

THE BORSUK-ULAM THEOREM IN REAL-COHESIVE HOMOTOPY TYPE THEORY

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ABSTRACT. Borsuk-Ulam!

WRITING NOTES

Writing assignments:

- Amelia—section 5
- Chandrika—section 4
- Daniel—sections 2 and 3

Formalizing the cohomology proofs will be determined later.

1. INTRODUCTION

2. OVERVIEW OF REAL-COHESIVE HOMOTOPY TYPE THEORY

OUTLINE:

- HoTT as foundations
- Interpreting AlgTop theorems in HoTT is obstructed by discontinuous functions
- Relating continuous and discontinuous with flat and sharp, which are borrowed from cohesive topoi
- Formalizing flat and sharp in HoTT + axioms needed, e.g. Rflat
- Connecting sets used in AlgTop with HITs used in HoTT via shape

Homotopy type theory (HoTT) is an expression of a style of mathematics that expands the notion of “identity” to include logical identity, homotopy equivalence, and path connectedness. Experts call this style *Univalence foundations*. And as foundations, there is an ambitious program to encode all of mathematics in homotopy type theory. There is a growing community working to realize these ambitions and this paper belongs to this group.

Our present goal is to bring the classical theory of algebraic topology into the fray, and in particular the Borsuk-Ulam theorem. However, the HoTT approach to algebraic topology comes with an immediate challenge: the presence of so many fixed point theorems where, in the course of a proof, the fixed point must be specified precisely, not only up to homotopy. What is the problem with this? It is that homotopy type theory only works up to homotopy. Compare, for instance, the topological circle

$$\mathbb{S}^1 := \{(x, y) \in \mathbb{R}^2 \mid x^2 + y^2 = 1\}$$

with the homotopy type theoretical circle defined by a pair of constructors **base** and **loop**: **base** = **base**. One has infinitely many points that can be described exactly

and the other has a single point. Brouwer’s Fixed Point Theorem illustrates this problem nicely. We provide its statement and proof here for reference.

Theorem 2.1. *Let \mathbb{D}^2 denote the topological disk $\{(x, y) \in \mathbb{R}^2 \mid x^2 + y^2 \leq 1\}$. Any continuous map $f: \mathbb{D}^2 \rightarrow \mathbb{D}^2$ has a fixed point.*

Proof. Suppose that f is continuous but does not have a fixed point, hence $f(x) \neq x$ for all $x \in \mathbb{D}^2$. For each $x \in \mathbb{D}^2$, draw a ray from $f(x)$ to x . This ray intersects the circle in a point we denote by $s(x)$. This defines a continuous function $s: \mathbb{D}^2 \rightarrow \mathbb{S}^1$ with the property that $s(x) = x$ for all x on the boundary of \mathbb{D}^2 . That implies that the identity on \mathbb{S}^1 factors as the inclusion $\mathbb{S}^1 \hookrightarrow \mathbb{D}^2$ followed by s . Applying the fundamental group function π_1 to this factorization gives that the identity on $\pi_1(\mathbb{S}^1) = \mathbb{Z}$ factors through $\pi_1(\mathbb{D}^2) = 1$ which is absurd. \square

Note how this proof relied on our precise specification of the point $s(x)$ on the circle. This point cannot be specified precisely in HoTT. Even if we did work with the only homotopical point on the circle, that is with \mathbb{S}^1 , there is no way to relate \mathbb{S}^1 to \mathbb{S}^1 inside of type theory. Semantically speaking, this involves comparing a topological space with ∞ -groupoids. This is done using the fundamental ∞ -groupoid construction. No such construction exists in HoTT. This is the problem that real-cohesive homotopy theory solves. It does so by proposing to combine two already existing, but previously unrelated, type semantics: topological and ∞ -groupoidal. With this proposal, there are three puzzles to be solved.

- (a) We need to define a model for a *topological ∞ -groupoid*.
- (b) What rules or axioms can we equip HoTT with so that we can compare, for example, \mathbb{S}^1 to \mathbb{S}^1 .
- (c) Topology is incompatible with the law of the excluded middle, which is required to prove these classic fixed point theorems. How can we resolve this?

Shulman’s original paper on real-cohesive HoTT [?] discusses the solution to these puzzles in detail. Presently, we are content to simply say that the Lawvere’s theory of cohesion offers a solution. Of course, we need to adapt cohesion to homotopy type theory and we leave the description of this to Shulman, but we do provide a high-level description of the role that cohesion plays.

A *category of cohesive space* is a pair of categories equipped with a string of adjunctions

$$\begin{array}{c} \text{Spaces} \\ \begin{array}{c} f_! \downarrow \quad f^* \uparrow \quad f_* \downarrow \quad f^! \uparrow \\ \text{Sets} \end{array} \end{array}$$

with $f_! \dashv f^* \dashv f_* \dashv f^!$ and such that $f_!$ preserves finite products. As Lawvere puts it, the objects of Sets should be thought of as *abstract sets* which

... may be conceived of as a bag of dots which are devoid of properties apart from mutual distinctness [?].

