

# Privacy by Design in Machine Learning Data Collection: UX Experimentation in HRI Setting

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## Abstract

Designing successful user experiences that use machine learning systems is an area of increasing importance. In supervised machine learning for biometric systems, such as for face recognition, the user experience can be improved. In order to use biometric authentication systems, users are asked for their biometric information together with their personal information. In contexts where there is a frequent and large amount of users to be enrolled, the human expert assisting the data collection process is often replaced in favour of software with a step-by-step user interface. However, this may introduce limitations to the overall user experience of the system. User experience should be addressed from the very beginning, during the design process. Furthermore, data collection might also introduce privacy concerns in users and potentially lead to them to not use the system. For these reasons, we propose a privacy by design approach in order to maximize the user experience of the system while reducing privacy concerns of users. To do so we suggest a novel experiment in a Human-Robot interaction setting. We investigate the effects of embodiment and transparency on privacy and user experience. We expect that embodiment would enhance the overall user experience of the system, independently from transparency, whereas we expect that transparency would reduce privacy concerns of the participants. In particular, we forecast that transparency, together with embodiment, would significantly reduce privacy considerations of participants, thus maximising the amount of personal information provided by a user.

## Introduction

Data collection, like the name suggests, is the process of gathering and measuring information. This is a necessary task for every machine learning system (Chen, Mao, and Liu 2014), and collecting data in an *efficient* and *responsible* manner is extremely important, especially in biometric authentication systems (Wayman et al. 2005). We propose a novel experimental methodology to test the user experience of data collection interfaces for face recognition systems, while at the same time gathering insights for dealing with privacy issues involved in the process. In developing the proposed data collection system we make use of a *privacy by design* approach. We plan to situate the experiment

in a bank. Since their customers usually know to be protected by laws when asked for sensitive data (Turner, Zavod, and Yurcik 2001), this is a good context to test the effects on privacy concerns. In this paper we focus our investigation to supervised machine learning systems for face recognition. These systems provide on-line enrolment processes on first contact of the user with the biometric system. These are used to gather biometric samples of the user's face and related personal details.

A supervised machine learning algorithm uses labelled training data to teach itself how to classify new observations in the correct classes. For huge amount of data, the process of labelling can be efficiently realized using crowd-sourcing. However, the benefits of this methodology are limited to data gathered for off-line training, thus becoming unsuitable for on-line data collection. For instance, a face recognition system requires to register and enrol a new face and the related details of the person every time a new user needs to be recognised by the system. Since users generally do not possess any previous experience with the system they are being registered with, the first measurement is often guided by a professional who explains the use of the biometric reader (Matyáš and Říha 2002). This Human-Human interaction can indeed facilitate the data collection process, making it more effective and efficient. However, in order to minimise the associated costs, this solution is often replaced in favour of the provision of software having a guided graphic user interface (GUI).

More importantly, the data to be collected can contain sensitive information. Thus, the data collection process can become a potential threat for users' privacy (Wayman et al. 2005). No matter how appealing and usable is the system; if users do not trust a system, they are likely not to use it (Pearson 2009). This problem is particularly significant when the user is aware of the data collection process and it is necessary to gain their consent to collect their private information.

Privacy issues that arise in real-time data collection can be addressed explicitly, by providing specific guidelines aimed at reducing the amount of sensitive data stored in the system (Fung et al. 2010) or by using encryption algorithms to safely store data (Basharat, Azam, and Muzaffar 2012). In addition, privacy can be implicitly addressed by the machine learning algorithm itself. For instance, the algorithm can learn which features to extract from inputs after a train-

ing phase. This new representation is then extracted from new observations in order to classify them with competitive recognition rates. However, the extracted features might not contain enough information for reconstructing the original input back (Amos, Ludwiczuk, and Satyanarayanan 2016), thus relieving privacy concerns. Despite these important precautions, the majority of naïve users do not know the underlying details of the machine learning algorithm used, what data would be stored by the system, and how. Thus, this lack of transparency might impact on users' trust and lead to, possibly unfounded, privacy concerns.

Given the significance of these issues, in this paper we propose a methodology to investigate the effect that *embodiment* and *transparency* have on the *user experience* and on the *privacy considerations* of users during real-time data collection.

We expect that embodying a face enrolment system in a robotic platform, and enhancing the transparency of the underlying machine learning system through an appropriate GUI would mitigate users' privacy concerns, while at the same time providing a better user experience.

## Privacy by Design in Human-Machine Interactions

Privacy by design incorporates privacy considerations directly into the design process of a system. This allows the system to integrate privacy management from the very beginning, rather than adding it after the system is fully developed. Existing systems built without including privacy considerations as a core part of their development often results in poor privacy management (Anthonysamy, Greenwood, and Rashid 2013). When this becomes evident to their users they might lose trust in the system, and potentially reduce its usage (Anthonysamy, Greenwood, and Rashid 2013).

