

Renormalization of Symmetry Improved 3PIEA gap equations at 2 loops

Supplement to thesis Chapter 4.

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Mathematica notebook to compute counter-terms for two loop truncations of the SI-3PIEA.

Hartree-Fock

```
ClearAll[geom, neom, intrules, regularisedtadpoles, mg2soln, cteq, cts,  $\delta m$ ,  $\delta \lambda$ ];
```

Hartree-Fock gap equations with counterterms

Goldstone equation of motion. Quantities in reference to the paper are:

p is the four-momentum flowing through the propagators Δ_G^{-1} and Δ_N^{-1} ,

mg^2 is the Goldstone mass squared m_G^2 ,

Z and $Z\Delta$ are the wavefunction a propagator renormalization constants,

m^2 is the (renormalized) Lagrangian mass parameter, δm_1^2 is its counter-term,

λ is the (renormalized) four point coupling,

$\delta\lambda_{1a}$, $\delta\lambda_{2a}$, $\delta\lambda_{2b}$ are the independent coupling counter-terms,

v is the scalar field vacuum expectation value,

\hbar is the reduced Planck constant,

n is the number of fields in the $O(n)$ symmetry group,

$t_{\infty g}$, $t_{\infty n}$ are the divergent tadpole integrals for the Goldstone, Higgs resp.,

$t_{fin g}$, $t_{fin n}$ are the finite parts of the tadpoles for the Goldstone, Higgs resp.

$$\begin{aligned} \text{geom} = p^2 - mg^2 = & Z Z\Delta p^2 - m^2 - \delta m_1^2 - Z\Delta \frac{\lambda + \delta\lambda_{1a}}{6} v^2 - \\ & \frac{\hbar}{6} \left((n+1) \lambda + (n-1) \delta\lambda_{2a} + 2 \delta\lambda_{2b} \right) Z\Delta^2 (t_{\infty g} + t_{fin g}) - \frac{\hbar}{6} (\lambda + \delta\lambda_{2a}) Z\Delta^2 (t_{\infty n} + t_{fin n}) \end{aligned}$$

Higgs equation of motion

$$\text{neom} = p^2 - mn^2 = \frac{-\lambda v^2}{3} Z\Delta + p^2 - mg^2$$

Infinite parts of tadpoles in MSbar

MSbar rules for $4 - 2\epsilon$ dimensions

$$\text{regularisedtadpoles} = \{t\omega g \rightarrow c0 \Lambda^2 + c1 \text{mg2} \text{Log}[\Lambda^2 / \mu^2], t\omega n \rightarrow c0 \Lambda^2 + c1 \text{mn2} \text{Log}[\Lambda^2 / \mu^2]\}$$

Sub in tadpole expressions, eliminate mn2 and solve for mg2

```
mg2soln =
mg2 /. (geom /. regularisedtadpoles /. Solve[neom, mn2][[1]] // Solve[#, mg2][[1]] &)
```

Gather divergences proportional v, tfing and tfinn and set independently to zero

First we subtract the finite equation of motion, then gather coefficients of the remainder into a list and set each to zero (after some trimming and simplifying).

```
cteq =
((CoefficientList[mg2soln + (-m^2 - \frac{\lambda}{6} v^2 - \frac{\hbar}{6} ((n+1) \lambda) (tfing) - \frac{\hbar}{6} (\lambda) (tfinn)), {p, v,
tfing, tfinn}]] // Flatten) //
DeleteDuplicates // Simplify // FullSimplify) == 0 // Thread
```

Solve for counterterms

```
cts = {\delta m_1^2, \delta \lambda_{1a}, \delta \lambda_{2a}, \delta \lambda_{2b}, Z, Z_\Delta} /. Solve[cteq, {\delta m_1, \delta \lambda_{1a}, \delta \lambda_{2a}, \delta \lambda_{2b}, Z, Z_\Delta}] //
FullSimplify // DeleteDuplicates
```

Z_Δ is redundant in this truncation, can remove it :

```
cts /. Z_\Delta \rightarrow 1 // FullSimplify
```

```
\delta \lambda_{2a} == \frac{n+2}{n+4} \delta \lambda_{1a} /. Solve[cteq, {\delta m_1, \delta \lambda_{1a}, \delta \lambda_{2a}, \delta \lambda_{2b}, Z, Z_\Delta}] /. {Z_\Delta \rightarrow 1} //
FullSimplify // DeleteDuplicates
```

Sunset

NOTE: this uses some of the same variable names as the Hartree-Fock code! Be careful not to clobber what you need to keep.

```
ClearAll[geom, neom, intrules, regularisedtadpoles, mg2soln, cteq, \delta m, \delta \lambda, \delta \lambda, \delta \lambda, \delta \lambda];
```

Equations of motion

Additional variables relative to the Hartree-Fock case:

Ing is the sunset integral $I_{\text{NG}}(\rho)$

Ifingp is the finite sunset integral $I_{\text{NG}}^{\text{fin}}(p)$,

Ifing0 is $I_{\text{NG}}^{\text{fin}}(m_G)$,

Ifingn is $I_{\text{NG}}^{\text{fin}}(m_N)$,

$\delta\lambda$ is the sunset graph coupling counter-term,

I_μ , T_μ and c_μ are the auxiliary integrals I_μ , T_μ and c_μ respectively.

