

Horus

localhost:5000/edit_shot?shot=sab_closeUpCircle

The screenshot shows a composite view of a quadcopter flight planning interface. On the left is a Google Earth-style map of the Stanford University campus, featuring buildings like the Stanford Memorial Auditorium, Serra Mall, and Hoover Tower. A green wireframe cone indicates the camera's field of view, centered on the Hoover Tower. Below the map are two progress bars: 'Look-From Progress' (green line) and 'Look-At Progress' (blue line), both starting at 00:00.00 and ending at 60.00s. To the right of the map are four data plots: 'Start Capture' (button), 'Inspector' (radio buttons for Camera Properties: Narrow, Medium, Wide, currently Medium selected), 'Feasibility Plots' (Motor Forces vs. Time), 'Altitude Above Sea Level' (Altitude vs. Time), and 'Quad Horizontal Velocity' (Velocity vs. Time). A large arrow points from the interface to the right, leading to a film strip.

