

# Precision Temperature Control

An Arduino-Based System for Engineering Students

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For Engineering Students

Mechanical Engineering, Electrical Engineering • Applied Physics

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# Why Master Temperature Control? Applications in Research and Industry

## Criticality in Engineering Research

Many experiments—chemical reactions, material testing, biological incubators—require precise, stable temperature environments for reproducible results.

## Industrial Relevance

Temperature control is the backbone of HVAC systems, process automation, data center cooling, and smart manufacturing ecosystems.

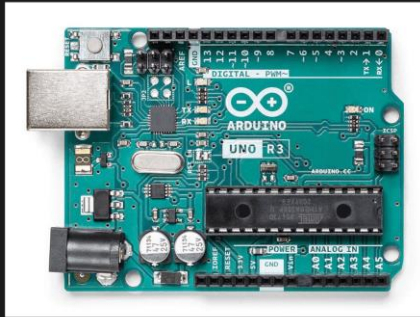
## System Overview

This project demonstrates a simple ON/OFF (Bang-Bang) control system using three core components: Sensing (LM35), Processing (Arduino Uno), and Actuation (Relay).

## Learning Outcome

Students gain hands-on experience in analog signal processing, digital control logic, and interfacing high-power loads with microcontrollers.

# The Arduino Uno: Bridging the Physical and Digital Worlds



## Microcontroller

Based on the **ATmega328P**, operating at 5V logic. It is the processing unit that executes the control algorithm.

## Analog Input Pins (A0–A5)

Essential for reading the continuous voltage signal from the LM35 sensor with high precision.

## Digital I/O Pins (D0–D13)

Used to send a simple ON/OFF signal to the relay module (specifically **D7** in this project).

## 10-Bit ADC Resolution

Provides **1024 discrete levels** (0 to 1023) for a 0V to 5V input range, crucial for temperature accuracy ( $\sim 0.49^{\circ}\text{C}$  resolution).

## LM35: Linear, Calibrated, and Ready-to-Use Temperature Sensing

### Precision IC Sensor

Unlike non-linear thermistors, the LM35 is a precision integrated-circuit sensor that outputs a voltage directly proportional to temperature.

### Linear Scale Factor

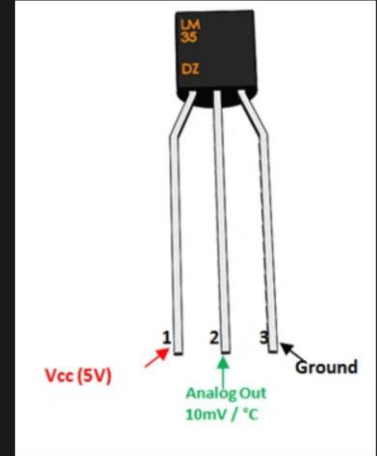
The sensor provides a linear output of **10 mV per degree Celsius (10mV/°C)**. This simplifies the conversion code significantly.

### Operating Range

Capable of measuring temperatures from **-55°C to 150°C**, covering most common lab and industrial environments.

### Simple Interface

Connects to the Arduino's **Analog Pin A0**. The three-pin interface (VCC, GND, OUT) requires no external calibration or signal conditioning.



# The Relay Module: Safely Controlling High-Power Loads

## Function

An electrically operated switch that allows the low-power Arduino (5V, ~20mA) to control high-power AC or DC loads (e.g., 240V AC, 10A).

## Electrical Isolation

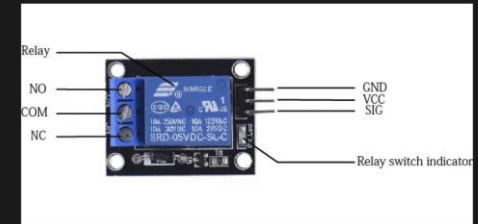
The module includes an **optocoupler**, providing complete electrical separation between the sensitive Arduino circuit and the high-voltage load circuit, ensuring safety.

