

# Photoacoustic observation of O<sub>2</sub> absorption peaks at visible frequencies.

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## Abstract

This report presents our final experience for the course of Experimental Physics (advanced), held by prof. M. Scotoni, University of Trento, during academic year 2012/13.

The task was to observe at least one line in the visible part of the absorption spectrum of  $O_2$  at ambient conditions, using the photoacoustic effect. As a starting point, we have been given a photoacoustic chamber and a red laser diode to excite the oxygen with, together with a case and a controller to adjust the diode temperature and driving current.

The report will begin with a brief introduction to the principles of photoacoustics. In Chapter 1 the apparatus and the measurement instruments are globally described, while in Chapter 2 we expose some solutions to optimize the apparatus for the measurement we needed to do, as well as some issues we encountered in setting up the most delicate parts.

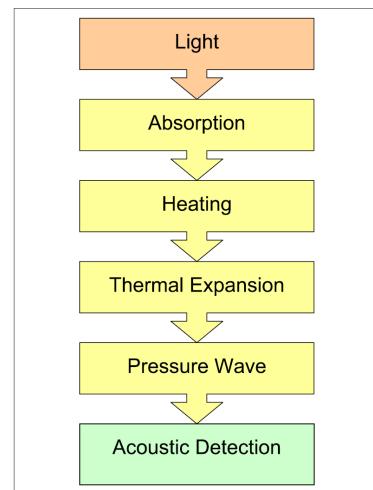
In Chapter 3 the collected measurements are presented and discussed. Section 3.2 deals with the search of the chamber resonance, Section 3.3 with the search of the oxygen peaks. Section 3.4 is about the actual observation of the peaks and the study of their shape. Section 3.5 contains a small analysis we did on the behaviour of the laser diode. The results in there are important to understand where some effects we encountered across all the previous sections come from.

Appendices A to C are intended to provide a basic theoretical background about three key elements of our apparatus: the ECDL, the lock-in and the etalon.

# Introduction to photoacoustics

In order to detect the absorption lines of O<sub>2</sub> in the visible region, we did a photoacoustic measurement. This kind of measurement turns useful every time one is interested in the absorption properties of a gas, but the absorption is too weak to be detected via a standard measurement. This can happen because the pressure of the studied gas is very low, or because it is very diluted into a mix of other gases, or just because the gas has a very poor response to a certain frequency stimulation, which is the case of the oxygen at visible frequencies. A standard measurement of absorbance is basically just a difference between the intensity of the impinging light and that of the light passed through the gas, so that one can account for the photons which were absorbed by looking how much light fails to exit the champion.

Photoacoustics exploits a different mechanism (Fig. 1), as it considers directly the effect the absorbed light has on the gas. In fact, the photons absorbed by the gas molecules excite electronic or vibronic modes (depending on the frequency). Apart for the case of fluorescence or phosphorescence (phenomena which usually happen exciting atomic modes and not molecular ones), the excited molecules subsequently relax, releasing their energy in form of heat. This leads to a pressure increase in the gas. If the exciting light is modulated in frequency, which is the case for a laser passing through a chopper, one gets the pressure to increase and decrease at the chopping frequency, which means a sound wave is generated that can be detected by a microphone. To enhance the signal, the chopping usually happens at the first longitudinal resonant frequency of the chamber, so that the maximum acoustic signal is found in the center. Incidentally, the chopper modulation allows also the exploitation of a lock-in amplifier, which further improves the sensibility of this configuration to small absorption signals.



**Figure 1:** Steps of a photoacoustic measurement.

# Chapter 1

## Description of the apparatus

### 1.1 General overview

The setup we used featured the typical photoacoustic experiment characteristics. There was a source of light, a laser in our case, impinging on the gas into a cavity. A mechanical chopper provided a modulation of the light in order to match a proper frequency of the cavity. The acoustic signal, detected by microphones, was filtered by a lock-in amplifier referenced with the chopping frequency. The light path was controlled through optical elements such as mirrors, lenses and beam-splitters (Fig. 1.1).

The laboratory instrumentation shown in Fig. 1.2 was used to take measurements and drive the various devices. Other elements we used include:

- $\pm 15$  V power supplier for the microphones
- membrane vacuum pump
- rubber pipes and valves to control the gas flow.

The data series were acquired with a computer, via a dynamic signal acquisition module<sup>1</sup>, running the following software:

- *Avasoft*<sup>©</sup> by Avantes, the software provided along with the Avaspec spectrometer
- *Signal Express*<sup>TM</sup> by labVIEW<sup>TM</sup>
- *Spectrum*, a labVIEW<sup>TM</sup> virtual instrument installed on the laboratory PCs.

We shall now describe in more details the core elements of the apparatus.

### 1.2 Laser source

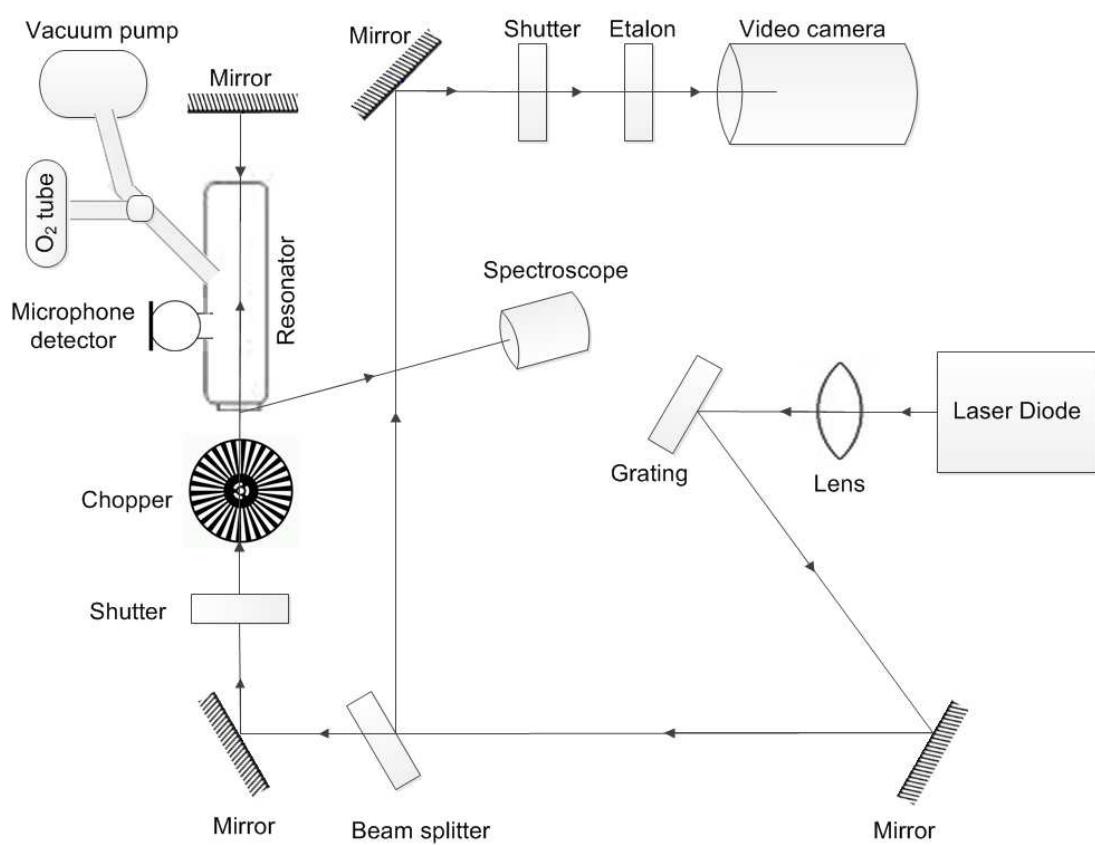
We used an external cavity laser device, formed by the following elements:

- a single mode multi-quantum well AlGaInP laser diode<sup>2</sup>. The lasing wavelength

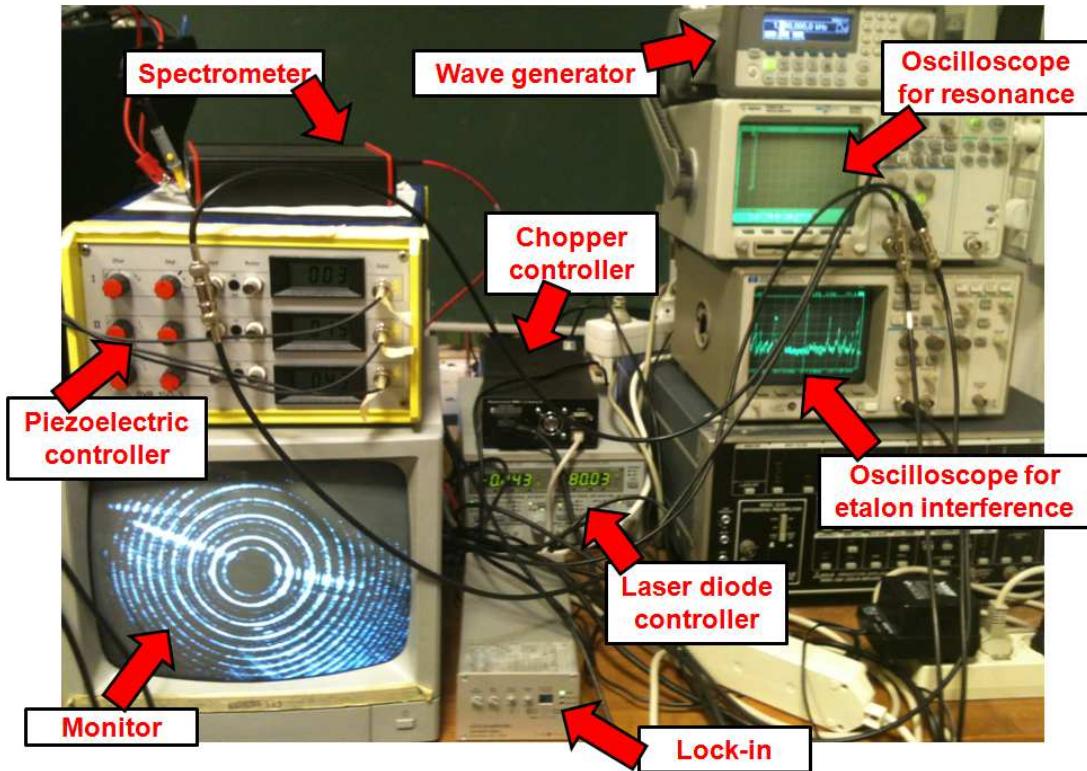
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<sup>1</sup>National Instrument PCI-4462: <http://www.ni.com/pdf/manuals/373770j.pdf>

<sup>2</sup>Hitachi HL6738MG: [http://pdf.datasheetcatalog.com/datasheets/50/502031\\_DS.pdf](http://pdf.datasheetcatalog.com/datasheets/50/502031_DS.pdf)



**Figure 1.1:** Diagram of the experimental apparatus.



**Figure 1.2:** Electronic instrumentation used to control the apparatus.

could be tuned from about 680 nm to 695 nm by adjusting the driving current and the diode temperature.

- a temperature controller case<sup>3</sup> to set the temperature of the diode.
- an external cavity, i.e. a setup that feeds back the laser diode with the first diffraction order of a 1800 grooves/mm grating. Namely, we implemented the so called Littrow configuration (Appendix A.3). The external cavity allowed us to better select a given lasing mode, thus getting a smaller emission linewidth. The grating was put on a piezoelectric mechanical actuator<sup>4</sup>, which permitted nm-order adjustments of its position. Since a grating diffracts different frequencies at different angles, moving the grating we could control the frequency fed back to the laser and thus enhanced. This is how we got a fine tuning of the frequency, and how we were able to make the 2-3 GHz scan to see the absorption line (more on this in Section 2.3).

<sup>3</sup>Thorlabs TCLDM9: <http://www.thorlabs.de/Thorcat/1900/TCLDM9-Manual.pdf>

<sup>4</sup>Thorlabs KC1-T-PZ/M: [http://www.thorlabs.de/Thorcat/2400/KC1-T-PZ\\_M-AutoCADPDF.pdf](http://www.thorlabs.de/Thorcat/2400/KC1-T-PZ_M-AutoCADPDF.pdf)

### 1.3 Acoustic chamber

The gas to analyze, pure O<sub>2</sub> at atmospheric pressure, was contained in a brass chamber, featuring :

- an internal cavity, about 10 cm long, where the gas actually resonated. Other two smaller cavities, half as long, were present before and after the main cavity. Since we couldn't open the brass chamber, we had no way to accurately measure the dimensions and the position of the main cavity with respect to the other two ones. It should be noticed that our chamber had been recycled from another experiment and was not explicitly thought for the usage we do of it
- four microphones put about halfway in the chamber, one for each side of it. Due to the fact that the chamber couldn't be opened, we don't know whether the microphones were actually halfway. Anyway a possible misplacement would not affect the validity of our measurement, as it would result just in a less intense signal
- an active strain gauge vacuometer<sup>5</sup> to measure the pressure in the chamber.

### 1.4 Reference arm

Once generated in the ECDL, the laser beam was split by a simple glass into two rays: one going through the chopper and entering the acoustic chamber, the other passing through an etalon. The interference pattern (see Appendix C) was monitored with a video camera. This was useful, since the the spectroscope resolution, as reported in Section 2.3, was too poor to detect the small laser frequency shifts due to fine tuning with the external cavity. The etalon instead could detect this shift as a variation of the diameter in the diffraction rings. Moreover, the PAL(Phase Alternating Line) analogic video signal could be observed with an oscilloscope as well, to get a quantitative measurement of the rings movements thanks to the measurement functions of the instrument. With respect to the spectroscope, also, the etalon allowed a clearer and faster detection of multi-mode emission

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<sup>5</sup>Edwards ASG-1000-NW16:

<http://www.ultimatevacuum.dk/D35725880%20ASG%20user%20manual.pdf>

## Chapter 2

# Experimental setup and hardware improvements

Most of our efforts during the experiment were due to the difficulty of finding strong and stable absorption peaks, and tuning our laser on such peaks. The issues encountered during this process can be grouped in these main categories:

1. aligning the grating and minimizing the laser sensitivity to environmental noise sources such as temperature variations and vibrations.
2. focusing the laser beam in the audio cavity without touching the walls.
3. controlling and measuring the laser frequency.

Understanding the behaviour of our apparatus under these aspects was important in order to face the main problem of distinguishing the shape of the absorption peaks from the actually measured peaks, as the latter were distorted by several factors such as mode-hopping and the low-pass filtering of the lock-in amplifier. The subject will be fully discussed in Section 3.4.1.

The following sections of this chapter will describe how we faced the previously listed experimental challenges.

### 2.1 Building and optimizing the external cavity laser

The external laser cavity was described in Section 1.2, while the some theoretical principles about the Littrow configuration ECDL are lined up in Appendix A.3. Optimizing this part of apparatus was one of the tasks that required more attention. We ended up in developing the following ideas.

- We put the grating as near as possible to the laser diode, in order to minimize the sensitivity of the cavity to external factors such as vibrations and cavity length changes due to temperature fluctuations.

- In order to align as much as possible the first order reflection beam back in the laser, we set the laser current under the original threshold current, i.e. the threshold current it would have without any external cavity, and adjusted the micrometric screws until we had laser emission at the lower threshold current possible. This procedure also allowed us to obtain the maximum optical power output from the laser (finally we got about 12 mW entering the chamber).
- During the early development of the experimental apparatus the convergent lens included in the LD case was a bit misplaced, so the outgoing beam was not parallel. We didn't know the case could be opened, and we thought we would have had to deal with the beam as it was. Thus we added a small divergent lens between the laser and the grating, in order to make the beam as parallel as possible. This was intended to avoid power losses in the feedback beam and loss of resolution of the grating. (The one-to-one correspondence between angle and diffracted frequency, described in Appendix A.2, is valid only for a parallel incident wave). Plus we added several other lenses in various points of the apparatus to focus the light and make it parallel. Only later we discovered the possibility of adjusting the position of the first lens (that internal to the case). Fixing that one made unnecessary any other lens in the apparatus.

