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Nonlinear Optimization Problems

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1 Sheet 1

1.1 Exercise 1

Let $X \subseteq \mathbb{R}^n$ be a nonempty convex set and $f : \mathbb{R}^n \rightarrow \mathbb{R}$ a convex function. Show that every local minimum of f w.r.t. X is a global minimum of f w.r.t. X .

Let $x^* \in X$ be the local minimum of f w.r.t. X . Then there is an ε -ball $B_\varepsilon(x^*) = \{x \in X : \|x^* - x\| \leq \varepsilon\}$ such that $f(x^*) \leq f(x)$ for all $x \in B_\varepsilon(x^*) \cap X$. Now suppose x^* is not a global minimum then there is a $x_0 \in X$ such that $f(x_0) < f(x^*)$. Since X is convex there is a line connecting x_0 and x^* in X . This line has elements of the form

$$L = \{(1 - \lambda)x_0 - \lambda x^* : \lambda \in [0, 1]\} \subseteq X \quad (1)$$

Now for all $z \in L$ with $z = (1 - \lambda)x_0 - \lambda x^*$ ($\forall \lambda \in [0, 1]$) it holds that

$$\|x^* - (1 - \lambda)x_0 - \lambda x^*\| \leq \varepsilon \quad (2)$$

$$(1 - \lambda)\|x^* - x_0\| \leq \varepsilon \Rightarrow \lambda \simeq 1 \quad (3)$$

and

$$f((1 - \lambda)x_0 + \lambda x^*) \leq \lambda f(x^*) + (1 - \lambda)f(x_0) \quad (4)$$

$$< \lambda f(x^*) + (1 - \lambda)f(x_0) \quad (5)$$

$$= f(x_0) \quad (6)$$

This means that we found a $\tilde{x} = \lambda x^* - (1 - \lambda)x_0 \in B_\varepsilon(x^*)$ such that $f(\tilde{x}) < f(x^*)$ which is a contradiction since x^* is a local minimum in $B_\varepsilon(x^*)$. This means that x^* is a global minimum of f w.r.t. X .

1.2 Exercise 2

Let $X \subseteq \mathbb{R}^n$ be a nonempty, $x_0 \in X$. Show that

1. $T_X(x_0)$ is a nonempty closed cone
2. If X is convex, then $T_X(x_0) = \text{cl} \left(\bigcup_{\lambda \geq 0} \lambda (X - x_0) \right)$
3. If X is convex then $(T_X(x_0))^* = -N_X(x_0)$

The statements will be proven in chronological order. Starting with 1. the Bouligand tangent cone to X is defined as

$$T_X(x_0) = \{d \in \mathbb{R}^n : \exists (x^k)_{k \geq 0} \subset X, \exists (t_k)_{k \geq 0} \searrow 0 : \frac{x^k - x_0}{t_k} \rightarrow d\} \quad (7)$$

Now $T_X(x_0)$ is nonempty since for $x^k = x_0$ for all k and a sequence $t_k = \frac{1}{k}$ we have

$$\frac{x^k - x_0}{t_k} \rightarrow 0 \in T_X(x_0) \quad (8)$$

To show that $T_X(x_0)$ is closed, consider a sequence $(d_k)_{k \geq 0} \subset T_X(x_0)$ with convergence point $d \in \mathbb{R}^n$. To show that it is closed we need to show that $d \in T_X(x_0)$. So for all $d_n \in (d_k)_{k \geq 0} \subset T_X(x_0)$ there exists a sequence $(x^{n,k})_{k \geq 0} \subset X$ and a sequence $(t_{n,k})_{k \geq 0}$ with $t_{n,k} \searrow 0$ as $k \rightarrow \infty$ such that

$$\frac{x^{n,k} - x_0}{t_{n,k}} \rightarrow d_n \quad \forall n \geq 0, \quad (9)$$

and

$$\lim_{n \rightarrow \infty} \lim_{k \rightarrow \infty} \frac{x^{n,k} - x_0}{t_{n,k}} = d. \quad (10)$$

Then there exist K_ε and N_δ for $\varepsilon, \delta > 0$ such that

$$\|d_k - d\| \leq \varepsilon \quad \forall k \geq K_\varepsilon, \quad (11)$$

$$\left\| \frac{x^{n,K_\varepsilon} - x_0}{t_{n,K_\varepsilon}} - d_{K_\varepsilon} \right\| \leq \delta \quad \forall n \geq N_\delta. \quad (12)$$