Many governments address privacy through guidelines and laws. For example, Australia provides clear guidelines around the use, collection and management of personal data. The Australian Privacy Principles (APPs), included in Schedule 1 of the Privacy Act 1988<sup>1</sup>, state that “entities manage personal information in an open and transparent way”. Indeed, labelling and storage of sensitive biometric information, such as a biometric template for machine learning of facial information, is specifically included in the APP. Users must choose whether an entity is allowed to store personal information about them and must be informed as to what the stored information will be used for. Hence, designing a system accounting for these requirements, while also targeting the best user experience, becomes crucial.

In the context of institutions like banks, information collected from people (say, customers) can have significant privacy issues. For instance, it is not ethical for such organizations to deceptively collect personal information that might be exposed to the public or other technical employees of the organization. Sometimes it might be necessary to provide (disclose) the information for analytical purposes but institutions “have to evaluate the potential ethical or unethical

use of disclosed information” (Turilli and Floridi 2009). As such, it is important that the organization enables a mechanism of full transparency in the information collection procedure. “Information transparency is not an ethical principle per se” (Turilli and Floridi 2009, pag. 107) but having a less transparent method of information collection from people might impose some privacy concerns. This might in turn prevent them from willingly providing some information which they think is private for them and may be disclosed by the organization collecting the information. Hence, it is the requirement of an organization to have a more transparent mechanism of collecting information and explaining how the information will be stored and used so that the people providing the information can make suitable choices and are not concerned about threats to their privacy.

Making use of a human assistant to collect the data while providing information about the system, the data collected and the rights of the person can enhance users' trust and relieve privacy concerns. However, this solution is not always feasible in machine learning systems, because of its high costs. Thus, often the alternative is to provide software to assist the user during the data collection process. It has been shown that robots can be an effective alternative to human-to-human interactions, because of their embodiment, which simple computer based applications cannot exhibit (Kidd and Breazeal 2004). In fact, robots can speak, gesture, gaze, *etc.*, thus resembling a social human interaction and facilitate the data collection process, while providing a greater sense of trust and reliability than a simple disembodied software (Kidd and Breazeal 2004). Hence, similarly to transparency, investigating the impact of embodiment in privacy by design settings becomes crucial too.

In the following section we provide an experimental methodology to test the effect of embodiment and transparency on privacy and user experience in the context of a face enrolment system situated in a bank.

## Proposed Methodology

### Participants

We propose to design a preliminary survey to select our participants. We aim to include a population homogeneously ranging from 18 to 45 years old, evenly split into males and females, and balanced in terms of computer literacy. Pre-conditions for accessing to this experiment would be to be proficient in English reading and listening, and own a profile on Facebook, Instagram, LinkedIn and Twitter.

The participants would be recruited from students and staff of the University of Technology Sydney, and staff and customers of Commonwealth Bank located in Sydney.

### Used Material

The experiment consists of two settings. The first setting involves using a robot guiding users during a face enrolment process. In the second setting participants experience the same face enrolment process without the involvement of a robot.

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<sup>1</sup><https://www.legislation.gov.au/Details/C2016C00838>

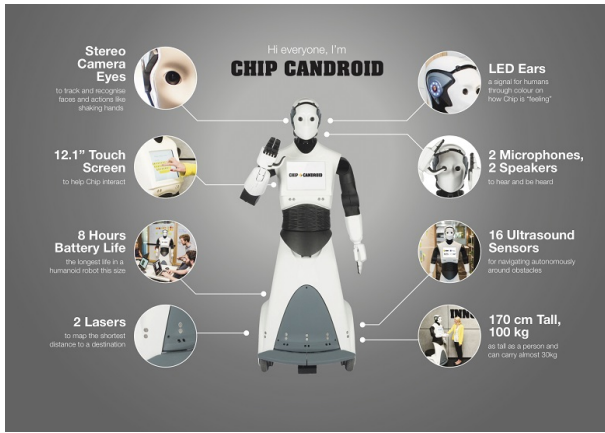


Figure 1: Technical details of the used robot platform for the embodied setting of the experiment.

**Robotic Platform** We use a PAL REEM service robot<sup>2</sup>, a wheel-based robot equipped with a pair of stereo cameras on its head. The robot also has a pair of 4-degree of freedom (DOF) arms and 7-DOF hands that can perform human-like gestures. More importantly, the robot has a built-in touch screen, used during our experiment to display the graphic user interface of the face enrolment system (Fig. 1).

The REEM touch screen is used as the main interface to gather user’s inputs during the first setting of the experiment (Fig. 2). To entice a user to provide face enrolment information, the robot will perform various arm motions and audio instructions/cues to user in addition to the visual information shown on its screen. We record the user interactions through the touch screen.

