170330 smBlO meeting

서정훈

simulator/simulate.py parameters

```
class Simulate(object):
    def __init__(self, background_factory, camera_factory, photophysics_factory, psf_factory, x_size = 256, y_size = 256
):
```

test/test_simulator.py

test/test_simulator.py

```
def test simulate 2():
    dax_name = storm_analysis.getPathOutputTest("test_sim2.dax")
bin_name = storm_analysis.getData("test/data/test sim olist.bin")
    sim = simulate.Simulate(lambda settings, xs, ys, i3data : background.UniformBackground(settings, xs, ys, i3data, pho
tons = 20),
                                lambda settings, xs, ys, i3data : camera.EMCCD(settings, xs, ys, i3data, 100.0, emccd gain =
    , preamp gain = 1.0, read noise = 5),
                                lambda settings, xs, ys, i3data : photophysics.SimpleSTORM(settings, xs, ys, i3data,
 off time = 10.0),
                                lambda settings, xs, ys, i3data : psf.PupilFunction(settings, xs, ys, i3data, 160.0, [[]
 , 2]]),
                               x \text{ size} = 100, y \text{ size} = 75)
    sim.simulate(dax name, bin name, 5)
```

test/test_simulator.py

simulator/background.py

```
class Background(simbase.SimBase):
    def init (self, sim fp, x size, y size, i3 data):
        simbase.SimBase. init (self, sim fp, x size, y size, i3 data)
class UniformBackground(Background):
    def init (self, sim fp, x size, y size, i3 data, photons = 1
        Background. init (self, sim fp, x size, y size, i3 data)
        self.saveJSON({"background"
                                                  : str(photons)}})
        self.bg image = numpy.ones((x size, y size)) * photons
    def getBackground(self, frame):
        return self.bg image
    def getEmitterBackground(self, i3 data in):
        i3 data = numpy.copy(i3 data \overline{i}n)
        for i in range(i3 data['x'].size):
            x = int(round(i3 data['x'][i]))
            y = int(round(i3 data['y'][i]))
            i3 data['bg'][i] = self.bg image[x,y]
        return i3 data
```

simulator/camera.py

class SCMOS(Camera):

```
class Camera(simbase.SimBase):
                     class Ideal(Camera):
                                class EMCCD(Camera):
```

```
A sCMOS camera. The sCMOS calibration data needs to be the same size as the simulated images.
```

simulator/photophysics.py

```
class PhotoPhysics(simbase.SimBase):

Returns location and intensity (peak height in photons) of
the emitters that are on in the current frame.

"""
```

1

```
class AlwaysOn(PhotoPhysics):
        All the emitters are on all the time.
"""
```

2

```
class SimpleSTORM(PhotoPhysics):
    """
    Each emitter on for 1 frame out of every 1000 frames on average, both are exponentially distributed.

Args:
        on_time : Average on time in frames.
        off_time : Average off time in frames.
    """
```

simulator/psf.py

```
class PSF(simbase.SimBase):
                                   class PupilFunction(PSF):
    class GaussianPSF(PSF):
    class Spline2D(splineToPSF.SplineToPSF2D):
                                                         class Spline(PSF):
                                                    5
      class Spline3D(splineToPSF.SplineToPSF3D):
                                                    spline_file parameter 필요
```

spliner/psf_to_spline.py

5. Use psf_to_spline.py to convert the measured PSF into a spline that can be used by spliner/cspline for analyzing STORM movies:

```
>>> import storm_analysis.spliner.psf_to_spline as psf_to_spline
>>> psf_to_spline.psfToSpline("beads_psf.psf", "beads_psf.spline", 12)
Generating 3D spline.
Generating XY splines.
Generating fitting spline.
Calculating spline coefficients.
```

Note:

"12" is the size of the spline in pixels in x and y.

This will create two files:

- (1) beads_psf.spline A file containing the spline coefficients.
- (2) spline.dax The spline as a z-stack. This is 2x upsampled so the its final size is 24 x 24 x 24.