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Contents

1	Introduction						
2	Mai	n Sectio	on	4			
	2.1	Noncommutative Geometric Spaces					
		2.1.1	*-Algebra	4			
		2.1.2	Finite Discrete Space	4			
		2.1.3	Finite Inner Product Spaces and Representations	5			
		2.1.4	Algebraic Modules	7			
		2.1.5	Balanced Tensor Product and Hilbert Bimodules	8			
		2.1.6	Kasparov Product and Morita Equivalence	9			
	2.2	Finite	Spectral Triples	12			
		2.2.1	Metric on Finite Discrete Spaces	12			
		2.2.2	Properties of Matrix Algebras	15			
		2.2.3	Morphisms Between Finite Spectral Triples	16			
	2.3	Finite	Real Noncommutative Spaces	19			
		2.3.1	Finite Real Spectral Triples	19			
		2.3.2	Morphisms Between Finite Real Spectral Triples	21			
	2.4	Heat I	Kernel Expansion	24			
		2.4.1	The Heat Kernel	24			
		2.4.2	Spectral Functions	24			
		2.4.3	General Formulae	25			
		2.4.4	Heat Kernel Coefficients	26			
	2.5	st-commutative Manifold	28				
		2.5.1	Two-Point Space	28			
		2.5.2	Product Space	29			
		2.5.3	U(1) Gauge Group	30			
	2.6	Nonco	ommutative Geometry of Electrodynamics	31			
		2.6.1	The Finite Space	32			
		2.6.2	A noncommutative Finite Dirac Operator	34			
		2.6.3	Almost commutative Manifold of Electrodynamics	34			
		2.6.4	Spectral Action	35			
		2.6.5	Fermionic Action	37			
3	Con	clusion	l	39			
4	Ack	nowled	gment	39			

Abstract

Noncommutative geometry is a branch of mathematics that has deep connections to applications in physics. From reconstructing the theory of electrodynamics with minimal coupling to gravity, to deriving the full Lagrangian of the standard model and predicting the Higgs mass. One of the reasons for this is the natural existence of a nontrivial gauge group of a mathematical structure called the spectral triple, which encodes (classical) geometrical data intro algebraic data. Altogether this thesis is based on literature work, mostly from Walter D. Suijlekom's book [1]. We summarize enough information to both establish the basic backbone of noncommutative geometry and to further out derive the Lagrangian of electrodynamics.

1 Introduction

Noncommutative geometry is a branch of mathematics that incorporates many different mathematical fields, e.g. Functional analysis, K-Theory, Differential Geometry, Representation Theory and many more. The origins can be dated back to the 1940s where two Russian mathematicians Gelfand and Naimark proved a theorem that connects (in the sense of duality) (classical) geometry and algebras. From the beginning it was obvious that noncommutative geometry has physical applications, explicitly with gauge theories, since a nontrivial gauge group arises naturally from the main structure of noncommutative geometry called the spectral triple. We will naturally use this property to present how to derive the Lagrangian of electrodynamics 2.5, and additionally get a purely gravitational Lagrangian. In regards to this to get to the action principles in terms of geometrical invariants, a method called the heat kernel expansion is used.

The aim of this thesis is to give a basic foundation of noncommutative geometry and to present a physical application which can be derived from this theory. Additionally we emphasize that this thesis is only literature work, where chapters 2.1, 2.2, 2.3, 2.5 and 2.6 are from the work of Walter D. Suijlekom's book [1] and chapter 2.4 from D.V. Vassilevich's paper [2].

The prominent structure of noncommutative geometry is the spectral triple. The most basic form of a spectral triple consists of a unital C^* algebra A acting on a Hilbertspace H. Together with a self-adjoint operator D in H, with specific conditions coinciding with the Dirac operator on a Riemannian spin^C manifold which square is the Laplacian (up to a scalar term).

The structure of the thesis is based on first getting the background knowledge of non-commutative geometry and the heat kernel expansion. Then by combining this insight we work out the Lagrangian of electrodynamics. In this regard the first two chapters 2.1 and 2.2 go through the basic version of noncommutative geometry, in the sense of finite discrete spaces. It is important to understand these basics, since the they build up the ground work of constructing the almost commutative manifold of electrodynamics, that is the Two-Point space F_X . Additionally the notion of equivalence relations between spectral triples, called Morita equivalence is introduced

The next chapter 2.3 extends the finite spectral triple with a real structure, called the real finite spectral triple, we also examine Morita equivalence within this extension.

Chapter 2.4 explains the heat kernel and leads off to the heat kernel expansion, where the famous heat kernel coefficients arise. Hereof we calculate the heat kernel coefficients, which become important when calculating the Lagrangian of the almost commutative manifold of electrodynamics.

In the last two chapters 2.5 and 2.6 we go over the ideas and the process of constructing the almost commutative manifold, that will give rise to the Lagrangian of electrodynamics and an additional purely gravitational Lagrangian.

2 Main Section

2.1 Noncommutative Geometric Spaces

2.1.1 *-Algebra

To grasp the idea of encoding geometrical data into a spectral triple we introduce the first ingredient of a spectral triple, an unital * algebra.

Definition 1

A vector space A over \mathbb{C} is called a complex, unital algebra if for all $a, b \in A$:

$$A \times A \to A \tag{2.1}$$

$$(a, b) \mapsto a \cdot b, \tag{2.2}$$

with an identity element:

$$1a = a1 = a. (2.3)$$

Extending the definition, a *-algebra is an algebra A with a conjugate linear map (involution) *: $A \rightarrow A$, $\forall a, b \in A$ satisfying

$$(a b)^* = b^* a^*, (2.4)$$

$$(a^*)^* = a. (2.5)$$

In the following all unital algebras are referred to as algebras.

2.1.2 Finite Discrete Space

Let us consider an example, a *-algebra of continuous functions C(X) on a discrete topological space X with N points. Functions of a continuous *-algebra C(X) assign values to $\mathbb C$ and for $f, g \in C(X)$, $\lambda \in \mathbb C$ and $x \in X$ they provide the following structure:

• pointwise linear

$$(f+g)(x) = f(x) + g(x),$$
 (2.6)

$$(\lambda f)(x) = \lambda(f(x)), \tag{2.7}$$

• pointwise multiplication

$$f g(x) = f(x)g(x), (2.8)$$

• pointwise involution

$$f^*(x) = \overline{f(x)}. (2.9)$$

The *-algebra C(X) is *isomorphic* to a *-algebra \mathbb{C}^N with involution (N number of points in X), we write $C(X) \simeq \mathbb{C}^N$. Isomorphisms are bijective maps that preserve structure and don't lose physical information. A function $f: X \to \mathbb{C}$ can be represented with $N \times N$ diagonal matrices, where each diagonal value represents the function value

at the corresponding i-th point for i = 1,...,N. Matrix multiplication and hermitian conjugation of matrices we have a preserving structure.

Moreover we can map between finite discrete spaces X_1 and X_2 with a function

$$\phi: X_1 \to X_2.$$
 (2.10)

For every such map there exists a corresponding map

$$\phi^*: C(X_2) \to C(X_1),$$
 (2.11)

which 'pulls back' values even if ϕ is not bijective. Note that the pullback does not map points back, but maps functions on an *-algebra C(X). The pullback, in literature often called a *-homomorphism or a *-algebra map under pointwise product has the following properties

$$\phi^*(f g) = \phi^*(f) \ \phi^*(g), \tag{2.12}$$

$$\phi^*(\overline{f}) = \overline{\phi^*(f)},\tag{2.13}$$

$$\phi^*(\overline{f}) = \overline{\phi^*(f)},$$

$$\phi^*(\lambda f + g) = \lambda \phi^*(f) + \phi^*(g).$$
(2.13)
$$(2.14)$$

The map $\phi: X_1 \to X_2$ is an injective (surjective) map, if only and if the corresponding pullback $\phi^*: C(X_2) \to C(X_1)$ is surjective (injective). To clarify let us say that X_1 has n points and X_2 with m points. Then there are three different cases, first n = m and obviously ϕ is bijective and ϕ^* too. Then n > m, in this case ϕ assigns n points to m points when n > m, which is by definition surjective. On the other hand ϕ^* assigns m points to n points when n > m, which is by definition injective. Lastly n < m, which is completely analogous to the case n > m.

Definition 2

A (complex) matrix algebra A is a direct sum, for $n_i, N \in \mathbb{N}$

$$A = \bigoplus_{i=1}^{N} M_{n_i}(\mathbb{C}). \tag{2.15}$$

The involution is the hermitian conjugate. A * algebra with involution is referred to as a matrix algebra

To summarize, from a topological discrete space X, we can construct a *-algebra C(X) which is isomorphic to a matrix algebra A. Then the question instantly arises, if we can construct X given A? For a matrix algebra A, which in most cases is not commutative, the answer is generally no. Hence there are two options. We can restrict ourselves to commutative matrix algebras, which are the vast minority and not physically interesting. Or we can allow more morphisms (isomorphisms) between matrix algebras.

2.1.3 Finite Inner Product Spaces and Representations

Until now we have looked at finite topological discrete spaces, moreover we can consider a finite dimensional inner product space H (finite Hilbertspaces), with inner product $(\cdot,\cdot)\to\mathbb{C}$. We denote L(H) as the *-algebra of operators on H equipped with a product given by composition and involution of the adjoint, $T \mapsto T^*$. Then L(H) is a normed vector space with

$$||T||^2 = \sup_{h \in H} \{ (T \ h, \ T \ h) : (h, \ h) \le 1 | \ T \in L(H) \}, \tag{2.16}$$

$$||T|| = \sup \{\sqrt{\lambda} : \lambda \text{ eigenvalue of } T\}.$$
 (2.17)

The Hilbertspace allows us to define representations of *-algebras.

Definition 3

The representation of a finite dimensional *-algebra A is a pair (H, π) , where H is a finite dimensional inner product space and π is a *-algebra map

$$\pi: A \to L(H). \tag{2.18}$$

We call the representation (H, π) irreducible if

- $H \neq \emptyset$,
- only \emptyset or H is invariant under the action of A on H.

Here are some examples of reducible and irreducible representations

- For $A = M_n(\mathbb{C})$ the representation $H = \mathbb{C}^n$, A acts as matrix multiplication H is irreducible.
- For $A = M_n(\mathbb{C})$ the representation $H = \mathbb{C}^n \oplus \mathbb{C}^n$, with $a \in A$ acting in block form $\pi : a \mapsto \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix}$ is reducible.

Naturally there are also certain equivalences between different representations.

Definition 4

Two representations of a *-algebra A, (H_1, π_1) and (H_2, π_2) are called unitary equivalent if there exists a map $U: H_1 \to H_2$ such that.

$$\pi_1(a) = U^* \pi_2(a) U \tag{2.19}$$

Furthermore we define a mathematical structure called the structure space, which will become important later when speaking of the duality between a spectral triple and a geometrical space.

Definition 5

Let A be a *-algebra then, \hat{A} is called the structure space of all unitary equivalence classes of irreducible representations of A.

Given a representation (H, π) of a *-algebra A, the **commutant** $\pi(A)'$ of $\pi(A)$ is defined as a set of operators in L(H) that commute with all $\pi(a)$

$$\pi(A)' = \{ T \in L(H) : \ \pi(a) \ T = T \ \pi(a) \ \forall a \in A \}$$
 (2.20)

The commutant $\pi(A)'$ is also a *-algebra, since it has unital, associative and involutive properties. The unitary property is given by the unital operator of the *-algebra of operators L(H), which exists by definition because H is a inner product space. Associativity is given by the *-algebra of L(H), where $L(H) \times L(H) \mapsto L(H)$, which is associative

by definition. The involutive property is also given by the *-algebra L(H) with a map $*: L(H) \mapsto L(H)$ only for a $T \in H$ that commutes with $\pi(a)$.

For a unital algebra *-algebra A, the matrices $M_n(A)$ with entries in A form a unital *-algebra, because the unitary operation in $M_n(A)$ is given by the identity Matrix, which exists in every entry in $M_n(A)$ and behaves like in A. Associativity is given by matrix multiplication. Lastly, involution is given by the conjugate transpose.

Consider a representation $\pi: A \to L(H)$ of a *-algebra A and set $H^n = H \oplus ... \oplus H$, n times. Then we have the following representation $\tilde{\pi}: M_n(A) \to L(H^n)$ for the Matrix algebra with $\tilde{\pi}((a_{ij})) = (\tilde{\pi}(a_{ij})) \in M_n(A)$, since a direct isomorphisms of $A \simeq M_n(A)$ and $H \simeq H^n$ exists. Meaning $\tilde{\pi}$ is a valid reducible representation.

By looking at $\tilde{\pi}: M_n(A) \to L(H^n)$ a * algebra representation of $M_n(A)$. We see that $\pi: A \to L(H^n)$ is a representation of A. The fact that $\tilde{\pi}$ and π are unitary equivalent, there is a map $U: H^n \to H^n$ given by $U = \mathbb{I}_n$, thus

$$\pi(a) = \mathbb{1}_n^* \,\tilde{\pi}((a_{ij})),\tag{2.21}$$

$$\mathbb{1}_n = \tilde{\pi}((a_{ij})) = \pi(a_{ij}) \Rightarrow a_{ij} = a \, \mathbb{1}_n. \tag{2.22}$$

With help of the structure space \hat{A} , a commutative matrix algebra can be used to reconstruct a discrete space. Since $A \simeq \mathbb{C}^N$ all irreducible representation are of the form

$$\pi_i: (\lambda_1, ..., \lambda_N) \in \mathbb{C}^N \mapsto \lambda_i \in \mathbb{C}$$
 (2.23)

for i = 1,...,N, and thus $\hat{A} \simeq \{1,...,N\}$. We can conclude that there is a duality between discrete spaces and commutative matrix algebras. This duality is called the *finite dimensional Gelfand duality*

Our aim is to make a further generalization by constructing a duality between finite dimensional spaces and *equivalence classes* of matrix algebras that preserves general non-commutativity of matrices. Equivalence classes are described by a concept of isomorphisms between matrix algebras called *Morita Equivalence*.