On the other hand, the objects of Spaces should be thought of as abstract sets together with a sort of *cohesion* between the “dots”. For our purposes, we think of cohesion as a topology though, in reality, this definition above axiomatizes the various forms that cohesion may take, each functor playing a different role. The $f_!$ functor tells us which points are “stuck” together through the cohesion by returning

a set of connected components. The f^* functor endows a set with the discrete topology. The f_* functor forgets the topology of a space. The $f^!$ functor endows a set with the codiscrete topology on a set. From this string of adjoints, we get another adjoint string $\int \dashv \flat \dashv \sharp$ on Spaces comprised of the **shape operation** $\int := f^* f_!$, the **flat operation** $\flat := f^* f_*$, and the **sharp operation** $\sharp := f^! f_*$.

To see how the axiomatic cohesion addresses the above puzzles, we will speak in the language of sets and categories instead of type theory. In other words, we restrict our attention to the semantics of the relevant type theory.

To solve the first puzzle, constructing a topological ∞ -groupoid, we ask first that Spaces and Sets are toposes. A cohesive topos is also a *local and locally connected topos* which can be constructed using sheaves on a site that satisfy certain properties. By expanding this construction to the $(\infty, 1)$ -category, we can obtain cohesive $(\infty, 1)$ -toposes using ∞ -sheaves on a site as shown by Schreiber [?]. The objects of a resulting cohesive $(\infty, 1)$ -topos are precisely the topological groupoids we seek.

The second puzzle involves comparing a space with its homotopy type. Again modifying axiomatic cohesion, we replace the categories Sets and Spaces with the $(\infty, 1)$ -categories of Spaces and ∞ -Groupoids. We also replace the functors with ∞ -functors. The validity of this rests on work by Schreiber [?]. In this setup, applying \int to a space returns the fundamental ∞ -groupoid, an excellent proxy for the homotopy type.

Axiomatic cohesion also provides a solution to the final puzzle: the failure of the *continuous excluded middle*. Given that we are working with topological objects, we require that excluded middle holds continuously, but in general it does not. Given a space X and subspace U , there is no continuous inverse to the inclusion $U + (X \setminus U) \rightarrow X$ because, even though the underlying sets are the same, the topologies are different. If we can introduce discontinuous functions $X \rightarrow U + (X \setminus U)$, then we can find a discontinuous inverse to the inclusion, therefore obtaining a modified, “discontinuous” law of the excluded middle. Hence, the existence of a law of the excluded middle in our context hinges on the introduction of such discontinuous functions. To this end, recall that \flat retopologizes discretely and \sharp retopologizes codiscretely. If $\text{hom}(X, Y)$ is the space of continuous functions from X to Y , then both $\text{hom}(\flat X, Y)$ and $\text{hom}(X, \sharp Y)$ contain the discontinuous, by which we mean not necessarily continuous, functions from X to Y .

Moving towards syntax means introducing into homotopy type theory the constructors that mirror the semantics of \int , \flat , and \sharp . Upon adding these constructors, we obtain *cohesive homotopy type theory*. The “real” part of name comes from an additional axiom included so that we can capture the topology syntactically using continuous paths from the reals. This axiom states

A crisp type A is discrete if and only if the function that returns a constant path $A \rightarrow (\mathbb{R} \rightarrow A)$ is an equivalence.

Calling A a crisp variable means that we perform constructions on it without regarding the topology, such as defining maps $\flat A \rightarrow Y$ or $X \rightarrow \sharp A$. When including this axiom along with the syntactic versions of shape, flat, and sharp, we get *real-cohesive homotopy type theory*.

3. TRANSLATING BORSUK-ULAM TO HOMOTOPY TYPE THEORY

OUTLINE:

- **Subsection 1.** Give statements for BU-classic, BU-odd, BU-retract) a la wikipedia. The proof strategy: show BU-retract implies BU-odd which is equivalent to BU-classic, then prove BU-retract. Give the proof for BU-retract.
- **Subsection 2.** Translate the classical statement into propositions as types. We want to model classical proof. The failure of contrapositive rule in constructive logic—(not q implies not p) is (p implies not not q)—means our proof strategy is BU-retract implies not not BU-odd which is equivalent to not not BU-classic. But not not BU-classic is sharp BU-classic. Prove BU-retract.
- To close out the section, list the ingredients we need to prove BU-retract.

