

# How to Install Erika Enterprise (Windows)

**Avees Lab**

# Cygwin 설치

<http://Cygwin.com> 접속 후 운영체제에 맞는 Cygwin 다운로드

# Cygwin

*Get that [Linux](#) feeling - on Windows*

## This is the home of the Cygwin project

### What...

#### ...is it?

Cygwin is:

- a large collection of GNU and Open Source tools which provide functionality similar to a [Linux distribution](#) on Windows.
- a DLL (cygwin1.dll) which provides substantial POSIX API functionality.

#### ...isn't it?

Cygwin is not:

- a way to run native Linux apps on Windows. want it to run on Windows.
- a way to magically make native Windows apps run on Linux. Again, you need to build your apps *from scratch* for Linux functionality.

The Cygwin DLL currently works with all recent, commercially released x86 32 bit and 64 bit versions of Windows, starting with Windows XP SP3.

For more information see the [FAQ](#).

### Current Cygwin DLL version

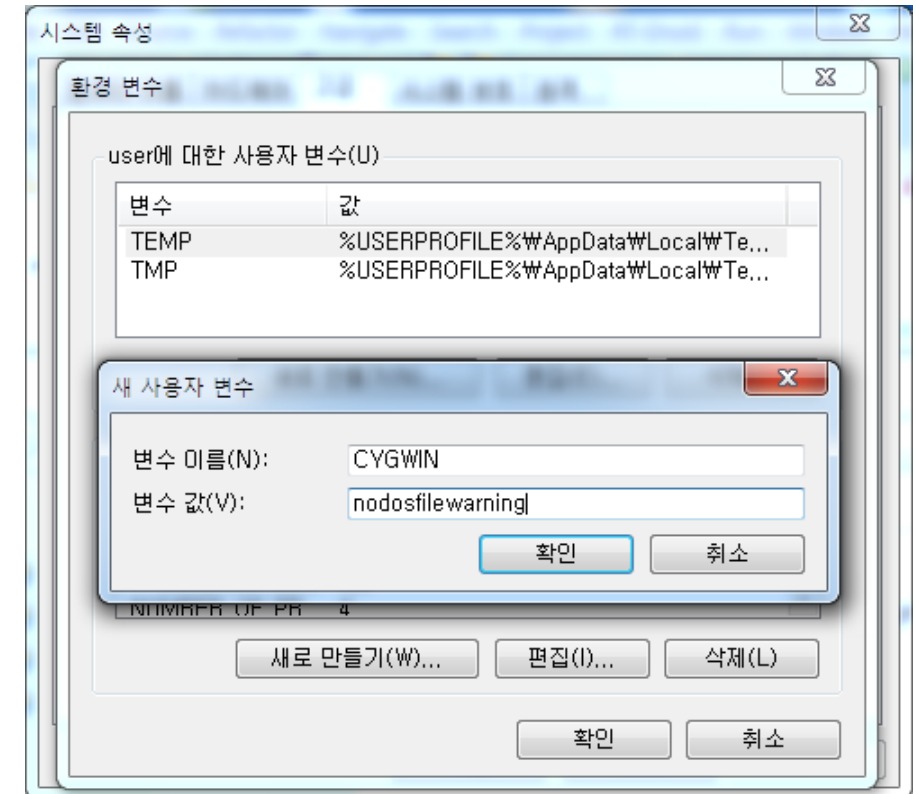
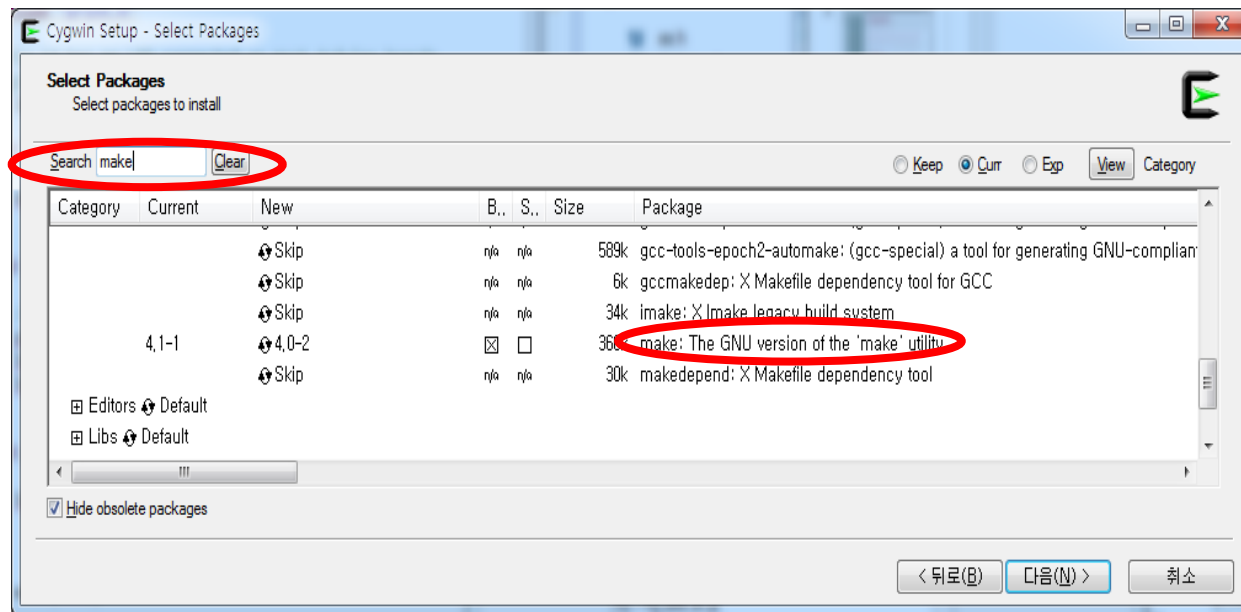
The most recent version of the Cygwin DLL is [2.0.0](#). Install it by running [setup-x86.exe \(32-bit installation\)](#) or [setup-x86\\_64.exe \(64-bit installation\)](#).

운영체제에 맞는  
Cygwin 다운로드 !

