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ECGR 2254  
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## Project 1 Report

### Problem 1:

a.

To find the current  $I_s$  after the switch closed, first had to convert the inductance to impedance.

$$L = 4.5mH$$

$$\omega = 2\pi 60 \text{ rad/s}$$

$$Z_L = j\omega L = j1.69\Omega$$

After switch closes:

$$Z_{eq} = Z_L + Z_R = 0.1 + j1.69\Omega = 1.69e^{j86.6}\Omega$$

Apply Euler's identity:

$$V_s(t) = 480\sqrt{2}\cos(2\pi 60t - \Phi) \text{ V} = 480\sqrt{2}e^{j2\pi 60t}e^{-j\Phi}$$

$$I_s(0^-) = \frac{V_s(0^-)}{Z_{eq}} = 400e^{j\Phi} \text{ A}$$

$$\rightarrow A = 400$$

b.

$$L = 4.5 \text{ mH}$$

$$R = 0.1\Omega$$

$$V_s = 480\sqrt{2}\cos(2\pi 60t - \Phi)$$

Apply KCL:

$$V_s - V_R - V_L = 0$$

$$V_R = I * R$$

$$V_L = L \frac{di}{dt}$$

$$\rightarrow L \frac{di}{dt} + IR = V_s \text{ divide both sides by L}$$

$$\frac{di}{dt} + \frac{R}{L}I = \frac{V_s}{L}$$

c.

Transient:

$$i(t) = ce^{st}, s = -22.22$$

$$\tau = \frac{-1}{s} = \frac{1}{22.2}$$

Steady State:

$$\omega = 2\pi 60$$

$$T = \frac{2\pi}{\omega} = \frac{1}{60}$$

$$\Delta t \ll \frac{T}{100} \text{ and } \Delta t \ll \frac{5\tau}{100}$$

$$\frac{T}{100} < \frac{5\tau}{100}$$

$$\rightarrow \Delta t = \frac{T}{100} = \frac{1}{6000}$$

d.

clear all

y\_0 = 0;

tau = 0.045;

T = 1/60;

delta\_t = T/100;

A = 6788; %starting voltage divided by resistance of 0.1

omega = 2 \* pi \* 60;

phi = 87.5 \* pi/180;

a = tau/delta\_t;

t = [0:delta\_t:1];

y = zeros(size(t));

x = A \* cos(omega \* t - phi);

%x = A \* exp(j\*omega\*t)\*exp(-j\*phi);

for n = 1:length(t)-1

    if n == 1

        y(1) = y\_0;

        y(n+1) = ((x(n))-y(n)+a\*y(n))/a;

    else

        y(n+1) = ((x(n))-y(n)+a\*y(n))/a;

    end

end

figure(1);

plot(t,y);

To find the value of  $\Phi$  that gave the largest value after  $t = 0$ , I started by using generic values such as 0, 45, 90, 135, and 180. Using these values, I found that  $\Phi = 90$  gave the largest value, so I tried to break it down and use numbers close to 90 to see if I could find the  $\Phi$  value that gave the absolute largest value after  $t = 0$ . Doing so, I found that  $\Phi = 87.5$  gave the value of 733.737, which was the largest value after  $t = 0$ .

e.

