```
1
      // Vzorový projekt
      #include "stm8s.h"
 2
 3
      #include "milis.h"
 4
      #include "stdio.h"
      #include "spse_stm8.h"
 5
 6
      #include "stm8 hd44780.h"
 7
 8
      const uint16 t perioda01=10;
      uint16_t posledni cas=0;
9
      uint16_t sekundy=\overline{0};
10
      uint16_t milisekundy=0;
uint16_t minuty=0;
11
12
     uint16_t mezicas01=0;
uint16_t mezicas02=0;
13
14
      uint16_t mezicas03=0;
1.5
16
      uint8 t textove pole[32];
17
      uint8 t aktualni stav=0;
      uint8_t minuly_stav=0;
18
19
      uint8 t start=0;
20
     void stopky(void);
21
22
23
      void main(void) {
24
      CLK HSIPrescalerConfig(CLK PRESCALER HSIDIV1); // taktovat MCU na 16MHz
25
      GPIO Init(GPIOD, GPIO PIN 6, GPIO MODE OUT PP LOW SLOW);
26
      GPIO Init(GPIOD, GPIO PIN 5, GPIO MODE OUT PP LOW SLOW);
27
      GPIO Init (GPIOE, GPIO PIN 4, GPIO MODE IN FL NO IT);
28
      init milis();
29
      lcd init();
30
      lcd gotoxy(10,0);
      lcd_puts(":");
31
32
      lcd_gotoxy(13,0);
33
      lcd_puts(".");
34
      lcd_gotoxy(10,1);
35
      lcd_puts(":");
      lcd_gotoxy(13,1);
36
37
      lcd_puts(".");
38
      lcd_gotoxy(11,1);
39
      lcd_puts("00");
40
      lcd_gotoxy(8,1);
41
      lcd puts("00");
42
      lcd_gotoxy(14,1);
      lcd puts("00");
43
      lcd gotoxy(11,0);
44
      lcd_puts("00");
45
      lcd_gotoxy(8,0);
46
      lcd puts("00");
47
48
      lcd gotoxy(14,0);
49
      lcd_puts("00");
      lcd_gotoxy(4,0);
50
51
      lcd puts("cas ");
52
      lcd gotoxy(0,1);
53
      lcd puts("mezicas ");
54
55
      while(1){
56
      if (start==1) {
57
      stopky();
58
      sprintf(textove pole,"%02u",milisekundy);
59
      lcd gotoxy(14,0);
60
      lcd_puts(textove_pole);
61
62
      sprintf(textove pole, "%02u", sekundy);
63
      lcd_gotoxy(11,0);
64
      lcd_puts(textove_pole);
65
      sprintf(textove_pole,"%02u",minuty);
66
67
      lcd_gotoxy(8,0);
68
      lcd puts(textove_pole);
69
70
71
        if(GPIO_ReadInputPin(GPIOE,GPIO_PIN_4) == RESET && minuly_stav==0) {
```

```
72
           minuly_stav = 1;
 73
           if (start==0) { start=1; }
 74
           else{start=0;}
 75
 76
 77
         if(GPIO ReadInputPin(GPIOE,GPIO PIN 4)!=RESET && minuly stav==1){
           minuly_stav = 0;
 78
 79
 80
 81
 82
 83
 84
 85
 86
 87
 88
       if (GPIO_ReadInputPin(GPIOD,GPIO_PIN_6)!=RESET) { //Zde je mezičas, který po stisku
       tlačítka na NP napíše na displej hodnoty proměnných.
 89
       lcd gotoxy(10,1);
       lcd_puts(":");
 90
 91
       lcd_gotoxy(13,1);
 92
       lcd puts(".");
 93
       sprintf(textove pole,"%02u",mezicas02);
 94
       lcd gotoxy (11,1);
 95
       lcd puts(textove pole);
 96
       sprintf(textove pole, "%02u", mezicas03);
 97
       lcd gotoxy(8,1);
 98
       lcd puts(textove pole);
 99
       sprintf(textove pole,"%02u",mezicas01);
100
       lcd gotoxy(14,1);
101
       lcd_puts(textove_pole);
102
103
104
       if (GPIO_ReadInputPin(GPIOD,GPIO_PIN_5)!=RESET) {
105
       sekundy=0;
106
       milisekundy=0;
107
      minuty=0;
108
      mezicas01=0;
109
      mezicas02=0;
110
      mezicas03=0;
111
       lcd gotoxy(11,1);
112
       lcd_puts("00");
113
       lcd gotoxy(8,1);
114
       lcd puts("00");
       lcd\_gotoxy(14,1);
115
       lcd_puts("00");
116
117
       lcd gotoxy(11,0);
       lcd puts("00");
118
       lcd_gotoxy(8,0);
119
120
       lcd_puts("00");
121
       lcd gotoxy(14,0);
122
       lcd_puts("00");
123
124
125
126
       }
127
128
129
130
131
132
133
134
135
136
137
138
139
140
       void stopky (void) {
141
       if(milis() - posledni_cas >= perioda01){//zde je funkce, která se stará o chod stopek.
```

```
142
       posledni cas = milis();
143
      milisekundy=milisekundy+1;
144
      mezicas01=milisekundy;}
145
      if (milisekundy>=98) {
146
      milisekundy=0;
147
      sekundy=sekundy+1;
148
      mezicas02=sekundy;
149
150
      if(sekundy>=60){
151
      sekundy=0;
152
      minuty=minuty+1;
153
      mezicas03=minuty;
154
155
       }
156
157
158
159
       #ifdef USE FULL ASSERT
160
161
162
163
       * @brief Reports the name of the source file and the source line number
164
      * where the assert param error has occurred.
165
      * @param file: pointer to the source file name
166
      * @param line: assert param error line source number
167
      * @retval : None
168
169
      void assert failed(u8* file, u32 line)
170
       /* User can add his own implementation to report the file name and line number,
171
172
      ex: printf("Wrong parameters value: file %s on line %d\r\n", file, line) */
173
174
       /* Infinite loop */
175
      while (1)
176
       {
177
       }
178
179
       #endif
180
181
```

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