$$\begin{aligned} \text{geom} &= p^2 - mg2 + i \hbar \left(\frac{(\lambda) v}{3} \right)^2 (I_{\text{fingp}} - I_{\text{fing0}}) = \\ &Z \Delta p^2 - m^2 - \delta m_1^2 - Z \Delta \frac{\lambda + \delta \lambda_1 a}{6} v^2 - \frac{\hbar}{6} \left((n+1) \lambda + (n-1) \delta \lambda_{2a} + 2 \delta \lambda_{2b} \right) Z \Delta^2 (tg) - \\ &\frac{\hbar}{6} (\lambda + \delta \lambda_{2a}) Z \Delta^2 (tn) + i \hbar \left(\frac{(\lambda + \delta \lambda) v}{3} \right)^2 Z \Delta^3 \text{Ing} \\ \text{neom} &= p^2 - mn2 + i \hbar \left(\frac{(\lambda) v}{3} \right)^2 (I_{\text{fingp}} - I_{\text{fingn}}) = \\ &\frac{-Z \Delta (\lambda + \delta \lambda) v^2}{3} + p^2 - mg2 + i \hbar \left(\frac{(\lambda) v}{3} \right)^2 (I_{\text{fingp}} - I_{\text{fing0}}) \end{aligned}$$

Divergent parts subtracted with auxiliary integrals and MSbar

$$\begin{aligned} \text{intrules} &= \{ \text{Ing} \rightarrow I_\mu + I_{\text{fingp}} + I_{\text{fing0}}, \\ &tg \rightarrow T_\mu - i (mg2 - \mu^2) I_\mu + \hbar \left(\frac{(\lambda + \delta \lambda) v}{3} \right)^2 c_\mu + t_{\text{fing}}, \\ &tn \rightarrow T_\mu - i (mn2 - \mu^2) I_\mu + \hbar \left(\frac{(\lambda + \delta \lambda) v}{3} \right)^2 c_\mu + t_{\text{finn}} \} \\ \text{regularisedtadpoles} &= \\ &\{ I_\mu \rightarrow c2 \text{Log} \left[\frac{\Lambda^2}{\mu^2} \right], T_\mu \rightarrow c0 \Lambda^2 + c1 \mu^2 \text{Log} \left[\frac{\Lambda^2}{\mu^2} \right], c_\mu \rightarrow a0 \text{Log} \left[\frac{\Lambda^2}{\mu^2} \right]^2 + a1 \text{Log} \left[\frac{\Lambda^2}{\mu^2} \right] \} \end{aligned}$$

Sub everything in, eliminate mn2 and solve for mg2

$$\begin{aligned} \text{mg2soln} &= \left((\text{geom} /. \text{intrules} /. \text{regularisedtadpoles}) /. \text{Solve}[\text{neom}, mn2][[1]] \right) // \\ &\text{Solve}[\#, mg2] \&)[[1]] \end{aligned}$$

Gather kinematically distinct divergences for Goldstone EOM

$$\begin{aligned} \text{cteq} &= \left(\left(mg2 - m^2 - \frac{\lambda}{6} v^2 - \frac{\hbar}{6} \left((n+1) \lambda \right) (t_{\text{fing}}) - \frac{\hbar}{6} (\lambda) (t_{\text{finn}}) /. \text{mg2soln} \right) // \right. \\ &\text{CoefficientList}[\#, \{p, v, t_{\text{fing}}, t_{\text{finn}}, I_{\text{fingp}}\}] \& // \text{Flatten} // \\ &\left. \text{Simplify} // \text{DeleteDuplicates} \right) == 0 // \text{Thread} \end{aligned}$$

Solve for counter-terms from Goldstone EOM

Note there are two solutions differing by a sign for $\delta\lambda$.

$$\begin{aligned} \text{cts} &= \\ &\text{Solve}[\text{cteq}, \{\delta m_1, \delta \lambda_{1a}, \delta \lambda_{2a}, \delta \lambda_{2b}, \delta \lambda, Z, Z \Delta\}] // \text{FullSimplify} // \text{DeleteDuplicates}; \end{aligned}$$

```
{δm12, δλ1a, δλ2a, δλ2b, δλ, Z, ZΔ} /. cts // DeleteDuplicates
```

Gather kinematically distinct divergences for Higgs EOM

```
cteq2 =
  ( ( ( ( ( (mn2 - (λ v2 / 3) - m2 - λ / 6 v2 - ħ / 6 ((n+1) λ) (tfing) - ħ / 6 (λ) (tfinn) /. mg2soln) /. Solve[
    neom, mn2][[1]] /. mg2soln) /. cts // FullSimplify //
    DeleteDuplicates) /. {tfing → 0, tfinn → 0} // Expand) //
    CoefficientList[#, {p, v, tfing, tfinn, Ifingp}] & // Flatten //
    Simplify // DeleteDuplicates) == 0 // Thread
```

Solve for counter-terms from Higgs EOM

```
cts2 = Solve[cteq2[[2]], {ZΔ}]
```

Both equations should have the same solution:

```
(ZΔ /. Solve[cteq2[[3]], {ZΔ}][[1]]) - (ZΔ /. cts2[[1]]) == 0
```

Final Counterterms

```
({δm12, δλ1a, δλ2a, δλ2b, δλ, Z, ZΔ} /. cts /. cts2 // Simplify)[[1]] //
DeleteDuplicates;
```

```
counterterms = Thread[{δm12, δλ1a, δλ2a, δλ2b, δλ, Z, ZΔ} → %[[1]]]
```

The should be momentum independent :

```
({δm12, δλ1a, δλ2a, δλ2b, δλ, Z, ZΔ} /. counterterms // DeleteDuplicates // D[#, p] &)[[1]] == 0 // Thread
({δm12, δλ1a, δλ2a, δλ2b, δλ, Z, ZΔ} /. counterterms // DeleteDuplicates //
D[#, Ifingp] &)[[1]] == 0 // Thread
```