

# Factorial Design Analysis for Distance Optimization

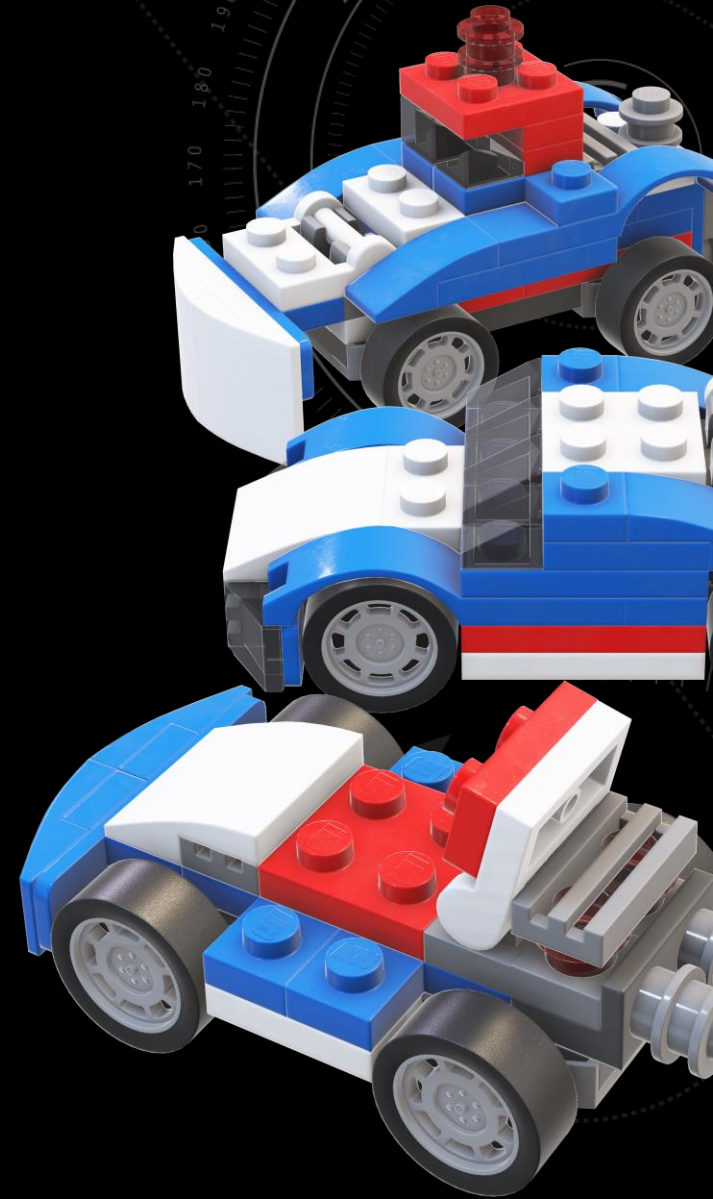
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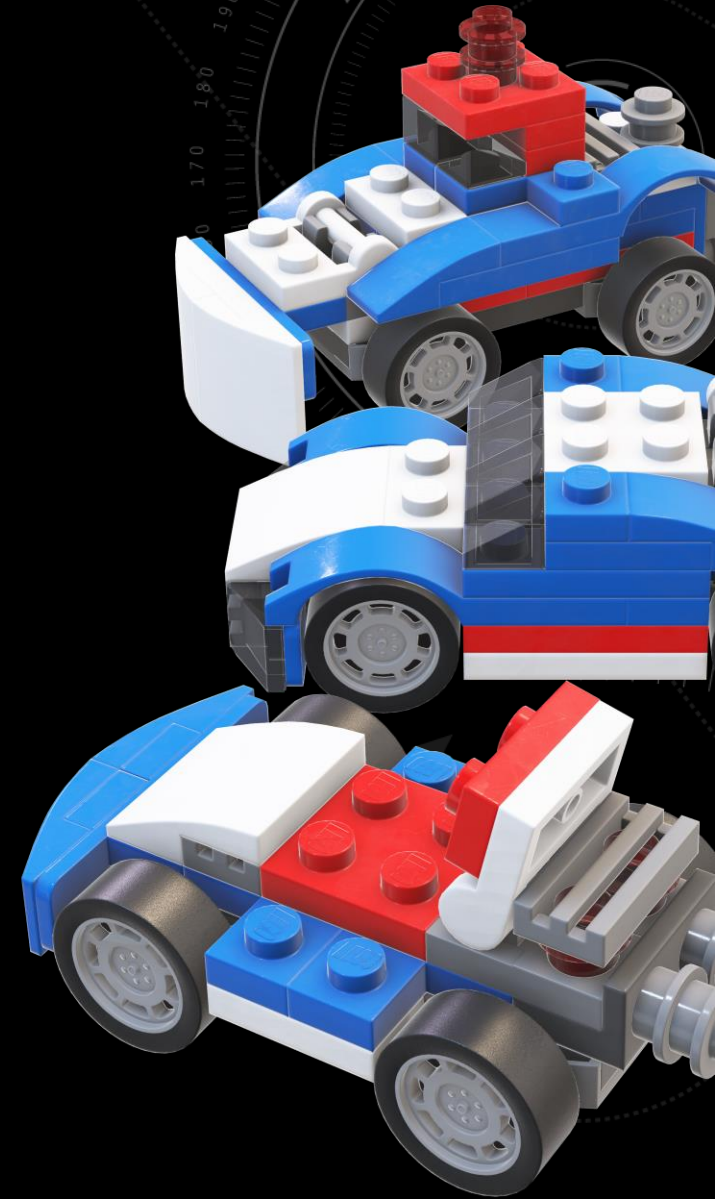
# Define – Objectives & Goals