$$L = 4.5 \text{ mH}$$

$$R_s = 0.1 \Omega$$

$$R_s = 23.04 \Omega$$

$$V_s = 480\sqrt{2}e^{j2\pi 60}e^{j\Phi} \text{ V}$$

$$Z_L = j\omega L = j1.69$$

$$Z = 23.14 + j1.69 \Omega = 23.2e^{j4.18}$$

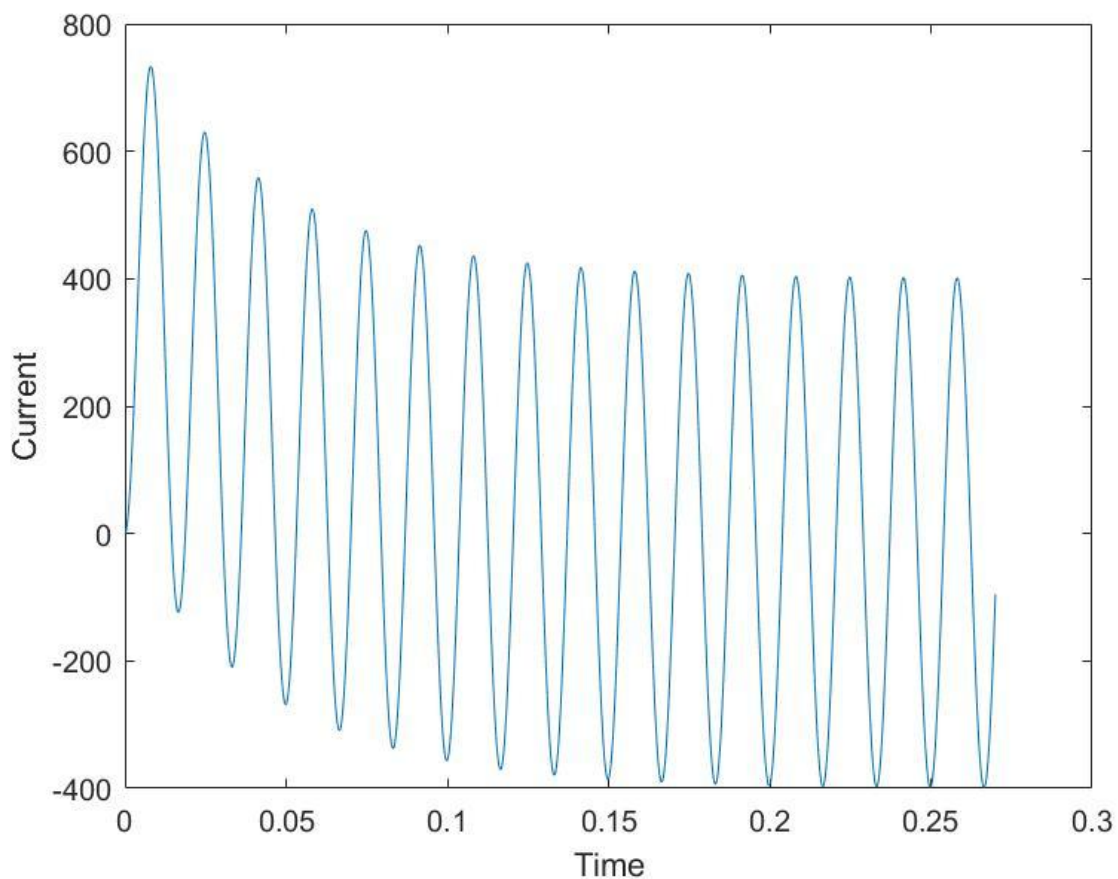
$$I_s(0-) = \frac{V_s}{Z} = 29.26e^{j\Phi} = 29.29\cos(2\pi 60t - \Phi) \text{ A}$$

Plug in  $t = 0$  and  $\Phi = 87.5$

$$29.26\cos(-87.5) = 1.276 \text{ A}$$

f.

After plugging in  $y_0 = 1.276 \text{ A}$ , the current peaked at 734.805 A.



**Problem 2:**

a.

To find the current  $I_s$  after the switch opened, first had to convert the inductance to impedance.

$$L = 2.65 \text{ mH}$$

$$\omega = 2\pi 60 \text{ rad/s}$$

$$Z_L = j\omega L = j0.999\Omega$$

$$R_{eq} = 144\Omega || 7.2\Omega = 6.86\Omega = Z_R$$

$$Z_{eq} = Z_L + Z_R = 6.86 + j0.999\Omega = 6.93e^{j8.28^\circ}\Omega$$

Apply Euler's identity to  $V_s(t)$  :

$$V_s(t) = 120\sqrt{2}\cos(2\pi 60t) = 120\sqrt{2}e^{j2\pi 60t}$$

$$i_s(t) = \frac{V_s(t)}{Z_{eq}} = 24.48e^{j2\pi 60t} e^{-j8.28^\circ} \text{ A} = 24.48\cos(2\pi 60t - 8.28^\circ) \text{ A}$$

$$\rightarrow i_s(0^-) = 24.48\cos(2\pi 60(0) - 8.28^\circ) \text{ A} = 24.22 \text{ A}$$

b.

$$L = 2.65 \text{ mH}$$

$$R = 144\Omega$$

$$V_s = 120\sqrt{2}\cos(2\pi 60t)$$

Apply KCL:

$$V_s - V_R - V_L = 0$$

$$V_R = I * R$$

$$V_L = L \frac{di}{dt}$$

$$\rightarrow L \frac{di}{dt} + IR = V_s \text{ divide both sides by } L$$

$$\frac{di}{dt} + \frac{R}{L}I = \frac{V_s}{L}$$

C.