## Active-LOW Trigger

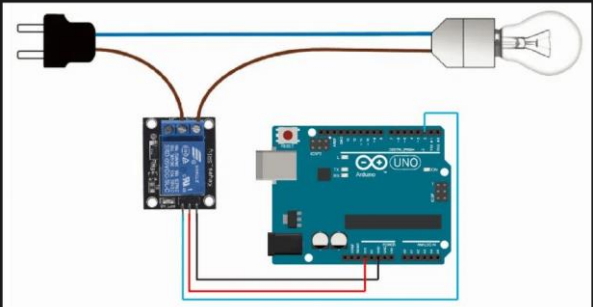
Most Arduino-compatible relays are **Active-LOW**, meaning the relay is activated (switches ON) when the Arduino pin (D7) is set to **LOW (0V)**.

## Terminal Configuration

The load is connected to the **Common (COM)** and **Normally Open (NO)** terminals, ensuring the load is OFF by default (fail-safe).



# Interconnection: Mapping Components to the Arduino Uno



## Connection Specifications

| Component    | Pin | Connection  | Function                  |
|--------------|-----|-------------|---------------------------|
| LM35 Sensor  | OUT | Arduino A0  | Analog Temperature Signal |
| Relay Module | IN  | Arduino D7  | Digital Control Signal    |
| LM35/Relay   | VCC | Arduino 5V  | Power Supply              |
| LM35/Relay   | GND | Arduino GND | Ground Reference          |

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# From Raw ADC Value to Calibrated Temperature (°C)

## ① ADC Reading

The Arduino reads a raw value (`analogValue`) between 0 and 1023 from analog pin A0.

## ② Voltage Conversion

The voltage output by the LM35 is calculated using:

$$\text{Voltage (V)} = (\text{analogValue} / 1024) \times 5.0$$

This converts the discrete ADC value to a continuous voltage between 0V and 5V.

## ③ Temperature Conversion

Since the LM35 has a scale factor of 10 mV/°C (or 0.01 V/°C), the temperature is:

$$\text{Temperature (°C)} = \text{Voltage (V)} / 0.01$$

Dividing by the scale factor converts voltage directly to degrees Celsius.

## ④ System Resolution

The system's theoretical resolution is approximately 0.49°C per ADC step, calculated as:

$$\text{Resolution} = (5000 \text{ mV} / 1024) / 10 \text{ mV/°C} \approx 0.49\text{°C}$$

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# The Control Algorithm: Simple Threshold-Based Switching

1

## Set Point (Threshold)

A desired temperature (`setPoint`) is defined in the code (e.g., 30°C). This is the target temperature the system aims to maintain.

2

## Control Loop

The system continuously compares the measured temperature (`currentTemp`) with the `setPoint` in the main Arduino loop, executing thousands of times per second.

3

## Cooling Logic (Example)

If the system is controlling a cooling fan:

```
IF currentTemp > setPoint, THEN activate relay (set D7 LOW) → turn fan ON  
ELSE (if currentTemp ≤ setPoint), THEN deactivate relay (set D7 HIGH) → turn fan OFF
```

4

## Code Structure

The logic is implemented within the Arduino `loop()` function, ensuring continuous monitoring and rapid response to temperature changes.



# Hysteresis: Ensuring System Stability and Component Longevity

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## The Problem of Chattering

Without hysteresis, if the temperature hovers at the **setPoint** (e.g., 30.0°C), the relay can **rapidly switch ON and OFF** as tiny fluctuations occur — this is called **"chattering."**

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## The Solution: Hysteresis Band

Introduce a **Hysteresis Band** (e.g.,  $\pm 1.0^\circ\text{C}$ ) to create two thresholds and prevent rapid switching:

**Turn ON Threshold:**  $\text{setPoint} + \text{Hysteresis}$  (e.g.,  $31.0^\circ\text{C}$ )

**Turn OFF Threshold:**  $\text{setPoint} - \text{Hysteresis}$  (e.g.,  $29.0^\circ\text{C}$ )

③

## Improved Control Logic

The fan turns **ON only when temperature exceeds  $31.0^\circ\text{C}$**  and stays ON until it drops below  $29.0^\circ\text{C}$ , creating a  **$2^\circ\text{C}$  dead band** where the relay is stable.

