# Introduction to JACK Intelligent Software Agents

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#### Outline

- What is JACK?
- Review of the BDI Model
- JACK Concepts
  - Agents
  - Beliefs
  - Events
  - Plans
  - Capabilities
- The JACK Development Environment
- JDE Design Diagrams
- Resources

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#### What is JACK?

- Commercial Agent Toolkit
  - Developed by Agent Oriented Software (AOS) in Melbourne
- Agent oriented programming language
- Team oriented programming language
- A set agent oriented extensions to Java and an agent oriented run time environment.
- Agent oriented development environment (JDE)
- A set of supporting tools and infrastructure

# **JACK Applications**

- Modelling human decision making in multi-agent simulations.
- Control of unmanned vehicles.
- RoboCup
- Manufacturing
- ..

#### Beliefs, Desires and Intentions

Internal mental attitudes of a rational BDI agent (or mental state):

#### Beliefs

What an agent believes about the world, itself and other agents (informational).

#### **Desires**

What an agent want to achieve (motivational).

#### Intentions

How the agent tries to achieve desires (deliberational).

#### Rational Agency and BDI

Daniel Dennet: Folk Psychology

Michael Bratman: Rational Agency

Rao and Georgeff: Formal Logical Framework

Programming Languages: PRS, dMARS, JACK, JAM, C-PRS, IRMA

# Theoretical BDI Interpreter (Rao and Georgeff)

#### **BDI** Interpreter

```
initialize-state();
repeat
    options := option-generator(event-queue);
    selected-options := deliberate(options);
    update-intentions(selected-options);
    execute();
    get-new-external-events();
    drop-successful-attitudes();
    drop-impossible-attitudes();
end repeat
```

#### Adapted from Wooldridge...

```
procedure AGENT CONTROL LOOP 1
    while True do
        observe-the-world();
        update-internal-world-model();
        deliberate-about-what-intention-to-achieve-next()
        use-means-end-reasoning-to-get-a-plan-for-next-intention()
        execute-the-plan
    end while
end procedure
```

#### Adapted from Wooldridge...

```
procedure AGENT CONTROL LOOP 2(B_0)
B \leftarrow B_0
while True do
\rho \leftarrow \text{get\_next\_percept}();
B \leftarrow \text{brf}(B, \rho);
D \leftarrow \text{deliberate}(B);
\pi \leftarrow \text{plan}(B, I);
execute(\pi);
end while
end procedure
```

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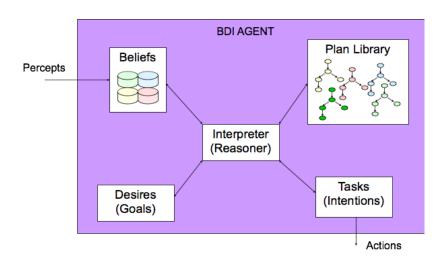
#### Adapted from Wooldridge...

```
procedure AGENT CONTROL LOOP 3(B_0, I_0)
     B \leftarrow B_0
     I \leftarrow I_0
    while True do
          \rho \leftarrow \text{get\_next\_percept()};
          B \leftarrow \mathsf{brf}(B, \rho);
          D \leftarrow \text{options}(BI);
          I \leftarrow \text{filter}(B, D, I);
          \pi \leftarrow \mathsf{plan}(B, I);
          execute(\pi);
     end while
end procedure
```

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#### Ideas Behind JACK

- Implementations of the BDI model
- Idea of plans as reciples (pre-planning)
- Least commitment
- Bounded rationality
- Dynamic environment
- Goals, beliefs, plans
- Intentions and run-time (not design time) constructs



# BDI Execution Concepts in JACK

# BDI Dynamics (1)

- An event occurs.
  - A goal is posted (internal).
  - A change in the environment and hence a change in belief (external).
- 2 Agent reasoner searches through the plan library to find the set of plans which can handle this event (defined by the invocation condition).
- This may result in in 10 plans out of 500 which can handle the event. Out of these 10 plans, the agent reasoner then chooses only those which are appropriate for this context that is, the current situation.

# BDI Dynamics (2)

- 5 This may result in 6 plans out of the 10 which are applicable in this context.
- The agent then chooses one of the plans, puts it on the **intention stack**, and starts executing the plan steps in the plan.
- This executing plan is called an **intention** to achieve the original **goal**.
- If the plan fails, the agent will try on of the other applicable plans until one of them succeeds in achieving the goal or all of them fail, in which case the goal will fail.

# **BDI Dynamics Notes**

- It is possible to determine which plan is chosen in the applicable plan set by using meta-level reasoning.
- Plans can wait until particular beliefs are satisfied.
- Plan steps can involve trying to achieve sub-goals.
- When trying to achieve a sub-goal, the existing plan is suspended and the new plan is put on top of the **intention stack**.

# Setting Up the JACK Environment

#### These instructions were correct in 2003

Needs Java 1.4.x, does not yet work with Java 1.5

```
Windows set CLASSPATH=c:\ aos\ lib\ jack.jar;.
```

Bash CLASSPATH=/aos/jack/lib/jack.jar:. export CLASSPATH

csh/tcsh setenv CLASSPATH=/usr/local/aos/jack/lib/jack.jar:.

