# Evaluation of IR Models

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#### Abstract

The objective of this project is to implement various IR models and evaluate their performance based on Mean Average Precision(MAP) values. A dataset containing twitter data in three different languages(English, German and Russian), 15 sample queries and corresponding sample manual relevance were provided. The twitter data provided were atfirst indexed in Solr and then evaluated by using Trec eval program. The scores obtained gave us an idea of how relevant were the results given by our Solr instance. Different techniques used to obtain greater map values are described in the later sections. The best values obtained for BM25, Divergence From Random(DFR) and Vector Space Model(VSM) are 0.7601, 0.7507 and 0.7507 respectively.

### 1 Introduction

The main goal of this project is to improve search result of Solr instance using different techniques. We have implemented IR models such as BM25, Divergence From Randomness (DFR) and Vector Space Model(VSM) and used the training queries provided to judge the relevance/precision of our results with the help of the TREC tool. Mean Average Precision(MAP) is used to judge the relevancy of our system. Following are the techniques used:

- Tuning the parameters of IR Models
- Creating a common text all field and Boosting
- Using various filters and tokenizers
- Using query parsers and query expansion techniques
- Multilingual Support
- Translation of queries and Synonyms

#### 2 Overview of IR Models

### 2.1 Best Matching(BM25)

The Best Matching (BM25), Okapi Weighting is a probabilistic Information Retrieval (IR) model. It is used by search engines to rank matching documents according to their relevance to given search query.

## 2.2 Divergence From Randomness(DFR)

The Divergence from Randomness (DFR) paradigm is a generalisation of one of the very first models of Information Retrieval, Harter's 2-Poisson indexing-model. It is based on the following components: Randomness Model, First Normalization and Term Frequency Normalization.

## 2.3 Vector Space Model(VSM)

Alternative name is Term Vector Model, and is an algebraic model used for representing documents and queries as vectors in the term space. It allows computing a continuous degree of similarity between queries and documents. It ranks documents according to their possible relevance and partial matching.

We have successfully implemented the 3 models and created 3 cores for the same [Refer Figure 1]



Figure 1: Successful Implementation of Various IR Models

## 3 Experiments and Results

#### 3.1 Tuning the parameters of IR Models

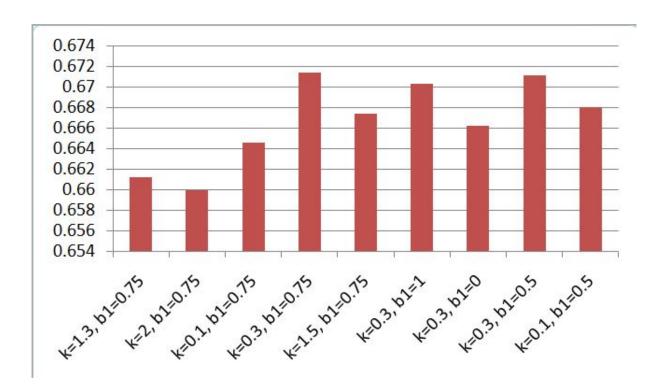
#### 3.1.1 Best Matching(BM25)

The default similarity class in solr-6.2.0 is BM25. If no similarity class is added to the schema, then the default is **BM25SimilarityFactory**. However, we can add BM25SimilarityFactory to the schema to tweak the values of k1 and b

```
<similarity class="solr.BM25SimilarityFactory">
    <float name="k1">1.2</float>
    <float name="b">0.75</float>
    </similarity>
```

The default MAP and nDCG score obtained were **0.6636** and **0.8292** as shown below: 001 0.2854 ndcg 002 0.4202 map ndcg 002 0.6143 003 0.5729 map 003 ndcg 0.8672 map 004 0.5724 004 ndcg 0.8590 005 map 005 0.7244 ndcg 006 map 0.4991 ndcg 006 0.7126 007 0.8333 ndcg 007 0.9639 map 008 1.0000 ndcg 008 1.0000 009 1.0000 map ndcg 009 0.9931 010 1.0000 map ndca 010 1.0000 1.0000 map 011 012 0.6616 ndcg 011 1.0000 map 0.1041 012 map 013 ndcg 0.8972 0.4312 014 0.6386 013 map ndcg map 015 0.8667 014 0.8673 ndcg 0.6636 0.9407 ndcg 015 gm\_map 0.5838 ndcg 0.8292 all

