

Renormalization of Soft Symmetry Improved 2PIEA gap equations in the Hartree-Fock approximation

Supplement to thesis Chapter 5 "Soft Symmetry Improvement"

Mathematica notebook to compute counter-terms for the Hartree-Fock truncation of the SSI-2PIEA

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Hartree-Fock

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In[41]:= ClearAll[veom, geom, neom, regularisedtadpoles, mg2soln, mn2soln,  
           cteq, cteq2, cteqs, ctsolns, cts, ctegs3, rnveom, veomCtEqs,  $\delta m$ ,  $\delta \lambda$ ];
```

Hartree-Fock gap equations with counterterms

Goldstone equation of motion. Quantities in reference to the paper are:

p is the four-momentum flowing through the propagators Δ_G^{-1} and Δ_N^{-1} ,

mg^2 is the Goldstone mass squared m_G^2 ,

mn^2 is the Higgs mass squared m_H^2 ,

Z and $Z\Delta$ are the wavefunction a propagator renormalization constants,

m^2 is the (renormalized) Lagrangian mass parameter, δm_0^2 , δm_1^2 are its counter-terms,

λ is the (renormalized) four point coupling,

$\delta \lambda_0$, $\delta \lambda_{1a}$, $\delta \lambda_{1b}$, $\delta \lambda_{2a}$, $\delta \lambda_{2b}$ are the independent coupling counter-terms,

v is the scalar field vacuum expectation value,

\hbar is the reduced Planck constant,

n is the number of fields in the $O(n)$ symmetry group,

ξ is the stiffness parameter,

ϵ is the solution of the Goldstone zero mode equation,

$ssi = \frac{1}{\sqrt{\beta} m_G^2} \left(\frac{1}{\epsilon} - 1 \right)$ is the soft symmetry improvement term in the propagator eoms,

$ssi2 = \frac{1}{\xi} (n-1) 2 (m_G^2 \epsilon)^2$ is the other soft symmetry improvement term in the vev eom,

$t_{\infty g}$, $t_{\infty n}$ are the divergent tadpole integrals for the Goldstone, Higgs resp.,

$t_{fin g}$, $t_{fin n}$ are the finite parts of the tadpoles for the Goldstone, Higgs resp.

Vev equation of motion

$$\text{In[42]:= } \mathbf{veom} = \mathbf{Z} \Delta^{-1} \left(\mathbf{m}^2 + \delta \mathbf{m}_0^2 \right) \mathbf{v} + \frac{\lambda + \delta \lambda_0}{6} \mathbf{v}^3 + \frac{\hbar}{6} \mathbf{Z} \Delta \left(\mathbf{n} - 1 \right) \left(\lambda + \delta \lambda_{1a} \right) \mathbf{v} \left(\mathbf{t}\omega\mathbf{g} + \mathbf{t}\mathbf{f}\mathbf{i}\mathbf{n}\mathbf{g} + \mathbf{s}\mathbf{s}\mathbf{i} \right) +$$

$$\frac{\hbar}{6} \mathbf{Z} \Delta \left(3 \lambda + \delta \lambda_{1a} + 2 \delta \lambda_{1b} \right) \mathbf{v} \left(\mathbf{t}\omega\mathbf{n} + \mathbf{t}\mathbf{f}\mathbf{i}\mathbf{n}\mathbf{n} \right) + \mathbf{v} \mathbf{s}\mathbf{s}\mathbf{i}^2$$

Goldstone equation of motion

$$\text{In[43]:= } \mathbf{geom} = \mathbf{p}^2 - \mathbf{mg}2 == \mathbf{Z} \mathbf{Z} \Delta \mathbf{p}^2 - \mathbf{m}^2 - \delta \mathbf{m}_1^2 - \mathbf{Z} \Delta \frac{\lambda + \delta \lambda_{1a}}{6} \mathbf{v}^2 -$$