4. TOPOLOGICAL AND HOMOTOPICAL REAL PROJECTIVE SPACES

OUTLINE:

- Define n-disks as both sets and types, the latter which is simply 1, since they're contractible. Show that $\int \mathbb{D} = \mathbb{D}$
- Define n-spheres as sets. Use pushouts to glue disks together. Explain why we need to glue with a collar—i.e. the “topology” (as encoded by continuous paths $\mathbb{R} \rightarrow \mathbf{X}$ of a type \mathbf{X} . Show, via Shulman, that $\int \mathbb{S}^n = \mathbb{S}^n$
- Define \mathbb{RP}^n as sets using pushouts and collaring. Recall Bulcholtz and Egbert's definition of HIT \mathbb{RP}^n . Prove that $\int \mathbb{RP}^n = \mathbb{RP}^n$

4.1. Defining \mathbb{RP}^n . We define \mathbb{RP}^n using push outs, tautological bundles, spheres, and a inductive process, following the work of Rijike [].

\mathbb{RP}^1 is defined as the following push out, where $a(-1, x) = \frac{x}{4}$ and $a(1, x) = \frac{x}{4} + \frac{3}{4}$, and $b(\pm 1, x) := (0, a(\pm 1, x))$.

$$\begin{array}{ccc} \mathbb{S}^0 \times \mathbb{I} & \xhookrightarrow{a_1} & \mathbb{I} \\ \downarrow b_1 & & \downarrow \\ \{0\} \times \mathbb{I} & \longrightarrow & \mathbb{RP}^1 \end{array}$$

The tautological bundle \mathbb{T}^1 over \mathbb{RP}^1 is defined by the constructors $\mathbb{I} \mapsto \mathbb{R}$ and $(\{0\} \times \mathbb{I}) \mapsto \mathbb{R}$ and the transition maps Id and $-Id$.

From here, we proceed inductively. \mathbb{RP}^n is defined as the following pushout.

$$\begin{array}{ccc} \mathbb{S}^{n-1} \times \mathbb{I} & \xhookrightarrow{a_n} & \mathbb{D}^n \\ \downarrow b_n & & \downarrow \\ \mathbb{T}^{n-1} & \longrightarrow & \mathbb{RP}^n \end{array}$$

where a_n and b_n are both inclusions of $\mathbb{S}^{n-1} \times \mathbb{I}$ as thickened boundary of \mathbb{T}^{n-1} and \mathbb{D}^n .

The tautological bundle \mathbb{T}^n is defined by the constructors

5. COHOMOLOGY

OUTLINE:

- **Subsection 1.** Define cohomology for $\mathbb{Z}/2\mathbb{Z}$ coefficients and the EM-spaces for \mathbb{RP}^n
- **Subsection 2.** Show that we get a commutative graded ring structure for cohomology of any type \mathbf{X} with $\mathbb{Z}/2\mathbb{Z}$ -coefficients. Follow Brunerie's thesis.
- **Subsection 3.** Compute $\mathbb{Z}/2\mathbb{Z}$ -cohomology ring for \mathbb{RP}^n using Mayer-Vietoris. This needs us to first compute cohomology for disks and spheres.

5.1. Cohomology and EM-spaces for \mathbb{RP}^n . We follow a similar construction for cohomology as found in [?], modifying their construction with \mathbb{Z} coefficients to have coefficients in $\mathbb{Z}/2\mathbb{Z}$. In order to define cohomology, we must first define Eilenberg-MacLane spaces $K(\mathbb{Z}/2\mathbb{Z}, n)$. Eilenberg-MacLane spaces $K(G, n)$ were defined for arbitrary group G by Finster and Licata in [?], and so we follow their construction.

Definition 5.1. For $n : \mathbb{N}$, the type **Eilenberg-MacLane space** $K(\mathbb{Z}/2\mathbb{Z}, n)$ is the n -truncated and $(n - 1)$ -connected pointed type defined by

$$K(\mathbb{Z}/2\mathbb{Z}, n) := \begin{cases} \mathbb{Z}/2\mathbb{Z} & \text{for } n = 0 \\ ||\Sigma^{n-1}\mathbb{RP}^2||_n & \text{for } n \geq 1, \end{cases}$$

where Σ^{n-1} indicates the reduced suspension.

AMELIA: G showed equivalence of K_n and ΩK_{n+1} at this point. I don't think that's necessary given Finster and Licata.

Given this construction of the EM spaces, we define cohomology in the following way.

Definition 5.2. For a type \mathbf{X} and $n : \mathbb{N}$, the n -th cohomology group of \mathbf{X} is the type

$$H^n(\mathbf{X}; \mathbb{Z}/2\mathbb{Z}) := ||\mathbf{X} \rightarrow K(\mathbb{Z}/2\mathbb{Z}, n)||_0.$$

AMELIA: B also defines reduced cohomology as well, not i'm not sure we need that.

5.2. Commutative Graded Ring Structure.

5.3. Computing the Cohomology Ring of \mathbb{RP}^n .

6. THE BORSUK-ULAM THEOREM

OUTLINE:

- The proof is done by this point. Just put it all together and reconnect the dots for the reader.