

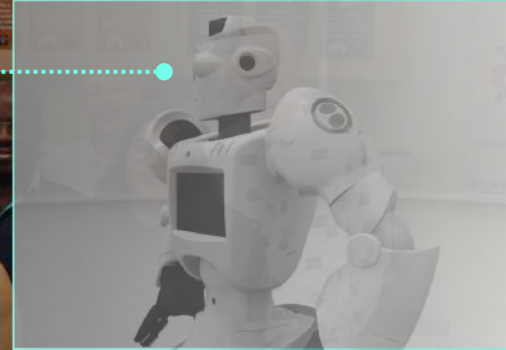
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function () {
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MIKE KIM

mikekim.fullstack@gmail.com :: 647.636.6379

234-70 Atkinson Rd, Toronto, ON, CANADA M3J 2S5

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}
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PERSONAL STATEMENT

With a career spanning over two decades as a Robotics Software Engineer, my journey has been nothing short of extraordinary, from orchestrating space robot missions to revolutionizing the realm of medical robotics. Amid this voyage, I witnessed the remarkable evolution of online platforms, driven by the transformative force of AI, and recognized it as the undeniable future. This realization ignited a new passion within me, propelling me towards an exciting career transition.

I dedicated six months to intensive training at the Seytech bootcamp, where I acquired the skills necessary to excel in the dynamic field of front-end development. Armed with this newfound knowledge, I embarked on a freelancing venture LaLaSol project that would forever alter my perspective on technology and its endless possibilities. My freelance journey not only enhanced my technical skills but also strengthened my ability to communicate effectively, meet client expectations, and deliver top-notch solutions within deadlines.

Now, I stand poised to embrace my new role as a front-end developer. I am irresistibly drawn to companies that value innovation, foster a culture of continuous learning, and thrive on collaborative teamwork.

My journey in front-end development has just begun, and I am eager to contribute my skills and passion to exciting, forward-thinking projects.

SKILL SETS

Front-end Developer

HTML (86%)

CSS/SASS (86%)

JavaScript (88%)

React JS (87%)

Back-end Developer

Strapi (86%)

Node.js (85%)

Django RESTful (87%)

SQL (84%)

Development IDE

VS Code (90%)

QT C++ (89%)

QT C++ (91%)

