



# Domain-Constrained Diffusion Models to Synthesize Tabular Data: A Case Study in Power Systems



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## Motivation

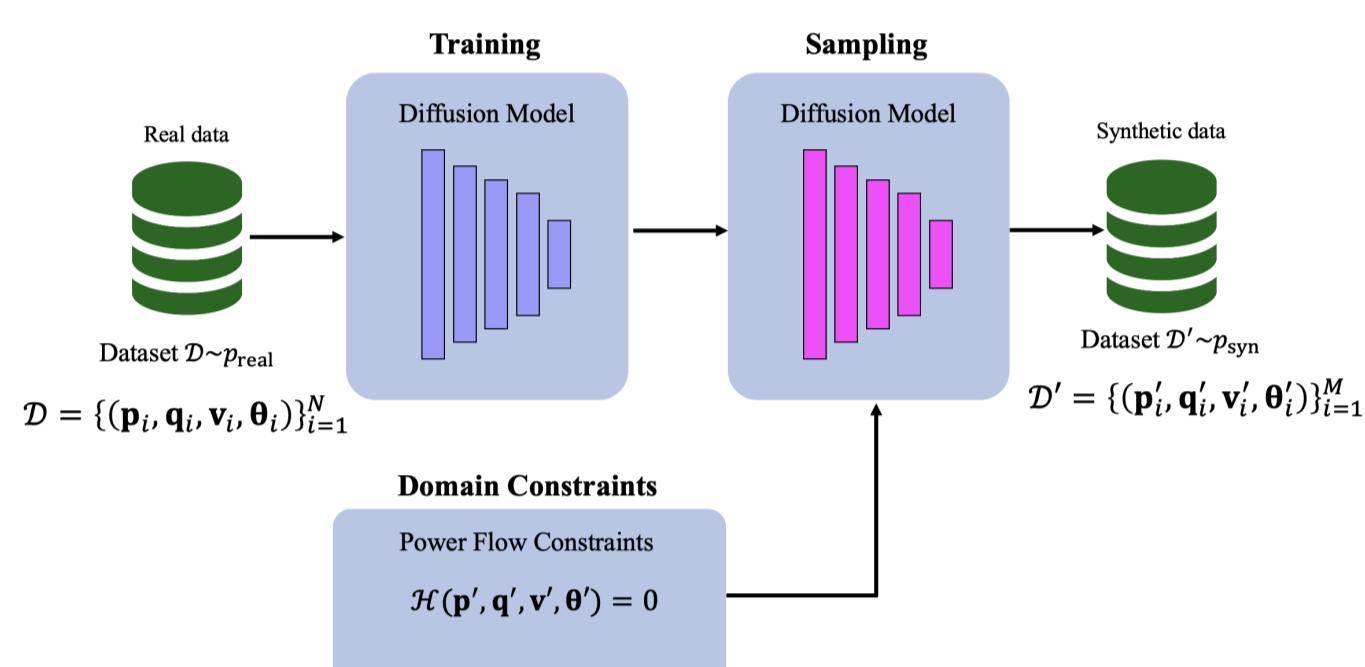
- Access to real-world data is often limited due to **privacy, security, and legal barriers**, hindering the training of Machine Learning (ML) models across domains.

A synthetic dataset is artificially generated data that enjoys the statistical properties of real-world data without containing any actual records.

- High-quality synthetic data must go beyond **statistics** by adhering to **domain-specific constraints** that ensure real-world feasibility.

## Problem Setup

**Goal:** Given a dataset including real power flow data points, we aim to synthesize (1) **statistically representative** and (2) **high fidelity** power flow data points:



A high-level view of the problem setup.