# Cygwin 설치

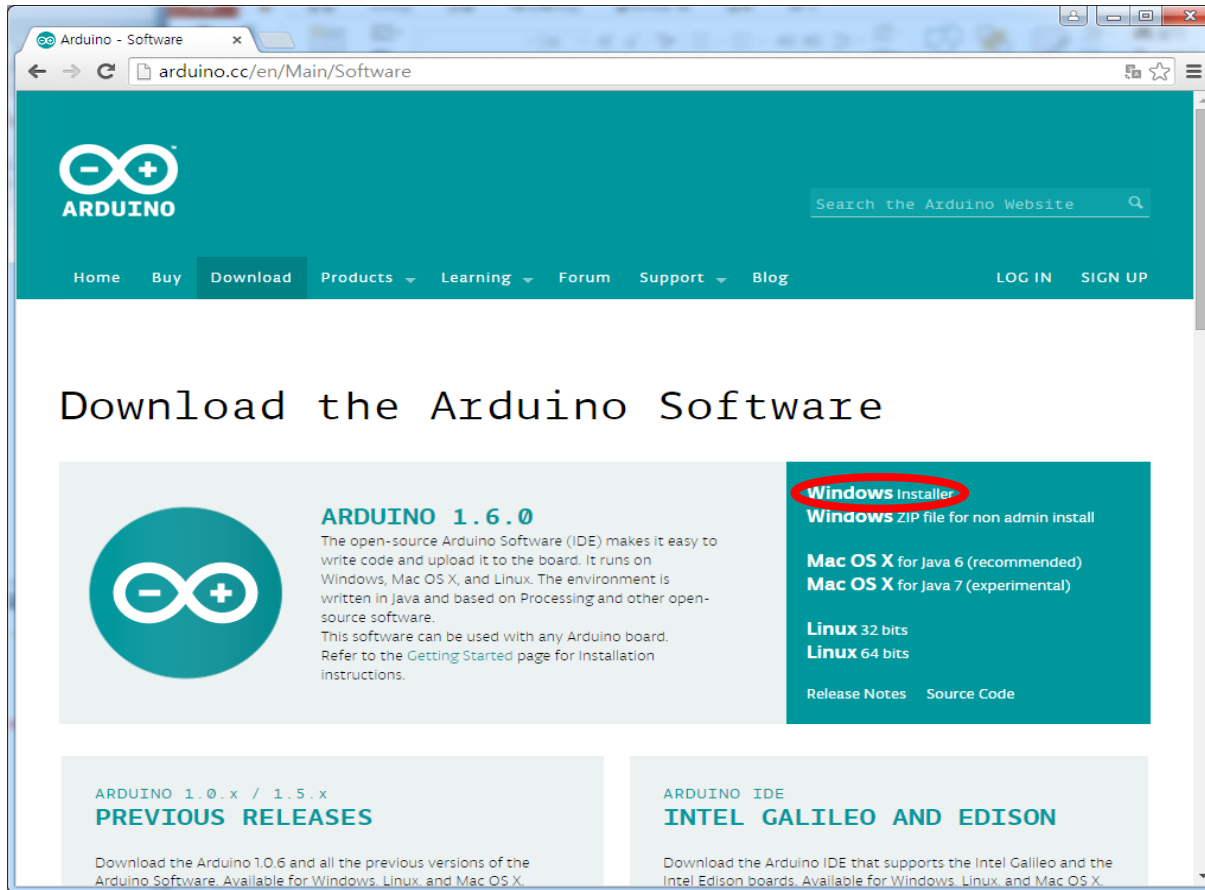
설치시 make 추가 **Devel Category**

설치 후 사용자 변수 추가 (제어판 -> 시스템 -> 고급시스템설정 -> 환경변수)



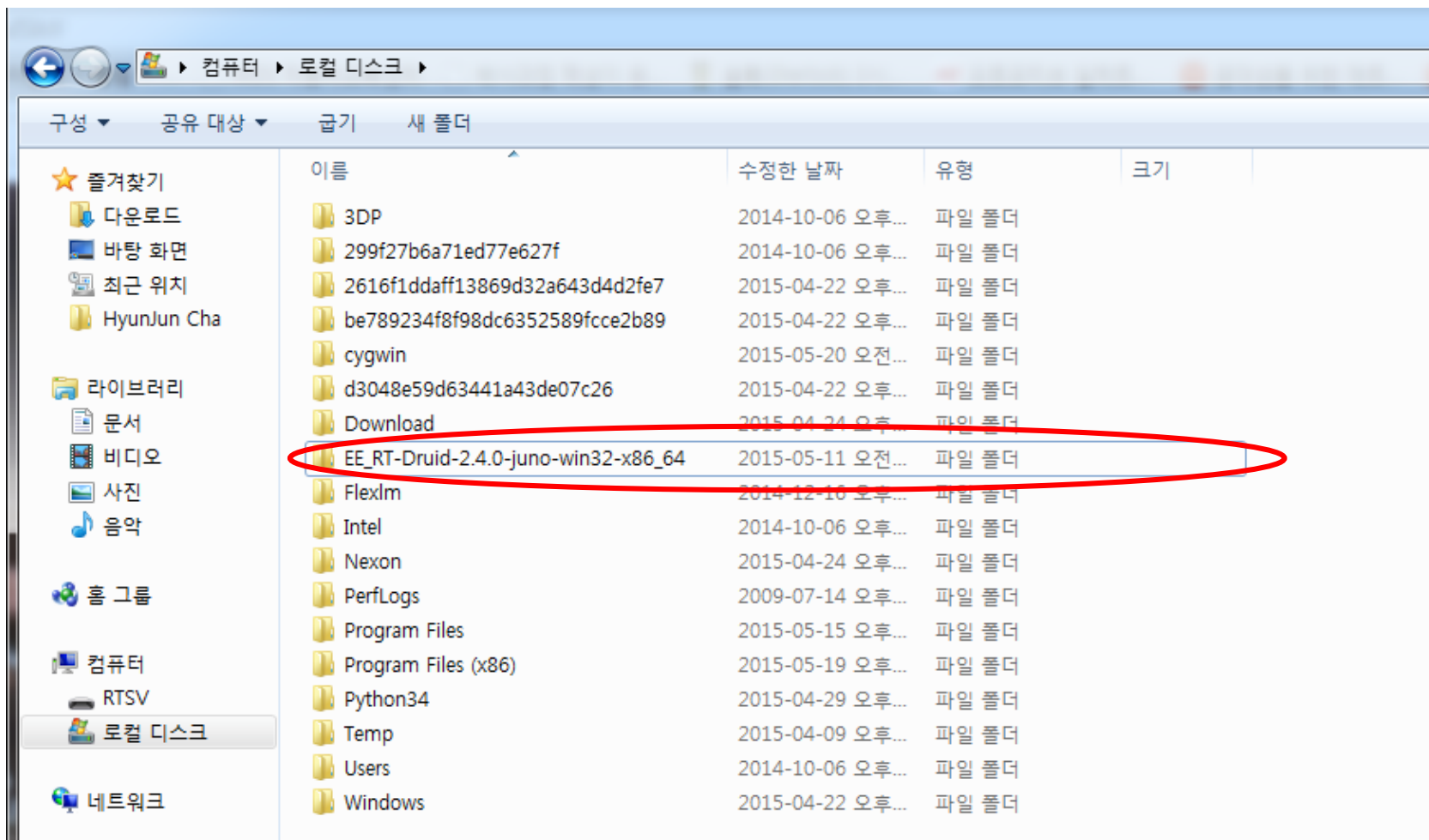
# Arduino IDE 설치

설치시 경로를 C:\Warduino-1.6.0 로 지정



# Erika Enterprise IDE 설치 (압축만 풀면 됨)

운영체제에 맞는 RT-Druid 압축파일 복사 후 압축 풀기  
압축을 푼 다음 폴더를 C:\로 복사



# Erika Enterprise IDE 설치

다음과 같이 수정

```
##
## Author: 2014, Giuseppe Serano
##

##Check if is the stack that we're asking for
ifeq ($(call iseeopt, __ARDUINO_SDK__), yes)

## Check the Arduino library selection
ifeq ($(findstring __LIB_ARDUINO_SDK__, $(LIB_OPT)), __LIB_ARDUINO_SDK__)
INCLUDE_ARDUINO_SDK = YES
endif

## Check if it's selected all libs inclusion
ifeq ($(call iseeopt, __BUILD_ALL_LIBS__), yes)
INCLUDE_ARDUINO_SDK = YES
endif

##
## If the library is required
##
ifeq ($(INCLUDE_ARDUINO_SDK), YES)

ifndef ARDUINO_SDK_FILES
export ARDUINO_SDK_FILES = C:/arduino-1.6.0
endif

ifeq ($(call iseeopt, __RTD_LINUX__), yes)
ARDUINO_SDK_ROOT := #
$(call short_native_path, $(ARDUINO_SDK_FILES))
else
ARDUINO_SDK_ROOT := #
$(shell cygpath $(call short_native_path, $(ARDUINO_SDK_FILES)))
endif

EE_VPATH += $(ARDUINO_SDK_ROOT)

EEOPT += ARDUINO=160

##
## Library code
##
## Add the inc path to the include pathlist
## New include mechanism

INCLUDE_PATH := $(ARDUINO_SDK_ROOT)/hardware/arduino/avr/cores/arduino #
$(INCLUDE_PATH)

ifeq ($(call iseeopt, __ARDUINO_UNO_328__), yes)
INCLUDE_PATH := $(ARDUINO_SDK_ROOT)/hardware/arduino/avr/variants/standard #
$(INCLUDE_PATH)
endif
```

C:\WEE\_RT-Druid-2.4.0-juno-win32-x86\_64\W  
eclipse\plugins\com.eu.evidence.ee\_2.4.0.20141105\_0021\W  
ee\_files\contrib\arduino\cfg 밑에 있는  
[libcfg.mk](http://libcfg.mk) 파일 수정

# Erika Enterprise IDE 설치

다음과 같이 수정

```
ifeq ($(call iseeopt, __ATMEGA__), yes)
```

```
ifeq ($(call iseeopt, __AVR8__), yes)
```

```
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/wiring.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/wiring_digital.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/wiring_analog.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/wiring_pulse.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/wiring_shift.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/CDC.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/HardwareSerial.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/HID.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/IPAddress.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/new.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/Print.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/Stream.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/Tone.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/USBCore.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/WMath.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/WString.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/hooks.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/WInterrupts.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/abi.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/HardwareSerial0.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/HardwareSerial1.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/HardwareSerial2.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/HardwareSerial3.cpp
```