## 2.2 Focusing the laser in the acoustic chamber

The laser beam was not allowed to touch the walls of the chamber, otherwise it would be partially absorbed by them heating up the chamber instead of the gas. This of course could spoil the measurement, generating signal far from the actual absorption wavelength of the oxygen. To avoid this, it was important to perfectly align the beam into the chamber, as well as to make it parallel to avoid divergence. Moreover, since the beam had not a circular section, we used a slit to cut the sides, which could more easily hit the walls. The price was a loss of optical power, of course, but it was worth it to minimize the risk of touching walls.

In order to maximize the measured signal we also put a mirror after the chamber which reflected the beam back into the chamber. The alignment of the backwards beam was even more tricky: if we directed it back exactly on the same path of the first beam, it would return into the laser and the whole optical path would act as a second, much longer external cavity. In fact, the two interfered leading to uncontrollable suppression or enhancement of the optical power, as well as driving the laser out of its current lasing mode. To use also the secondary beam, then, it was necessary to align it in such a way that neither did it diverge or touch the walls of the chamber, nor did it collimate with the incoming beam.

## 2.3 Tuning the laser emission

Let's define the *piezoelectric tunability*, to indicate how much we could tune the output frequency of our ECDL by moving the piezoelectric actuators without having the laser to change mode (mode hopping was a serious issue we faced). In order to measure this factor the wavelength resolution of the spectrometer was not sufficient, so we used the etalon combined with the video camera, as described in Section 1.4. Then we made the measurement according to the following procedure:

1. We measured the distance, in ns of the PAL signal, between the first and the second emission orders (rings) of a mode. This is proportional to the free spectral range (FSR) of the etalon, defined in Appendix C.3.
2. We moved the piezoelectric actuators of the maximum amount possible without changing mode, and measured the shift in the position of the first order ring between the two extremal configurations.
3. Comparing this position shift with the FSR, we were able to estimate the piezoelectric tunability.

The estimation we found depended on the laser mode we were trying to tune, and ranged from about 2 to 3.5 GHz. The uncertainty was of about 1 GHz estimated from the etalon diffraction peak width. The importance of this value is readily understood if we compare it to the bandwidth of the oxygen peaks we are going to measure, which is of the order of 10 GHz. The conclusion we get is that it is impossible to scan a whole peak keeping fixed the laser mode, whence the importance that is assumed by the study of the peaks shape, carried out in Section 3.4.

During these measurements we noticed also that the width of the diffraction peaks emitted by the etalon do not correspond to the theoretical 250 MHz calculated from the etalon specifications, but rather to a FWHM of approximately 1-3 GHz (almost the same as the piezoelectric tunability). Several factors could contribute to broaden the width of the peak beyond the original declared performance of the etalon. They are hereafter exposed in order of the importance we assigned to them.

1. The resolution of the camera (the time resolution of the oscilloscope is negligible with respect to the actual width of the ring visualized).
2. The part of the circle we look at (as can be seen by Fig. C.2 the width of the interference pattern is noisy, thus not perfectly constant around the circle).
3. Dirt and imperfections on the etalon surface.
4. Misalignment and divergence of the impinging beam. An ideal etalon produces zero-width lines only when illuminated by a non-diverging beam.

5. The output bandwidth of the laser, some tens of MHz after having been tuned with a ECDL.
6. The error in choosing what pixel line to take for the measurement. We could observe only one horizontal line of the screen for each measurement. Any pixel line which is not exactly lying on the diameter of the diffraction ring would bring a larger white (illuminated) portion than the actual minimum width.

As anticipated before, in controlling the laser emission with the ECDL we faced some big issues with instability and mode hopping. Probably they were due to imperfections in the Littrow configuration ECDL. In principle, the grating should be set in such a way that, by moving the piezoelectric actuators, it only undergoes a rotation without changing the position of the point where the light impinges on it (which actually neither is a point, as a real diode emission has always an extended shape).

If the aforementioned condition is not fulfilled, that is, if the point where the light hits the grating doesn't lie on the axis of the rotation, then a movement in the actuators causes not only a rotation, i.e. a change in the frequency that is fed back to the laser diode, but also a variation in the length of the external cavity. This length variation had on the output frequency a much bigger effect than the rotation itself.

## Chapter 3

# Measurements and results

### 3.1 General remarks

A photoacoustic measurement requires a chopper to modulate the incoming laser at the longitudinal resonance frequency of the chamber, in order to maximize the signal measured by the microphones.

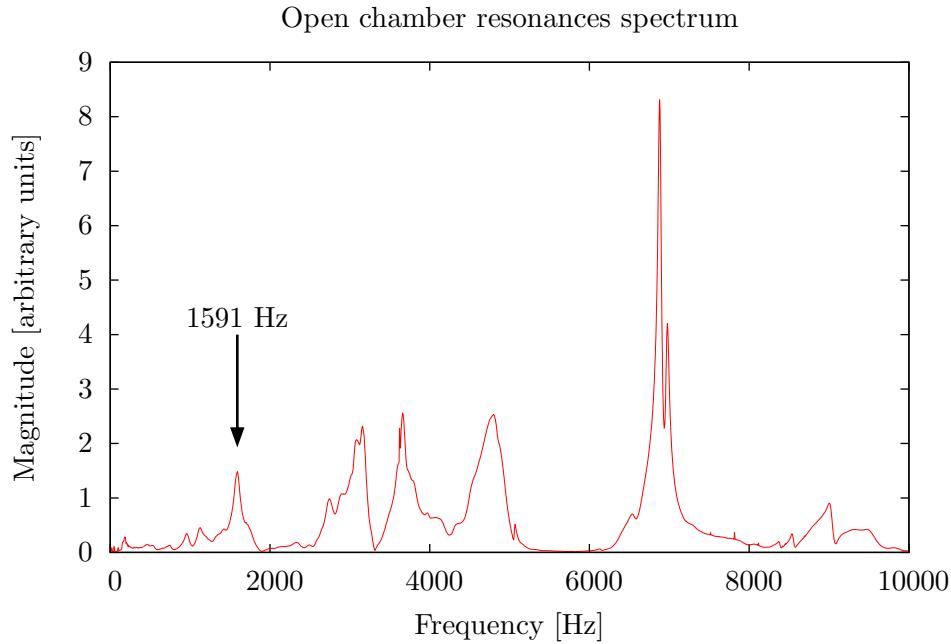
About the microphones, it should be noticed that we didn't know their gain, neither it was possible with our instruments to make a calibration curve. In addition, we thought that understanding in deep the complicated, though interesting, physical processes between the photon absorption and the acoustic wave generation was too far from the general purpose of this work. This implies that, throughout this report, the absorption magnitude signals won't be reported neither with the dimensions of gas absorbance neither with the mechanical dimensions of sound waves. Instead they will be reported in volts, that is, the true (amplified) microphone output that entered the lock-in amplifier. This choice, instead of just using arbitrary units, at least allows us to compare results from different measurements, or even compare our data with those from other groups that used our very same microphones.

### 3.2 Finding chamber resonances

The first step of the measurement session was dedicated to find the best resonant frequency. We were told about an approximated length of the internal chamber of 10 cm, hence we expected the first resonating longitudinal mode to be a  $\simeq 20$  cm long wave. Considering the chamber full of atmospheric pressure O<sub>2</sub> at room temperature, with sound speed 326 m/s this corresponds to a frequency of 1630 Hz.

#### 3.2.1 Open chamber measurement

We did the measurement stimulating the air inside the chamber through a speaker connected to a waveform generator, and looking at the signal coming from microphones.



**Figure 3.1:** Spectrum of the open chamber, excited with a loudspeaker. The magnitude is set in arbitrary units because this spectrum has been acquired by a software whose unity conversion settings we couldn't control.

Since we were not able to insert a speaker inside the chamber (this was small), we excited the open chamber from outside through a hole. The resulting spectrum is shown in Fig. 3.1. In doing this, we differ from the true experimental conditions in three aspects:

- we have air instead of  $O_2$
- we have an open chamber instead of a closed one
- the wave signal coming from a small hole aside, instead of being generated in the middle of the chamber.

In principle it's easy to correct the spectrum taken in air, in order to apply it to oxygen: in first approximation one has to deal just with a different sound velocity. On the other side, it is more difficult to take into account the acoustic and dynamic modifications the chamber undergoes for being open or closed, as well as for the pressure wave to be originated from a lateral point instead of a diffused volume within the chamber. For these reasons, this cannot be considered as a true spectrum for the chamber we actually used in the absorption measurement. It is nothing more than a useful starting point. Eventually the real resonance frequency had to be experimentally determined with a closed chamber full of oxygen excited from the laser. Also the frequency response of both the loudspeaker and the microphones were unknown,

and this could in principle affect the shape of this plot. We looked in a range from 0 to 10 kHz, although we later observed that our chopper wouldn't be able to reach frequencies above few kHz.

We located a clear peak at 1591 Hz, which can be attributed to the first longitudinal mode of the chamber, assuming a length  $l$  of the chamber slightly greater than the declared 10 cm

$$l = \frac{343 \text{ m/s}}{1591 \text{ Hz}} \cdot \frac{1}{2} = 10.78 \text{ cm}$$

### 3.2.2 Closed chamber measurement

Starting from the open chamber datum, we injected O<sub>2</sub> in the chamber and began to look for signal by chopping the laser at 1591 Hz. It was promptly clear that there would not be need to further seek for resonances, as the intensity of the signal was high enough even at 1591 Hz, without any correction due to the gas change. We thus decided to delay the search for the acoustic resonance peak in oxygen and proceed with the experiment, in order to save time and give more attention to other issues such as stabilizing the laser emission or look for the oxygen absorption peaks.

Later, at the end of the experiment, we decided that completeness required us to provide the value of maximum resonance with oxygen, even though our measurement were all taken at 1591 Hz. Since the mechanical chopper failed to follow the waveform generator even for the slowest frequency sweep, we couldn't take a spectrum. Changing the frequency by hand we found however the peak at 1512 Hz, where we expected it according to a sound speed in atmospheric pressure oxygen of 323 m/s and a chamber length of 10.78 cm

$$f_{\text{O}_2}^{\text{PEAK}} = \frac{323 \text{ m/s}}{2 \cdot 10.78 \text{ cm}} \simeq 1512 \text{ Hz.}$$

## 3.3 Looking for the O<sub>2</sub> peaks

The next step after setting up and optimizing the apparatus was trying to find the best measurement conditions to see the peak. This means to find the frequency of the O<sub>2</sub> absorption peaks, trying the different acoustic resonance wavelengths and changing the laser parameters (current, temperature and position of our piezoelectric actuators). We were able to measure absorption at various different frequencies, listed in Table 3.1:

During these measurements we first noticed the instability of our laser emission in time. For example, when we found some peaks at a certain injection current, temperature and piezoelectric position, after some minutes that peak would drift away and we needed to change the piezoelectric position in order to find it again. After a longer time, like a couple of hours, the peak would decrease in intensity and eventually fade completely, forcing us to change temperature or current of the laser in order to

Wavelength [nm]
686.25
686.70
686.75
686.80
686.95
687.05
687.10
687.20
687.25
687.35
687.45

**Table 3.1:** Measured absorption wavelengths for O<sub>2</sub> at ambient pressure and temperature.

see it again (or to find some other peak). We are going to discuss more accurately this uncontrolled frequency evolution effect in Section 3.5.

### 3.4 Shape of the peaks

After having found some absorption peaks and approximately measured their wavelength using the spectrometer, we tried to acquire their shape as well. As seen in Section 1.2, the piezoelectric tunability was too narrow to acquire one whole peak, so it was important to understand which section of the peak we were looking at. This information allowed us to acquire different points of the same absorption peak, by slightly modifying the output frequency of the laser. The frequency instability in time of the laser output was the biggest deal in doing these measurements.

As explained in Section 3.4.1, the shape of the peaks was determined by many parameters. This means that we needed to control all of them (or at least the three most important) at the same time. To do this we used a computer, together with a data acquisition board exploiting four analog inputs, and we were able to log for every single measurement:

- the magnitude of the audio wave coming from the lock-in amplifier
- the position of the piezoelectric actuator responsible for the rotation of the grating around the  $z$  axis
- the wavelength of the highest laser peak, measured by the spectroscope software and converted to an analog signal through the integrated DAC
- the intensity of such peak or, depending on the needs, the ratio between the intensity of the peak and its integral (in order to detect multi-modal emission).

With this setup, the measurements were performed by sweeping the position of the piezoelectric actuators with the waveform generator. We split them in 3 sessions: single full sweeps, multiple full sweeps and multiple focused sweeps.

### 3.4.1 Factors influencing the shape of the peaks

Before discussing the procedures of measuring the shape of the absorption peaks, it was necessary to analyse which factors had influence on this shape in all the measurements we did. The most important ones were mode hopping, multi-mode emission and low-pass deformation, which are discussed in the subsequent paragraphs. Other factors such as

- variations in the speed of the chopper
- variations in the oxygen pressure and concentration
- sample rate of our instruments
- cables capacitance

should have been not relevant when compared to the first three factors.

#### Mode hopping

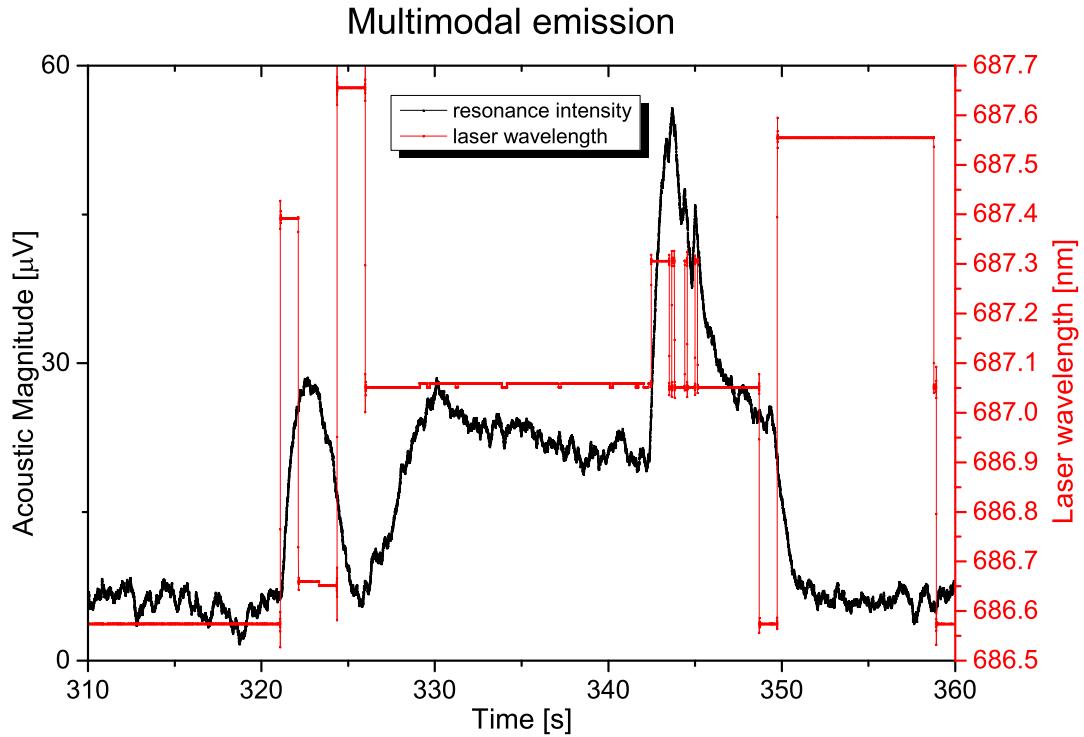
Mode hopping is the factor which most distorted the shape of the measured peaks, limiting us to see only a portion of them. As discussed in Section 2.3, the linear range of tunability we can exploit to scan the absorption peak is indeed smaller than the peak width. As the laser exits this interval, a mode jump happens, thus making the photoacoustic resonance to fade away. We got around this by logging the wavelength of the emission peak, measured with the spectrometer and calculated by the *Avaspec*© software in real time<sup>1</sup>. Superimposing this data to the acoustic magnitude ones, we could distinguish between the parts of the peaks which really corresponded to the absorption peak shape and the parts affected by mode-hopping.

