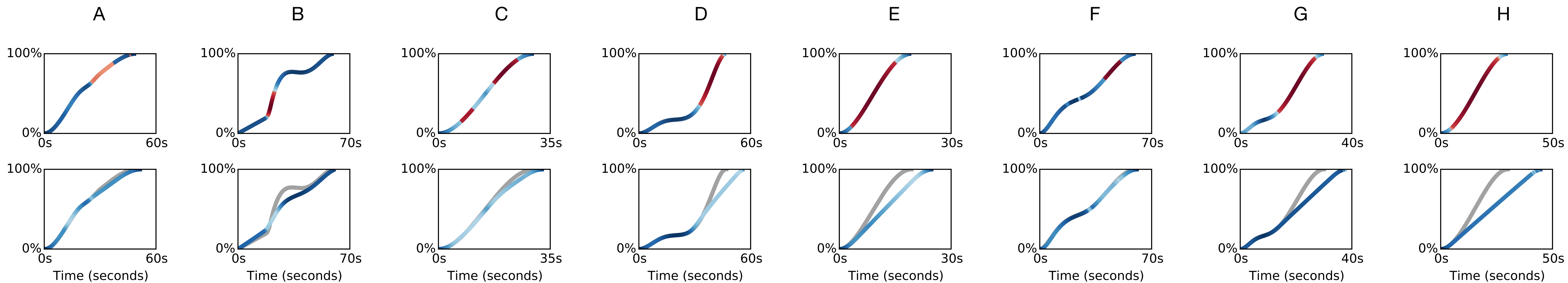


a

Trajectory

Infeasible Input
Progress Curve

Feasible Output
Progress Curve

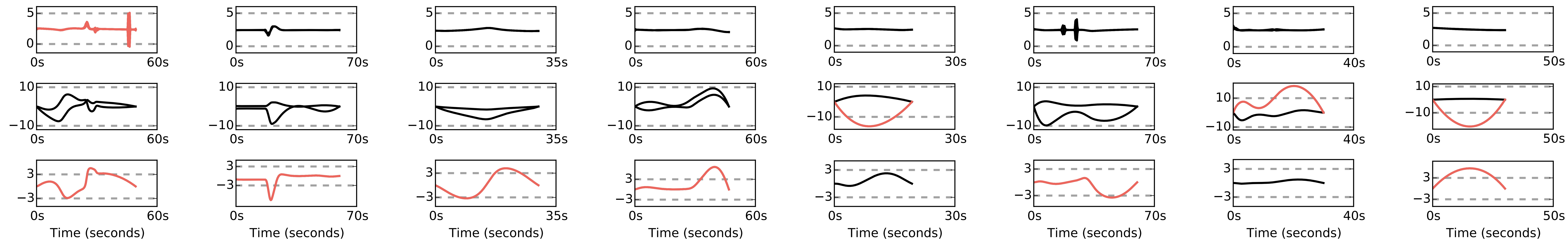


b

Infeasible Input
Control Forces
(Newtons)

Infeasible Input
Horizontal Velocity
(meters per second)

Infeasible Input
Vertical Velocity
(meters per second)



c

Feasible Output
Control Forces
(Newtons)

Feasible Output
Horizontal Velocity
(meters per second)

Feasible Output
Vertical Velocity
(meters per second)