$$\frac{\hbar}{6} \left(\left(\mathbf{n} + 1 \right) \lambda + \left(\mathbf{n} - 1 \right) \delta \lambda_{2a} + 2 \delta \lambda_{2b} \right) \mathbf{Z} \Delta^2 \left(\mathbf{t}\omega\mathbf{g} + \mathbf{t}\mathbf{f}\mathbf{i}\mathbf{n}\mathbf{g} + \mathbf{s}\mathbf{s}\mathbf{i} \right) - \frac{\hbar}{6} \left(\lambda + \delta \lambda_{2a} \right) \mathbf{Z} \Delta^2 \left(\mathbf{t}\omega\mathbf{n} + \mathbf{t}\mathbf{f}\mathbf{i}\mathbf{n}\mathbf{n} \right)$$

Higgs equation of motion

$$\text{In[44]:= } \mathbf{neom} = \mathbf{p}^2 - \mathbf{mn}2 == \mathbf{Z} \mathbf{Z} \Delta \mathbf{p}^2 - \mathbf{m}^2 - \delta \mathbf{m}_1^2 - \mathbf{Z} \Delta \mathbf{v}^2 \frac{\left(3 \lambda + \delta \lambda_{1a} + 2 \delta \lambda_{1b} \right)}{6} -$$

$$\frac{\hbar}{6} \left(\lambda + \delta \lambda_{2a} \right) \left(\mathbf{n} - 1 \right) \mathbf{Z} \Delta^2 \left(\mathbf{t}\omega\mathbf{g} + \mathbf{t}\mathbf{f}\mathbf{i}\mathbf{n}\mathbf{g} + \mathbf{s}\mathbf{s}\mathbf{i} \right) - \frac{\hbar}{6} \left(3 \lambda + \delta \lambda_{2a} + 2 \delta \lambda_{2b} \right) \mathbf{Z} \Delta^2 \left(\mathbf{t}\omega\mathbf{n} + \mathbf{t}\mathbf{f}\mathbf{i}\mathbf{n}\mathbf{n} \right)$$

Infinite parts of tadpoles in MSbar

MSbar rules for $4 - 2\epsilon$ dimensions

$$\text{In[45]:= } \mathbf{regularisedtadpoles} = \left\{ \mathbf{t}\omega\mathbf{g} \rightarrow \mathbf{c}0 \Lambda^2 + \mathbf{c}1 \mathbf{mg}2 \text{Log} \left[\Lambda^2 / \mu^2 \right], \mathbf{t}\omega\mathbf{n} \rightarrow \mathbf{c}0 \Lambda^2 + \mathbf{c}1 \mathbf{mn}2 \text{Log} \left[\Lambda^2 / \mu^2 \right] \right\}$$

Sub in tadpole expressions, eliminate mn2 and solve for mg2

$$\text{In[46]:= } \mathbf{mg2soln} = \mathbf{mg}2 /. \left(\mathbf{geom} /. \mathbf{regularisedtadpoles} /. \right.$$

$$\left. \mathbf{Solve}[\mathbf{neom} /. \mathbf{regularisedtadpoles}, \mathbf{mn}2][[1]] // \mathbf{Solve}[\#, \mathbf{mg}2][[1]] \& \right)$$

$$\text{In[47]:= } \mathbf{mn2soln} = \mathbf{mn}2 /. \left(\mathbf{neom} /. \mathbf{regularisedtadpoles} /. \mathbf{mg}2 \rightarrow \mathbf{mg2soln} // \mathbf{Solve}[\#, \mathbf{mn}2][[1]] \& \right)$$

Gather divergences proportional v, tfing and tfinn and set independently to zero

First we subtract the finite equation of motion, then gather coefficients of the remainder into a list and set each to zero (after some trimming and simplifying).

$$\text{In[48]:= } \mathbf{cteq} =$$

$$\left(\left(\mathbf{CoefficientList}[\mathbf{mg2soln} + \left(-\mathbf{m}^2 - \frac{\lambda}{6} \mathbf{v}^2 - \frac{\hbar}{6} \left(\left(\mathbf{n} + 1 \right) \lambda \right) \left(\mathbf{t}\mathbf{f}\mathbf{i}\mathbf{n}\mathbf{g} + \mathbf{s}\mathbf{s}\mathbf{i} \right) - \frac{\hbar}{6} \left(\lambda \right) \left(\mathbf{t}\mathbf{f}\mathbf{i}\mathbf{n}\mathbf{n} \right) \right), \right.$$

$$\left. \left\{ \mathbf{p}, \mathbf{v}, \mathbf{t}\mathbf{f}\mathbf{i}\mathbf{n}\mathbf{g}, \mathbf{t}\mathbf{f}\mathbf{i}\mathbf{n}\mathbf{n} \right\} // \mathbf{Flatten} \right) //$$

$$\mathbf{DeleteDuplicates} // \mathbf{Simplify} // \mathbf{FullSimplify} \Big) == 0 // \mathbf{Thread}$$

