# Michael Elliot King

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### Education

2009 - 2014 B.Eng., Mechanical Engineering

McGill University - Montreal, Quebec

## Relevant Experience

## 8/2013 - 8/2014 Co-Founder & Mechanical Engineering Lead ~

McGill Robotics - A.U.V. Design Team - Montreal, Quebec

3rd place static, 10th place overall - AUVSI International RoboSub Competition in San Diego - July 2014

- Created and implemented a comprehensive team structure, brand strategy, work environment, and management system for a student organization with 98 members
- Lead all mechanical design, manufacturing, implementation, and testing for the team of 60 developing an autonomous underwater vehicle from scratch
- Designed the vehicle assembly with Inventor for FEA, dynamic modeling, 3D printing, machine drawings

#### 9/2013 - 7/2014 Development of a Variable-Friction Shoe-Surface Mechanism $\leadsto$

Independent Interdisciplinary Design Project - Montreal, Quebec

- Created from scratch a mechanism to fit in the sole of a shoe and dynamically simulate the friction of a full range of surfaces
- Designed the mechanical, electrical and software systems using Inventor and Arduino
- Manufactured complete functioning prototype of mechanism to 0.05mm tolerances using conventional milling  $\dot{\sigma}$  turning, CNCing, and welding
- Implemented a PD controller to actuate two compact braking pads using a stepper motor, gear system, and lead screws

## 9/2013 - 5/2014 Development of the Propulsion & Control System for an A.U.V. $\leadsto$

Mechanical Engineering Senior Capstone Project – Montreal, Quebec

- Designed and simulated a 5-DOF propulsion and control system using C++ and ROS
- Implemented the system by interfacing with the planner, computer vision, and motor control

#### 8/2012 - 8/2013 MATERIAL COLLECTION SYSTEM LEADER | MARKETING & MEDIA DIRECTOR $\leadsto$

McGill LunarEx Robotics Design Team - Montreal, Quebec

Placed 12th out of 50 international teams at NASA's Lunabotics Mining Competition in Orlando, Florida

- Lead the efforts of a five person group responsible for designing, manufacturing and assembling the mechanism that collects and dumps lunar regolith simulant
- Brought original concepts to realization through CADing, machining, assembly, and testing
- Developed rebranding strategies to increase interest in robotics and team credibility

# Software & Programming Skills

Computer Aided Design: Inventor, Solidworks, AutoCAD

Data Analysis: MATLAB, Excel

Programming Languages: Python, C, C++, Objective-C, ROS

Version Control Systems: Git, Autodesk 360

Web Development: HTML5, CSS, Markdown, Jekyll, Google Analytics, SEO Media & Graphics: Illustrator, Lightroom, Photoshop, InDesign, Final Cut Pro

Last updated October 7, 2014 • For the most recent version, see michaelelliotking.com/resume