Identify the most  
significant  
factors affecting  
distance



# Define – Objectives & Goals

Optimize the  
response variable  
(distance)  
through factorial  
design



# Define – Objectives & Goals

**Removing or  
optimizing factors  
with low impact  
based on analysis**





# Measure – Methodology

**Factorial Design**

**Factors: A, B, C, D, E**

**Levels: +1 & -1**

**Response variable:**

**Distance (inches)**



# Measure – Methodology

**Data analysis**

**Used coded  
coefficients to  
determine effects**

# Measure – Methodology

**Iterative Refinement**  
Removed significant  
factors or  
interactions  
Observed changes in  
R-square and model  
accuracy

# Measure – Factors & Rationale

## Factors:

A (wheel size)

+1 Large Wheels

-1 Small Wheels

B (Length of the car)

+1 Long car

-1 Long car

C (Width of the car)

+1 Wide

-1 Narrow

D (amount of wheels)

+1 6 wheels

-1 4 wheels

E (Center of gravity)

+1 weight in the back

-1 weight in the front

Total observations:

$$2^5 = 32$$

## Thought process behind selections

1. A (Wheel size)

The thought process behind the size of the wheel is to determine if the weight of the wheels has an affect on the distance traveled.

2. B (Length of the car)

The thought process behind this is the stability of the car. Shorter cars were causing the car to drift at an earlier time

3. C (Width of the car)

The thought process behind this is also the stability of the car. Or in other words the center of gravity, a wider car was more stable.

4. D (Amount of wheels)

The thought process behind this is rolling resistance. Increasing the amount of wheels also increases the contacts with the surface and that gave a result in a higher rolling resistance (not in all cases)

5. E (Center of gravity)

Distributing the weight in certain areas in the car can cause a variation of effects on speed.



# Measure – Controlling Noise

## Consistent Ramp Setup:

We ensured the ramp height (18 inches), Length (40 inches) and angle were constant throughout all the trials

## Surface Consistency:

Conducted all trials on the same smooth surface to minimize variation in friction

## Randomization:

Ran the trials in a random order as provided by Minitab to prevent systematic bias from creeping into the experiment

## Controlled Environment:

Ensured the experiment was conducted indoors to avoid external factors like wind or uneven lighting affecting measurements.

## Consistent Release Technique:

Used the same released method (aligned the car and let go without push) to standardize the start point and initial force



# Measure – Experimental Setup (visuals)



**Height of the chair is 18 inches**

**Length of the ramp (slope) is 40 inches**



**The above images visually show and explain the controlled setup and the noise blocking**

# Analyze - Experimental Results & Insights

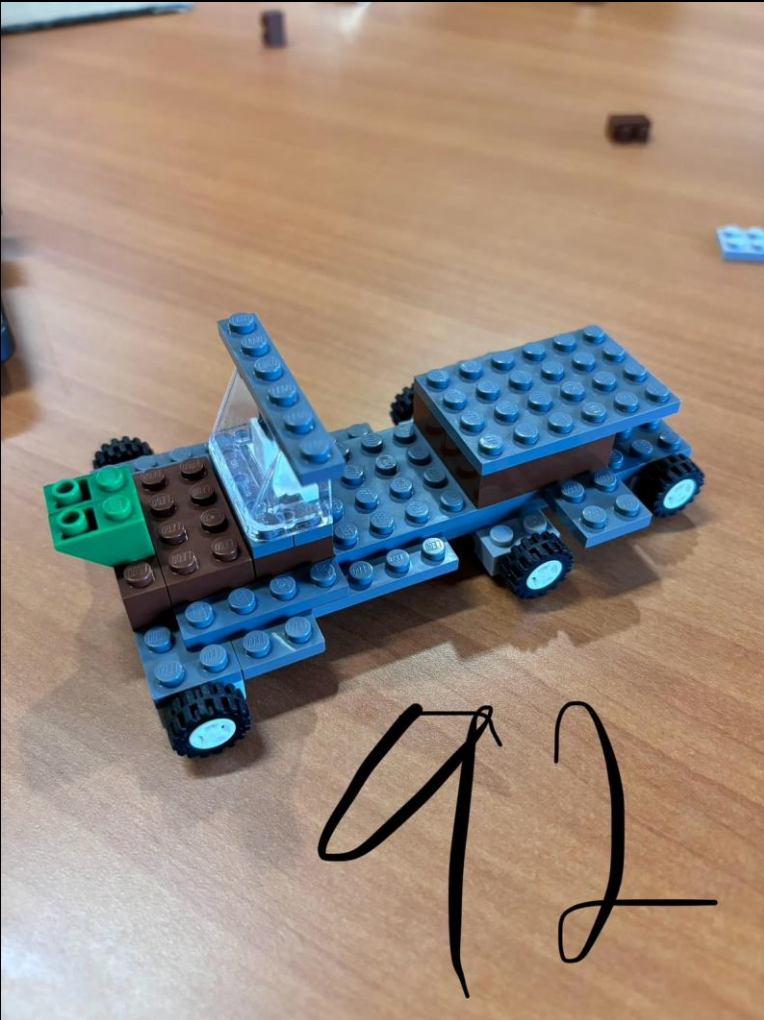
Observations	A	B	C	D	E	Distance
1	-	-	-	-	-	61
2	+	-	-	-	-	58
3	-	+	-	-	-	80.1
4	+	+	-	-	-	50
5	-	-	+	-	-	63.2
6	+	-	+	-	-	43
7	-	+	+	-	-	87.2
8	+	+	+	-	-	74
9	-	-	-	+	-	53
10	+	-	-	+	-	45.2
11	-	+	-	+	-	76
12	+	+	-	+	-	54
13	-	-	+	+	-	75
14	+	-	+	+	-	57
15	-	+	+	+	-	81
16	+	+	+	+	-	23
17	-	-	-	-	+	72
18	+	-	-	-	+	34.5
19	-	+	-	-	+	68
20	+	+	-	-	+	58
21	-	-	+	-	+	66
22	+	-	+	-	+	71
23	-	+	+	-	+	93
24	+	+	+	-	+	80
25	-	-	-	+	+	30.5
26	+	-	-	+	+	31.5
27	-	+	-	+	+	88
28	+	+	-	+	+	60
29	-	-	+	+	+	56
30	+	-	+	+	+	53
31	-	+	+	+	+	92
32	+	+	+	+	+	39