To conclude the proof consider

$$\left\| \frac{x^{N_\delta, K_\varepsilon} - x_0}{t_{N_\delta, K_\varepsilon}} - d \right\| \quad (13)$$

$$= \left\| \left(\frac{x^{N_\delta, K_\varepsilon} - x_0}{t_{N_\delta, K_\varepsilon}} - d_{K_\varepsilon} \right) + (d_{K_\varepsilon} - d) \right\| \quad (14)$$

$$\leq \varepsilon + \delta \quad (15)$$

Meaning that $d \in T_X(x_0)$. Then $T_X(x_0)$ is really a cone because $\forall d \in T_X(x_0)$ and $\lambda > 0$ we have that $\lambda d \in T_X(x_0)$ by the choice $t_{k,\lambda} = \frac{1}{\lambda} t_k$

$$\frac{x^k - x}{t_{k,\lambda}} = \lambda \frac{x^k - x_0}{t_k} \rightarrow \lambda d \in T_X(x_0) \quad (16)$$

For number 2 additionally X is a convex set. And by definition of a cone $\bigcup_{\lambda \geq 0} \lambda (X - x_0)$ is a cone. And the union of convex sets is also convex the set $\text{cl} \left(\bigcup_{\lambda \geq 0} \lambda (X - x_0) \right)$ is also. convex. For number 3 we simply calculate

$$-(T_X(x_0))^* = -\{s \in \mathbb{R}^n : s^T d \geq 0 \forall d \in T_X(x_0)\} \quad (17)$$

$$= \{s \in \mathbb{R}^n : s^T d \leq 0 \forall d \in T_X(x_0)\} \quad (18)$$

$$= \{s \in \mathbb{R}^n : s^T (x - x_0) \leq 0 \forall x \in X\} \quad (19)$$

Since *forall* $x \in X$ there exists an appropriate sequence converging to x subjected to the tangent cone elements.

1.3 Exercise 3

Let $X \subseteq \mathbb{R}^n$ be nonempty and $\text{dist}_X : \mathbb{R}^n \rightarrow \mathbb{R}$, with $\text{dist}_X(y) = \inf\{\|y - x\| : x \in X\}$. Then consider the directional derivative of a function $f : \mathbb{R}^n \rightarrow \mathbb{R}$ at direction d at $x_0 \in \mathbb{R}^n$

$$f'(x_0; d) = \lim_{t \downarrow 0} \frac{f(x_0 + td) - f(x_0)}{t} \quad (20)$$

Show that if $X \subseteq \mathbb{R}^n$ is nonempty and convex then the tangent cone can be written as

$$T_X(x_0) = \{d \in \mathbb{R}^n : (\text{dist}_X)'(x_0; d) = 0\}. \quad (21)$$

First we note

$$(\text{dist}_X)'(x_0; d) = \lim_{t \downarrow 0} \frac{\text{dist}_X(x_0 + td)}{t} = 0, \quad (22)$$

is true for all $x_0 + td \in X$. Since X is convex we have that

$$T_X(x_0) = \text{cl} \left(\bigcup_{\lambda} (X - x_0) \right) \quad (23)$$

$$= \text{cl}(\{\lambda(x - x_0) : x \in X, \lambda \geq 0\}) \quad (24)$$

Then $(\text{dist}_X)'(x_0; d) = 0$ holds only for vectors of the form $d = \lambda(x - x_0)$, $\lambda \geq 0$ and $x \in X$.

1.4 Exercise 4

We consider the general constrained optimization problem

$$\begin{aligned} \min \quad & f(x), \\ \text{s.t.} \quad & g_i(x) \leq 0, i = 0, \dots, m \\ & h_j(x) = 0, j = 0, \dots, p \\ & x \in \mathbb{R}^n \end{aligned} \quad (25)$$

for $f, g_i, h_j : \mathbb{R}^n \rightarrow \mathbb{R}$, $i = 0, \dots, m$ and $j = 0, \dots, p$ continuously differentiable. Let x_0 be a feasible element of the problem and

$$X_{\text{lin}} := \{x \in \mathbb{R}^n : g_i(x_0) + \nabla g_i(x_0)^T(x - x_0), i = 0, \dots, m \quad (26)$$

$$h_j(x_0) + \nabla h_j(x_0)^T(x - x_0), j = 0, \dots, p\}. \quad (27)$$

Show that $T_{\text{lin}}(x_0) = T_{X_{\text{lin}}}(x_0)$.