Below is the graph that represents MAP values for different values of  $\mathbf{k1}$  and  $\mathbf{b}$  for 20 rows



Results for BM25: Usually the default values should suffice for BM25 model. The parameter b controls to what degree document length normalizes tf values, we got the best values for MAP when keeping b to 0.75. Reason is the document length for this corpus is more or less equal throughout, without much variance, hence the default value of b works good. The optimum MAP and nDCG value was obtained keeping k1 = 0.3 and b = 0.75. The MAP and nDCG values obtained through trec\_eval were 0.6714 and 0.8428, if 20 documents were retrieved.

#### 3.1.2 Divergence From Randomness(DFR)

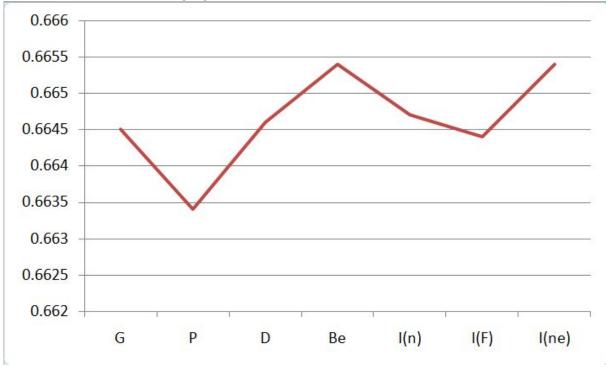
The default DFR model had the following settings:

The default MAP and nDCG score obtained were **0.6645** and **0.8273** as shown below:

9 1/ ci co_crai q	C 112000 D1/1	ndca	001	0 5722
map	001	0.2979 ndcg	001	0.5732
map	002	0.4173 ndcg	002	0.6136
map	003	0.5610ndcg	003	0.8683
map	004	0.5804 ndcg	004	0.8601
map	005	0.5000 ndcg	005	0.7244
map	006	0.4474 ndcg	006	0.6972
map	007	0.8333 ndca	007	0.9639
map	008	1.0000 ndca	008	1.0000
map	009	1.0000 ndca	009	0.9931
map	010		010	1.0000
map	011	1.0000 ndcg		
map	012	0.7211 ndcg	011	1.0000
map	013	0.1041 ndcg	012	0.9158
map	014	0.6386 ndcg	013	0.4312
map	015	0.8667 ndcg	014	0.8278
map	all	0.6645 ndcg	015	0.9407
gm_map	all	0.5840 ndcg	all	0.8273

The DFR has three parameters **basicModel** which is the basic model of the information content, **afterEffect** specifies the first normalization of information gain and **Normalization** refers to the second normalization. A parameter 'c' that controls the term frequency normalization with respect to the document length which is specified for normalization H1 and H2.

Below is the graph that shows the change in MAP values keeping AfterEffect as B and Normalization as H2, and changing the **basicModel** in each case for 20 documents:



Below is the table for further changes in basic settings for DFR:

basicModel	afterEffect	normalization	С	Map Values
Be	В	H2	1000	0.6801
Be	В	H2	1.2	0.6649
I(ne)	В	H2	1000	0.6678
Be	L	H2	1000	0.6921

Table 1: Map Values for changes in basicModel, afterEffect, normalization and c

Results for DFR: We found an optimum value keeping basicModel as Be, Aftereffect as L and 2nd Normalization as H2. Hence we have chosen the above parameters for our DFR Model. The MAP and nDCG values obtained through trec\_eval were 0.6921 and 0.8443, if 20 documents were retrieved.