#### Multi-mode emission

The ECDL didn't always emit light on a single wavelength, but often it would emit in 2 or 3, rarely on 4, different wavelengths at the same time. One or more of these emissions could correspond to one of the oxygen absorption lines, thus generating a measurable photoacoustic effect (Fig. 3.2). This situation rose the problem that the relative intensity of the various emitted wavelengths was not constant even within the tunability range. Therefore the shape of the peak in such situation could be distorted by the change of intensity. In addition, our apparatus could log and register only the

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<sup>1</sup>within a response time smaller than  $10^{-1}$  s.



**Figure 3.2:** We can see two different absorption peaks, both of them appearing during a multi-mode laser emission. The first peak corresponds to a wavelength of 687.40 nm but suddenly jumps to a wavelength of 686.65 nm, while the second corresponds to an absorption wavelength of 687.30 nm but jumps back and forth several times to the frequency of 687.05 nm. This means that the laser is emitting in at least two different modes at the same time. While initially one of the two is the strongest, after a bit the other becomes higher and the spectrometer starts indicating it as the main peak. In such a situation the shape of the peak is severely deformed by the changes in intensity of the various modes. Laser parameters: 29.10 °C; 73.23 mA.

wavelength and intensity of the strongest emitted peak, even when the laser was not emitting in a single mode. This made very difficult to distinguish between single-mode and multi-mode emissions just looking at the recorded data. Indeed the only way we had to suppose a multi-mode emission according to the recorded data was looking for

- fast jumps between two wavelengths competing in being the main one
- decreases in the main peak intensity or in the intensity-peak integral ratio, though difficult because these two parameters were quite noisy.

The best solution we found, however, was to personally attend to the measurements and observe the etalon interference pattern to detect multi-mode emissions. Also it was important to try many different sets of laser parameters, in order to avoid multi-mode emissions which contained absorption wavelengths.

### Noise and lock-in low pass filter

The lock-in amplifier we used contained an adjustable low pass filter to control the output signals. A higher time constant allows to filter out more noise, but on the other side it would correspond to a lower slew rate of the signal. This deformed the shape of the peaks, especially when the signal changed abruptly during a mode hop or in fast sweep measurement. After several attempts we found that a time constant of 1 second gave a quite stable output without requiring us to make too slow measurements.

#### 3.4.2 Single full sweeps

In this kind of measurement, we set the laser diode temperature and injection current, waited about 15 minutes to get emission stability, and started sweeping the piezoelectric crystal along its full driving range (0-150 V), using a linear ramp function with a period of about 11 minutes. This kind of experiment showed all the different absorption peaks available with that choice of laser parameters, and also to study the periodicity of the laser modes with respect to the grating position.

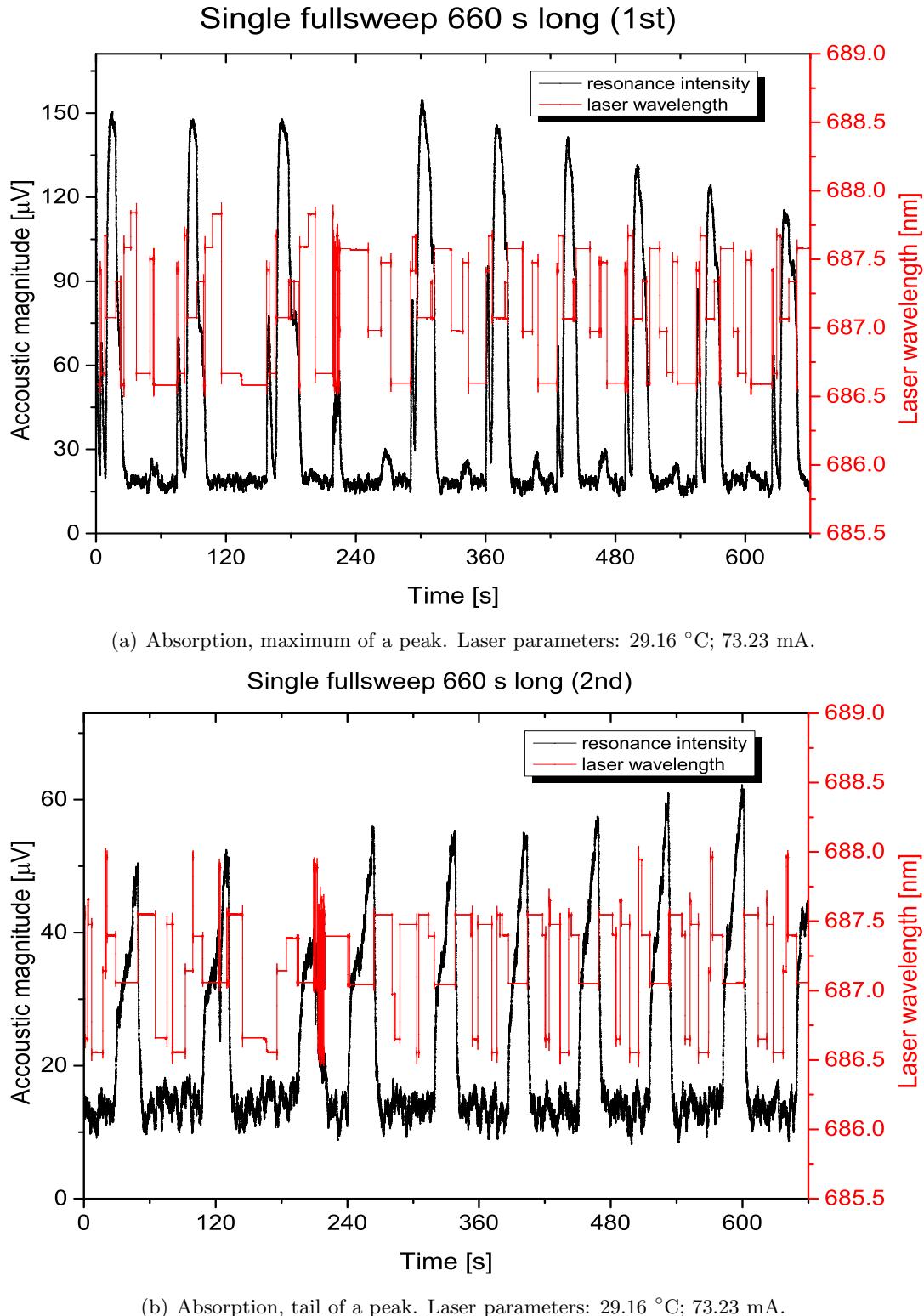
Figs. 3.3 and 3.4 show the result of this first session of measurements. In Fig. 3.3(a) a full sweep of the piezoelectric actuators made the laser to hop its emission mode many times. But only few of those modes met the absorption peak of the oxygen, thus resulting in a high signal. In Fig. 3.3(b) the same modes gives a much lower signal: we moved far away from the absorption peak maximum, even though we didn't change any of the parameters. This is due to the laser frequency drift discussed in Section 3.5.

In Fig. 3.4 we slightly changed one of the laser parameters: the diode temperature. The whole modes pattern is now completely reshuffled with respect to Fig. 3.3, and the full sweep of the piezoelectric actuators shown in Fig. 3.4(a) now highlights three different absorption peaks. A closer observation, in Fig. 3.4(b), permits to fully appreciate this, as well as to see the signal deformation due to the factors discussed in Section 3.4.1.

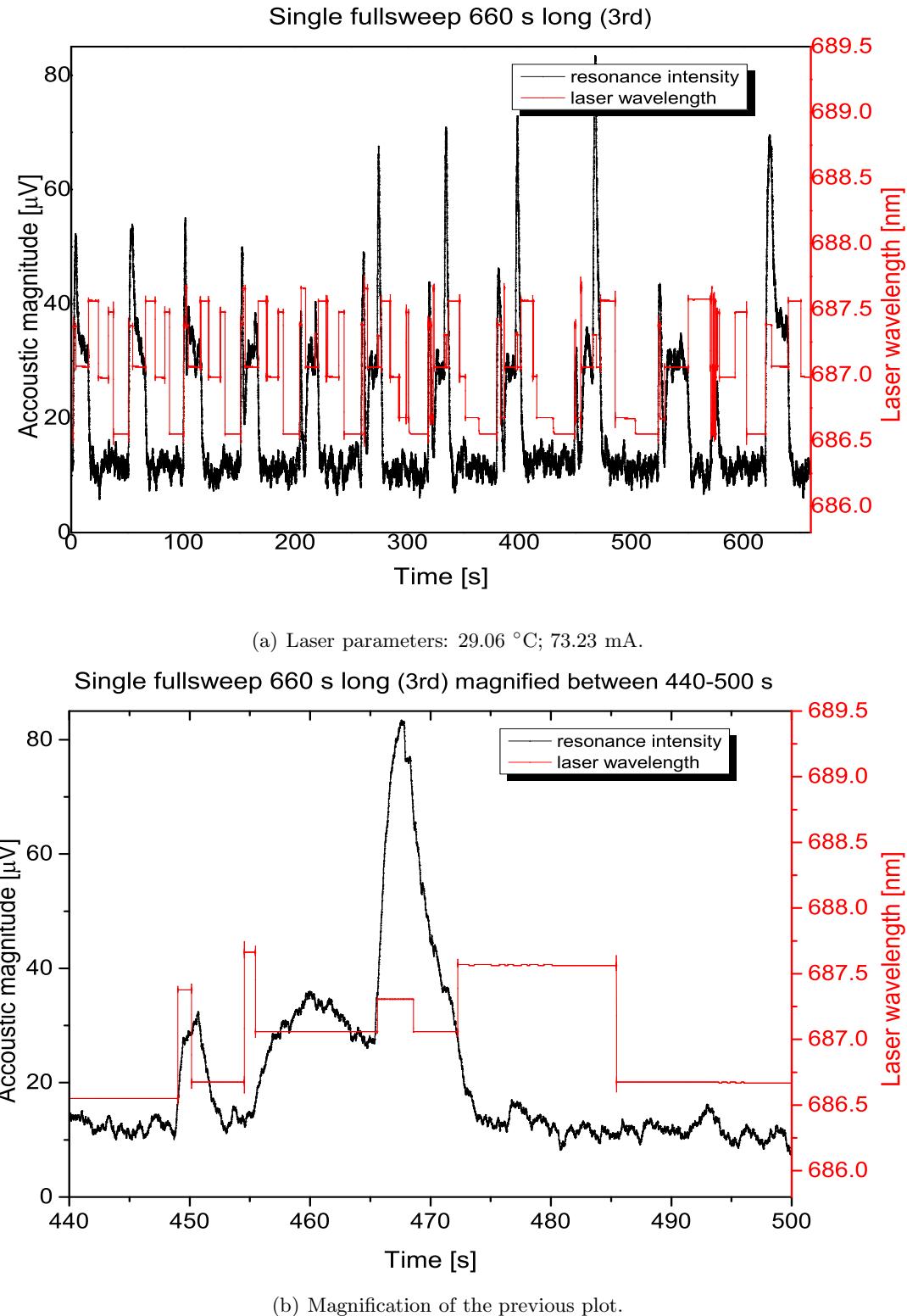
Looking at the peak wavelength plots we noticed that the laser mode jumping is somehow periodical with respect to the piezoelectric sweeping voltage. That is, for portions of the sweep about 50-100 V large the modes hop from one to another according to a constant pattern. This can be easily seen in Fig. 3.5, which shows both the wavelength of the main emission peak and its intensity, during part of the sweep shown in Fig. 3.3(a). The pattern, followed clearly for at least a couple of periods, is shown in Table 3.2.

#### 3.4.3 Multiple full sweeps

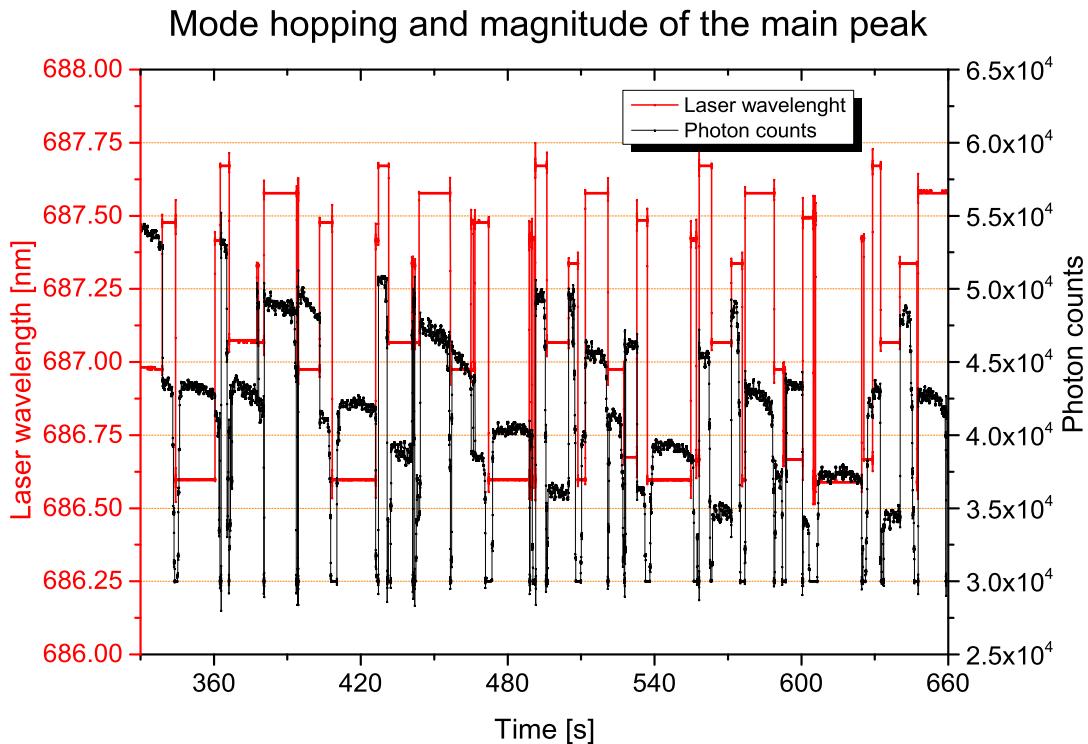
Since these measurement took quite a long time every sweep, doing repeated measurements most of time resulted in unmatchable data, because of the uncontrolled



**Figure 3.3:** Photoacoustic absorption of a  $\simeq 687.0$  nm peak. The wavelength shift between the two plots is of the order of  $10^{-2}$  nm, thus it's not visible on the scale. The noisy parts at  $\simeq 220$  s are due to the fast backwards ramp of the sweeping.



