# Project 1: Computational Physics - FYS3150

# Fredrik Hoftun & Mikkel Metzsch Jensen

# September 09, 2020

# **Contents**

1	Introduction				
2	Met	hod	2		
	2.1	defining the problem	2		
	2.2	Rewritting the problem as a set of linear equations	2		
	2.3	General solution using Gausian elimination	4		
	2.4	Simplified problem specific solution	5		
	2.5	LU decomposition			
		<u>=</u>	6		
	2.7	Implementation	6		
3	Results				
	3.1	General algorithm	8		
	3.2	Special algorithm	8		
	3.3	LU decomposition	8		
4	Discussion		8		
5	Con	clusion	8		
6	Ref	erences	8		

#### **Abstract**

The goal of this project were to... What did we do? What did we find?

#### 1 Introduction

- 1. Motivate the reader
- 2. What have I done
- 3. The structure of the report
- 4. conlusion?

In this project we will investegate different approaches to solve the onedimensional Poisson equation with Dirichlet boundary conditions given as follows:

$$u''(x) = f(x), \quad x \in (0,1), \quad u(0) = u(1) = 0$$

We will rewrite this as a set of linear equations, and solve it by a number of different computational approaches on either gaussian elimination or LU decomposition. We will solve the equation above with the function:

$$f(x) = 100e^{-10x}$$

Where the analytical solution then is given as:

$$u(x) = 1 - (1 - e^{-10})x - e^{-10x}$$

We will use the analytical solution to evaluate the precision of the numerical solutions for different steplength between the discretized gridpoints  $x_i$ .

#### 2 Method

Show test and example og code somewhere in method. Show that your code works before showing results later.

## 2.1 defining the problem

## 2.2 Rewritting the problem as a set of linear equations

In order to solve the Poisson equation numerically we discretize u as  $v_i$  with grid points  $x_i = ih$  in the interval  $x \in [x_0 = 0, x_1 = 1]$ . We then have

the step length h = 1/(n+1). We use the following second derivative approximation

$$-u''(x_i) \approx -\frac{v_{i+1} + 2v_i - v_{i+1}}{h^2} = f(x_i)$$

 $\iff$ 

$$-v_{i-1} + 2v_i - v_{i+1} = h^2 f(x_i)$$

We define the colum vector  $\mathbf{v} = [v_1, v_2, \dots, v_{n+1}]$  and try to setup the equation for every step i. As we do this we see a pattern appearing

$$\begin{bmatrix} 2 & -1 & 0 & \cdots & 0 \end{bmatrix} \begin{bmatrix} v_0 \\ \vdots \\ v_{n+1} \end{bmatrix} = h^2 f(x_0)$$

$$\begin{bmatrix} 2 & -1 & 0 & \cdots & \cdots & 0 \\ -1 & 2 & -1 & 0 & \cdots & \cdots \end{bmatrix} \begin{bmatrix} v_0 \\ \vdots \\ v_{n+1} \end{bmatrix} = h^2 \begin{bmatrix} f(x_0) \\ f(x_1) \end{bmatrix}$$

:

$$\begin{bmatrix} 2 & -1 & 0 & \cdots & \cdots & 0 \\ -1 & 2 & -1 & 0 & \cdots & \cdots \\ 0 & -1 & 2 & -1 & 0 & \cdots \\ \vdots & & & \ddots & \ddots & \cdots \\ 0 & \cdots & & -1 & 2 & -1 \\ 0 & \cdots & & 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} v_0 \\ \vdots \\ v_{n+1} \end{bmatrix} = h^2 \begin{bmatrix} f(x_0) \\ f(x_1) \\ \vdots \\ f_{n+1} \end{bmatrix}$$

From this we see that we can write the problem as a linear set of equation:

$$\mathbf{A}\mathbf{v} = \mathbf{g}$$

With the following definitions:

$$\mathbf{A} = \begin{bmatrix} 2 & -1 & 0 & \cdots & \cdots & 0 \\ -1 & 2 & -1 & 0 & \cdots & \cdots \\ 0 & -1 & 2 & -1 & 0 & \cdots \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ 0 & \cdots & & -1 & 2 & -1 \\ 0 & \cdots & & 0 & -1 & 2 \end{bmatrix} \quad , \mathbf{v} = \begin{bmatrix} v_0 \\ v_1 \\ \vdots \\ v_{n+1} \end{bmatrix} \quad , \tilde{\mathbf{g}} = h^2 \begin{bmatrix} f(x_0) \\ f(x_1) \\ \vdots \\ f_{n+1} \end{bmatrix}$$