## Key insights

- Impact of gravity (E):** +1 weight in the back traveled farther.
- Effect of Length (B):** +1 longer cars Performed better in terms of distance
- Wheel size (A):** +1 and -1 had a mixed effect, sometimes reducing performance. This could be due to added weight and rolling distance but -1 gave us our TOP 2 92 and 92 distance traveled
- Width of the car (C):** +1 wider cars showed better performance overall, likely due to improved stability and reduced shift during rolling
- Number of wheels (D):** the effect of having more wheels (+1) was inconsistent. In some cases, it increased rolling resistance and reduced distance



## Analyze - TOP Performers



Parameters	92	93
A	Smaller Wheels (-1)	Smaller Wheels (-1)
B	Longer Car (+1)	Longer car (+1)
C	Wider Car (+1)	Wider Car (+1)
D	6 Wheels (+1)	4 Wheels (-1)
E	Weight in the back (+1)	Weight in the back (+1)



# Analyze – Model Simplification

## Initial Factorial Regression model

### Coded Coefficients

Term	Effect	Coef	SE Coef	T-Value	P-Value	VIF
Constant		61.66		*	*	*
A	-19.425	-9.712	*	*	*	1.00
B	14.587	7.294	*	*	*	1.00
C	8.350	4.175	*	*	*	1.00
D	-9.050	-4.525	*	*	*	1.00
E	0.7375	0.3688	*	*	*	1.00
A*B	-8.987	-4.494	*	*	*	1.00
A*C	-2.250	-1.125	*	*	*	1.00
A*D	-4.175	-2.088	*	*	*	1.00
A*E	2.112	1.056	*	*	*	1.00
B*C	-3.963	-1.981	*	*	*	1.00
B*D	-0.6125	-0.3062	*	*	*	1.00
B*E	5.850	2.925	*	*	*	1.00
C*D	-3.625	-1.813	*	*	*	1.00
C*E	5.087	2.544	*	*	*	1.00
D*E	-2.513	-1.256	*	*	*	1.00
A*B*C	-3.638	-1.819	*	*	*	1.00
A*B*D	-7.663	-3.831	*	*	*	1.00
A*B*E	0.3000	0.1500	*	*	*	1.00
A*C*D	-7.150	-3.575	*	*	*	1.00
A*C*E	3.562	1.781	*	*	*	1.00
A*D*E	0.7375	0.3687	*	*	*	1.00
B*C*D	-11.512	-5.756	*	*	*	1.00
B*C*E	-1.9750	-0.9875	*	*	*	1.00
B*D*E	7.175	3.587	*	*	*	1.00
C*D*E	-2.312	-1.156	*	*	*	1.00
A*B*C*D	-2.212	-1.106	*	*	*	1.00
A*B*C*E	-4.675	-2.337	*	*	*	1.00
A*B*D*E	-3.400	-1.700	*	*	*	1.00
A*C*D*E	-1.4125	-0.7063	*	*	*	1.00
B*C*D*E	1.4500	0.7250	*	*	*	1.00
A*B*C*D*E	5.275	2.637	*	*	*	1.00