2.1.4 Algebraic Modules

An important part of the Morita Equivalence are algebraic modules, later extended by Hilbert bimodules.

Definition 6

Let A, B be algebras (need not be matrix algebras)

1. *left* A-module is a vector space E, that carries a left representation of A, that is \exists a bilinear map $\gamma: A \times E \rightarrow E$ with

$$(a_1 \ a_2) \cdot e = a_1 \cdot (a_2 \cdot e); \ a_1, a_2 \in A, e \in E.$$
 (2.24)

2. right B-module is a vector space F, that carries a right representation of A, that is there exists a bilinear map $\gamma: F \times B \to F$ with

$$f \cdot (b_1 \ b_2) = (f \cdot b_1) \cdot b_2; \ b_1, b_2 \in B, f \in F$$
 (2.25)

3. left A-module and right B-module is a bimodule, a vector space E satisfying

$$a \cdot (e \cdot b) = (a \cdot e) \cdot b; \quad a \in A, b \in B, e \in E$$
 (2.26)

An A-module homomorphism is linear map $\phi : E \to F$ which respects the representation of A, e.g. for left module.

$$\phi(a e) = a\phi(e); \quad a \in A, e \in E. \tag{2.27}$$

We will use the notation

- _AE, for left A-module E;
- ${}_{A}E_{B}$, for right *B*-module *F*;
- ${}_{A}E_{B}$, for A-B-bimodule E, simply bimodule.

From a simple observation, we see that an arbitrary representation $\pi: A \to L(H)$ of a *-algebra A, turns H into a left module ${}_{A}H$. If ${}_{A}H$ than $(a_1 \ a_2)h = a_1(a_2 \ h)$ for $a_1, a_2 \in A$ and $h \in H$. We take the representation of an $a \in A$, $\pi(a)$, and write

$$(\pi(a_1) \ \pi(a_2))h = \pi(a_1)(\pi(a_2) \ h) = (T_1 \ T_2)h = T_1(T_2 \ h)$$
 (2.28)

For $T_1, T_2 \in L(H)$, which operate naturally from the left on h.

Furthermore notice that that an *-algebra A is a bimodule ${}_{A}A_{A}$ with itself, given by the map

$$\gamma: A \times A \times A \to A,\tag{2.29}$$

which is the inner product of a *-algebra.

2.1.5 Balanced Tensor Product and Hilbert Bimodules

In this chapter we introduce the balanced tensor product later called the Kasparov product. This operation allows us to naturally construct a bimodule of a third algebra in chapter 2.1.6.

Definition 7

Let A be an algebra, E be a right A-module and F be a left A-module. The balanced tensor product of E and F forms a A-bimodule.

$$E \otimes_A F := E \otimes F / \left\{ \sum_i e_i a_i \otimes f_i - e_i \otimes a_i f_i : \quad a_i \in A, \ e_i \in E, \ f_i \in F \right\}. \quad (2.30)$$

The symbol / denotes the quotient space. By careful examination we can say that the operation \otimes_A takes two left/right modules and makes a bimodule. Additionally with the help of the tensor product of the two modules and the quotient space which takes out all the elements from the tensor product that don't preserver the left/right representation and that are duplicates.

Definition 8

Let A, B be matrix algebras. The Hilbert bimodule for (A,B) is given by an A-B-bimodue E and by an B-valued inner product $\langle \cdot, \cdot \rangle_E : E \times E \to B$, which satisfies

the following conditions for $e, e_1, e_2 \in E$, $a \in A$ and $b \in B$

$$\langle e_1, a \cdot e_2 \rangle_E = \langle a^* \cdot e_1, e_2 \rangle_E$$
 sesquilinear in A , (2.31)

$$\langle e_1, e_2 \cdot b \rangle_E = \langle e_1, e_2 \rangle_E b$$
 scalar in B, (2.32)

$$\langle e_1, e_2 \rangle_E = \langle e_2, e_1 \rangle_E^*$$
 hermitian, (2.33)

$$\langle e, e \rangle_E \ge 0$$
 equality holds iff $e = 0$. (2.34)

We denote $KK_f(A, B)$ as the set of all Hilbert bimodules of (A, B).

And indeed the Hilbert bimodule extension takes a representation $\pi:A\to L(H)$ of a matrix algebra A and turns H into a Hilbert bimodule for (A,\mathbb{C}) , because the representation for a $a\in A$, $\pi(a)=T\in L(H)$ fulfills the conditions of the \mathbb{C} -valued inner product for $h_1,h_2\in H$

- $\langle h_1, \pi(a) h_2 \rangle_{\mathbb{C}} = \langle h_1, T h_2 \rangle_{\mathbb{C}} = \langle T^*h_1, h_2 \rangle_{\mathbb{C}}, T^*$ given by the adjoint,
- $\langle h_1, h_2 \pi(a) \rangle_{\mathbb{C}} = \langle h_1, h_2 T \rangle_{\mathbb{C}} = \langle h_1, h_2 \rangle_{\mathbb{C}}$, T acts from the left,
- $\langle h_1, h_2 \rangle_{\mathbb{C}}^* = \langle h_2, h_1 \rangle_{\mathbb{C}}$, hermitian because of the \mathbb{C} -valued inner product
- $\langle h_1, h_2 \rangle \geq 0$, \mathbb{C} -valued inner product.

Take again the A-A bimodule given by an *-algebra A. By looking at the following inner product $\langle \cdot, \cdot \rangle_A : A \times A \to A$

$$\langle a, a \rangle_A = a^* a' \quad a, a' \in A., \tag{2.35}$$

it becomes clear that $A \in KK_f(A, A)$. Simply checking the conditions in $\langle \cdot, \cdot \rangle_A$ for $a, a_1, a_2 \in A$

$$\langle a_1, a \cdot a_2 \rangle_A = a^* a \cdot a_2 = (a^* a_1)^* a_2 = \langle a^* a_1, a_2 \rangle,$$
 (2.36)

$$\langle a_1, a_2 \cdot a \rangle_A = a_1^* (a_2 \cdot a) = (a^* a_2) \cdot a = \langle a_1, a_2 \rangle_A a,$$
 (2.37)

$$\langle a_1, a_2 \rangle_A^* = (a_1^* a_2)^* = a_2^* (a_1^*)^* = a_2^* a_1 = \langle a_2, a_1 \rangle.$$
 (2.38)

2.1.6 Kasparov Product and Morita Equivalence

Definition 9

Let $E \in KK_f(A,B)$ and $F \in KK_F(B,D)$ the Kasparov product is defined as with the balanced tensor product

$$F \circ E := E \otimes_B F. \tag{2.39}$$

Then $F \circ E \in KK_f(A, D)$ is equipped with a *D*-valued inner product

$$\langle e_1 \otimes f_1, e_2 \otimes f_2 \rangle_{E \otimes_R F} = \langle f_1, \langle e_1, e_2 \rangle_E f_2 \rangle_F \tag{2.40}$$

The Kasparov product for *-algebra homomorphism $\phi: A \to B$ and $\psi: B \to C$ are isomorphisms in the sense that

$$E_{\psi} \circ E_{\phi} \equiv E_{\phi} \otimes_{B} E_{\psi} \simeq E_{\psi \circ \phi} \in KK_{f}(A, C). \tag{2.41}$$

The direct computation for $a \in A$, $b \in B$, and $c \in C$ which is $\psi \circ \phi$ shows us

$$a \cdot b \cdot c = \psi(\phi(a) \cdot b) \cdot c \tag{2.42}$$

An interesting case arises when looking at $E_{\mathrm{id}_A} \simeq A \in KK_f(A,A)$, where id_A is the identity in A. Let E_{ϕ} be A with a natural right representation. It follows that $E_{\phi} \simeq A$, where an inner product, acting from the left on A for ϕ , a', $a \in A$ reads

$$a' a = (\phi(a') a) \in A,$$
 (2.43)

which is satisfied only by $\phi = id_A$.

Definition 10

Let A, B be matrix algebras. They are called Morita equivalent if there exists an $E \in KK_f(A,B)$ and an $F \in KK_f(B,A)$ such that

$$E \otimes_B F \simeq A$$
 and $F \otimes_A E \simeq B$, (2.44)

where \simeq denotes the isomorphism between Hilbert bimodules and note that A or B is a bimodule by itself.

Since we land in the same space as we started, the modules E and F are each others inverse in regards to the Kasparov Product. More clearly, in the definition we have $E \in KK_f(A,B)$. Naturally we start from A and $E \otimes_B F$, which lands in A. On the other hand we have $F \in KK_f(B,D)$ and start from B, $F \otimes_A E$, which lands in B.

By definition $E \otimes_B F$ is a A - D bimodule. Since

$$E \otimes_B F = E \otimes F / \left\{ \sum_i e_i \ b_i \otimes f_i - e_i \otimes b_i \ f_i \ \middle| \ e_i \in E_i, \ b_i \in B, \ f_i \in F \right\}, \tag{2.45}$$

the last part takes out all tensor product elements of E and F that don't preserver the left/right representation and that are duplicates.

Additionally $\langle \cdot, \cdot \rangle_{E \oplus_B F}$ defines a D valued inner product, as $\langle e_1, e_2 \rangle_E \in B$ and $\langle f_1, f_2 \rangle_F \in C$ by definition. So for $\langle e_1, e_2 \rangle_E = b$ we have

$$\langle e_1 \otimes f_1, e_2 \otimes f_2 \rangle_{E \otimes_R F} = \langle f_1, \langle e_1, e_2 \rangle_E f_2 \rangle_F = \langle f_1, b f_2 \rangle_F \in C$$
 (2.46)

Picking up the example of (A,A), the Hilbert bimodule A, we can consider an $E \in KK_f(A,B)$ for

$$E \circ A = A \oplus_A E \simeq E. \tag{2.47}$$

We conclude, that ${}_{A}A_{A}$ is the identity element in the Kasparov product (up to isomorphism). Let us examine another example for $E = \mathbb{C}^{n}$, which is a $(M_{n}(\mathbb{C}), \mathbb{C})$ Hilbert bimodule with the standard \mathbb{C} inner product. Further let $F = \mathbb{C}^{n}$, which is a $(\mathbb{C}, M_{n}(\mathbb{C}))$ Hilbert bimodule by right matrix multiplication with $M_{n}(\mathbb{C})$ valued inner product, we can write

$$\langle v_1, v_2 \rangle = \bar{v_1} v_2^t \in M_n(\mathbb{C}). \tag{2.48}$$

If we take the Kasparov product of E and F

$$F \circ E = E \otimes_{\mathbb{C}} F \simeq M_n(\mathbb{C}),$$
 (2.49)

$$E \circ F = F \otimes_{M_{n}(\mathbb{C})} E \simeq \mathbb{C}, \tag{2.50}$$

we see that $M_n(\mathbb{C})$ and \mathbb{C} are Morita equivalent!

Lemma 1

Two matrix algebras are Morita Equivalent if, and only if their their structure spaces are isomorphic as discreet spaces (have the same cardinality / same number of elements).

Proof. Let A, B be Morita equivalent. Then there exist the modules ${}_{A}E_{B}$ and ${}_{B}F_{A}$ with

$$E \otimes_B F \simeq A$$
 and $F \otimes_A E \simeq B$. (2.51)

Also consider $[(\pi_B, H)] \in \hat{B}$. We can construct a representation of A, which reads

$$\pi_A \to L(E \otimes_B H) \quad \text{with} \quad \pi_A(a)(e \otimes v) = ae \otimes w$$
 (2.52)

Vice versa, we have $[(\pi_A, W)] \in \hat{A}$ and we can construct π_B as

$$\pi_B: B \to L(F \otimes_A W) \text{ and } \pi_B(b)(f \otimes w) = bf \otimes w.$$
(2.53)

Now we need to show that the representation π_A is irreducible if and only if π_B is irreducible. For (π_B, H) to be irreducible, we need $H \neq \emptyset$ and only \emptyset or H to be invariant under the Action of B on H. Than $E \otimes_B H$ and $E \otimes_B H \simeq A$ cannot be empty, because E preserves left representation of A.

Lastly we need to check if the association of the class $[\pi_A]$ to $[\pi_B]$ is independent of the choice of representatives π_A and π_B . The important thing is that $[\pi_A] \in \hat{A}$ respectively $[\pi_B] \in \hat{B}$, hence any choice of representation is irreducible, because the structure space denotes all unitary equivalence classes of irreducible representations.

Note that the statements $E \simeq H$ and $F \simeq W$ are not particularly true, since all infinite dimensional Hilbertspaces are isomorphic. Here we are looking at finite dimensional Hilbertspaces. Another thing to keep in mind, is that for $[\pi_B, H] \in \hat{B}$ and looking at algebraic bimodules, we know that H is a bimodule of B, hence $E \otimes_B H \simeq A$, and for $[\pi_A, W]$, which is the same. Finally we can conclude, that these maps are each others inverses, thus $\hat{A} \simeq \hat{B}$.

Lemma 2

The matrix algebra $M_n(\mathbb{C})$ has a unique irreducible representation (up to isomorphism) given by the defining representation on \mathbb{C}^n .

Proof. We know \mathbb{C}^n is a irreducible representation of $A = M_n(\mathbb{C})$. Let H be irreducible and of dimension k, then we define a map

$$\phi: A \oplus \dots \oplus A \to H^* \tag{2.54}$$

$$(a_1,...,a_k) \mapsto e^1 \circ a_1^t + ... + e^k \circ a_k^t,$$
 (2.55)

where $\{e^1,...,e^k\}$ is the basis of the dual space H^* and (\circ) being the pre-composition of elements in H^* and A acting on H. This forms a morphism of $M_n(\mathbb{C})$ modules, provided a matrix $a \in A$ acts on H^* with $v \mapsto v \circ a^t$ ($v \in H^*$). Furthermore this morphism is surjective, thus making the pullback $\phi^* : H \mapsto (A^k)^*$ injective. Now identify $(A^k)^*$ with A^k as a A-module and note that $A = M_n(\mathbb{C}) \simeq \bigoplus^n \mathbb{C}^n$ as a $n \in A$ module. It follows that H is a submodule of $A^k \simeq \bigoplus^{nk} \mathbb{C}$. By irreducibility $H \simeq \mathbb{C}$.