For the reminder

$$T_{\text{lin}}(x_0) := \{d \in \mathbb{R}^n : \nabla g_i(x_0)^T d, \forall i \in \mathcal{A}(x_0) \quad (28)$$

$$\nabla h_j(x_0)^T d, j = 0, \dots, p\}, \quad (29)$$

where $\mathcal{A}(x_0) = \{i = 0, \dots, m : g_i(x_0) = 0\}$. First we show that X_{lin} is convex then we can use the second part of exercise 2. So for all $x, y \in X_{\text{lin}}$ we need to show that $z = (1 - \lambda)x + \lambda y \in X_{\text{lin}}$, this is done by checking the conditions

$$\nabla g_i(x_0) + \nabla g_i(x_0)^T(z - x_0) \quad (30)$$

$$= \nabla g_i(x_0) + \nabla g_i(x_0)^T((1 - \lambda)x + \lambda y - x_0) \quad (31)$$

$$= \nabla g_i(x_0) + \nabla g_i(x_0)^T(x - \lambda x + \lambda y - x_0) \quad (32)$$

$$= \nabla g_i(x_0) + \nabla g_i(x_0)^T(x - x_0) + \nabla g_i(x_0)^T(-\lambda x + \lambda y) \quad (33)$$

$$\leq \lambda \nabla g_i(x_0)^T(-x + y) \quad (\lambda \geq 0) \quad (34)$$

$$\leq \nabla g_i(x_0)^T(-x + y + x_0 - x_0) + g_i(x_0) - g_i(x_0) \quad (35)$$

$$= -\nabla g_i(x_0) - \nabla g_i(x_0)^T(x - x_0) + \nabla g_i(x_0) + \nabla g_i(x_0)^T(y - x_0) \quad (36)$$

$$\leq 0 \quad (37)$$

and similarly for h_j

$$\nabla h_j(x_0) + \nabla h_j(x_0)^T(z - x_0) \quad (38)$$

$$= \nabla h_j(x_0) + \nabla h_j(x_0)^T((1 - \lambda)x + \lambda y - x_0) \quad (39)$$

$$= \nabla h_j(x_0) + \nabla h_j(x_0)^T(x - \lambda x + \lambda y - x_0) \quad (40)$$

$$= \nabla h_j(x_0) + \nabla h_j(x_0)^T(x - x_0) + \nabla h_j(x_0)^T(-\lambda x + \lambda y) \quad (41)$$

$$= \lambda \nabla h_j(x_0)^T(-x + y) \quad (42)$$

$$= \lambda \nabla h_j(x_0)^T(-x + y + x_0 - x_0) + \lambda h_j(x_0) - \lambda h_j(x_0) \quad (43)$$

$$= \lambda (-\nabla h_j(x_0) - \nabla h_j(x_0)^T(x - x_0) + \nabla h_j(x_0) + \nabla h_j(x_0)^T(y - x_0)) \quad (44)$$

$$= 0 \quad (45)$$

Thereby X_{lin} is convex and

$$T_{X_{lin}}(x_0) = \bigcup_{\lambda \geq 0} \lambda (X_{lin} - x_0). \quad (46)$$

Additionally $T_{lin}(x_0)$ is a polyhedral so per definition

$$T_{lin}(x_0) = \bigcup_{\lambda \geq 0} \lambda (X_{lin} - x_0) \quad (47)$$

1.5 Exercise 5

Let $g : \mathbb{R}^2 \rightarrow \mathbb{R}^4$ with

$$g(x, y) = \begin{pmatrix} \pi - 2x \\ -y - 1 \\ 2x - 3\pi \\ y - \sin(x) \end{pmatrix}. \quad (48)$$

and

$$X = \{(x, y) \in \mathbb{R}^2 : g(x, y) \leq 0\}. \quad (49)$$

The set X has the following constraints on x, y

$$\pi - 2x \leq 0 \Rightarrow x \geq \frac{\pi}{2} \quad (50)$$

$$-y - 1 \leq 0 \Rightarrow y \geq -1 \quad (51)$$

$$2x - 3\pi \leq 0 \Rightarrow x \leq \frac{3\pi}{2} \quad (52)$$

$$y - \sin(x) \leq 0 \Rightarrow y \leq 1, \quad (53)$$

meaning $x \in [\frac{\pi}{2}, \frac{3\pi}{2}]$ and $y \in [-1, 1]$. The tangent cones of X w.r.t $x_1 = (\frac{\pi}{2}, 1)^T$, $x_2 = (\pi, 0)^T$ and $x_3 = (\frac{3\pi}{2}, -1)^T$ are

$$T_X(x_1) = \{(0, -\lambda)^T, (\lambda, 1)^T : \lambda > 0\} \quad (54)$$

$$T_X(x_2) = \{\lambda(\cos(x), \sin(x))^T, (\lambda, 1)^T : \lambda > 0\} \quad (55)$$

$$T_X(x_3) = \{(-\lambda, 0)^T, (0, \lambda)^T : \lambda > 0\} \quad (56)$$

Graphically it represents the following

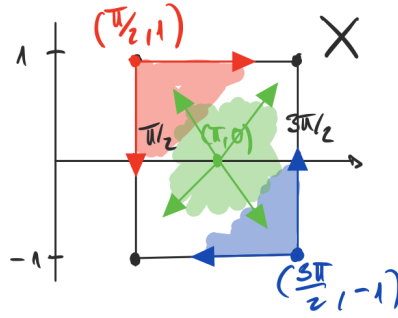


Figure 1: Graphical representation of X and tangent cones $T_X(x_i)$, $i = 1, 2, 3$