## Simplified Model

### Coded Coefficients

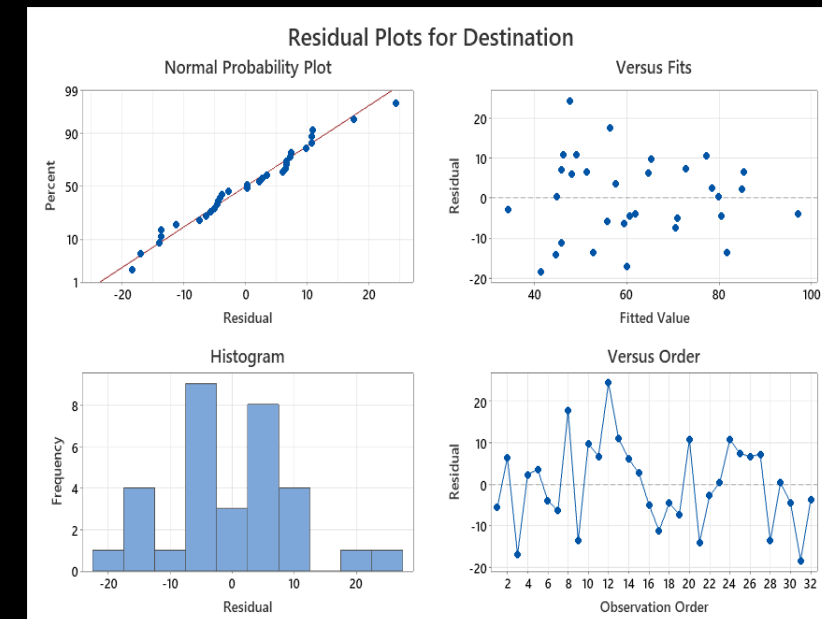
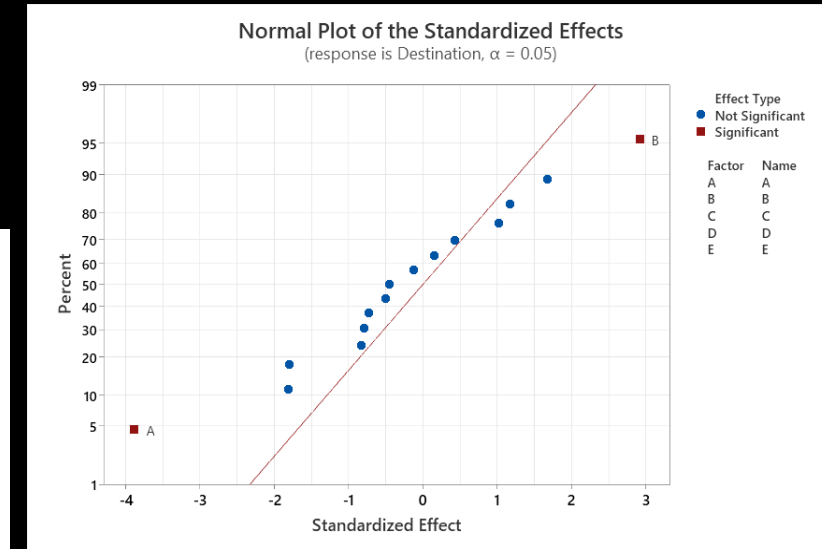
Term	Effect	Coef	SE Coef	T-Value	P-Value	VIF
Constant		61.66	2.50	24.67	0.000	
A	-19.42	-9.71	2.50	-3.89	0.001	1.00
B	14.59	7.29	2.50	2.92	0.010	1.00
C	8.35	4.17	2.50	1.67	0.114	1.00
D	-9.05	-4.53	2.50	-1.81	0.089	1.00
E	0.74	0.37	2.50	0.15	0.885	1.00
A*B	-8.99	-4.49	2.50	-1.80	0.091	1.00
A*C	-2.25	-1.13	2.50	-0.45	0.659	1.00
A*D	-4.18	-2.09	2.50	-0.84	0.416	1.00
A*E	2.11	1.06	2.50	0.42	0.678	1.00
B*C	-3.96	-1.98	2.50	-0.79	0.440	1.00
B*D	-0.61	-0.31	2.50	-0.12	0.904	1.00
B*E	5.85	2.92	2.50	1.17	0.259	1.00
C*D	-3.62	-1.81	2.50	-0.73	0.479	1.00
C*E	5.09	2.54	2.50	1.02	0.324	1.00
D*E	-2.51	-1.26	2.50	-0.50	0.622	1.00

### Model Summary

S	R-sq	R-sq(adj)	R-sq(pred)
14.1403	70.28%	42.42%	0.00%

These images show a simplified model where factors A, B, and D (and their interaction A\*B) emerge as significant.

- P-values: A & B are highly significant. D is borderline, A\*B interaction shows moderate significance.
- Residual plots suggest good model fit, with no obvious violations of assumptions
- R-squared would be considered moderate at that percentage





# Analyze – Reduced Model

## Initial Factorial Regression model

### Coded Coefficients

Term	Effect	Coef	SE Coef	T-Value	P-Value	VIF
Constant		61.66	2.50	24.67	0.000	
A	-19.42	-9.71	2.50	-3.89	0.001	1.00
B	14.59	7.29	2.50	2.92	0.010	1.00
C	8.35	4.17	2.50	1.67	0.114	1.00
D	-9.05	-4.53	2.50	-1.81	0.089	1.00
E	0.74	0.37	2.50	0.15	0.885	1.00
A*B	-8.99	-4.49	2.50	-1.80	0.091	1.00
A*C	-2.25	-1.13	2.50	-0.45	0.659	1.00
A*D	-4.18	-2.09	2.50	-0.84	0.416	1.00
A*E	2.11	1.06	2.50	0.42	0.678	1.00
B*C	-3.96	-1.98	2.50	-0.79	0.440	1.00
B*D	-0.61	-0.31	2.50	-0.12	0.904	1.00
B*E	5.85	2.92	2.50	1.17	0.259	1.00
C*D	-3.62	-1.81	2.50	-0.73	0.479	1.00
C*E	5.09	2.54	2.50	1.02	0.324	1.00
D*E	-2.51	-1.26	2.50	-0.50	0.622	1.00

## Simplified Model

### Analysis of Variance

Source	DF	Adj SS	Adj MS	F-Value	P-Value
Model	15	7565.3	504.35	2.52	0.038
Linear	5	5938.4	1187.67	5.94	0.003
A	1	3018.6	3018.64	15.10	0.001
B	1	1702.4	1702.36	8.51	0.010
C	1	557.8	557.78	2.79	0.114
D	1	655.2	655.22	3.28	0.089
E	1	4.4	4.35	0.02	0.885
2-Way Interactions	10	1626.9	162.69	0.81	0.621
A*B	1	646.2	646.20	3.23	0.091
A*C	1	40.5	40.50	0.20	0.659
A*D	1	139.4	139.44	0.70	0.416
A*E	1	35.7	35.70	0.18	0.678
B*C	1	125.6	125.61	0.63	0.440
B*D	1	3.0	3.00	0.02	0.904
B*E	1	273.8	273.78	1.37	0.259
C*D	1	105.1	105.12	0.53	0.479
C*E	1	207.1	207.06	1.04	0.324
D*E	1	50.5	50.50	0.25	0.622
Error	16	3199.2	199.95		
Total	31	10764.4			