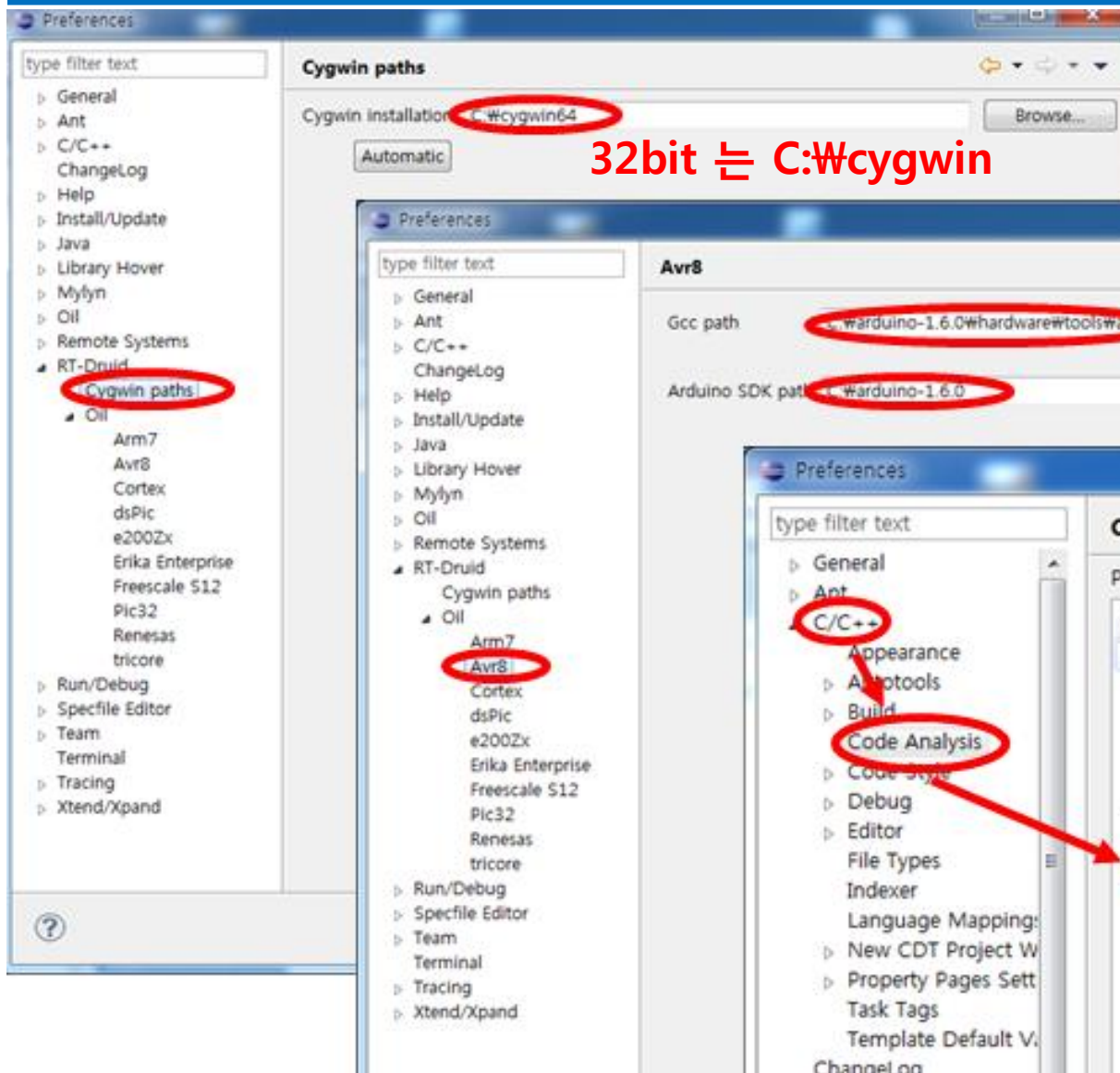
최신 버전 Arduino의  
바뀐 소스코드 리스트

Copy&paste용



```
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/wiring.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/wiring_digital.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/wiring_analog.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/wiring_pulse.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/wiring_shift.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/CDC.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/HardwareSerial.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/HID.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/IPAddress.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/new.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/Print.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/Stream.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/Tone.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/USBCore.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/WMath.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/WString.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/hooks.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/WInterrupts.c
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/abi.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/HardwareSerial0.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/HardwareSerial1.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/HardwareSerial2.cpp
EE_SRCS_ARDUINO_SDK += hardware/arduino/avr/cores/arduino/HardwareSerial3.cpp
```

