

# **Independence Properties of Directed Probabilistic Graphical Models**

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November 11, 2020

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# Motivation

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Consider, for example, a Bayesian Hidden Markov Model.

$$p(\pi, \theta, X, Y) = \underbrace{p(\pi) p(\theta)}_{\text{prior}} \underbrace{p(X_0) \prod_{t=1}^T p(X_t | X_{t-1}) p(Y_t | X_t)}_{\text{(complete data) likelihood}}$$

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- How can we know this?
- More generally: How can we easily answer queries about (conditional or marginal) independence ?

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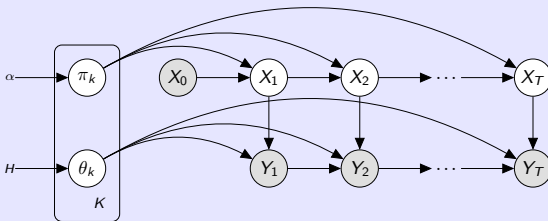
Consider, for example, a Bayesian Hidden Markov Model.

$$p(\underbrace{\pi, \theta}_{\text{joint}}, X, Y) = \underbrace{p(\pi) p(\theta)}_{\text{prior}} \underbrace{p(X_0) \prod_{t=1}^T p(X_t | X_{t-1}) p(Y_t | X_t)}_{\text{(complete data) likelihood}}$$

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## Representation as a *probabilistic graphical model*





# Directed Probabilistic Graphical Models

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## Joint distributions

The starting point for a directed probabilistic graphical model is a particular factorization of a joint density:

$$p(X_1, \dots, X_n) = \prod_{i=1}^n p(X_i \mid \pi_i) \quad (2.1)$$

where the conditioning set  $\pi_i$  is referred to as the **parents** of variable  $i$ .

(2.1) simplifies the factorizations which are *always* true, by the chain rule of probability:

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In other words, (2.1) restricts our consideration to a certain subset of joint probability distributions.

Consider, e.g., the structure imposed in Bayesian models by independent priors or conditionally i.i.d likelihoods.

# Directed probabilistic graphical models

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# Directed probabilistic graphical models

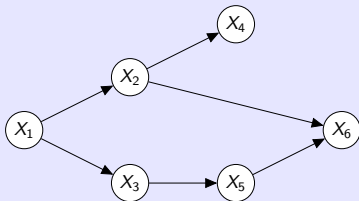
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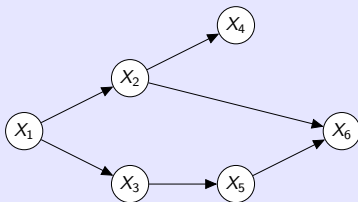
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$$p(X) = p(X_1) p(X_2 \mid X_1) p(X_3 \mid X_1) p(X_4 \mid X_2) p(X_5 \mid X_3) p(X_6 \mid X_5, X_2)$$

# Independence in Canonical Graphs

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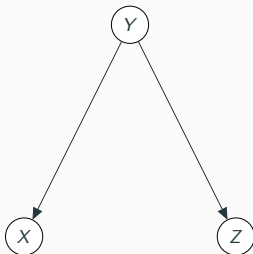
# Three canonical graphs

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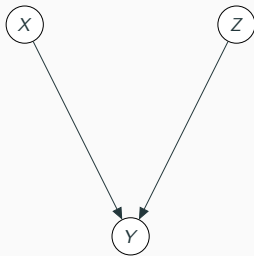
**Cascade**



**Common parent**



**v-structure**



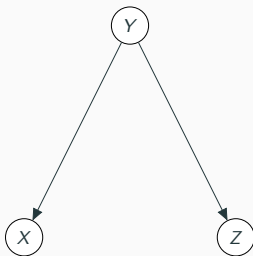
# Three canonical graphs : Marginal Independence

**Cascade**



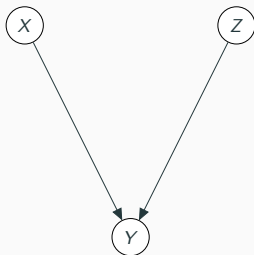
$Z \not\perp\!\!\!\perp X$

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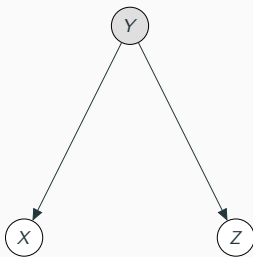
# Three canonical graphs : Conditional Independence

**Cascade**



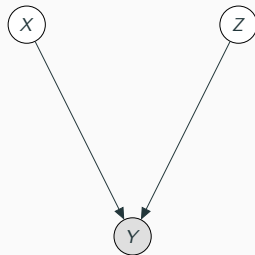
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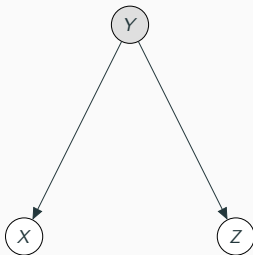
# Three canonical graphs : Take Home

**Cascade**

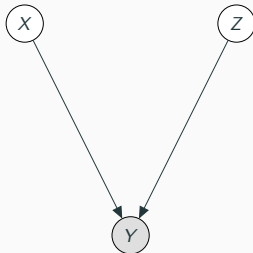


Knowing Y **decouples** X and Z

**Common parent**



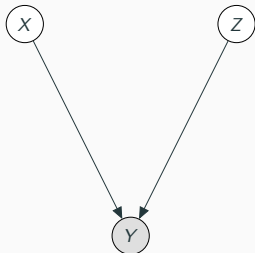
**v-structure**



Knowing Y  
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# Competing explanations

## v-structure



The independence properties of the v-structure is commonly understood through a **competing explanations** paradigm.