## Diffusion Models

- Forward** diffusion process gradually adds noise to input:

$$\mathbf{x}_t = \sqrt{\bar{\alpha}_t} \mathbf{x}_0 + \sqrt{1 - \bar{\alpha}_t} \epsilon_t, \quad \epsilon_t \sim \mathcal{N}(0, \mathbb{I}), t \in (0, T].$$

- Reverse** diffusion process learns to generate data by denoising:

$$\mathbf{x}_{t-1} = \mu_\theta(\mathbf{x}_t, t) + \sigma_t \epsilon_t, \quad \epsilon_t \sim \mathcal{N}(0, \mathbb{I}), t \in (T, 0].$$

- Training:** The loss function to train the denoiser neural network:

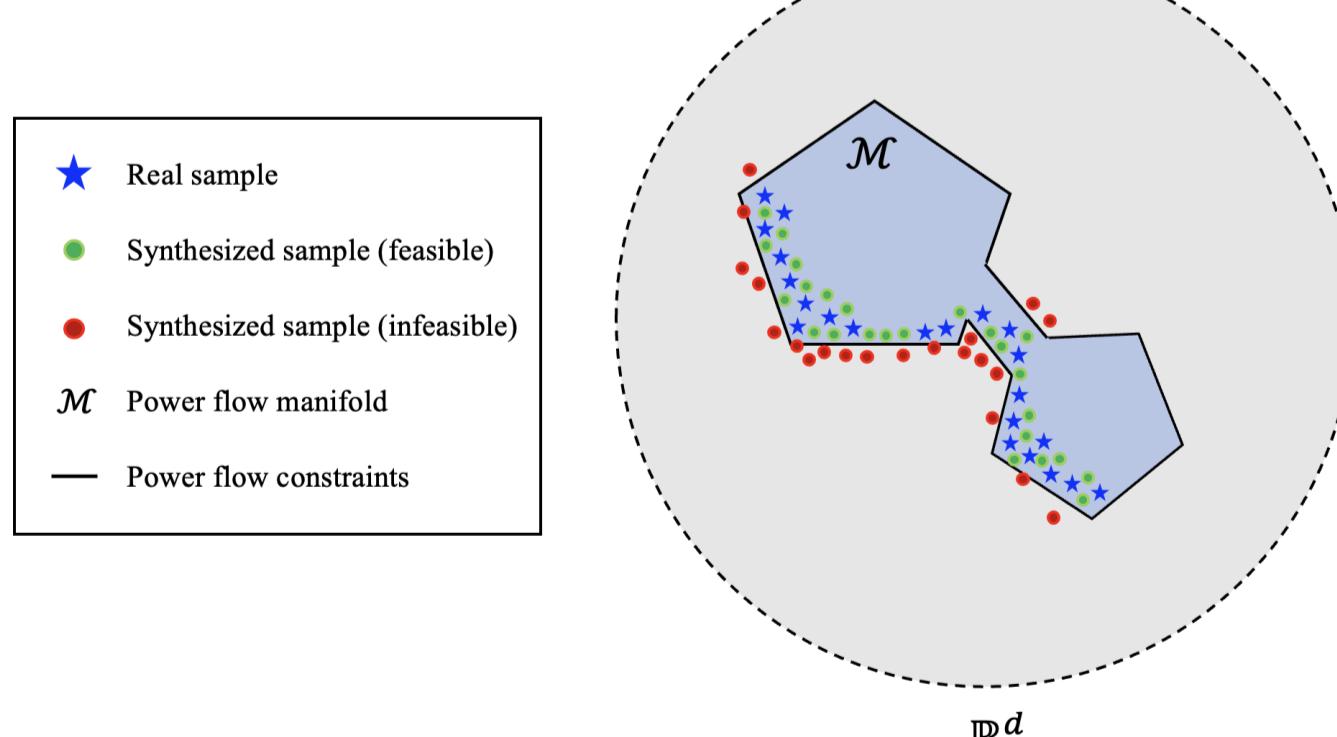
$$\mathcal{L}_{\text{diff}} = \mathbb{E}_{\mathbf{x}_0, \epsilon, t} [\|\epsilon - \epsilon_\theta(\mathbf{x}_t, t)\|^2].$$

