# Introductory Seminar Advanced Numerical Analysis

Exercise sheet 5, due date: 04.04.2022

### Exercise 1 (SSOR preconditioning).

Let  $A \in \mathbb{R}^{n \times n}$  be a SPD matrix with the additive decomposition  $A = L + D + L^T$  where D consists of the diagonal entries of A and L is lower triangular. Consider for  $\omega \in (0, 2)$  the parameter dependent matrix

$$C_{\omega} = \frac{1}{2 - \omega} \left( \frac{1}{\omega} D + L \right) \left( \frac{1}{\omega} D \right)^{-1} \left( \frac{1}{\omega} D + L^{T} \right).$$

- (1) Write  $C_{\omega}$  in the form  $KK^T$  with an invertible lower-triangular matrix K.
- (2) Explain why  $C_{\omega}^{-1}$  may be viewed as an approximation for  $A^{-1}$  and argue why  $C_{\omega}$  serves as a candidate for a preconditioning matrix.

#### Exercise 2 (M-matrix).

Let  $n, m \in \mathbb{N}$ . Further, let  $I \in \mathbb{R}^{m \times m}$  be the identity matrix in  $\mathbb{R}^{m \times m}$  and Q the banded matrix

$$Q = \begin{pmatrix} 4 & -1 & & & \\ -1 & 4 & -1 & & & \\ & \ddots & \ddots & \ddots & \\ & & -1 & 4 & -1 \\ & & & 4 \end{pmatrix} \in \mathbb{R}^{m \times m}.$$

Let  $A \in \mathbb{R}^{nm \times nm}$  be the matrix which arises from I and Q via

$$A = \begin{pmatrix} Q & -I & & & \\ -I & Q & -I & & & \\ & \ddots & \ddots & \ddots & \\ & & -I & Q & -I \\ & & & Q \end{pmatrix} \in \mathbb{R}^{nm \times nm}.$$

The matrix A originates from the 5-point discretization of the Poisson problem on the unit square.

- (1) Show that Q is invertible.
- (2) Show that A is a so-called "(inverse) monotone" matrix, or M-matrix. That is, all entries of the inverse of A are non-negative.

#### Exercise 3 (Polynomial norm bound).

Let  $A \in \mathbb{R}^{n \times n}$  be a SPD matrix and  $b \in \mathbb{R}^n$  a right-hand side. Suppose we apply the CG-method for solving the system Ax = b (as defined in the lecture notes p. 65). Recall that the k-th iterate  $x_k$  of the CG method satisfies the A-norm optimality condition

$$||x_k - x||_A = \min_{y \in x_0 + B_k} ||y - x||_A$$

where

$$B_k = \operatorname{span} \{p_0, \dots, p_{k-1}\} = \operatorname{span} \{r_0, Ar_0, \dots, A^{k-1}r_0\}$$

and the search directions  $p_k$  form an A-orthogonal system. Use the above facts to prove the following statement: If the spectrum of A lies in the interval  $[a,b] \subset (0,\infty)$  then for any polynomial  $p \in \mathbb{P}_k$  with p(0) = 1 we have

$$||x_k - x||_A \le \left(\sup_{t \in [a,b]} |p(t)|\right) ||x_0 - x||_A.$$

Show that this, in particular, implies that

$$||x_k - x||_A \le \inf_{p \in \mathbb{P}_k, p(0) = 1} (||p||_{C[a,b]}) ||x_0 - x||_A.$$

# Exercise 4 (GMRES method).

Let  $A \in \mathbb{R}^{n \times n}$  be a SPD matrix and  $b \in \mathbb{R}^n$  a right-hand side. In a similar fashion as in Exercise 3 we can show that the iterates  $x_k$  of the CG method satisfy the  $A^{-1}$ -norm optimality

$$||Ax_k - b||_{A^{-1}} = \min_{y \in x_0 + C_k} ||Ay - b||_{A^{-1}}$$

with  $C_k = \text{span}\{p_0, Ap_0, \dots, A^{l-1}p_0\}$ . The so-called "generalized minimal residual method" (GMRES), instead, formally constructs a sequence of iterates  $x_k^{G}$  by

$$||Ax_k^{G} - b||_2 = \min_{y \in x_0 + C_k} ||Ay - b||_2.$$

Prove that the GMRES method allows for an error inequality similar to the one that was derived for the CG-method, namely

$$||Ax_k^{G} - b||_2 \le \inf_{p \in \mathbb{P}_k, p(0) = 1} ||p(A)||_2 ||Ax_0 - b||_2.$$

## Exercise 5 (Richardson iteration).

Let  $A \in \mathbb{R}^{n \times n}$  and  $b \in \mathbb{R}^n$ .

- (1) Take  $A, b, n, \omega$  as an input and implement the damped Richardson iteration with damping parameter  $\omega$ .
- (2) Now let

$$A = \begin{pmatrix} 3 & 1 & 1 \\ 1 & 3 & 1 \\ 1 & 1 & 4 \end{pmatrix}, \quad b = \begin{pmatrix} 2 \\ -4 \\ 3 \end{pmatrix}.$$

Find a suitable damping parameter  $\omega$  and calculate a numerical approximation of the solution of the equation Ax = b using the implementation from (1).