#### 3.1.3 Vector Space Model(VSM)

This was the default similarity class in previous versions i.e before Solr-6.0. The VSM similarity class is implemented through the ClassicSimilarityFactory.

similarity class="solr.ClassicSimilarityFactory"/

The default MAP and nDCG score obtained were 0.6483 and 0.8217 as shown below: ndcg 0.5954 002 001 map 002 0.3923 ndcg 003 map ndcg 004 map 004 005 ndcg map 005 5000 006 ndcg 006 map ndcg 007 map 008 map ndcg map 1.0000 ndcg 009 map ndcg 011 0000 ndcg 011 1.0000 012 0.4615 map ndcg 012 0.8035 0.1098 map ndcg map 7028 map 014 0.8916 015 ndcg a11 0.6483 map 015 0.8979 ndcg a11 gm\_map 0.5701 a11 ndcg 0.8217

There are no parameters which can be configured for VSM, hence there is no tuning required.

Results for VSM: The MAP and nDCG values obtained through trec\_eval were **0.6483** and **0.8217**, if 20 documents were retrieved.

## 3.2 Creating a common text all field and Boosting

We created a common field named **text\_all** to store all text\_en, text\_ru and text\_de data as phrases,not as tokens.

As the relevance depends on how similar the search result is based on a query, the creation of a field which can store all the text from various other language specific text fields can help in increasing the relevancy. Boosting the score for that newly created field, using the qf and pf parameters in the query syntax helped in increasing MAP values to some extent.

```
<field name="text_all" type="text_all" indexed="true" stored="true" multiValued="true"/>
<copyField source="text_de" dest="text_all"/>
<copyField source="text_en" dest="text_all"/>
<copyField source="text_ru" dest="text_all"/>
```

#### 3.3 Using various filters and tokenizers

For text\_en, text\_de and text\_ru fields, we have used **UAX29URLEmailTokenizerFactory** as this tokenizer splits the text field into tokens, treating whitespace and punctuation as delimiters.

KeywordTokenizerFactory is used for text\_all field as it does not break the text into tokens, and stores them as phrases. This helped us match the queries to a better extent. KeywordTokenizerFactory didnot go well with DFR and VSM and hence for those StandardTokenizerFactory is being used.

Other filters which helped in increasing MAP values are:

- LowerCaseFilterFactory
- StopFilterFactory
- PorterStemFilterFactory
- RemoveDuplicateTokens

The above filters are applied at both indexing and query time.

Results for BM25: Using KeywordTokenizerFactory the map values for BM25 increased from 0.6714 to 0.6756.

## 3.4 Using query parsers and query expansion techniques

The standard query parser searches mainly in the default fields specified in the config, and returns the results, depending on the cumulative score from all the fields for a given document. However, the DisMax query parser is designed to process simple phrases entered by users and to search for individual terms across several fields using different weighting (boosts) based on the significance of each field. The Extended DisMax (eDisMax) query parser is an improved version of the DisMax query parser.

We have used the DisMax Query Parser using **defType=dismax** in the query. As hashtags contains most of the relevant terms we had given more weightage to **tweet\_hashtags and tweet\_urls**. **text\_all** is boosted as it contains phrases and is much better than having tokenized fields.

```
Following clause is added in the url: qf = text\_all^2 + tweet\_hashtags^{1.0} + tweet\_urls^{1.0} + text\_en^2 + text\_de^{1.2} + text\_ru^{1.2} \& pf = text\_all^2 + tweet\_hashtags^{1.0} + tweet\_urls^{1.0} + text\_en^2 + text\_de^{1.2} + text\_ru^{1.2} \& pf = text\_all^2 + tweet\_hashtags^{1.0} + tweet\_urls^{1.0} + text\_en^2 + text\_de^{1.2} + text\_ru^{1.2} \& pf = text\_all^2 + tweet\_urls^{1.0} + tweet\_urls^{1.0} + text\_de^{1.2} + text\_ru^{1.2} \& pf = text\_all^2 + tweet\_urls^{1.0} + tweet\_urls^{1.0} + text\_de^{1.2} + text\_ru^{1.2} \& pf = text\_all^2 + tweet\_urls^{1.0} + tweet\_urls^{1.0} + text\_de^{1.2} + text\_de^{1.2} + text\_ru^{1.2} \& pf = text\_all^2 + text\_
```

```
text all^2
```

Results for BM25: The MAP value found was 0.6781, if 20 documents were retrieved. Results for DFR: The MAP value found was 0.6801, if 20 documents were retrieved. Results for VSM: The MAP value found was 0.6684, if 20 documents were retrieved.