- Sampling:**

$$\mathbf{x}_{t-1} = \frac{\sqrt{\bar{\alpha}_t}(1 - \bar{\alpha}_{t-1})}{1 - \bar{\alpha}_t} \mathbf{x}_t + \frac{\sqrt{\bar{\alpha}_{t-1}} \beta_t}{1 - \bar{\alpha}_t} \hat{\mathbf{x}}_0 + \sigma_t z, \quad z \sim \mathcal{N}(0, \mathbb{I}), t \in [T, 0].$$

## Diffusion Guidance based on Power Flow Constraints

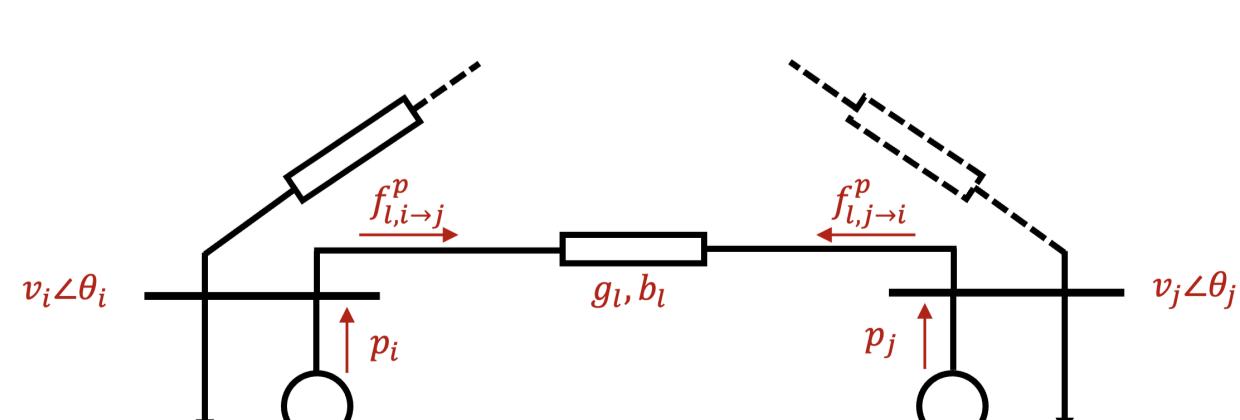
- In practice, a diffusion model may generate power flow data points that are **infeasible** due to **learning** and **sampling** errors.



- Active and reactive power balance constraints:

$$p_b - \sum_{l \in \mathcal{L}: i=b} f_{l,i \rightarrow j}^p - \sum_{l \in \mathcal{L}: j=b} f_{l,j \rightarrow i}^p = 0, \quad \forall b \in \mathcal{B}$$

$$q_b - \sum_{l \in \mathcal{L}: i=b} f_{l,i \rightarrow j}^q - \sum_{l \in \mathcal{L}: j=b} f_{l,j \rightarrow i}^q = 0, \quad \forall b \in \mathcal{B}$$



How can we enforce power flow constraints in generated samples?

- Our goal is to minimize the data consistency loss  $R_{\mathcal{H}}(\mathbf{x})$  on the clean data manifold  $\mathcal{M}$ :

$$\min_{\mathbf{x} \in \mathcal{M}} R_{\mathcal{H}}(\mathbf{x}),$$

where  $\mathcal{H}(\cdot)$  encodes the equality constraints and

$$R_{\mathcal{H}}(\mathbf{x}) = \|\mathcal{H}(\mathbf{x})\|_2^2.$$

- We take one step of Riemannian gradient descent on  $\mathcal{M}$ :

$$\hat{\mathbf{x}}'_{0|t} = \hat{\mathbf{x}}_{0|t} - \tau_t \operatorname{grad} R_{\mathcal{H}}(\hat{\mathbf{x}}_{0|t}),$$

where

$$\operatorname{grad} R_{\mathcal{H}}(\hat{\mathbf{x}}_{0|t}) = \mathcal{P}_{T_{\hat{\mathbf{x}}_{0|t}} \mathcal{M}} (\nabla_{\mathbf{x}_t} R_{\mathcal{H}}(\hat{\mathbf{x}}_{0|t})).$$

