

Mikihisa Yuasa

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EDUCATION

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| University of Illinois Urbana-Champaign , Champaign, IL | Expected 05/2026 |
| Ph.D. in Aerospace Engineering | GPA: 3.63/4.00 |
| Research Areas: <i>Explainable Artificial Intelligence (XAI), Reinforcement Learning, Large Language Model (LLM).</i> | |
| Projects: | |
| <ul style="list-style-type: none">Built a learning-based control system for real-world autonomous vehicle (Polaris GEM) using ROS.Led team in creating algorithm to prevent language model hallucinations using multiple small models. | |
| University of Wisconsin-Madison , Madison, WI | 08/2017 – 05/2021 |
| B.S. in Engineering Mechanics with Astronautics Option; Certificate in French | GPA: 3.68/4.00 |

TECHNICAL SKILLS & AWARDS

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| Programming | Proficient: Python, C++, Rust, MATLAB, TypeScript, HTML/CSS, LaTeX, Experienced: Julia, C#, R |
| Software | Proficient: PyTorch, TensorFlow, JAX, CUDA, Pinecone, SOLIDWORKS, PTV Vissim, OpenFOAM, Tecplot, ParaView, Linux, React, Experienced: AWS, ROS/ROS2, Gazebo, SQL, GPGPU, Flutter, Ansys |
| Awards | Japan Student Services Organization Graduate Scholarship by the Government of Japan |
| Languages | Native: Japanese, Business: French |

WORK & RESEARCH EXPERIENCES

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| Graduate Research Assistant , <i>Dr. Huy Tran's Reinforcement Learning Research Group</i> | 08/2021 – Present |
| <ul style="list-style-type: none">Formulated a formal method framework to generate human-readable explanations for reinforcement learning.Constructed neural networks for inferring decision-making processes of autonomous systems using PyTorch.Developed transfer learning algorithm for ad hoc teaming of multi-agent reinforcement learning systems.Led the creation of an algorithm verification platform for robot navigation in both simulation and real-world. | |
| Large Language Model (LLM) R&D Intern , <i>Spiral.AI</i> , Tokyo, Japan | 05/2023 – 08/2023 |
| <ul style="list-style-type: none">Investigated an efficient searching algorithm for the knowledge base for domain-specific LLMs.Built a method to compactly store web-crawled data in a vector database using an LLM. | |
| Technical Intern , <i>Solid Oxide Fuel Cell Team, Bosch Corporation</i> , Tokyo, Japan | 07/2021 – 08/2021 |
| <ul style="list-style-type: none">Created educational materials to launch a business targeting the Japanese fuel cell industry.Investigated potential market demands for solid oxide fuel cells and autonomous vehicles in Japan. | |
| Undergraduate Research Assistant , <i>Dr. Bin Ran's Connected Automated Vehicles & Highways Lab</i> | 09/2019 – 05/2021 |
| <ul style="list-style-type: none">Conducted macroscopic mixed conventional and automated traffic simulations under severe weather.Led a team to model cooperation of connected automated vehicles using model predictive control. | |
| Undergraduate Research Assistant , <i>Dr. Jennifer Franck's Computational Fluid Dynamics Lab</i> | 05/2018 – 05/2021 |
| <ul style="list-style-type: none">Built a distributed computing algorithm to dynamically generate meshes around bioinspired structures.Implemented the algorithm as an opensource high performance computing library for CFD simulations in C++. | |

PUBLICATIONS & PRESENTATIONS

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| <u>Yuasa</u> , Tran, Sreevinas, "On Generating Explanations for Reinforcement Learning Policies: An Empirical Study," <i>under review at 2024 IEEE International Conference on Robotics and Automation (IROS 2024)</i> . [link] |
| Nigam, Parikh, <u>Yuasa</u> , Tran, "Coordination in Ad Hoc Teams with Generalized Policy Improvement," <i>presented at 2023 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2023)</i> . [link] |
| <u>Yuasa</u> , Lyons, Franck, "Simulations of flow over a bio-inspired undulated cylinders with dynamically morphing topography," <i>Journal of Fluids and Structures</i> , vol. 111, p. 103567, 2022. [link] |

LEADERSHIPS

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| Graduate School Application Counselling Volunteer , <i>XPLANE</i> | 08/2021 – Present |
| <ul style="list-style-type: none">Instructed academic writing targeting North American graduate school applications.Counselled graduate school application strategies and career paths for North American graduate programs. | |