

Recap

A : input space

B : data space

$F: A \rightarrow B$ (linear)

$$\text{IP: } b = Fa^+ + \varepsilon \quad \leadsto \quad a^+$$

F : $+ / \int$ \checkmark

F^{-1} : $- / \frac{d}{dx}$ \times

Naive approach:

$$a_{\text{rec}} = F^{-1}b = \dots = a^+ + F^{-1}\varepsilon \quad (F a_{\text{rec}} = b)$$

2. Classical approaches: regularization

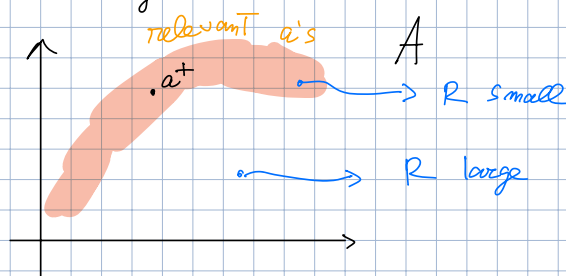
\rightarrow is relaxed

$$a_{\text{rec}} = \underset{a}{\operatorname{argmin}} \quad \frac{1}{2} \|Fa - b\|^2 + \lambda R(a)$$

$Fa \approx b$ fidelity Term \uparrow penalty Term \uparrow regularization parameter

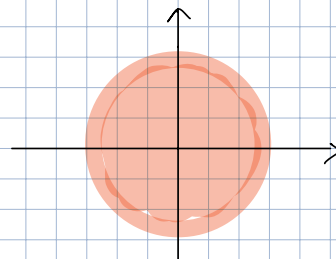
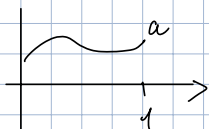
$\lambda = \lambda(\|\varepsilon\|)$

where $R: A \rightarrow [0, +\infty]$ is the **REGULARISER**, which should promote a priori knowledge on a^+ .



Examples

- $R(a) = \frac{1}{2} \|a\|^2$ Tikhonov reg.

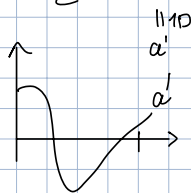


exercise:

$$a_{\text{rec}} = (F^T F + \lambda I)^{-1} F^T b \quad \left(\begin{smallmatrix} \lambda=0 \\ = (F^T F)^{-1} F^T b \end{smallmatrix} \right)$$

$$= \sum_j \frac{\sigma_j}{\sigma_j^2 + \lambda} \langle b, b_j \rangle a_j$$

• $R(a) = \frac{1}{2} \|\nabla a\|^2$

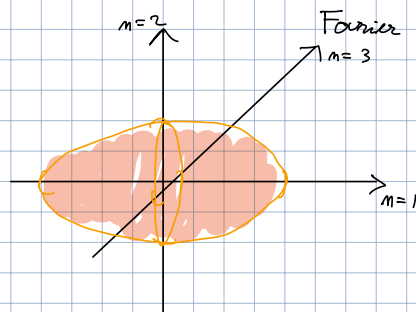


$a' \leftrightarrow n \cdot \hat{a}(n)$

Sobolev reg.

Gen. Tikh. reg.

smoothness promoted



Regularization Theory:

$\lambda = \lambda(\|\varepsilon\|) \Rightarrow \|a^* - a_{\text{rec}}^{\lambda}\| \leq \sigma(\|\varepsilon\|)$

• $R(a) = \|\Phi a\|_0$

where $\|x\|_0 = \#\{i=1 \dots m: x_i \neq 0\}$

$\Phi: \mathbb{R}^n \rightarrow \mathbb{R}^m$

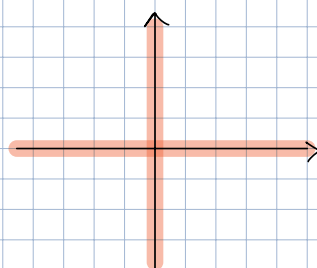
"change of basis"

e.g. $\Phi = I$

$\|\Phi a\|_0$ is relaxed to

$R(a) = \|\Phi a\|_1$

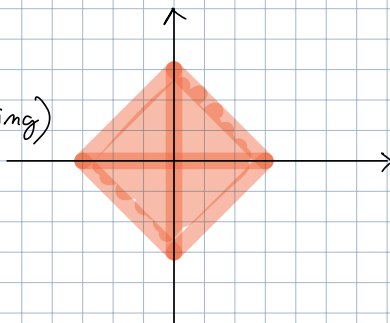
(Basis pursuit - compressed sensing)



$m=2$

$\|\Phi a\|_0 \leq 1$

→ 1-sparse vectors



$a_{\text{rec}} = \underset{a}{\operatorname{argmin}} \frac{1}{2} \|Fa - b\|^2 + \lambda \|\Phi a\|_1$

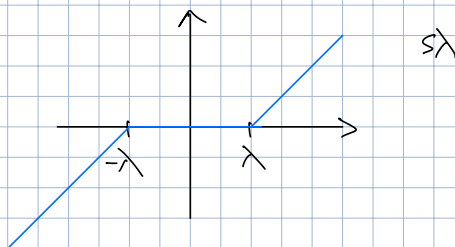
Proximal gradient descent: ($\Phi^T \Phi = \mathbf{I}$)

$$a_0 = 0$$

$$a_{j+1} = S_{\Phi, \lambda} \left(a_j - \underset{\text{step size}}{\gamma} \Phi^T (\Phi a_j - b) \right)$$

stop a_K

where $S_{\Phi, \lambda} = \Phi^T S_{\lambda} \Phi$, S_{λ} is the soft-thresholding operator: acting componentwise



$S_{\Phi, \lambda}$ is the PROXIMAL OPERATOR:

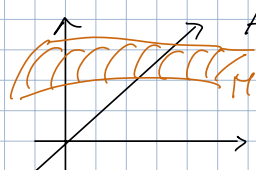
$$S_{\Phi, \lambda} = \text{prox}_{\gamma \lambda \|\Phi \cdot\|_1} / \quad \text{prox}_f(a) = \underset{x}{\operatorname{argmin}} \frac{1}{2} \|\mathbf{I}x - a\|^2 + f(x)$$

denoising problem

• $R(a) = \|\nabla a\|_1$ TOTAL VARIATION (TV)

sparse gradient \leadsto promotes piecewise-constant signals

$$R(a) = \begin{cases} 0 & a \in \mathcal{M} \subseteq \mathcal{A} \\ +\infty & a \notin \mathcal{M} \end{cases}$$



"manifold hypothesis"