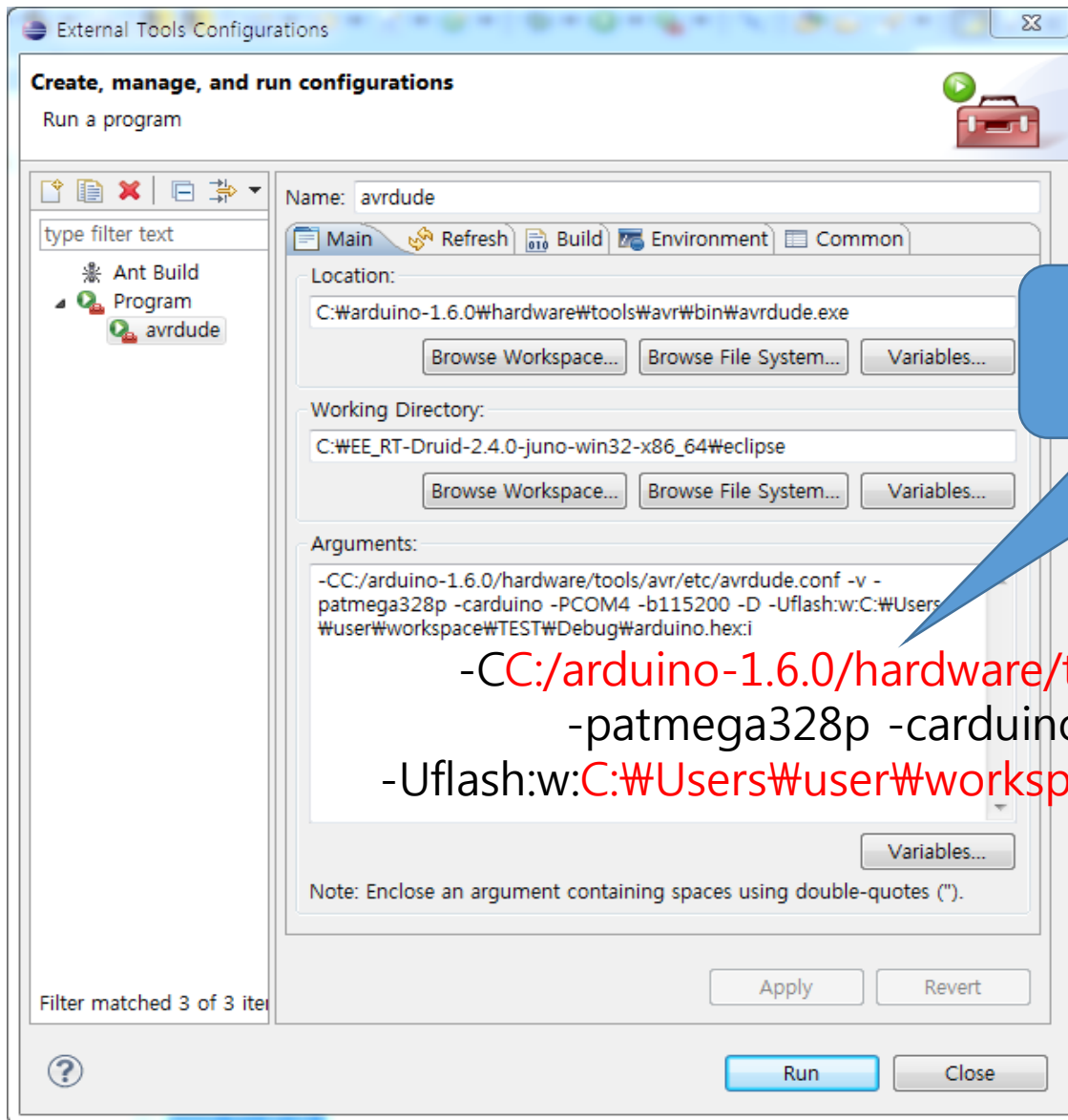
# eclipse의 Window -> Preference 수정



eclipse 가 실행되지 않을 때에는  
압축파일에 들어있는 jre파일 설치



# Run -> External Tools -> External Tools Configurations 추가 (avrdude)

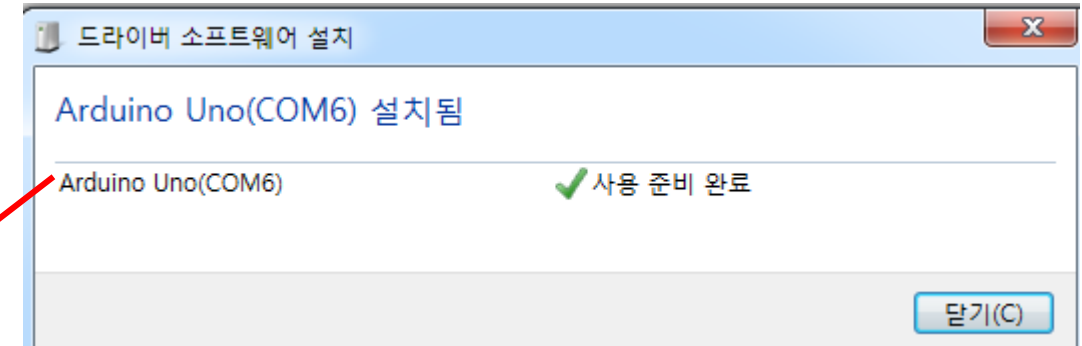
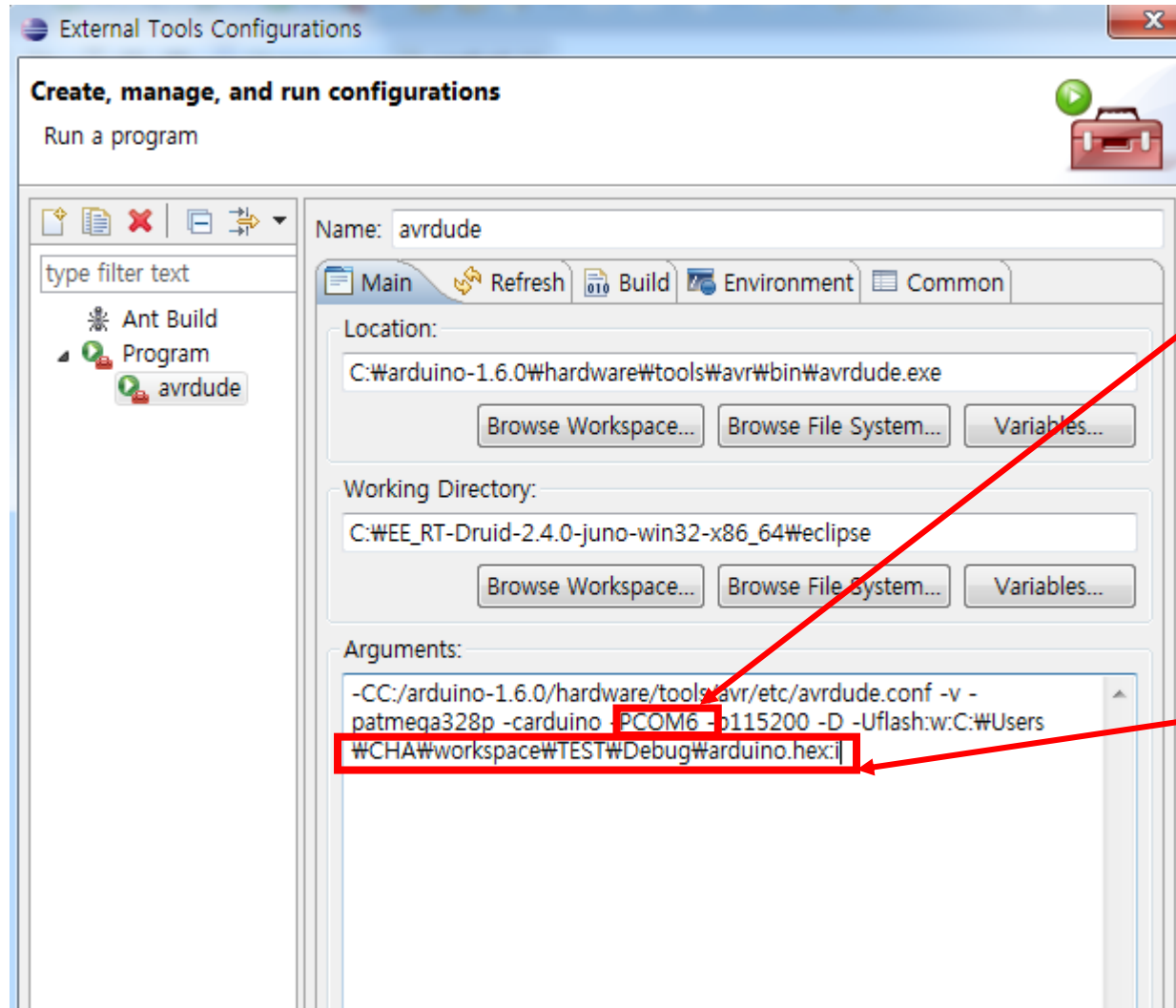


필요한 부분은 수정

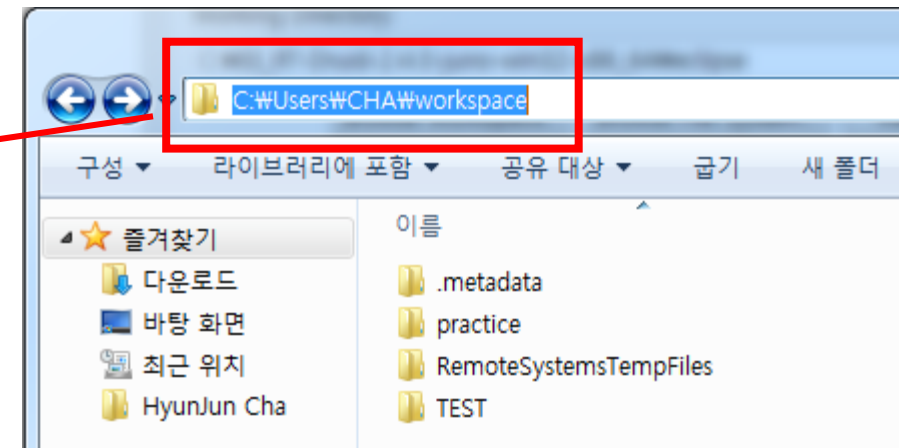
`-CC:/arduino-1.6.0/hardware/tools/avr/etc/avrdude.conf -v -  
-patmega328p -carduino -PCOM4 -b115200 -D  
-Uflash:w:C:\Users\user\workspace\TEST\Debug\arduino.hex:i`

붉은 글씨부분의 파일 경로를 확인하고  
공백에 유의할 것 !  
COM뒤에 숫자는 본인 컴퓨터에 맞게 수정  
다음 장의 예시 확인 !

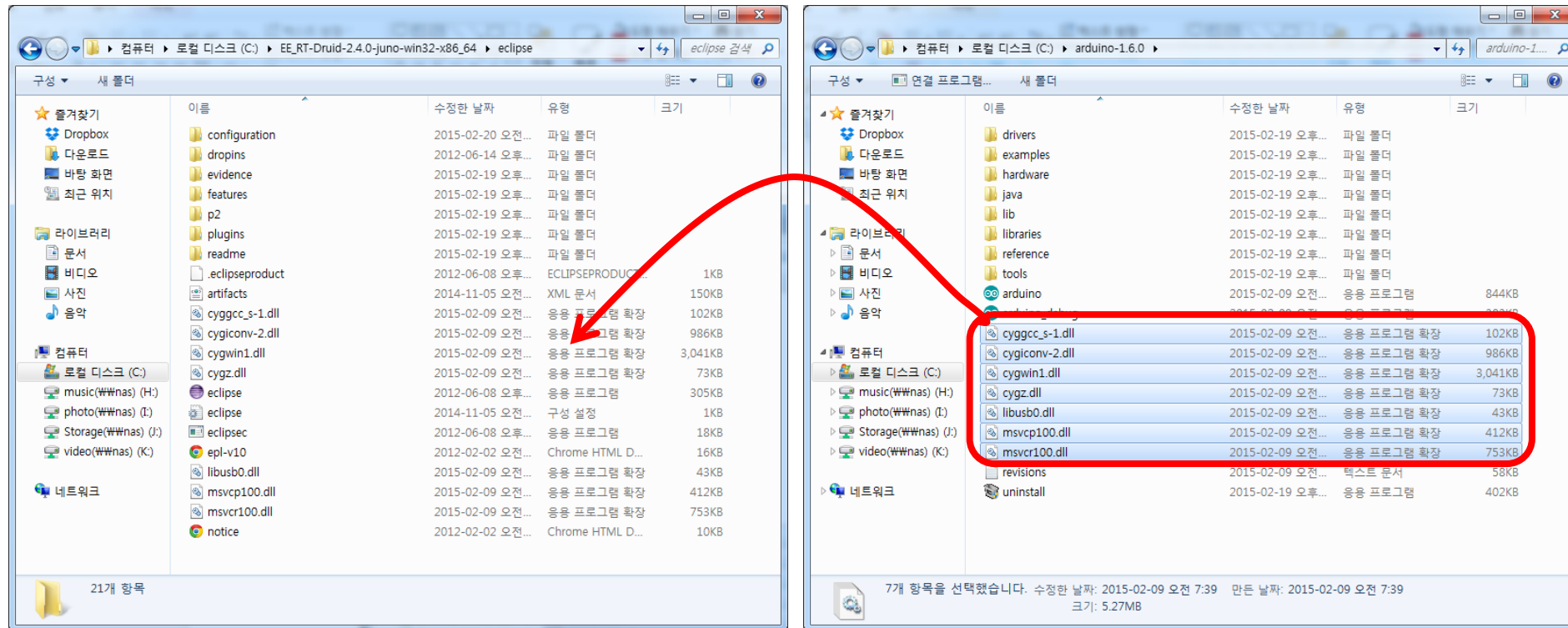
# Run -> External Tools -> External Tools Configurations 추가 (예시)