Let us look at an example, two matrix algebras A, and B.

$$A = \bigoplus_{i=1}^{N} M_{n_i}(\mathbb{C}), \quad B = \bigoplus_{j=1}^{M} M_{m_j}(\mathbb{C}). \tag{2.56}$$

Let $\hat{A} \simeq \hat{B}$, this implies N = M. Further define E with A acting by block-diagonal matrices on the first tensor and B acting in the same manner on the second tensor. Define F vice versa, ultimately reading

$$E := \bigoplus_{i=1}^{N} \mathbb{C}^{n_i} \otimes \mathbb{C}^{m_i}, \quad F := \bigoplus_{i=1}^{N} \mathbb{C}^{m_i} \otimes \mathbb{C}^{n_i}. \tag{2.57}$$

When we calculate the Kasparov product we get the following

$$E \otimes_B F \simeq \bigoplus_{i=1}^N (\mathbb{C}^{n_i} \otimes \mathbb{C}^{m_i}) \otimes_{M_{m_i}(\mathbb{C})} (\mathbb{C}^{m_i} \otimes \mathbb{C}^{n_i})$$
 (2.58)

$$\simeq \bigoplus_{i=1}^{N} \mathbb{C}^{n_i} \otimes \left(\mathbb{C}^{m_i} \otimes_{M_{m_i}(\mathbb{C})} \mathbb{C}^{m_i} \right) \oplus \mathbb{C}^{n_i}$$
 (2.59)

$$\simeq \bigoplus_{i=1}^{N} \mathbb{C}^{m_i} \otimes \mathbb{C}^{n_i} \simeq A. \tag{2.60}$$

On the other hand we get

$$F \otimes_A E \simeq B.$$
 (2.61)

To summarize, there is a duality between finite spaces and Morita equivalence classes of matrix algebras. Furthermore by replacing *-homomorphism $A \to B$ with Hilbert bimodules (A,B) we introduce a richer structure of morphism between matrix algebras.

2.2 Finite Spectral Triples

2.2.1 Metric on Finite Discrete Spaces

We can describe our finite discrete space X by a structure space \hat{A} of a matrix algebra A. To establish a distance between two points in X (as we would in a metric space) we use an array $\{d_{ij}\}_{i,j\in X}$ of *real non-negative* entries in X such that

- $d_{ij} = d_{ji}$ Symmetric
- $d_{ij} \le d_{ik}d_{kj}$ Triangle Inequality
- $d_{ij} = 0$ for i = j

In the commutative case, the algebra A is commutative and can describe the metric on X in terms of algebraic data.

Theorem 1

Let d_{ij} be a metric on X a finite discrete space with N points, $A = \mathbb{C}^N$ with elements $a = (a(i))_{i=1}^N$ such that $\hat{A} \simeq X$. Then there exists a representation π of A on a finite-dimensional inner product space H and a symmetric operator D on

$$H$$
 such that
$$d_{ij} = \sup_{a \in A} \left\{ \left| a(i) - a(j) \right| : \left| \left| \left[D, \pi(a) \right] \right| \right| \le 1 \right\}$$
 (2.62)

Proof. We claim that this would follow from the equality:

$$\left| \left| \left| [D, \pi(a)] \right| \right| = \max_{k \neq l} \left\{ \frac{1}{d_{kl}} |a(k) - a(l)| \right\}$$
 (2.63)

This can be proven with induction. Let us set $N=2, H=\mathbb{C}^2, \pi: A\to L(H)$ and a hermitian matrix D.

$$\pi(a) = \begin{pmatrix} a(1) & 0 \\ 0 & a(2) \end{pmatrix} \quad D = \begin{pmatrix} 0 & (d_{12})^{-1} \\ (d_{21})^{-1} & 0 \end{pmatrix}$$
 (2.64)

Then we compute the commutator

$$||[D, \pi(a)]|| = (d_{12})^{-1} |a(1) - a(2)|$$
 (2.65)

For the case $A=\mathbb{C}^3$, we have $H=(\mathbb{C}^2)^{\oplus 3}=H_2\oplus H_2^1\oplus H_2^2$. The representation $\pi(a)$ reads

$$\pi((a(1), a(2), a(3))) = \begin{pmatrix} a(1) & 0 \\ 0 & a(2) \end{pmatrix} \oplus \begin{pmatrix} a(1) & 0 \\ 0 & a(3) \end{pmatrix} \oplus \begin{pmatrix} a(2) & 0 \\ 0 & a(2) \end{pmatrix}$$
$$= \operatorname{diag}(a(1), a(2), a(1), a(3), a(2), a(3)) \tag{2.66}$$

And the operator D takes the form

$$D = \begin{pmatrix} 0 & x_1 \\ x_1 & 0 \end{pmatrix} \oplus \begin{pmatrix} 0 & x_2 \\ x_2 & 0 \end{pmatrix} \oplus \begin{pmatrix} 0 & x_3 \\ x_3 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & x_1 & 0 & 0 & 0 & 0 \\ x_1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & x_2 & 0 & 0 \\ 0 & 0 & x_2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & x_3 \\ 0 & 0 & 0 & 0 & x_3 & 0 \end{pmatrix}. \tag{2.67}$$

Then the norm of the commutator would be the largest eigenvalue

$$\left|\left|\left[D,\pi(a)\right]\right|\right| = \left|\left|D\pi(a) - \pi(a)D\right|\right|,\tag{2.68}$$

where the matrix in the norm from equation (2.68) is a skew symmetric matrix. Its eigenvalues are $i\lambda_1, i\lambda_2, i\lambda_3, i\lambda_4$. The λ 's are on the upper and lower diagonal. The matrix norm would be the maximum of the norm with the larges eigenvalues:

$$||[D, \pi(a)]|| = \max_{a \in A} \left\{ x_1 |a(2) - a(1)|, \\ x_2 |(a(3) - a(1))|, \\ x_3 |(a(3) - a(2))| \right\}.$$
 (2.69)

Hence the metric turns out to be

$$d = \begin{pmatrix} 0 & a(1) - a(2) & a(1) - a(3) \\ a(2) - a(1) & 0 & a(2) - a(3) \\ a(3) - a(1) & a(3) - a(2) & 0 \end{pmatrix}.$$
 (2.70)

Suppose this holds for N with π_N , $H_N = \mathbb{C}^N$ and D_N . Then it has to hold for N+1 with $H_{N+1} = H_N \oplus \bigoplus_{i=1}^N H_N^i$, since the representation reads

$$\pi_{N+1}(a(1),\ldots,a(N+1)) = \pi_N(a(1),\ldots,a(N)) \oplus \begin{pmatrix} a(1) & 0 \\ 0 & a(N+1) \end{pmatrix} \oplus \oplus \cdots \oplus \begin{pmatrix} a(N) & 0 \\ 01 & a(N+1) \end{pmatrix}.$$

$$(2.71)$$

And the operator D_{N+1} is

$$D_{N+1} = D_N \oplus \begin{pmatrix} 0 & (d_{1(N+1)})^{-1} \\ (d_{1(N+1)})^{-1} & 0 \end{pmatrix} \oplus \oplus \cdots \oplus \begin{pmatrix} 0 & (d_{N(N+1)})^{-1} \\ (d_{N(N+1)})^{-1} & 0 \end{pmatrix}.$$
 (2.72)

From this follows equation (2.63). Hence we can continue the proof by setting for fixed $i, j, a(k) = d_{ik}$, which then gives $|a(i) - a(j)| = d_{ij}$ and thereby it follows that

$$\frac{1}{d_{kl}}|a(k) - a(l)| = \frac{1}{d_{kl}}|d_{ik} - d_{il}| \le 1.$$
 (2.73)

To get a better understanding of the results of the theorem let us compute a metric on the space of three points given by $d_{ij} = \sup_{a \in A} \{|a(i) - a(j)| : ||[D, \pi(a)]|| \le 1\}$ for the set of data $A = \mathbb{C}^3$ acting in the defining representation $H = \mathbb{C}^3$, and

$$D = \begin{pmatrix} 0 & d^{-1} & 0 \\ d^{-1} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \tag{2.74}$$

for some $d \in \mathbb{R}$. From the data $A = \mathbb{C}^3$, $H = \mathbb{C}^3$ and D we compute the commutator

$$\left| \left| \left| [D, \pi(a)] \right| \right| = d^{-1} \left| \left| \begin{pmatrix} 0 & a(2) - a(1) & 0 \\ -(a(2) - a(1)) & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \right| \right|. \tag{2.75}$$

Hence the metric is

$$d = \begin{pmatrix} 0 & a(1) - a(2) & a(1) \\ a(2) - a(1) & 0 & a(2) \\ -a(1) & -a(2) & 0 \end{pmatrix}.$$
 (2.76)

The translation of the metric on X into algebraic data assumes commutativity in A, this can be extended to a noncommutative matrix algebra, by the following metric on a structure space \hat{A} of a matrix algebra $M_{n_i}(\mathbb{C})$

$$d_{ij} = \sup_{a \in A} \{ |\text{Tr}(a(i)) - \text{Tr}((a(j))| : ||[D, a]|| \le 1 \}.$$
 (2.77)

Equation (2.77) is special case of the Connes' distance formula on a structure space of A.

Finally we have all three ingredients to define a finite spectral triple, an mathematical structure which encodes finite discrete geometry into algebraic data.

Definition 11

A finite spectral triple is a tripe (A, H, D), where A is a unital *-algebra, faithfully represented on a finite-dimensional Hilbert space H, with a symmetric operator $D: H \to H$. (Note that A is automatically a matrix algebra.)

2.2.2 Properties of Matrix Algebras

Lemma 3

If A is a unital C^* algebra acting faithfully on a finite dimensional Hilbert space, then A is a matrix algebra of the Form:

$$A \simeq \bigoplus_{i=1}^{N} M_{n_i}(\mathbb{C}). \tag{2.78}$$

The wording 'acting faithfully on a Hilbertspace' means that the *-representation is injective, or for a *-homomorphism that means one-to-one correspondence

Proof. Since A acts faithfully on a Hilbert space, this means that A is a * subalgebra of a matrix algebra $L(H) = M_{\dim(H)}(\mathbb{C})$. Hence it follows, that A is isomorphic to a matrix algebra.

A simple illustration would be $A = M_n(\mathbb{C})$ for the algebra and $H = \mathbb{C}^n$ for the Hilbertspace. Since A acts on H with matrix multiplication and standard inner product and the operator D on H is a hermitian $n \times n$ matrix.

Definition 12

Given an finite spectral triple (A, H, D), the A-bimodule of Connes' differential one-forms is

$$\Omega_D^1(A) := \left\{ \sum_k a_k[D, b_k] : a_k, b_k \in A \right\}.$$
(2.79)

Additionally there is a map $d: A \to \Omega^1_D(A)$, $d = [D, \cdot]$, where d is a derivation of the *-algebra in the sense that

$$d(a b) = d(a)b + ad(b), \tag{2.80}$$

$$d(a^*) = -d(a)^*. (2.81)$$

Since we have $d(\cdot) = [D, \cdot]$, we can easily check the above equations

$$d(a b) = [D, a b] = [D, a]b + a[D, b]$$

= $d(a) b + a d(b)$. (2.82)

And

$$d(a^*) = [D, a^*] = Da^* - a^*D$$

$$= -(D^* a - a D^*) = -[D^*, a]$$

$$= -d(a)^*.$$
(2.83)

Furthermore $\Omega_D^1(A)$ is an A-bimodule, which can be seen by rewriting the defining equation (2.79) into

$$a (a_{k}[D,b_{k}]) b = a a_{k}(D b_{k} - b_{k} D) b =$$

$$= a a_{k}(D b_{k} b - b_{k} D b) =$$

$$= a a_{k}(D b_{k} b - b_{k} D b - b_{k} b D + b_{k} b D) =$$

$$= a a_{k}(D b_{k} b - b_{k} b D + b_{k} b D - b_{k} D b) =$$

$$= a a_{k}[D,b_{k} b] + a a_{k} b[D,b] =$$

$$= \sum_{k} a'_{k} [D,b'_{k}]$$
(2.84)

Lemma 4

Let $(A, H, D) = (M_n(\mathbb{C}), \mathbb{C}^n, D)$, where D is a hermitian $n \times n$ matrix. If D is not a multiple of the identity then

$$\Omega_D^1(A) \simeq M_n(\mathbb{C}) = A \tag{2.85}$$

Proof. Assume $D = \sum_i \lambda_i e_{ii}$ is diagonal, $\lambda_i \in \mathbb{R}$ and $\{e_{ij}\}$ is the basis of $M_n(\mathbb{C})$. Then for fixed i, j choose k such that $\lambda_k \neq \lambda_j$, hence we have

$$\left(\frac{1}{\lambda_k - \lambda_j} e_{ik}\right) [D, e_{kj}] = e_{ij}, \tag{2.86}$$

for $e_{ij} \in \Omega^1_D(A)$ by the above definition (2.79). Ultimately we have

$$\Omega_D^1(A) \subset L(\mathbb{C}^n) = H \simeq M_n(\mathbb{C}) = A \tag{2.87}$$

Consider an example

$$\left(A = \mathbb{C}^2, H = \mathbb{C}^2, D = \begin{pmatrix} 0 & \lambda \\ \bar{\lambda} & 0 \end{pmatrix}\right)$$
(2.88)

with $\lambda \neq 0$. We can show that $\Omega_D^1(A) \simeq M_2(\mathbb{C})$. The Hilbert Basis D can be extended in terms of the basis of $M_2(\mathbb{C})$, plugging this into equation (2.86) will get us the same cyclic result and thus $\Omega_D^1(A) \simeq M_2(\mathbb{C})$.

2.2.3 Morphisms Between Finite Spectral Triples

Next we will define an equivalence relation between finite spectral triples, called spectral unitary equivalence. This equivalence relation is given by the unitarity of the two matrix algebras themselves, and an additional map U which allows us to associate one operator to a second operator.