Transient:

$$i(t) = ce^{\frac{-t}{\tau}}$$

$$C = 24.22$$

$$\tau = \frac{L}{R} = 1.84e-5$$

Steady State:

$$\omega = 2\pi 60$$

$$T = \frac{2\pi}{\omega} = \frac{1}{60}$$

$$\Delta t \ll T \text{ and } \Delta t \ll \tau$$

$$\text{Check } \frac{T}{100} \text{ and } \frac{5\tau}{100}$$

$$\frac{T}{100} > \frac{5\tau}{100}$$

$$\rightarrow \Delta t = \frac{5\tau}{100} = 9.2 * 10^{-7}$$

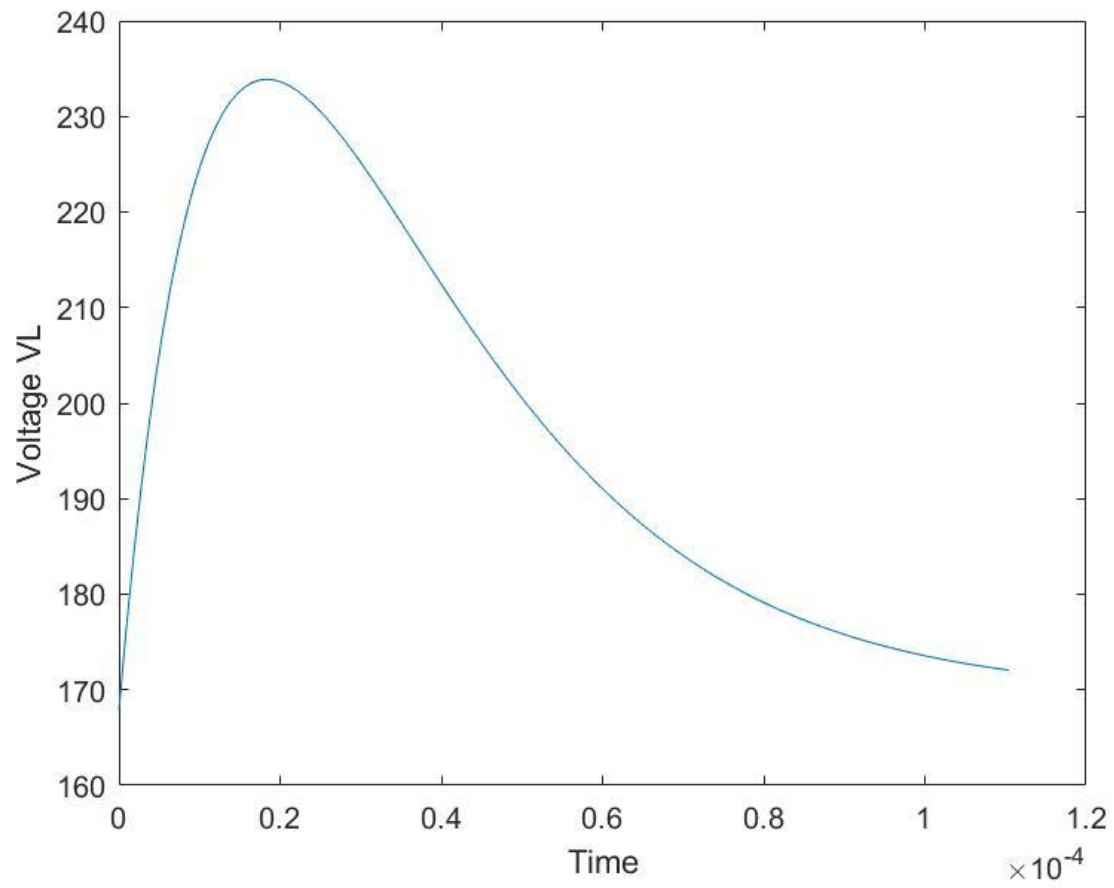
**d.**

```
clear all
y_0 = 167.9;%VL(0-)
abs(y_0);
angle(y_0)*180/pi;
R = 144;%ohms
L = 0.00265;%mH
tau = L/R;
T = 1/60;
delta_t = 5*tau/100;% < T/100
phi = 0;
A = 1.1785;%mag of i for t>0
omega = 2 * pi * 60;
a = tau/delta_t;%used to discretize diff eq
Z = 144 + j*0.999;%impedence after switch opens

%particular sol
t = [0:delta_t:6*tau];
yp = zeros(size(t));
x = R * (A * cos(omega * t - phi*pi/180) + 1.1785*exp(-t/tau));%multiply by R to get VL
for n = 1:1:length(t)-1
    if n == 1
        yp(1) = y_0;
        yp(n+1) = ((x(n))-yp(n)+a*yp(n))/a;
    else
        yp(n+1) = ((x(n))-yp(n)+a*yp(n))/a;
    end
end
figure(1);
plot(t,yp);
xlabel('Time');
ylabel('Voltage VL');
```