파일 경로를 확인하고 공백에 유의할 것 !

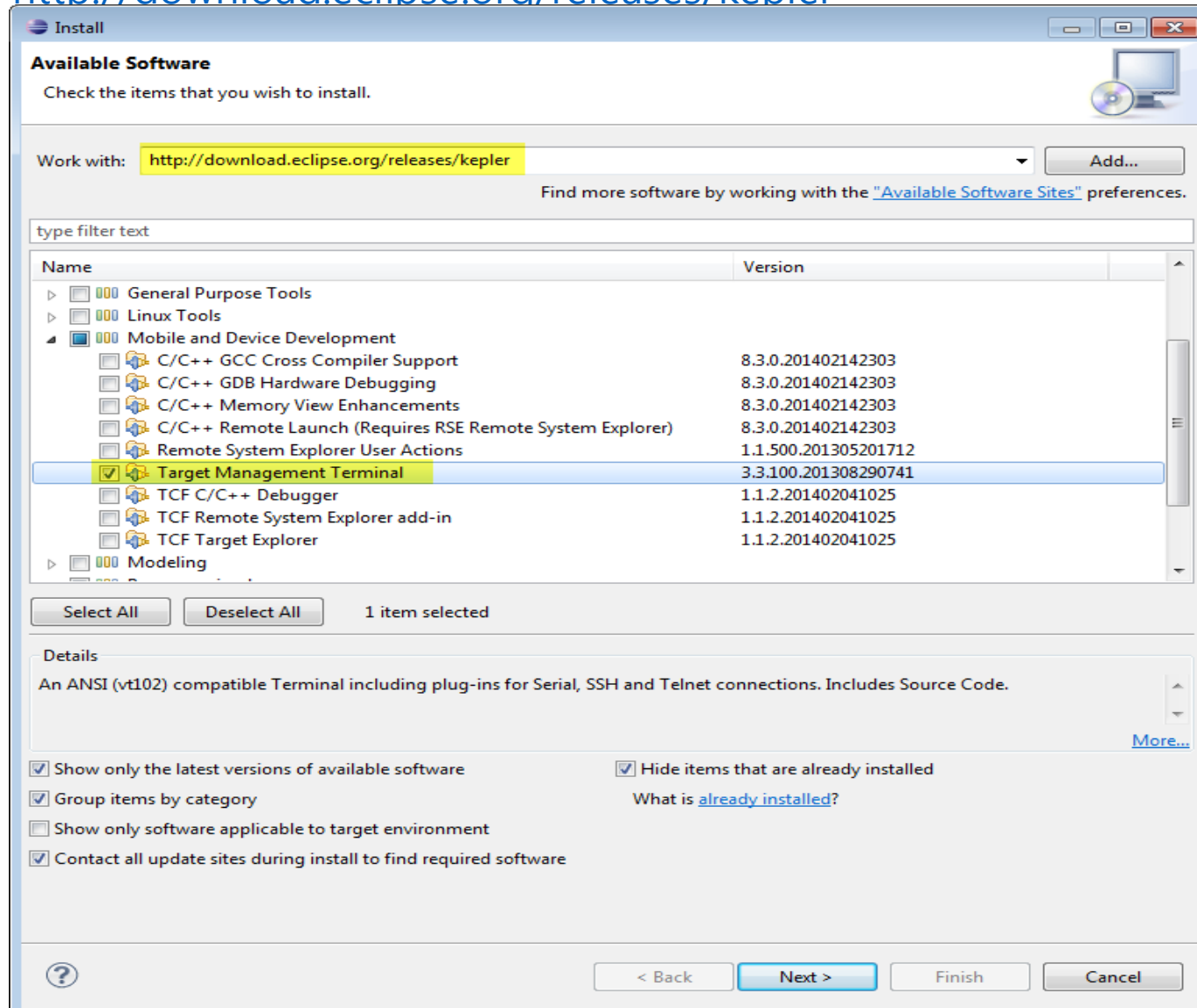


# Cygwin dlls eclipse 디렉토리에 복사 (avrdude 실행에 필요)



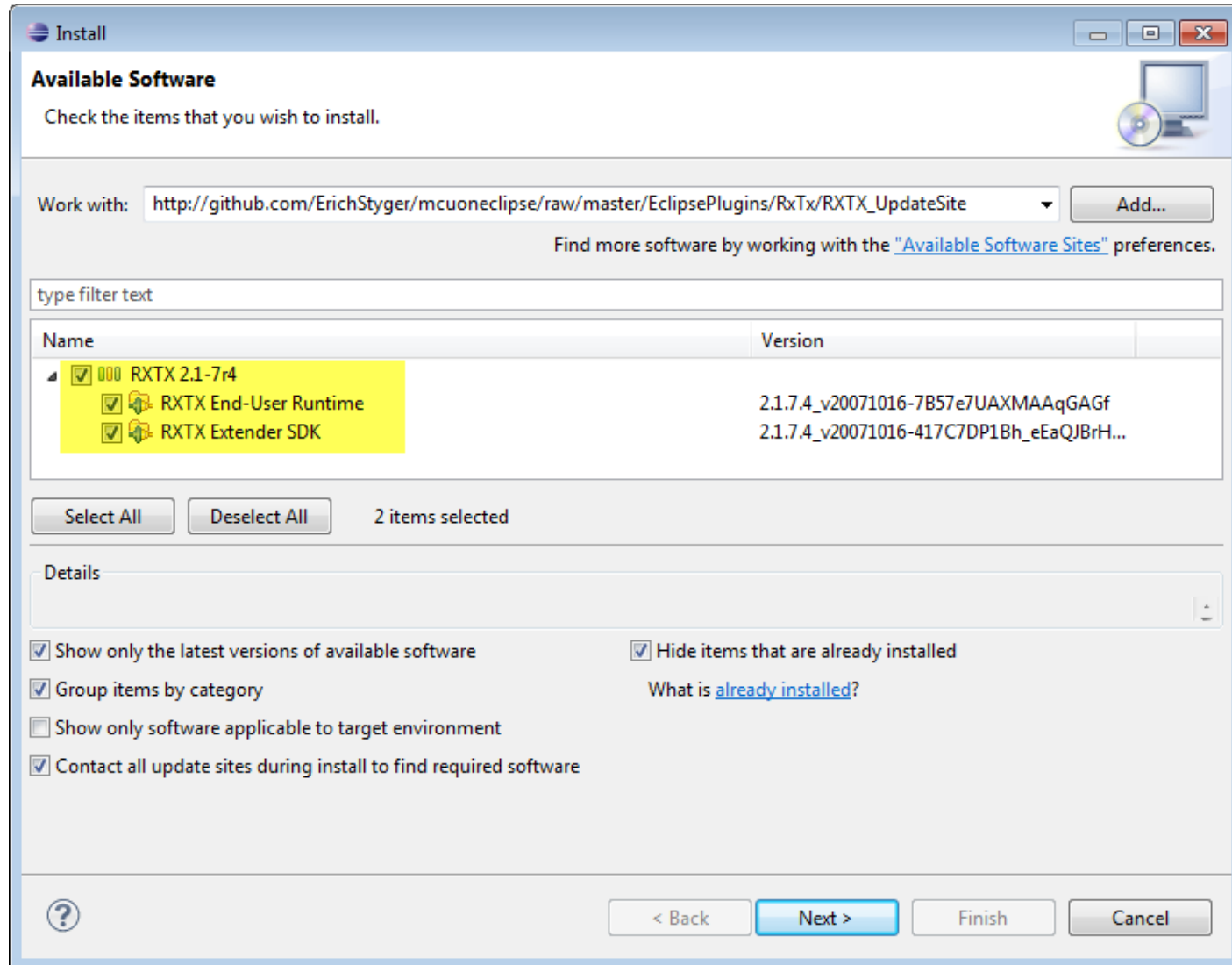
# Eclipse에서 Help -> Install New Software