**Figure 3.4:** In this measurement, the laser diode temperature is 0.1 °C lower than Fig. 3.3. We notice 3 different absorption wavelengths: 687.30, 687.35, 687.05 nm. Here are visible the deformations we studied in Section 3.4.1



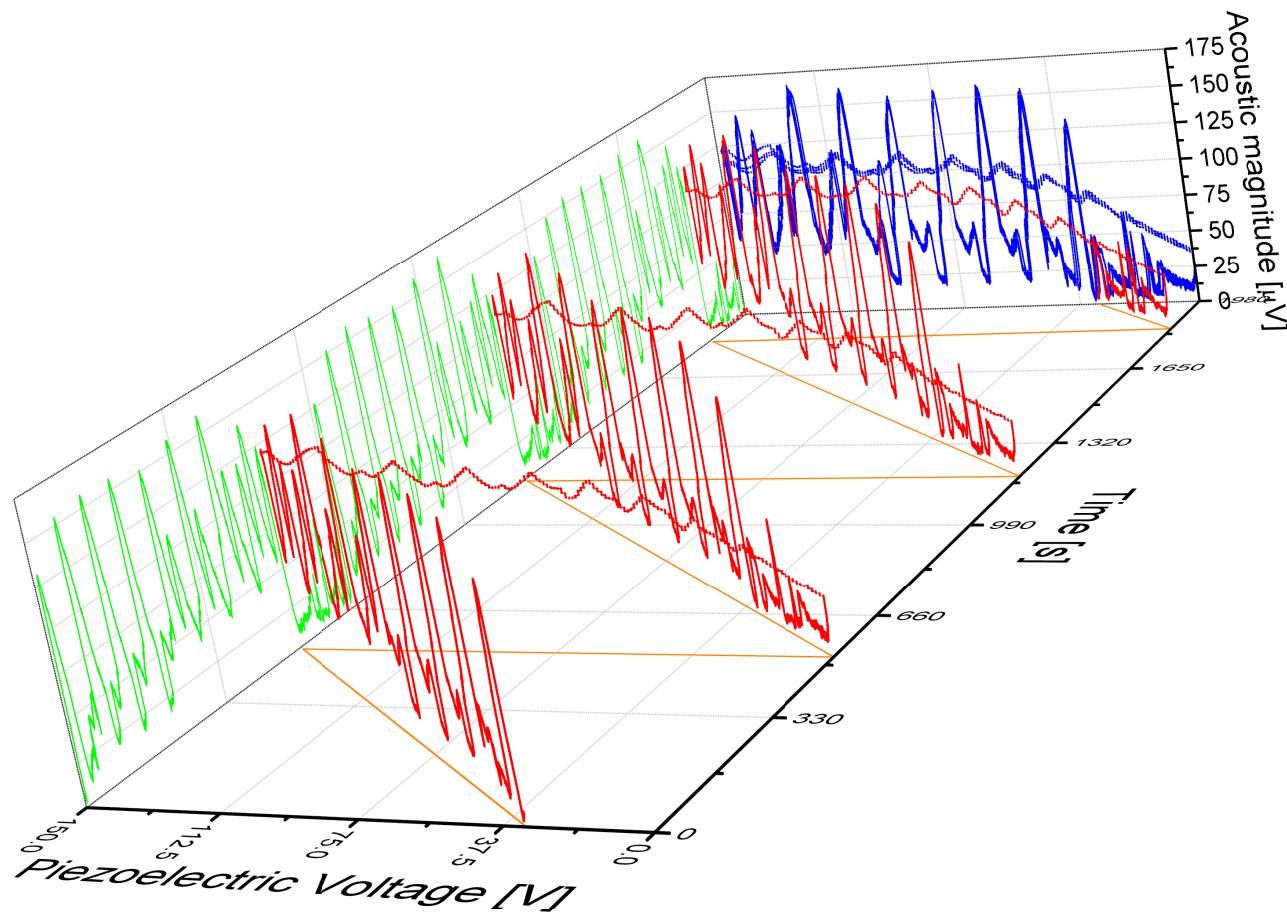
**Figure 3.5:** We can see that the laser follows the same hopping pattern for several seconds, corresponding to a piezoelectric voltage sweep of 75 V.

Time interval [s]	Wavelength [nm]
0	687.45
5	686.60
21	687.40
24	687.65
27	687.05
39	687.30
39	687.05
41	687.55
55	686.95

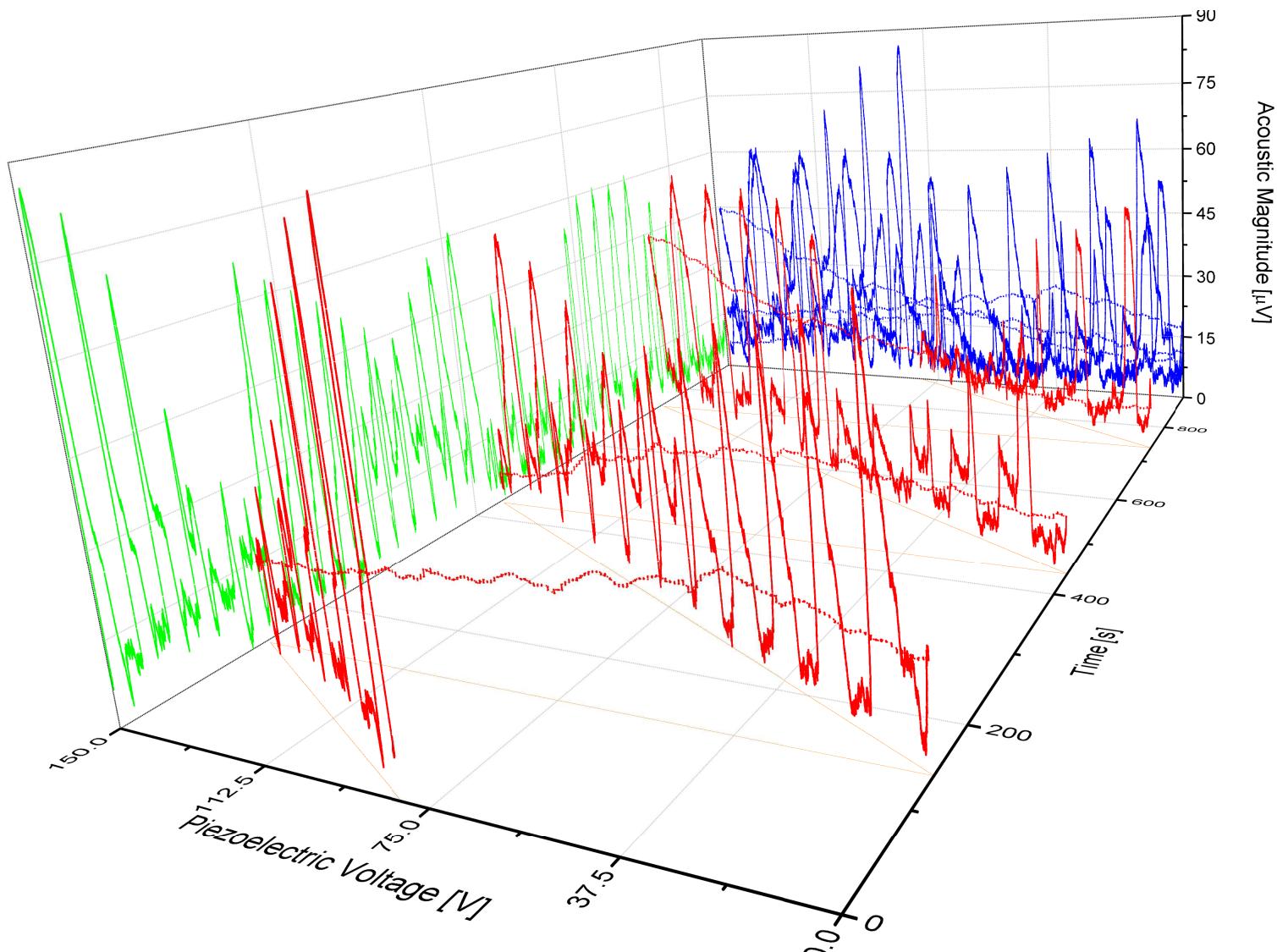
**Table 3.2:** Example of hopping pattern. The time intervals are calculated from the beginning of Fig. 3.5, 339 s.

evolution we already mentioned. The influence of such uncontrolled factors exhibited however a random behaviour, so that, after some trials, we were able to get a unique “lucky” measurement of 3 subsequent sweeps which matched almost perfectly. This is shown in Fig. 3.6.

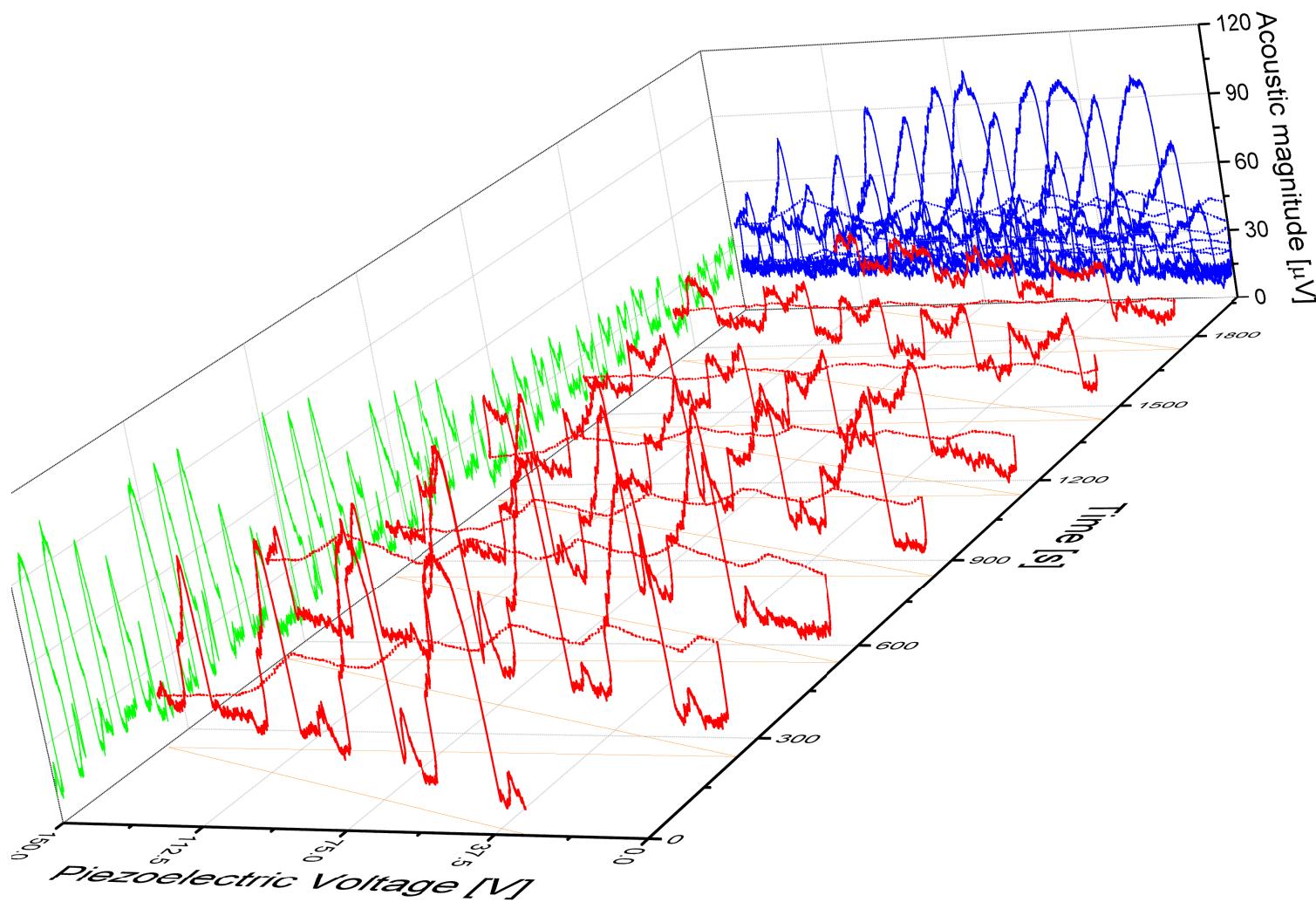
All the other attempts, instead, resulted in severe changes of the resonance pattern between one sweep and another. Studying the pattern of the wavelength vs voltage graphic helps in realizing that this difference is not to be ascribed to the photoacoustic part of the experiment (oxygen concentration/pressure, laser alignment) but is rather due to a change in the laser emission wavelength pattern. Figs. 3.7 and 3.8 provide meaningful examples of this behaviour. The change in the wavelength pattern is better shown in Section 3.4.4, where we focused on shorter multiple sweeps around a single absorption peak.



**Figure 3.6:** Three subsequent 0-150 V sweeps, of duration of 11 minutes each. Red: acoustic signal magnitude vs time and actuators voltage. Green: time projection. Blue: voltage projection. Notice that in the voltage projection the matching between the peaks of different sweeps is almost perfect. Laser parameters: 29,50 °C; 80,01 mA.



**Figure 3.7:** Despite these measurements are taken faster then usual (5 minutes each 0-150 V sweep) there is a big mismatch between the three sweeps. This mismatch is more evident in the magnitude vs voltage projection, where the peaks seem to be double-peaks. The time projections shows instead that they are single peaks. Laser parameters: 27,68 °C; 80,01 mA



**Figure 3.8:** In this measurement it is shown not only the fact that the peaks shift in voltage with time but can completely fade away after some minutes. Laser parameters: 25,03 °C; 80,01 mA

### 3.4.4 Multiple focused sweeps

Another measurement methodology we used exploited repeated single-peak sweeps instead of full 0 to 150 V sweeps. This was intended to better study both the absorption peak shape and the evolution caused by external factors. In this kind of measurements it is also possible to use uncontrolled evolution at our advantage, since sometimes it allowed to increase the tunability range before a mode hopping. Fig. 3.9 shows how repeating a measurement of the same peak changed the part of the peak we were able to see. In Fig. 3.9(a) the part of the peak we were able to see decreased after each sweep, while in Fig. 3.9(b) the scanned part of the peak instead increased “thanks” to the uncontrolled time evolution. In both of these examples we see that we could not usually measure the “tunability range” using the spectrometer data, but still we are able to see that the voltage to laser mode dependence changes with time.

In order to better study how the voltage to wavelength output changed with time we plotted all the sweeps of Fig. 3.9(a) on a voltage/intensity graphic, thus getting Fig. 3.10(a), and subsequently shifted them by the voltage required to match the part of the peak which most likely corresponded to the oxygen absorption peak (see Section 3.4), getting Fig. 3.10(b) as result.

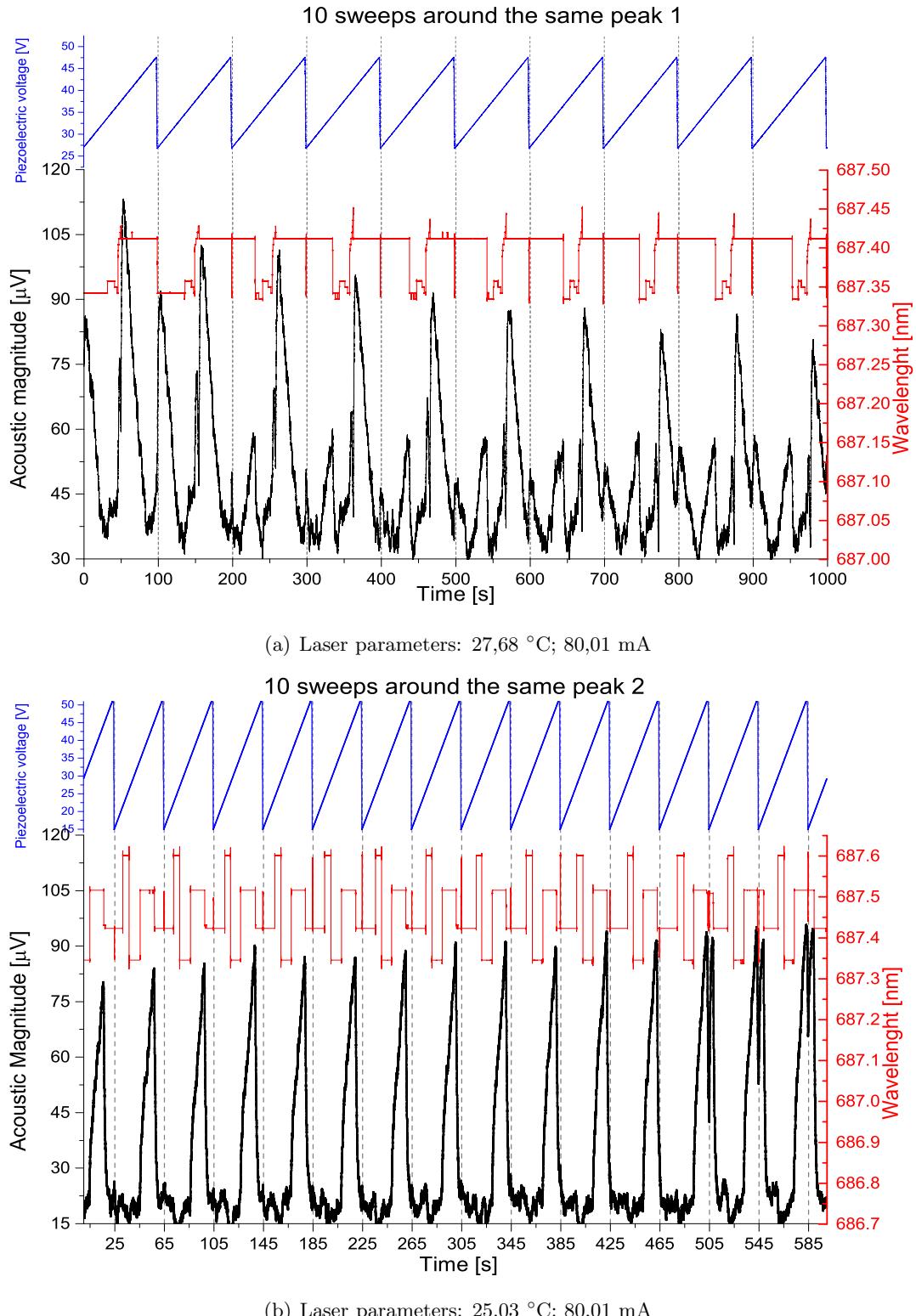
In order to make the edges of the peak match, we had to shift the various peaks of the values listed in Table 3.3