Suppose your house has a twitchy burglar alarm that is also sometimes triggered by earthquakes.

Let

$X = \{\text{your house got robbed}\}$

$Z = \{\text{an earthquake occurred nearby}\}$

$Y = \{\text{your burglar alarm goes off}\}$

Then it is (perhaps) intuitive that

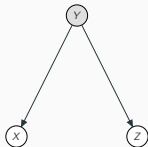
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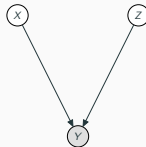


# Relevance to real models

## Common parent



## v-structure



In real models ...

- the **common parent structure** shows up with conditional i.i.d data models. (So imagine  $Y$  is a parameter and  $X$  and  $Z$  are two observations.) The observations are conditionally independent, but integrating out the random parameter induces dependencies in the observations. Note in particular that the observations are, in general, *dependent* in the predictive posterior.
- the **v-structure** shows up with independent priors. ( So imagine  $X$  and  $Z$  are model parameters given independent priors and  $Y$  is an observation.) Then the parameters are independent when generating data (i.e. in the prior), but they become dependent when doing inference (i.e. in the posterior).

# Independence in Directed PGM's

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# d-separation

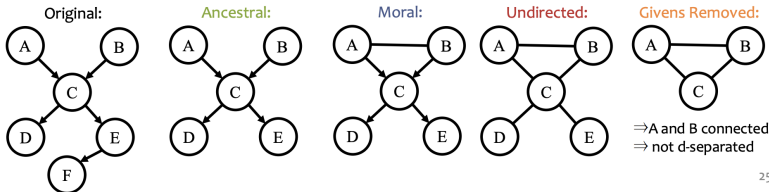
**If** variables X and Z are **d-separated** given a **set** of variables E  
**Then** X and Z are **conditionally independent** given the **set** E

## Definition #2:

Variables X and Z are **d-separated** given a **set** of evidence variables E iff there does **not** exist a path in the **undirected ancestral moral graph with E removed**.

1. **Ancestral graph**: keep only X, Z, E and their ancestors
2. **Moral graph**: add undirected edge between all pairs of each node's parents
3. **Undirected graph**: convert all directed edges to undirected
4. **Givens Removed**: delete any nodes in E

**Example Query:**  $A \perp\!\!\!\perp B \mid \{D, E\}$



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Image Credit: Matt Gormley (CMU).

## Worksheet for practice

# Fundamental property of Bayes networks

An oft-stated fact is:

*A node is independent of its non-descendants given its parents.*

This can easily be proven via d-separation.

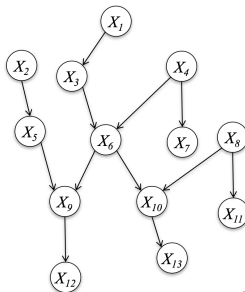
- The first step (“ancestral graph”) will remove all of  $X$ ’s children.
- The fourth step (“remove givens”) will remove  $X$ ’s parents.
- Thus,  $X$  will be disconnected from the rest of the graph.

## Markov Blanket

**Def:** the **co-parents** of a node are the parents of its children

**Def:** the **Markov Blanket** of a node is the set containing the node's parents, children, and co-parents.

**Thm:** a node is **conditionally independent** of every other node in the graph given its **Markov blanket**



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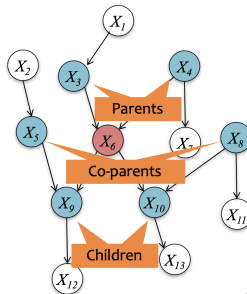
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**Example:** The Markov Blanket of  $X_6$  is  $\{X_3, X_4, X_5, X_8, X_9, X_{10}\}$



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## Markov Blankets: Why *co*-parents?

Why is it not sufficient for the Markov Blanket to only include the parents and children of  $X_i$ ?



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Why is it not sufficient for the Markov Blanket to only include the parents and children of  $X_i$ ?

The phenomenon of explaining away means that the observations of child nodes will not block paths to the co-parents.

This is why step 2 of the d-separation algorithm ("moralization") connects parents.

In the previous graph, the transformed graph would still have paths from  $X_6$  to, for example,  $X_8$  (and to  $X_{11}$ ).

## Proof of Markov Blanket statement

Let us consider the conditional distribution of some variable  $X_i$  given the factorization in (2.1):

$$\begin{aligned} p(X_i \mid X_{-i}) &= \frac{p(X_1, \dots, X_n)}{\int p(X_1, \dots, X_n) dX_i} \\ &= \frac{\prod_{k=1}^n p(X_k \mid \pi_k)}{\int \prod_{k=1}^n p(X_k \mid \pi_k) dX_i} \end{aligned}$$

All terms will cancel in the numerator and denominator except for terms of the form

1.  $p(X_i \mid \pi_i)$ , i.e. terms where  $i$  is the node itself
2.  $\{p(X_k \mid \pi_k) : i \in \pi_k\}$ , i.e. terms where  $i$  is one of the parents.

Terms of type (1) will depend on  $X_i$ 's parents, and terms of type (2) will depend on  $X_i$ 's children and co-parents.