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## Benefits: Stability and Longevity

- **Reduced Wear:** Eliminates rapid relay switching, extending lifespan.
- **System Stability:** Prevents oscillation and ensures smooth operation.
- **Energy Efficiency:** Fewer actuations lower power use.
- **Fundamental Principle:** Hysteresis is core to many control systems.

# Building the System: From Breadboard to Working Prototype

1

## Hardware Assembly

Securely connect all components on a breadboard or custom PCB according to the wiring diagram.

LM35 sensor → Arduino [A0](#)

Relay module → Arduino [D7](#)

Power and ground connections verified

2

## Software Setup

Install the Arduino IDE and upload the provided code to the Arduino Uno.

Download [temperature\\_controller.ino](#)

Connect Arduino via USB cable

Select correct board and COM port in IDE

Click Upload to program the device

3

## Configuration

Modify the code variables to match your experimental requirements.

Set [setPoint](#) (target temperature)

Define [Hysteresis](#) band ( $\pm 1.0^{\circ}\text{C}$  typical)

Adjust relay trigger logic if needed

Re-upload modified code to Arduino

4

## Testing & Debugging

Verify system operation and validate threshold behavior.

Open Arduino [Serial Monitor](#) (9600 baud)

Observe real-time temperature readings

Verify relay clicks at upper/lower thresholds

Connect load device to relay terminals

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## Future Enhancements: Moving Towards Advanced Control

### ① User Interface Enhancement

Integrate an [LCD or OLED display](#) to show real-time temperature and set point without relying on the Serial Monitor. This enables standalone operation and provides immediate visual feedback to users in the field.

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### ② Wireless Monitoring & Control

Add a [Wi-Fi \(ESP8266\) or Bluetooth module](#) to log data and allow remote monitoring/control via a web dashboard or mobile app. Enable real-time alerts and historical data analysis for long-term trend monitoring.

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### ③ Advanced Control Algorithm

Replace the simple ON/OFF (Bang-Bang) logic with a [PID \(Proportional-Integral-Derivative\) controller](#) for much smoother, more precise, and faster temperature regulation. PID eliminates overshoot and reduces settling time significantly.

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### ④ Data Logging & Analysis

Implement [SD card logging](#) to record temperature data over long periods for experimental analysis. Enable post-processing of data for statistical analysis, trend detection, and system performance validation.

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# Summary: A Foundation in Applied Control Systems

## Achieved Goal

Successfully designed and understood a **functional, safe, and stable temperature control system** using low-cost, open-source components. This system demonstrates the fundamental principles of embedded systems, sensor integration, and real-world control applications.

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## Key Takeaways

- **Converting raw ADC values** to meaningful physical quantities (temperature) requires understanding of sensor specifications and mathematical conversion.
- **Digital Actuation:** Microcontrollers can safely control high-power loads through relay modules with electrical isolation, enabling practical real-world applications.
- **Hysteresis in Control:** Introducing a dead band around the set point prevents system instability and component wear—a critical concept in all control systems.

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## Next Challenge: PID Control

Apply the **PID (Proportional-Integral-Derivative) control algorithm** to this system to achieve professional-grade temperature stability. PID control provides smoother regulation, faster response times, and better handling of disturbances compared to bang-bang control.

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## Resources & References

The full code, wiring diagram, component specifications, and documentation are available on the **original GitHub repository**: [github.com/mikelix/arduino-temperature-controller](https://github.com/mikelix/arduino-temperature-controller). Additional resources include Arduino IDE docs, the LM35 datasheet, relay module specs, and PID tutorials for further study.

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## Questions & Discussion