<http://download.eclipse.org/releases/kepler>



# Eclipse에서 Help -> Install New Software

<http://rxtx.qbang.org/eclipse>

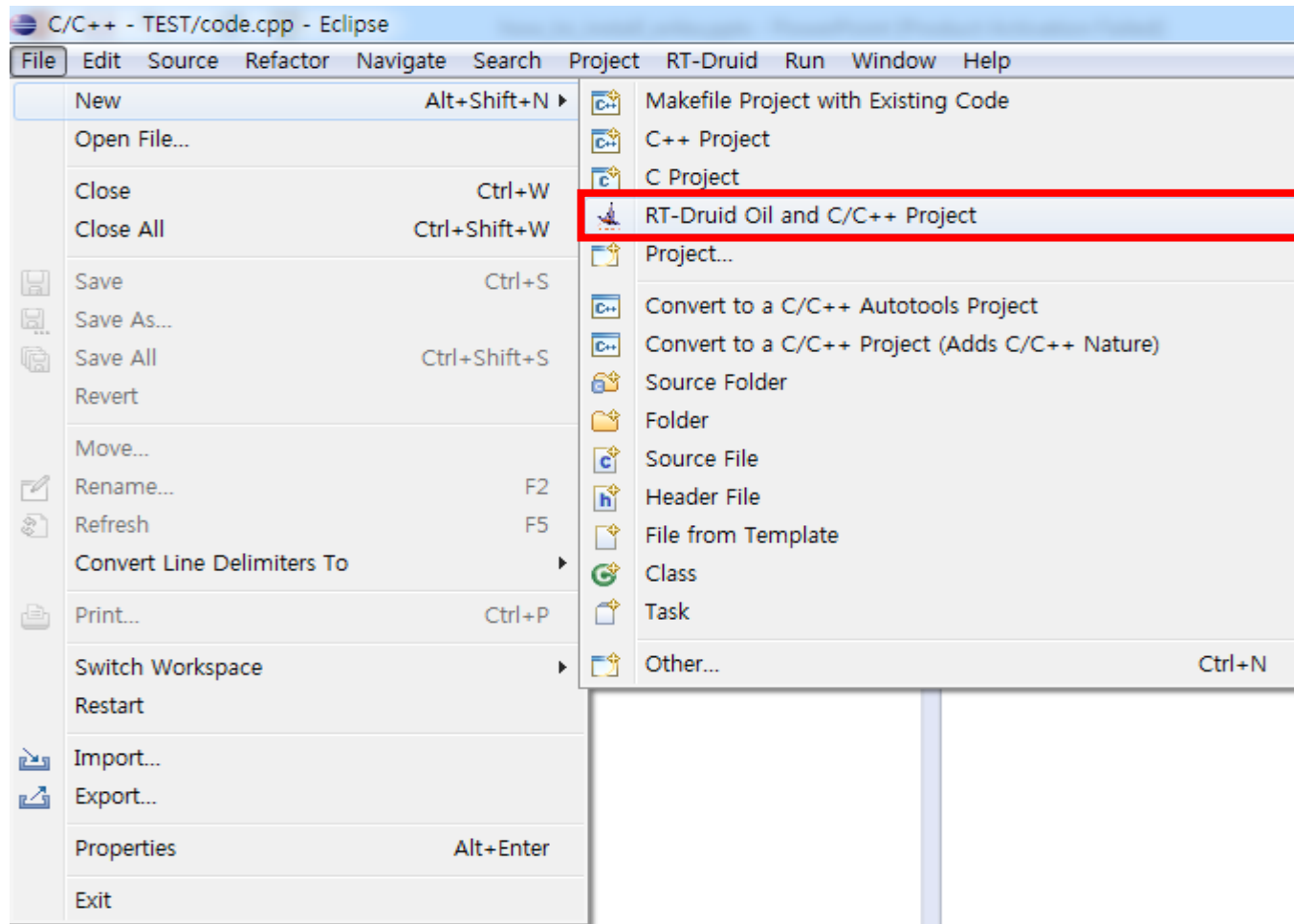


<http://mcuoneclipse.com/2014/03/23/serial-terminal-view-with-eclipse-kepler/>

참고사이트.