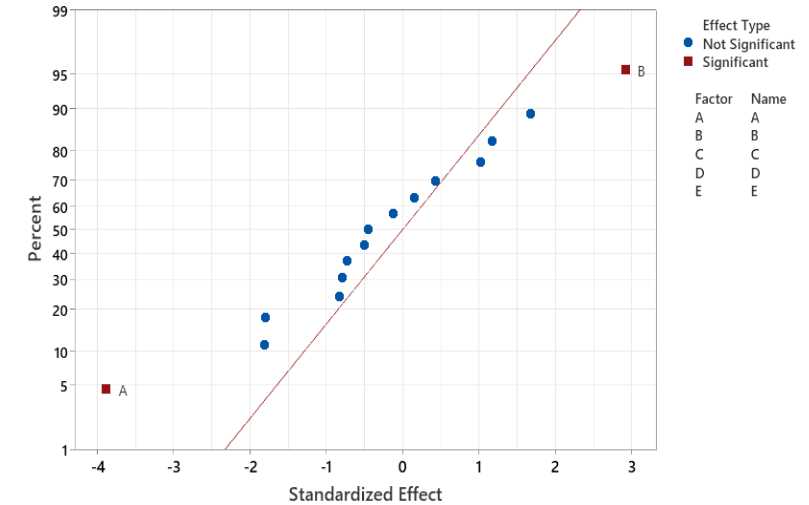
### Model Summary

S	R-sq	R-sq(adj)	R-sq(pred)
14.1403	70.28%	42.42%	0.00%

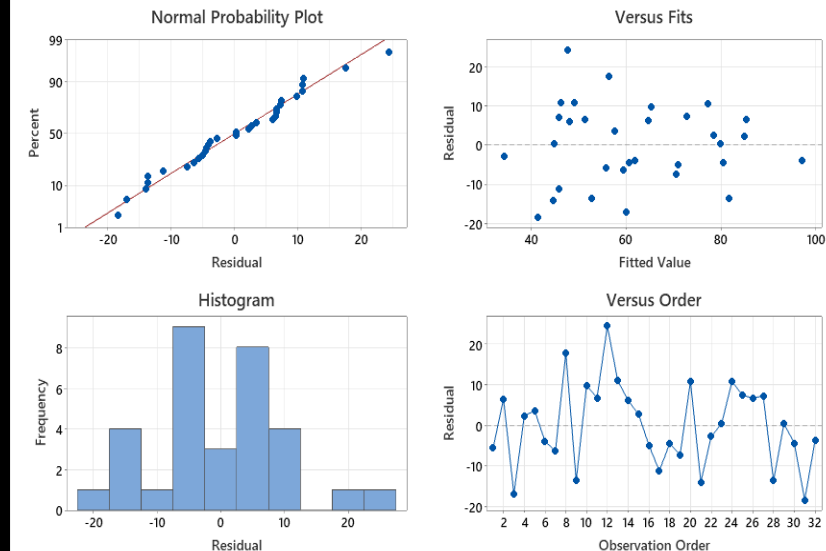
After removing higher-order interactions (5,4 and 3), the model was simplified to focus on significant factors and interactions

This step adheres to the sparsity of effects principle, allowing us to focus on the most impactful factors while reducing model complexity

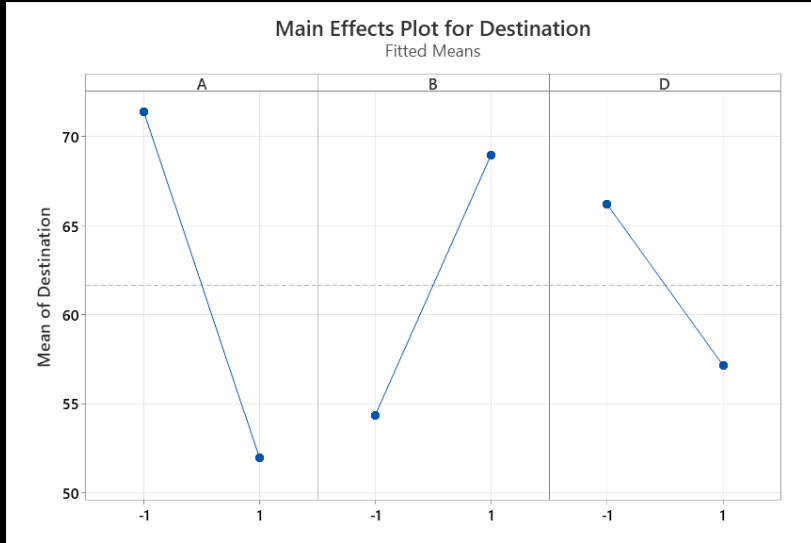
Normal Plot of the Standardized Effects  
(response is Destination,  $\alpha = 0.05$ )



Residual Plots for Destination



# Analyze – Main Effects and Interaction



Shows the individual impact of A, B, and D

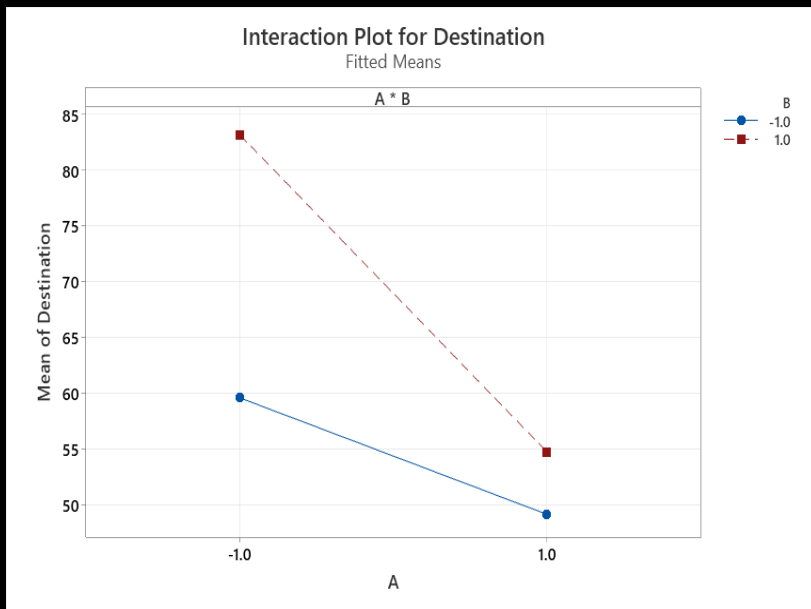
**A- Smaller wheels (-1) consistently lead to greater distance**