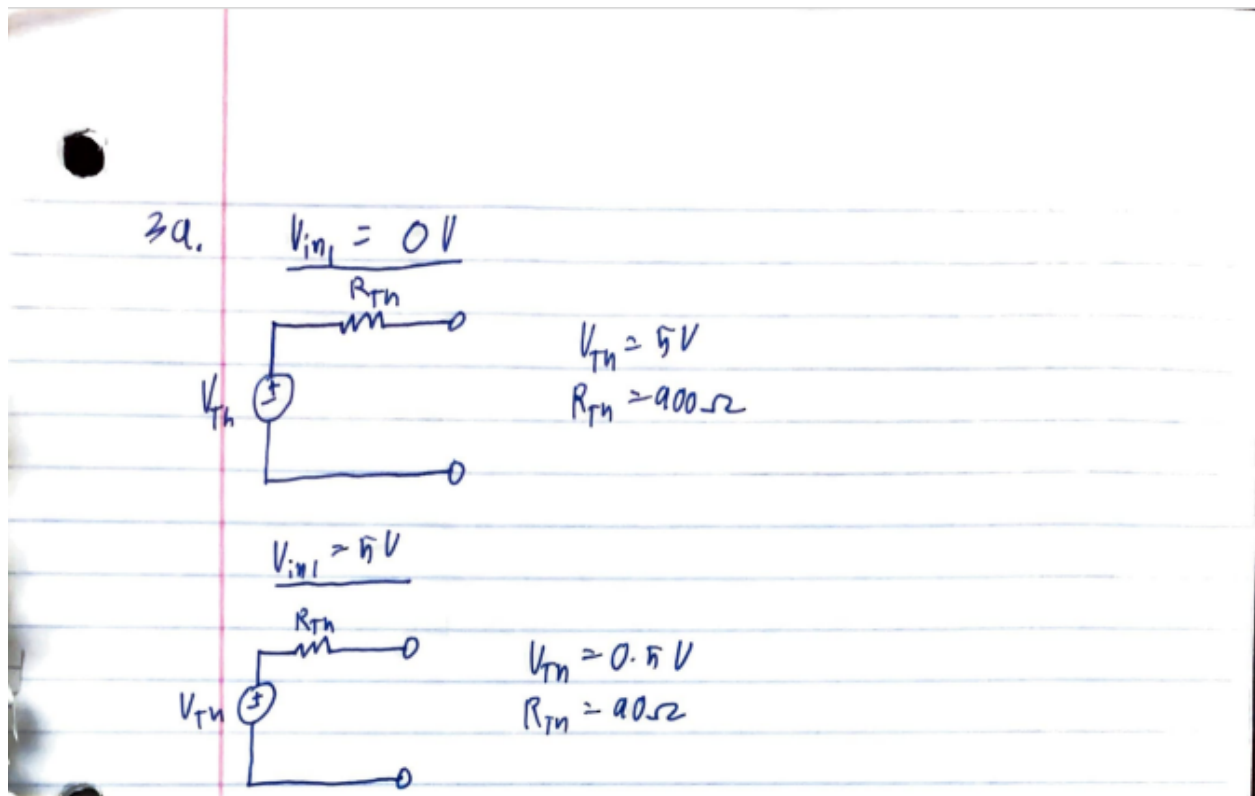
e.

The maximum value of the voltage was approximately 233.8 volts.



### Problem 3:

A.



b.

- $V_{th} = 5V$ .

Since the circuit is an open circuit, there is no current flowing which means the voltage on the node for  $V_{th}$  would remain 5.

- $R_{th} = 900\Omega$

Since there is no current, the two resistors are not connected in series or parallel so  $R_{th}$  would be the value of the load resistor.

- $V_{out1} \cong 5V$

Assuming the circuit has been in its state for a long time, most of the voltage would be absorbed in the capacitor and the inductor, which is what  $V_{out1}$  consists of.

- $V_{in2} \cong 5V$

The same value as  $V_{out1}$ . It is safe to assume most of the voltage was absorbed in the capacitor which gives the voltage for  $V_{in2}$ .

- $I_L \cong 0A$

If the circuit has been in the same state for a long time, most of the voltage would have been absorbed in the capacitor which would slow down the flow of the current.

c.

$$L = 100nH$$

$$C_{GS2} = 0.1pF$$

$$R_L = 900\Omega$$

$$R_{on} = 100\Omega$$

Apply KCL:

$$V_{th} - V_R - V_L - V_c = 0$$

$$\rightarrow V_R + V_L + V_c = V_{th}$$

$$V_R = i(t) * R$$

$$V_L = L * \frac{di(t)}{dt}$$

$$V_c = \frac{1}{C} \int i(t) dt$$

$$\rightarrow i(t)R + L \frac{di(t)}{dt} + \frac{1}{C} \int i(t) dt = V_{th}$$

$$\text{Sub } i(t) = C \frac{dv_c(t)}{dt}$$

$$C \frac{dv_c(t)}{dt} R + L \frac{dC \frac{dv_c(t)}{dt}}{dt} + \frac{1}{C} \int C \frac{dv_c(t)}{dt} dt = V_{th}$$

$$\rightarrow LC \frac{d^2 v_c(t)}{dt^2} + RC \frac{dv_c(t)}{dt} + V_c(t) = V_{th}$$