N of peak	Shift [V]	$\Delta$ Shift [V]
2	-0.04	-0.04
3	-0.065	-0.025
4	-0.1	-0.035
5	-0.12	-0.02
6	-0.142	-0.022
7	-0.157	-0.015
8	-0.185	-0.028
9	-0.195	-0.01
10	-0.22	-0.025

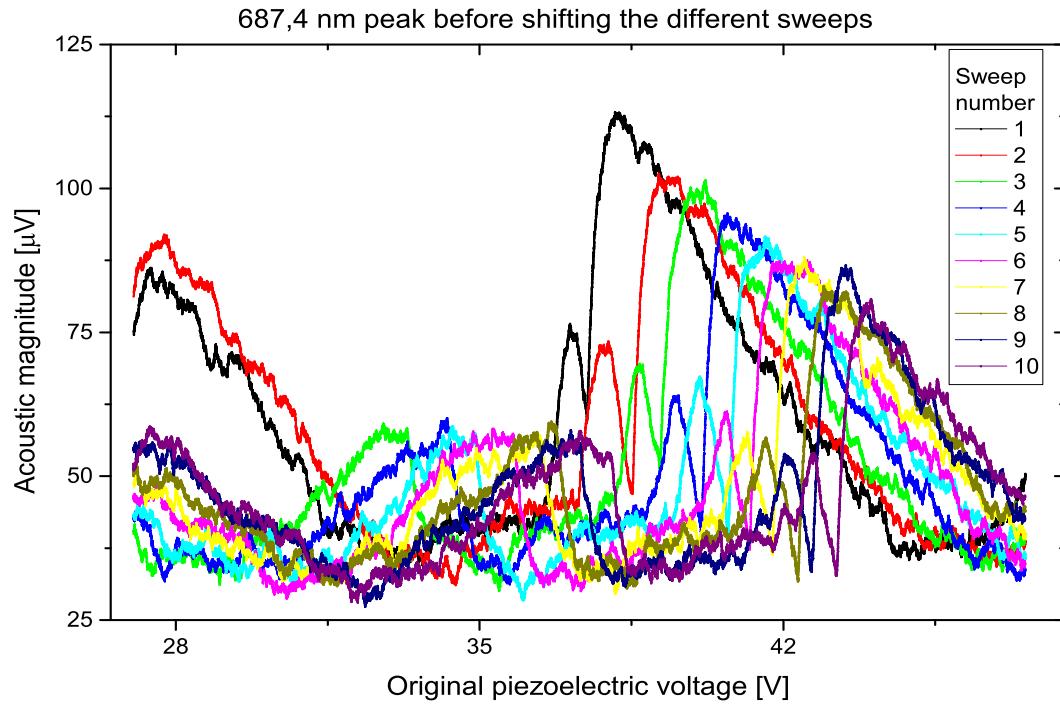
**Table 3.3:** Shifts of peaks in Fig. 3.10(b) with respect to the first peak and to the precedent peak.

Looking at these data we could notice that, while the evolution is monotonic during our whole measurement, its speed is not constant, i.e. every peak has to be shifted a different amount with respect to the previous one.

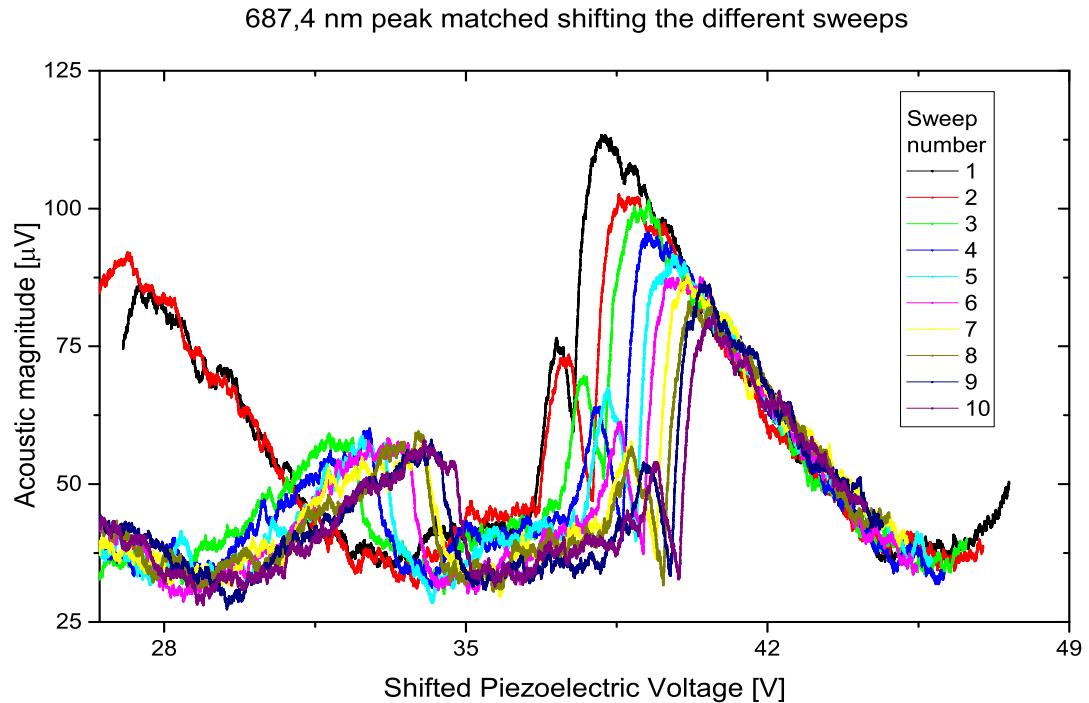
From the wavelength to voltage graph we can also see that, even after having shifted the sweeps in order to match the peak edges, the mode hopping from 687.35 nm (not corresponding to any absorption peak) to 687.41 nm is not happening at the same voltage in the various sweeps. This means that the environmental factors



**Figure 3.9:** The resonance frequency shifts after every measurement, changing the part of the peak (in black) we were able to scan and decreasing the maximum measurable intensity.

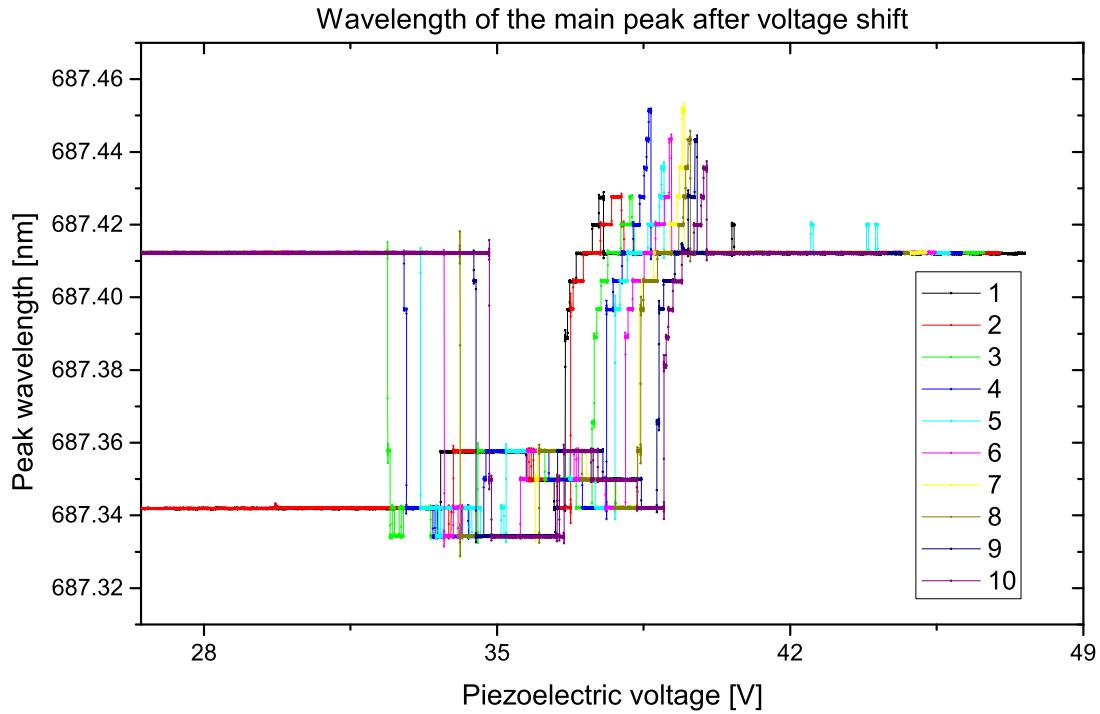


(a) Same measurement as Fig. 3.9(a), but rearranging the data to split the 10 different sweeps.



(b) Each measurement is now shifted of the values listed below in Table 3.3 in order to match the part of the peak corresponding to the oxygen absorption peak.

**Figure 3.10:** In order to compare the different signal peaks, and relate them to the same absorption peak, we shifted them manually during the data processing.



**Figure 3.11:** In this graphic the wavelength corresponding to each sweep has already been shifted of the same amount as the data in graph Fig. 3.10(b).

evolution cannot be modelled with a simple voltage drift (otherwise the voltage could find correction by just a voltage shift), but suffers the influence of more complicated factors. More efforts to study this kind of evolution have been described in Section 3.5.

## 3.5 Free laser drift analysis

### 3.5.1 Free evolution

To study how the evolution worked we acquired some measurements of the laser output using the spectrometer and the etalon, while keeping constant all the laser parameters (current, temperature and piezoelectric voltage). At first we took a short term measurement lasting 20 minutes. However, we understood that the evolution was quite slow, and that this first measurement was too short to be meaningful. We then took a second long term measurement, lasting a night time, in order to see whether a stable regime was reached. These are shown in Fig. 3.12.

The first thing we noticed was that the mode hopping due to the uncontrolled evolution followed the same pattern as the mode hopping due to the piezoelectric movement (see an example in Fig. 3.5 and Table 3.2). This suggested us the idea that one of the factors which generating this evolution could be a movement of the grating

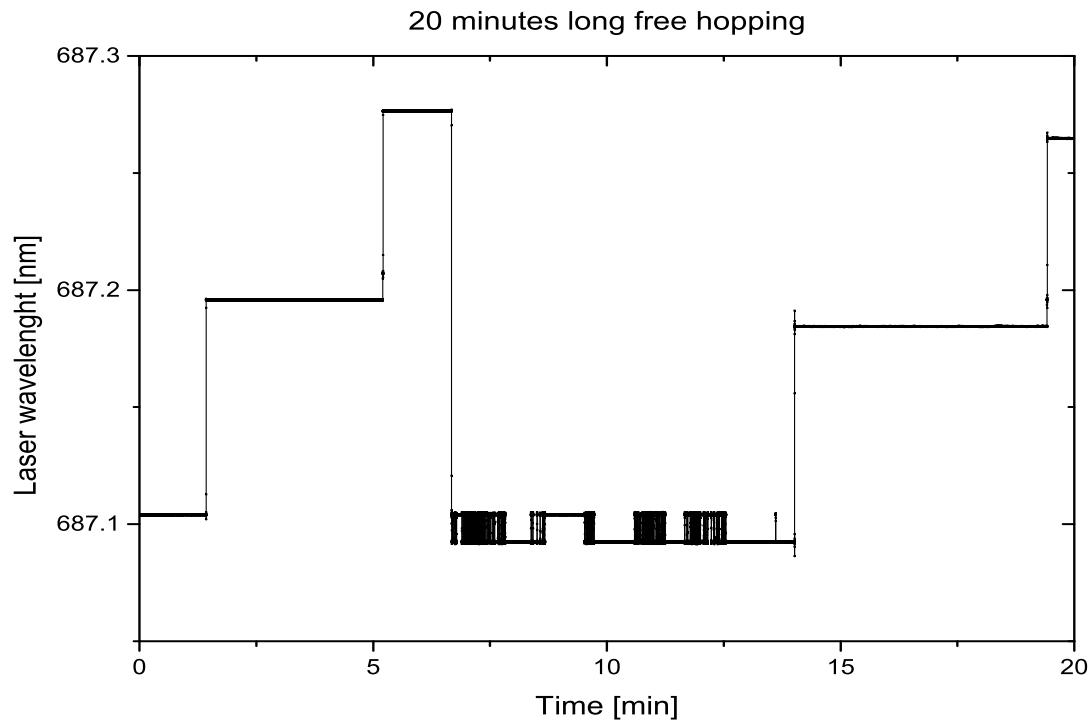
of the ECDL, allegedly caused by thermal expansion of the cage system holding it.

### 3.5.2 Heating- and cooling-induced evolution

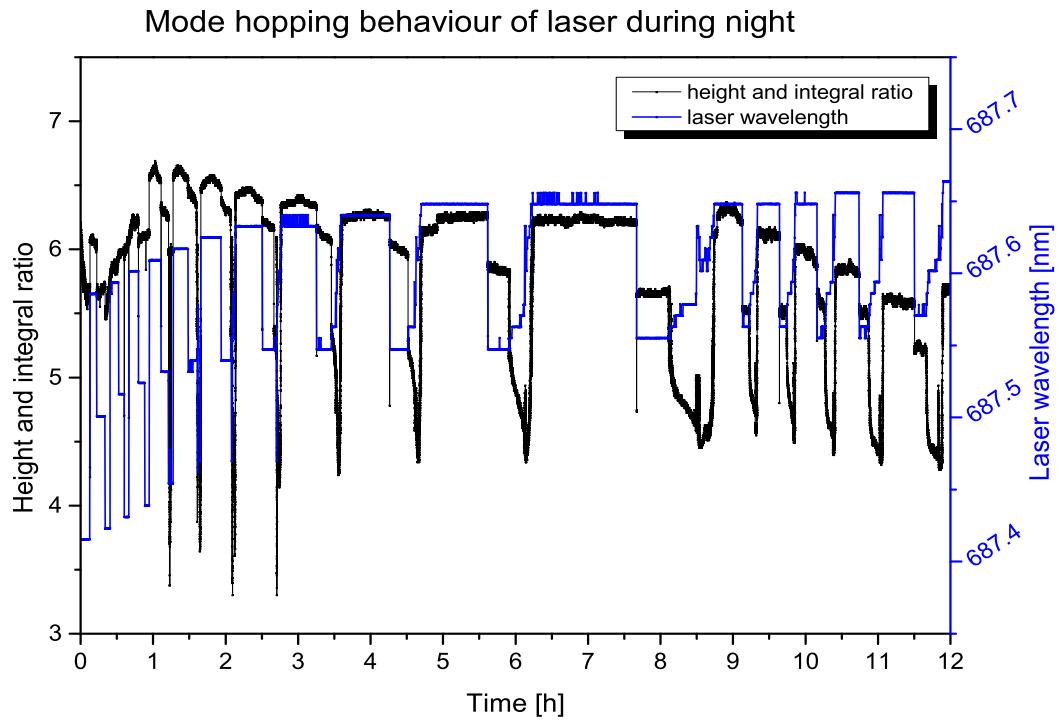
In order to confirm the fact that the evolution depends mainly on temperature (of the cage system or of the air) effects we put a tungsten lamp near the ECDL and turned it on. As we can see from Fig. 3.13, turning on the lamp increased the speed of the evolution a lot. After keeping the lamp on for a while we turned it off and took another measurement. This time we observed an evolution pattern almost as fast as the one with the lamp on, but with a reverse pattern. We interpreted this a signal that the system is cooling down.

### 3.5.3 Tunability change measurement

Since the resolution of our spectrometer was usually not good enough to distinguish a tunability change in time, we used the etalon to take a measurement similar to the tunability measurement of a mode (687.45 nm) several times, measuring the minimum and maximum wavelength before a mode hop for about two hours. The results in Table 3.4 show how not only the minimum and maximum piezoelectric voltages, but also the position of the etalon interference pattern change in time. Considering that the etalon FSR is of the order of 3-4 microseconds (on the video camera PAL signal), we found that the min-max drift is of the order of about one half as the tunability found in Section 2.3.

