OAC-LA: Assignment 2-MPC Sensing is life Sensing is life

Park 1 - Linearization around y=x2=15cm

Fiven system

$$\dot{x}_1 = -k_1 \sqrt{x_1} + z_{pn}$$
 $\dot{x}_2 = -k_2 \sqrt{x_2} + k_3 \sqrt{x_1} + z_{pn}$

For equilibrium: $\dot{x} = \begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = 0$
 $\dot{x} = -k_1 \sqrt{x_2} + k_3 \sqrt{x_1} + z_{pn}$
 $\dot{x} = -k_2 \sqrt{x_2} + k_3 \sqrt{x_1} = z_{pn}$
 $\dot{x} = -k_1 \sqrt{x_2} + k_3 \sqrt{x_1} = z_{pn}$
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 $\dot{x} = -k_1 \sqrt{x_1} + z_{pn}$
 $\dot{x} =$

hatre = Zpaje

$$\begin{array}{c|c}
x_{1/e} = \frac{1}{R^{2}} \frac{1}{2} p_{1/e}^{2} \\
\Rightarrow \frac{1}{2} \frac{1}{R^{2}} \frac{1}{2} p_{1/e}^{2} \\
\Rightarrow \frac{1}{2} \frac{1}{R^{2}} \frac{1}{2} \frac{1}{R^{2}} \frac{1}{2} \frac{1}{R^{2}} \frac{1}{2} \frac{1}{R^{2}} \\
\Rightarrow \frac{1}{2} \frac{1}{R^{2}} \frac{$$

$$\frac{\partial f}{\partial u_n} = \begin{bmatrix} \frac{1}{2} (\beta_n + \beta_n u_n)^{\frac{1}{2}} \cdot \beta_n \\ 0 \end{bmatrix} \frac{\partial f}{\partial u_n} = \begin{bmatrix} \frac{1}{2} (\beta_n + \beta_n u_n)^{\frac{1}{2}} \cdot \beta_n \\ \frac{1}{2} (\beta_n + \beta_n u_n)^{\frac{1}{2}} \cdot \beta_n \end{bmatrix}$$

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