Divide by LC

$$\rightarrow \frac{d^2 v_c(t)}{dt^2} + \frac{R}{L} \frac{dv_c(t)}{dt} + \frac{1}{LC} V_c(t) = \frac{V_{th}}{LC}$$

- $V_{in2}(0) \cong 0V$

The value of  $V_{in1}$  jumping to 5V makes  $V_{in2}$  and  $V_{out1}$  approximately equal to 0.



- $\frac{dv_{in}(0)}{dt} \cong \infty$

The value of  $V_{in1}$  instantaneously jumped to 5V at  $t = 0$ , which means the rate of change was nearly infinite.

- $V_{th} = 0.5V$

Since the switch closed, current would be flowing and 4.5v would be absorbed by the 900  $\Omega$  resistor, leaving 0.5V.

- $R_{th} = 90\Omega$

The switch closing creates a parallel relationship between the two capacitors, which when combined yield an equivalent resistance of 90 $\Omega$ .

d.

Transient

Assume  $v(t) = ce^{st}$

$$v'(t) = sce^{st}$$

$$v''(t) = s^2 ce^{st}$$

$$s^2 ce^{st} + \frac{R}{L} sce^{st} + \frac{1}{LC} ce^{st} = 0$$

$$s = (-4.5 \pm j * 8.93) * 10^9$$

$$\tau = \frac{1}{4.5 * 10^9} = 2.2 * 10^{-10}$$

$$\omega_d = 8.93 * 10^9$$

$$T = \frac{2\pi}{\omega_d} = 7.03 * 10^{-10}$$

$$\Delta t \ll T \text{ and } \Delta t \ll 5\tau$$

$$\frac{T}{100} < \frac{5\tau}{100}$$

Therefore,  $\Delta t = \frac{T}{100} = 7.04 * 10^{-12}$

e.

```
clear all
```

```
%values of circuit elements
```

```
R = 900;
```

```
C = 0.1 * 10^(-12);
```

```
L = 100 * 10^(-9);
```

```
%initial voltage
```

```
y_0 = 0;
```

```
y_prime_0 = 0;
```

```
%variables for diff eq
```

```
b = R/L;
```

```
c = 1/(L*C);
```

```
s = roots([1 b c]);
```

```
tau = -1/real(s(1))%time constant
```

```
omega_d = imag(s(1))%damping coeff
```

```
T_d = 2*pi/omega_d;%period
```

```
delta_t = T_d/100;%delta t to discretize
```

```
t = [0:delta_t:10*T_d];
```

```
y1 = zeros(size(t));
```

```
y2 = zeros(size(t));
```

```
x = ones(size(t));
```

```
for n = 1:length(t)-1
```

```
    if n == 1
```

```
        y1(1) = y_0;
```

```
        y2(1) = y_prime_0;
```

```
    end
```

```
    y1(n+1) = y1(n) + delta_t*y2(n);
```

```
    y2(n+1) = delta_t*(x(n) - b*y2(n) -c*y1(n))+y2(n);
```

```
end
```

```
figure(1);
```