Definition 13

Two finite spectral tripes (A_1, H_1, D_1) and (A_2, H_2, D_2) are called unitary equiva-

lent if $A_1 = A_2$ and there exists a map $U: H_1 \to H_2$ that satisfies

$$U \pi_1(a) U^* = \pi_2(a)$$
 with $a \in A_1$, (2.89)

$$U D_1 U^* = D_2. (2.90)$$

Notice that for any such U we have the relation $(A,H,D) \sim (A,H,\ UDU^*)$. And hence

$$U D U^* = D + U[D, U^*], (2.91)$$

are of the form of elements in $\Omega_D^1(A)$.

To make it clear that the above definition is an equivalence relation between finite spectral triples, we need to see if the relation satisfies reflexivity, symmetry and transitivity. Let us look then at three spectral triples (A_1,H_1,D_1) , (A_2,H_2,D_2) and (A_3,H_3,D_3) . For reflexivity $(A_1,H_1,D_1)\sim (A_1,H_1,D_1)$. So there exists the unitary map $U:H_1\to H_1$, which is the identity and always exists. On the other hand the symmetry condition requires

$$(A_1, H_1, D_1) \sim (A_2, H_2, D_2) \Leftrightarrow (A_2, H_2, D_2) \sim (A_1, H_1, D_1).$$
 (2.92)

Because U is unitary we can rewrite for the representation for A_1

$$U\pi_{1}(a)U^{*} = \pi_{2}(a) \mid \cdot U^{*} \boxdot U$$

$$U^{*}U\pi_{1}(a)U^{*}U = \pi_{1}(a) = U^{*}\pi_{2}(a)U.$$
(2.93)

The same relation applies for the symmetric operator *D*. Lastly for transitivity the condition is

$$(A_1, H_1, D_1) \sim (A_2, H_2, D_2)$$
 and $(A_2, H_2, D_2) \sim (A_3, H_3, D_3)$
 $\Rightarrow (A_1, H_1, D_1) \sim (A_3, H_3, D_3).$ (2.94)

Therefore the two unitary maps $U_{12}: H_1 \to H_2$ and $U_{23}: H_2 \to H_3$ are

$$U_{23} U_{12} \pi_1(a) U_{12}^* U_{23}^* = U_{23} \pi_2(a) U_{23}^*$$

= $\pi_3(a)$, (2.95)

$$U_{23} U_{12} D_1 U_{12}^* U_{23}^* = U_{23} D_2 U_{23}^*$$

= D_3 . (2.96)

In order to extend the equivalence relation we take a look at Morita equivalence of Matrix Algebras.

Definition 14

Let A be an algebra. We say that $I \subset A$, as a vector space, is a right(left) ideal if $a \ b \in I$ for $a \in A$ and $b \in I$ (or $b \ a \in I$, $b \in I$, $a \in A$). We call a left-right ideal simply an ideal.

Given a Hilbert bimodule $E \in KK_f(B,A)$ and (A,H,D) we construct a finite spectral triple on B, (B,H',D')

$$H' = E \otimes_A H. \tag{2.97}$$

We might define D' with

$$D'(e \otimes \xi) = e \otimes D\xi \tag{2.98}$$

Although this would not satisfy the ideal defining the balanced tensor product over A, which is generated by elements of the form

$$e \ a \otimes \xi - e \otimes a \ \xi, \quad e \in E, a \in A, \xi \in H.$$
 (2.99)

This inherits the left action on B from E and has a \mathbb{C} valued inner product space. B also satisfies the ideal

$$D'(e \otimes \xi) = e \otimes D \xi + \nabla(e) \xi, \quad e \in E, a \in A, \tag{2.100}$$

where ∇ is called the *connection on the right A-module E* associated with the derivation $d = [D, \cdot]$. The connection needs to satisfy the *Leibniz Rule*

$$\nabla(ae) = \nabla(e)a + e \otimes [D, a], \quad e \in E, \ a \in A. \tag{2.101}$$

Hence D' is well defined on $E \otimes_A H$

$$D'(e \ a \otimes \xi - e \otimes a \ \xi) = D'(e \ a \otimes \xi) - D'(e \otimes \xi)$$

$$= e \ a \otimes D \ \xi + \nabla(a \ e) \ \xi - e \otimes D(a \ \xi) - \nabla(e) \ a \ \xi$$

$$= 0. \tag{2.102}$$

With the information thus far we can prove the following theorem

Theorem 2

If (A,H,D) is a finite spectral triple and $E \in KK_f(B,A)$, then $(V,E \otimes_A H,D')$ is a finite spectral triple, provided that ∇ satisfies the compatibility condition

$$\langle e_1, \nabla e_2 \rangle_E - \langle \nabla e_1, e_2 \rangle_E = d \langle e_1, e_2 \rangle_E \quad e_1, e_2 \in E$$
 (2.103)

Proof. The computation for $E \otimes_A H$ is above . The only thing left is to show is, that D' is a symmetric operator. We can prove this by computing for $e_1, e_2 \in E$ and $\xi_1, \xi_2 \in H$ then

$$\langle e_{1} \otimes \xi_{1}, D'(e_{2} \otimes \xi_{2}) \rangle_{E \otimes_{A} H} = \langle \xi_{1}, \langle e_{1}, \nabla e_{2} \rangle_{E} \ \xi_{2} \rangle \langle \xi_{1}, \langle e_{1}, e_{2} \rangle_{E} \ D \ \xi_{2} \rangle_{H}$$

$$= \langle \xi_{1}, \langle \nabla e_{1}, e_{2} \rangle_{E} \ \xi_{2} \rangle_{H} + \langle \xi_{1}, d \langle e_{1}, e_{2} \rangle_{E} \ \xi_{2} \rangle_{H}$$

$$+ \langle D \ \xi_{1}, \langle e_{1}, e_{2} \rangle_{E} \ \xi_{2} \rangle_{H} - \langle \xi_{1}, [D, \langle e_{1}, e_{2} \rangle_{E}] \ \xi_{2} \rangle_{H}$$

$$= \langle D'(e_{1} \otimes \xi_{1}), e_{2} \otimes \xi_{2} \rangle_{E \otimes_{A} H}$$

$$(2.104)$$

Let us examine the scenario where we consider the difference of connections ∇ and ∇' on a right A-module E. Since both connections need to satisfy the Leibniz rule, the difference also should

$$\nabla(ea) - \nabla'(ea) = \nabla(e) + e \otimes [D, a]$$

$$- (\nabla'(e)a + e \otimes [D', a])$$

$$= \bar{\nabla}a + e \otimes (Da - aD - D'a + aD')$$

$$= \bar{\nabla}a + e \otimes ((D - D')a - a(D - D'))$$

$$= \bar{\nabla}a + e \otimes [D', a]$$

$$= \bar{\nabla}(ea). \tag{2.105}$$

Therefore $\nabla - \nabla'$ is a right *A*-linear map $E \to E \otimes_A \Omega^1_D(A)$.

To get a better grasp of the results let us construct a finite spectral triple (A, H', D') from (A, H, D). The derivation $d(\cdot): A \to A \otimes_A \Omega^1_D(A) = \Omega^1_D(A)$ is a connection on A, i.e. considered a right A-module

$$\nabla(e \cdot a) = d(a), \tag{2.106}$$

hence $A \otimes_A H \simeq H$. Next we can construct the operator D' for the connection $d(\cdot)$

$$D'(a\xi) = a(D\xi) + (\nabla a)\xi = D(a\xi). \tag{2.107}$$

By using the identity element in the connection relation we conclude

$$\nabla(e \cdot a) = \nabla(e)a + 1 \otimes d(a) = d(a)\nabla(e)a, \tag{2.108}$$

thus any connection $\nabla: A \to A \otimes_A \Omega^1_D(A)$ is given by

$$\nabla = d + \omega, \tag{2.109}$$

where $\omega \in \Omega^1_D(A)$. This becomes clear when looking at the difference operator D' with the connection on A, which is given by

$$D'(a \otimes \xi) = D'(a\xi) = a(D\xi) + (\nabla a)\xi$$

= $a(D\xi) + \nabla(e \cdot a)\xi$
= $D(a\xi) + \nabla(e)(a\xi)$, (2.110)

hence any such connection is of the form as in equation (2.109)

2.3 Finite Real Noncommutative Spaces

2.3.1 Finite Real Spectral Triples

In this chapter we supplement the finite spectral triples with a *real structure*. We additionally require a symmetry condition that that H is an A-A-bimodule rather than only a A-left module. This ansatz has tight bounds with physical properties such as charge conjugation, into which we will dive in deeper in later chapters. In regards to this we will need to set a basis of definitions to get an overview. First we introduce a \mathbb{Z}_2 -grading γ with the following properties

$$\gamma^* = \gamma, \tag{2.111}$$

$$\gamma^2 = 1, \tag{2.112}$$

$$\gamma D = -D\gamma, \tag{2.113}$$

$$\gamma a = a\gamma, \quad a \in A. \tag{2.114}$$

Then we can define a finite real spectral triple.

Definition 15

A finite real spectral triple is given by a finite spectral triple (A, H, D) and a antiunitary operator $J: H \to H$ called the real structure, such that

$$a^{\circ} := J \ a^* \ J^{-1}, \tag{2.115}$$

is a right representation of A on H, that is $(ab)^{\circ} = b^{\circ}a^{\circ}$. With two requirements

$$[a,b^{\circ}] = 0,$$
 (2.116)

$$[[D,a], b^{\circ}] = 0.$$
 (2.117)

The two properties are called the *commutant property*, they require that the left action of an element in A and $\Omega_D^1(A)$ commutes with the right action on A.

Definition 16

The KO-dimension of a real spectral triple is determined by the sings $\varepsilon, \varepsilon', \varepsilon'' \in \{-1, 1\}$ appearing in

$$J^2 = \varepsilon, \tag{2.118}$$

$$JD = \varepsilon DJ, \tag{2.119}$$

$$J \gamma = \varepsilon'' \gamma J. \tag{2.120}$$

Table 1: *KO*-dimension *k* modulo 8 of a real spectral triple

\overline{k}	0	1	2	3	4	5	6	7
$\overline{\epsilon}$	1	1	-1	-1	-1	-1	1	1
$oldsymbol{arepsilon'}$	1	-1	1	1	1	-1	1	1
$oldsymbol{arepsilon''}$	1		-1	-1 1	1		-1	

Even thought the KO-dimension of a real spectral triple is important, we will not be doing in-depth introduction of the KO-dimension, for this we reference again to [1].

Definition 17

An opposite-algebra A° of a A is defined to be equal to A as a vector space with the opposite product

$$a \circ b := ba \tag{2.121}$$

$$\Rightarrow a^{\circ} = Ja^*J^{-1},\tag{2.122}$$

which defines the left representation of A° on H

Definition 18

We call $\xi \in H$ cyclic vector in A if:

$$A\xi := a\xi : a \in A = H \tag{2.123}$$

We call $\xi \in H$ separating vector in A if:

$$a\xi = 0 \Rightarrow a = 0; \quad a \in A \tag{2.124}$$

Suppose (A, H, D = 0) is a finite spectral triple such that H possesses a cyclic and separating vector for A and let

$$J: H \to H \tag{2.125}$$

be the operator in $S = J\Delta^{1/2}$ with $\Delta = S^*S$. By composition $S(a\xi) = a * \xi$ this is literally anti-linearity, then $S(a\xi) = a * \xi$ defines a anti-linear operator. Furthermore the operator S is invertible because, if a $\xi \in H$ is cyclic then we have

$$S(A\xi) = A^*\xi = A\xi = H.$$
 (2.126)

Vice versa the same has to work for S^{-1} , otherwise ξ wouldn't exist, hence

$$S^{-1}(A^*\xi) = S^{-1}(H) = H. \tag{2.127}$$

Additionally J is anti-unitary because firstly, S is bijective thus $\Delta^{1/2}$ and J need to be bijective. Also have $J = S\Delta^{-1/2}$ and $\Delta^* = \Delta$, so for a $\xi_1, \xi_2 \in H$ we can write

$$\langle J\xi_{1}, J\xi_{2} \rangle = \langle J^{*}J\xi_{1}, \xi_{2} \rangle^{*} =$$

$$= \langle (\Delta^{-1/2})^{*}S^{*}S\Delta^{-1/2}\xi_{1}, \xi_{2} \rangle^{*} =$$

$$= \langle (\Delta^{-1/2})^{*}\Delta\Delta^{-1/2}\xi_{1}, \xi_{2} \rangle^{*} =$$

$$= \langle \Delta^{-1/2}\Delta^{1/2}\Delta^{1/2}\Delta^{-1/2}\xi_{1}, \xi_{2} \rangle^{*} =$$

$$= \langle \xi_{1}, \xi_{2} \rangle^{*} = \langle \xi_{2}, \xi_{1} \rangle, \qquad (2.128)$$

which concludes the anti-unitarity by definition.

2.3.2 Morphisms Between Finite Real Spectral Triples

Like the unitary equivalence relation for finite spectral triples, we can it extend it to finite real spectral triples.