**Disembodied Platform** As a comparison, the second settings of the experiment involves a face enrolment setup without the use of the robot. In alternative, we use a touch screen (an iPad mobile device) and a camera that are fixed on a blank wall (Fig. 2) respecting the same robot physical configuration. The GUI on the touch screen is exactly the same as the one in the robot setting. The same audio instructions are provided through the mobile device, but no gestures would be available.

**Face Recognition System** The experiment uses a face recognition system that is built upon the state-of-art OpenFace implementation (Amos, Ludwiczuk, and Satyanarayanan 2016). The face enrolment process in our system is designed to be user self-driven. That is, the enrolment system shows to the user the captured face image through REEM’s or iPad’s camera, and the user is asked to self-annotate the input face (*i.e.* providing the name and other personal information).

## Procedure

In our experiment we will consider two independent variables, namely *embodiment* and *transparency*. These vari-

<sup>2</sup><http://pal-robotics.com/wp-content/uploads/2016/03/REEM-Datasheet.pdf>

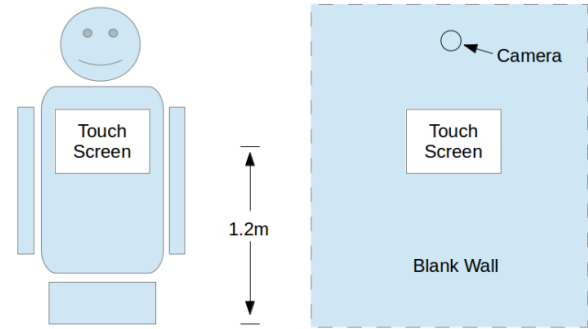


Figure 2: Face enrolment setup on the REEM robot (left) and the alternative disembodied setup on a blank wall (right).

ables are binary (*i.e.* either embodied or disembodied, and transparent or not transparent), thus leading to a  $2 \times 2$  between-subjects design. The participants would be evenly divided for each of the four settings (*i.e.* embodiment with transparency, embodiment without transparency, disembodiment with transparency and disembodiment without transparency).

We measure the user experience of users with the data collection system through the User Experience Questionnaire (UEQ), (Laugwitz, Held, and Schrepp 2008) whereas we measure the privacy consideration of users by counting the number of users allowing the system to collect their face, and, among them, the number of not compulsory information provided during the data collection process.

This additional information would be the access to their social networks accounts. The reason behind this choice is that a bank is usually perceived a reliable institution by users in safely storing their personal information (Turner, Zavod, and Yurcik 2001). Hence asking them to provide simple additional information (*e.g.* address, telephone number, *etc.*) would probably not elicit enough privacy concerns by users. On the contrary, we expect that by asking the users to provide access to their social networks accounts would be perceived as an intrusion outside the normal boundaries perceived appropriate for a bank institution. This would create more impacting privacy concerns in users, allowing us to efficiently measure the effects of embodiment and transparency on privacy.

The participants would stand in front of the enrolment system and interact with it, which would be either embodied (robot) or disembodied (tablet), depending on which setting they belong to, and decide if providing their consent in saving their details and additional information. In this first version of the experiment we do not investigate the effects on personification of the robot, thus not focusing on its personality or emotional capabilities.

During the transparent condition only, the data collection system would explain how the machine learning system is realized through a simple and user friendly example. Right after taking a picture of the user face, and before asking user’s consent, we will present the picture of a celebrity

which is the closest match for the retrieved picture of the user. The enrolment system would suggest that, given the present state of knowledge of the system, the user looks like such celebrity. We will explain through visual examples that the underlying system represent and save pictures of faces similarly to spatial coordinates (in order to allow everybody to understand the system we will use a 2-dimensional space as example). Hence, we will show a 2-dimensional plane with the picture of the user just taken together with a limited neighbourhood of other celebrities' faces in order to provide a visual example of the Euclidean distances between faces in such 2-dimensional space. The system would tell the user that the picture taken would not be stored 'as-if', but only as an abstract coordinate of such space, thus reducing risks for user's privacy.

## Expected Results

From the analysis of the results we would expect that:

- Embodiment of the system would positively impact on the user experience of the system, in both the transparent and not transparent conditions;
- Transparency of the system would significantly increase the number of users giving consensus for storing their face;
- Transparency in the embodied condition would increase the number of users releasing additional information about their social network accounts.

We believe that a robot platform having a humanoid form would encourage users to interact with natural interactions, as it happens with a human expert assisting the process. Thus, this would increase the ease of use of the system and enhance the overall user experience of the system. Furthermore, previous studies demonstrated that an embodied robot is perceived more trusting and reliable than virtual agents or computer applications (Kidd and Breazeal 2004). Hence, embodiment would not only impact on user experience, but also on trust and consequently privacy considerations. Finally, informing the users about the architecture underlying the face recognition system and give them the choice to go ahead with the process or not would provide them more sense of control, and consequently reduce their privacy concerns.

We think that this experiment would be really crucial for gathering information to make future data collection systems more efficient, user friendly, and most of all giving control to the users to manage their privacy from the very early stages of development.

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