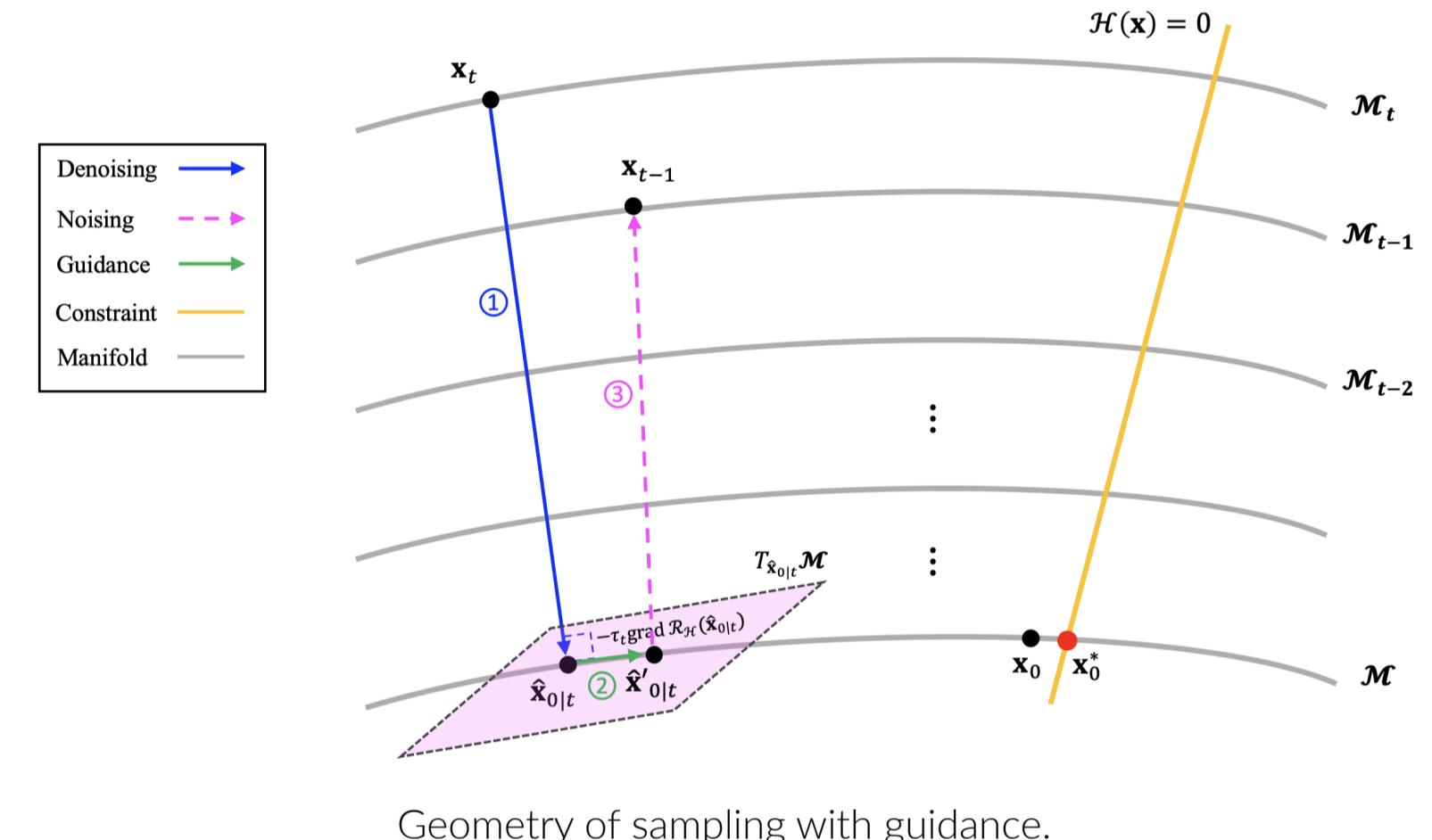
- Under affine subspace assumption of clean data manifold  $\mathcal{M}$ , we can prove:

$$\mathcal{P}_{T_{\hat{\mathbf{x}}_{0|t}} \mathcal{M}} (\nabla_{\mathbf{x}_t} R_{\mathcal{H}}(\hat{\mathbf{x}}_{0|t})) \approx \nabla_{\mathbf{x}_t} R_{\mathcal{H}}(\hat{\mathbf{x}}_{0|t}).$$

$$\hat{\mathbf{x}}'_{0|t} = \hat{\mathbf{x}}_{0|t} - \lambda_t \nabla_{\mathbf{x}_t} R_{\mathcal{H}}(\hat{\mathbf{x}}_{0|t}).$$

Sampling steps can be characterized as transitions from  $\mathcal{M}_t$  to  $\mathcal{M}_{t-1}$ :

- (1) we do a denoising step based on  $\mathbf{x}_t$  and estimate the clean data  $\hat{\mathbf{x}}_0$ ,
- (2) add the gradient guidance term,
- (3) add noise w.r.t. the corresponding noise schedule and obtain  $\mathbf{x}_{t-1}$ .

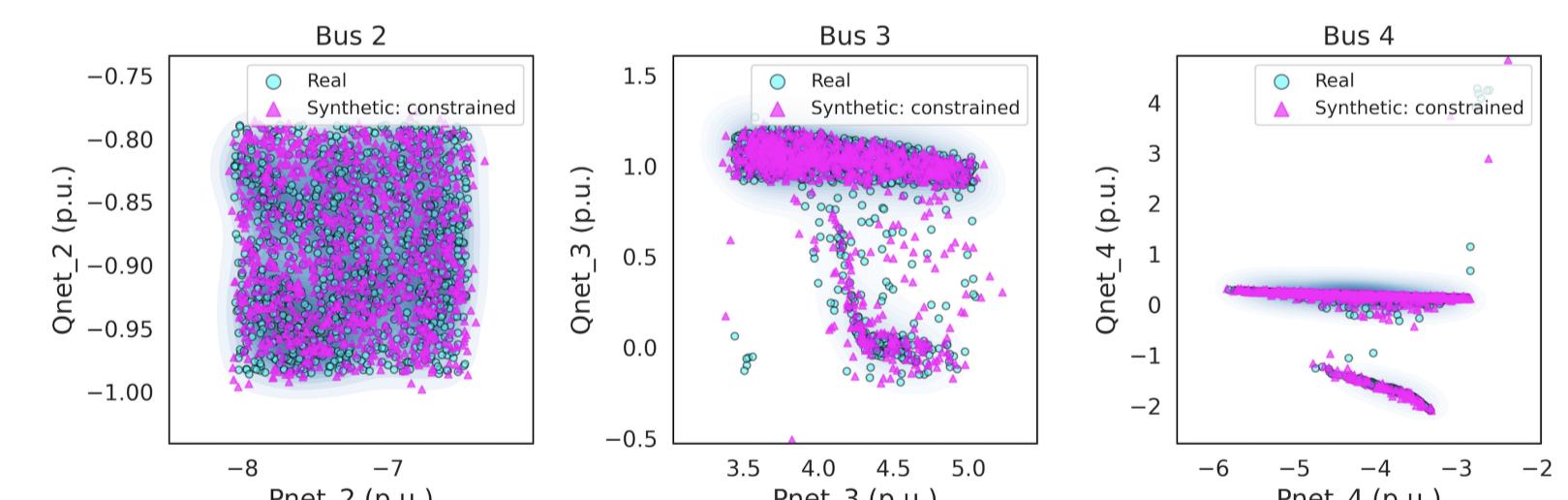


Geometry of sampling with guidance.