Definition 19

We call two finite real spectral triples $(A_1, H_1, D_1; J_1, \gamma_1)$ and $(A_2, H_2, D_2; J_2, \gamma_2)$ unitarily equivalent if $A_1 = A_2$ and if there exists a unitary operator $U: H_1 \to H_2$ such that

$$U \pi_1(a) U^* = \pi_2(a), \tag{2.129}$$

$$U D_1 U^* = D_2, (2.130)$$

$$U\gamma_1 U^* = \gamma_2, \tag{2.131}$$

$$U J_1 U^* = J_2. (2.132)$$

Definition 20

Let E be a B-A bimodule. The conjugate Module E° is given by the A-B-bimodule.

$$E^{\circ} = \{ \bar{e} : e \in E \}, \tag{2.133}$$

with

$$a \cdot \bar{e} \cdot b = b^* \ \bar{e} \ a^*, \quad \forall a \in A, b \in B.$$
 (2.134)

We bear in mind that E° is not a Hilbert bimodule for (A,B) because it doesn't have a natural B-valued inner product. But there is a A-valued inner product on the left A-module E° with

$$\langle \bar{e}_1, \bar{e}_2 \rangle = \langle e_2, e_1 \rangle, \quad e_1, e_2 \in E. \tag{2.135}$$

And linearity in *A* by the terms

$$\langle a \,\bar{e}_1, \bar{e}_2 \rangle = a \langle \bar{e}_1, \bar{e}_2 \rangle, \quad \forall a \in A.$$
 (2.136)

It turns out that E° is a Hilbert bimodule of (B°, A°) . A straightforward calculation of the properties of the Hilbert bimodule and its B° valued inner product gives the results. For $\bar{e}_1, \bar{e}_2 \in E^{\circ}$ and $a^{\circ} \in A, b^{\circ} \in B$ we write

$$\langle \bar{e}_{1}, a^{\circ} \bar{e}_{2} \rangle = \langle \bar{e}_{1}, Ja^{*} J^{-1} \bar{e}_{2} \rangle =$$

$$= \langle \bar{e}_{1}, Ja^{*} e_{2} \rangle$$

$$= \langle J^{-1} e_{1}, a^{*} e_{2} \rangle$$

$$= \langle a^{*} e_{1}, e_{2} \rangle = \langle J^{-1} (a^{\circ})^{*} J e_{1}, e_{2} \rangle$$

$$= \langle J^{-1} (a^{\circ})^{*} \bar{e}_{1}, e_{2} \rangle$$

$$= \langle (a^{\circ})^{*} \bar{e}_{1}, \bar{e}_{2} \rangle. \tag{2.137}$$

Next for $\langle \bar{e}_1, \bar{e}_2 b^{\circ} \rangle = \langle \bar{e}_1, \bar{e}_2 \rangle b^{\circ}$ we obtain

$$\langle \bar{e}_1, \bar{e}_2 b^{\circ} \rangle = \langle \bar{e}_1, \bar{e}_2 J b^* J^{-1} \rangle$$

$$= \langle \bar{e}_1, \bar{e}_2 \rangle J b^* J^{-1}$$

$$= \langle \bar{e}_1, \bar{e}_2 \rangle b^{\circ}. \tag{2.138}$$

Additionally we get

$$(\langle \bar{e}_1, \bar{e}_2 \rangle)_{E^{\circ}})^* = (\langle e_2, e_1 \rangle_E)^*$$

$$= \langle e_1, e_2 \rangle_E^*$$

$$= \langle \bar{e}_2, \bar{e}_2 \rangle_{E^{\circ}}.$$
(2.139)

And finally we have

$$\langle \bar{e}, \bar{e} \rangle = \langle e, e \rangle \ge 0$$
 (2.140)

Given the results thus far, given a Hilbert bimodule E for (B,A) one can construct a spectral triple $(B,H',D';J',\gamma')$ from $(A,H,D;J,\gamma)$. For H' we make a \mathbb{C} -valued inner product on H' by combining the A valued inner product on E and E° with the \mathbb{C} -valued inner product on H by defining

$$H' := E \otimes_A H \otimes_A E^{\circ}. \tag{2.141}$$

Then the action of B on H' takes the following form

$$b(e_2 \otimes \xi \otimes \bar{e}_2) = (be_1) \otimes \xi \otimes \bar{e}_2. \tag{2.142}$$

The right action of B on H' defined by action on the right components of E° is

$$J'(e_1 \otimes \xi \otimes \bar{e}_2) = e_2 \otimes J\xi \otimes \bar{e}_1, \tag{2.143}$$

where $b^{\circ} = J'b^*(J')^{-1}$ and $b^* \in B$ is the action on H'. Hence the connection reads

$$\nabla: E \to E \otimes_A \Omega_D^1(A) \tag{2.144}$$

$$\bar{\nabla}: E^{\circ} \to \Omega_D^1(A) \otimes_A E^{\circ},$$
 (2.145)

which gives the Dirac operator on $H' = E \otimes_A H \otimes_A E^{\circ}$ as

$$D'(e_1 \otimes \xi \otimes \bar{e}_2) = (\nabla e_1)\xi \otimes \bar{e}_2 + e_1 \otimes D\xi \otimes \bar{e}_2 + e_1 \otimes \xi(\bar{\nabla}\bar{e}_2). \tag{2.146}$$

And the right action of $\omega \in \Omega^1_D(A)$ on $\xi \in H$ is defined by

$$\xi \mapsto \varepsilon' J \omega^* J^{-1} \xi. \tag{2.147}$$

Finally for the grading one obtains

$$\gamma' = 1 \otimes \gamma \otimes 1. \tag{2.148}$$

Summarizing we can write down the following theorem

Theorem 3

Suppose $(A, H, D; J, \gamma)$ is a finite spectral triple of KO-dimension k, let ∇ be a connection satisfying the compatibility condition (same as with finite spectral triples). Then $(B, H', D'; J', \gamma')$ is a finite spectral triple of KO-Dimension k. (H', D', J', γ')

Proof. The only thing left is to check is, if the KO-dimension is preserved. That is one needs to check if if the ε 's are the same.

$$(J')^2 = 1 \otimes J^2 \otimes 1 = \varepsilon, \tag{2.149}$$

$$J'\gamma' = \varepsilon''\gamma'J'. \tag{2.150}$$

Lastly for ε' one obtains

$$J'D'(e_1 \otimes \xi \otimes \bar{e}_2) = J'((\nabla e_1)\xi \otimes \bar{e}_2 + e_1 \otimes D\xi \otimes \bar{e}_2 + e_1 \otimes \xi(\tau \nabla e_2))$$

$$= \varepsilon'D'(e_2 \otimes J\xi \otimes \bar{e}_2)$$

$$= \varepsilon'D'J'(e_1 \otimes \xi \bar{e}_2)$$
(2.151)

Let us take a look at $\nabla: E \Rightarrow E \otimes_A \Omega^1_d(A)$, the right connection on E and consider the following anti-linear map

$$\tau: E \otimes_A \Omega_D^1(A) \to \Omega_D^1(A) \otimes_A E^{\circ}$$
 (2.152)

$$e \otimes \omega \mapsto -\omega^* \otimes \bar{e}.$$
 (2.153)

Interestingly the map $\bar{\nabla}: E^{\circ} \to \Omega_D^1(A) \otimes E^{\circ}$ with $\bar{\nabla}(\bar{e}) = \tau \circ \nabla(e)$ is a left connection, that means show that it satisfied the left Leibniz rule, for one

$$\tau \circ \nabla(ae) = \bar{\nabla}(a\bar{e}) = \bar{\nabla}(a^*\bar{e}). \tag{2.154}$$

And for two

$$\tau \circ \nabla(ae) = \tau(\nabla(e)a) + \tau \circ (e \otimes d(a))$$

$$= a^* \bar{\nabla}(\bar{e}) - d(a)^* \otimes \bar{e}.$$

$$= a^* \bar{\nabla}(\bar{e}) + d(a^*) \otimes \bar{e}.$$
(2.155)

2.4 Heat Kernel Expansion

2.4.1 The Heat Kernel

The heat kernel K(t; x, y; D) is the fundamental solution to the heat equation

$$(\partial_t + D_x)K(t; x, y; D) = 0,$$
 (2.156)

which depends on the operator D of Laplacian type.

For a flat manifold $M = \mathbb{R}^n$ and $D = D_0 := -\Delta_\mu \Delta^\mu + m^2$ the Laplacian with a mass term and the initial condition

$$K(0; x, y; D) = \delta(x, y),$$
 (2.157)

takes the form of the standard fundamental solution

$$K(t;x,y;D_0) = (4\pi t)^{-n/2} \exp\left(-\frac{(x-y)^2}{4t} - tm^2\right). \tag{2.158}$$

Let us consider now a more general operator *D* with a potential term or a gauge field, the heat kernel then reads

$$K(t;x,y;D) = \langle x|e^{-tD}|y\rangle. \tag{2.159}$$

We can expand the heat kernel in t, still having a singularity from the equation (2.158) as $t \to 0$, on obtains

$$K(t;x,y;D) = K(t;x,y;D_0) \left(1 + tb_2(x,y) + t^2b_4(x,y) + \dots\right), \tag{2.160}$$

where $b_k(x,y)$ become regular as $y \to x$. These coefficients are called the heat kernel coefficients.

2.4.2 Spectral Functions

Manifolds M with a disappearing boundary condition for the operator e^{-tD} for t > 0, i.e. a trace class operator on $L^2(V)$. Meaning for any smooth function f on M the Heat kernel can be defined as

$$K(t, f, D) := \operatorname{Tr}_{L^2}(fe^{-tD}).$$
 (2.161)

Alternately an integral representation is

$$K(t, f, D) = \int_{M} d^{n}x \sqrt{g} \operatorname{Tr}_{V}(K(t; x, x; D) f(x)), \qquad (2.162)$$

in the regular limit $y \to y$. The Heat Kernel can be written in terms of the spectrum of D. Hence for an orthonormal basis $\{\phi_{\lambda}\}$ of eigenfunctions for D, which correspond to the eigenvalue λ one can rewrite the heat kernel into

$$K(t;x,y;D) = \sum_{\lambda} \phi_{\lambda}^{\dagger}(x)\phi_{\lambda}(y)e^{-t\lambda}.$$
 (2.163)

An asymptotic expansion as $t \to 0$ for the trace is then

$$\operatorname{Tr}_{L^2}(fe^{-tD}) \simeq \sum_{k \ge 0} t^{(k-n)/2} a_k(f, D),$$
 (2.164)

where

$$a_k(f,D) = (4\pi)^{-n/2} \int_M d^4x \sqrt{g} b_k(x,x) f(x).$$
 (2.165)

2.4.3 General Formulae

Let us summarize what we have obtained in the last chapter. We considered a compact Riemannian manifold M without boundary condition, a vector bundle V over M to define functions which carry discrete (spin or gauge) indices, an operator D of Laplace type over V and smooth function f on M.

There is an asymptotic expansion where the heat kernel coefficients with an odd index k = 2j + 1 vanish $a_{2j+1}(f,D) = 0$. On the other hand coefficients with an even index are locally computable in terms of geometric invariants

$$a_k(f,D) = \operatorname{Tr}_V\left(\int_M d^n x \sqrt{g}(f(x)a_k(x;D))\right) =$$

$$= \sum_I \operatorname{Tr}_V\left(\int_M d^n x \sqrt{g}(fu^I \mathscr{A}_k^I(D))\right). \tag{2.166}$$

The notation \mathscr{A}_k^I corresponds to all possible independent invariants of dimension k and u^I are constants. The invariants are constructed from $E, \Omega, R_{\mu\nu\rho\sigma}$ and their derivatives. If E has dimension two, then the derivative has dimension one. In this way if k=2 there are only two independent invariants, E and E. This corresponds to the statement $a_{2i+1}=0$.

If we consider $M = M_1 \times M_2$ with coordinates x_1 and x_2 and a decomposed Laplace style operator $D = D_1 \otimes 1 + 1 \otimes D_2$ the functions acting on operators and on coordinates are separable linearly by the following

$$e^{-tD} = e^{-tD_1} \otimes e^{-tD_2}, \tag{2.167}$$

$$f(x_1, x_2) = f_1(x_1) f_2(x_2),$$
 (2.168)

thus the heat kernel coefficients are separated by

$$a_k(x;D) = \sum_{p+q=k} a_p(x_1;D_1)a_q(x_2;D_2). \tag{2.169}$$

Lets say the eigenvalues of D_1 are $l^2, l \in \mathbb{Z}$, we can obtain the heat kernel asymmetries with the Poisson summation formula giving us an approximation in the order of $e^{-1/t}$

$$K(t, D_1) = \sum_{l \in \mathbb{Z}} e^{-tl^2} = \sqrt{\frac{\pi}{t}} \sum_{l \in \mathbb{Z}} e^{-\frac{\pi^2 l^2}{t}} =$$

$$\simeq \sqrt{\frac{\pi}{t}} + \mathscr{O}(e^{-1/t}). \tag{2.170}$$

The exponentially small terms have no effect on the heat kernel coefficients and the only nonzero coefficient is $a_0(1,D_1) = \sqrt{\pi}$, therefore the heat coefficients can be written as

$$a_k(f(x^2), D) = \sqrt{\pi} \int_{M_2} d^{n-1} x \sqrt{g} \sum_{I} \text{Tr}_V \left(f(x^2) u_{(n-1)}^I \mathscr{A}_n^I(D_2) \right). \tag{2.171}$$

Since all of the geometric invariants associated with D are in the D_2 part, they are independent of x_1 . This allows us to to choose for M_1 .

For $M_1=S^1$ with $x\in(0,2\pi)$ and $D_1=-\partial_{x_1}^2$ we can rewrite the heat kernel coefficients into

$$a_{k}(f(x_{2}),D) = \int_{S^{1}\times M_{2}} d^{n}x \sqrt{g} \sum_{I} \operatorname{Tr}_{V}(f(x_{2})u_{(n)}^{I}\mathscr{A}_{k}^{I}(D_{2})) =$$

$$= 2\pi \int_{M_{2}} d^{n}x \sqrt{g} \sum_{I} \operatorname{Tr}_{V}(f(x_{2})u_{(n)}^{I}\mathscr{A}_{k}^{I}(D_{2})). \tag{2.172}$$

Computing the two equations above we see that

$$u_{(n)}^{I} = \sqrt{4\pi}u_{(n+1)}^{I}. (2.173)$$

2.4.4 Heat Kernel Coefficients

To calculate the heat kernel coefficients consider the following variational equations

$$\frac{d}{d\varepsilon}\Big|_{\varepsilon=0} a_k(1, e^{-2\varepsilon f}D) = (n-k)a_k(f, D), \tag{2.174}$$

$$\frac{d}{d\varepsilon}\Big|_{\varepsilon=0} a_k(1, D - \varepsilon F) = a_{k-2}(F, D), \tag{2.175}$$

$$\frac{d}{d\varepsilon}\Big|_{\varepsilon=0} a_k(e^{-2\varepsilon f}F, e^{-2\varepsilon f}D) = 0. \tag{2.176}$$

Let us explain the equations above. To get the first equation (2.174) we simply differentiate

$$\frac{d}{d\varepsilon}\Big|_{\varepsilon=0} \operatorname{Tr}(\exp(-e^{-2\varepsilon f}tD) = \operatorname{Tr}(2ftDe^{-tD}) = -2t\frac{d}{dt}\operatorname{Tr}(fe^{-tD})), \tag{2.177}$$

additionally expand both sides in t and get equation (2.174). Equation (2.175) is derived similarly.