```
In[49]:= cteq2 =
  (CoefficientList[mn2soln + (-m^2 - \frac{\lambda}{2} v^2 - \frac{\hbar}{6} ((n-1) \lambda) (tfing + ssi) - \frac{\hbar}{2} (\lambda) (tfinn)),
    {p, v, tfing, tfinn}] // Flatten) //
  DeleteDuplicates // Simplify // FullSimplify) == 0 // Thread
```

Solve for counterterms

```
In[50]:= cteqs = {cteq, cteq2} // Flatten // FullSimplify // DeleteDuplicates
```

```
In[51]:= ctsolns =
  Solve[cteqs, {\delta m_1, \delta \lambda_{1a}, \delta \lambda_{2a}, \delta \lambda_{1b}, \delta \lambda_{2b}, Z, Z\Delta}] // FullSimplify // DeleteDuplicates
```

```
In[52]:= cts = {\delta m_1^2, \delta \lambda_{1a}, \delta \lambda_{2a}, \delta \lambda_{1b}, \delta \lambda_{2b}, Z, Z\Delta} /. ctsolns // FullSimplify // DeleteDuplicates
Z\Delta is redundant in this truncation, can remove it :
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```
In[53]:= cts /. Z\Delta \to 1 // FullSimplify
```

```
In[54]:= mg2soln /. ctsolns /. Z\Delta \to 1 // FullSimplify // DeleteDuplicates
```

```
In[55]:= mn2 /.
  ((neom /. regularisedtadpoles /. mg2 \to mg2soln /. ctsolns /. Z\Delta \to 1 // FullSimplify //
    DeleteDuplicates) // Solve[#, mn2] &) // FullSimplify
```

```
In[56]:= rnveom =
  veom /. {mg2 \to m^2 + \frac{\lambda}{2} v^2 + \frac{\hbar}{6} ((n+1) \lambda) (tfing + ssi) + \frac{\hbar}{6} (\lambda) (tfinn), mn2 \to m^2 + \frac{\lambda}{2} v^2 +
    \frac{\hbar}{6} ((n-1) \lambda) (tfing + ssi) + \frac{\hbar}{2} (\lambda) (tfinn)} // Simplify // DeleteDuplicates
```

```
In[57]:= veomCtEqs =
  (((CoefficientList[(\frac{1}{v} rnveom - (m^2 + \frac{\lambda}{6} v^2 + \frac{\hbar}{6} ((n-1) \lambda) (tfing + ssi) + \frac{\hbar}{2} (\lambda) (tfinn) +
    ssi2))] /. regularisedtadpoles /.
    {mg2 \to m^2 + \frac{\lambda}{6} v^2 + \frac{\hbar}{6} ((n+1) \lambda) (tfing + ssi) + \frac{\hbar}{6} (\lambda) (tfinn),
      mn2 \to m^2 + \frac{\lambda}{2} v^2 + \frac{\hbar}{6} ((n-1) \lambda) (tfing + ssi) + \frac{\hbar}{2} (\lambda) (tfinn)} //
    Simplify // Expand // FullSimplify, {v, tfing, tfinn}] //
    Simplify // Flatten) // DeleteDuplicates // Simplify //
    FullSimplify // DeleteDuplicates) == 0 // Thread)
```

```
In[58]:= ctegs3 = (veomCtEqs /. ctsolns // Simplify // DeleteDuplicates // FullSimplify)[[1]]
```

```
In[59]:= {\delta m_0^2, \delta \lambda_0} /. Solve[ctegs3, {\delta m_0, \delta \lambda_0}] /. Z\Delta \to 1 // DeleteDuplicates // Simplify
```

```
In[60]:= { $\delta m_1^2 == \delta m_0^2$ ,  $\delta \lambda_{1a} == \delta \lambda_{2a}$ ,  $\delta \lambda_{1b} == \delta \lambda_{2b}$ } /. ctsolns /. Solve[ctegs3, { $\delta m_0$ ,  $\delta \lambda_0$ }] /.  
Z $\Delta \rightarrow 1$  // FullSimplify // Flatten // DeleteDuplicates
```

```
In[61]:= { $\frac{\delta \lambda_{1a}}{\delta \lambda_{1b}}$ } /. ctsolns /. Solve[ctegs3, { $\delta m_0$ ,  $\delta \lambda_0$ }] /. Z $\Delta \rightarrow 1$  // FullSimplify // Flatten //  
DeleteDuplicates
```

```
In[62]:=  $\delta \lambda_{1b} == \delta \lambda_{2b}$  /. ctsolns /. Z $\Delta \rightarrow 1$  // FullSimplify // DeleteDuplicates
```

```
In[63]:=  $\delta \lambda_{1b}$  /. ctsolns /. Z $\Delta \rightarrow 1$  // FullSimplify // DeleteDuplicates
```

```
In[64]:= { $\delta \lambda_0 == 1 \delta \lambda_{1a} + 2 \delta \lambda_{1b}$ } /. ctsolns /. Solve[ctegs3, { $\delta m_0$ ,  $\delta \lambda_0$ }] /. Z $\Delta \rightarrow 1$  // FullSimplify //  
Flatten // DeleteDuplicates
```

```
In[65]:= { $\delta m_0^2 == -\frac{(c0 \Lambda^2 + c1 m^2 \text{Log}[\frac{\Lambda^2}{\mu^2}]) \lambda \hbar}{3} \left(\frac{\delta \lambda_{1a}}{\delta \lambda_{1b}} - 1\right)$ } /. ctsolns /. Solve[ctegs3, { $\delta m_0$ ,  $\delta \lambda_0$ }] /.  
Z $\Delta \rightarrow 1$  // FullSimplify // Flatten // DeleteDuplicates
```