{c} v^2 +
                                                                                                                                                                                                                          \frac{\hbar}{\epsilon} \left( \left( n+1 \right) \lambda \right) \left( \text{tfing} + \text{ssi} \right) + \frac{\hbar}{\epsilon} \left( \lambda \right) \left( \text{tfinn} \right), \, \text{mn2} \rightarrow
                                                                                                                                                                                                               m^2 + \frac{\lambda}{2} v^2 + \frac{\hbar}{6} ((n-1) \lambda) (tfing + ssi) + \frac{\hbar}{6} (\lambda) (tfinn) \} //
                                                                                                                                                                                         Simplify // Expand // FullSimplify, {v, tfing, tfinn}] //
                                                                                                                                                       Simplify // Flatten // DeleteDuplicates // Simplify //
                                                                                                              FullSimplify // DeleteDuplicates = 0 // Thread /.
                                                           Solve[cteqs, \{\delta m_1, \delta \lambda_{1a}, \delta \lambda_{2a}, \delta \lambda_{1b}, \delta \lambda_{2b}, Z\}] // Simplify //
                                            FullSimplify // DeleteDuplicates [[1]]
   \left\{\delta m_0^2, \delta \lambda_0\right\} /. Solve[ctegs3, \left\{\delta m_0, \delta \lambda_0\right\}] /. Z\Delta \to 1 // DeleteDuplicates // Simplify
```

$$\begin{split} \left\{\delta m_1^2 &== \delta m_0^2, \; \delta \lambda_{1\, a} == \delta \lambda_{2\, a}, \; \delta \lambda_{1\, b} == \delta \lambda_{2\, b}\right\} \; / \; \\ & \quad \text{Solve}[\text{cteqs}, \; \left\{\delta m_1, \; \delta \lambda_{1\, a}, \; \delta \lambda_{2\, a}, \; \delta \lambda_{1\, b}, \; \delta \lambda_{2\, b}, \; Z, \; Z\Delta \right\}] \; / \; \\ & \quad \text{Solve}[\text{cteqs3}, \; \left\{\delta m_0, \; \delta \lambda_0\right\}] \; / \; \; Z\Delta \to 1 \; / / \; \text{FullSimplify} \end{split}$$
 
$$\left\{\delta \lambda_{1\, a} = \frac{\left(3 \; (n+4) + \left(n+2\right) \, \kappa \, \lambda \, \tilde{h}\right)}{\left(n+2\right) \, \kappa \, \lambda \, \tilde{h} + 6} \; \delta \lambda_{1\, b}\right\} \; / \; \\ & \quad \text{Solve}[\text{cteqs}, \; \left\{\delta m_1, \; \delta \lambda_{1\, a}, \; \delta \lambda_{2\, a}, \; \delta \lambda_{1\, b}, \; \delta \lambda_{2\, b}, \; Z, \; Z\Delta \right\}] \; / \; \\ & \quad \text{Solve}[\text{cteqs3}, \; \left\{\delta m_0, \; \delta \lambda_0\right\}] \; / \; \; Z\Delta \to 1 \; / / \; \text{FullSimplify} \end{split}$$
 
$$\left\{\delta \lambda_{1\, b} \; / \; \; \text{Solve}[\text{cteqs}, \; \left\{\delta m_1, \; \delta \lambda_{1\, a}, \; \delta \lambda_{2\, a}, \; \delta \lambda_{1\, b}, \; \delta \lambda_{2\, b}, \; Z, \; Z\Delta \right\}] \; / \; \; \\ & \quad \text{Solve}[\text{cteqs3}, \; \left\{\delta m_1, \; \delta \lambda_{1\, a}, \; \delta \lambda_{2\, a}, \; \delta \lambda_{1\, b}, \; \delta \lambda_{2\, a}, \; \delta \lambda_{1\, b}, \; \delta \lambda_{2\, b}, \; Z, \; Z\Delta \right\}] \; / \; \\ & \quad \text{Solve}[\text{cteqs3}, \; \left\{\delta m_0, \; \delta \lambda_0\right\}] \; / \; \; \; Z\Delta \to 1 \; / / \; \text{FullSimplify} \end{split}$$
 
$$\left\{\delta m_0^2 = -\frac{m^2 \, \kappa \, \lambda \, \tilde{h}}{3} \; \left(\frac{\delta \lambda_{1\, a}}{\delta \lambda_{1\, b}} - 1\right)\right\} \; / \; \; \text{Solve}[\text{cteqs}, \; \left\{\delta m_1, \; \delta \lambda_{1\, a}, \; \delta \lambda_{2\, a}, \; \delta \lambda_{1\, b}, \; \delta \lambda_{2\, b}, \; Z, \; Z\Delta \right\}] \; / \; . \end{split}$$

Solve[ctegs3,  $\{\delta m_0$ ,  $\delta \lambda_0\}$ ] /.  $Z\Delta \to 1$  // FullSimplify