For equation (2.176) look at the following operator

$$D(\varepsilon, \delta) = e^{-2\varepsilon f} (D - \delta F), \tag{2.178}$$

for k = n we take equation (2.174) and we obtain

$$\frac{d}{d\varepsilon}\Big|_{\varepsilon=0} a_n(1, D(\varepsilon, \delta)) = 0. \tag{2.179}$$

Then we take the variation in terms of δ , evaluated at $\delta = 0$ and swap the differentiation, allowed by theorem of Schwarz

$$0 = \frac{d}{d\delta} \left| \frac{d}{\delta = 0} \frac{d}{d\varepsilon} \right|_{\varepsilon = 0} a_n(1, D(\varepsilon, \delta)) =$$

$$= \frac{d}{d\varepsilon} \left| \frac{d}{\delta = 0} \frac{d}{\delta = 0} \right|_{\delta = 0} a_n(1, D(\varepsilon, \delta)) =$$

$$= a_{n-2}(e^{-2\varepsilon f}F, e^{-2\varepsilon f}D), \qquad (2.180)$$

which gives us equation (2.176).

Now that the ground basis is established, we can calculate the constants u^{I} , and by that the first three heat kernel coefficients read

$$a_0(f,D) = (4\pi)^{-n/2} \int_M d^n x \sqrt{g} \text{Tr}_V(a_0 f), \qquad (2.181)$$

$$a_2(f,D) = (4\pi)^{-n/2} \frac{1}{6} \int_M d^n x \sqrt{g} \text{Tr}_V)(f\alpha_1 E + \alpha_2 R), \tag{2.182}$$

$$a_4(f,D) = (4\pi)^{-n/2} \frac{1}{360} \int_M d^n x \sqrt{g} \text{Tr}_V (f(\alpha_3 E_{,kk} + \alpha_4 R E + \alpha_5 E^2 \alpha_6 R_{,kk} + \alpha_7 R^2 + \alpha_8 R_{ij} R_{ij} + \alpha_9 R_{ijkl} R_{ijkl} + \alpha_{10} \Omega_{ij} \Omega_{ij})),$$
(2.183)

where the comma subscript, denotes the derivative and constants α_I do not depend on the dimension of the Manifold and we can compute them with our variational identities.

The first coefficient α_0 can be read from the heat kernel expansion of the Laplacian on S^1 (above), $\alpha_0 = 1$. For α_1 we use (2.175), the coefficient k = 2 is

$$\frac{1}{6} \int_{M} d^{n}x \sqrt{g} \operatorname{Tr}_{V}(\alpha_{1}F) = \int_{M} d^{n}x \sqrt{g} \operatorname{Tr}_{V}(F), \qquad (2.184)$$

which means $\alpha_1 = 6$. Looking at the coefficient k = 4 we have

$$\frac{1}{360} \int_{M} d^{n}x \sqrt{g} \operatorname{Tr}_{V}(\alpha_{4} F R + 2\alpha_{5} F E) = \frac{1}{6} \int_{M} d^{n}x \sqrt{g} \operatorname{Tr}_{V}(\alpha_{1} F E + \alpha_{2} F R), \quad (2.185)$$

thus $\alpha_4 = 60\alpha_2$ and $\alpha_5 = 180$.

By applying (2.176) to n = 4 we get

$$\frac{d}{d\varepsilon}|_{\varepsilon=0}a_2(e^{-2\varepsilon f}F, e^{-2\varepsilon f}D) = 0. \tag{2.186}$$

Collecting the terms with $\text{Tr}_V(\int_M d^n x \sqrt{g}(Ff_{,jj}))$ we obtain $\alpha_1 = 6\alpha_2$, that is $\alpha_2 = 1$, so $\alpha_4 = 60$.

Now we let $M = M_1 \times M_2$ and split $D = -\Delta_1 - \Delta_2$, where $\Delta_{1/2}$ are Laplacians for M_1, M_2 . This allows us to decompose the heat kernel coefficient for k = 4 into

$$a_4(1, -\Delta_1 - \Delta_2) = a_4(1, -\Delta_1)a_0(1, -\Delta_2) + a_2(1, -\Delta_1)a_2(1, -\Delta_2) + a_0(1, -\Delta_1)a_4(1, -\Delta_2),$$

$$(2.187)$$

with E=0 and $\Omega=0$ and by calculating the terms with R_1R_2 (scalar curvature of $M_{1/2}$) we obtain $\frac{2}{360}\alpha_7=(\frac{\alpha_2}{6})^2$, thus $\alpha_7=5$.

For n = 6 we get

$$0 = \text{Tr}_{V} \left(\int_{M} d^{n}x \sqrt{g} (F(-2\alpha_{3} - 10\alpha_{4} + 4\alpha_{5}) f_{,kk} E + \right. \\ + \left. (2\alpha_{3} + 10\alpha_{6}) f_{,iijj} + \right. \\ + \left. (2\alpha_{4} - 2\alpha_{6} - 20\alpha_{7} - 2\alpha_{8}) f_{,ii} R + \left. (-8\alpha_{8} - 8\alpha_{6}) f_{,ij} R_{ij} \right) \right)$$

$$(2.188)$$

we obtain $\alpha_3 = 60$, $\alpha_6 = 12$, $\alpha_8 = -2$ and $\alpha_9 = 2$

To get α_{10} we use the Gauss-Bonnet theorem, ultimately giving us $\alpha_{10} = 30$. We leave out this lengthy calculation and refer to [2] for further reading.

Let us summarize our calculations which ultimately lead us to the following heat kernel coefficients

$$\alpha_0(f,D) = (4\pi)^{-n/2} \int_M d^n x \sqrt{g} \text{Tr}_V(f),$$
(2.189)

$$\alpha_2(f,D) = (4\pi)^{-n/2} \frac{1}{6} \int_M d^n x \sqrt{g} \text{Tr}_V(f(6E+R)), \qquad (2.190)$$

$$\alpha_4(f,D) = (4\pi)^{-n/2} \frac{1}{360} \int_M d^n x \sqrt{g} \text{Tr}_V(f(60E_{,kk} + 60RE + 180E^2 + (2.191)))$$

$$+12R_{,kk}+5R^{2}-2R_{ij}R_{ij}2R_{ijkl}R_{ijkl}+30\Omega_{ij}\Omega_{ij})). (2.192)$$

2.5 Almost-commutative Manifold

2.5.1 Two-Point Space

One of the basics forms of noncommutative space is the Two-Point space $X := \{x, y\}$. The Two-Point space can be represented by the following spectral triple

$$F_X := (C(X) = \mathbb{C}^2, H_F, D_F; J_F, \gamma_f).$$
 (2.193)

Three properties of F_X stand out. First of all the action of C(X) on H_F is faithful for $dim(H_F) \ge 2$, thus a simple choice for the Hilbertspace can be made, for instance $H_F = \mathbb{C}^2$. Furthermore γ_F is the \mathbb{Z}_2 grading, which allows for a decomposition of H_F into

$$H_F = H_F^+ \otimes H_F^- = \mathbb{C} \otimes \mathbb{C}, \tag{2.194}$$

where

$$H_F^{\pm} = \{ \psi \in H_F | \gamma_F \psi = \pm \psi \},$$
 (2.195)

are two eigenspaces. And lastly the Dirac operator D_F lets us interchange between the two eigenspaces H_F^{\pm} ,

$$D_F = \begin{pmatrix} 0 & t \\ \bar{t} & 0 \end{pmatrix}, \quad \text{with } t \in \mathbb{C}.$$
 (2.196)

The Two-Point space F_X can only have a real structure if the Dirac operator vanishes, i.e. $D_F = 0$. In that case the KO-dimension is 0, 2 or 6. To elaborate further, we draw the only two diagram representations of F_X at $\mathbb{C} \oplus \mathbb{C}$ on $\mathbb{C} \oplus \mathbb{C}$, which are



Figure 1: Two diagram representations of F_X

If the Two-Point space F_X would be a real spectral triple then D_F can only go vertically or horizontally. This would mean that D_F vanishes. As for the KO-dimension The diagram on the left has KO-dimension 2 and 6, the diagram on the right 0 and 4. Yet KO-dimension 4 is ruled out because $dim(H_F^{\pm}) = 1$ (Lemma 3.8 in [1]), which ultimately means $J_F^2 = -1$ is not allowed.

Product Space 2.5.2

By Extending the Two-Point space with a four dimensional Riemannian spin manifold, we get an almost commutative manifold $M \times F_X$, given by

$$M \times F_X = \left(C^{\infty}(M, \mathbb{C}^2), L^2(S) \otimes \mathbb{C}^2, D_M \otimes 1; J_M \otimes J_F, \gamma_M \otimes \gamma_F \right), \tag{2.197}$$

where

$$C^{\infty}(M, \mathbb{C}^2) \simeq C^{\infty}(M) \oplus C^{\infty}(M).$$
 (2.198)

According to Gelfand duality the algebra $C^{\infty}(M,\mathbb{C}^2)$ of the spectral triple corresponds to the space

$$N := M \otimes X. \tag{2.199}$$

Keep in mind that we still need to find an appropriate real structure on the Riemannian spin manifold, J_M . Furthermore the total Hilbertspace can be decomposed into H = $L^2(S) \oplus L^2(S)$, such that for $\underline{a,b \in C^{\infty}(M)}$ and $\underline{\psi,\phi \in L^2(S)}$ we have

$$(a,b)\in C^{\infty}(N) \qquad \qquad (\psi,\phi)\in H$$

$$(a,b)(\psi,\phi) = (a\psi,b\phi). \tag{2.200}$$

Along with the decomposition of the total Hilbertspace a distance formula on $M \times F_X$ can be considered with

$$d_{D_F}(x,y) = \sup\{|a(x) - a(y)| : a \in A_F, ||[D_F, a]|| \le 1\}.$$
 (2.201)

To calculate the distance between two points on the Two-Point space $X = \{x, y\}$, between x and y, we consider an $a \in \mathbb{C}^2 = C(X)$, which is specified by two complex numbers a(x) and a(y). Then we simplify the commutator inequality in (2.201)

$$||[D_F, a]|| = ||(a(y) - a(x)) \begin{pmatrix} 0 & t \\ \bar{t} & 0 \end{pmatrix}|| \le 1,$$
 (2.202)

$$\Leftrightarrow |a(y) - a(x)| \le \frac{1}{|t|}.\tag{2.203}$$

The supremum then gives us the distance

$$d_{D_F}(x,y) = \frac{1}{|t|}. (2.204)$$

An interesting observation here is that, if the Riemannian spin manifold can be represented by a real spectral triple then a real structure J_M exists, along the lines it follows that t = 0 and the distance becomes infinite. This is a purely mathematical observation and has no physical meaning.

We can also construct a distance formula on N (in reference to a point $p \in M$) between two points on $N = M \times X$, (p,x) and (p,y). Then an $a \in C^{\infty}(N)$ is determined by $a_x(p) := a(p,x)$ and $a_y(p) := a(p,y)$. The distance between these two points is

$$d_{D_F \otimes 1}(n_1, n_2) = \sup \{ |a(n_1) - a(n_2)| : a \in A, ||[D \otimes 1, a]|| \}.$$
 (2.205)

On the other hand if we consider $n_1 = (p, x)$ and $n_2 = (q, x)$ for $p, q \in M$ then

$$d_{D_M \otimes 1}(n_1, n_2) = |a_x(p) - a_x(q)|$$
 for $a_x \in C^{\infty}(M)$ with $||[D \otimes 1, a_x]|| \le 1$ (2.206)

The distance formula turns to out to be the geodesic distance formula

$$d_{D_M \otimes 1}(n_1, n_2) = d_g(p, q), \tag{2.207}$$

which is to be expected since we are only looking at the manifold. However if $n_1 = (p, x)$ and $n_2 = (q, y)$ then the two conditions are

$$||[D_M, a_x]|| \le 1$$
, and (2.208)

$$||[D_M, a_y|| \le 1. (2.209)$$

These conditions have no restriction which results in the distance being infinite! And $N = M \times X$ is given by two disjoint copies of M which are separated by infinite distance. The distance is only finite if $[D_F, a] < 1$. In this case the commutator generates a scalar field and the finiteness of the distance is related to the existence of scalar fields.

2.5.3 U(1) Gauge Group

To get a insight into the physical properties of the almost commutative manifold $M \times F_X$, that is to calculate the spectral action, we need to determine the corresponding Gauge group. For this we set of with simple definitions and important propositions to help us break down and search for the gauge group of the Two-Point F_X space which we then extend to $M \times F_X$. We will only be diving superficially into this chapter, for further reading we refer to [1].

Definition 21

Gauge Group of a real spectral triple is given by

$$\mathfrak{B}(A,H;J) := \{ U = uJuJ^{-1} | u \in U(A) \}. \tag{2.210}$$

Definition 22

A *-automorphism of a *-algebra A is a linear invertible map

$$\alpha: A \to A$$
, with (2.211)

$$\alpha(ab) = \alpha(a)\alpha(b), \tag{2.212}$$

$$\alpha(a)^* = \alpha(a^*). \tag{2.213}$$

The **Group of automorphisms of the *-Algebra** A is denoted by (A).

The automorphism α is called **inner** if

$$\alpha(a) = uau^* \quad \text{for } U(A), \tag{2.214}$$

where U(A) is

$$U(A) = \{ u \in A | uu^* = u^*u = 1 \}.$$
 (unitary) (2.215)

The Gauge group of F_X is given by the quotient $U(A)/U(A_J)$. To get a nontrivial Gauge group so we need to choose a $U(A_J) \neq U(A)$ and $U((A_F)_{J_F}) \neq U(A_F)$. We consider our Two-Point space F_X to be equipped with a real structure, which means the operator vanishes, and the spectral triple representation is

$$F_X := \begin{pmatrix} \mathbb{C}^2, \mathbb{C}^2, D_F = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}; J_f = \begin{pmatrix} 0 & C \\ C & 0 \end{pmatrix}, \gamma_F = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \right). \tag{2.216}$$

Here C is the complex conjugation, and F_X is a real even finite spectral triple (space) of KO-dimension 6.