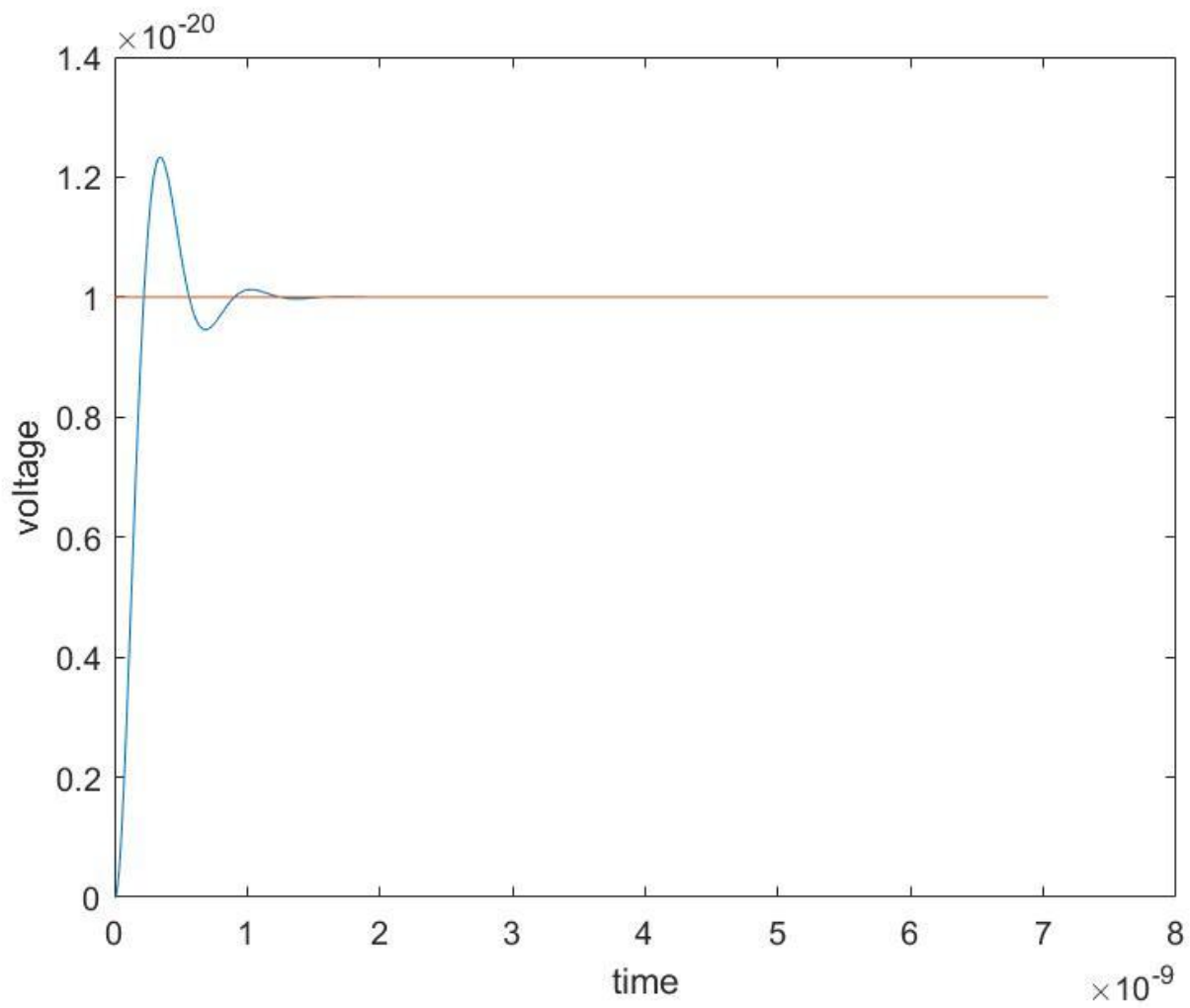
```
plot(t,y1,t,(1/c)*ones(size(t)));
```

```
xlabel('time')
```

```
ylabel('voltage')
```

f.

It took  $v(t)$  until time  $t \cong 2.6 \cdot 10^{-9}$  s to become reliably less than 1V.



**Problem 4:****a.**

$$x_{out}(t) = x(t)\cos(2\pi ft)$$

$$x(t) = x_{audio}(t)\cos(2\pi ft)$$

Sub  $x(t)$  into  $x_{out}(t)$

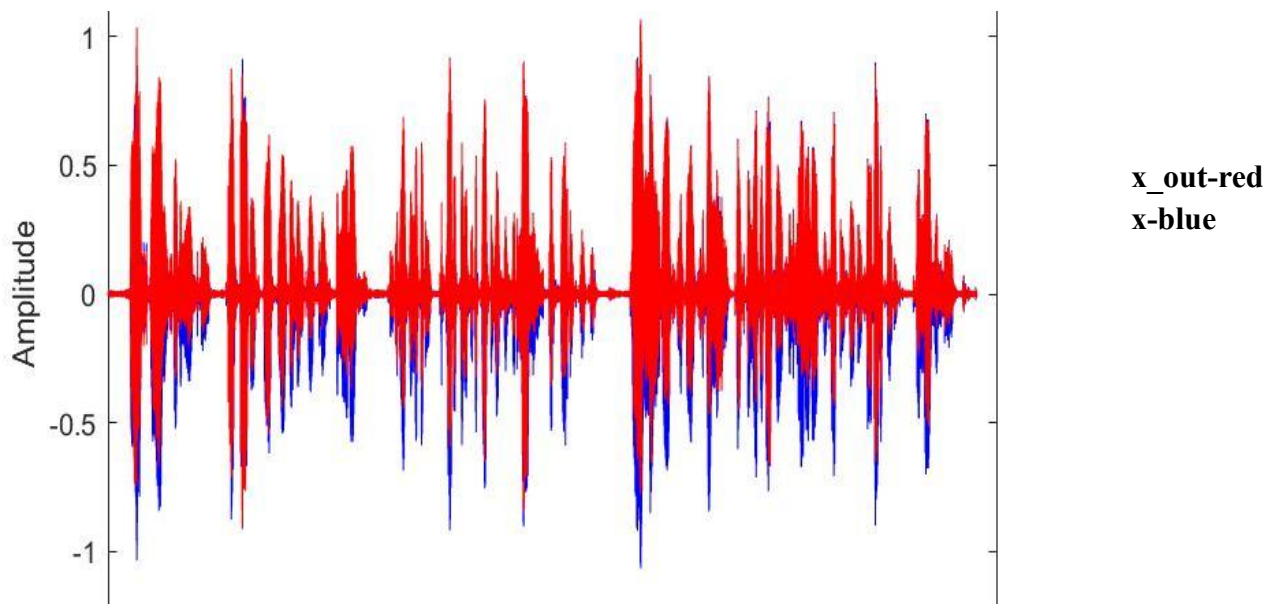
$$x_{out}(t) = x_{audio}(t)\cos^2(2\pi ft)$$

