

	ROS2	MQTT	Apache Kafka	YARP	OROCOS	MOOS	ZeroMQ
Open-source	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Robot Specific Libraries and Tools	Yes	No	No	Yes	Yes	Yes	No
Community support	10	8	8	8	7	7	9
Documentation	8	7	7	7	6	8	8
Ease of use	7	8	5	6	6	4	7
Scalability	9	8	10	8	8	8	10
Real-time performance	7	9	9	9	8	8	8
Interoperability	9	9	8	8	7	8	10
Programming languages	9	10	9	7	8	6	10
Total	59	59	56	53	50	49	62