Proposition 1

The Gauge group of the Two-Point space $\mathfrak{B}(F_X)$ is U(1).

Proof. Note that $U(A_F) = U(1) \times U(1)$. We need to show that $U(A_F) \cap U(A_F)_{J_F} \simeq U(1)$, such that $\mathfrak{B}(F) \simeq U(1)$. So for an element $a \in \mathbb{C}^2$ to be in $(A_F)_{J_F}$, it has to satisfy $J_F a^* J_F = a$,

$$J_F a^* J^{-1} = \begin{pmatrix} 0 & C \\ C & 0 \end{pmatrix} \begin{pmatrix} \bar{a}_1 & 0 \\ 0 & \bar{a}_2 \end{pmatrix} \begin{pmatrix} 0 & C \\ C & 0 \end{pmatrix} = \begin{pmatrix} a_2 & 0 \\ 0 & a_1 \end{pmatrix}. \tag{2.217}$$

This can only be the case if $a_1 = a_2$. So we have $(A_F)_{J_F} \simeq \mathbb{C}$, whose unitary elements from U(1) are contained in the diagonal subgroup of $U(A_F)$.

An arbitrary hermitian field $A_{\mu}=-ia\partial_{\mu}b$ is given by two U(1) Gauge fields $X_{\mu}^{1},X_{\mu}^{2}\in C^{\infty}(M,\mathbb{R})$. However A_{μ} appears in combination $A_{\mu}-J_{F}A_{\mu}J_{F}^{-1}$:

$$A_{\mu} - J_{F} A_{\mu} J_{F}^{-1} = \begin{pmatrix} X_{\mu}^{1} & 0 \\ 0 & X_{\mu}^{2} \end{pmatrix} - \begin{pmatrix} X_{\mu}^{2} & 0 \\ 0 & X_{\mu}^{1} \end{pmatrix} =: \begin{pmatrix} Y_{\mu} & 0 \\ 0 & -Y_{\mu} \end{pmatrix} = Y_{\mu} \otimes \gamma_{F}, \quad (2.218)$$

where Y_{μ} the U(1) Gauge field is defined as

$$Y_{\mu} := X_{\mu}^{1} - X_{\mu}^{2} \in C^{\infty}(M, \mathbb{R}) = C^{\infty}(M, i \ u(1)). \tag{2.219}$$

Proposition 2

The inner fluctuations of the almost-commutative manifold $M \times F_X$ are parameterized by a U(1)-gauge field Y_μ as

$$D \mapsto D' = D + \gamma^{\mu} Y_{\mu} \otimes \gamma_{F} \tag{2.220}$$

The action of the gauge group $\mathfrak{B}(M \times F_X) \simeq C^{\infty}(M, U(1))$ on D' is implemented by

$$Y_{\mu} \mapsto Y_{\mu} - i \, u \partial_{\mu} u^*; \quad (u \in \mathfrak{B}(M \times F_X)).$$
 (2.221)

2.6 Noncommutative Geometry of Electrodynamics

In this chapter we go through a derivation Electrodynamics with the almost commutative manifold $M \times F_X$ and the abelian gauge group U(1). The conclusion is an unified description of gravity and electrodynamics although in the classical level.

The almost commutative Manifold $M \times F_X$ outlines a local gauge group U(1). The inner fluctuations of the Dirac operator relate to Y_μ the gauge field of U(1). According to the setup we ultimately arrive at two serious problems.

First of all the operator D_F , in the Two-Point space F_X , must vanish such that a real structure can exists. However this implies that the electrons are massless.

The second problem arises when looking at the Euclidean action for a free Dirac field

$$S = -\int i\bar{\psi}(\gamma^{\mu}\partial_{\mu} - m)\psi d^{4}x, \qquad (2.222)$$

where ψ , $\bar{\psi}$ must be considered as two independent variables. This means that the fermionic action S_f needs two independent Dirac spinors. Let us try and construct two independent Dirac spinors with our data, first take a look at the decomposition of the basis and of the total Hilbertspace $H = L^2(S) \otimes H_F$. For the orthonormal basis of H_F we can write $\{e,\bar{e}\}$, where $\{e\}$ is the orthonormal basis of H_F^+ and $\{\bar{e}\}$ the orthonormal basis of H_F^- . Accompanied with the real structure we arrive at the following relations

$$J_F e = \bar{e} \quad J_F \bar{e} = e, \tag{2.223}$$

$$\gamma_F e = e \qquad \gamma_F \bar{e} = \bar{e}. \tag{2.224}$$

Along with the decomposition of $L^2(S) = L^2(S)^+ \oplus L^2(S)^-$ and $\gamma = \gamma_M \otimes \gamma_F$ we can obtain the positive eigenspace

$$H^{+} = L^{2}(S)^{+} \otimes H_{F}^{+} \oplus L(S)^{-} \otimes H_{F}^{-}. \tag{2.225}$$

So, for an $\xi \in H^+$ we can write

$$\xi = \psi_L \otimes e + \psi_R \otimes \bar{e}, \tag{2.226}$$

where $\psi_L \in L^2(S)^+$ and $\psi_R \in L^2(S)^-$ are the two Wheyl spinors. We denote that ξ is only determined by one Dirac spinor $\psi := \psi_L + \psi_R$. Since **we require two independent spinors**, our conclusion is that the definition of the fermionic action gives too much restrictions to the Two-Point space F_X .

2.6.1 The Finite Space

To solve the two problems we simply enlarge (double) the Hilbertspace. This is visualized by introducing multiplicities in Krajewski Diagrams [1] which will also allow us to choose a nonzero Dirac operator that will connect the two vertices and preserve real structure making our particles massive and bringing anti-particles into the mix.

We start of with the same algebra $C^{\infty}(M,\mathbb{C}^2)$, corresponding to space $N=M\times X$. The Hilbertspace describes four particles, meaning it has four orthonormal basis elements. It describes **left handed electrons** and **right handed positrons**. This way we have $\{\underline{e_R,e_L}, \overline{e_R,\overline{e_L}}\}$ an orthonormal basis for $H_F=\mathbb{C}^4$. Accompanied with the left-handed right-handed

real structure J_F allowing us to interchange particles with antiparticles by the following

equations

$$J_F e_R = \bar{e}_R, \tag{2.227}$$

$$J_F e_L = \bar{e_L}, \tag{2.228}$$

$$\gamma_F e_R = -e_R, \tag{2.229}$$

$$\gamma_F e_L = e_L, \tag{2.230}$$

where J_F and γ_F have to following properties

$$J_F^2 = 1, (2.231)$$

$$J_F \gamma_F = -\gamma_F J_F. \tag{2.232}$$

By the means of γ_F we have two options to decompose the total Hilbertspace H, firstly into

$$H_F = \underbrace{H_F^+}_{\text{ONB}} \oplus \underbrace{H_F^-}_{\text{ONB}}, \qquad (2.233)$$

or alternatively into the eigenspace of particles and their antiparticles (electrons and positrons) which is preferred in literature and which will be used further out

$$H_F = \underbrace{H_e}_{\text{ONB}} \oplus \underbrace{H_{\bar{e}}}_{\text{ONB}}, \qquad (2.234)$$

the shortening 'ONB' means orthonormal basis.

The action of $a \in A = \mathbb{C}^2$ on H with respect to the ONB $\{e_L, e_R, \bar{e}_L, \bar{e}_R\}$ is represented by

$$a = (a_1, a_2) \mapsto \begin{pmatrix} a_1 & 0 & 0 & 0 \\ 0 & a_1 & 0 & 0 \\ 0 & 0 & a_2 & 0 \\ 0 & 0 & 0 & a_2 \end{pmatrix}$$
 (2.235)

Do note that this action commutes wit the grading and that $[a,b^{\circ}] = 0$ with $b := J_F b^* J_F$ because both the left and the right action are given by diagonal matrices according to equation (2.235). Furthermore note that we are still left with $D_F = 0$ and the following spectral triple

$$\left(\mathbb{C}^2, \mathbb{C}^2, D_F = 0; J_F = \begin{pmatrix} 0 & C \\ C & 0 \end{pmatrix}, \gamma_F = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}\right). \tag{2.236}$$

It can be represented in the following Krajewski diagram, with two nodes of multiplicity two bellow

Figure 2: Krajewski diagram of the spectral triple from equation 2.236

2.6.2 A noncommutative Finite Dirac Operator

To extend our spectral triple with a non-zero Operator, we need to take a closer look at the Krajewski diagram above. Notice that edges only exist between multiple vertices, meaning we can construct a Dirac operator mapping between the two vertices. The operator can be represented by the following matrix

$$D_F = \begin{pmatrix} 0 & d & 0 & 0 \\ \bar{d} & 0 & 0 & 0 \\ 0 & 0 & 0 & \bar{d} \\ 0 & 0 & d & 0 \end{pmatrix}$$
 (2.237)

We can now define the finite space F_{ED} .

$$F_{ED} := (\mathbb{C}^2, \mathbb{C}^4, D_F; J_F, \gamma_F) \tag{2.238}$$

where J_F and γ_F are as in equation (2.236) and D_F from equation (2.237).

2.6.3 Almost commutative Manifold of Electrodynamics

The almost commutative manifold $M \times F_{ED}$ has KO-dimension 2, and is represented by the following spectral triple

To nowing spectral triple
$$M \times F_{ED} := \left(C^{\infty}(M, \mathbb{C}^2), \ L^2(S) \otimes \mathbb{C}^4, \ D_M \otimes 1 + \gamma_M \otimes D_F; \ J_M \otimes J_F, \ \gamma_M \otimes \gamma_F \right). \tag{2.239}$$

The algebra didn't change, thus we can decompose it like before

$$C^{\infty}(M, \mathbb{C}^2) = C^{\infty}(M) \oplus C^{\infty}(M). \tag{2.240}$$

As for the Hilbertspace, we can decomposition it in the following way

$$H = (L^2(S) \otimes H_e) \oplus (L^2(S) \otimes H_{\bar{e}}). \tag{2.241}$$

Note that the one component of the algebra is acting on $L^2(S) \otimes H_e$, and the other one acting on $L^2(S) \otimes H_{\bar{e}}$. In other words the components of the decomposition of both the algebra and the Hilbertspace match by the action of the algebra.

The derivation of the gauge theory is the same for F_{ED} as for the Two-Point space F_X . We have $\mathfrak{B}(F) \simeq U(1)$ and for an arbitrary gauge field $B_{\mu} = A_{\mu} - J_F A_{\mu} J_F^{-1}$ we can write

$$B_{\mu} = \begin{pmatrix} Y_{\mu} & 0 & 0 & 0 \\ 0 & Y_{\mu} & 0 & 0 \\ 0 & 0 & Y_{\mu} & 0 \\ 0 & 0 & 0 & Y_{\mu} \end{pmatrix} \quad \text{for } Y_{\mu}(x) \in \mathbb{R}.$$
 (2.242)

There is one single U(1) gauge field Y_{μ} , carrying the action of the gauge group

$$\mathfrak{B}(M \times F_{ED}) \simeq C^{\infty}(M, U(1)) \tag{2.243}$$

The space $N = M \times X$ consists of two copies of M. If $D_F = 0$ we have infinite distance between the two copies, yet now we have adjusted the spectral triple to have a nonzero Dirac operator. The new Dirac operator still has a commuting relation with the algebra $[D_F, a] = 0 \ \forall a \in A$, and we should note that the distance between the two copies of M is still infinite. This is purely an mathematically abstract observation and doesn't affect physical results.

2.6.4 Spectral Action

In this chapter we bring all our results together to establish an Action functional to describe a physical system. It turns out that the Lagrangian of the almost commutative manifold $M \times F_{ED}$ corresponds to the Lagrangian of Electrodynamics on a curved background manifold (+ gravitational Lagrangian), consisting of the spectral action S_b (bosonic) and of the fermionic action S_f .

The simplest spectral action of a spectral triple (A, H, D) is given by the trace of a function of D. We also consider inner fluctuations of the Dirac operator

$$D_{\omega} = D + \omega + \varepsilon' J \omega J^{-1}, \qquad (2.244)$$

where $\omega = \omega^* \in \Omega^1_D(A)$.

Definition 23

Let $f : \mathbb{R} \to \mathbb{R}$ be a suitable function **positive and even**. The spectral action is then

$$S_b[\omega] := Tr(f(\frac{D_\omega}{\Lambda}))$$
 (2.245)

where Λ is a real cutoff parameter. The minimal condition on f is that $f(\frac{D_{\omega}}{\Lambda})$ is a trace class operator. A trace class operator is a compact operator with a well defined finite trace independent of the basis. The subscript b in S_b stands for bosonic, because in physical applications ω will describe bosonic fields.

In addition to the bosonic action S_b , we can define a topological spectral action S_{top} . Leaning on the grading γ the topological spectral action is

$$S_{top}[\omega] := Tr(\gamma f(\frac{D_{\omega}}{\Lambda})).$$
 (2.246)

Definition 24

The fermionic action is defined by

$$S_f[\omega, \psi] = (J\tilde{\psi}, D_{\omega}\tilde{\psi}) \tag{2.247}$$

with $\tilde{\psi} \in H_{cl}^+ := \{\tilde{\psi} : \psi \in H^+\}$, where H_{cl}^+ is a set of Grassmann variables in H in the +1-eigenspace of the grading γ .