**B- Car length (+1) perform better, increasing stability & reducing drift**

**D- Number of wheels (-1) tend to reduce rolling resistance, improving performance**

Closing Statement:

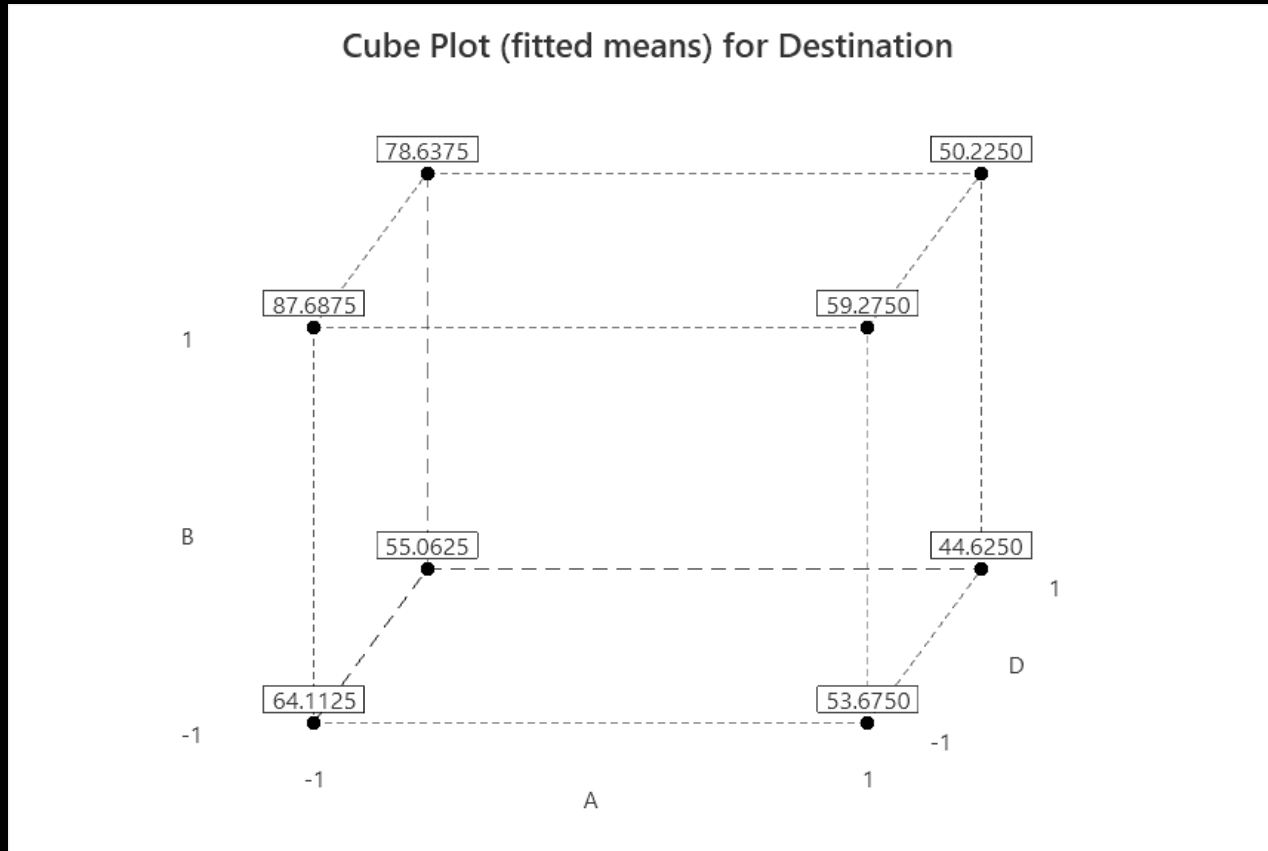
The main effects and interaction analysis confirm that wheel size and car length are the primary drivers of distance, with fewer wheels playing a secondary role



Highlights the combined effects of A and B

- **The performance of wheel size (A) is dependent on car length (B)**
- **Small wheels (-1) combined with a longer car (+1) yields the best results, achieving the highest distance.**

# Analyze – Cube Plot



The cube plot shows how factor combinations influence the response variable (distance)