Use trig identity:  $\cos^2(x) = \frac{1}{2}(1 + \cos(2x))$

$$\rightarrow x_{out}(t) = \frac{1}{2}(x_{audio}(t)(1 + \cos(4\pi ft)))$$

**b.**

Zooming in on the graph, it was clear that  $x_{out}$  had a higher frequency. This makes sense, as in part a,  $x_{out}$  was in terms of  $\cos(4\pi ft)$ , which would effectively double the frequency compared to  $x$ , which was in terms of  $\cos(2\pi ft)$ .



**c.**

*Start by using KVL on left hand loop*

$$x_{out}(t) = V_L + V_C$$

$$\text{Sub } V_L = L \frac{di_L(t)}{dt}$$

*Apply KCL at node*

$$i_c = i_L - i_R$$

$$\text{Sub } i_R(t) = \frac{V_C(t)}{R}$$

$$\text{Sub } i_c = C \frac{dV_c(t)}{dt}$$

*Solve for  $i_L$*

$$i_L = C \frac{dV_c(t)}{dt} + \frac{V_c(t)}{R}$$

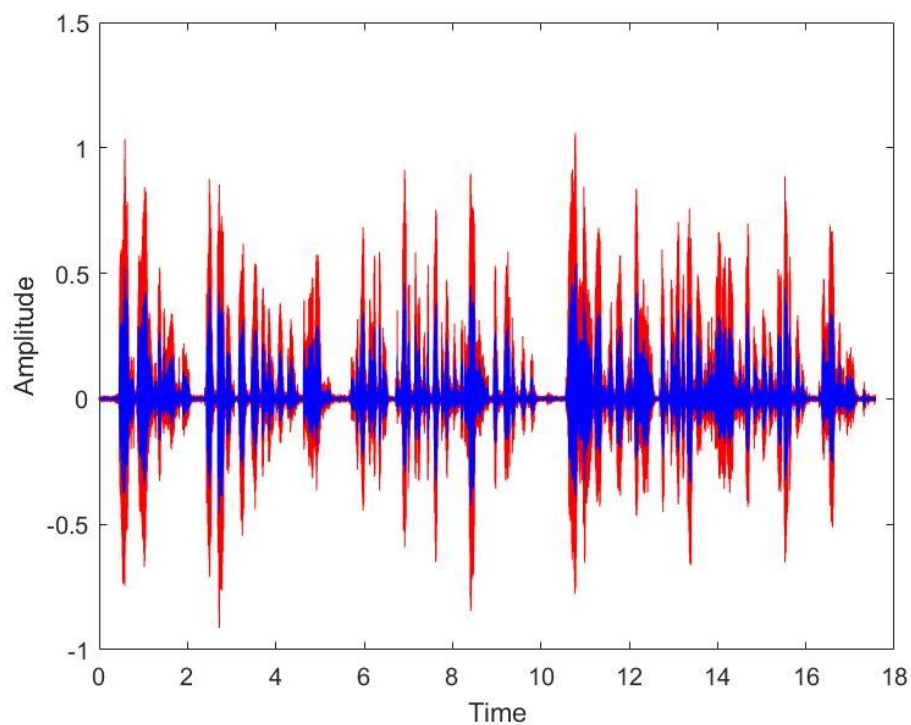
*Sub  $i_L$  into KVL equation*

$$x_{out}(t) = L \frac{d}{dt} \left( C \frac{dV_c(t)}{dt} + \frac{V_c(t)}{R} \right) + V_C$$

$$x_{out}(t) = LC \frac{d^2 V_c(t)}{dt^2} + \frac{L}{R} \frac{dV_c(t)}{dt} + V_C$$