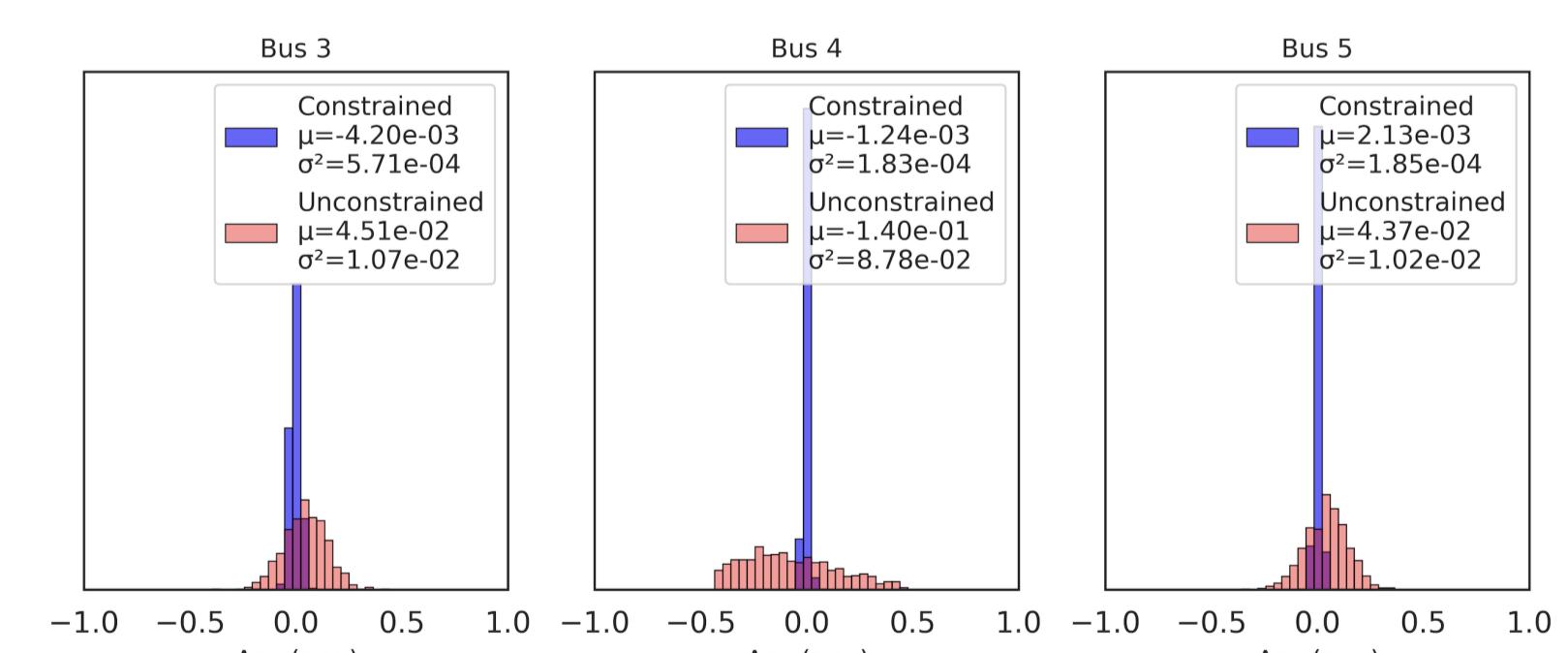
## Results

**Test System:** PJM 5-BUS System

- Distribution Matching: joint distribution



- Histograms of violation magnitude for active power balance constraints



## Conclusion

- Synthesized power flow data points effectively capture the **pattern, domain, and modes** of underlying distributions of the real data.
- The proposed **gradient guidance** approach successfully enforces power flow constraints during sampling, ensuring the feasibility of the generated data.