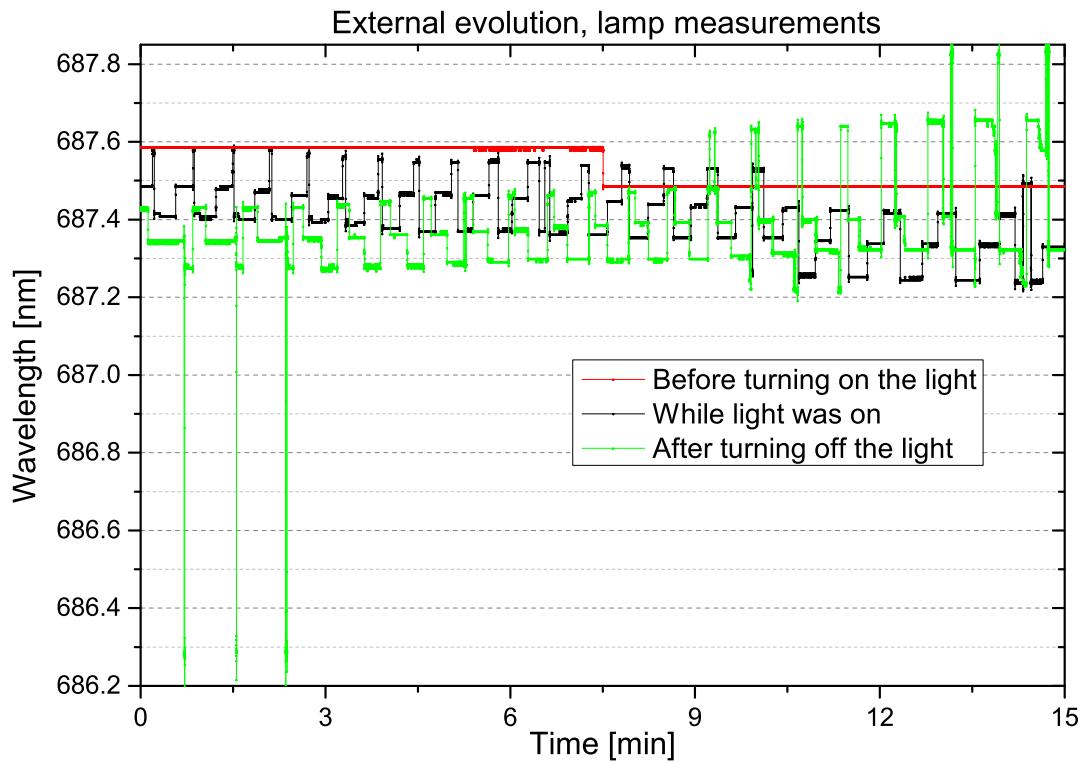


(a) Twenty minutes measurement. No equilibrium configuration is reached, nor clear pattern is visible.  
Laser parameters: 29,50 °C; 80,00 mA.



(b) Twelve hours measurement. A low frequency pattern appears, and this looks very similar to the mode hopping pattern due to the grating movements. Laser parameters: 25,03 °C; 80,01 mA.

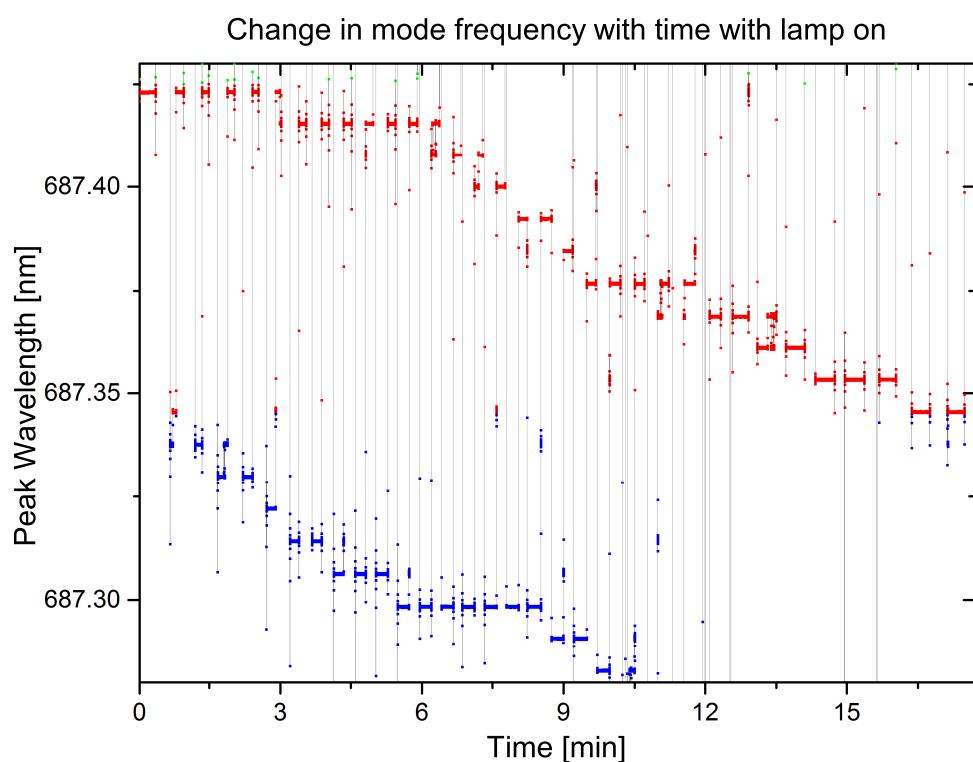
**Figure 3.12:** Laser free drift measurements.



**Figure 3.13:** During the measurements with the lamp turned on we were eventually able to see the difference in the minimum and maximum wavelength of the same mode after some drifts, as represented in the next graphic. Laser parameters: 27,68 °C; 80,01 mA.

Time [min]	$\Delta\text{Min}$ [ns]	Min volt. [V]	$\Delta\text{Max}$ [ns]	Max volt. [V]	Tunab. [ns]
15	0	19	180	24	720
30	250	20	<40	27	500
50	260	23	260	29	480
95	-330	23	-360	29	440
135	330	29	220	38	560

**Table 3.4:** Shifts of the maximum and minimum positions on the oscilloscope of the 687.45 nm mode. As discussed in Section 2.3, the uncertainty on the time measurement is estimated to be  $\simeq 40$  ns.



**Figure 3.14:** The wavelength of both of the mode shown here decreases after some periods of hopping. Laser parameters: 25.03 °C; 80.01 mA.

## Appendix A

# Extended Cavity Diode Laser (ECDL)

### A.1 Introduction to LD tuning

The light emitted by a diode laser is often practically useless to an experimentalist because of several different reasons:

- greatly diverges in an oval shape pattern
- because of the small cavity of the laser it has a larger bandwidth which means that diode lasers emit light over a broader range of wavelengths than other kinds of lasers
- could have an unstable wavelength due to temperature or current fluctuations.

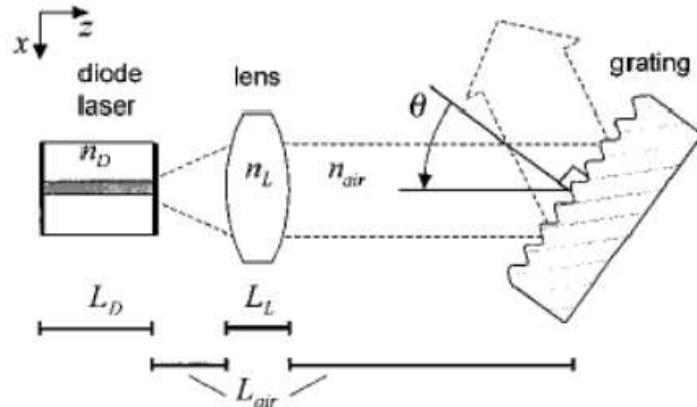
The first problem makes it necessary to collimate the output of the diode laser, that is, bend the diverging light through a lens (or several lenses) so that all the output goes in one direction. One can achieve this result by using a single lens as long as the laser is placed exactly at the focal point of the lens one chooses. The focal point of a lens is also the point through which all light parallel to its normal axis will converge. Hence, if we place our diode laser at the focal point of our collimating lens all light from the diode laser that passes through the lens will exit parallel to the normal axis and all light that enters the face of the lens at normal incidence will be focused the diode laser.

The broad linewidth of solitary diode laser often reduces their usefulness for spectroscopy applications. To overcome this problem several techniques have been developed, for example:

- negative electronic feedback
- resonant optical feedback from a high-finesse optical cavity

- extended-cavity configurations

Among all these techniques that can be used to reduce the laser linewidth down to the kHz range, the extended-cavity configuration with grating feedback has become the most popular. It provides a simple mean to achieve a wide wavelength tuning range and a narrow linewidth. The external cavity could also solve the instability through optical feedback, severely reducing mode hoping. In our experiment we used an external cavity in Littrow configuration so we will focus on explaining how such a cavity and it's main components work. A schematic layout of the extended-cavity laser is outlined in Fig. A.1. The laser system consists of a diode laser as the active medium, a collimating lens and a diffraction grating. The external cavity is formed between the rear facet of the diode laser and the grating as a wavelength selective mirror. The laser frequency depends critically on the optical length of the cavity, which is sensitive to any changes in the refractive index of the cavity media (diode laser, lens, and air) and to changes in the physical cavity length. The collimation lens of the ECDL (Extended Cavity Diode Laser) is one critical part of attaining optical feedback. The second part of our system that allows optical feedback is the diffraction grating.



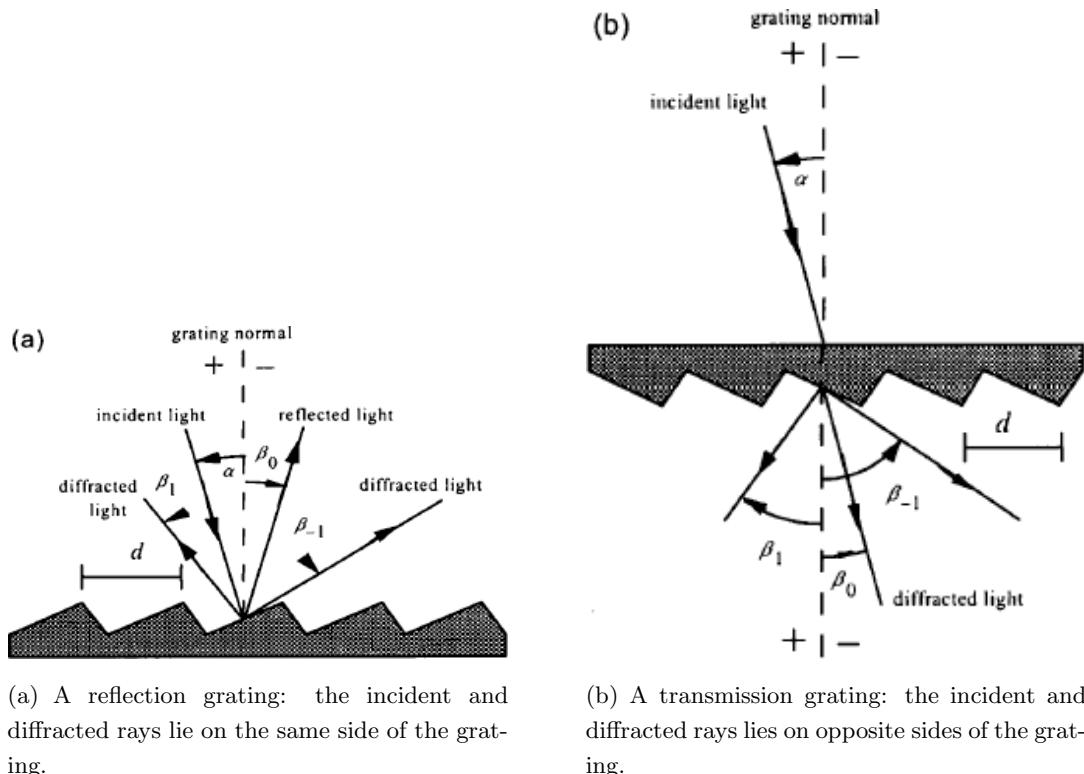
**Figure A.1:** Schematic layout of the extended cavity laser. The total optical path length in the cavity is  $L_{EC} = L_D n_D + L_L n_L + L_{AIR} n_{AIR}$

## A.2 Diffraction theory for a grating

A diffraction grating is a finely scored reflective material that, due to its geometry, allows only certain wavelengths of light incident at an angle to interfere constructively with itself as it is reflected outwards.

The light diffracted by each groove combines to form a diffracted wavefront. Diffraction by a grating can be visualized from the geometry in Fig. A.3, which shows a light

ray of wavelength  $\lambda$  incident at an angle  $\alpha$  and diffracted by a grating along angles  $\beta_M$ . These angles are measured from the grating normal, which is the dashed line perpendicular to the grating surface at its center. The sign convention for these angles depends on whether the light is diffracted on the same side or the opposite side of the grating as the incident light. In Fig. A.2(a), which shows a reflection grating, the angles are  $\alpha > 0$  and  $\beta_1 > 0$  (since they are measured counter-clockwise from the grating normal), while we have  $\beta_0 < 0$  and  $\beta_{-1} < 0$  (since they are measured clockwise from the grating normal). Diagram Fig. A.2(b) shows the case for a transmission grating.



**Figure A.2:** A comparison between reflection and transmission grating.

The formula for constructively diffracted orders of light reflected from a diffraction grating is:(VERIFICO NOMI DEGLI ANGOLI!!!111!!!!111!!!1111)

$$d \sin \theta = m\lambda \quad (\text{A.1})$$

where  $d$  is the spacing between reflective surfaces,  $\theta$  is the angle of incidence,  $\lambda$  is the wavelength of the incident light and  $m$  is an integer. One consequence of the above equation is that spectra diffracted off a grating are reproduced at several different angular positions about the grating. The various replications of the spectra are called *orders of diffraction* and obey the following relationship

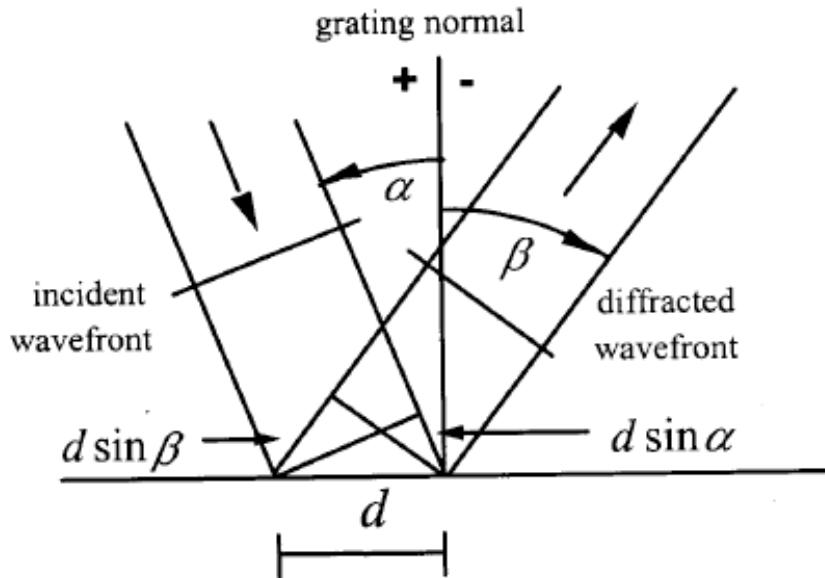
$$\sin \theta_I + \sin \theta_M = Nm\lambda \quad (\text{A.2})$$

where  $\theta_M$  is the angle of the  $m$ th order diffracted beam,  $N$  is the spatial frequency of the grating (units  $\text{mm}^{-1}$ ), and  $\theta_I$  and  $\lambda$  are the incident light angle and wavelength respectively.