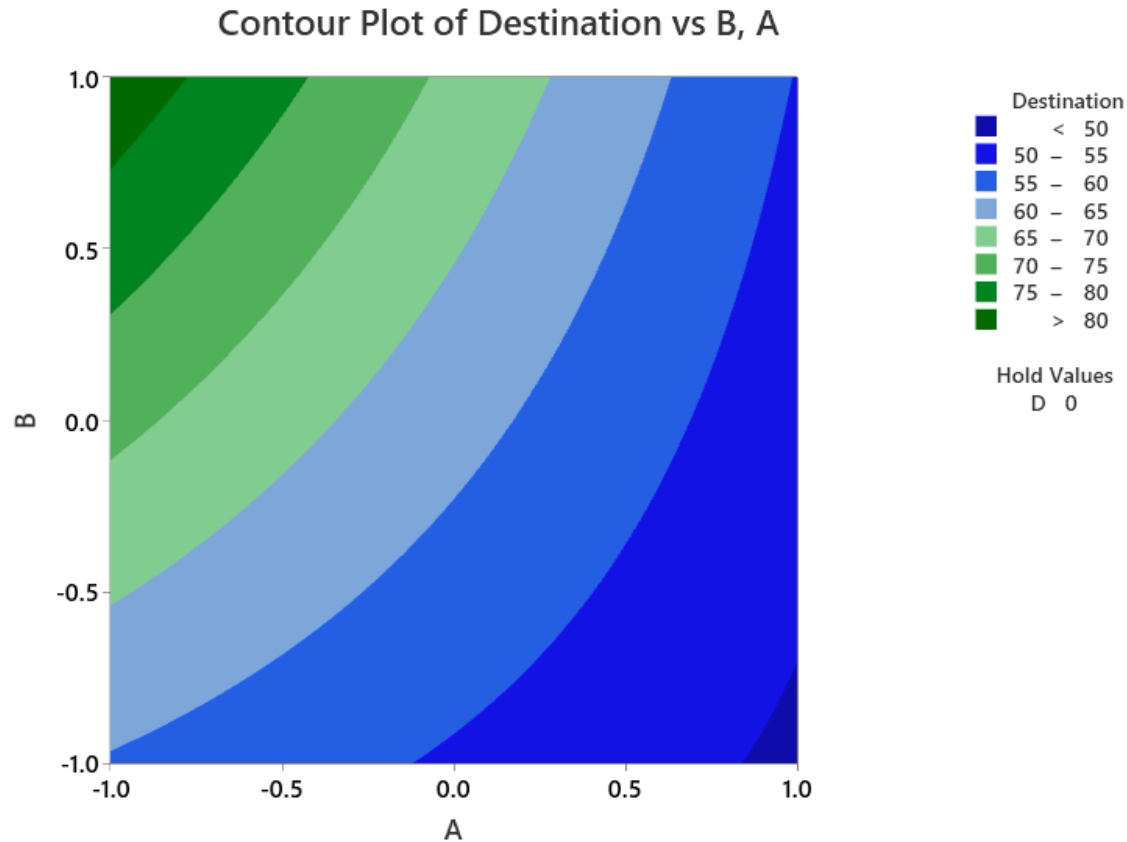
Best performance:

- **A (-1), B (+1), D (-1)** achieved the highest distance traveled

Worst performance:

- **A (+1), B (-1), D (+1)** achieved the lowest distance traveled

# Analyze – Interaction Analysis (contour plot)



- The green regions in the plot represent the highest performance (distance > 75 inches) and blue regions represent the lowest performance (distance < 50)
- Optimal performance occurs when A is low and B is high
- As A increases (moving toward +1) the performance decreases regardless of B
- The transition between regions clearly shows the interaction between A and B

# Improve— Final Model Results

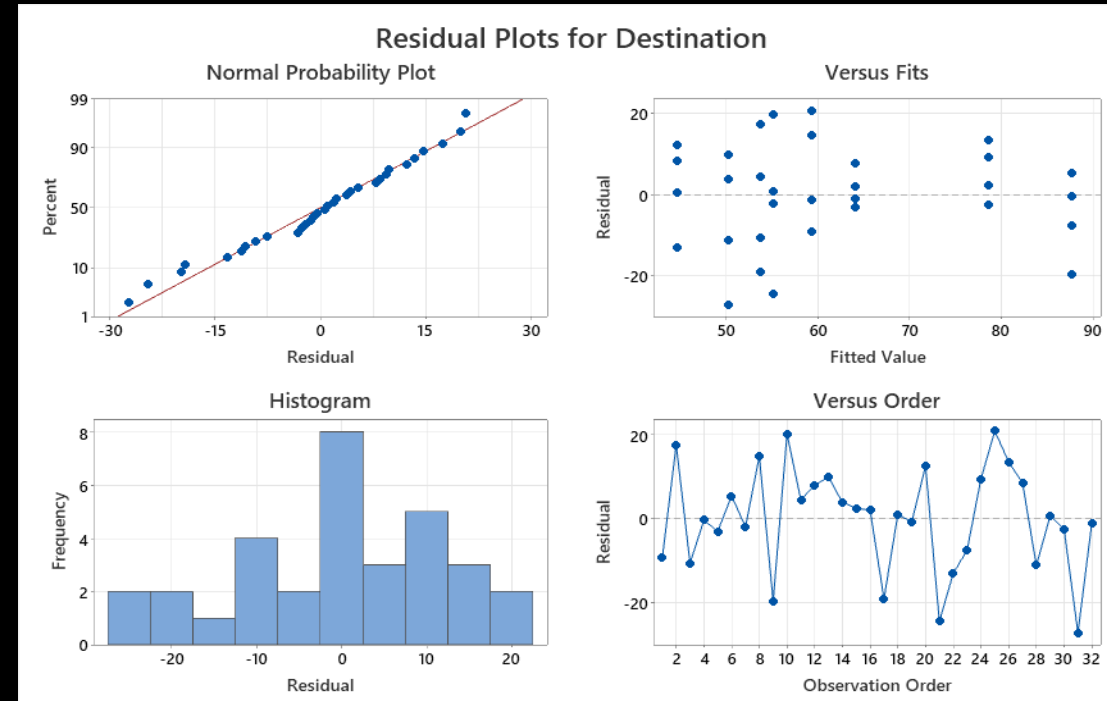
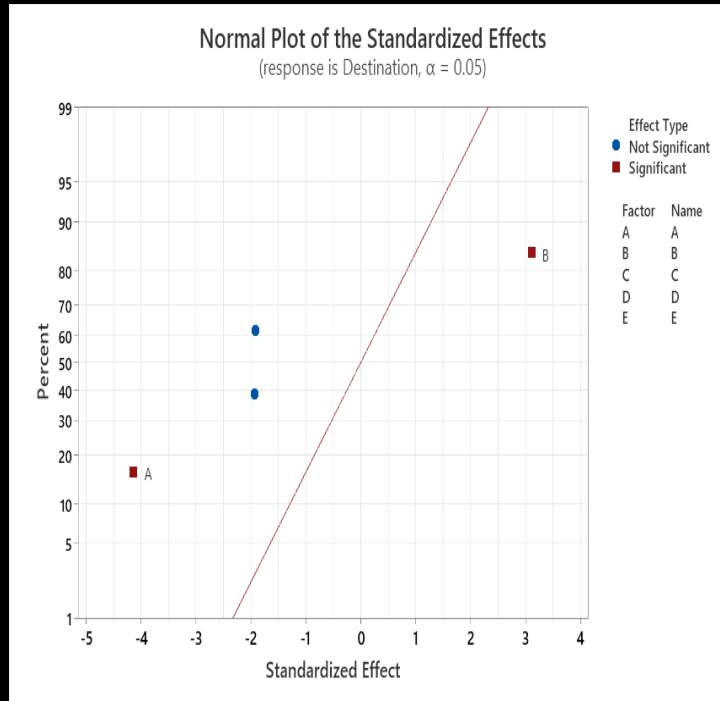
## Coded Coefficients