### JACK File Types

- .jack Any JACK object definition.
- .agent JACK agent definition.
  - .cap JACK capability definition.
  - .plan JACK plan definition.
- .event JACK event definition.
  - .bel JACK beliefset definition.
- .view JACK view definition.
- .java Java class or interface definition.

# Compiling JACK

The JACK Build is a two step process:

- **1** Generate Java code from the original .agent, .plan, .bel .event etc. files.
- Compile the Java code

#### Building JACK code...

\$ java aos.main.JackBuild

#### Running is the same as Java programs...

\$ java Test

# JACK Agent Language (JAL)

The JACK Agent Language extends Java to support Agent Oriented programming:

- It defines new base classes, interfaces and methods.
- It provides extensions to the Java syntax to support new agent-oriented classes, definitions and statements.
- It provides semantic extensions (runtime differences) to support the execution model required by an agent-oriented software system.

#### Class Level Constructs in JAL

- Agent Used to define the behaviour of an intelligent software agent. This includes capabilities an agent has, what type of messages and events it responds to and which plans it will use to achieve its goals.
- Capability Allows the functional components that make up an agent to be aggregated and reused. A capability can be made up of plans, events, beliefsets and other capabilities that together serve to give an agent certain abilities.
- BeliefSet The beliefset construct represents agent beliefs using a generic relational model.
  - View The view construct allows general purpose queries to be made about an underlying data model. The data model may be implemented using multiple beliefsets or arbitrary Java data structures.
  - Event The event construct describes an occurrence in response to which the agent must take action.
    - Plan An agent's plans are analogous to functions. They are the instructions the agent follows to try to achieve its goals and handle its designated events.

```
plan MovementResponse extends Plan
       #handles event RobotMoveEvent moveResponse;
       #uses agent implementing RobotInterface robot;
       static boolean relevant (RobotMoveQEvent ev)
              return (ev.ID == RobotMoveQEvent.REPLY_SAFE || ev.ID == RobotMoveQEvent.REPLY_DEAD);
       body()
              if (moveResponse.ID==REPLAY_SAFE)
              System.err.println("Robot_Safe_to_Move");
              robot.updatePosition(moveResponse.Lane, moveResponse.Displacement);
              else
                      // robot didn't make it
                      System.err.println("Robot_is_Dead");
                      robot.die();
```

### Agent Declarations – .agent

- BeliefSets and Views which the agent can use and refer to.
- *Events* (both internal and external) that the agent is prepared to handle.
- Plans that the agent can execute.
- *Events* the agent can post **internally** (to be handled by other plans).
- Events the agent can send externally to other agents.

```
agent Pilot extends Agent
       #private data Position myPosition;
       #private data Position airportPosition:
       #private data FuelLevel fuelRemaining;
       #handles event TakeOffClearance clearedForTakeOff;
       #posts event StormDetected detectedStorm;
       #sends event RequestLanding landingRequest;
       #uses plan TakeOff;
       #uses plan Cruise;
       #uses plan LandAircraft;
       #uses plan AvoidStorm;
       #has capability EmergencyLanding elanding;
       Pilot(String name)
              super(name);
```

# Events (.event)

- Two broad categories of events
  - Normal events
  - 2 BDI events
- The key difference between normal events and BDI events is how an agent selects plans for execution.
- With normal events, the agent selects the first applicable plan instance for a given event and executes that plan instance only.
- The handling of BDI events is more complex and powerful. An agent can assemble a plan set for a given event, apply sophisticated heuristics for plan choice and act intelligently on plan failure.

# Event Types in JACK

- Event
- MessageEvent
- BDIFactEvent
- BDIMessageEvent
- BDIGoalEvent
- InferenceGoalEvent
- PlanChoice

```
event TakeOffClearance extends Event
{
    String airTrafficController;
    String runway;

    #posted as clearedForTakeOff(String atc, String rwy)
    {
            airTrafficController = atc;
            runway = rwy;
      }
}
```

# Plans (.plans)

- The Plan class describes a sequence of actions that an agent can take when an event occurs.
- Whenever an event is posted and an agent adopts a task to handle it, the first thing the agent does is try to find a plan to handle the event.
- Plans can be thought of as pages from a procedures manual. They describe, in explicit detail, exactly what an agent should do when a given event occurs.
- Each plan is capable of handling a single event.
- When an instance of a given event arises, the agent may execute one of the plans that declare they handle this event.

# Discriminating Between Plans

- An agent may further discriminate between plans that declare they handle an event by determining whether a plan is relevant.
- It does this by executing the relevant() method of each plan.
- Once the relevant plan(s) have been identified, the agent determines which of these are applicable. It does this by executing the plans' context() method.
- The context method is a JACK Agent Language logical **expression** that can bind the values of the plan's logical members.
- For every possible set of bindings, a separate applicable instance of the plan is generated.
- When the agent has found all applicable instances of each relevant plan, it selects one of these to execute.

# Reasoning Method Statements

# Example Beliefset — BookData.bel

# Illustrating a Relation

# Jack Capabilities

#### Resources

- http://www.agent-software.com/
- http://agent-software.com/products/jack/documentation\_and\_instructi/