When monochromatic light impinges on a grating surface, it is diffracted into discrete directions. We can easily calculate the separation between these directions by inverting /refgianfrancioschio.

$$\beta[\lambda] = \arcsin \left[ \frac{m\lambda}{d} - \sin \alpha \right] \quad (\text{A.3})$$

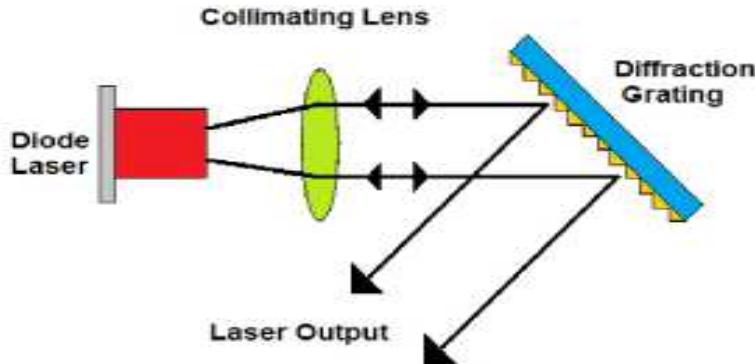
When  $m = 0$ , the grating acts as a mirror, and the wavelengths are not separated ( $\beta = -\alpha$  for all  $\lambda$ ); this is called specular reflection or *the zeroth order*.



**Figure A.3:** Geometry of diffraction, for planar wavefronts.

### A.3 Littrow configuration ECDL

In the Littrow configuration for the external cavity, shown in Fig. A.4, the grating is aligned in way such that the first order diffraction from the grating is coupled directly back into the laser, while the zeroth-order diffraction is reflected as the output beam. The lasing wavelength is dependent on the angle of the incident laser beam with respect to the grating, otherwise known as the Littrow angle  $\theta$ . There are 3 cavities which set up such configuration:



**Figure A.4:** Schematic diagram of external cavity in Littrow configuration.

1. Laser diode cavity or internal Fabry-Pérot cavity
2. External cavity between grating and back side of the diode
3. Parasitic cavity between grating and the front facet of the diode

The key to the Littrow configuration is the backcoupling of the first-order diffraction beam from the grating into the laser diode. Without this feedback, the Littrow laser cannot achieve single-mode emission and will lase at a wavelength set by the gain peak of the semiconductor active region. When the feedback beam is well aligned, interference fringes are expected in the output beam and the laser remains in single-mode despite small temperature and current changes.

#### A.4 Main sources of noise in a ECDL

The frequency of a solitary diode laser is sensitive to variations in the injection current and the junction temperature. This is mainly caused by changes in the refractive index of the active medium and in the optical gain. These effects can be reduced in an ECDL but other many noise factors are introduced due to the instability of the optical length of the external cavity. We will now summarize the main factors which influence the optical length of the cavity.

The optical length of the collimating lens changes with temperature. This is caused by thermal expansion of the material and temperature dependence of the refractive index. Their effects on the laser frequency are described by the relationship

$$\frac{d\nu}{dT_L} = -\nu \frac{L_L}{L_{EC}} \alpha_L (n_L - n_{AIR} + \beta_L n_L) \quad (\text{A.4})$$

where  $n_L$  and  $n_{AIR}$  are the refractive indices of the lens material and air respectively, and  $L_L$  and  $L_{EC}$  are the physical length of the lens and the total optical path length of the external cavity, respectively. The thermal expansion coefficient of the lens material is denoted by  $\alpha_L$  and the relative temperature coefficient of the refractive index by  $\beta_L$ .

The refractive index of air is mainly sensitive to variations in pressure  $p$  and temperature  $T_{\text{AIR}}$ . The variations in the laser frequency due to these changes are described by

$$\frac{d\nu}{dp} = -\nu \frac{L_{\text{AIR}}}{L_{\text{EC}}} \frac{dn_{\text{AIR}}}{dp} \quad (\text{A.5})$$

$$\frac{d\nu}{dT_{\text{AIR}}} = -\nu \frac{L_{\text{AIR}}}{L_{\text{EC}}} \frac{dn_{\text{AIR}}}{dT_{\text{AIR}}} \quad (\text{A.6})$$

where  $L_{\text{AIR}}$  is the cavity length containing air.

The mechanical structure of the cavity often contains micrometric screws and piezo-electric transducers (PZTs) for wavelength control. The sensitivity of the laser frequency to thermal expansion of these parts can be written as

$$\frac{d\nu}{dT_{\text{M}}} = \pm \nu \frac{L_{\text{M}}}{L_{\text{EC}}} \alpha_{\text{M}} \quad (\text{A.7})$$

where  $L_{\text{M}}$  and  $\alpha_{\text{M}}$  are the length and the thermal expansion coefficient of the mechanical part, respectively.

A transverse displacement along  $x$  axis of the collimating lens with respect to the laser diode changes the beam direction. This causes a frequency shift due to a change in the cavity length. For a small displacement, the frequency shift can be written as

$$\frac{d\nu}{dx} = \frac{\nu \tan \theta}{f_{\text{L}}} \quad (\text{A.8})$$

$$\frac{d\nu_{\text{G}}}{dT} = -\nu_{\text{G}} \alpha_{\text{G}} \quad (\text{A.9})$$

where  $f_{\text{L}}$  is the focal length of the lens and  $\theta$  is the angle between the grating normal and the incident beam, while  $\nu_{\text{G}}$  and  $\alpha_{\text{G}}$  are the central frequency of the grating feedback and the grating thermal expansion coefficient respectively. The displacement of the lens can be caused, for example, by asymmetric thermal expansion relative to the optical axis or by mechanical vibration of the lens holder.

There are additional effects that influence mainly the short-term frequency stability of the laser: current- and PZT driver noise, mechanical vibrations, acoustic disturbances, and rapid changes in the refractive index of air caused by air flow. All of these factors have an effect on the length of the external cavity and, consequently, generate frequency modulation of the laser.

## Appendix B

# The lock-in amplifier

### B.1 Basic theory

A lock-in amplifier is a device which is useful for extracting a frequency modulated narrow band signal from a noisy environment by using a phase sensitive detector. The output will typically be a DC voltage which is proportional to the original signal amplitude. The device has two inputs as shown in Fig. B.1. One is the input signal that is to be measured, and the other is a reference. The reference should have the same frequency as the modulation frequency of the original signal. This signal is usually a sync-signal originating from the same source as the input signal modulator (in our experiment an optical chopper).

The input signal of the lock-in is first passed through an amplifier of gain  $g$ , which is adjustable and is used to control the sensitivity of the lock-in. The reference signal instead is led through a sine-former, i.e. a block consisting of many components which transform the signal to ensure it has sinusoidal form and a specific predetermined amplitude.

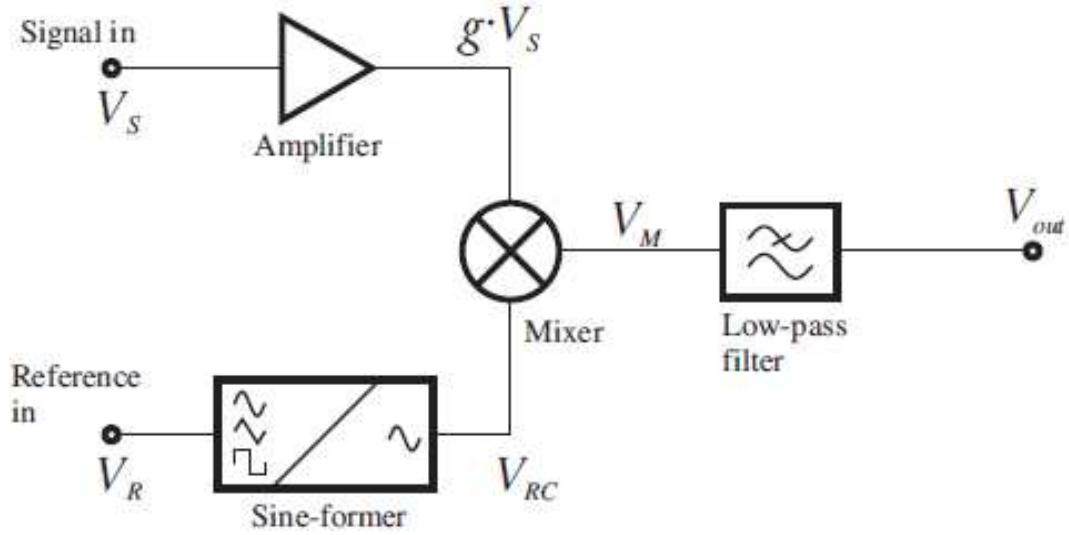
The following Eq. (B.1) states the modulated input signal  $K[t]$  if we assume it is sinusoidally modulated<sup>1</sup>, where  $f$  is the frequency of the carrier, while Eq. (B.2) states the reference signal after it has passed through the sine-former, and assuming it has the exact same frequency  $f$  as the input signal.

$$V_S = K[t] \cos[2\pi ft + \phi_S] \quad (\text{B.1})$$

$$V_{RC} = \cos[2\pi ft + \phi_R] \quad (\text{B.2})$$

---

<sup>1</sup>Of course this is not out case, but thanks to Fourier decomposition we can think of any generic signal as a sum of sinusoidal components.



**Figure B.1:** Block scheme of a lock-in amplifier.

The mixer then combines these two signals by multiplying them, giving

$$\begin{aligned} V_M &= K[t]g \cos[2\pi ft + \phi_S] \cos[2\pi ft + \phi_R] \\ &= \frac{1}{2}K[t]g (\cos[\phi_S - \phi_R] + \cos[2\pi \cdot 2ft + \phi_S + \phi_R]) \end{aligned} \quad (\text{B.3})$$

As can be seen in Eq. (B.3), assuming the bandwidth of the input signal  $K[t]$  is much smaller than the carrier frequency, the result consists of two frequency components. One at zero (DC), and one at the double of the carrier frequency. If the low pass filter is set correctly the double frequency component will be completely removed, and the output is therefore as stated by

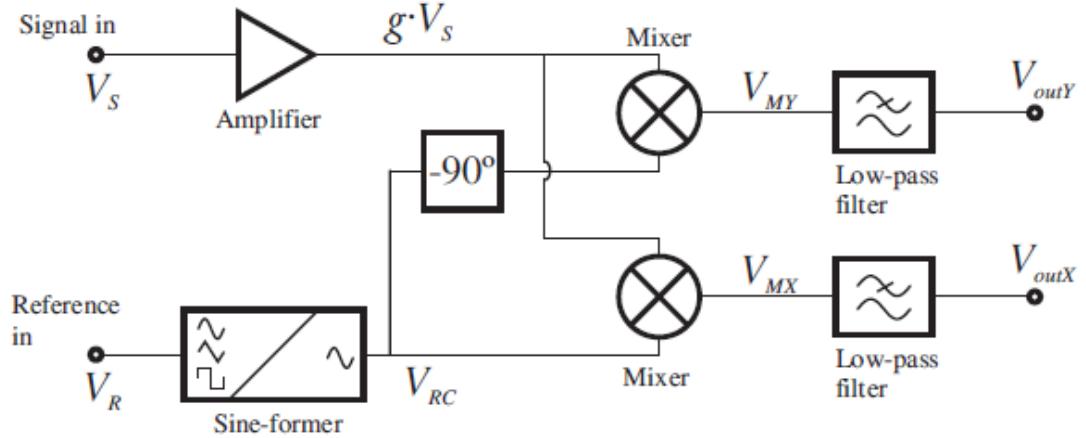
$$V_{\text{OUT}} = \frac{1}{2}K[t]g \cos [\phi_S - \phi_R] \quad (\text{B.4})$$

We can see that the output is a DC voltage which is proportional to the original signal amplitude  $K[t]$ . The amplifier gain  $g$  is such that, when assuming  $\phi_S = \phi_R$ , the output is 10V if the RMS-value of the input signal is the same as the sensitivity-setting. For lower input signals, the output is proportionally lower, and a higher input would eventually overload the lock-in. In most lock-in amplifiers, the sensitivity can be tuned according to the characteristics of the input signal.

## B.2 Dual lock-in amplifier

In the single lock-in amplifier we just studied, the output signal not only depends on the amplitude of the original signal, but also on the phase difference between the modulation and the reference signal given to the amplifier, which could be unknown

or unstable. In order to solve such problem and to make things easier the dual lock-in amplifier was implemented. The dual lock-in amplifier has instead two mixers with dedicated low pass filters. One of these mixers multiplies the reference and the input signal like before, and the other one multiplies the input signal with the reference phase shifted by  $90^\circ$ . Fig. B.2 illustrates this principle.



**Figure B.2:** A dual lock-in amplifier

The two outputs then become

$$V_{\text{OUT}}^X = \frac{1}{2}K[t]g \cos [\phi_S - \phi_R] \quad (\text{B.5})$$

$$V_{\text{OUT}}^Y = \frac{1}{2}K[t]g \sin [\phi_S - \phi_R]. \quad (\text{B.6})$$

$V_{\text{OUT}}^X$  is called the in phase component of the output, while  $V_{\text{OUT}}^Y$  is called the quadrature component. For convenience it could be useful to define a new complex quantity  $V_{\text{OUT}}^{\text{CP}}$  like

$$V_{\text{OUT}}^{\text{CP}} = V_{\text{OUT}}^X + iV_{\text{OUT}}^Y \quad (\text{B.7})$$

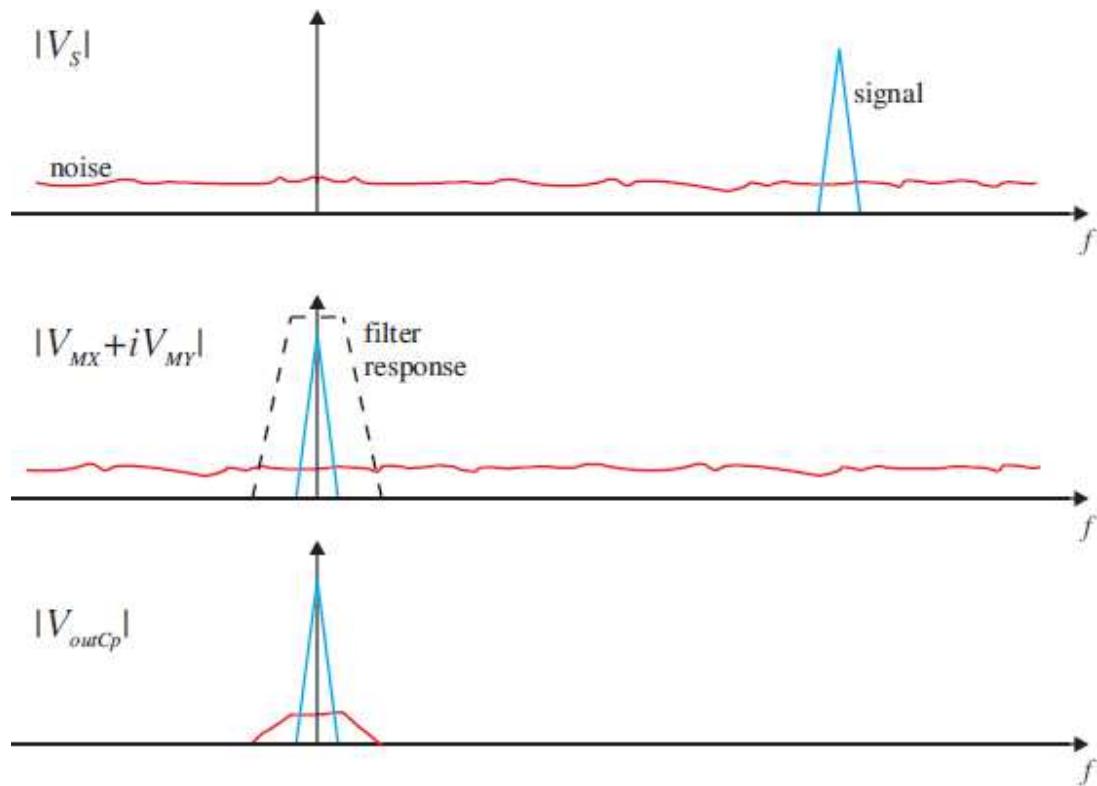
No matter what the phase difference between the input and the reference is, the magnitude of  $V_{\text{OUT}}^{\text{CP}}$  doesn't depend on the phase difference and can now be used to find the amplitude of the input signal modulated at frequency  $f$ .

### B.3 Low-pass filter

The low pass filters in Figs. B.1 and B.2 are supposed to remove the double frequency component in Eq. (B.3). In addition these filters may remove a lot of additional noise which unavoidably adds to the signal during the trasduction and trasmission of the

signal. Fig. B.3 shows such an example. Here the mixing process causes a shift in the spectrum such that the desired signal is shifted to  $f = 0$  (DC). The dotted line represents the frequency response of the filter, and should be multiplied with the input signal to give the output. All the noise which is not within the bandwidth of the filter is removed.