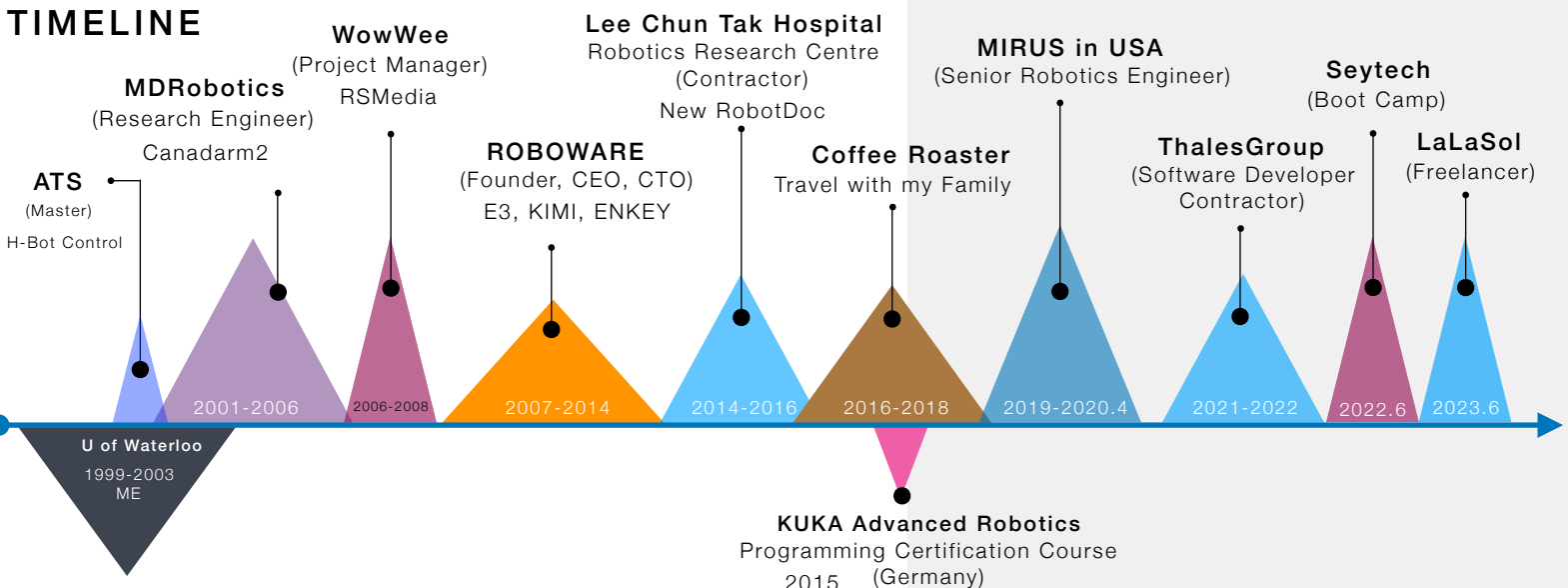
Source Code Control

Git/Hub (87%)

My Portfolio (more info please visit the below link)



TIMELINE



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}



WORK EXPERIENCE

LaLaSol - Toronto, Canada
2023

Freelanser Fullstack Developer.

LaLaSol Eduction platform which allows teacher create courses easily by clicking pre-built components with preview result.

THALES - Toronto, Canada
2021-2022

Train Signal System Software & Tool Developer.

Tools developer for automated testing for London subway transit at Thales

MIRUS LLT - Atlanta, USA
Medical Device company
<https://mirusmed.com/>
2019-2020.4

Senior Medical Robotics Engineer. Full Stack Stand-alone Application Developer.

Spine Surgical Robot Software development - FK, IK for Staubli Robot, Generated Path-plan to Robot, Simulator and Staubli Robot Server and Interface. (QT, VTK, Staubli Robot, 3D fiducial Marker Interface)

Lee Chun Tak Hospital
- Seoul
Robotics Research Centre
2014-2018

Full Stack Stand-alone Application Developer: Contract (Orthoplanner S/W)

Knee Replacement Software development, allowing physicians predefine the implant position and rotation of the femur and tibia and their simulation before the knee surgical robot performs surgeries.

(VC++ MFC, VTK: Image Segmentation, Joint Kinematics, DICOM Transfer)

ROBOWARE - Seoul
Intelligence Robotics
2007-2014

Founder & CEO/CTO

As a founder and CEO of ROBOWARE my Goal was to bring affordable personal robots to kids, educational fields and families. At the same period of time I made contribution to medical robot area with my knowledge and experiences.

Key Achievements:

Developed Robot Operating System, Medical robot system, Produced robot platforms



E3-ROMA

2007~2009



ENGKEY

2010~2013



KIBOT

2010~2011



KIBOT2

2011~2012



KIMI

2012~2013

WowWee - Hong Kong R&D
Interactive Toy Robotics
2006-2008

Project Manager

WowWee Company was the world leading robotic toy company and I was co-leading the couple of projects such as RSMedia and Elvis Presley Robot

Key Achievements:

Managing production lines and developed embedded, motion generation S/W



RS Media



Elvis Presley Robot

MDRobotics - Toronto R&D
Space Robotics
2001-2006

Researcher Engineer

MDRobotics' company is the most famous space robot company

Key Achievements:

Participation in developing Canada Arm (SSRMS, SPDM)

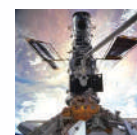
Participation in Hubble Telescope projects in NASA's Goddard Space Flight Centre



SSRMS(Canadarm2)



SPDM



Hubble Telescope

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EDUCATION

Coffee Roaster

Florence, Italy

2017

- *Became the Coffee Roaster*
Trained by the professional artisan coffee roaster.

Coffee Barista

Istanbul, Turkey

2017

- *Obtained the CSA Certification*

KUKA Advanced Robotics

Programming Certification Course
- Augsburg, Germany

2015

- *KUKA LBR Platform Application Developer*

Obtained the certification of KUKA LBR Med lightweight robot for a medical product.