### 3.5 Multilingual Support

For multilingual support, we had added **ICUTokenizerFactory**, as it processes multilingual text and tokenizes it appropriately based on its script attribute.

### 3.6 Translation of queries and Synonyms

After implementing all the above techniques we weren't getting satisfactory results. Also, there were many relevant tweets in languages other than the query language. There were many texts which were not getting captured in solr. For instance,

**Refugee** → refugee, flüchtling, Flüchtlinge, Flüchtling

 $General \rightarrow general, Generäle, officers$ 

Querying in all the three languages could have helped in fetching more relevant tweets. In order to implement the same, we tried to add synonyms for the various tokens which were used in the queries as a part of multi-language query expansion. For example, if someone queries Putin, then Solr would also search for путин, which is the Russian translation for Putin. Simliarly, there were many words which were translated into English, Russian and German, and added as synonyms in the **synonyms.txt** file.

```
million, Mio
Airbnb, Instacart, Kickstarter, Tech Companies, Tech Firm
asyl, убежище, asylum
civil war, Bürgerkrieg, гражданская война
Flüchtlingshilfe, refugee relief
US, U.S, USA, America, Америка, Amerika, США
Syrien, Syria, Cupus, SYRIA
ISIS.terrorist
russia, Russia, Russia's, Russian, Россия, Russische,
interview, Interview, Vorstellungsgespräch, vorstellungsgespräch, Bewerbungsgespräch, bewerbungsgespräch, интервьк
challenges, проблемы, Herausforderungen, herausforderungen, Herausforderung, herausforderung
обаму, obama
бьет, beats, beat
путин, putin, Putin
беженцев, refugees, Refugees, Flüchtlinge
убит, Kills, kill, killed, Killed, ISIS, funeral
полицией, police, Police
Problematik, problem
begrüßt, hailed, welcomed
germany, Germany, Deutschland, Германия
krise, crisis, кризис
bombed, bombardiert, fegen, bombardieren, разбомбленный
terrorist, terroristisch, terrorist, террорист
air force, luftwaffe, luftstreitkraft, luft kraft, воздушные силы
```

Implementing query expansion using synonyms gave us a significant boost in relevance

for all of the different models by around 10%.

#### Results for BM25:

The MAP and nDCG value found was **0.7601** and **0.8805**, if 20 documents were retrieved. The MAP and nDCG value found was **0.8384** and **0.9400**, if 1000 documents were retrieved.

#### Results for DFR:

The MAP and nDCG value found was **0.7507 and 0.8772**, if 20 documents were retrieved. The MAP and nDCG value found was **0.7971 and 0.9371**, if 1000 documents were retrieved.

#### Results for VSM:

The MAP and nDCG value found was **0.7507 and 0.8772**, if 20 documents were retrieved. The MAP and nDCG value found was **0.7971 and 0.9371**, if 1000 documents were retrieved.

## 4 Conclusion

We have successfully implemented the three IR models and we tried to improve the performance of all the three models by using various techniques described above.