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Constant		61.66	2.34	26.32	0.000	
A		-19.42	9.71	2.34	0.000	1.00
B		14.59	7.29	2.34	0.004	1.00
D		-9.05	4.53	2.34	0.064	1.00
A*B		-8.99	4.49	2.34	0.066	1.00

## Model Summary

S	R-sq	R-sq(adj)	R-sq(pred)
13.2525	55.95%	49.42%	38.12%

**Conclusion:** The final model shows significant effects for A (wheel size), B (Length) and D (number of wheels), along with their interaction A\*B



This is the final model after excluding insignificant factors and interactions.

- **P-values:** A and B remain significant. D and A\*B show moderate significance and improvement from previous results.
- **R-squared:** Although it dropped from 70% to 55.95%, the simplified model is statistically robust, focusing only on significant predictors and reducing the risk of overfitting. Adjusted R-squared values indicate improved model reliability.
- **Residual plots:** normal probability plot and histogram suggest normality while residuals vs. fits indicate no patterns.



# Improve— Financial Analysis & Cost Optimization

**A financial analysis was conducted to evaluate the cost parts used in the optimized car design**

## **Key Findings:**

**- The most expensive components:**

- 1) part 15, \$5000 (quantity 5)**
- 2) Part 2, \$4,000 (quantity 2)**
- 3) Part 12, \$4,000 (quantity 4)**

**Several parts were excluded from the design due to inefficiency or minimal impact on performance**

## **• Cost-performance Trade-offs:**

- The optimized design provides the best performance but a higher cost**
- Potential savings: possibly reducing quantities of less critical parts after investigation**

Car parts	total prices per part		quantity
car part 2	\$	4,000.00	2
car part 4	\$	2,000.00	4
car part 5	\$	1,200.00	6
car part 6	\$	4,000.00	4
car part 7	\$	1,000.00	1
car part 8	\$	3,600.00	3
car part 9	\$	200.00	2
car part 10	\$	100.00	1
car part 11	\$	500.00	1
car part 12	\$	4,000.00	4
car part 14	\$	500.00	1
car part 15	\$	5,000.00	5
car part 16	\$	1,000.00	2
total	\$	27,100.00	

# Control - Recommendations

## Wheel Size (A): Choose Smaller Wheels

Smaller wheels reduce the rotational inertia, allowing the car to move further with less energy loss



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## Car Length (B): Opt for a Long Car

Longer car improves aerodynamics by reducing drift and drag during motion.



# Control - Recommendations

## **Wheel Size (A): Choose Smaller Wheels**

**Smaller wheels reduce the rotational inertia, allowing the car to move further with less energy loss**

## **Car Length (B): Opt for a Long Car**

**Longer car improves aerodynamics by reducing drift and drag during motion.**

## **Number of Wheels (D): Use 4 Wheels**

**Four wheels reduce rolling resistance compared to six wheels, leading to better energy efficiency.**



# Control - Recommendations

## Wheel Size (A): Choose Smaller Wheels

Smaller wheels reduce the rotational inertia, allowing the car to move further with less energy loss

## Car Length (B): Opt for a Long Car

Longer car improves aerodynamics by reducing drift and drag during motion.

## Number of Wheels (D): Use 4 Wheels

Four wheels reduce rolling resistance compared to six wheels, leading to better energy efficiency.

## Interaction of Wheel Size and Length of the car

The best performance is achieved when small wheels (-1) are combined with a long car (+1).

This combination maximizes rolling efficiency (due to small wheels) and stability (due to the long car), as demonstrated in the interaction plot.



## Control - Conclusion

The project analyzed factors influencing the distance traveled by a LEGO car and identified optimal configurations. Smaller wheels, a longer car, and 4 wheels resulted in the maximum distance traveled. The interaction between wheel size and car length was significant, with small wheels combined with a long car performing best.

The insights gained from this project can be applied to real-world vehicle design, emphasizing the importance of minimizing rolling resistance, optimizing aerodynamics, and balancing weight distribution.