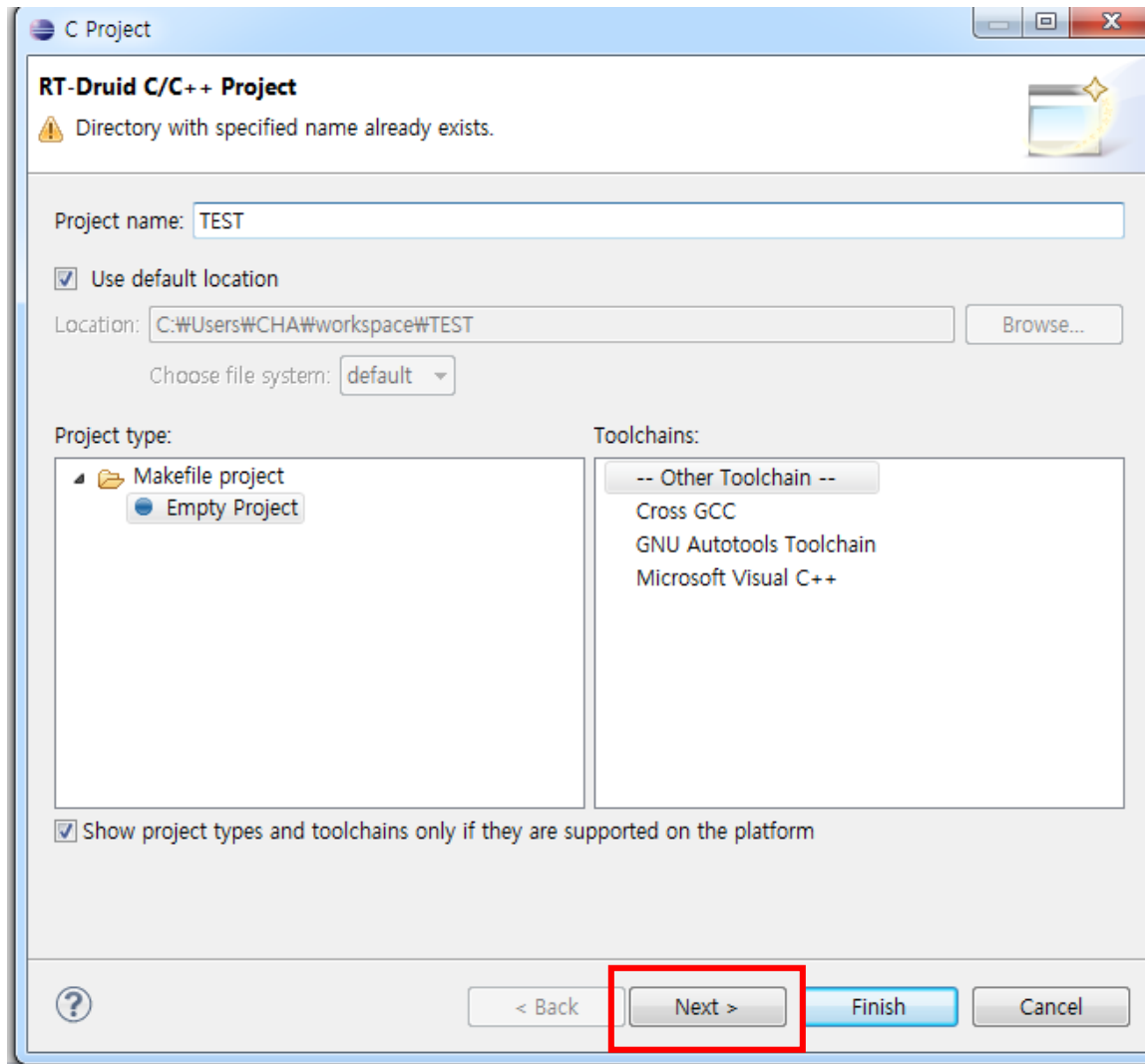
# eclipse Demo 파일 만들기

eclipse 실행 -> New -> RT Druid Oil and C/C++ Project

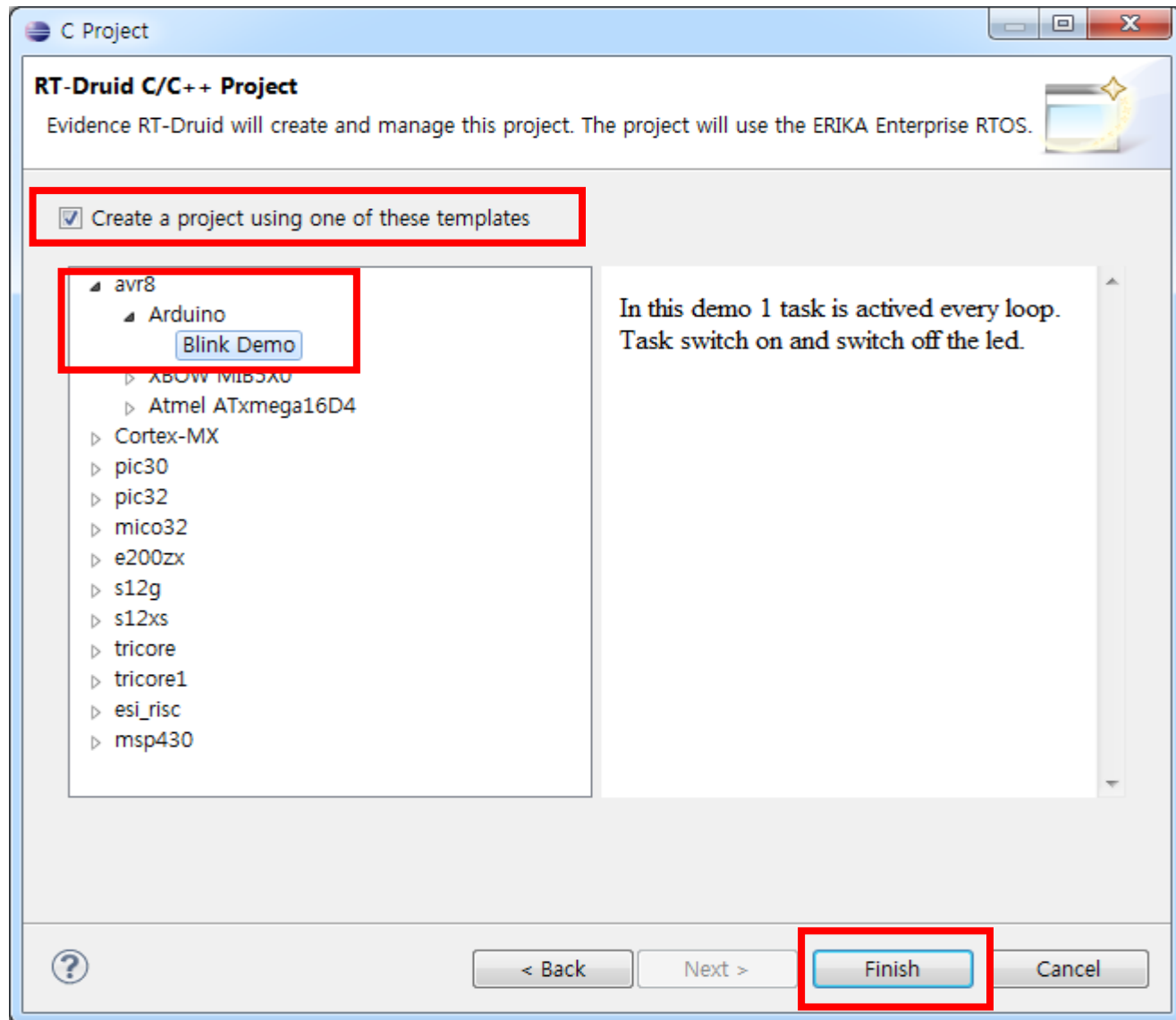


# eclipse Demo 파일 만들기

Project name : TEST 후 Next 버튼 클릭



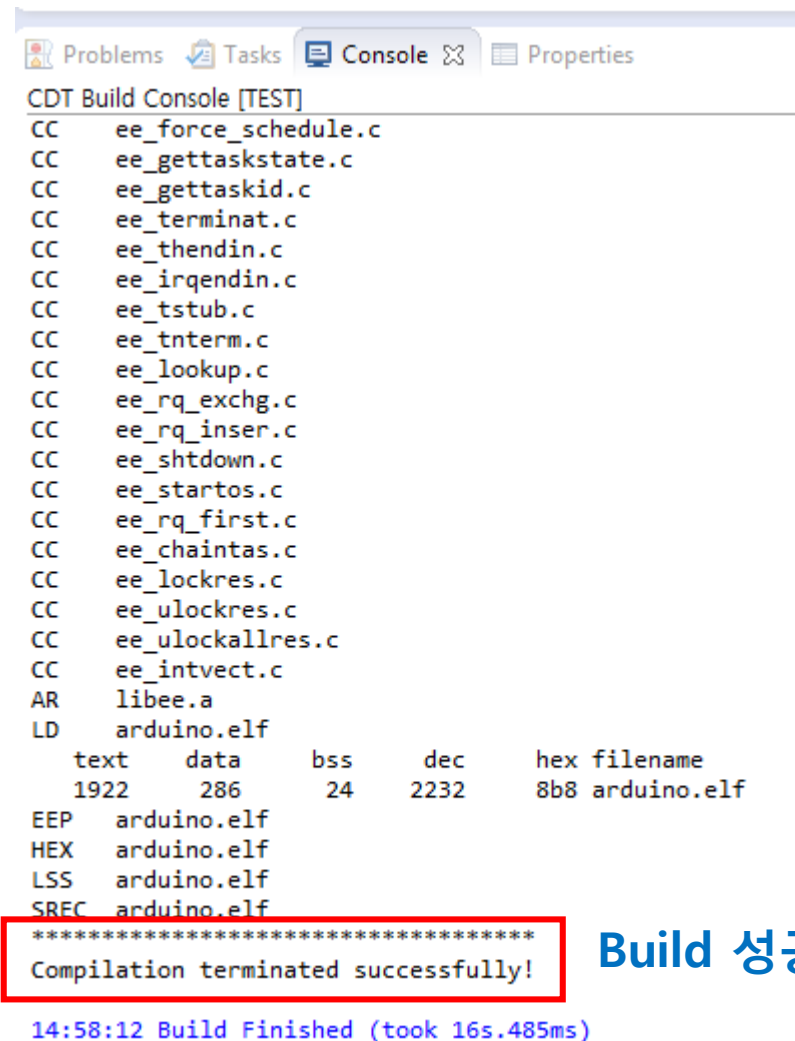
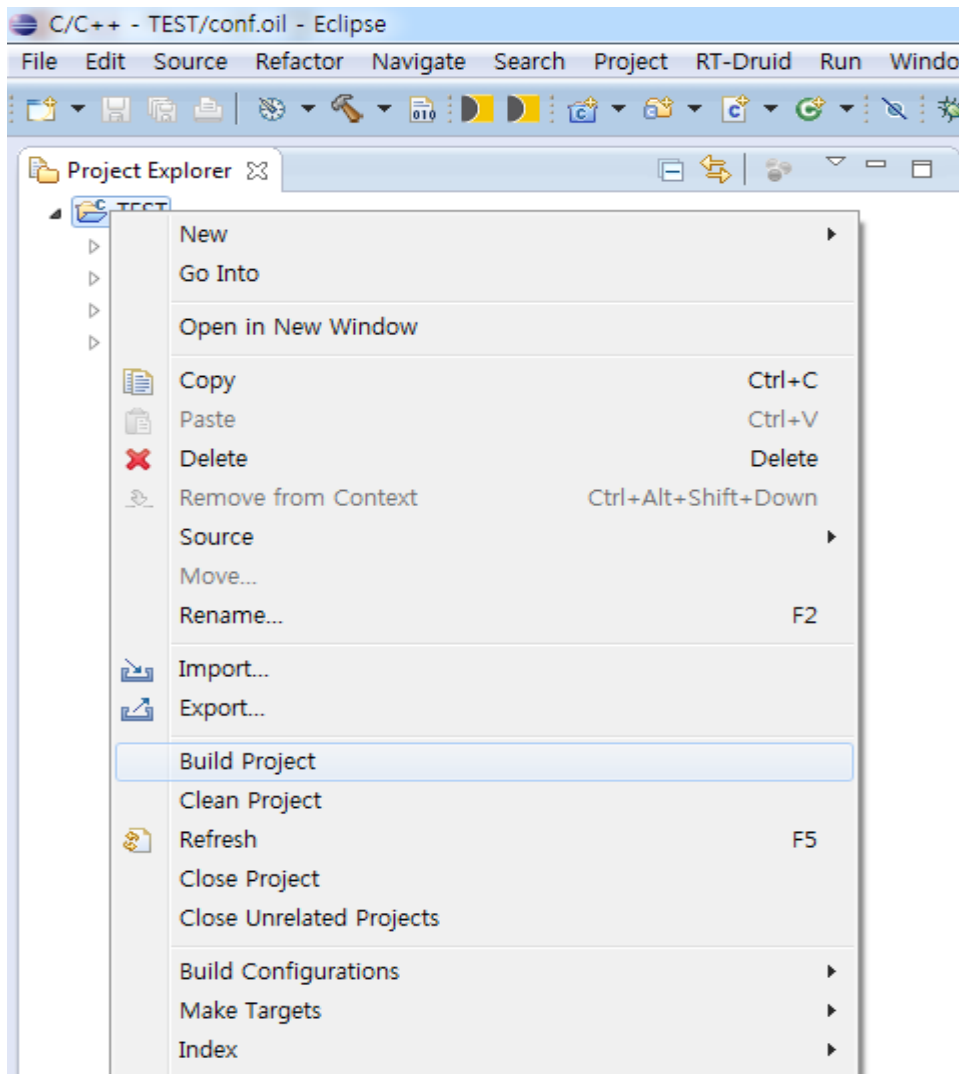
# eclipse Demo 파일 만들기