*Divide by LC*

$$\frac{x_{out}(t)}{LC} = \frac{d^2 V_c(t)}{dt^2} + \frac{1}{RC} \frac{dV_c(t)}{dt} + \frac{1}{LC} V_c(t)$$



**X\_out-red**  
**y-blue**

**d.**

clear all

%define variables

fileID = fopen('problem4.bin','r');

x = fread(fileID, 'single');

fclose(fileID);

f = 50\*10<sup>3</sup>; %frequency

f\_samp = 2.205 \* 10<sup>6</sup>; %frequency of sample

delta\_t = 1/f\_samp;

endpt = (size(x)-1) \* delta\_t; %end of time vector

%create time vector and x\_out

t = [0:delta\_t:endpt];

t = transpose(t); %t same dim as x and demodulator

demod = cos(2\*pi\*f\*t);

x\_out = x .\* demod; %V source for low pass filter

%plots for x and x\_out

plot(t,x,'b')

hold on

plot(t,x\_out,'r')

hold off

%values for low pass filter

L = 253.3\*10<sup>-6</sup>; %henry

C = 1\*10<sup>-6</sup>; %farad

R = 11.254; %ohms

b = 1/(R\*C);

c = 1/(L\*C);

```

y_0 = 0;
y_prime_0 = 0;
y1 = zeros(size(t));
y2 = zeros(size(t));
%x = ones(size(t));

%discretized diff eq for low pass filter
for n = 1:length(t)-1
    if n == 1
        y1(1) = y_0;
        y2(1) = y_prime_0;
    end
    y1(n+1) = y1(n) + delta_t*y2(n);
    y2(n+1) = delta_t*(c*x_out(n) - b*y2(n) -c*y1(n))+y2(n);
end

%plot comparing y(t) to x_out
figure(1);
plot(t,x_out,'r')
hold on
plot(t,y1, 'b');
hold off

%used to play sample
x_audio = downsample(y1,100);
%sound(x_audio,22.05e3);
%sound(downsample(x_out,100),22.05e3);

```

The downsampled version of `x_out` sounded a lot less clear and had somewhat of a high pitched echo present. This is because `x_out` did not go through the low pass filter, which allowed the higher frequencies to be played which made it sound less clear and more high pitched. When tampering with the frequency by even the slightest bit, it made the audio sound completely distorted and unlegible.

**Problem 5:****a.**

We needed an  $x_3(t)$  that when multiplied by  $x(t)$ , left  $x_{aud}(t)$  alone.

$$x(t) = x_{aud}(t)e^{j2\pi ft}$$

$$\text{Need } x_{out}(t) = x_{aud}(t)$$

$$x_{out}(t) = x_3(t)x(t) = x_3(t)x_{aud}(t)e^{j2\pi ft}$$

$$x_{aud}(t) = x_3(t)x_{aud}(t)e^{j2\pi ft}$$

$$x_3(t) = e^{-j2\pi ft}$$

**b.**

clear all

%define variables

fileID = fopen('problem5.bin','r');

x\_in = fread(fileID, 'single');

fclose(fileID);

f = 50\*10<sup>3</sup>; %frequency

f\_samp = 2.205 \* 10<sup>6</sup>; %frequency of sample

delta\_t = 1/f\_samp;

%index variables

index = 0;

%create x vector

for n = 1:1:length(x\_in)/2

    x(n) = x\_in(n+index)+j\*x\_in(n+index+1);

    index = index + 1;

end

x = transpose(x);

%%end of part b



**c.**

clear all

%define variables

fileID = fopen('problem5.bin','r');

x\_in = fread(fileID, 'single');

fclose(fileID);

f = 50\*10<sup>3</sup>; %frequency

f\_samp = 2.205 \* 10<sup>6</sup>; %frequency of sample

delta\_t = 1/f\_samp;

%index variables

index = 0;

%create x vector

for n = 1:1:length(x\_in)/2

    x(n) = x\_in(n+index)+j\*x\_in(n+index+1);

    index = index + 1;

end

x = transpose(x);

%%end of part b

%create time vector

endpt = (length(x)-1) \* delta\_t; %end of time vector

t = [0:delta\_t:endpt];

t = transpose(t);

x\_3 = exp(-j\*2\*pi\*f\*t); %x3 vector

%x\_out vectors

x\_out = x .\* x\_3;

x\_real = real(x\_out);

x\_imag = imag(x\_out);

x\_audio = downsample(x\_real,100);

x\_audio2 = downsample(x\_imag,100);

%sound(x\_audio,22.05e3);

sound(x\_audio2,22.05e3);