University of WATERLOO

Graduate School - Waterloo

1999-2003

- *Master Degree of Mechanical Engineering*

Obtained NSERC Full Scholarship and Fellowship
Developed the DynaSim S/W to simulate the multi-body motion
Thesis: Multi-body Kinematics & Dynamics Analytical Simulation

PERSONAL PROJECT

I-Stacker Robot Platform

2020 - present

- **Integrative retail and food service robotics platform**

Roast Coffee Been

2018

- Roasting coffee beans for my family and friends.
- Produced computerized profile by the customized roast machine integrated with sensor

Education Robot Platform

2018

- Developing the robot H/W & S/W platform for a scenario based education system.

Home-made 3D Printer

2018

- Built the 3D printer for making the prototype.

PID - Coffee Machine

2018

- Developed the PID controller and mobile app which can be integrated into any espresso coffee machine for the precise brewing temperature and weight control interfacing with mobile device.

POS System

2018

- Developed POS (Point Of Sale) system for a coffee shop
- Mobile Device APP connected in the web server

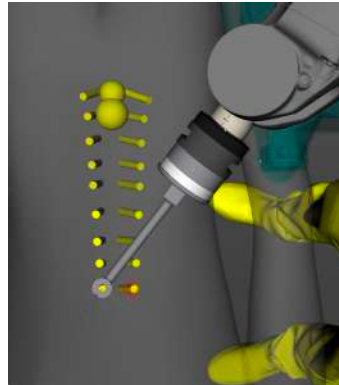
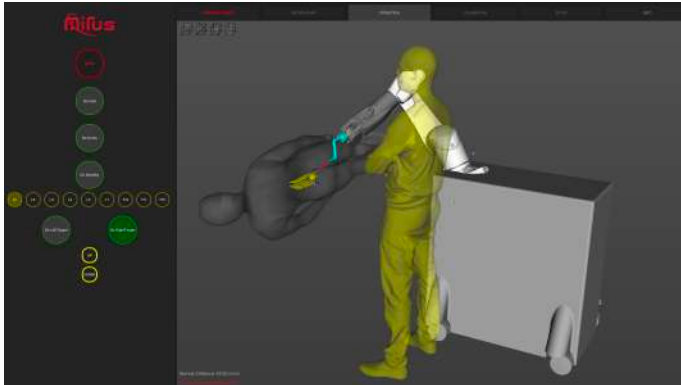
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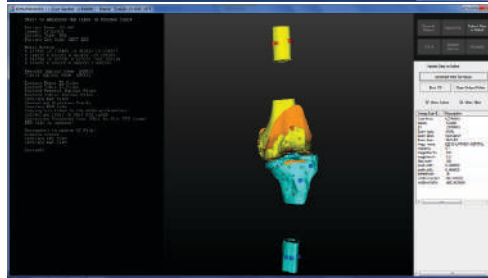
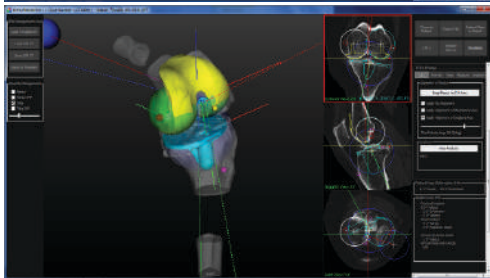
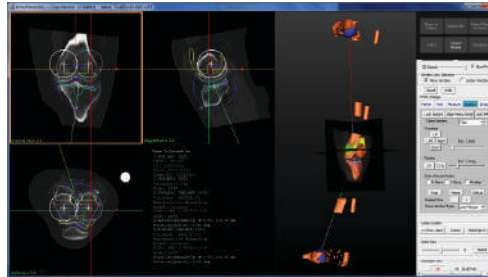
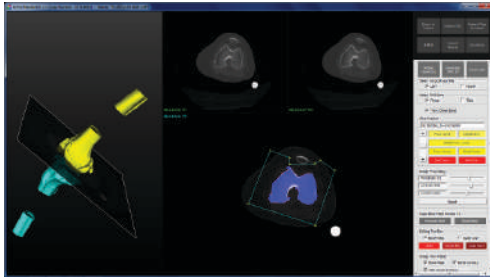
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S/W SCREEN SHOT