In most lock-in amplifiers the low-pass filter is adjustable through two parameters. One of them is the time constant  $\tau$ . If the input were to suddenly change, this is the time it would take before the output is adjusted to 63% of this change. The second parameter is the number of such filters which influences the resulting cutoff slope. Between one and four filters with the same time constant  $\tau$  can be cascaded to form a sharper filter.



**Figure B.3:** The low pass filter removes all the noise which is not within the bandwidth of the filter.

# Appendix C

## Etalon

### C.1 Introduction

The etalon is an optical device made of two perfectly parallel semi-reflecting surfaces. It can be thought as a Fabry-Pérot cavity which walls are fixed. This geometry can be implemented either with an air-based or a solid design. The first one consists in two surfaces separated by air, one of which usually can be moved via piezoelectric actuators. The second one is just made from a piece of glass (or other materials suitable for the desired application) with a partially reflecting coating covered facets (Fig. C.1). While the air based etalons make longer cavities, thus more precise, they are extremely delicate and cumbersome to manage, mostly because the two surfaces must be kept parallel within hundredths of wavelength. The solid state ones, on the other hand, are usually smaller and less performing, but way more robust and easier to use.

Every time the impinging beam encounters one of the two optical surfaces the light is partially reflected and partially transmitted. Multiple reflections occur inside the two surfaces leading to an infinite number of rays departing from the interferometer in both the transmitted and reflected directions. Contiguous beams differ for a constant phase and this causes an interference pattern, as shown in Fig. C.2.

### C.2 Theoretical treatment

To derive the phase difference between two adjacent beams, let's begin calculating the difference in their optical paths (Fig. C.3). We thus choose two parallel beams, such as  $OB$  and  $CD$ , and draw a wavefront perpendicular to them,  $AC$ . The optical path difference between  $A$  and  $C$  is given by

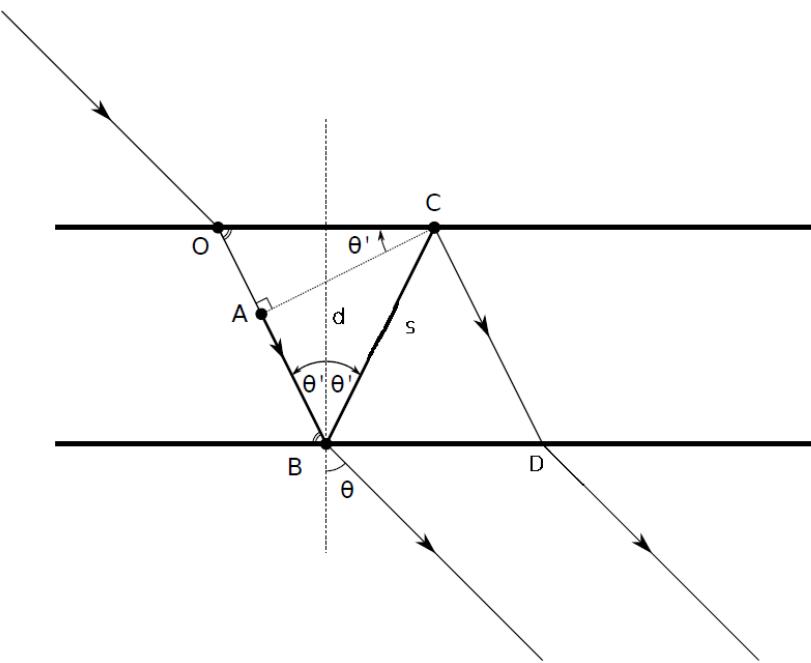
$$\overline{ABC} = \overline{AB} + \overline{BC} \quad (\text{C.1})$$



**Figure C.1:** Solid state etalons.



**Figure C.2:** The etalon diffraction pattern seen through our video camera.



**Figure C.3:** The impinging beam changes direction due to refraction index difference between the air and the medium, the angles  $\theta$  and  $\theta'$  being related to the refraction indices  $n$  (air) and  $n'$  (medium) by Snell's law.

We call  $d$  the width of the etalon, and  $s$  the distance traveled by the beam from one surface to the other one, so that

$$\overline{BC} = \overline{OB} \equiv s = \frac{d}{\cos \theta'}. \quad (\text{C.2})$$

From elementary geometry considerations we get the following relationships:

$$\overline{AB} = \overline{OB} - \overline{OA} \quad (\text{C.3})$$

$$\overline{OA} = \sqrt{\overline{OC}^2 - \overline{AC}^2} \quad (\text{C.4})$$

$$\overline{OC} = 2s \sin \theta' \quad (\text{C.5})$$

$$\overline{AC} = s \sin(2\theta') \quad (\text{C.6})$$

Then we write

$$\begin{aligned} \overline{OA} &= \sqrt{4s^2 \sin^2 \theta' - s^2 \sin^2(2\theta')} \\ &= \sqrt{4s^2 \sin^2 \theta' \left(1 - \frac{\sin^2(2\theta')}{4 \sin^2 \theta'}\right)} \\ &= 2s \sin \theta' \sqrt{1 - \cos^2 \theta'} \\ &= 2s \sin^2 \theta' \end{aligned} \quad (\text{C.7})$$

Putting all together we get the optical path difference

$$\begin{aligned} \overline{ABC} &= \overline{AB} + \overline{BC} \\ &= \overline{OB} - \overline{OA} + \overline{BC} \\ &= s - 2s \sin^2 \theta' + s \\ &= 2s(1 - \sin^2 \theta') \\ &= 2s \cos^2 \theta' \\ &= 2d \cos \theta'. \end{aligned} \quad (\text{C.8})$$

If the incident light has wavelength  $\lambda_0$  in the vacuum and the etalon medium has refractive index  $n'$ , the light wave vector inside the medium is

$$k = \frac{2\pi}{\lambda_0} n' \quad (\text{C.9})$$

and the phase shift between two adjacent rays is

$$\Delta = k \cdot \overline{ABC} = \frac{4\pi}{\lambda_0} n' d \cos \theta' \quad (\text{C.10})$$

Now, indicating by  $T$  the overall etalon transmission coefficient and by  $R$  the reflection coefficient corresponding to one round-trip, the total amplitude of the electric field in some point after the etalon is the sum of those of the subsequent rays

$$E_T = E_0 T + E_0 T R e^{i\Delta} + E_0 T R^2 e^{i2\Delta} + E_0 T R^3 e^{i3\Delta} + \dots \quad (\text{C.11})$$

which is nothing but the geometrical series, that can be summed up ( $|R e^{i\Delta}| < 1$ ) to yield

$$E_T = E_0 T \sum_j (R e^{i\Delta})^j = \frac{E_0 T}{1 - R e^{i\Delta}} \quad (\text{C.12})$$

What we observe is actually the transmitted intensity

$$I_T = |E_T|^2 = |E_0|^2 \frac{T^2}{|1 - Re^{i\Delta}|^2} \quad (\text{C.13})$$

The denominator can be rewritten as

$$\begin{aligned} |1 - Re^{i\Delta}| &= (1 - Re^{i\Delta})(1 - Re^{-i\Delta}) \\ &= 1 - R(e^{i\Delta} + e^{-i\Delta}) + R^2 \\ &= 1 - 2R \cos \Delta + R^2 \\ &= 1 - 2R \left(1 - 2 \sin^2 \frac{\Delta}{2}\right) + R^2 \\ &= 1 - 2R + 4R \sin^2 \frac{\Delta}{2} + R^2 \\ &= (1 - R)^2 + 4R \sin^2 \frac{\Delta}{2} \\ &= (1 - R)^2 \left(1 + \frac{4R}{(1 - R)^2} \sin^2 \frac{\Delta}{2}\right) \end{aligned} \quad (\text{C.14})$$

So that the transmitted intensity becomes

$$I_T = I_0 \frac{T^2}{(1 - R)^2} \frac{1}{\left(1 + \frac{4R}{(1 - R)^2} \sin^2 \frac{\Delta}{2}\right)} \quad (\text{C.15})$$

One defines a *peak constant*

$$C_{\text{PEAK}} \equiv \frac{T^2}{(1 - R)^2} \quad (\text{C.16})$$

which is equal to 1 for an ideal surface such that  $1 = R + T$ . In a real surface, instead, some absorption  $A$  is present, so that  $1 = R + T + A$ . The peak constant in this case can be rewritten as

$$C_{\text{PEAK}} = \frac{(1 - A - R)^2}{(1 - R)^2} = \left(1 - \frac{A}{1 - R}\right)^2 \quad (\text{C.17})$$

Furthermore we shall define the *coefficient of finesse*<sup>1</sup>

$$F \equiv \frac{4R}{(1 - R)^2}. \quad (\text{C.18})$$

In the ideal etalon case we have  $A \simeq 0$ , which implies  $C_{\text{peak}} \simeq 1$ , so that Eq. (C.15) eventually reduces to

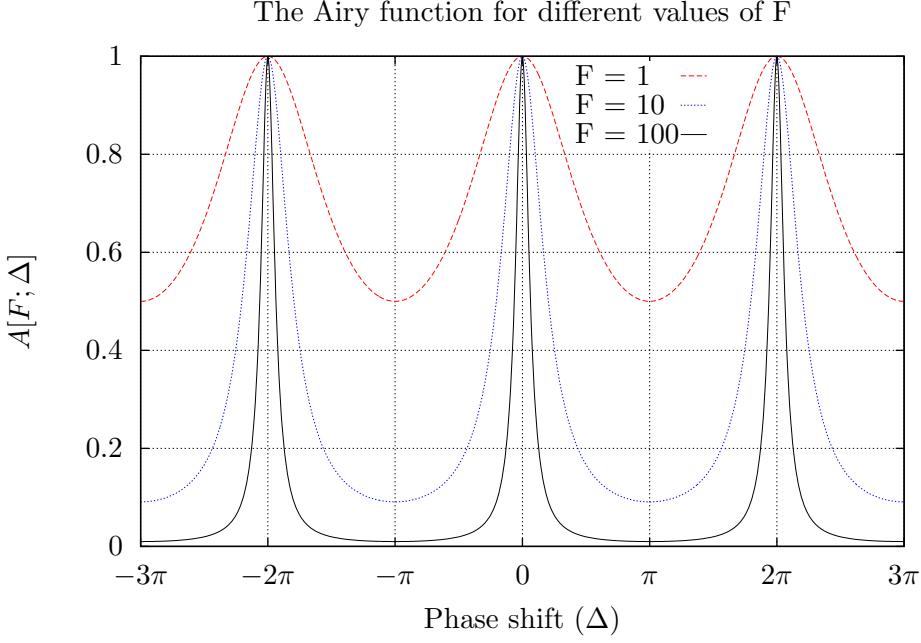
$$I_T = I_0 \frac{1}{1 + F \sin^2 \frac{\Delta}{2}} \quad (\text{C.19})$$

The transmitted intensity is thus given by the constant input intensity value, modulated by the so called *Airy function* plotted in Fig. C.4

$$\frac{I_T}{I_0} = \frac{1}{1 + F \sin^2 \frac{\Delta}{2}} \equiv A[F; \Delta] \quad (\text{C.20})$$

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<sup>1</sup>Not to be confused with the *finesse* defined further in this discussion (pg. 47). These parameters are strongly correlated, though, and literature is not uniform on which of them is to be called “finesse”.



**Figure C.4:** The Airy function peaks when the phase shift is an integer multiple of  $2\pi$ . As the finesse coefficient increases, the peaks become more sharp and their position is better defined.

### C.3 Interference pattern

As is clear from Fig. C.4, the interference maxima take place for  $\Delta = 2m\pi$ , where  $m$  is an integer representing the order of diffraction. From Eq. (C.10) we have

$$m = \frac{2n'}{\lambda_0} d \cos \theta' \quad (\text{C.21})$$

Looking at Eq. (C.15), we define the intensity at the maximum and at the minimum as

$$I_{\text{MAX}} \equiv \frac{I_T[\Delta = 2m\pi]}{I_0} = C_{\text{PEAK}} = \frac{T^2}{(1-R)^2} \quad (\text{C.22})$$

$$I_{\text{MIN}} \equiv \frac{I_T[\Delta = (2m+1)\pi]}{I_0} = \frac{T^2}{(1-R)^2 + 4R} = \frac{T^2}{(1+R)^2} \quad (\text{C.23})$$

We shall now define a *contrast factor*

$$\mathcal{C} \equiv \frac{I_{\text{MAX}}}{I_{\text{MIN}}} = \left( \frac{1+R}{1-R} \right)^2 = 1+F \quad (\text{C.24})$$

which is also a useful parameter in the characterization of an etalon.

To describe how defined are the peaks, we have to consider their full width at half maximum (FWHM). Thus we observe the points around a maximum whose intensity is  $I_T = I_{\text{MAX}}/2$ . They have a phase shift

$$\Delta = 2m\pi \pm \frac{\varepsilon}{2} \quad (\text{C.25})$$

where  $\varepsilon$  is now the FWHM expressed as a phase. Putting this into Eq. (C.15) we get the identity

$$\frac{1}{2} = \frac{1}{1 + F \sin^2 \frac{\varepsilon}{4}} \quad ;$$

$$F \sin^2 \frac{\varepsilon}{4} = 1$$

If now we approximate  $\sin(\varepsilon/4) \simeq \varepsilon/4$  we get the phase expression for the FWHM, as a function of the coefficient of finesse  $F$

$$\varepsilon = \frac{4}{\sqrt{F}} \quad (\text{C.26})$$

Two contiguous maxima are separated by the quantity known as *free spectral range* (FSR). In the frequency domain its value depends on the device, and is actually one of the parameters characterizing an etalon. In the phase domain its value is always  $2\pi$ , by definition. Doing the ratio between the peaks separation and their width, one gets a very important parameter which is called the *finesse* of the etalon

$$\mathcal{F} \equiv \frac{2\pi}{\varepsilon} = \frac{\pi}{2} \sqrt{F} = \frac{\pi \sqrt{R}}{1 - R} \quad (\text{C.27})$$

## C.4 Etalon as a spectroscope

It is possible to build a direct relationship between the angular separation of the rings and the wavelength  $\lambda_0$  of the incident light. We put ourself under the approximation of nearly perpendicular incident light, so that

$$\sin \theta' \simeq \theta'$$

$$\sin \theta \simeq \theta$$

Snell's law then simplifies to

$$\frac{\sin \theta'}{n'} = \frac{\sin \theta}{n} \quad \Rightarrow \quad \frac{\theta'}{n'} = \frac{\theta}{n}$$

The small angles approximation also implies

$$\cos \theta' \simeq 1 - \frac{\theta'^2}{2}$$

$$\simeq 1 - \left( \frac{n'}{n} \right)^2 \frac{\theta^2}{2}$$

These approximations being valid, we recall Eq. (C.21)

$$m = \frac{2n'}{\lambda_0} d \cos \theta' \quad \Rightarrow \quad m = \frac{2n'}{\lambda_0} d \left( 1 - \left( \frac{n'}{n} \right)^2 \frac{\theta^2}{2} \right)$$

For a normal incident wave we have

$$m_0 = \frac{2n'd}{\lambda_0} \equiv m_1 + e \quad (\text{C.28})$$

where we defined  $m_1$  and  $e$  as the integer and fractional part of  $m_0$ , respectively.

Putting together the above equations we find

$$\begin{aligned} \theta &= \frac{1}{n} \sqrt{\frac{n'\lambda_0}{d}} \sqrt{\frac{2n'd}{\lambda_0} - m} \\ &= \frac{1}{n} \sqrt{\frac{n'\lambda_0}{d}} \sqrt{m_1 - m + e} \end{aligned} \quad (\text{C.29})$$

Now, by redefining the integer part as  $m_1 - m = p - 1$ , we obtain the angle for the  $p$ th order:

$$\theta_p = \frac{1}{n} \sqrt{\frac{n'\lambda_0}{d}} \sqrt{p - 1 + e} \quad (\text{C.30})$$

and if we focus the rings onto a screen with a convergent lens, of focal ratio  $f$ , the diameter of the bright ring is

$$D_p^2 = (2f\theta_p)^2 = \frac{4n'\lambda_0 f^2}{n^2 d} (p - 1 + e). \quad (\text{C.31})$$