The comparison between default and final model of BM25 for 20 retrieved documents:

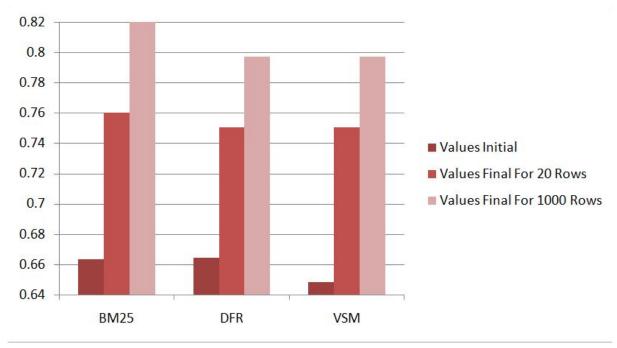
The comparison between default and final model of **DFR** for **20** retrieved documents:

map	001	0.2979 map	001	0.2165
map	002	0.4173 map	002	0.5999
map	003	0.5610 map	003	0.7162
map	004	0.5804 map	004	0.7346
map	005	0.5000 map	005	0.6500
map	006	0.4474 map	006	0.9889
map	007	0.8333 map	007	1.0000
map	008	1.0000 map	008	1.0000
map	009	1.0000 map	009	1.0000
map	010	1.0000 map	010	1.0000
map	011	1.0000 map	011	1.0000
map	012	0.7211 map	012	0.4423
map	013	0.1041 map	013	0.2244
map	014	0.6386 map	014	0.7663
map	015	0.8667 map	015	0.9216
map	all	0.6645 map	all	0.7507
gm_map	all	0.5840 gm_map	all	0.6801

The comparison between default and final model of VSM for 20 retrieved documents:

<pre>\$ ./trec_eval</pre>	-q -c -M1000 D:/M	NS/1stSem/	map	001	0.2165
map	001	0.2817	map	002	0.5999
map	002	0.3923	map	003	0.7162
map	003	0.5729	map	004	0.7346
map	004	0.5724	map	005	0.6500
map	005	0.5000	map	006	0.9889
map	006	0.5257	map	007	1.0000
map	007	0.8333	map	008	1.0000
map	008	1.0000	map	009	1.0000
map	009	1.0000	map	010	1.0000
map	010	1.0000	map	011	1.0000
map	011	1.0000	map	012	0.4423
map	012	0.4615	map	013	0.2244
map	013	0.1000	map	014	0.7663
map	014	0.7028	map	015	0.9216
map	015	0.7721 0.6483	map	a11	0.7507
map	all all	0.6483	gm_map	all	0.6801
gm_map	all	0.3/01	gii_iiap	411	0.0001

Below is a graph depicted to show the initial and final values:



For generalized system, BM25 model proved to be most efficient model after all the efforts made for improvement. The techiques used above provided some improvement to the system, but there is a lot more scope of improvement to do in future prospects.

## References

- $[1] \ http://ir.dcs.gla.ac.uk/wiki/DivergenceFromRandomness.$
- $[2] \ https://lucene.apache.org/solr/guide/6\_6/the-standard-query-parser.html/ \\$
- $[3] \ https://lucene.apache.org/solr/guide/6\_6/the-dismax-query-parser.html/ \\$
- [4] https://lucene.apache.org/solr/guide/6\_6/tokenizers.html Tokenizers-UAX29URLE<br/>mail Tokenizer
- $[5] \ https://lucene.apache.org/solr/guide/6\_6/tokenizers.html/lucene.apache.org/solr/guide/6\_6/tokenizers.html/lucene.apache.org/solr/guide/6\_6/tokenizers.html/lucene.apache.org/solr/guide/6\_6/tokenizers.html/lucene.apache.org/solr/guide/6\_6/tokenizers.html/lucene.apache.org/solr/guide/6\_6/tokenizers.html/lucene.apache.org/solr/guide/6\_6/tokenizers.html/lucene.apache.org/solr/guide/6\_6/tokenizers.html/lucene.apache.org/solr/guide/6\_6/tokenizers.html/lucene.apache.org/solr/guide/6\_6/tokenizers.html/lucene.apache.org/solr/guide/6\_6/tokenizers.html/lucene.apache.org/solr/guide/6\_6/tokenizers.html/lucene.apache.org/solr/guide/6\_6/tokenizers.html/lucene.apache.org/solr/guide/6\_6/tokenizers.html/lucene.apache.org/solr/guide/6\_6/tokenizers.html/lucene.apache.org/solr/guide/6\_6/tokenizers.html/lucene.apache.$