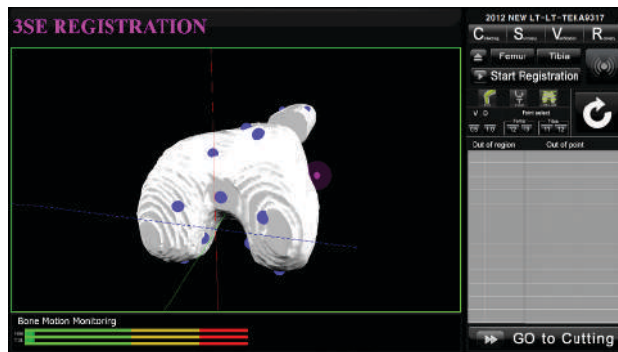
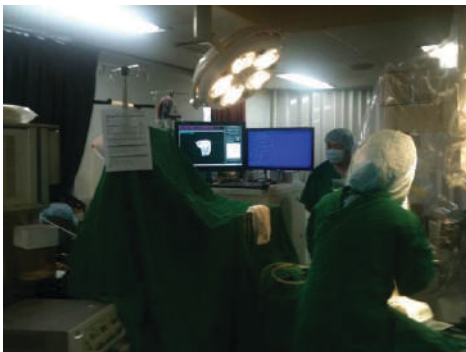
MirusRobotPlanner with Staubli Robot - 2020



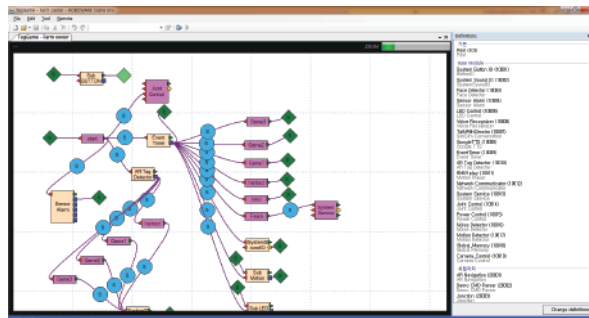
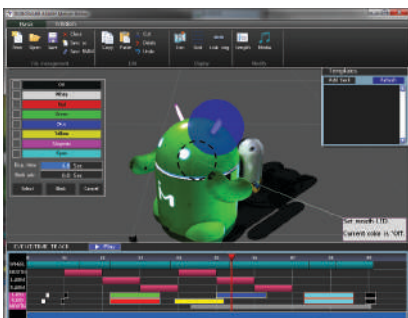
Orthoplanner S/W for Knee Replacement Surgery - 2016



3D Registration for RoboDoc- 2013



Scenario Editor for Robot - 2012



YOUTUBE LINK



KIMI - 2013

<http://www.youtube.com/watch?v=0g1nnFoLKEU>

<http://www.youtube.com/watch?v=GzFPysSzje4&feature=youtu.be>

<http://youtu.be/BBpelHrJ8Fc>

OMNI BASE - 2012

<http://www.youtube.com/watch?v=fFpV15BbvQ0>

<http://www.youtube.com/watch?v=RSochyYrEw8>



KIBOT2 - 2012

<http://www.youtube.com/watch?v=nFMrh2v6Yks>



KIBOT1 - 2011

<http://www.youtube.com/watch?v=cIQ81Ap7-mU>



ENGKEY - 2011

<http://www.youtube.com/watch?v=SOBTSp-UIKs>

<http://www.youtube.com/watch?v=csL-c3KP2OQ>

http://youtu.be/wM09lb4_RNU

<https://www.youtube.com/watch?v=PhmDkQizZSg>



E3 ROMA - 2008

<http://www.youtube.com/watch?v=FwDYV-0zB-w>

<http://www.youtube.com/watch?v=22FGdLgvd4>