In this project we use  $f(x) = 100e^{-10x}$ . The solution for the Poisson equation in this case is given to be  $u(x) = 1 - (1 - e^{-10})x - e^{-10x}$ . We can ensure that this is true by inserting it and checking that the equation holds remains true. First find the double derivative of u(x):

$$u'(x) = -(1 - e^{-10}) + 10e^{-10x}, \quad u''(x) = -100e^{-10x}$$

We now see that the solution satisfy the Poisson equation:

$$-u''(x) = 100e^{-10x} = f(x)$$

#### 2.3 General solution using Gausian elimination

Do Gaussial elimination... (or not)

We can solve our problem generally using Gaussian elimination on the matrix  $\mathbf{A}\mathbf{v} = \mathbf{g}$ , where  $a_i$  are the elements below the diagonal,  $b_i$  are the elements on the diagonal and  $c_i$  are the elements above the diagonal.

#### Algorithm 1 General algorithm

1: **for**  $i=2,\ldots,n$  **do**  $\Rightarrow$  Forward substitution eliminating  $a_i$   $\Rightarrow$  Update  $b_i$   $\Rightarrow$  Update  $b_i$   $\Rightarrow$  Update  $g_i$   $\Rightarrow$  Eackward substitution obtaining  $v_i$   $\Rightarrow$  Eackward substitution obtaining

We can calculate the algorithms number of Floating Point Operations Per Second (FLOPS) easily. Each arithmetic operation is one FLO(PS). So in our forward substitution we have  $2 \cdot 3$  FLOPS and in the backward substitution we have 1+3 FLOPS. The forward substitution goes from 2 to n, totaling n-2 points. The backward substitution also has n-2 points. Then the total number of FLOPS are:

$$(6+3)(n-2)+1=9n-17$$

#### 2.4 Simplified problem specific solution

In this specific case we have a=-1, b=2, c=-1 which means we can further simplify our matrix **A**:

$$\mathbf{A} = \begin{bmatrix} 2 & -1 & 0 & \cdots & \cdots & 0 \\ -1 & 2 & -1 & 0 & \cdots & \cdots \\ 0 & -1 & 2 & -1 & 0 & \cdots \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ 0 & \cdots & & -1 & 2 & -1 \\ 0 & \cdots & & 0 & -1 & 2 \end{bmatrix} \sim \begin{bmatrix} 2 & -1 & 0 & \cdots & \cdots & 0 \\ 0 & 3/2 & -1 & 0 & \cdots & \cdots \\ 0 & -1 & 2 & -1 & 0 & \cdots \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ 0 & \cdots & & -1 & 2 & -1 \\ 0 & \cdots & & 0 & -1 & 2 \end{bmatrix}$$

$$\sim \begin{bmatrix} 2 & -1 & 0 & \cdots & \cdots & 0 \\ 0 & 3/2 & -1 & 0 & \cdots & \cdots \\ 0 & 0 & 4/3 & -1 & 0 & \cdots \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ 0 & \cdots & & -1 & 2 & -1 \\ 0 & \cdots & & 0 & -1 & 2 \end{bmatrix} \sim \begin{bmatrix} 2 & -1 & 0 & \cdots & \cdots & 0 \\ 0 & 3/2 & -1 & 0 & \cdots & \cdots \\ 0 & 0 & 4/3 & -1 & 0 & \cdots \\ 0 & 0 & 4/3 & -1 & 0 & \cdots \\ 0 & \cdots & \cdots & \cdots & \cdots & \cdots \\ 0 & \cdots & 0 & i_n/i_n - 1 & -1 \\ 0 & \cdots & 0 & 0 & i_n + 1/i_n \end{bmatrix}$$

Where we have called the last diagonal element  $i_n$ . We see that  $b_i = \frac{i+1}{i}$ , reducing the computation time. With our new  $b_i$  we can create a new algorithm.