Then we look at the linearized tangent cones $T_{\text{lin}}(x_i) = \{d \in \mathbb{R}^2 : \nabla g_i(x_i)^T d \leq 0 \forall i \in \mathcal{A}(x_i)\}$. First we calculate the gradients of entries of g

$$\nabla g_1(x, y) = (-2, 0)^T \quad \nabla g_2(x, y) = (0, -1)^T \quad (57)$$

$$\nabla g_3(x, y) = (2, 0)^T \quad \nabla g_4(x, y) = (-\cos(x), 1)^T \quad (58)$$

then for all $j \in \{1, 2, 3, 4\}$ and $i \in \{1, 2, 3\}$ we check if $g_j(x_i) \leq 0$ and construct $\mathcal{A}(x_i)$ and then find d subjected to the condition. For x_1 we have

$$g_1(x_1) = 0, \quad g_2(x_1) \neq 0, \quad g_3(x_1) \neq 0, \quad g_4(x_1) = 0 \quad (59)$$

$$\Rightarrow \mathcal{A}(x_1) = \{1, 2\} \quad (60)$$

Then

$$T_{\text{lin}} = \{d \in \mathbb{R}^2 : (0, 1)d \leq 0, (-2, 0)d \leq 0\} \quad (61)$$

$$= \{(\lambda, 0)^T, (0, -\lambda)^T : \lambda > 0\} \quad (62)$$

For x_2 we have

$$g_1(x_1) \neq 0, \quad g_2(x_1) \neq 0, \quad g_3(x_1) \neq 0, \quad g_4(x_1) \neq 0 \quad (63)$$

$$\Rightarrow \mathcal{A}(x_1) = \{4\} \quad (64)$$

Then

$$T_{\text{lin}} = \{d \in \mathbb{R}^2 : (1, 1)d \leq 0\} \quad (65)$$

$$= \{(-\lambda, \lambda)^T, (\lambda, -\lambda)^T, (-\lambda, 0)^T, (0, -\lambda)^T : \lambda > 0\} \quad (66)$$

For x_3 we have

$$g_1(x_1) \neq 0, \quad g_2(x_1) = 0, \quad g_3(x_1) = 0, \quad g_4(x_1) = 0 \quad (67)$$

$$\Rightarrow \mathcal{A}(x_1) = \{2, 3, 4\} \quad (68)$$

Then

$$T_{\text{lin}} = \{d \in \mathbb{R}^2 : (0, -1)d \leq 0, (2, 0)d \leq 0, (0, 1)d \leq 0\} \quad (69)$$

$$= \{(-\lambda, 0)^T : \lambda > 0\} \quad (70)$$

We conclude that $T_{X_{\text{lin}}}(x_i) = T_{\text{lin}}(x_i)$ only for $i = 1$.

1.6 Exercise 6

Let $A \in \mathbb{R}^{n \times m}$ and $b \in \mathbb{R}^m$. Prove using the strong duality theorem of linear optimization that the following statements are equivalent

1. The system $Ax = b$ has a solution $x \leq 0$
2. It holds $b^T d \geq 0$ for all $d \in \mathbb{R}^m$ with $A^T d \leq 0$

we show that 1 is equivalent to $\neg \exists d \in \mathbb{R}^m : Ad \leq 0$ and $b^T d > 0$. Consider the following primal dual

$$\max \quad 0^T x \quad (71)$$

$$\text{s.t.: } Ax = b$$

$$x \geq 0$$

and

$$\min \quad b^T d \quad (72)$$

$$\text{s.t.: } Ad \leq 0$$

$$d \in \mathbb{R}^m$$

$$(73)$$

Consider a solution of $Ax = b$ such that $x \geq 0$. This means that the primal is true, so there exists an optimal solution since $0^T x = 0$ then 0 must be this primal optimal. By the duality 0 must be the optimal of the dual problem, which means $b^T d = 0$ so there is no $d \in \mathbb{R}^m : b^T d > 0$. On the other hand $\neg \exists d \in \mathbb{R}^m : Ad \leq 0$ and $b^T d > 0$ so $\forall d' \in \mathbb{R}^m$ we have that $Ad' > 0$ or $b^T d \leq 0$ such that $b^T d \leq 0$ for all $d \in \mathbb{R}^m$. So we can conclude that there exists a solution because the primal has at least one feasible $x \in \mathbb{R}^m : Ax = b, x \geq 0$. Thereby the two statements above are equivalent.