# eclipse Demo Build

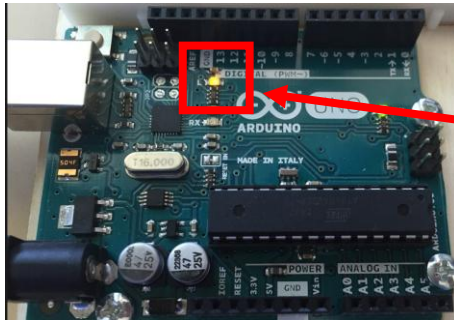
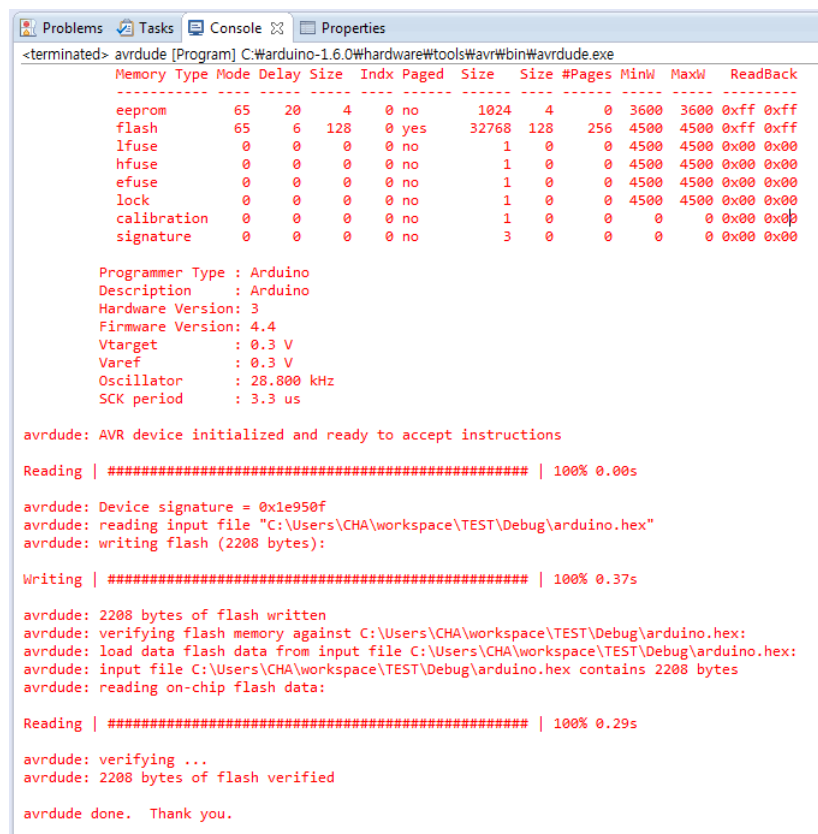
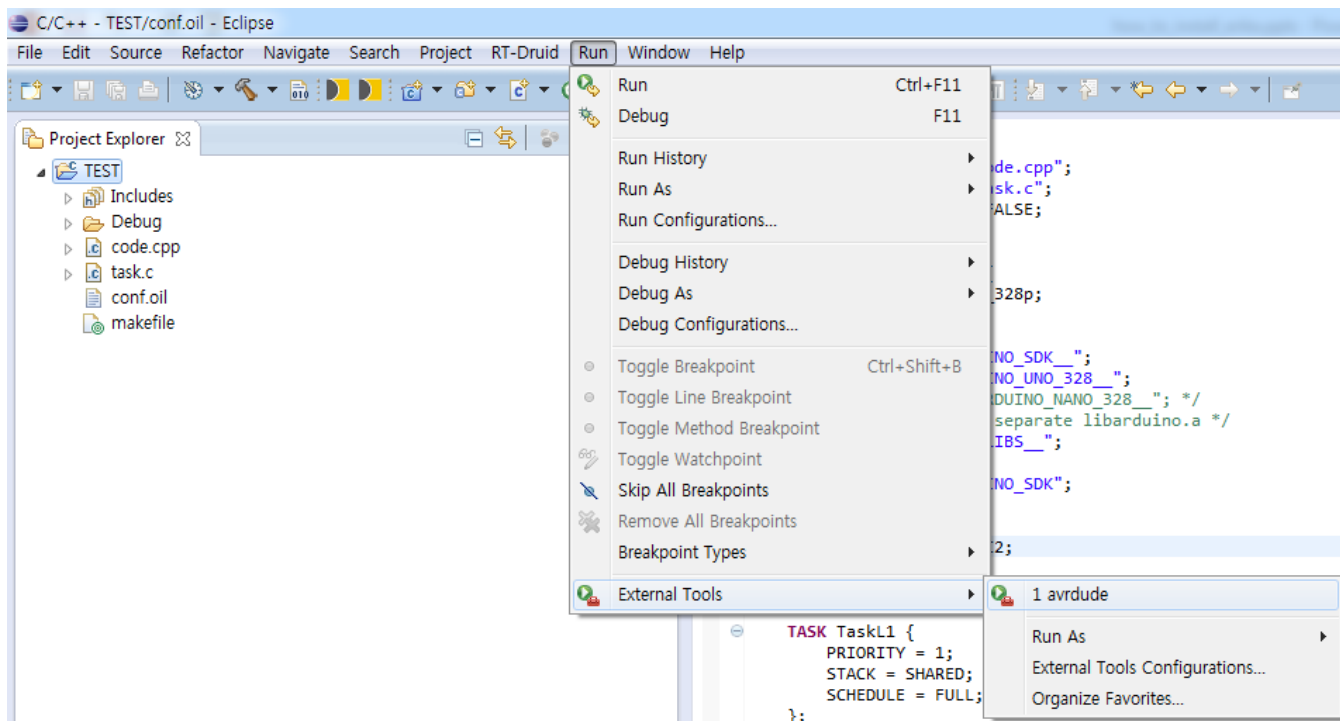
TEST 우클릭 후 Build Project 클릭



Build 성공시 나오는 문구

# Arduino에 업로드

Run -> External Tools -> avrdude 클릭



업로드 성공시 나오는 문구 !  
보드의 LED가 깜빡거리는 것을 확인!

**THANK YOU**