Grassmann variables are a set of Basis vectors of a vector space, they form a unital algebra over a vector field V, where the generators are anti commuting, that is for Grassmann variables θ_i , θ_j we have

$$\theta_i \theta_i = -\theta_i \theta_i, \tag{2.248}$$

$$\theta_i x = x \theta_i \quad x \in V, \tag{2.249}$$

$$(\theta_i)^2 = 0 \quad (\theta_i \theta_i = -\theta_i \theta_i). \tag{2.250}$$

Proposition 3

The spectral action of the almost commutative manifold M with $\dim(M) = 4$ with

a fluctuated Dirac operator is

$$Tr(f\frac{D_{\omega}}{\Lambda}) \sim \int_{\mathcal{M}} \mathcal{L}(g_{\mu\nu}, B_{\mu}, \Phi) \sqrt{g} d^4x + O(\Lambda^{-1}),$$
 (2.251)

where

$$\mathcal{L}(g_{\mu\nu}, B_{\mu}, \Phi) = N\mathcal{L}_M(g_{\mu\nu})\mathcal{L}_B(B_{\mu}) + \mathcal{L}_{\phi}(g_{\mu\nu}, B_{\mu}, \Phi). \tag{2.252}$$

The Lagrangian \mathcal{L}_M is of the spectral triple $(C^{\infty}(M), L^2(S), D_M)$, represented by the following term

$$\mathscr{L}_{M}(g_{\mu\nu}) := \frac{f_{4}\Lambda^{4}}{2\pi^{2}} - \frac{f_{2}\Lambda^{2}}{24\pi^{2}}s - \frac{f(0)}{320\pi^{2}}C_{\mu\nu\rho\sigma}C^{\mu\nu\rho\sigma}, \qquad (2.253)$$

where $C^{\mu\nu\rho\sigma}$ is the Weyl tensor defined in terms of the Riemannian curvature tensor $R_{\mu\nu\rho\sigma}$ and the Ricci tensor $R_{\nu\sigma} = g^{\mu\rho}R_{\mu\nu\rho\sigma}$ such that

$$C^{\mu\nu\rho\sigma}C_{\mu\nu\rho\sigma} = R_{\mu\nu\rho\sigma}R^{\mu\nu\rho\sigma} - 2R_{\nu\sigma}R^{\nu\sigma} + \frac{1}{2}s^2. \tag{2.254}$$

The kinetic term of the gauge field is described by the Lagrangian \mathcal{L}_B , which takes the following shape

$$\mathscr{L}_B(B_{\mu}) := \frac{f(0)}{24\pi^2} Tr(F_{\mu\nu}F^{\mu\nu}). \tag{2.255}$$

Lastly \mathscr{L}_{ϕ} is the scalar-field Lagrangian with a boundary term, given by

$$\mathcal{L}_{\phi}(g_{\mu\nu}, B_{\mu}, \Phi) := -\frac{2f_{2}\Lambda^{2}}{4\pi^{2}} Tr(\Phi^{2}) + \frac{f(0)}{8\pi^{2}} Tr(\Phi^{4}) + \frac{f(0)}{24\pi^{2}} \Delta(Tr(\Phi^{2})) + \frac{f(0)}{48\pi^{2}} s Tr(\Phi^{2}) \frac{f(0)}{8\pi^{2}} Tr((D_{\mu}\Phi)(D^{\mu}\Phi)).$$
(2.256)

Proof. The dimension of the manifold M is $\dim(M) = \operatorname{Tr}(id) = 4$. For an $x \in M$, we have an asymptotic expansion of the term $\operatorname{Tr}(f(\frac{D_{\omega}}{\Lambda}))$ as Λ goes to infinity, which can be written as

$$\operatorname{Tr}(f(\frac{D_{\omega}}{\Lambda})) \simeq 2f_4\Lambda^4 a_0(D_{\omega}^2) + 2f_2\Lambda^2 a_2(D_{\omega}^2) + f(0)a_4(D_{\omega}^4) + O(\Lambda^{-1}). \tag{2.257}$$

We have to note here that the heat kernel coefficients are zero for uneven k, and they are dependent on the fluctuated Dirac operator D_{ω} . We can rewrite the heat kernel coefficients in terms of D_M , for the first two terms a_0 and a_2 we use $N := \text{Tr}(\mathbb{1}_{H_F})$ and one obtains

$$a_0(D_{\omega}^2) = Na_0(D_M^2), \tag{2.258}$$

$$a_2(D_\omega^2) = Na_2(D_M^2) - \frac{1}{4\pi^2} \int_M \text{Tr}(\Phi^2) \sqrt{g} d^4 x.$$
 (2.259)

For a_4 we extend in terms of coefficients of F from equation (2.192)

$$\frac{1}{360}\text{Tr}(60RE) = -\frac{1}{6}S(NR + 4\text{Tr}(\Phi^2))$$
 (2.260)

$$E^{2} = \frac{1}{16}R^{2} \otimes 1 + 1 \otimes \Phi^{4} - \frac{1}{4}\gamma^{\mu}\gamma^{\nu}\gamma^{\rho}\gamma^{\sigma}F_{\mu\nu}F^{\mu\nu} +$$

$$+ \gamma^{\mu}\gamma^{\nu} \otimes (D_{\mu}\Phi)(D_{\nu}\Phi) + \frac{1}{2}s \otimes \Phi^{2} + \text{ traceless terms}, \qquad (2.261)$$

$$\frac{1}{360} \text{Tr}(180E^2) = \frac{1}{8} R^2 N + 2 \text{Tr}(\Phi^4) + \text{Tr}(F_{\mu\nu}F^{\mu\nu}) +
+ 2 \text{Tr}((D_{\mu}\Phi)(D^{\mu}\Phi)) + s \text{Tr}(\Phi^2)$$
(2.262)

$$\frac{1}{360}\text{Tr}(-60\Delta E) = \frac{1}{6}\Delta(NR + 4\text{Tr}(\Phi^2)). \tag{2.263}$$

The cross terms of the trace in $\Omega^E_{\mu\nu}\Omega^{E\mu\nu}$ vanishes because of the antisymmetric property of the Riemannian curvature tensor, reading

$$\Omega^{E}_{\mu\nu}\Omega^{E\mu\nu} = \Omega^{S}_{\mu\nu}\Omega^{S\mu\nu} \otimes 1 - 1 \otimes F_{\mu\nu}F^{\mu\nu} + 2i\Omega^{S}_{\mu\nu} \otimes F^{\mu\nu}. \tag{2.264}$$

The trace of the cross term $\Omega_{\mu\nu}^S$ vanishes because

$$\operatorname{Tr}(\Omega_{\mu\nu}^{S}) = \frac{1}{4} R_{\mu\nu\rho\sigma} \operatorname{Tr}(\gamma^{\mu}\gamma^{\nu}) = \frac{1}{4} R_{\mu\nu\rho\sigma} g^{\mu\nu} = 0, \tag{2.265}$$

then the trace of the whole term is given by

$$\frac{1}{360} \text{Tr}(30\Omega_{\mu\nu}^E \Omega^{E\mu\nu}) = \frac{N}{24} R_{\mu\nu\rho\sigma} R^{\mu\nu\rho\sigma} - \frac{1}{3} \text{Tr}(F_{\mu\nu} F^{\mu\nu}). \tag{2.266}$$

Finally plugging the results into the coefficient a_4 and simplifying one gets

$$a_4(x, D_{\omega}^4) = Na_4(x, D_M^2) + \frac{1}{4\pi^2} \left(\frac{1}{12} s \text{Tr}(\Phi^2) + \frac{1}{2} \text{Tr}(\Phi^4) + \frac{1}{4} \text{Tr}((D_{\mu}\Phi)(D^{\mu}\Phi)) + \frac{1}{6} \Delta \text{Tr}(\Phi^2) + \frac{1}{6} \text{Tr}(F_{\mu\nu}F^{\mu\nu}) \right). \tag{2.267}$$

The only thing left is to substitute the heat kernel coefficients into the heat kernel expansion in equation (2.257).

2.6.5 Fermionic Action

We remind ourselves the definition of the fermionic action in definition 2.6.4 and the manifold we are dealing with in equation (2.239). The Hilbertspace H_F is separated into the particle-antiparticle states with ONB $\{e_R, e_L, \bar{e}_R, \bar{e}_L\}$. The orthonormal basis of H_F^+ is $\{e_L, \bar{e}_R\}$ and consequently for H_F^- , $\{e_R, \bar{e}_L\}$. The decomposition of a spinor $\psi \in L^2(S)$ in each of the eigenspaces H_F^\pm is $\psi = \psi_R + \psi_L$. Meaning for an arbitrary $\psi \in H^+$ we can write

$$\Psi = \chi_R \otimes e_R + \chi_L \otimes e_L + \Psi_L \otimes \bar{e}_R + \Psi_R \otimes \bar{e}_L, \tag{2.268}$$

where $\chi_L, \psi_L \in L^2(S)^+$ and $\chi_R, \psi_R \in L^2(S)^-$.

Since the fermionic action yields too much restriction on F_{ED} (modified Two-Point space F_X) one redefines it by taking into account the fluctuated Dirac operator

$$D_{\omega} = D_{M} \otimes i + \gamma^{\mu} \otimes B_{\mu} + \gamma_{M} \otimes D_{F}. \tag{2.269}$$

The Fermionic Action is

$$S_F = (J\tilde{\xi}, D_{\omega}\tilde{\xi}) \tag{2.270}$$

for a $\xi \in H^+$. Then the straight forward calculation gives

$$\frac{1}{2}(J\tilde{\xi}, D_{\omega}\tilde{\xi}) = \frac{1}{2}(J\tilde{\xi}, (D_{M} \otimes i)\tilde{\xi})$$
(2.271)

$$+\frac{1}{2}(J\tilde{\xi},(\gamma^{\mu}\otimes B_{\mu})\tilde{\xi}) \tag{2.272}$$

$$+\frac{1}{2}(J\tilde{\xi},(\gamma_{M}\otimes D_{F})\tilde{\xi}), \qquad (2.273)$$

(note that we add the constant $\frac{1}{2}$ to the action). For the term in (2.271) we calculate

$$\frac{1}{2}(J\tilde{\xi},(D_M\otimes 1)\tilde{\xi}) = \frac{1}{2}(J_M\tilde{\chi}_R,D_M\tilde{\psi}_L) + \frac{1}{2}(J_M\tilde{\chi}_L,D_M\tilde{\psi}_R) + \frac{1}{2}(J_M\tilde{\psi}_L,D_M\tilde{\psi}_R) + \frac{1}{2}(J_M\tilde{\chi}_R,D_M\tilde{\chi}_L)$$

$$= (J_M\tilde{\chi},D_M\tilde{\chi}). \tag{2.274}$$

For the term in (2.272) we have

$$\frac{1}{2}(J\tilde{\xi},(\gamma^{\mu}\otimes B_{\mu})\tilde{\xi}) = -\frac{1}{2}(J_{M}\tilde{\chi}_{R},\gamma^{\mu}Y_{\mu}\tilde{\psi}_{R}) - \frac{1}{2}(J_{M}\tilde{\chi}_{L},\gamma^{\mu}Y_{\mu}\tilde{\psi}_{R}) +
+ \frac{1}{2}(J_{M}\tilde{\psi}_{L},\gamma^{\mu}Y_{\mu}\tilde{\chi}_{R}) + \frac{1}{2}(J_{M}\tilde{\psi}_{R},\gamma^{\mu}Y_{\mu}\tilde{\chi}_{L}) =
= -(J_{M}\tilde{\chi},\gamma^{\mu}Y_{\mu}\tilde{\psi}).$$
(2.275)

And for (2.273) we can write

$$\frac{1}{2}(J\tilde{\xi},(\gamma_{M}\otimes D_{F})\tilde{\xi}) = +\frac{1}{2}(J_{M}\tilde{\chi}_{R},d\gamma_{M}\tilde{\chi}_{R}) + \frac{1}{2}(J_{M}\tilde{\chi}_{L},\bar{d}\gamma_{M}\tilde{\chi}_{L}) +
+\frac{1}{2}(J_{M}\tilde{\chi}_{L},\bar{d}\gamma_{M}\tilde{\chi}_{L}) + \frac{1}{2}(J_{M}\tilde{\chi}_{R},d\gamma_{M}\tilde{\chi}_{R}) =
= i(J_{M}\tilde{\chi},m\tilde{\psi}).$$
(2.276)

A small problem arises, we obtain a complex mass parameter d, but we can write d := im for $m \in \mathbb{R}$, which stands for the real mass.

Finally the fermionic action of $M \times F_{ED}$ takes the form

$$S_f = -i \left(J_M \tilde{\chi}, \gamma (\nabla_{\mu}^S - i \Gamma_{\mu}) \tilde{\Psi} \right) + \left(S_M \tilde{\chi}_L, \bar{d} \tilde{\psi}_L \right) - \left(J_M \tilde{\chi}_R, d \tilde{\psi}_R \right). \tag{2.277}$$

Ultimately we arrive at the full Lagrangian of the almost commutative manifold $M \times F_{ED}$, which is the sum of the purely gravitational Lagrangian

$$\mathcal{L}_{grav}(g_{\mu\nu}) = 4\mathcal{L}_{M}(g_{\mu\nu}) + \mathcal{L}_{\phi}(g_{\mu\nu}), \tag{2.278}$$

and the Lagrangian of electrodynamics

$$\mathscr{L}_{ED} = -i \left\langle J_M \tilde{\chi}, \left(\gamma^{\mu} (\nabla^S_{\mu} - i Y_{\mu}) - m \right) \tilde{\psi} \right) \right\rangle + \frac{f(0)}{6\pi^2} Y_{\mu\nu} Y^{\mu\nu}. \tag{2.279}$$

3 Conclusion

We conclude that the framework of noncommutative geometry can fully describe the physics of electrodynamics. This is done by introducing the spectral and fermionic action principles of the almost commutative manifold $M \times F_{ED}$ constructed from a four dimensional Riemannian spin manifold and a modification of the two point space F_X . By going through rough calculations of the heat kernel coefficients to describe the Lagrangian in terms of geometrical invariants we finally arrive at the Lagrangians in equations (2.278) and (2.279).

With a similar complex ansatz Walter D. Suijlekom describes in his book [1] how to figure out a specific version of a spectral triple corresponding the almost commutative manifold which delivers the physics of the full Standard Model and with this information accurately calculating the mass of the Higgs boson. Moreover he describes more accurately the correspondence of the gauge theory of an almost commutative manifold, which brings this noncommutative geometry to the interest of physicists in the first place.

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