#### **Algorithm 2** Special algorithm, where $a_i = -1$ , $b_i = 2$ , $c_i = -1$

1: **for**  $i=2,\ldots,n$  **do**2:  $b_i=i+1/i$   $\Rightarrow$  Update  $b_i$ 3:  $g_i=g_i+g_{i-1}/b_{i-1}$   $\Rightarrow$  Update  $g_i$ 4: **end for**5:  $v_n=0$   $\Rightarrow$  Backward substitution obtaining  $v_i$ 6: **for**  $i=n-1,\ldots,1$  **do**7:  $v_i=\frac{g_i+v_{i+1}}{b_i}$ 

Similarly to the general algorithm we can calculate total FLOPS:

$$(2*2+2)(n-2)+1=6n-11$$

Which for large *n* is considerably less.

8: end for

# 2.5 LU decomposition

For the LU decomposition we ... FLOPS  $O(n^3)$  se https://en.wikipedia.org/wiki/LU\_decomposition,søk etter "float"

## 2.6 Comparing precision and error

# 2.7 Implementation

We used C++ to implement our algorithms ... and we used Pythons library Matplotlib to plot our results.

#### 3 Results

GITHUB LINK HERE Max error:

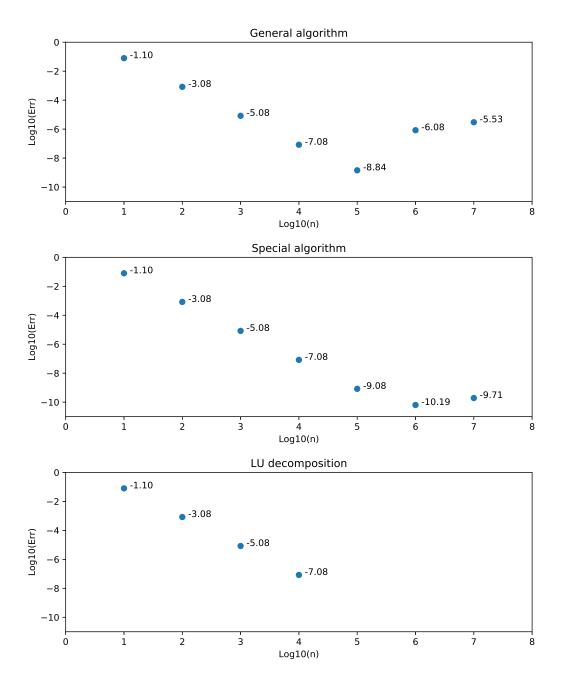


Figure 1: Log10 of the maximum error for each numerical solution compared to the analytical solution for different number of gridpoints n and different numerical methods.

Table 1: CPU Time

N	General algorithm [s]	Special algorithm	LU Decomposition
$10^{1}$	$3 \times 10^{-6}$	$3 \times 10^{-6}$	$9.81 \times 10^{-4}$
$10^{2}$	$4 \times 10^{-6}$	$4 \times 10^{-6}$	$1.96 \times 10^{-4}$
$10^{3}$	$3.8 \times 10^{-5}$	$3.7 \times 10^{-5}$	$1.02 \times 10^{-2}$
$10^{4}$	$3.41 \times 10^{-4}$	$3.54 \times 10^{-4}$	2.45
$10^{5}$	$3.79 \times 10^{-3}$	$3.50 \times 10^{-3}$	nan
$10^{6}$	$3.57 \times 10^{-2}$	$3.24 \times 10^{-2}$	nan
$10^{7}$	$3.16 \times 10^{-1}$	$3.24 \times 10^{-1}$	nan

- 3.1 General algorithm
- 3.2 Special algorithm
- 3.3 LU decomposition

#### 4 Discussion

Error analysis

# 5 Conclusion

In this report we have used three different ways of computing  $A\mathbf{v} = \mathbf{g}$  and have seen that efficiency of the methods vary greatly. We have witnessed the importance of efficient implementation of algorithms ...

## 6 References

# References

[1] Test